DIGITAL IMAGE PROCESSING

Image Restoration: Session 3

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It minimizes local variances of the restored estimated

Procedure for restoration tasks in multiple periodic interference

Isolate the principal contributions of the interference pattern

Subtract a variable, weighted portion of the pattern from the corrupted image

Optimum Notch Filtering

Extract the principal frequency components of the interference pattern

Place a notch pass filter at the location of each spike.

Optimum Notch Filtering

Optimum Notch Filtering

Assume that w(x,y) remains essentially constant over the neighborhood gives the approximation w(x+s, y+t) = w(x,y)

n iltering

Optimum Notch Filtering

Linear, Position-Invariant Degradations

Linear, Position-Invariant Degradations

Linear, Position-Invariant Degradations: Continuous Impulse Function

Homogeneity

Linear, Position-Invariant Degradations

Convolution integral in 2-D

Linear, Position-Invariant Degradations



Since degradations are modeled as being the result of convolution, image deconvolution is used frequently to signify linear image restoration.

Estimating the Degradation Function

Three principal ways to estimate the degradation function

- Observation
- 2. Experimentation
- 3. Mathematical Modeling

Estimating the Degradation Function: Mathematical Modeling (Method1)

- Environmental conditions cause degradation
 - A model about atmospheric turbulence

Estimating the Degradation Function: Mathematical Modeling (Method2)

□ Derive a mathematical model from basic principles
E.g., An image blurred by uniform linear motion between the image and the sensor during image acquisition

Estimating the Degradation Function: Mathematical Modeling (Method2)

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Estimating the Degradation Function: Mathematical Modeling (Example)

Next Class

- ☐ Image Restoration
 - **More Filters**

Thank you: Question?