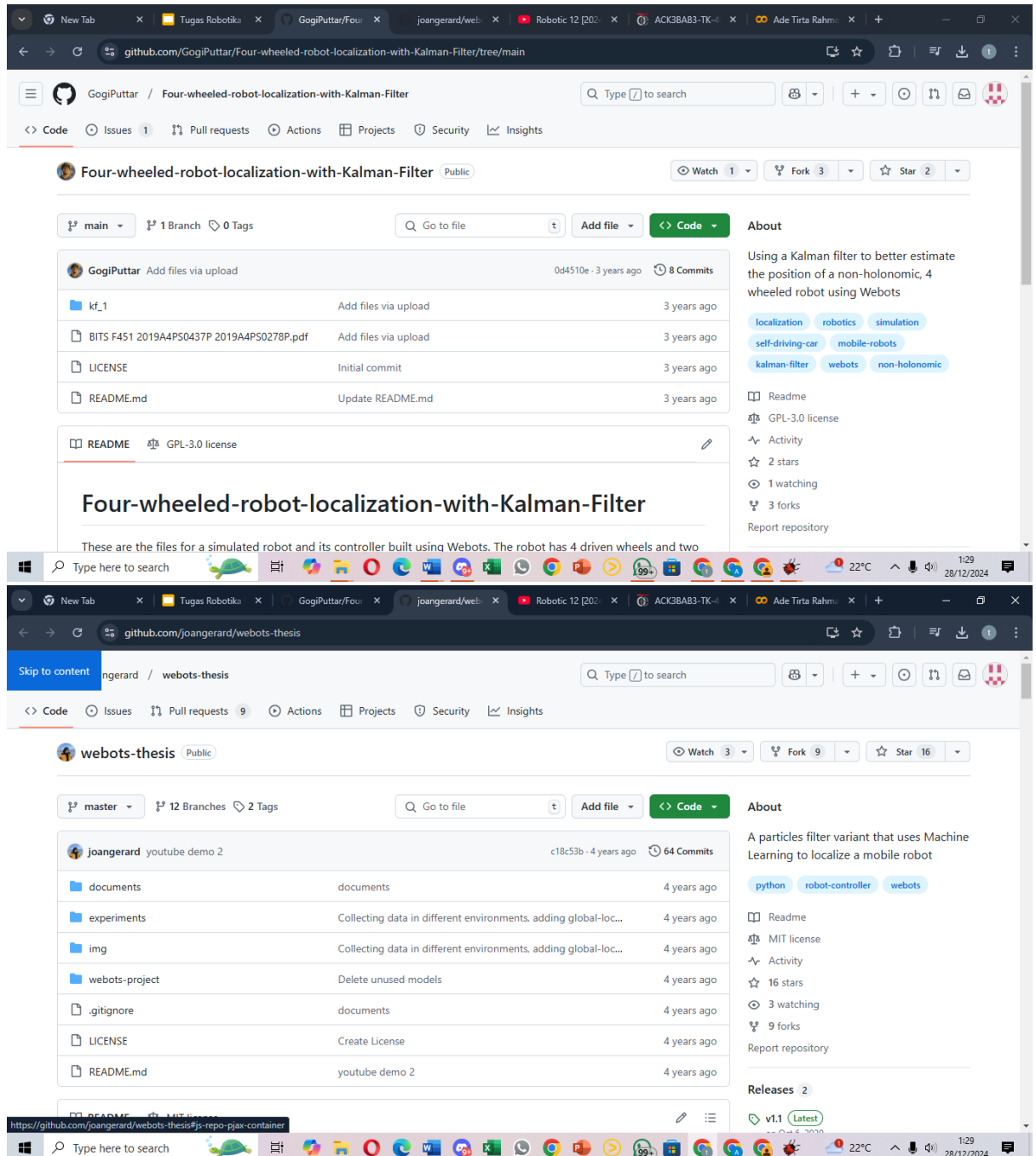


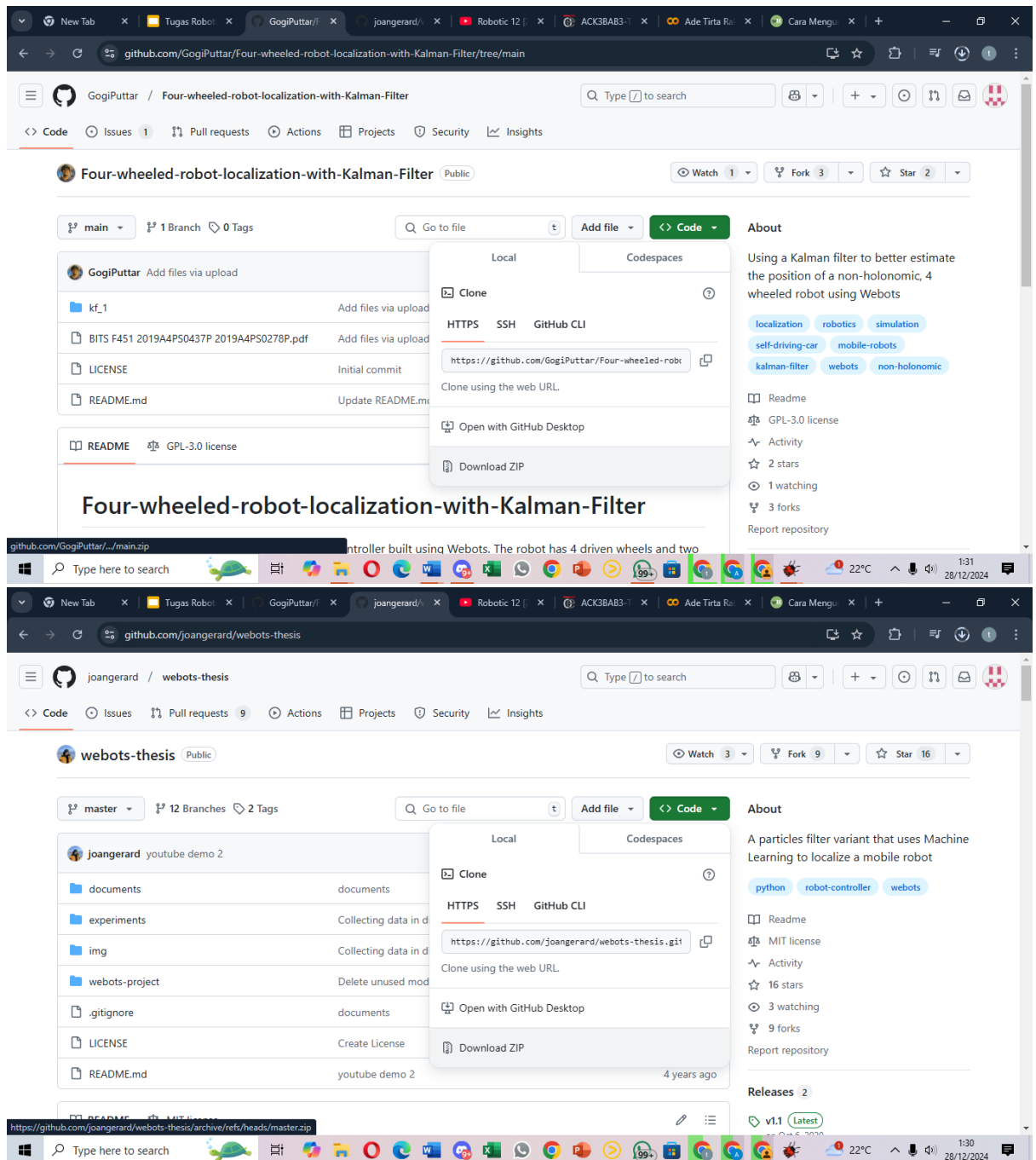
Ade Tirta Rahmat Hidayat – 1103203212 – TK45G06

## Robot Positioning Estimation using ML Techniques and Four-Wheeled Robot Localization with Kalman Filter

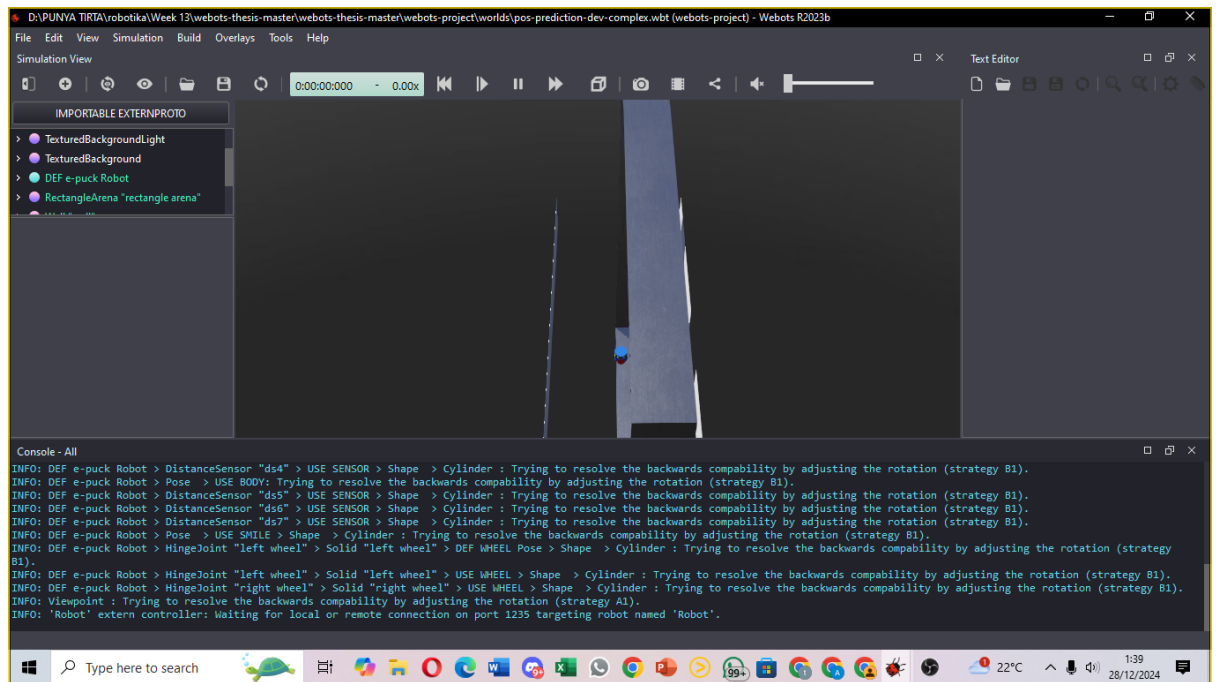
1. Buka file github yang sudah disediakan



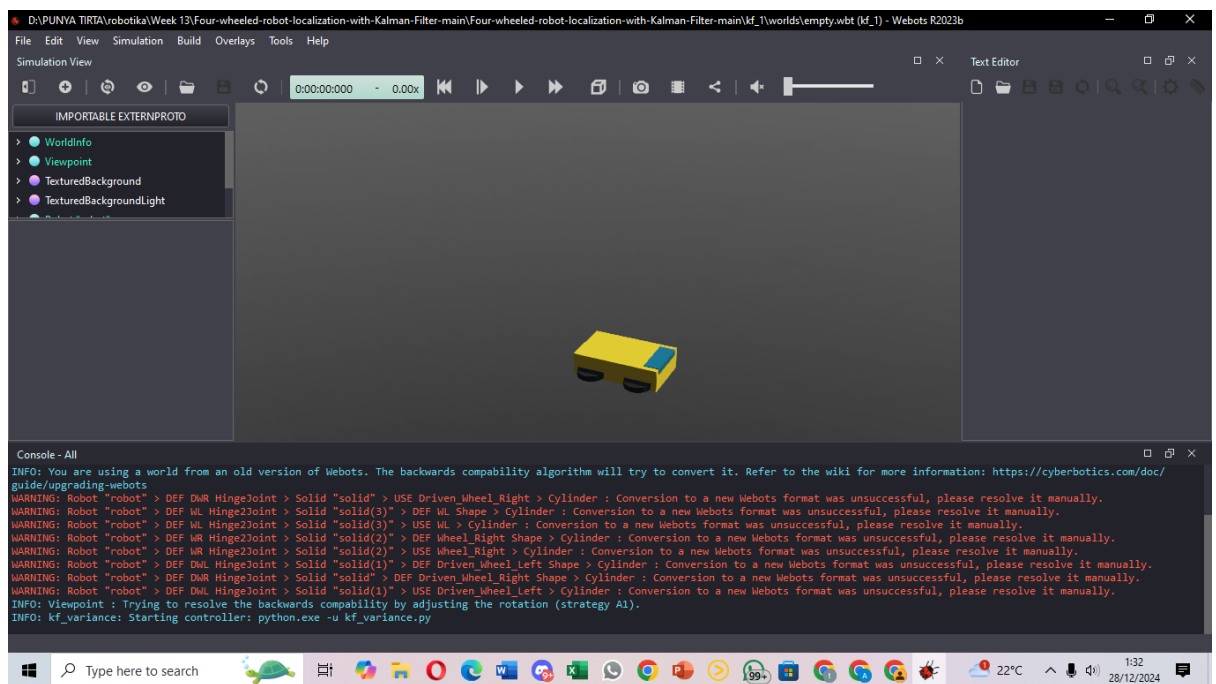
2. Unduh file controllers dan world webotsnya.



3. Open file world pada Webots.  
Robot Positioning:



## Four-Wheeled:



4. Di sini saya mengalami kendala seperti ini:

Four Wheeled: Ketika saya menjalankan eksperimen webots tersebut, robot mobil menghilang.

File dan video record:

<https://drive.google.com/drive/folders/1EJ9qe7ausfWDmLNp5fbFWTLEhJQCuzX2?usp=sharing>