
SOLUTIONS DAMPED Oscillations

QUESTION 1

(a) In the equation of motion,

$$m\ddot{x} + \gamma \dot{x} + m\omega_0^2 x = 0 \quad \text{or} \quad \ddot{x} + \frac{\gamma}{m} \dot{x} + \omega_0^2 x = 0$$

$m\ddot{x}$ is the **net force**

$-\gamma \dot{x}$ is the **damping force**

$-m\omega_0^2 x$ is the **natural restoring force**

or

\ddot{x} is the **net acceleration**

$-(\gamma/m) \dot{x}$ is the **acceleration due to the damping force**

$-\omega_0^2 x$ is the **acceleration due to the natural restoring force**

x is the displacement from equilibrium

m is the mass of the oscillator

γ is the damping constant

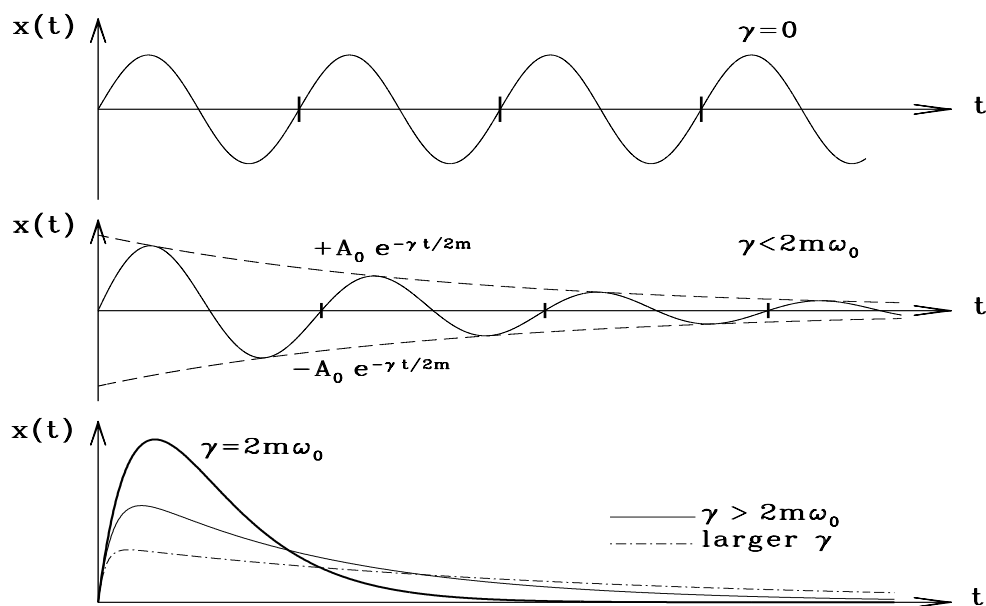
ω_0 is the natural angular frequency

(b) **Solution (i) is for critical damping**, which occurs when $\gamma = 2m\omega_0$. This provides for the fastest return to equilibrium.

Solution (ii) is for underdamping (or light damping), when $\gamma < 2m\omega_0$. This entails oscillation about equilibrium with an exponentially decaying amplitude.

Solution (iii) is for overdamping (or heavy damping), when $\gamma > 2m\omega_0$. This gives non-oscillatory, aperiodic motion with a monotonic approach to equilibrium at late times, which is slower than for critical damping.

Sketches at the top of next page.



QUESTION 2

The equation of motion for a damped oscillator is **in general**

$$m\ddot{x} + \gamma\dot{x} + m\omega_0^2 x = 0 \quad \text{or} \quad \ddot{x} + \frac{\gamma}{m}\dot{x} + \omega_0^2 x = 0$$

In this case, given that

$$2\ddot{x} + 12\dot{x} + 50x = 0$$

and told that $m = 2$ kg, then essentially by inspection:

(a) The damping constant is

$$\gamma = 12 \text{ kg s}^{-1}$$

and

$$m\omega_0^2 = 50 \quad \Rightarrow \quad \omega_0 = \sqrt{50/2} = 5 \text{ s}^{-1}$$

(b) Here $2m\omega_0 = 2 \times (2 \text{ kg}) \times (5 \text{ s}^{-1}) = 20 \text{ kg s}^{-1}$. This is greater than $\gamma = 12 \text{ kg s}^{-1}$, so the system is **underdamped**. Thus the motion is **still oscillatory and periodic**. The damped angular frequency gives the period:

$$\omega = \sqrt{\omega_0^2 - \frac{\gamma^2}{4m^2}} = \sqrt{5^2 - \frac{12^2}{4 \times (2^2)}} = 4 \text{ s}^{-1} \quad \Rightarrow \quad T = 2\pi/\omega = \pi/2 \text{ s}$$

(c) Fastest return to equilibrium is for critical damping, which requires

$$\gamma = 2m\omega_0 = 20 \text{ kg s}^{-1}$$

The equation of motion then would be

$$2\ddot{x} + 20\dot{x} + 50x = 0 \quad \text{or} \quad \ddot{x} + 10\dot{x} + 25x = 0$$

QUESTION 3

- (a) The pendulum has a length of $L = 0.60$ m, and so the natural angular frequency of oscillations is

$$\omega_0 = \sqrt{g/L} = \sqrt{(9.81 \text{ m s}^{-2})/(0.60 \text{ m})} = 4.0435 \text{ s}^{-1}$$

Given $\gamma = 0.016 \text{ kg s}^{-1}$ and $m = 0.010 \text{ kg}$,

$$2m\omega_0 = 0.0809 \text{ kg s}^{-1} > \gamma$$

and therefore the pendulum is underdamped. The damped angular frequency is

$$\omega = \sqrt{\omega_0^2 - \gamma^2/(4m^2)} = 3.9636 \text{ s}^{-1} \simeq 0.98 \omega_0$$

and hence the period is

$$T = 2\pi/\omega = 1.585 \text{ sec} \simeq 1.02 T_0 \quad [T_0 = 2\pi/\omega_0 = 1.554 \text{ s}]$$

- (b) The time-dependent amplitude of underdamped oscillations is

$$A(t) \equiv A_0 e^{-\gamma t/(2m)}$$

To find when the amplitude falls by a factor of 1000, set $A(t)/A_0 = 1/1000$, so

$$A(t)/A_0 = e^{-\gamma t/(2m)} = 0.001 \implies t = \ln(0.001)/[-\gamma/(2m)] = 8.63 \text{ sec}$$

Then, the mechanical energy is proportional to the square of amplitude, $E_{\text{tot}}(t) \propto A(t)^2$, so if the amplitude decreases by a factor of 10^3 then the **energy decreases by a factor of 10^6** .

- (c) For the pendulum to be critically damped, it must have $\gamma = 2m\omega_0$. But $\omega_0 = \sqrt{g/L}$ for a simple pendulum. Given $m = 0.010 \text{ kg}$, $\gamma = 0.016 \text{ kg s}^{-1}$, and $g = 9.81 \text{ m s}^{-2}$:

$$\begin{aligned} \gamma = 2m\omega_0 &\implies \gamma = 2m \sqrt{g/L} \implies L = 4m^2 g / \gamma^2 \\ &\implies \mathbf{L = 15.3 \text{ m}} \end{aligned}$$