

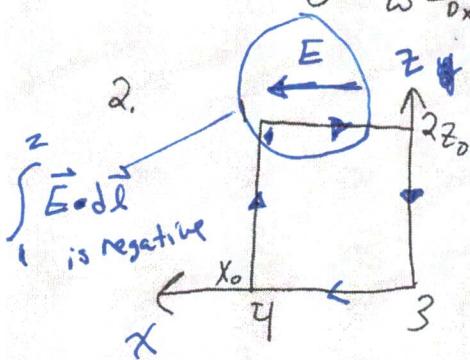
6.1

$$\nabla \times \vec{E} = \left(\frac{\partial E_z}{\partial y} - \frac{\partial E_y}{\partial z} \right) \hat{x} + \left(\frac{\partial E_x}{\partial z} - \frac{\partial E_z}{\partial x} \right) \hat{y} + \left(\frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} \right) \hat{z}$$

$$= \frac{\partial E_y}{\partial z} \hat{y} = -KE_{0x} \sin(Kz - \omega t) \hat{y}$$

$$-\frac{\partial \beta}{\partial t} = -KE_{0x} \sin(Kz - \omega t) \hat{y} \rightarrow \beta = KE_{0x} \int \sin(Kz - \omega t) dt$$

$$\beta = \frac{K}{\omega} E_{0x} \cos(Kz - \omega t) = \frac{1}{c} E_{0x} \cos(Kz - \omega t) \hat{y}$$



$$\oint \vec{E} \cdot d\vec{l} = \int_1^2 \vec{E} \cdot d\vec{l} + \int_2^3 \vec{E} \cdot d\vec{l} + \int_3^4 \vec{E} \cdot d\vec{l} + \int_4^1 \vec{E} \cdot d\vec{l}$$

$$\int_1^2 \vec{E} \cdot d\vec{l} = \int_1^2 E_x \cos(Kz - \omega t) dl$$

$$dl = \text{length of line segment} = x_2 - x_1 = x_0 - 0 = x_0$$

$$\int_1^2 \vec{E} \cdot d\vec{l} = E_{0x} x_0 \cos(Kz_0 - \omega t)$$

No change in $z \rightarrow z = z_0$

Based on
diagram
& loop dir,
this term is
negative.

$$\int_2^3 \vec{E} \cdot d\vec{l} = 0 \text{ because } d\vec{l} \text{ is perpendicular to the } E\text{-field}$$

$$\int_3^4 \vec{E} \cdot d\vec{l} = \int_3^4 E_{0x} \cos(Kz - \omega t) dl \quad dl = x_0 - 0 = x_0 \text{ and no charge in } z, \text{ at } z=0$$

$$\int_3^4 \vec{E} \cdot d\vec{l} = E_{0x} x_0 \cos(\omega t) \quad (\cos(-\omega t) = \cos(\omega t))$$

$$\int_4^1 \vec{E} \cdot d\vec{l} = 0 \text{ because } d\vec{l} \text{ is perpendicular to the } E\text{-field}$$

$$\oint \vec{E} \cdot d\vec{l} = E_{0x} x_0 \cos(Kz_0 - \omega t) + 0 + E_{0x} x_0 \cos(\omega t) + 0$$

$$= E_{0x} x_0 [\cos(Kz_0 - \omega t) + \cos(\omega t)] \quad \text{X}$$

loop dir determines \hat{n} dir
for $\oint \mathbf{B} \cdot d\mathbf{a}$

$$\Phi_B \oint \mathbf{B} \cdot d\mathbf{a} = \int_0^{z_0} \frac{1}{c} E_{0x} \cos(K_2 z - \omega t) x_0 dz$$

$$= -\frac{1}{c} \frac{E_{0x} x_0}{K} \left[\sin(-K_2 z + \omega t) \right]_0^{z_0} = -\frac{1}{c} \frac{E_{0x} x_0}{K} \left[\sin(-K_2 z_0 + \omega t) - \sin(\omega t) \right]$$

$$-\frac{d\Phi_B}{dt} = -\frac{1}{c} \frac{E_{0x} x_0}{K} \left[\sin(K_2 z - \omega t) + \sin(\omega t) \right] \frac{d}{dt}$$

$$= \frac{1}{c} \frac{\omega}{K} E_{0x} x_0 [\cos(K_2 z_0 - \omega t) + \cos(\omega t)]$$

$$= E_{0x} x_0 [\cos(K_2 z_0 - \omega t) + \cos(\omega t)] = \oint \mathbf{E} \cdot d\mathbf{l}$$

3.

$$\oint \mathbf{B} \cdot d\mathbf{l} = \int_1^2 \mathbf{B} \cdot d\mathbf{l} + \int_2^3 \mathbf{B} \cdot d\mathbf{l} + \int_3^4 \mathbf{B} \cdot d\mathbf{l} + \int_4^1 \mathbf{B} \cdot d\mathbf{l}$$

$$\int_1^2 \mathbf{B} \cdot d\mathbf{l} = \int_1^2 \frac{1}{c} E_{0x} \cos(K_2 z - \omega t) dl$$

$$dl = y_2 - y_1 = y_0 - 0 = y_0$$

$$\int_2^3 \mathbf{B} \cdot d\mathbf{l} = \frac{1}{c} E_{0x} \cos(K_2 z_0 - \omega t) y_0$$

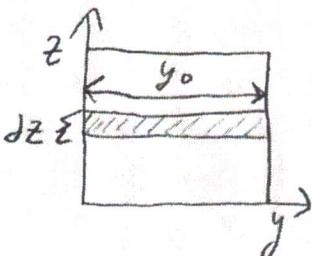
$\int_3^4 \mathbf{B} \cdot d\mathbf{l} = 0$ because dl is perpendicular to the B -field

$$\int_4^1 \mathbf{B} \cdot d\mathbf{l} = \frac{1}{c} E_{0x} \cos(K_2 z_1 - \omega t) y_0 \quad z_1 = 0 \quad \text{so} \quad \int_3^4 \mathbf{B} \cdot d\mathbf{l} = \frac{1}{c} E_{0x} \cos(\omega t) y_0$$

$\int_3^4 \mathbf{B} \cdot d\mathbf{l} = 0$ because dl is perpendicular to the B -field

$$\oint \mathbf{B} \cdot d\mathbf{l} = \frac{1}{c} E_{0x} \cos(K_2 z_0 - \omega t) y_0 + 0 + \frac{1}{c} E_{0x} \cos(\omega t) y_0 + 0$$

$$= \frac{1}{c} E_{0x} y_0 [\cos(K_2 z_0 - \omega t) + \cos(\omega t)]$$



Area of B -field that contributes to the E -flux

$$dA = y_0 dz$$

$$\Phi_E = \int E \cdot dA = \int_0^{z_0} E_{ox} \cos(K_2 z - \omega t) y_0 dz$$

$$= -\frac{E_{ox} y_0}{K} [\sin(-K_2 z + \omega t)] \Big|_0^{z_0} = -\frac{E_{ox} y_0}{K} [-\sin(K_2 z_0 - \omega t) - \sin(\omega t)]$$

$$= \frac{E_{ox} y_0}{K} [\sin(K_2 z_0 - \omega t) + \sin(\omega t)]$$

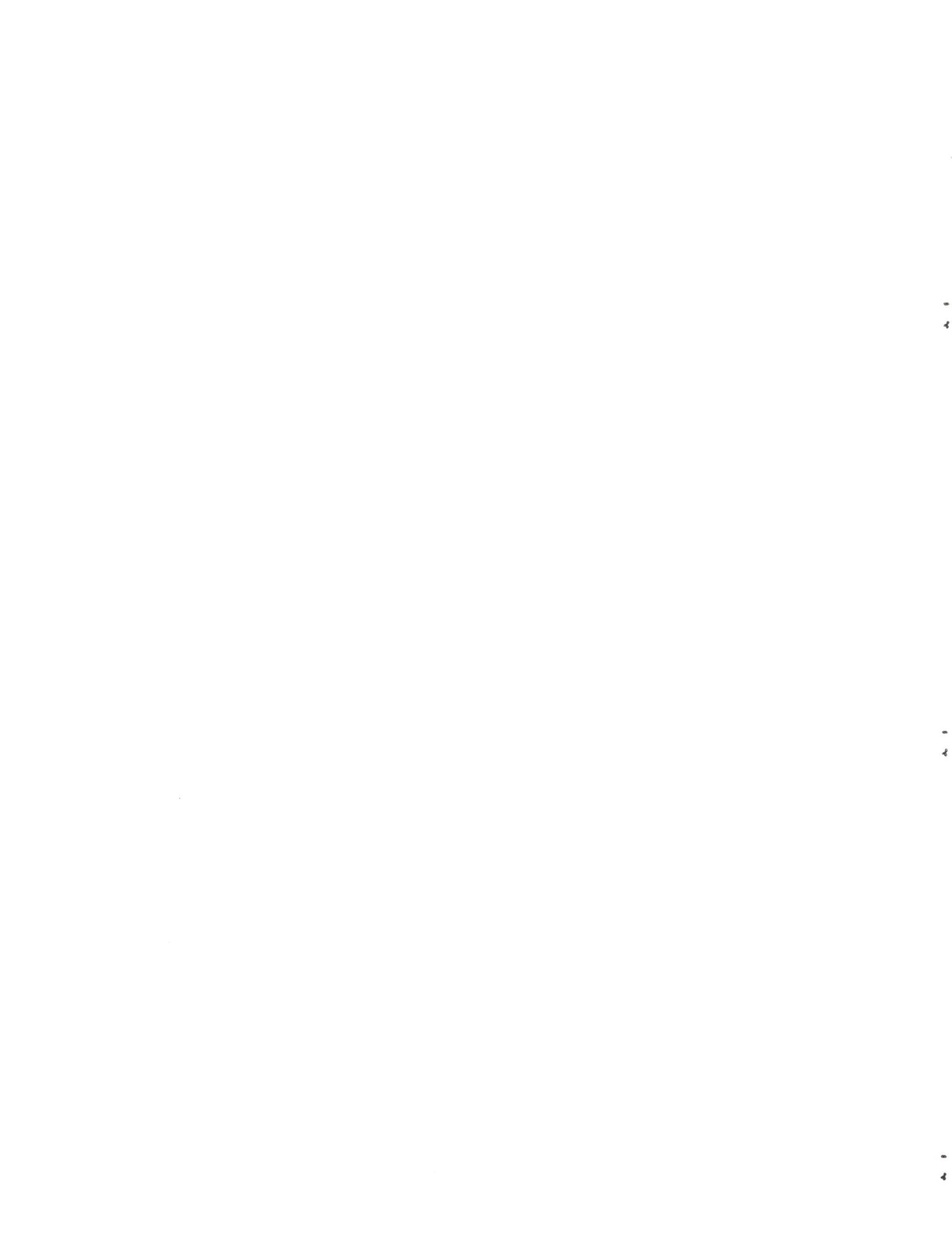
$$-\frac{d\Phi_E}{dt} = -\frac{E_{ox} y_0}{K} [\sin(K_2 z_0 - \omega t) + \sin(\omega t)] \frac{d}{dt}$$

$$= \frac{\omega}{K} E_{ox} y_0 [\cos(K_2 z_0 - \omega t) + \cos(\omega t)]$$

$$= C E_{ox} y_0 [\cos(K_2 z_0 - \omega t) + \cos(\omega t)]$$

$$\frac{1}{c^2} (C E_{ox} y_0 [\cos(K_2 z_0 - \omega t) + \cos(\omega t)]) = \frac{1}{c} E_{ox} y_0 [\cos(K_2 z_0 - \omega t) + \cos(\omega t)]$$

$$\frac{1}{c} E_{ox} y_0 [\cos(K_2 z_0 - \omega t) + \cos(\omega t)] = \phi_B - d\phi_B$$



$$6.2. E = E_{0x}(x,t)\hat{x} + E_{0y}(x,t)\hat{y} + E_{0z}(x,t)\hat{z}$$

$$B = B_{0x}(x,t)\hat{x} + B_{0y}(x,t)\hat{y} + B_{0z}(x,t)\hat{z}$$

Show this
using Maxwell's
eqns.

$$1. \frac{\partial^2 f}{\partial t^2} \rightarrow \frac{\partial^2 E_y(x,t)}{\partial x^2} = k^2 E_y''(x,t), \quad \frac{\partial^2 E_y(x,t)}{\partial y^2} = \frac{\partial^2 E_y(x,t)}{\partial z^2} = 0$$

$$\frac{\partial^2 E_z(x,t)}{\partial x^2} = k^2 E_z''(x,t), \quad \frac{\partial^2 E_z(x,t)}{\partial y^2} = \frac{\partial^2 E_z(x,t)}{\partial z^2} = 0$$

$$\frac{\partial^2 B_y(x,t)}{\partial x^2} = k^2 B_y''(x,t), \quad \frac{\partial^2 B_y(x,t)}{\partial y^2} = \frac{\partial^2 B_y(x,t)}{\partial z^2} = 0$$

$$\frac{\partial^2 B_z(x,t)}{\partial x^2} = k^2 B_z''(x,t), \quad \frac{\partial^2 B_z(x,t)}{\partial y^2} = \frac{\partial^2 B_z(x,t)}{\partial z^2} = 0$$

$$\frac{\partial^2 f}{\partial t^2} \rightarrow \frac{\partial^2 E_y(x,t)}{\partial t^2} = \omega^2 E_y''(x,t) \quad \frac{\partial^2 B_y(x,t)}{\partial t^2} = \omega^2 B_y''(x,t)$$

$$\frac{\partial^2 E_z(x,t)}{\partial t^2} = \omega^2 E_z''(x,t) \quad \frac{\partial^2 B_z(x,t)}{\partial t^2} = \omega^2 B_z''(x,t)$$

$$\frac{\partial^2 E_y(x,t)}{\partial x^2} = E_y''(x,t) = \frac{\omega^2}{k^2} E_y''(x,t) = \frac{1}{c^2} E_y''(x,t)$$

$$\frac{\partial^2 E_y(x,t)}{\partial y^2} = \frac{\partial^2 E_y(x,t)}{\partial z^2} = 0 \rightarrow \omega^2 E_y''(x,t) = 0 \text{ and } \omega^2 E_z''(x,t) = 0$$

Wave is propagating only in x direction

$$\frac{\partial^2 B_z(x,t)}{\partial x^2} = E_z''(x,t) = \frac{\omega^2}{k^2} E_z''(x,t) = \frac{1}{c^2} E_z''(x,t)$$

$$\frac{\partial^2 E_z(x,t)}{\partial y^2} = \frac{\partial^2 E_z(x,t)}{\partial z^2} = 0 \rightarrow \omega^2 E_y''(x,t) = 0 \text{ and } \omega^2 E_z''(x,t) = 0$$

Wave is propagating only in x direction

$$\frac{\partial^2 B_y(x,t)}{\partial x^2} = B_y''(x,t) = \frac{\omega^2}{k^2} B_y''(x,t) = \frac{1}{c^2} B_y''(x,t)$$

$$\frac{\partial^2 B_y(x,t)}{\partial y^2} = \frac{\partial^2 B_y(x,t)}{\partial z^2} = 0 \rightarrow \omega^2 B_y''(x,t) = 0 \text{ and } \omega^2 E_z''(x,t) = 0$$

$$\frac{\partial^2 B_z(x,t)}{\partial x^2} = B_z''(x,t) = \frac{\omega^2}{k^2} B_z''(x,t) = \frac{1}{c^2} B_z''(x,t)$$

$$\frac{\partial^2 B_z(x,t)}{\partial y^2} = \frac{\partial^2 B_z(x,t)}{\partial z^2} = 0 \rightarrow \omega^2 B_z''(x,t) = 0 \text{ and } \omega^2 E_z''(x,t) = 0$$

2. $\frac{\partial^2 E_x(x,t)}{\partial x^2} = \frac{\partial^2 B_x(x,t)}{\partial x^2} = 0$ The wave propagates in the x -direction but does not vary in that direction

$$\frac{\partial^2 E_x(x,t)}{\partial t^2} = \omega^2 E_x''(x,t) \quad \frac{\partial^2 B_x(x,t)}{\partial t^2} = \omega^2 B_x''(x,t)$$

$$\omega^2 E_x''(x,t) = \omega^2 B_x''(x,t) = 0$$

The partial derivatives of E_x and B_x wrt y and z are 0 since the waves do not propagate in that direction. That leaves:

$$E_x''(x,t) = B_x''(x,t) = 0$$

$$3. \nabla^2 E = \nabla^2 \begin{bmatrix} E_x \\ E_y \\ E_z \end{bmatrix} = \begin{bmatrix} \frac{\partial^2 E_x}{\partial x^2} + \frac{\partial^2 E_x}{\partial y^2} + \frac{\partial^2 E_x}{\partial z^2} \\ \frac{\partial^2 E_y}{\partial x^2} + \frac{\partial^2 E_y}{\partial y^2} + \frac{\partial^2 E_y}{\partial z^2} \\ \frac{\partial^2 E_z}{\partial x^2} + \frac{\partial^2 E_z}{\partial y^2} + \frac{\partial^2 E_z}{\partial z^2} \end{bmatrix} = \begin{bmatrix} 0 + 0 + 0 \\ K^2 E_y''(x,t) + 0 + 0 \\ K^2 E_z''(x,t) + 0 + 0 \end{bmatrix}$$

$$\frac{1}{c^2} \frac{\partial^2 E}{\partial t^2} = \frac{1}{c^2} \begin{bmatrix} 0 \\ \omega^2 E_y''(x,t) \\ \omega^2 E_z''(x,t) \end{bmatrix} \rightarrow \begin{bmatrix} E_x \\ E_y \\ E_z \end{bmatrix} = \frac{1}{c^2} \begin{bmatrix} 0 \\ \omega^2 K^2 E_y''(x,t) \\ \omega^2 K^2 E_z''(x,t) \end{bmatrix} = \frac{1}{c^2} \begin{bmatrix} 0 \\ c^2 E_y''(x,t) \\ c^2 E_z''(x,t) \end{bmatrix}$$

$$\nabla^2 B = \nabla^2 \begin{bmatrix} B_x \\ B_y \\ B_z \end{bmatrix} = \begin{bmatrix} \frac{\partial^2 B_x}{\partial x^2} + \frac{\partial^2 B_x}{\partial y^2} + \frac{\partial^2 B_x}{\partial z^2} \\ \frac{\partial^2 B_y}{\partial x^2} + \frac{\partial^2 B_y}{\partial y^2} + \frac{\partial^2 B_y}{\partial z^2} \\ \frac{\partial^2 B_z}{\partial x^2} + \frac{\partial^2 B_z}{\partial y^2} + \frac{\partial^2 B_z}{\partial z^2} \end{bmatrix} = \begin{bmatrix} 0 + 0 + 0 \\ K^2 B_y''(x,t) + 0 + 0 \\ K^2 B_z''(x,t) + 0 + 0 \end{bmatrix}$$

$$\frac{1}{c^2} \frac{\partial^2 B}{\partial t^2} = \frac{1}{c^2} \begin{bmatrix} 0 \\ \omega^2 B_y''(x,t) \\ \omega^2 B_z''(x,t) \end{bmatrix} \rightarrow \begin{bmatrix} B_x \\ B_y \\ B_z \end{bmatrix} = \frac{1}{c^2} \begin{bmatrix} 0 \\ \omega^2 K^2 B_y''(x,t) \\ \omega^2 K^2 B_z''(x,t) \end{bmatrix} = \frac{1}{c^2} \begin{bmatrix} 0 \\ c^2 B_y''(x,t) \\ c^2 B_z''(x,t) \end{bmatrix}$$

6.3.

$$1. E = E_{0x} \cos(k_2 z - \omega t + d_x) \hat{x}$$

$$\nabla^2 E = \nabla^2 \begin{bmatrix} E_x \\ E_y \\ E_z \end{bmatrix} = \begin{bmatrix} 0 + 0 - k_2^2 E_{0x} \cos(k_2 z - \omega t + d_x) \\ 0 + 0 + 0 \\ 0 + 0 + 0 \end{bmatrix}$$

$$= \frac{1}{c^2} \frac{d^2 E(x,t)}{dt^2} = \frac{1}{c^2} \begin{bmatrix} -\omega^2 E_{0x} \cos(k_2 z - \omega t + d_x) \\ 0 \\ 0 \end{bmatrix}$$

$$-k_2^2 E_{0x} \cos(k_2 z - \omega t + d_x) = \frac{1}{c^2} [\omega^2 E_{0x} \cos(k_2 z - \omega t + d_x)] \hat{x}$$

$$E_{0x} \cos(k_2 z - \omega t + d_x) = \frac{1}{c^2} [c^2 E_{0x} \cos(k_2 z - \omega t + d_x)] \hat{x}$$

$$B = B_{0x} \cos(k_2 z - \omega t + d'_x) \hat{x} + B_{0y} \cos(k_2 z - \omega t + d'_y) \hat{y}$$

$$\nabla^2 B = \nabla^2 \begin{bmatrix} B_x \\ B_y \\ B_z \end{bmatrix} = \begin{bmatrix} 0 + 0 - k_2^2 B_{0x} \cos(k_2 z - \omega t + d'_x) \\ 0 + 0 - k_2^2 B_{0x} \cos(k_2 z - \omega t + d'_y) \\ 0 + 0 + 0 \end{bmatrix}$$

$$\frac{1}{c^2} \frac{d^2 B(x,t)}{dt^2} = \frac{1}{c^2} \begin{bmatrix} -\omega^2 B_{0x} \cos(k_2 z - \omega t + d'_x) \\ -\omega^2 B_{0x} \cos(k_2 z - \omega t + d'_y) \\ 0 \end{bmatrix}$$

$$-k_2^2 B_{0x} \cos(k_2 z - \omega t + d'_x) = \frac{1}{c^2} [\omega^2 B_{0x} \cos(k_2 z - \omega t + d'_x)] \hat{x}$$

$$B_{0x} \cos(k_2 z - \omega t + d'_x) = \frac{1}{c^2} [c^2 B_{0x} \cos(k_2 z - \omega t + d'_x)] \hat{x}$$

$$-k_2^2 B_{0y} \cos(k_2 z - \omega t + d'_y) = \frac{1}{c^2} [-\omega^2 B_{0y} \cos(k_2 z - \omega t + d'_y)] \hat{y}$$

$$B_{0y} \cos(k_2 z - \omega t + d'_y) = \frac{1}{c^2} [c^2 B_{0y} \cos(k_2 z - \omega t + d'_y)] \hat{y}$$

$$2. \nabla \times E = -\frac{\partial B}{\partial t}$$

$$\nabla \times E = \left(\frac{\partial E_z}{\partial y} - \frac{\partial E_y}{\partial z} \right) \hat{x} + \left(\frac{\partial E_x}{\partial z} - \frac{\partial E_z}{\partial x} \right) \hat{y} + \left(\frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} \right) \hat{z}$$

$$\nabla \times E = \frac{\partial E_x}{\partial z} \hat{y} = K_z E_{0x} \sin(K_z z - \omega t + d_x) \hat{y}$$

$$\begin{aligned} -\frac{\partial B}{\partial t} &= -B_{0x} \cos(K_z z - \omega t + d_x) \hat{x} \frac{\partial}{\partial t} - B_{0y} \cos(K_z z - \omega t + d_y) \hat{y} \frac{\partial}{\partial t} \\ &= w B_{0x} \sin(K_z z - \omega t + d_x) \hat{x} + w B_{0y} \sin(K_z z - \omega t + d_y) \hat{y} \end{aligned}$$

$$d_x = \omega t, \quad B_{0x} = 0, \quad d_y = d_y'$$

$$E_{0x} \sin(K_z z - \omega t + d_x) = \frac{1}{c} \left[\frac{w}{K} B_{0y} \sin(K_z z - \omega t + d_y') \right] \hat{y}$$

$$3. E = E_{0y} \cos(K_z z - \omega t + d_y) \hat{y}$$

state
prop.
const.

$$\nabla \times E = -\frac{\partial E_y}{\partial z} \hat{x} = -K_z E_{0y} \sin(K_z z - \omega t + d_y) \hat{x}$$

$$-\frac{\partial B}{\partial t} = w B_{0x} \sin(K_z z - \omega t + d_x) \hat{x} + w B_{0y} \sin(K_z z - \omega t + d_y) \hat{y}$$

$$d_x = \omega t, \quad B_{0y} = 0, \quad d_y = d_y', \quad c = |w/K|, \quad E_{0x} \propto B_{0y}$$

$$E_{0y} \sin(K_z z - \omega t + d_y) = \frac{1}{c} \left[\frac{w}{K} B_{0y} \sin(K_z z - \omega t + d_y') \right] \hat{x}$$

$$4. B = \frac{1}{c} \hat{K} \times E = \begin{matrix} K_x & K_y & K_z \\ \hline E_x & E_y & E_z \end{matrix}$$

$$\frac{1}{c} [(K_y E_z - K_z E_y) \hat{x} - (K_x E_z - K_z E_x) \hat{y} + (K_x E_y - K_y E_x) \hat{z}]$$

$$\text{For } E = E_{0x} \cos(K_z z - \omega t + d_x) \hat{x}$$

$$B = \frac{1}{c} [K_z E_x \hat{y} - K_y E_x \hat{z}] \quad K_y = 0 \text{ so } B = \frac{1}{c} [K_z E_x \hat{y}] = \frac{1}{c} K_z E_{0x} \cos(K_z z - \omega t + d_x) \hat{y}$$

$$\text{For } E = E_{0y} \cos(K_z z - \omega t + d_y) \hat{y}$$

$$B = \frac{1}{c} [-K_z E_y \hat{x} + K_x E_y \hat{z}] \quad K_x = 0 \text{ so } B = \frac{1}{c} [-K_z E_y \hat{x}] = -\frac{1}{c} K_z E_{0y} \cos(K_z z - \omega t + d_y) \hat{x}$$

$$6.4 \quad \nabla \times E = -\frac{\partial B}{\partial t}$$

$$\nabla \times E = \operatorname{Re} [e^{-i\omega t} \nabla \tilde{E} e^{ik_r r}] = \operatorname{Re} [e^{-i\omega t} (ik_y \tilde{E}_2 e^{ik_r r} - \tilde{E}_y (ik_2) e^{ik_r r}) \hat{x}]$$

$$-\frac{\partial B}{\partial t} = -\operatorname{Re} [\tilde{B}_x (-i\omega) e^{-i\omega t} e^{ik_r r}] \hat{x}$$

$$\nabla \times E = -\frac{\partial B}{\partial t} = \operatorname{Re} [e^{-i\omega t} (ik_y \tilde{E}_2 e^{ik_r r} - \tilde{E}_y (ik_2) e^{ik_r r}) \hat{x}] = \operatorname{Re} [\tilde{B}_x (-i\omega) e^{-i\omega t} e^{ik_r r} \hat{x}]$$

$$= \operatorname{Re} [(\tilde{E}_2 k_y - \tilde{E}_y k_2) \hat{x}] = \tilde{B}_x (\omega) \hat{x}$$

$$= \operatorname{Re} [\frac{\hat{K} \times \tilde{E}}{c} = \tilde{B}]$$

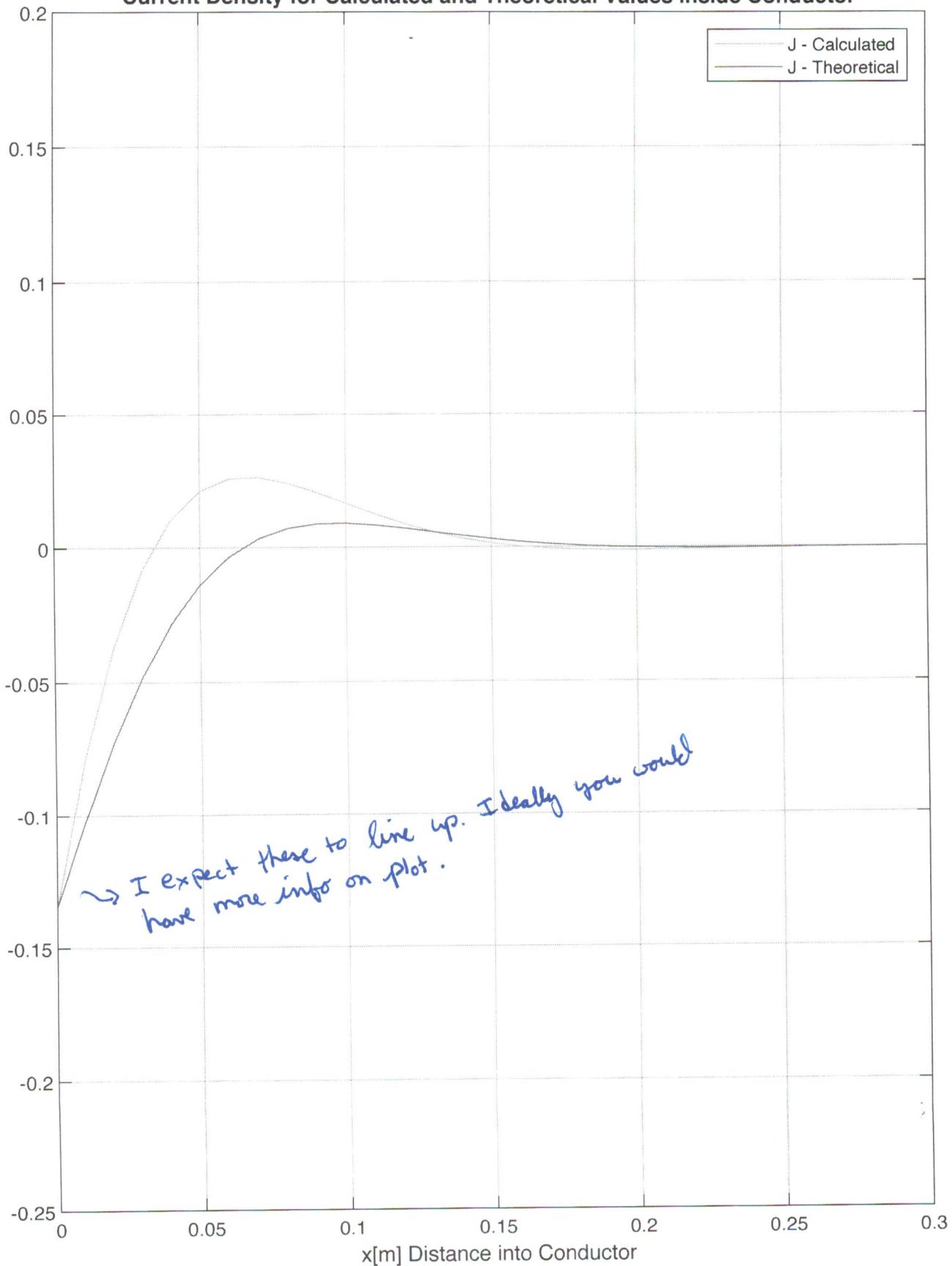
$\operatorname{Re} [\frac{\hat{K} \times \tilde{E}}{c} = \tilde{B}]$ and $\operatorname{Im} [\frac{\hat{K} \times \tilde{E}}{c} = \tilde{B}]$ are in phase

so Re and Im are dropped

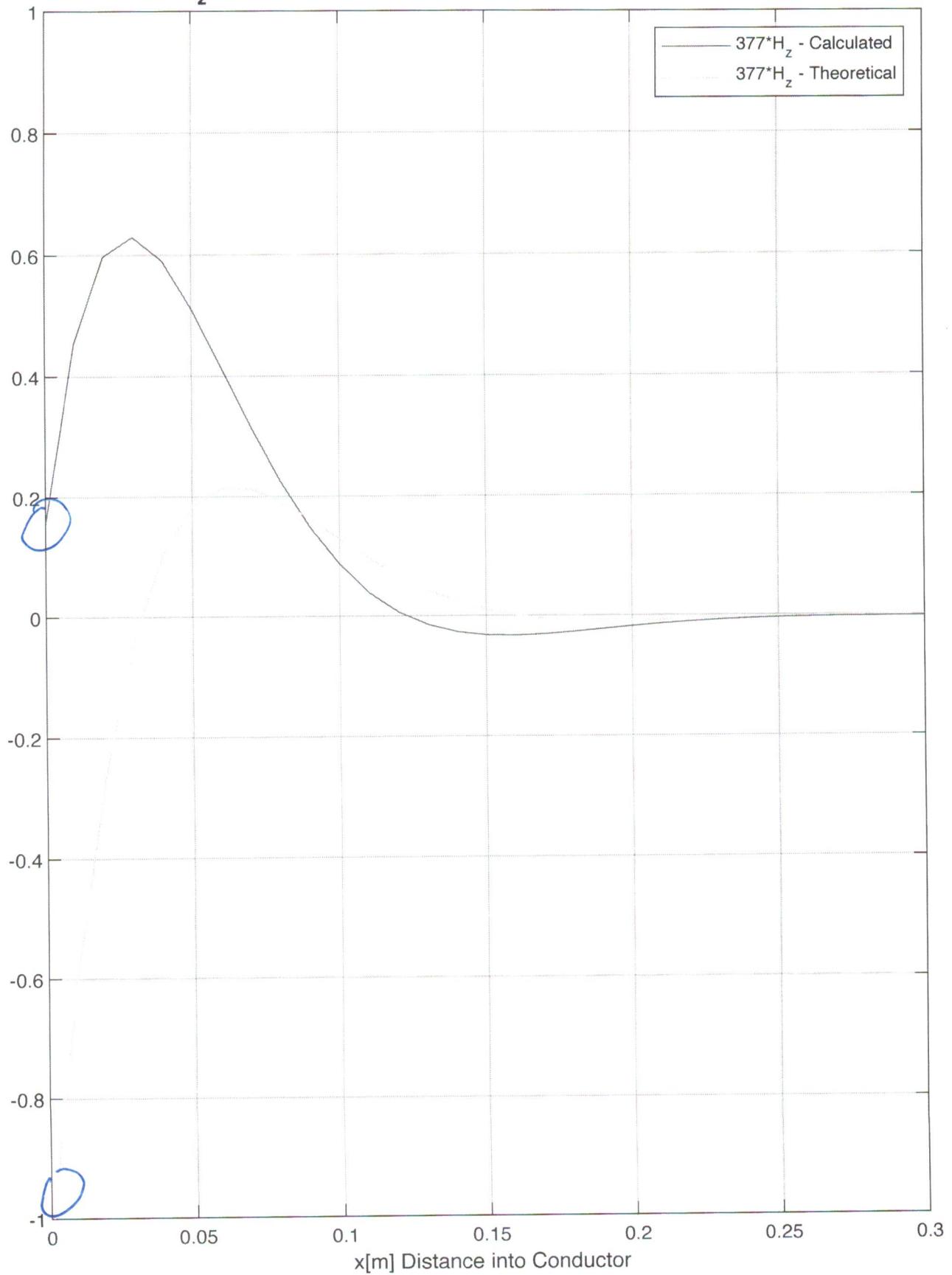
$$B = \frac{1}{c} \hat{K} \times E \text{ and } \tilde{B} = \frac{1}{c} \hat{K} \times \tilde{E}$$

What does "in phase" mean in this context?

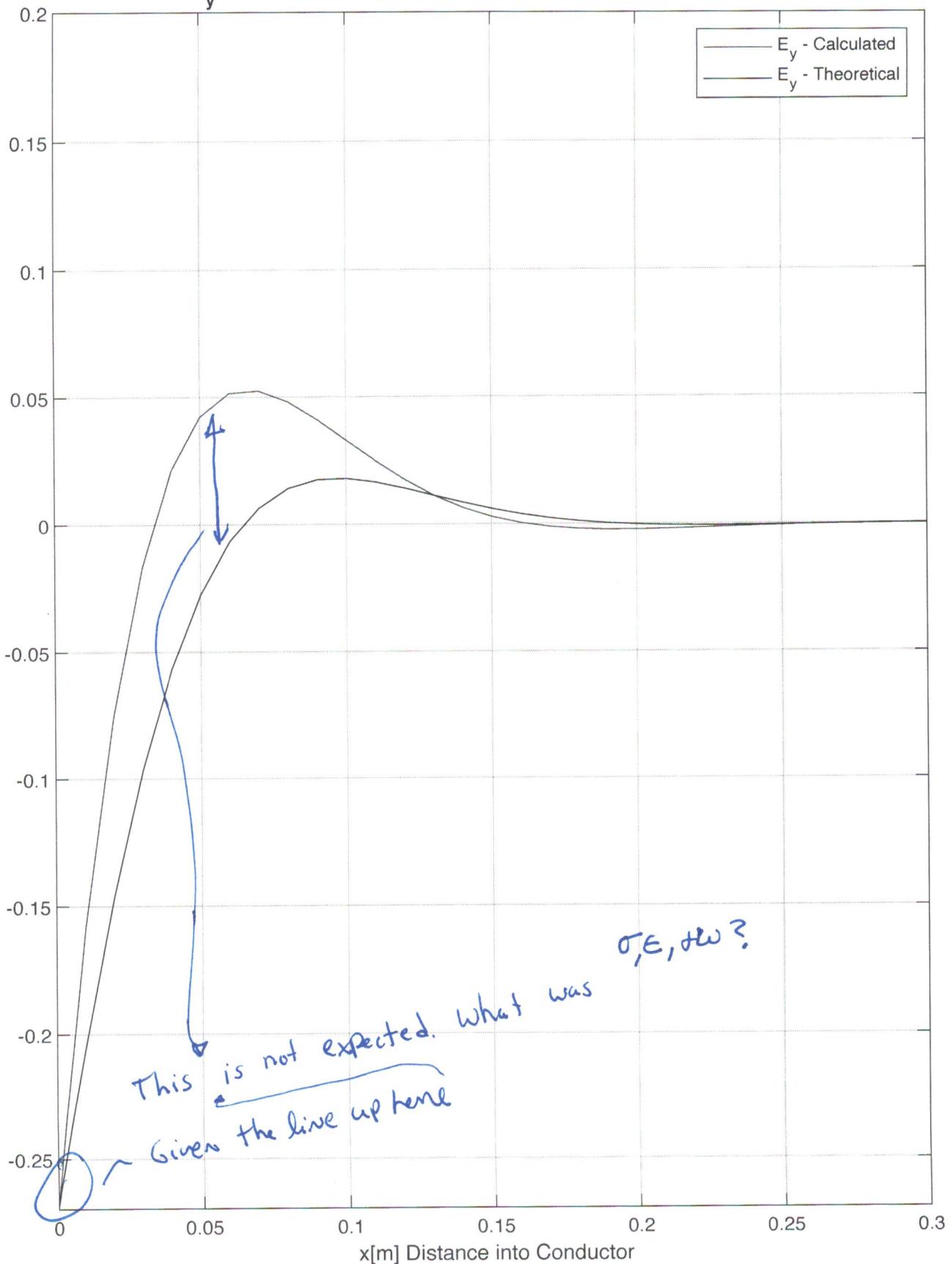
Current Density for Calculated and Theoretical Values Inside Conductor



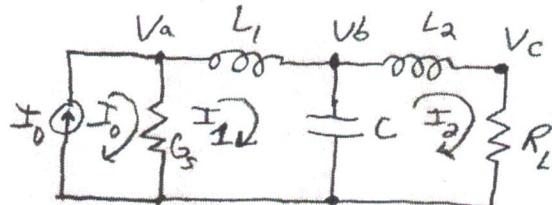
H_z for Calculated and Theoretical Values Inside Conductor



E_y for Calculated and Theoretical Values Inside Conductor



4.3b.



$$L_1 \frac{dI_1}{dt} + \frac{1}{C} \int (I_1 - I_2) dt + \frac{(I_1 - I_0)}{G_s} = 0$$

$$L_2 \frac{dI_2}{dt} + I_2 R_L + \frac{1}{C} \int (I_2 - I_1) dt = 0$$

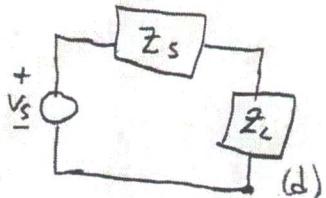
Node V_a: $I_0 = V_a G_s + \frac{1}{L_1} \int (V_a - V_b) dt \rightarrow I_0 - V_a G_s - \frac{1}{L_1} \int (V_a - V_b) dt = 0$

Node V_b: $\frac{1}{L_1} \int (V_b - V_a) dt + C \frac{dV_b}{dt} + \frac{1}{L_2} \int (V_b - V_c) dt = 0$

Node V_c: $\frac{V_c}{R_L} + \frac{1}{L_2} \int (V_c - V_b) dt = 0$

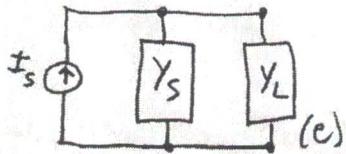
Ideally you would show or comment about result being same as V source system. (point of problem)

4.3c.



$$I_L = \frac{V_s}{Z_s + Z_L} \quad \text{current through the load impedance}$$

$$V_L = V_s \left(\frac{Z_L}{Z_s + Z_L} \right)$$



$$V_L = \frac{I_s}{Y_s + Y_L}$$

$$I_s = V_s Y_s, \quad Y_s = Z_s^{-1} \rightarrow I_s = \frac{V_s}{Z_s}$$

$$V_L = \frac{I_s}{Y_s + Y_L} \rightarrow \frac{\left(V_s / Z_s \right)}{\left(Z_s^{-1} \right) + \left(Z_L^{-1} \right)} = V_s \left(\frac{Z_L}{Z_s + Z_L} \right)$$

Current through load admittance:

$$I_L = V_L Y_L = V_s \left(\frac{Z_L}{Z_s + Z_L} \right) \left(Z_L^{-1} \right) = \frac{V_s}{Z_s + Z_L}$$

I_L is the same for the current flowing through the load impedance and the current through the load admittance.

V_L is also the same for the voltage across the load impedance and the voltage across the load admittance.

4.3 d. For the current in the circuit:

$$I = \frac{V_s}{Z_s + Z_L} \quad \text{where } Z_s = R_s + jX_s \text{ and } Z_L = R_L + jX_L$$

$$I = \frac{V_s}{(R_s + jX_s) + (R_L + jX_L)} = \frac{V_s}{(R_s + R_L) + j(X_s + X_L)}$$

For power to the load, $W_L = \frac{R_L}{2} II^* \rightarrow$ can you derive?

$$II^* = \left[\frac{V_s}{(R_s + R_L) + j(X_s + X_L)} \right]^* = \left[\frac{V_s}{(R_s + R_L) + j(X_s + X_L)} \right] \left[\frac{(R_s + R_L) - j(X_s + X_L)}{(R_s + R_L) - j(X_s + X_L)} \right]$$

$$II^* = \frac{V_s [(R_s + R_L) - j(X_s + X_L)]}{(R_s + R_L)^2 + (X_s + X_L)^2}$$

$$W_L = \frac{R_L}{2} \left[\frac{V_s}{(R_s + R_L) + j(X_s + X_L)} \right] \left[\frac{V_s [(R_s + R_L) - j(X_s + X_L)]}{(R_s + R_L)^2 + (X_s + X_L)^2} \right]$$

$$= \frac{R_L}{2} \left[\frac{V_s}{(R_s + R_L)^2 + (X_s + X_L)^2} \right]$$

For max power to load: $\frac{\partial W_L}{\partial X_L} = 0$ and $\frac{\partial W_L}{\partial R_L} = 0$ + surface

$$\frac{\partial W_L}{\partial X_L} = \frac{\partial}{\partial X_L} \left(\frac{R_L}{2} \left[\frac{V_s}{(R_s + R_L)^2 + (X_s + X_L)^2} \right] \right) = 0$$

$$= -R_L V_s (X_s + X_L) \frac{1}{[(R_s + R_L)^2 + (X_s + X_L)^2]^2} \rightarrow -R_L V_s (X_s + X_L) = 0, \quad X_L = -X_s$$

$W(R_L^*, X_L^*)$ is concave down.

$$\frac{\partial W_L}{\partial R_L} = \frac{\partial}{\partial R_L} \left(\frac{R_L}{2} \left[\frac{V_s}{(R_s + R_L)^2 + (X_s + X_L)^2} \right] \right) = 0$$

$$= \frac{V_s}{2} \left[\frac{-2R_L (R_s + R_L) + [(R_s + R_L)^2 + (X_s + X_L)^2]}{[(R_s + R_L)^2 + (X_s + X_L)^2]^2} \right] = 0$$

$$-2R_L(R_S + R_L) + [(R_S + R_L)^2 + (X_S + X_L)^2] = 0$$

$$\text{As } X_L = -X_S,$$

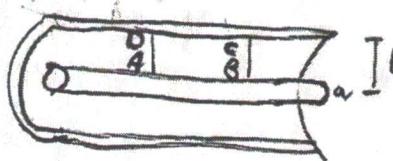
$$-2R_L(R_S + R_L) + [(R_S + R_L)^2 + 0] = 0$$

$$-2R_L R_S - 2R_L^2 + R_S^2 + R_L^2 + 2R_L R_S = R_S^2 - R_L^2 = 0, \quad R_L = R_S$$

Max power to the load when $R_L = R_S$ and $X_L = -X_S$

$$Z_L = R_L + jX_L = R_S + j(-X_S) = R_S - jX_S = (R_S + jX_S)^* = Z_S^*$$

4.6e.



$$\oint_{ABED} E \cdot d\ell = -j\omega \int_S B \cdot dS$$

$$\int_S B \cdot dS = IL_e dz$$

$$\oint_{ABCD} E \cdot d\ell = -j\omega I L_e dz$$

inner surface of the outer conductor

$$\text{for } E_Z = I(Z_{\text{inner}})_{\text{outer}}$$

$$E_Z = I \left(\frac{R_{sb}}{2\pi b} + \frac{j\omega L_{ib}}{2\pi b} \right)$$

b = radius of outer conductor

R_{sb} = resistance

L_{ib} = inductance

$$\text{why this eqn? usually } R = \frac{L}{A}$$

$$\text{for } E_Z = -I(Z_{\text{inner}})_{\text{inner}} \quad \text{outer surface of inner conductor}$$

$$E_Z = -I \left(\frac{R_{sa}}{2\pi a} + \frac{j\omega L_{ia}}{2\pi a} \right)$$

a = radius of inner conductor

R_{sa} = resistance

L_{ia} = inductance

$$\oint_{ABCD} E \cdot d\ell = -j\omega I L_e dz$$

$$I \left(\frac{R_{sa}}{2\pi a} + \frac{j\omega L_{ia}}{2\pi a} \right) dz + V_{CB} + I \left(\frac{R_{sb}}{2\pi b} + \frac{j\omega L_{ib}}{2\pi b} \right) dz - V_{DA} = -j\omega I L_e dz$$

$$V_{DA} - V_{CB} = I \left(j\omega L_e + \frac{R_{sa}}{2\pi a} + \frac{j\omega L_{ia}}{2\pi a} + \frac{R_{sb}}{2\pi b} + \frac{j\omega L_{ib}}{2\pi b} \right) dz$$

$$V_{DA} - V_{CB} = \cancel{D} \times$$

$$= \cancel{dV}$$

$$\frac{dV}{dz} = (\quad)$$

For current from C to D,

$$I_C - I_D = j\omega(C_{D2})V$$

$$C = \frac{2\pi\epsilon}{h(b/a)} \frac{f}{m}$$

$$I_C - I_D = j\omega \left(\frac{2\pi\epsilon d_2}{h(b/a)} \right) V$$

matches capacitance shown in
Fig. P4.6e