## Control Systems

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### **CONTENTS**

### 1 Feedback Circuits

Abstract—This manual is an introduction to control systems based on GATE problems.Links to sample Python codes are available in the text.

Download python codes using

svn co https://github.com/gadepall/school/trunk/control/codes

### 1 FEEDBACK CIRCUITS

1.0.1. Figure 1.0.1 shows a feedback transconductance amplifier implemented using an op amp with open-loop gain  $\mu$ , a very large input resistance, and an output resistance  $r_o$ . The output current  $I_o$  that is delivered to the load resistance  $R_L$  is sensed by the feedback network composed of the three resistances  $R_M$ ,  $R_1$ , and  $R_2$ , and a proportional voltage  $V_f$  is fed back to the negative-input terminal of the op amp.

Find G,H and T. If the loop gain is large, find an approximate expression for T and state precisely the condition for which this applies.

**Solution:** The parameters given are shown in the TABLE.1.0.1:1 The equivalent circuit of

Parameter	Value
input resistance	$\infty$
output resistance	$r_o$
Input voltage	$V_s$
Output Voltage	$V_o$

TABLE 1.0.1: 1

the amplifier is in fig.1.0.1:2

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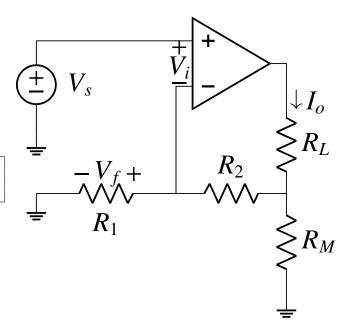


Fig. 1.0.1: 1 Original Circuit

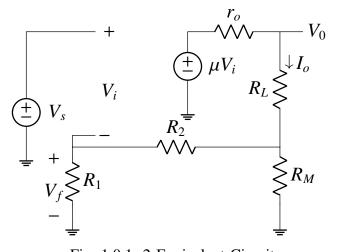


Fig. 1.0.1: 2 Equivalent Circuit

# 1.0.2. Calculating G **Solution:**

$$G = \frac{I_o}{V_i}$$
 (1.0.2.1)

From fig 
$$1.0.1:2$$
  $(1.0.2.2)$ 

$$\implies G = \mu$$
 (1.0.2.3)

### 1.0.3. Calculating H

**Solution:** 

$$H = \frac{V_f}{I_o}$$
 (1.0.3.1)

(1.0.3.2)

From the equivalent circuit in fig 1.0.1:2

$$V_f = R_1 I_o \frac{R_M}{R_M + R_1 + R_2} \tag{1.0.3.3}$$

$$V_f = R_1 I_o \frac{R_M}{R_M + R_1 + R_2}$$
 (1.0.3.3)  

$$\implies H = \frac{R_1 R_M}{R_1 + R_2 + R_M}$$
 (1.0.3.4)

### 1.0.4. Calculating T

**Solution:** 

$$T = \frac{G}{1 + GH} \tag{1.0.4.1}$$

(1.0.4.2)

From the equivalent circuit in fig 1.0.1:2

$$T = \frac{\mu (R_1 + R_2 + R_M)}{R_1 + R_2 + R_M + \mu R_1 R_M}$$
 (1.0.4.3)

Parame- ters	Definition	For given circuit
Open loop gain	G	μ
Feedback factor	Н	$\frac{R_1 R_M}{R_1 + R_2 + R_M}$
Loop gain	GH	$\mu_{R_1 + R_2 + R_M}^{R_1 R_M}$
Amount of feedback	1+GH	$1 + \frac{\mu \bar{R}_1 R_M}{R_1 + R_2 + R_M}$
Closed loop gain	Т	$\frac{\mu(R_1 + R_2 + R_M)}{R_1 + R_2 + R_M + \mu R_1 R_M}$

TABLE 1.0.4: 1

### 1.0.5. When Loop Gain is large

### **Solution:**

$$GH \gg 1, \tag{1.0.5.1}$$

$$T \approx \frac{1}{H} = \frac{R_1 + R_2 + R_M}{R_1 R_M} \tag{1.0.5.2}$$

This is the key to designing a successful feedback system; if we can guarantee that  $GH \gg 1$ for the frequencies that we are interested in, then the closed-loop gain will not be dependent on the details of the plant gain G. This is

very useful, since in some cases the feedback function H can be implemented with a simple resistive divider, which can be cheap and accurate.