

CONTROL SYSTEMS

ASSIGNMENT 1

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The impulse response of a system is $h(t) = t u(t)$. For an input $u(t-1)$, the output is:

A) $\frac{t^2}{2} u(t)$ B) $\frac{t(t-1)}{2} u(t-1)$ C) $\frac{(t-1)^2}{2} u(t-1)$ D) $\frac{t^2-1}{2} u(t-1)$

Laplace Transform

$$F(s) = \int_0^{\infty} f(t) \frac{1}{e^{st}} dt$$

$f(t)$	$F(s)$
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1	$\frac{1}{s}$
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t	$\frac{1}{s^2}$
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$u(t)$	$\frac{1}{s}$
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Impulse response of system is $h(t) = tu(t)$

Input $x(t) = u(t-1)$

The output will be $y(t) = x(t) * h(t)$

Taking Laplace transform on both the sides we get

$$Y(s) = X(s)H(s) = \frac{1}{se^s} \times \frac{1}{s^2} = \frac{1}{s^3 e^s}$$

Taking the inverse Laplace Transform we get

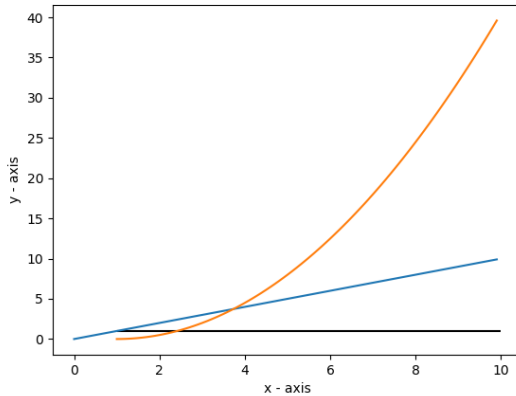
$$y(t) = p(t - 1)$$

where $p(t)$ = parabolic function

$$\frac{1}{s^3} = \frac{t^2}{2} u(t)$$

$$\frac{1}{e^s s^3} = \frac{(t-1)^2}{2} u(t - 1)$$

Solution



Solution

