

3.1.1.  $\frac{d}{dx} \left( \frac{d\psi}{dx} \right) = 0$

$\left( \frac{d\psi}{dx} \right) = A \rightarrow \psi(x) = Ax + B$

Please provide a few words that justifies each step. Imagine if you were explaining this to someone and they asked "why" for each step.

At  $x=0$ ,  $\psi=0 \rightarrow 0=0+B \rightarrow B=0$

At  $x=d$ ,  $\psi=V_0 \rightarrow V_0=Ad+0 \rightarrow A=V_0/d$

$\psi = (V_0/d)x$

$\Delta\psi = - \int_a^b E \cdot d\ell = - \frac{d\psi}{dx} a_x = - \frac{V_0}{d} a_x$

$Q = \int \rho_s dS = \int \epsilon_0 E \cdot a_n = \int \epsilon_0 \left( -\frac{V_0}{d} a_x \right) dS$

Here it looks like you are taking a dot product between two scalars.

$a_n = a_x$  on lower plate  $Q = - \frac{\epsilon_0 V_0}{d} S$

$a_n = -a_x$  on top plate  $Q = \frac{\epsilon_0 V_0}{d} S$

$C = \frac{|Q|}{V_0} = \frac{\epsilon_0 S}{d}$

You have only one capacitance using a hybrid of both methods. The point of the problem was to show how two different approaches can be used to find C and they are the same.

3.1.2.  $\psi = \psi(s)$ ,  $\nabla^2 \psi = 0$

$\nabla^2 \psi = \frac{1}{s} \frac{d}{ds} \left( s \frac{d\psi}{ds} \right) = 0$

$s \frac{d\psi}{ds} = A \rightarrow \frac{d\psi}{ds} = \frac{A}{s} \rightarrow \psi = A \ln(s) + B$

$\psi(s=a)=0 \rightarrow 0=A \ln(a)+B \rightarrow B=-A \ln(a)$

$\psi(s=b)=V_0 \rightarrow V_0=A \ln(b)+B=A \ln(b)-A \ln(a)=A \ln(b/a) \rightarrow A = \frac{V_0}{\ln(b/a)}$

$\psi = \frac{V_0}{\ln(b/a)} \ln(s) + (-A \ln(a)) = \frac{V_0}{\ln(b/a)} (\ln(s) - \ln(a)) = \frac{V_0}{\ln(b/a)} \ln(s/a)$

$E = -\frac{\partial \psi}{\partial s} a_s = -\frac{A}{s} a_s = -\frac{V_0}{s \ln(b/a)} a_s$

$Q = \int \epsilon_0 E \cdot dS = \int_0^{2\pi L} \int_0^{2\pi L} \frac{V_0 \epsilon_0 s}{s \ln(b/a)} dz d\phi = \frac{2\pi L \epsilon_0 V_0}{\ln(b/a)}$

$C = \frac{Q}{V_0} = \frac{2\pi L \epsilon_0}{\ln(b/a)} \rightarrow \frac{C}{L} = \frac{2\pi \epsilon_0}{\ln(b/a)}$



$$3.1.3. \quad \nabla^2 \psi = \frac{1}{r^2} \frac{d}{dr} \left( r^2 \frac{d\psi}{dr} \right) = 0$$

$$\frac{d}{dr} \left( r^2 \frac{d\psi}{dr} \right) = 0 \rightarrow r^2 \frac{d\psi}{dr} = A \rightarrow \frac{d\psi}{dr} = \frac{A}{r^2}$$

$$\psi = -\frac{A}{r} + B$$

$$\psi(r=b) = 0 \rightarrow 0 = -\frac{A}{b} + B \rightarrow B = \frac{A}{b}$$

$$\psi = -\frac{A}{r} + \frac{A}{b} = A \left( \frac{1}{b} - \frac{1}{r} \right)$$

$$\psi(r=a) = V_0 \rightarrow V_0 = A \left( \frac{1}{b} - \frac{1}{a} \right) \rightarrow A = \frac{V_0}{\left( \frac{1}{b} - \frac{1}{a} \right)}$$

$$\psi = \frac{V_0 \left( \frac{1}{r} - \frac{1}{b} \right)}{\left( \frac{1}{a} - \frac{1}{b} \right)}$$

$$E = -\frac{d\psi}{dr} a_r = -\frac{A}{r^2} a_r = \frac{V_0}{r^2 \left( \frac{1}{a} - \frac{1}{b} \right)} a_r$$

$$Q = \int \epsilon E \cdot dS = \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} \frac{\epsilon_0 \epsilon_r V_0}{r^2 \left( \frac{1}{a} - \frac{1}{b} \right)} r^2 \sin \theta d\phi d\theta = \frac{4\pi \epsilon_0 \epsilon_r V_0}{\left( \frac{1}{a} - \frac{1}{b} \right)}$$

$$C = \frac{Q}{V_0} = \frac{4\pi \epsilon_0 \epsilon_r}{\left( \frac{1}{a} - \frac{1}{b} \right)}$$

Why is epsilon\_r in this problem but not the other problems?

3.1.4.