

Ans

Q1)

$$C(t) = (x(t), y(t)) = (\cos t + t \sin t, \sin t - t \cos t)$$

$$C'(t) = \frac{dC(t)}{dt} = (-\sin t + t \cos t + \sin t, \cos t - (t \sin t + \cos t)) \\ = (t \cos t, t \sin t)$$

$$\|C'(t)\| = \sqrt{(t \cos t)^2 + (t \sin t)^2} = \sqrt{t^2 (\cos^2 t + \sin^2 t)} = t$$

$$\therefore \text{speed} = \|C'(t)\| = t$$

$$\text{arclength} = L_c(t) = \int_a^b t dt = \left. \frac{t^2}{2} \right|_a^b = \frac{1}{2} (b^2 - a^2)$$

1 To obtain unit speed parametrization, divide by $\|C'(t)\|$

$$\cdot \frac{C(t)}{\|C'(t)\|} = 1$$

$$S(t) = \frac{\cos t + t \sin t}{t}, \frac{\sin t - t \cos t}{t}$$

$$C'(s) = \frac{t(t \cos t) - (\cos t + t \sin t)}{t^2}, \frac{t(t \sin t) - (\sin t - t \cos t)}{t^2}$$

$$\|C'(s)\| = \sqrt{\left(\frac{t^2 \cos t - (\cos t + t \sin t)}{t^2}\right)^2 + \left(\frac{t^2 \sin t - (\sin t - t \cos t)}{t^2}\right)^2}$$

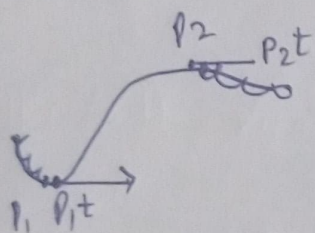
$$= \frac{1}{t^2} \sqrt{(t^2 \cos t - \cos t - t \sin t)^2 + (t^2 \sin t - \sin t + t \cos t)^2}$$

$$= \frac{1}{t^2} \sqrt{t^4} = 1.$$

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Ex 2

for again curve



$$\begin{aligned} P(t=0) &= P_1 & P'(t=0) &= P_1' \\ P(t=1) &= P_2 & P'(t=0) &= P_2' \end{aligned}$$

$$P(t) = at^3 + bt^2 + ct + d$$

$$P(0) = a \cdot 0 + b \cdot 0 + c \cdot 0 + d$$

$$P(1) = a \cdot 1 + b \cdot 1 + c \cdot 1 + d$$

$$P'(0) = 3a \cdot 0 + 2b \cdot 0 + c$$

$$P'(1) = 3a \cdot 1 + 2b \cdot 1 + c$$

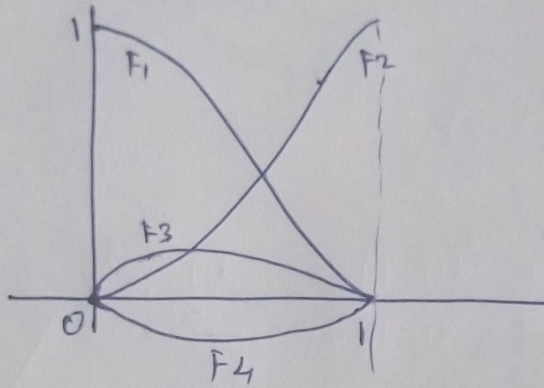
$$\begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \\ 3 & 2 & 1 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} P_1 \\ P_2 \\ P_1' \\ P_2' \end{bmatrix}$$

$$P(t) = (t^3 \ t^2 \ t \ 1) \underbrace{\begin{bmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & -1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}}_H \begin{bmatrix} P_1 \\ P_2 \\ P_1' \\ P_2' \end{bmatrix}$$

$$F_1(t) = 2t^3 - 3t^2 + 1 \quad F_2(t) = -2t^3 + 3t^2, \quad F_3(t) = t^3 - 2t^2 + t$$

$$F_4(t) = t^3 - t^2$$

Sketch



~~Sketch of~~

Sum : $2t^3 - 3t^2 + 1 - 2t^3 + 3t^2 + t^3 - 2t^2 + t + t^3 - t^2$

$$\text{Sum} = \sum F_i(t) \neq 1$$

\therefore This is not a Barycentric sum

Due to Rotation, the shape of the curve will not change.
& translation

1. The
Solutions