



Causal Ordering in Distributed Computing

Course: Distributed Computing

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About this Course

This course covers essential aspects that every serious programmer needs to know about Causal Ordering in Distributed Systems and the related concepts

What did you learn so far?

- → Goals / Challenges with Distributed Systems
- → Message Passing systems
 - Basic Primitive operations
 - → 3 types of EVENTs: Internal, send and receive
 - → States of a process and Channel
- → Distributed Sorting
 - → Odd Even Transposition Sort
 - → Sasaki's (n-1) rounds algorithms
 - Did you try (n-2) rounds algorithm for distributed sorting on line network?
 - Implementing Discrete Events Simulation

Implementation - How is it going?

5 3 2 **Initial State** 1 (0) (0) (0) (0) Round 0 1 (-1)(0) (0) (0) (0) Round 1 2^{u} 3 3 1 Round 2 5 3 5 -1)(-1)(0) (0) (1)3 5 Round 3 5 (-1)(-1)(1) (1) 4^u Round 4 5 3 5 (0) Solution 2 3 5 4

No knowledge about the Global position; Make copies of elements at intermediate nodes; Rule to select the final Solution; Computing n at runtime

Causal Ordering

A Model of Distributed Computations

Focused Topics:

- Causal Precedence Relation
- Models of Communication Networks
- Causal Ordering
- Global State and
- → Cuts of a DS
 - PAST and FUTURE events

A Distributed Program

- \rightarrow A distributed program is composed of a set of n asynchronous processes, $p_1, p_2, ..., p_i$, ..., p_n
- The processes do not share a global memory and communicate solely by passing messages
- → The processes do not share a global clock that is instantaneously accessible to these processes
- Process execution and message transfer are asynchronous
- → Without loss of generality, we assume that each process is running on a different processor
- ightharpoonup Let c_{ij} denote the channel from process p_i to p_j and let m_{ij} denote a message sent by p_i to p_j
- → The message transmission delay is finite and unpredictable

A Model of Distributed Executions

- → The execution of a process consists of a sequential execution of its actions.
- → The actions are atomic and modeled as three types of events: internal events, message send events, and message receive events
- \rightarrow Let e_i^x denote the x^{th} event at process p_i .
- → For a message m, let send(m) and receive(m) denote send and receive events, respectively.
- → The occurrence of events changes the states of respective processes and channels.
- → Internal event → changes state of the process
- → Send and Receive events change the state of the process that sends / receives the message & the state of the channel on which the message is sent / received respectively

A Model of Distributed Executions

- → The events at a process are linearly ordered by their order of occurrence.
- The execution of process p_i produces a sequence of events $e_i^{\ l}$, $e_i^{\ 2}$, ..., $e_i^{\ x}$, $e_i^{\ x+l}$, ... and is denoted by H_i where

$$H_i = (h_i, \rightarrow i)$$

 h_i is the set of events produced by p_i and binary relation $\rightarrow i$ defines a linear order on these events

- → Linear Relation: Mathematically, the independent variable is multiplied by the slope coefficient, added by a constant, which determines the dependent variable
- → Relation \rightarrow *i* expresses causal dependencies among the events of p_i

A Model of Distributed Executions (contd.)

- → The send and the receive events signify the flow of information between processes and establish causal dependency from the sender process to the receiver process
- \rightarrow Define a relation \rightarrow_{msg} that captures the causal dependency due to message exchanges as follows:

For every message m that is exchanged between two processes, we have

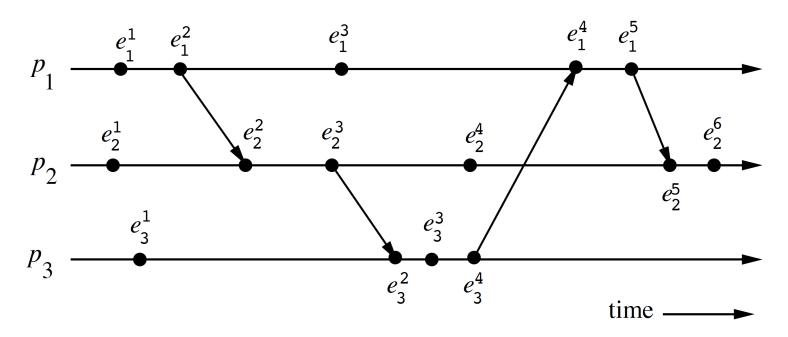
$$send(m) \rightarrow_{msg} receive(m)$$

Relation \rightarrow_{msg} defines causal dependencies between the pairs of corresponding send and receive events

A State-Time diagram

- → The evolution of a distributed execution is depicted by a space-time diagram
- → A horizontal line represents the progress of a specific process
- A dot indicates an event
- → A slant arrow indicates a message transfer
- → Since an event execution is atomic (indivisible and instantaneous), it is justified to denote it as a dot on a process line

A State-Time diagram - An Example



\rightarrow For Process p_1 :

Second event is a message send event First and Third events are internal events Fourth event is a message receive event

Partial Order / Total Ordering

A relation \leq is a total order on a set S (" \leq totally orders S") if the following properties hold:

- **1. Reflexivity:** $a \le a$ for all a in S
- **2.** Antisymmetry: $a \le b$ and $b \le a$ implies a = b
- **3.** Transitivity: $a \le b$ and $b \le c$ implies $a \le c$
- 4. Comparability (trichotomy law): For any a, b in S, either $a \le b$ or $b \le a$.

First 3 properties \rightarrow the axioms of a partial order Addition of trichotomy law defines a total order $H=(H, \rightarrow)$

Causal Precedence Relation

- → The execution of a distributed app. results in a set of distributed events
- → Let $H=U_ih_j$ denote the set of events executed in a distributed computation.
- \rightarrow Define a binary relation \rightarrow on the set H that expresses causal dependencies between events in the distributed execution.

$$\forall e_{i}^{x}, \ \forall e_{j}^{y} \in H, \ e_{i}^{x} \rightarrow e_{j}^{y} \iff \begin{cases} e_{i}^{x} \rightarrow_{i} e_{j}^{y} \ i.e., (i = j) \land (x < y) \\ or \\ e_{i}^{x} \rightarrow_{msg} e_{j}^{y} \\ or \\ \exists e_{k}^{z} \in H : e_{i}^{x} \rightarrow e_{k}^{z} \land e_{k}^{z} \rightarrow e_{j}^{y} \end{cases}$$

The causal precedence relation induces an irreflexive partial order on the events of a distributed computation that is denoted as $H=(H, \rightarrow)$

Causal Precedence Relation (contd)

→ The relation → is as defined by Lamport "happens before"

An event e_1 happens before the event e_2 and denoted by $e_1 \rightarrow e_2$ if the following holds true:

- \rightarrow e_1 occurs before e_2 on the same process OR
- \rightarrow e_1 is the send message and e_2 is the corresponding receive message OR
- → There exists another event e' such that e_1 happens before e' and e' happens before e_2

Causal Precedence Relation (contd)

For any two events e_i and e_j , $e_i \not \to e_j$ denotes the fact that event e_j does not directly or transitively dependent on event e_i

That is, event e_i does not causally affect event e_i

In this case, event e_i is not aware of the execution of e_i or any event executed after e_i on the same process.

Note the following two rules:

 \rightarrow For any two events e_i and e_j

$$e_i \not\rightarrow e_j does \ not \ imply \ e_j \not\rightarrow e_i$$

→ For any two events e_i and e_j

$$e_i \rightarrow e_j \Rightarrow e_j \quad \not \longrightarrow ei$$
.

Concurrent Events

 \rightarrow For any two events e_i and e_j :

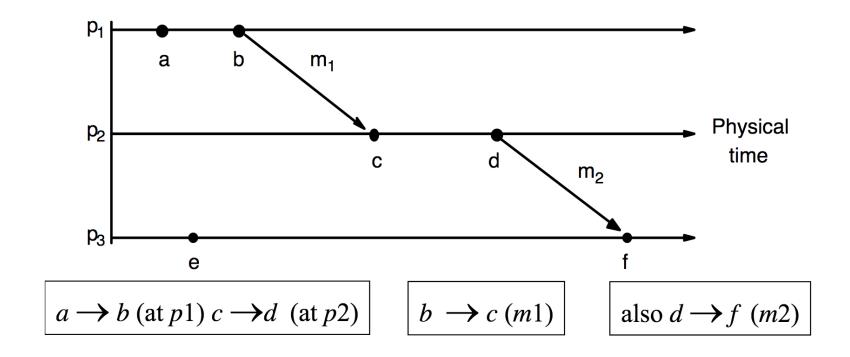
Example:

$$e_3^3 || e_2^4 \text{ and } e_2^4 || e_1^5 \text{ but } e_3^3 \text{ not } || e_1^5$$

- The relation || is not transitive; that is, $(e_i || e_i) \land (e_i || e_k) does not imply e_i || e_k$
- \rightarrow For any two events e_i and e_j in a distributed execution,

$$e_i \rightarrow e_j \ OR \ e_j \rightarrow e_i, \ OR \ e_i \mid\mid e_j$$

Concurrency - An Example



Not all events are related by \rightarrow , e.g., a $\not\rightarrow$ e and e $\not\rightarrow$ a they are said to be concurrent; write as $a \parallel e$

Logical vs. Physical concurrency

- Two events are logically concurrent if and only if they do not causally affect each other.
- → In physical concurrency: events occur at the same instant in physical time.
- Two+ events may be logically concurrent even though they do not occur at same instant in physical time.
- → If processor speed and message delays would have been different, the execution of these events could have very well coincided in physical time.
- → Whether a set of logically concurrent events coincide in the physical time or not, does not change the outcome of the computation.
- → A set of logically concurrent events may not have occurred at the same instant in physical time, we can assume that these events occurred at the same instant in physical time.

Models of Communication networks

- → There are several models of the service provided by communication networks: FIFO, Non-FIFO, and causal ordering
- → In the FIFO model, each channel acts as a first-in first-out message queue and thus, message ordering is preserved by a channel.
- → In the non-FIFO model, a channel acts like a set in which the sender process adds messages and the receiver process removes messages from it in a random order.

Causal Ordering

- The "causal ordering" model is based on Lamport's "happens before" relation
- A system that supports the causal ordering model satisfies the following property:

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CO: For any two messages m_{ij} and m_{kj}, if send(m_{ij}) \rightarrow send(m_{kj}), then receive(m_{ij}) \rightarrow receive(m_{kj})
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- This property ensures that causally related messages destined to the same destination are delivered in an order that is consistent with their causality relation.
- → Causally ordered delivery of messages implies FIFO message delivery. (Note that $CO \subseteq FIFO \subseteq Non-FIFO$.)
- Causal ordering model considerably simplifies the design of distributed algorithms because it provides a built-in synchronization.

Global State

- → A collection of the local states of its components:
 - → The processes and the communication channels
- The state of a process is defined by the local contents of processor registers, stacks, local memory, etc
- The state of channel depends the set of messages in transit in the channel
- → An internal event changes only state of the process
- → A send event changes
 - state of the process that sends the message and
 - the state of the channel on which the message is sent.
- → Similarly a receive event changes
 - the state of the process that receives the message and
 - the state of the channel on which the message is received

Global State (contd)

Notations

- → LS_i^x denotes the state of p_i after occurrence of event e_i^x and before the event e_i^{x+l}
- $\rightarrow LS_i^0$ denotes the initial state of process p_i
- → LS_i^x is a result of the execution of all the events executed by process pi till e_i^x
- **→** Let $send(m) \le LS_i^x$ denote the fact:

$$\exists y, 1 \leq y \leq x \text{ s.t } e_i^y = send(m)$$

→ Let rec(m) (not \leq) LS_i^x denote the fact:

$$\forall y, 1 \leq y \leq x \text{ s.t } e_i^y \text{ (not equal to) } rec(m)$$

Global State (contd)

→ The global state of a distributed system is a collection of the local states of the processes and the channels.

A global state GS is defined as,

$$GS = \{\bigcup_{i} LS_{i}^{x_{i}}, \bigcup_{j,k} SC_{jk}^{y_{j},z_{k}}\}$$

- → For a global state to be meaningful, the states of all the components of the distributed system must be recorded at the same instant
- → Two important situations (Impossible !!):
 - the local clocks at processes were perfectly synchronized
 - there were a global system clock that can be instantaneously read by the processes

A Consistent Global State

Basic idea:

- → A state should not violate causality an effect should not be present without its cause
- → A message cannot be received if it was not sent.
- → Such states are called consistent global states and are meaningful global states.
- → Inconsistent global states are not meaningful in the sense that a distributed system can never be in an inconsistent state

A Consistent Global State

Definition:

→ A global state is a consistent global state iff

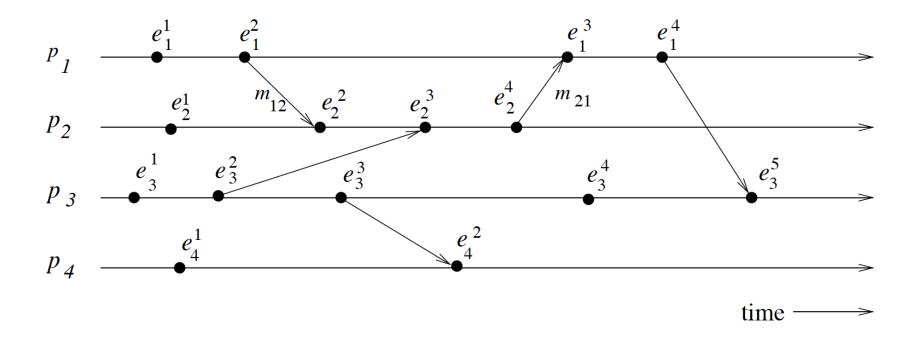
$$\forall m_{ij} : send(m_{ij}) \not\leq LS_i^{x_i} \Leftrightarrow m_{ij} \not\in SC_{ij}^{x_i,y_j} \bigwedge rec(m_{ij}) \not\leq LS_j^{y_j}$$

Where the global state is given by

$$GS = \{\bigcup_{i} LS_{i}^{x_{i}}, \bigcup_{i,k} SC_{ik}^{y_{i},z_{k}}\}$$

→ This implies that the channel state and process state must not include any message that process pi sent after executing event

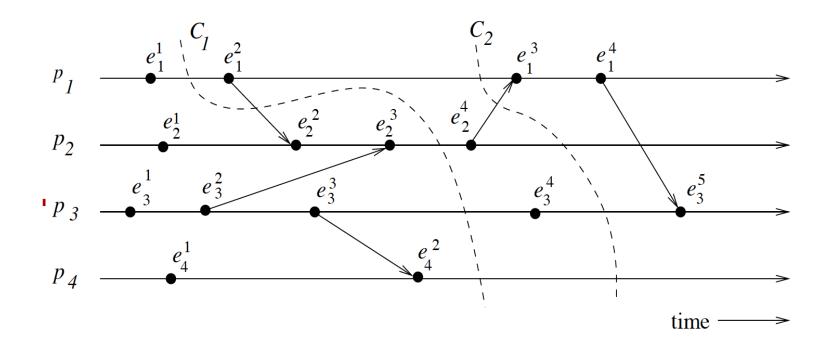
Consistent Global State - An Example



Consistent Global State - Details

- A global state GS1 = $\{LS_1^1, LS_2^3, LS_3^3, LS_4^2\}$ is inconsistent because
 - → the state of p₂ has recorded the receipt of message m₁₂
 - → The state of p₁ has not recorded its send
- → A global state GS2 consisting of local states {LS₁², LS₂⁴, LS₃⁴, LS₄²} is consistent;
- → all the channels are empty except C₂₁ that contains message m₂₁.

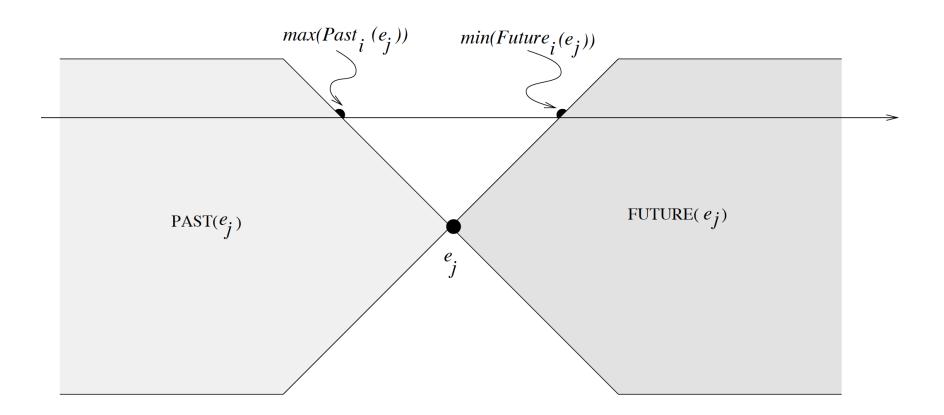
Cuts of a Distributed Computation



Cuts of a Distributed Computation

- → In a consistent cut, every message received in the PAST of the cut was sent in the PAST of that cut
 - → In previous figure, cut C2 is a consistent cut
- → All messages that cross the cut from the PAST to the FUTURE are in transit in the corresponding consistent global state.
- → A cut is inconsistent if a message crosses the cut from the FUTURE to the PAST
 - → In previous figure cut C1 is an inconsistent cut

Past and Future Cones of an event



Physical vs Logical clocks?

- **→** Logical Clocks
 - Design and Implementation
- **→** Three Different Ways
 - → Scalar Time
 - → Vector Time
 - → Matrix Time
- **→** Virtual Clocks
 - Time Wrap Mechanism
- Clock Synchronization
 - → NTP Synchronization Protocol

Summary

→ A Model of Distributed Computations

- Distributed Sorting
 - Design and Implementation Issues
- **→** Causal Precedence Relations
- Global State and Cuts of a DS
- **→** PAST and FUTURE events
- → What about the ordering of events?
 - → How do we efficiently handle the ordering of events (discrete events)?
 - → Lamport's Logical Clocks?
 - Many more to come up ... stay tuned in !!

How to reach me?

- → Please leave me an email: rajendra [DOT] prasath [AT] iiits [DOT] in
- → Visit my homepage @
 - http://www.iiits.ac.in/FacPages/indexrajendra.html

OR

→ http://rajendra.2power3.com

Help among Yourselves?

- Perspective Students (having CGPA above 8.5 and above)
- Promising Students (having CGPA above 6.5 and less than 8.5)
- Needy Students (having CGPA less than 6.5)
 - Can the above group help these students? (Your work will also be rewarded)
- You may grow a culture of collaborative learning by helping the needy students

Thanks ...

