## Approximately Optimal Arm Identification

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### The Setting

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An arm j is said to be  $\epsilon$ , m-optimal if  $p_m - p_j \leq \epsilon$ .

Intuitively,  $\epsilon$  is the tolerance in returning sub-optimal arms

#### Problem Statement

Given a bandit instance, the objective is to return a set of m,  $(\epsilon, m)$ -optimal arms.

Considering the PAC framework, we want an algorithm that, with probability atleast  $1-\delta$ , terminates and returns m such arms.

### **Applications**

#### Webpage Advertisement Problem

A website owner has n options of advertisements but can only put up an m sized subset. His objective is to identify the m most likely to bring in more revenue.

<u>Assumption:</u> Viewership is roughly constant.

 $\Rightarrow$  In this scenario, we model the quantized up-time as pulls and clicks as reward 1.



Kalyanakrishnan, et. al. in [2] suggest some approaches towards algorithms for this problem.

The intuitive idea is that if an arm is sampled sufficiently large number of times, the confidence bounds on that arm is sufficiently tight and hence, with large probability  $(\epsilon, m)$ -optimal arms will be returned.

We will briefly look at these.

### Direct Algorithm

Each arm is sampled a sufficiently large number of times -  $O(\frac{2}{\epsilon^2} \log(\frac{n}{\delta}))$  times. Then the empirically the best m arms are selected.

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### Halving Algorithm

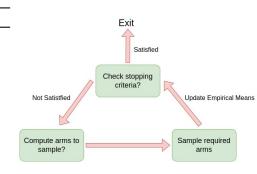
The main idea of Halving is to perform binary search on the sequence of arms. This brings down sample to  $O(\frac{m}{\epsilon^2}\log(\frac{m}{\delta}))$ .

## General Algorithmic Framework

```
Algorithm 1: A general algorithm

Result: m(\epsilon, m)-optimal arms
initialize history;
while !shouldStop(history) do

selectedArms =
selectArms(history);
result =
sample(selectedArms);
update(history, result);
```



return topK(history)

end

### Sampling Strategy

At every pull, we maintain the sets of 'top' (m) and 'bottom' (n-m) arms. The paper discusses a greedy sampling strategy which is quite intuitive. According to this, we sample the arms which are more likely to have been misclassified.

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#### selectArms

$$egin{aligned} h_*^t &= \operatornamewithlimits{argmin}_{h \in Top^t} \{\hat{p}_h^t - eta(u_h, t)\} \ I_*^t &= \operatornamewithlimits{argmax}_{l \in Bottom^t} \{\hat{p}_l^t + eta(u_l, t)\} \end{aligned}$$

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$$\begin{aligned} & h_*^t = \underset{h \in Top^t}{\operatorname{argmin}} \{ \hat{p}_h^t - \beta(u_h, t) \} \\ & l_*^t = \underset{l \in Bottom^t}{\operatorname{argmax}} \{ \hat{p}_l^t + \beta(u_l, t) \} \end{aligned}$$

Here  $\beta(u,t)$  is a function of the number of pulls u and total pulls t.

$$\beta(u,t) = \sqrt{\frac{1}{2u}\log(\frac{k_1nt^4}{\delta})}$$
, where  $k_1 = \frac{5}{4}$ 



### **Stopping Criteria**

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This is captured by the inequality:

#### shouldStop

$$\{\hat{p}_{l_*^t}^t + eta(u_{l_*^t}^t,t)\}$$
 -  $\{\hat{p}_{h_*^t}^t$  -  $eta(u_{h_*^t}^t,t)\}$   $<\epsilon$ 

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$$\{\hat{p}_{l_*^t}^t + \beta(u_{l_*^t}^t, t)\}$$
 -  $\{\hat{p}_{h_*^t}^t - \beta(u_{h_*^t}^t, t)\}$   $< \epsilon$ 

The sample complexity of this algorithm is  $\mathcal{O}(H^{\epsilon/2}log(\frac{H^{\epsilon/2}}{\delta}))$ , where  $H^{\epsilon/2} = \sum_{a \in arms} \frac{1}{[\Delta_a \vee \frac{\epsilon}{\delta}]^2}$ .

#### What have we done?

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- We select a  $t_0$  before which the algorithm would never stop even if the previously mentioned inequality is satisfied.
- We replace  $\delta$  in the expression of  $\beta(u,t)$  by  $\tilde{\delta}$ .

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- We replace  $\delta$  in the expression of  $\beta(u,t)$  by  $\tilde{\delta}$ .

 $\tilde{\delta}$  should thus be the largest possible value that still would give the PAC guarantees. Intuitively, this will reduce  $\beta(u,t)$  and hence number of the runs.

The conditions which the variables should satisfy have been described below.

- $4 \cdot \tilde{\delta} \leq (146 \cdot n \cdot \log(\frac{n}{\delta}))^2$
- $\sum_{i=1}^{\infty} \frac{1}{i^3} \ge \left(\sum_{i=t_0}^{\infty} \frac{1}{i^3}\right) \cdot \frac{\tilde{\delta}}{\delta}$

We choose the maximum  $\tilde{\delta}$  and minimum  $t_0$  satisfying the above inequalities.

We can argue theoretically<sup>1</sup> that on the modifications mentioned above we can achieve the required confidence as required for the PAC algorithm with much smaller number of runs.

 $<sup>^1</sup>$ Detailed reasoning and mathematical argument for the same would be provided in the report

#### Results

We ran LUCB1 (original) and LUCB2 (modified) for several bandit instances. Two of those instances are given below:

```
b1 = [0.9, 0.8, 0.7, 0.6, 0.595, 0.592, 0.3, 0.2, 0.1]
2 b5 = [0.9, 0.8, 0.795, 0.655, 0.6224, 0.61, 0.6, 0.5, 0.4]
     0.3, 0.2, 0.1]
```

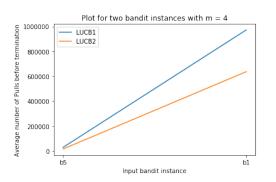
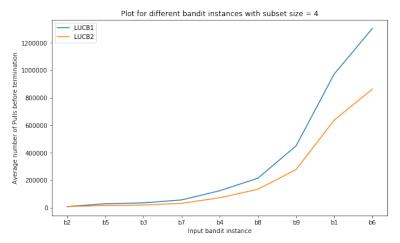


Figura: Sample complexity for m=4,  $\delta=0.1$  over\_b1 and b5

#### Results

Here are some more instances with varied means and number of arms. In every case m=4,  $\delta=0.1$ .



### An alternative notion of $\epsilon$ -closeness

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### Objective

Given parameters  $\epsilon$  and  $\delta$ , we want to select an m-sized subset of arms, V, such that with probability at least  $1-\delta$ ,  $p_i^V \geq (1-\epsilon)p_i^{true}$ .

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The main distinction is that here the tolerance is relative (proportional to true reward probability) rather than absolute.

## Second Look at Halving [2]

```
1: R_1 \leftarrow T_n.
 2: \epsilon_1 \leftarrow \frac{\epsilon}{4}; \delta_1 \leftarrow \frac{\delta}{2}.
  3: for l=1 to \lceil log(\frac{n}{m}) \rceil do
  4: for all a \in R_l do
                 Sample arm a \left\lceil \frac{2}{\epsilon_*^2} ln(\frac{3m}{\delta_l}) \right\rceil times; let \hat{p}_a be its av-
                 erage reward.
  6: end for
  7: Find R'_l \subset R_l such that |R'_l| = \max(\lceil \frac{|R_l|}{2} \rceil, m), and
            \forall i \in R_l \ \forall j \in (R_l - R'_l): (\hat{p}_i > \hat{p}_j).
  8: R_{l+1} \leftarrow R'_l
  9: \epsilon_{l+1} \leftarrow \frac{3}{4} \epsilon_l; \delta_{l+1} \leftarrow \frac{1}{2} \delta_l.
10: end for
11: Return R_{\lceil log(\frac{n}{m}) \rceil + 1}.
```

Figura: Halving Algorithm

### Adapting for Multiplicative Tolerance

### Algorithm 1: ME-AS

```
 \begin{array}{lll} \textbf{1 input: } B, \epsilon, \delta, k \\ \textbf{2 for } \mu = 1/2, 1/4, \dots \textbf{do} \\ \textbf{3} & S = \text{ME}(B, \epsilon, \delta, \mu, k); \\ \textbf{4} & \{(a_i, \hat{\theta}^{US}(a_i)) \mid 1 \leq i \leq k\} = \text{US}(S, \epsilon, \delta, (1 - \epsilon/2)\mu, k); \\ \textbf{5} & \textbf{if } \hat{\theta}^{US}(a_k) \geq 2\mu \textbf{ then} \\ \textbf{6} & \textbf{return } \{a_1, \dots, a_k\}; \end{array}
```

#### Algorithm 2: Median Elimination (ME)

Figura: Guess and Validate Mechanism

#### More ideas

For this variant, they propose a halving based algorithm with sample complexity  $O(\frac{n}{\epsilon^2} \frac{1}{\rho_t^{true}} \log \frac{m}{\delta})$ 

Can we have an improvement over this by proposing a greedy strategy similar to LUCB?



#### References

- [1] CAO, W., LI, J., TAO, Y., AND LI, Z. On top-k selection in multi-armed bandits and hidden bipartite graphs. In Advances in Neural Information Processing Systems (2015), pp. 1036–1044.
- [2] KALYANAKRISHNAN, S., AND STONE, P. Efficient selection of multiple bandit arms: Theory and practice. In *Proceedings of the Twenty-seventh International Conference on Machine Learning (ICML* 2010) (2010), J. Fürnkranz and T. Joachims, Eds., Omnipress, pp. 511–518.
- [3] KALYANAKRISHNAN, S., TEWARI, A., AUER, P., AND STONE, P. PAC subset selection in stochastic multi-armed bandits. In *Proceedings* of the Twenty-ninth International Conference on Machine Learning (ICML 2012) (New York, NY, USA, 2012), J. Langford and J. Pineau, Eds., Omnipress, pp. 655–662.

