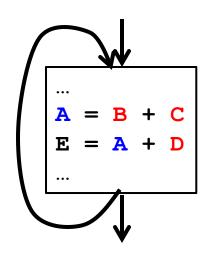
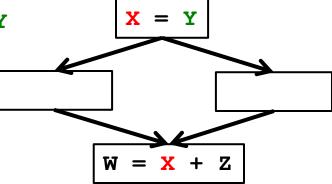
Static Single Assignment (SSA)

Where Is a Variable Defined or Used?

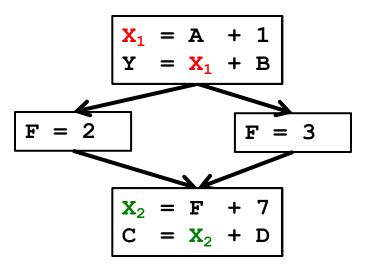
- <u>Example</u>: Loop-Invariant Code Motion
 - Are B, C, and D only defined outside the loop?
 - Other definitions of A inside the loop?
 - Uses of A inside the loop?
- <u>Example</u>: Copy Propagation
 - For a given use of X:
 - Are all reaching definitions of X:
 - copies from same variable: e.g., X = Y
 - Where **Y** is not redefined since that copy?
 - If so, substitute use of X with use of Y





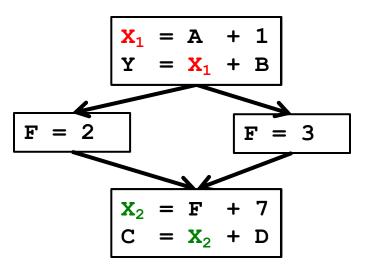
- It would be nice if we could traverse directly between related uses and def's
 - this would enable a form of sparse code analysis (skip over "don't care" cases)

Appearances of Same Variable Name May Be Unrelated



- The values in reused storage locations may be provably independent
 - in which case the compiler can optimize them as separate values
- Compiler could use renaming to make these different versions more explicit

Definition-Use and Use-Definition Chains



- Use-Definition (UD) Chains:
 - for a given definition of a variable X, what are all of its uses?
- <u>Definition-Use (DU) Chains:</u>
 - for a given use of a variable X, what are all of the reaching definitions of X?

DU and UD Chains Can Be Expensive

```
foo(int i, int j) {
                                    In general,
   switch (i) {
                                             N defs
   sase 0: x=3;break;
   case 1: x=1, break;
                                             M uses
   case 2 : x = 6 : break :
                                            \Rightarrow O(NM) space and time
            x=7; break;
   case v=x=7; break;
   case 1 = v = x + 4; break;
   case 2: v=x-2; break;
   case 3: y=x+1; break;
   default: y=x+9;
             One solution: limit each variable to ONE definition site
```

DU and UD Chains Can Be Expensive (2)

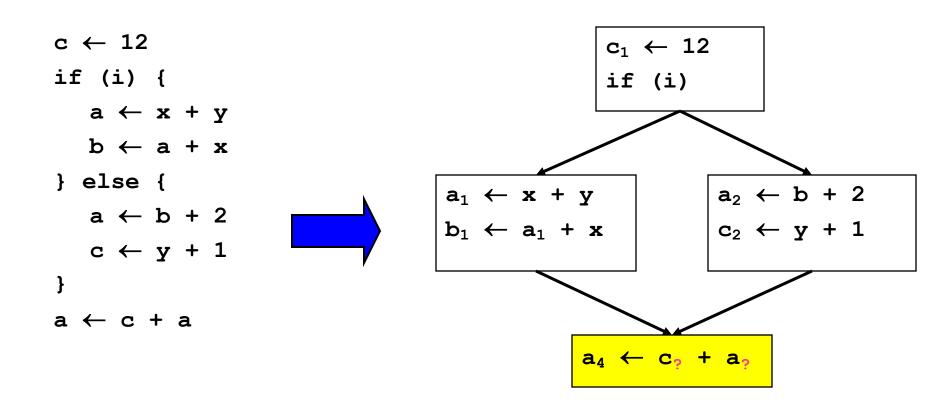
```
foo(int i, int j) {
   switch (i) {
  case 0: x=3; break;
  case 1: x=1; break;
  case 2: x=6;
  case 3: x=7;
  default: x = 11:
   x1 = x; // x1 is one of the above x's
   switch (j) {
   case 0: y=x1+7;
   case 1: y=x_1+4;
   case 2: y=x1-2;
   case 3: y=x_1+1;
  default: y=x1+9;
             One solution: limit each variable to ONE definition site
```

Static Single Assignment (SSA)

- Static single assignment is an IR where every variable is assigned a value at most once in the program text
- Easy for a basic block (reminiscent of Value Numbering):
 - Visit each instruction in program order:
 - LHS: assign to a fresh version of the variable
 - RHS: use the *most recent version* of each variable

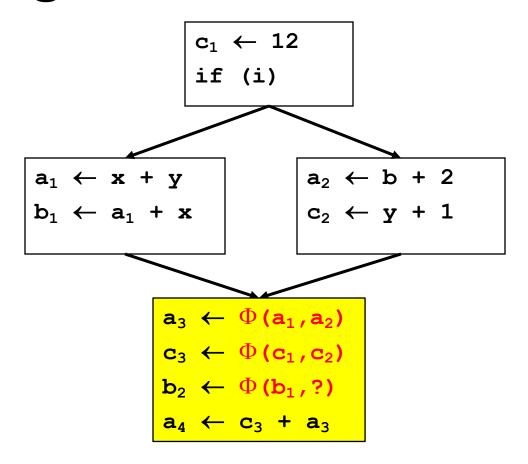
$$\begin{vmatrix} a \leftarrow x + y \\ b \leftarrow a + x \\ a \leftarrow b + 2 \\ c \leftarrow y + 1 \\ a \leftarrow c + a \end{vmatrix} \qquad \begin{vmatrix} a_1 \leftarrow x + y \\ b_1 \leftarrow a_1 + x \\ a_2 \leftarrow b_1 + 2 \\ c_1 \leftarrow y + 1 \\ a_3 \leftarrow c_1 + a_2 \end{vmatrix}$$

What about Joins in the CFG?



 \rightarrow Use a notational fiction: a Φ function

Merging at Joins: the Φ function



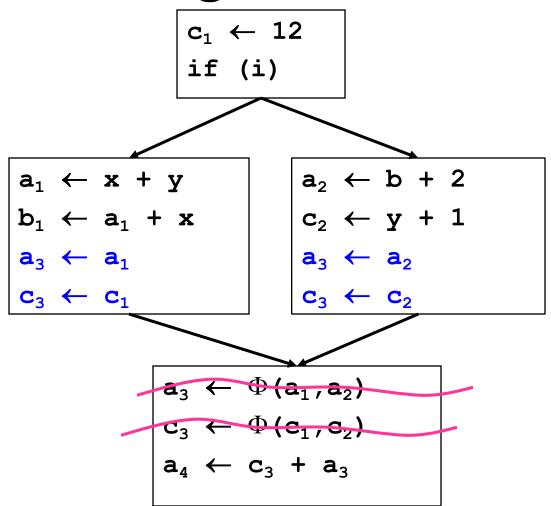
The Φ function

- At a basic block with p predecessors, there are p arguments to the Φ function.

$$x_{\text{new}} \leftarrow \Phi(x_1, x_2, \dots, x_p)$$

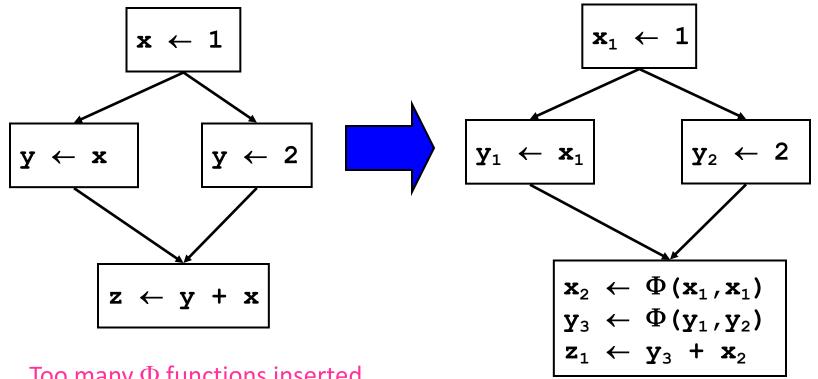
- How do we choose which x_i to use as value of Φ ?
 - For static analysis we just use □
 - For code gen, add moves on each incoming edge

"Implementing" Φ



Trivial SSA

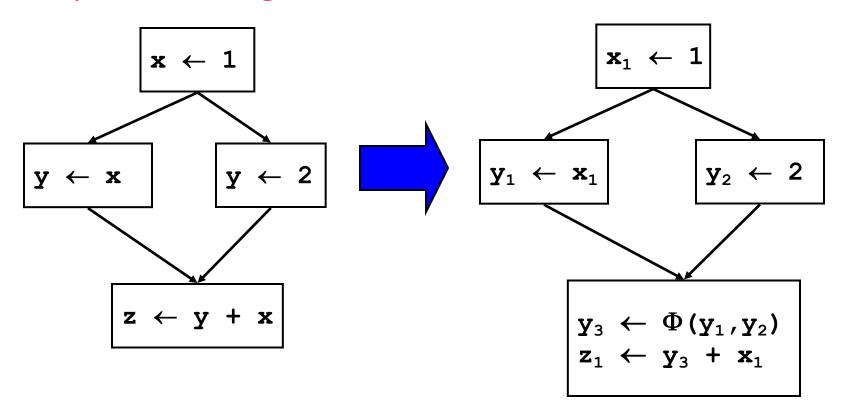
- Each assignment generates a fresh variable.
- At each join point insert Φ functions for all live variables.



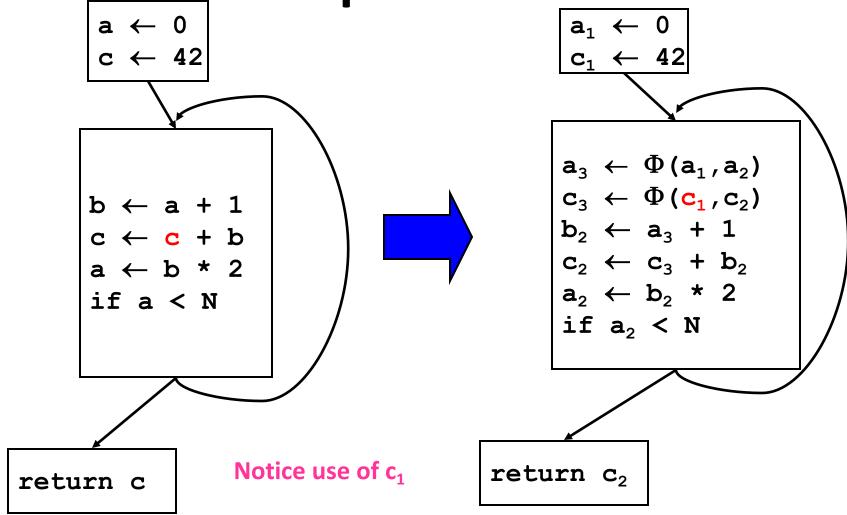
Too many Φ functions inserted.

Minimal SSA

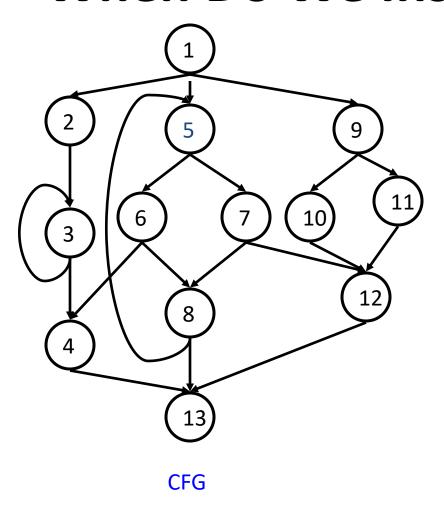
- Each assignment generates a fresh variable.
- At each join point insert Φ functions for all live variables with multiple outstanding defs.



Another Example



When Do We Insert Φ ?



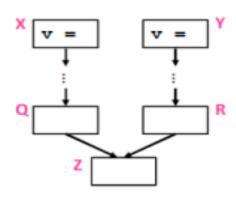
If there is a def of \mathbf{a} in block 5, which nodes need a $\Phi()$?

When do we insert Φ ?

- We insert a Φ function for variable V in block Z iff:
 - V is defined more than once
 - (i.e., A defined in X and Y AND $X \neq Y$)
 - there exists a non-empty path from x to z, P_{xz} ,
 - and a non-empty path from y to z, P_{yz} , s.t.
 - $P_{xz} \cap P_{yz} = \{z\}$

(Z is only common block along paths)

- $z \notin P_{xq}$ or $z \notin P_{yr}$ where $P_{xz} = P_{xq} \rightarrow z$ and $P_{yz} = P_{yr} \rightarrow z$ (at least one path reaches Z for first time)
- Entry block contains an implicit def of all vars
- Note: v = Φ(...) is a def of v



Path Convergence

Control flow dominators

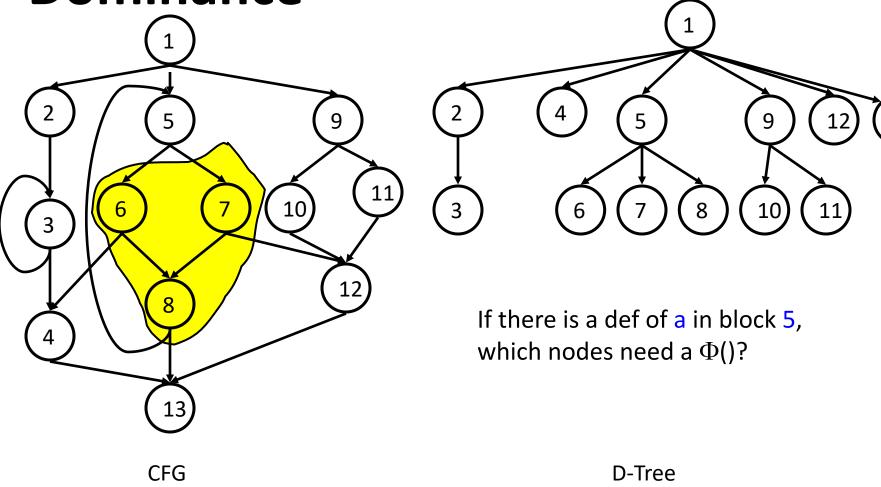
- Given two nodes, n and m, in a CFG
- n dominates m (aka n dom m)
 - if every path from the entry to m passes through n
- Every node trivially dominates itself
 - n strictly dominates m (aka n sdom m)
 - If n dom m and $n \neq m$
- Dominance relation induces a tree-shaped ordering on CFG nodes

Dominance Property of SSA

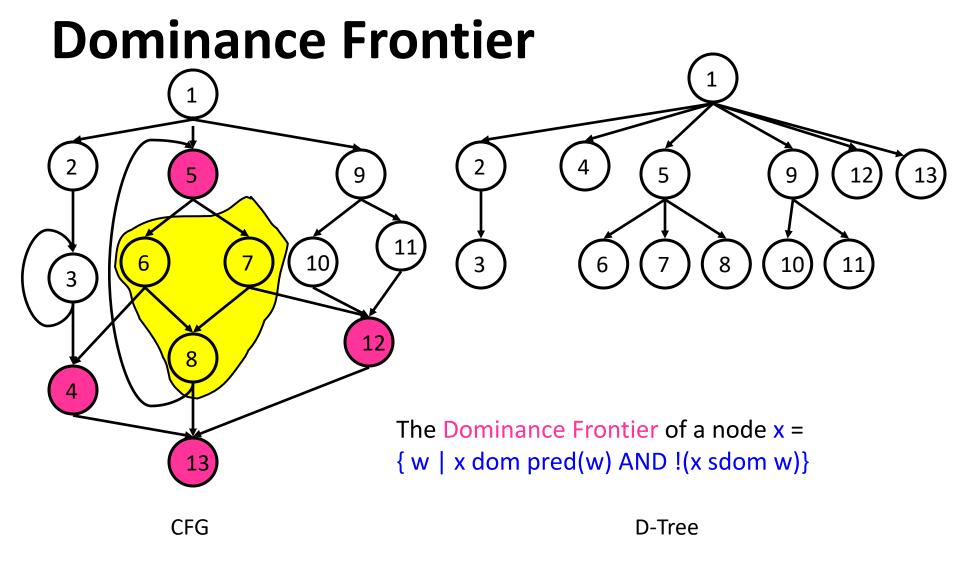
- In SSA, definitions dominate uses.
 - If x_i is used in $x \leftarrow \Phi(..., x_i, ...)$, then BB(x_i) dominates ith predecessor of BB(PHI)
 - If x is used in $y \leftarrow ... x ...$, then BB(x) dominates BB(y)

 We can use this for an efficient algorithm to convert to SSA

Dominance

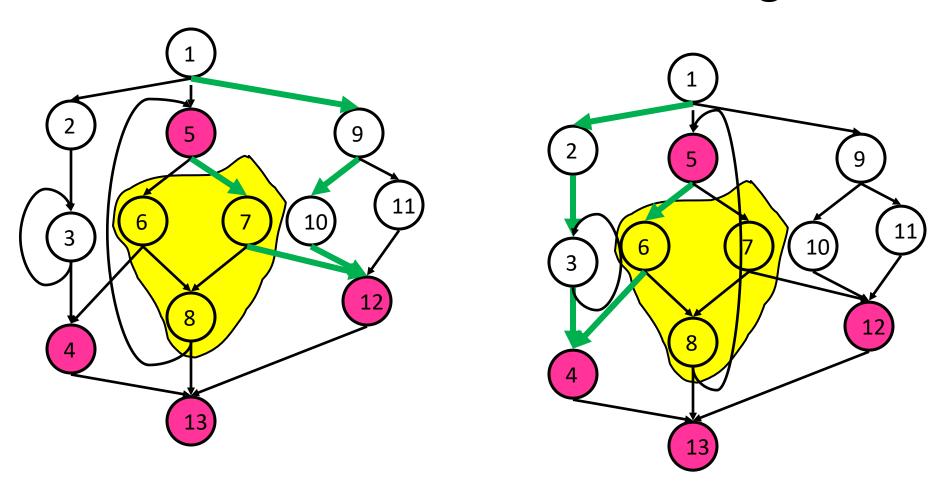


x strictly dominates w (x sdom w) iff x dom w AND $x \neq w$



x strictly dominates w (x sdom w) iff x dom w AND $x \neq w$

Dominance Frontier and Path Convergence



If there is a def of **a** in block **5**, nodes in DF(**5**) need a Φ () for **a**

Using Dominance Frontier to Compute SSA

- place all $\Phi()$
- Rename all variables

Using Dominance Frontier to Place Φ()

- Gather all the defsites, i.e., assignments, of every variable
- foreach variable
 - foreach defsite
 - foreach node in DominanceFrontier(defsite)
 - if we haven't put $\Phi()$ in node, then put one in
 - if this node didn't define the variable before, then add this node to the defsites
- This computes the Iterated Dominance Frontier on the fly, inserting the minimal number of Φ () necessary

Using Dominance Frontier to Place $\Phi()$

```
foreach node n {
  foreach variable v defined in n {
    varsdef[n] \cup = \{v\}
    defsites[v] \cup = \{n\}
foreach variable v {
  W = defsites[v]
  while W not empty {
    n = remove node from W
    foreach y in DF[n] {
       if y \notin PHI[v] {
         insert "v \leftarrow \Phi(v,v,...)" at top of y
         PHI[v] = PHI[v] \cup \{y\}
         if v \notin varsdef[y]: W = W \cup \{y\}
```

Renaming Variables

- Algorithm:
 - Walk the D-tree, renaming variables as you go
 - Replace uses with most recent renamed def
- For straight-line code this is easy
- What if there are branches and joins?
 - use the closest def such that the def is above the use in the D-tree

• <u>Implementation:</u>

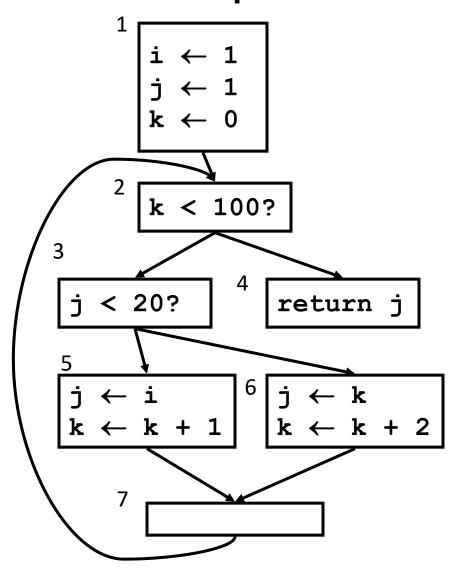
- for each var: rename (v)
- rename(v) {

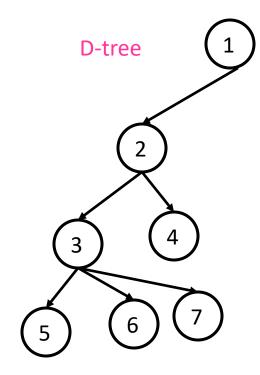
replace uses with top of stack

at def: push onto stack call rename(v) on all children in D-tree

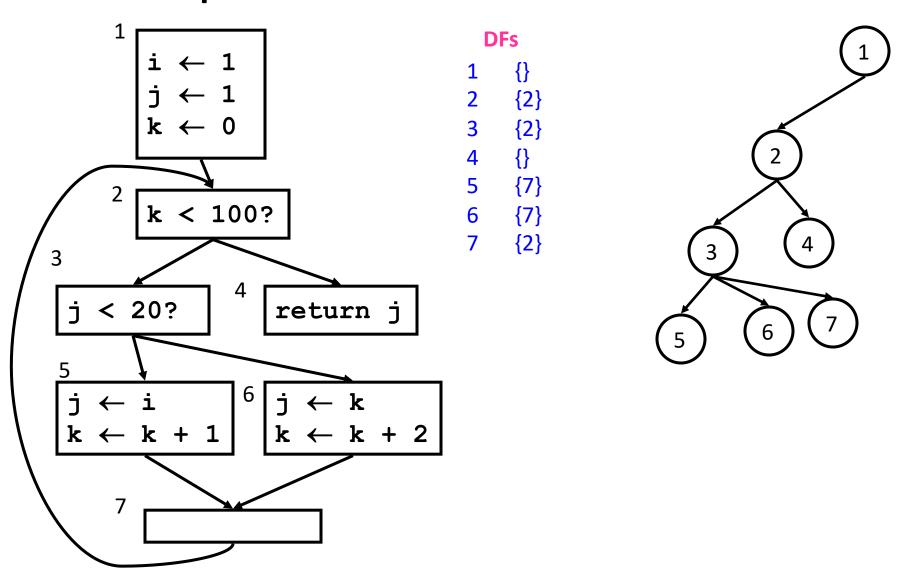
if D-tree leaf, replace uses of CFG successors for each def in this block pop from stack

Compute Dominance Tree

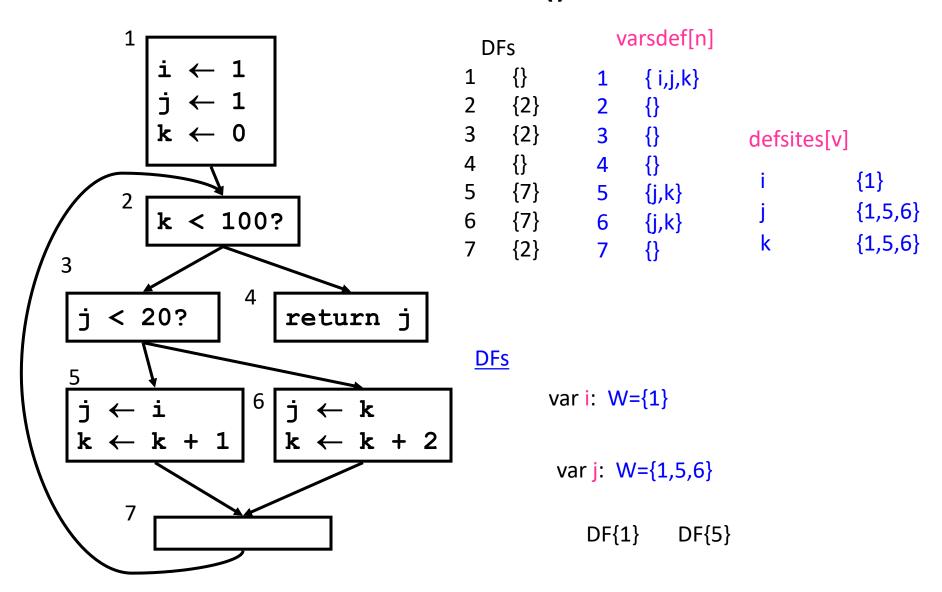




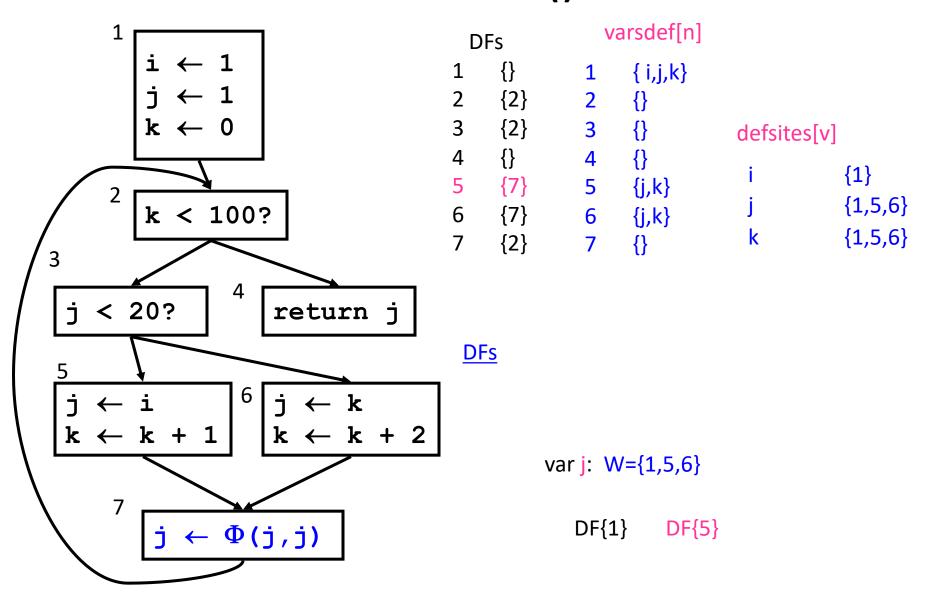
Compute Dominance Frontiers

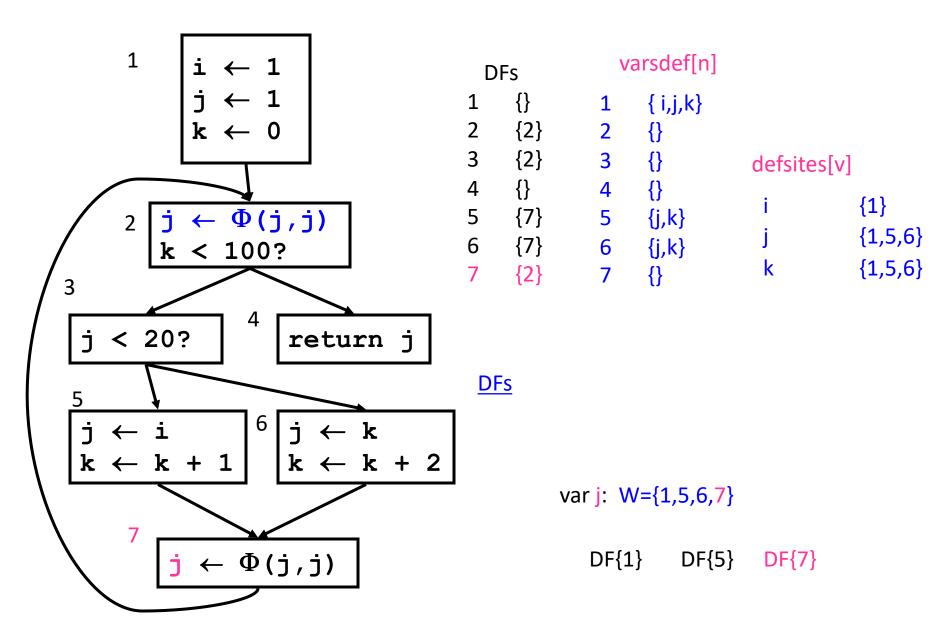


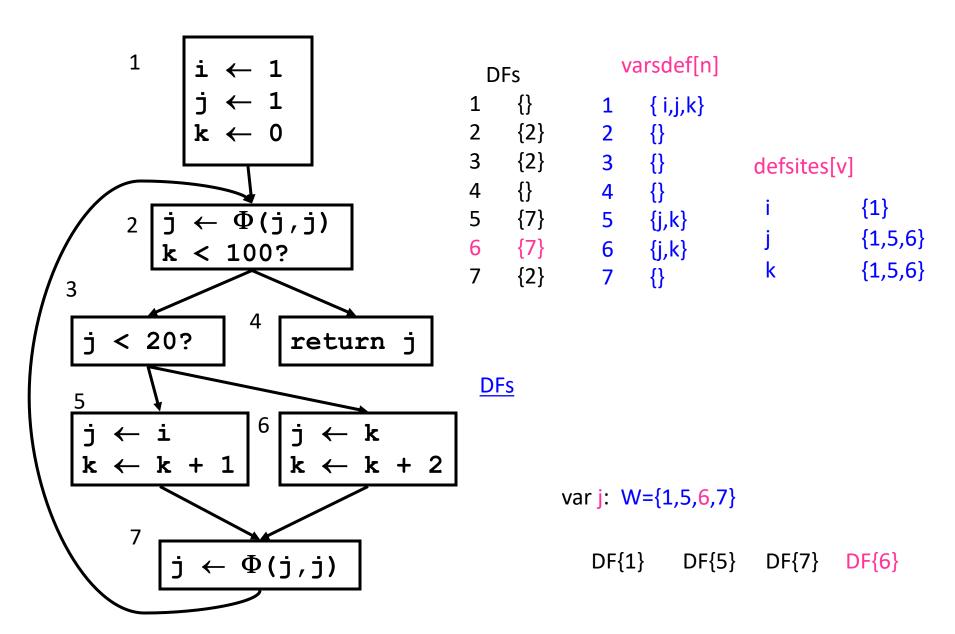
Insert $\Phi()$

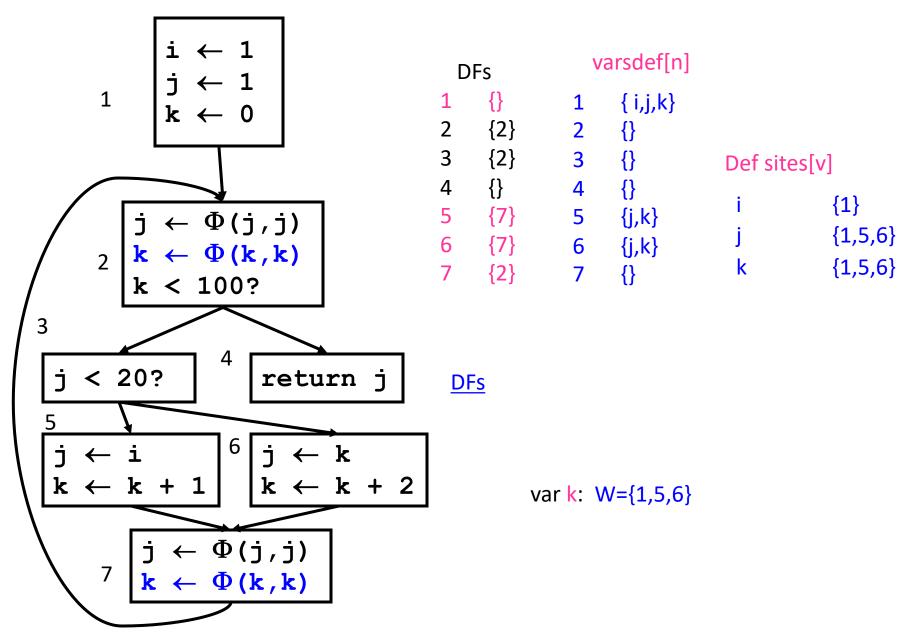


Insert $\Phi()$

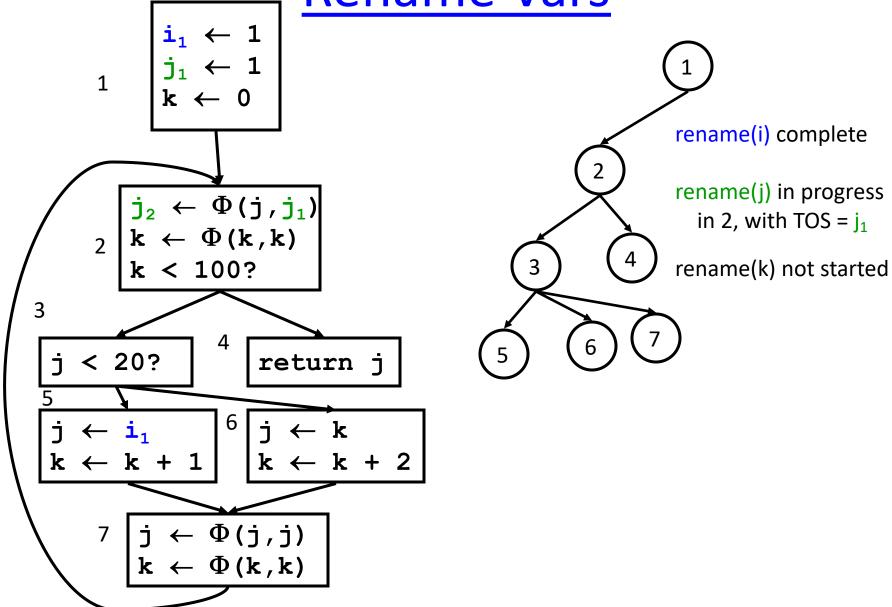




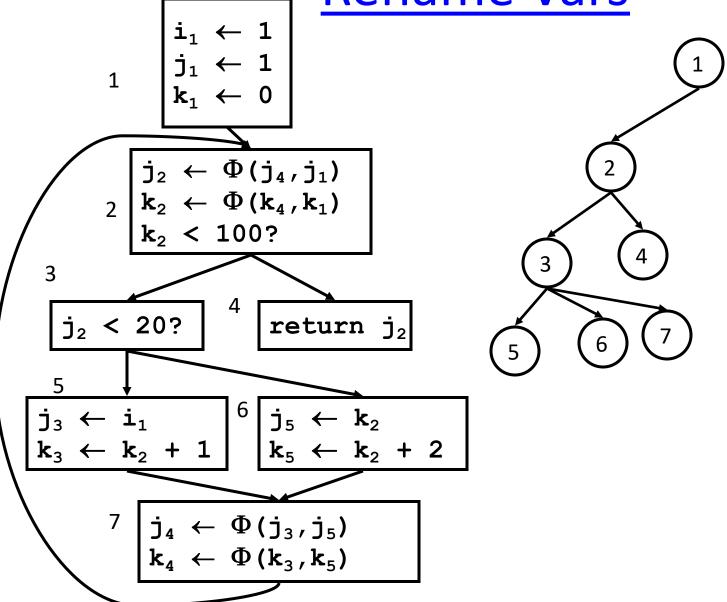




Rename Vars



Rename Vars



SSA Properties

- Only 1 assignment per variable
- Definitions dominate uses

Constant Propagation with SSA

- If "v ← c", replace all uses of v with c
- If " $v \leftarrow \Phi(c,c,c)$ " (each input is the same constant), replace all uses of v with c

```
W ← list of all defs
while !W.isEmpty {
       S ← remove from W
       if ((S has form "\mathbf{v} \leftarrow \mathbf{c}'') ||
             (S has form "\mathbf{v} \leftarrow \Phi(\mathbf{c},...,\mathbf{c})")) then {
             delete S
             foreach stmt U that uses v {
                replace v with c in U
                W add (U)
```

Other Optimizations with SSA

- Copy propagation
 - delete " $x \leftarrow \Phi(y,y,y)$ " and replace all x with y
 - delete " $x \leftarrow y$ " and replace all x with y

- Constant Folding
 - (Also, constant conditions too!)

