

Sampling and Inference for Beta Neutral-to-the-Left Models of Sparse Networks

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Temporal networks

Example

- ▶ Messages sent between people over time
- ▶ Protein-protein interactions

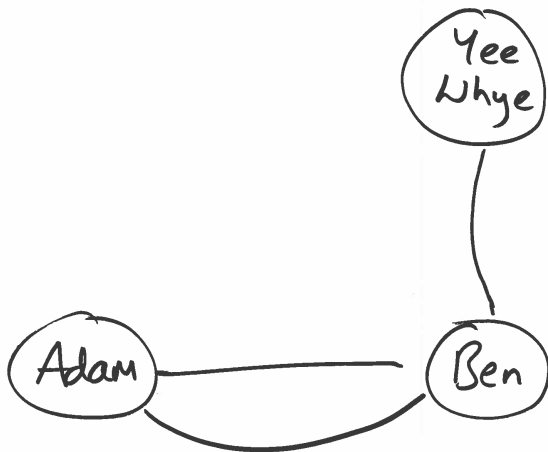
Temporal networks



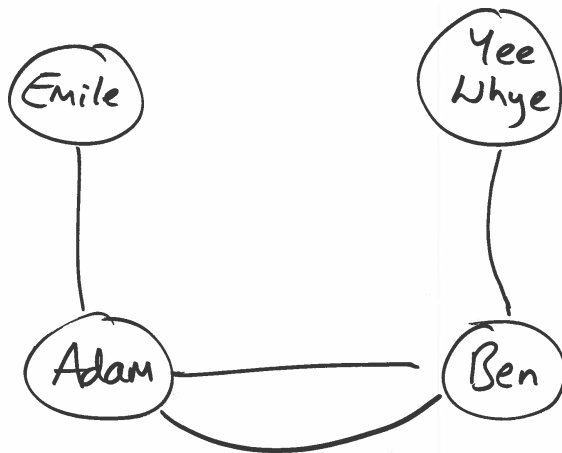
Temporal networks



Temporal networks

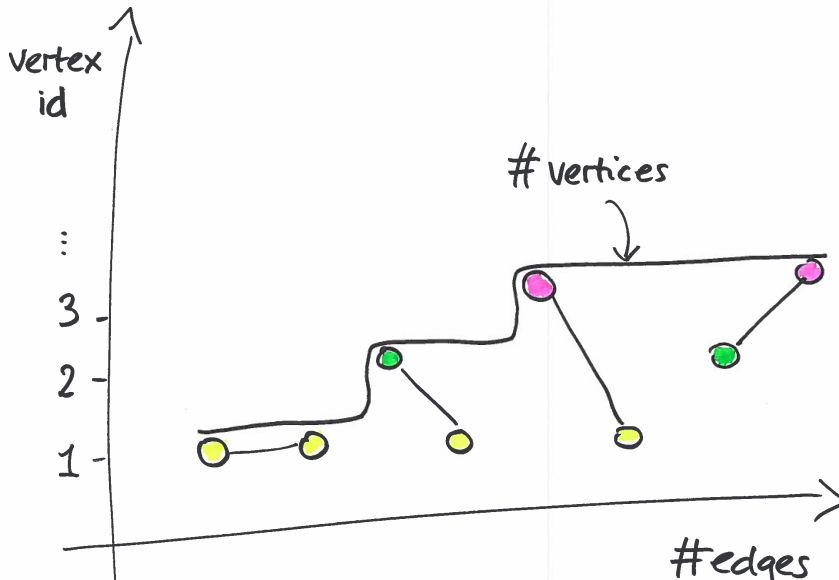


Temporal networks

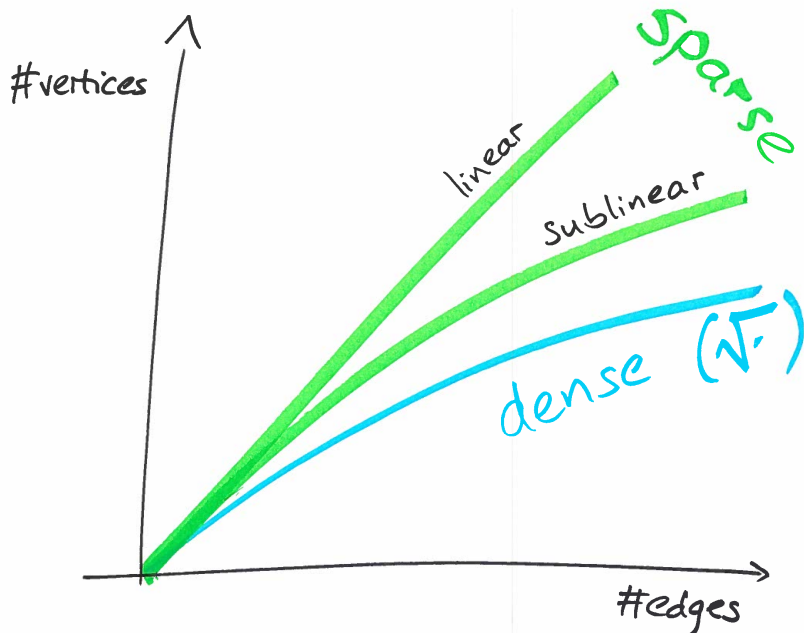


Edges and vertices

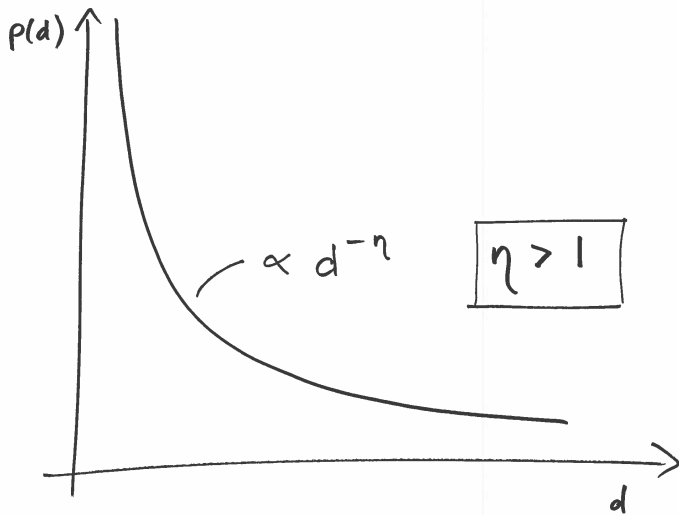
TODO: break picture into 4



Sparsity



Power law degree distribution



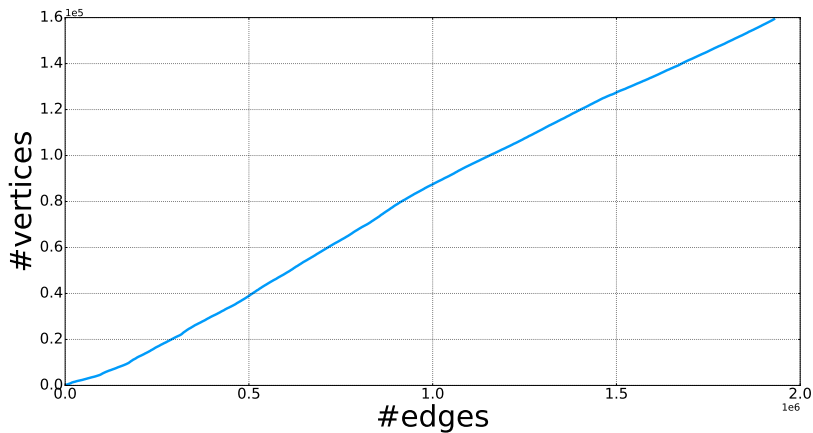
Sparsity and power law

Sublinear sparsity $\iff \eta \in (1, 2)$

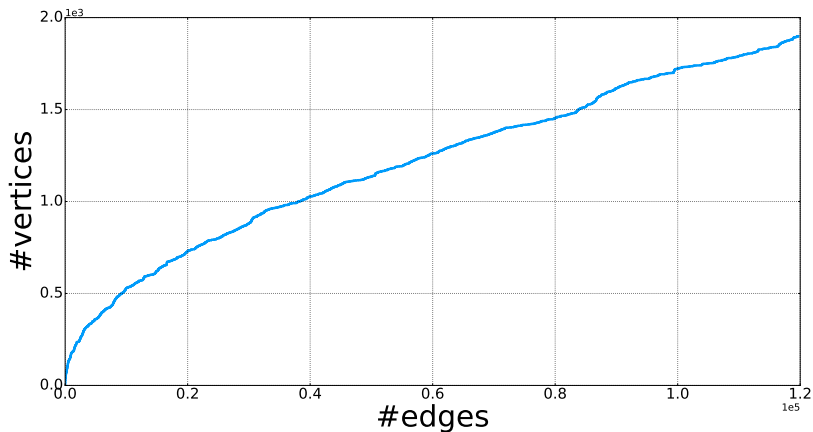
Linear sparsity $\iff \eta > 2$

Empirical study

SNAP dataset [1]	# of vertices	# of edges
Ask Ubuntu	159,316	964,437
UCI social network	1,899	20,296
⋮	⋮	⋮



UCI social network



Models



Vertex
exchangeable

Models

dense

sparse

Vertex
exchangeable

Models

dense

sparse

Vertex
exchangeable

Preferential
attachment

Models

dense

sparse

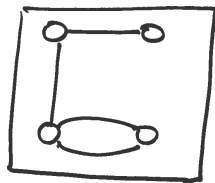
Vertex
exchangeable

Edge
exchangeable

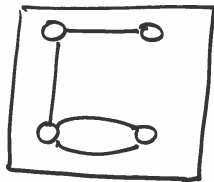
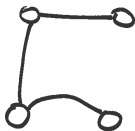
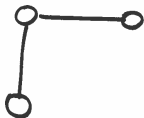
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Preferential
attachment

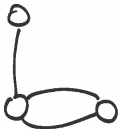
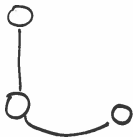
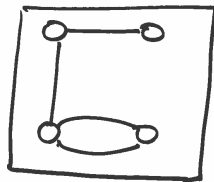
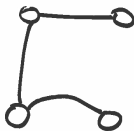
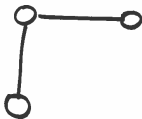
Edge exchangeable models [2], [3]



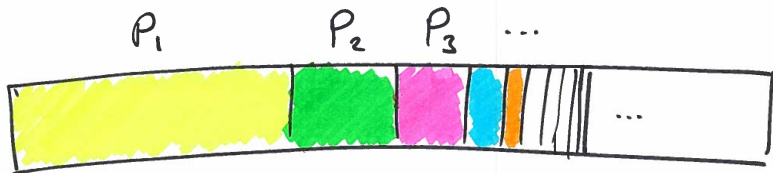
Edge exchangeable models [2], [3]



Edge exchangeable models [2], [3]



Paintbox representation

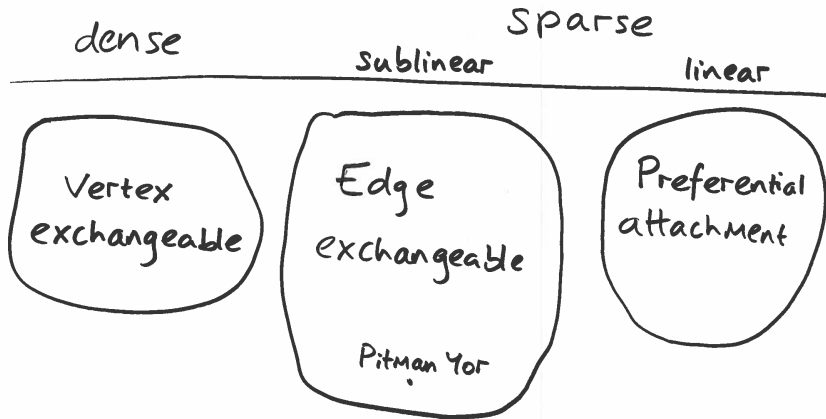


Paintbox representation

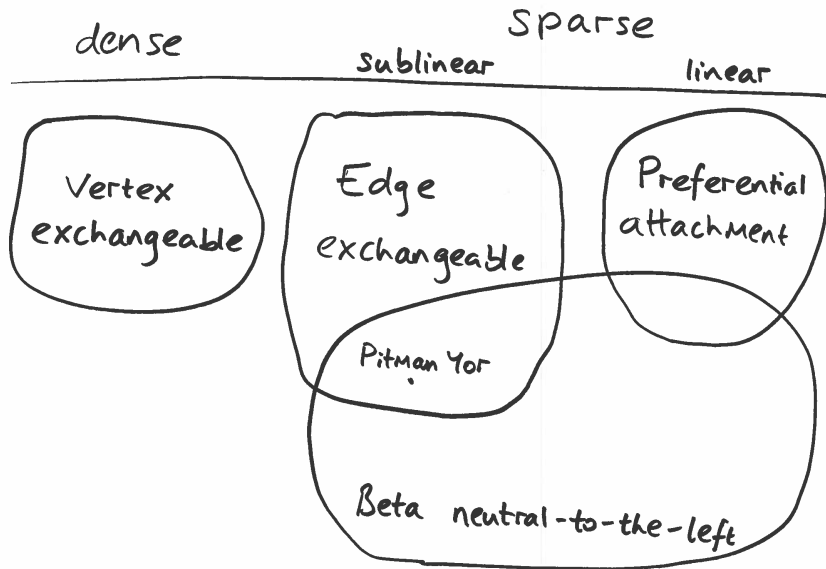
Consequence

- ▶ Edge exchangeable models have sublinear sparsity

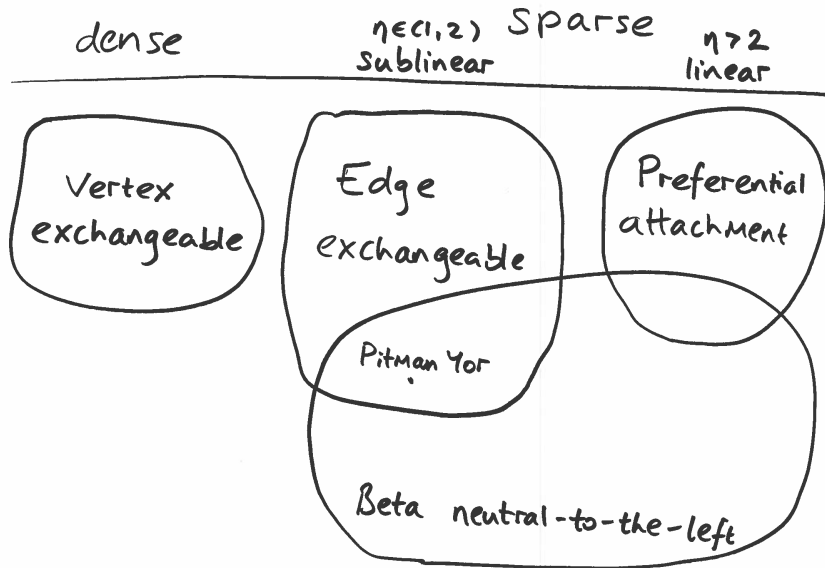
Models



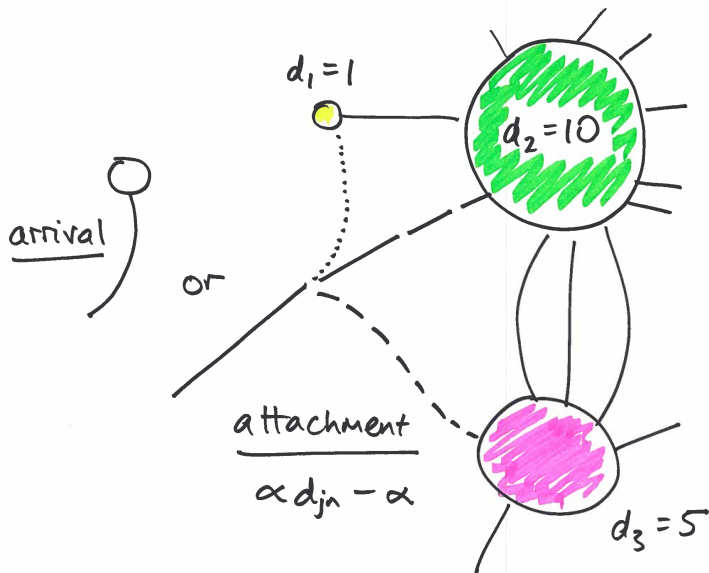
Models



Models



Beta Neutral-to-the-left Model [4]



Latent representation

$k = 1$ 

$k = 2$ 

$k = 3$ 

$k = 4$ 

Sampling and inference

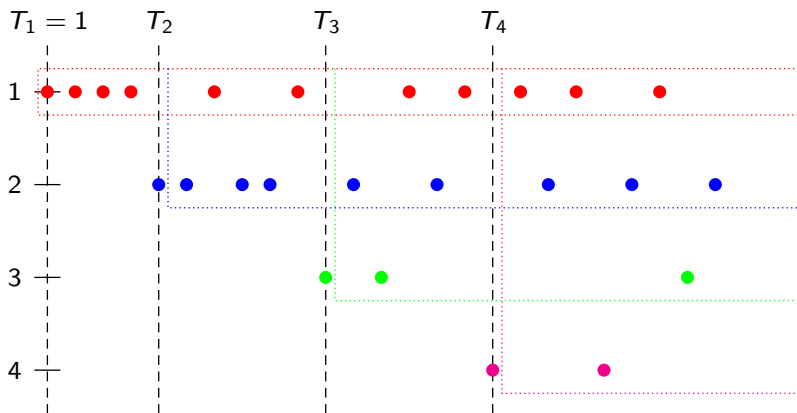
Why a paper on sampling and inference for BNTL models?

Sampling and inference

Why a paper on sampling and inference for BNTL models?

- ▶ Inference is notoriously difficult for *non-exchangeable* structures
- ▶ Need to identify *exchangeable substructures*

Exchangeable substructure



Gibbs structure

The joint density has **Gibbs structure**

$$p(\text{graph}|\mathbf{T}) = \prod_{j=1}^K p(\text{choose } j \text{ } d_j \text{ times out of } n - T_j)$$

- ▶ $K = \#\text{vertices}$
- ▶ $n = \#\text{edges}$
- ▶ $d_j = \text{degree of vertex } j$
- ▶ $T_j = \text{arrival time of vertex } j$

Gibbs structure

Explicitly

$$p(\text{graph}|\mathbf{T}) = \frac{\Gamma(d_1 - \alpha)}{\Gamma(n - K\alpha)} \prod_{j=2}^K \frac{\Gamma(T_j - j\alpha)\Gamma(d_j - \alpha)}{\Gamma(T_j - 1 - (j-1)\alpha)\Gamma(1 - \alpha)}$$

- ▶ $K = \#\text{vertices}$
- ▶ $n = \#\text{edges}$
- ▶ $d_j = \text{degree of vertex } j$
- ▶ $T_j = \text{arrival time of vertex } j$

Available data

Observation	Unobserved variables
Entire history	α, ϕ, Ψ
Degrees in arrival order	$\alpha, \phi, \Psi, \mathbf{T}$
Snapshot	$\alpha, \phi, \Psi, \mathbf{T}, \sigma$

- ▶ α = BTNL parameter $\in (-\infty, 1)$
- ▶ ϕ = arrival distribution parameters
- ▶ Ψ = latent sociabilities
- ▶ \mathbf{T} = arrival times
- ▶ σ = arrival order

Gibbs sampler

Variable	Gibbs sampling scheme
α	MCMC, e.g. slice sampling
ϕ	Depends on arrival dist. family Λ_ϕ
Ψ	$\Psi_j \text{graph}, \Psi_{\setminus j} \sim \text{Beta}(d_j - \alpha, \bar{d}_{j-1} - (j-1)\alpha)$ where $\bar{d}_j = \sum_{i=1}^j d_i$ can marginalise out Ψ
\mathbf{T}	Simple update for T_j , can't move past neighbours
σ	Initialise in descending degree order use M-H with adjacent swap proposal $\sigma_j \leftrightarrow \sigma_{j+1}$

Point estimation

If entire history observed, **maximum a posterior** (or **maximum likelihood**) estimates for α, ϕ computable

Experiments

- ▶ Gibbs: parameter recovery
- ▶ Gibbs: scalability
- ▶ Point estimation with massive graphs

Parameter recovery

- ▶ Simulate 500 edges with fixed α
- ▶ Arrivals either \mathcal{PYP} or Geom
- ▶ Observe final snapshot of the graph

Gen. arrival distn.	Inference model	$ \hat{\alpha} - \alpha^* $	Pred. log-lik.
$\mathcal{PYP}(1.0, 0.75)$	$(\tau, \mathcal{PYP}(\theta, \tau))$	0.046 ± 0.002	-2637.0 ± 0.1
$\mathcal{PYP}(1.0, 0.75)$	$(\alpha, \text{Geom}(\beta))$	0.049 ± 0.004	-2660.5 ± 0.7
Geom(0.25)	$(\tau, \mathcal{PYP}(\theta, \tau))$	0.086 ± 0.002	-2386.8 ± 0.1
Geom(0.25)	$(\alpha, \text{Geom}(\beta))$	0.043 ± 0.003	-2382.6 ± 0.2

Scalability

- Simulate with fixed α and $\text{Geom}(\beta)$ arrivals

	100 edges	10000 edges
$ \hat{\alpha} - \alpha^* $	0.12 ± 0.01	0.01 ± 0.00
$ \hat{\beta} - \beta^* $	0.02 ± 0.00	0.00 ± 0.00
Effective Sample Size	0.90 ± 0.04	0.75 ± 0.08
Runtime (s)	21 ± 0	2267 ± 2

- Runtime linear in #edges
- Most expensive Gibbs update is for \mathbf{T}

MLEs for SNAP datasets

- ▶ SNAP datasets
- ▶ Fit point estimates for α, ϕ
- ▶ Fit: coupled \mathcal{PYP} , uncoupled \mathcal{PYP} and $\text{Geom}(\beta)$ arrivals

MLEs for SNAP datasets

Ask Ubuntu

- ▶ Estimates of \mathcal{PYP} parameters vary significantly between coupled and uncoupled
 - ▷ $\hat{\theta}, \hat{\alpha} = 18080, 0.25$
 - ▷ $\hat{\theta}, \hat{\alpha}, \hat{\tau} = -0.99, -2.54, 0.99$
- ▶ Edge exchangeable models misspecified ($\eta > 2$)
- ▶ Using Geom estimates η well

Conclusion

- ▶ BNTL models are *flexible*
- ▶ BNTL models are *tractable*

Future work

- ▶ Scalability of inference
 - ▷ Metropolis-Hastings to update \mathbf{T} altogether
 - ▷ Variational inference for σ

References

- [1] Jure Leskovec and Andrej Krevl. SNAP Datasets: Stanford large network dataset collection. <http://snap.stanford.edu/data>, June 2014.
- [2] Diana Cai, Trevor Campbell, and Tamara Broderick. Edge-exchangeable graphs and sparsity. In *Advances in Neural Information Processing Systems*, pages 4249–4257, 2016.
- [3] Harry Crane and Walter Dempsey. Edge exchangeable models for interaction networks. *Journal of the American Statistical Association*, (just-accepted), 2017.
- [4] Benjamin Bloem-Reddy and Peter Orbanz. Preferential attachment and vertex arrival times. *arXiv preprint arXiv:1710.02159*, 2017.