

6.3.

$$1. E = E_{0x} \cos(k_z z - \omega t + \delta_x) \hat{x}$$

$$\nabla^2 E = \nabla^2 \begin{bmatrix} E_x \\ E_y \\ E_z \end{bmatrix} = \begin{bmatrix} 0 + 0 - k_z^2 E_{0x} \cos(k_z z - \omega t + \delta_x) \\ 0 + 0 + 0 \\ 0 + 0 + 0 \end{bmatrix}$$

$$= \frac{1}{c^2} \frac{d^2 E(x,t)}{dt^2} = \frac{1}{c^2} \begin{bmatrix} -\omega^2 E_{0x} \cos(k_z z - \omega t + \delta_x) \\ 0 \\ 0 \end{bmatrix}$$

$$-k_z^2 E_{0x} \cos(k_z z - \omega t + \delta_x) = \frac{1}{c^2} [-\omega^2 E_{0x} \cos(k_z z - \omega t + \delta_x)] \hat{x}$$

$$E_{0x} \cos(k_z z - \omega t + \delta_x) = \frac{1}{c^2} [c^2 E_{0x} \cos(k_z z - \omega t + \delta_x)] \hat{x}$$

$$B = B_{0x} \cos(k_z z - \omega t + \delta'_x) \hat{x} + B_{0y} \cos(k_z z - \omega t + \delta'_y) \hat{y}$$

$$\nabla^2 B = \nabla^2 \begin{bmatrix} B_x \\ B_y \\ B_z \end{bmatrix} = \begin{bmatrix} 0 + 0 - k_z^2 B_{0x} \cos(k_z z - \omega t + \delta'_x) \\ 0 + 0 - k_z^2 B_{0y} \cos(k_z z - \omega t + \delta'_y) \\ 0 + 0 + 0 \end{bmatrix}$$

$$\frac{1}{c^2} \frac{d^2 B(x,t)}{dt^2} = \frac{1}{c^2} \begin{bmatrix} -\omega^2 B_{0x} \cos(k_z z - \omega t + \delta'_x) \\ -\omega^2 B_{0y} \cos(k_z z - \omega t + \delta'_y) \\ 0 \end{bmatrix}$$

$$-k_z^2 B_{0x} \cos(k_z z - \omega t + \delta'_x) = \frac{1}{c^2} [-\omega^2 B_{0x} \cos(k_z z - \omega t + \delta'_x)] \hat{x}$$

$$B_{0x} \cos(k_z z - \omega t + \delta'_x) = \frac{1}{c^2} [c^2 B_{0x} \cos(k_z z - \omega t + \delta'_x)] \hat{x}$$

$$-k_z^2 B_{0y} \cos(k_z z - \omega t + \delta'_y) = \frac{1}{c^2} [-\omega^2 B_{0y} \cos(k_z z - \omega t + \delta'_y)] \hat{y}$$

$$B_{0y} \cos(k_z z - \omega t + \delta'_y) = \frac{1}{c^2} [c^2 B_{0y} \cos(k_z z - \omega t + \delta'_y)] \hat{y}$$

$$2. \nabla \times E = -\partial B / \partial t$$

$$\nabla \times E = \left(\frac{\partial E_z}{\partial y} - \frac{\partial E_y}{\partial z} \right) \hat{x} + \left(\frac{\partial E_x}{\partial z} - \frac{\partial E_z}{\partial x} \right) \hat{y} + \left(\frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} \right) \hat{z}$$

$$\nabla \times E = \frac{\partial E_x}{\partial z} \hat{y} = K_z E_{0x} \sin(K_z z - \omega t + d_x) \hat{y}$$

$$-\partial B / \partial t = -B_{0x} \cos(K_z z - \omega t + d'_x) \hat{x} \frac{d}{dt} - B_{0y} \cos(K_z z - \omega t + d'_y) \hat{y} \frac{d}{dt}$$

$$= \omega B_{0x} \sin(K_z z - \omega t + d'_x) \hat{x} + \omega B_{0y} \sin(K_z z - \omega t + d'_y) \hat{y}$$

$$d'_x = d'_y = B_{0x} = 0, \quad d_x = d'_y, \quad c = |\omega/k|, \quad E_{0x} \propto B_{0y}$$

$$E_{0x} \sin(K_z z - \omega t + d_x) = \frac{1}{c} \left[\frac{\omega}{K} B_{0y} \sin(K_z z - \omega t + d'_y) \right] \hat{y}$$

$$3. E = E_{0y} \cos(K_z z - \omega t + d_y) \hat{y}$$

$$\nabla \times E = -\frac{\partial E_y}{\partial z} \hat{x} = -K_z E_{0y} \sin(K_z z - \omega t + d_y) \hat{x}$$

$$-\partial B / \partial t = \omega B_{0x} \sin(K_z z - \omega t + d'_x) \hat{x} + \omega B_{0y} \sin(K_z z - \omega t + d'_y) \hat{y}$$

$$d'_x = d'_y = B_{0y} = 0, \quad d_y = d'_y, \quad c = |\omega/k|, \quad E_{0x} \propto B_{0y}$$

$$E_{0y} \sin(K_z z - \omega t + d_y) = \frac{1}{c} \left[\frac{\omega}{K} B_{0y} \sin(K_z z - \omega t + d'_y) \right] \hat{x}$$

$$4. B = \frac{1}{c} \hat{K} \times E = \begin{matrix} K_x & K_y & K_z \\ E_x & E_y & E_z \end{matrix}$$

$$\frac{1}{c} [(K_y E_z - K_z E_y) \hat{x} - (K_x E_z - K_z E_x) \hat{y} + (K_x E_y - K_y E_x) \hat{z}]$$

$$\text{For } E = E_{0x} \cos(K_z z - \omega t + d_x) \hat{x}$$

$$B = \frac{1}{c} [K_z E_x \hat{y} - K_y E_x \hat{z}] \quad K_y = 0 \text{ so } B = \frac{1}{c} [K_z E_x \hat{y}] = \frac{1}{c} K_z E_{0x} \cos(K_z z - \omega t + d_x) \hat{y}$$

$$\text{For } E = E_{0y} \cos(K_z z - \omega t + d_y) \hat{y}$$

$$B = \frac{1}{c} [-K_z E_y \hat{x} + K_x E_y \hat{z}] \quad K_x = 0 \text{ so } B = \frac{1}{c} [-K_z E_y \hat{x}] = -\frac{1}{c} K_z E_{0y} \cos(K_z z - \omega t + d_y) \hat{x}$$