

WHAT DO KNOTS HAVE TO DO WITH ALGEBRA?

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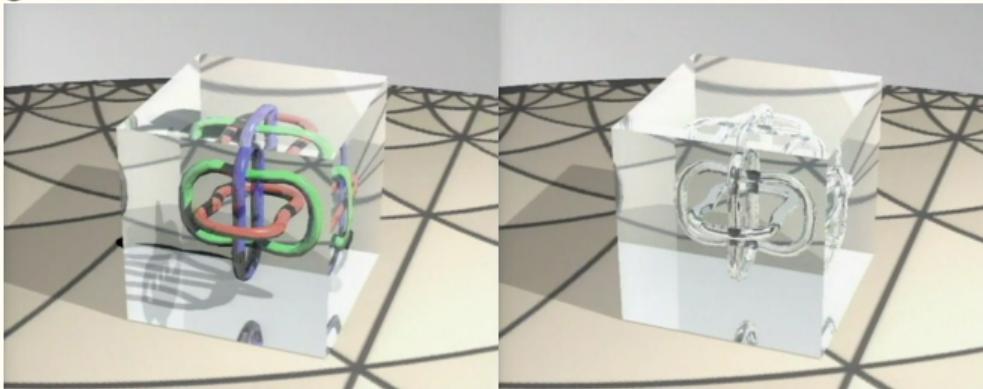
NZMS COLLOQUIUM, WAIKATO UNIVERSITY
26–28 NOV. 2025



László Moholy-Nagy, *Kinetisches Konstruktives System* (1922)
Bauhaus-Archiv Berlin

KNOTS

If k is a knot, then $\mathbb{S}^3 \setminus k$ is a smooth oriented 3-manifold.



Gunn and Maxwell, *Not Knot*: <https://www.youtube.com/watch?v=4aN6vX7qXPQ>
 $\mathbb{S}^3 \setminus k$ can be described combinatorially by a **knot diagram**.

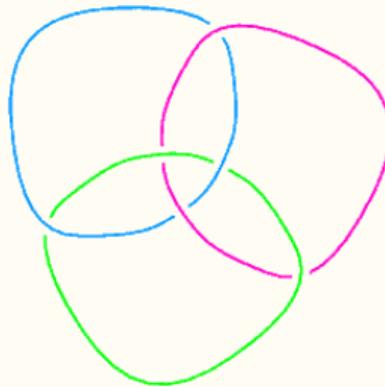
Why are these manifolds interesting to topologists?

Gordon/Luecke (1989)

Knots with one component are determined by their complements up to homeomorphism.

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<https://katlas.org/wiki/L6a4>

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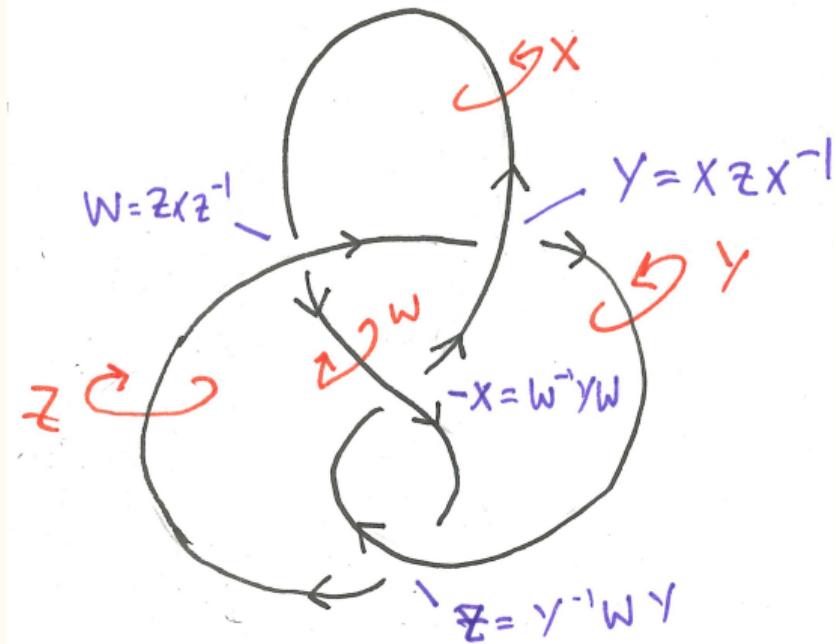
KNOTS: GROUPS FROM DIAGRAMS

Knot complements can be described combinatorially by diagrams.

Wirtinger (c.1905)

There is an algorithm that sends a diagram of a knot k to a presentation for $\pi_1(\mathbb{S}^3 \setminus k)$, where all generators are conjugate:

generators	relations
diagram arcs	crossings



$$\langle X, Y, Z, W : X^{-1}W^{-1}YW, Y^{-1}XZX^{-1}, Z^{-1}Y^{-1}WY, W^{-1}ZXZ^{-1} \rangle$$

REPRESENTATIONS OF KNOT GROUPS TO $\text{PSL}(2, \mathbb{F}_p)$

To understand a group G , we look at its representations.

Theorem (Riley, *Math. Comp.* (1971))

For any knot k , the surjective representations $\pi_1(\mathbb{S}^3 \setminus k) \rightarrow \text{PSL}(2, \mathbb{F}_p)$ (p prime) where every Wirtinger generator is order¹ p can be classified into conjugacy classes by performing at most

$$\left(\frac{p-1}{2}\right)^{n-1} \frac{(p+1)^{n-1} - 1}{p}$$

experiments, where n is the minimal number of bridges for a diagram of k .

The method of proof is purely combinatorial, relying only on information about the types of relators that can appear in a Wirtinger presentation.

¹The condition on the order is purely for simplification and there are more general results in the same paper.

REPRESENTATIONS OF KNOT GROUPS TO $\text{PSL}(2, \mathbb{C})$

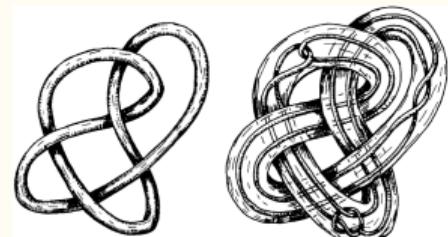
Theorem (Thurston, c. 1978)

If k is a link then $\mathbb{S}^3 \setminus k$ admits a Riemann metric of constant sectional curvature -1 if and only if it has no:

- embedded essential spheres;
- embedded essential discs;
- embedded essential tori;
- embedded essential annuli.

The hyperbolic structure on $\mathbb{S}^3 \setminus k$ induces a faithful, discrete representation

$$\pi_1(\mathbb{S}^3 \setminus k) \rightarrow \text{Isom}^+(\mathbb{H}^3) = \text{Conf}(\mathbb{S}^2) = \text{PSL}(2, \mathbb{C}).$$



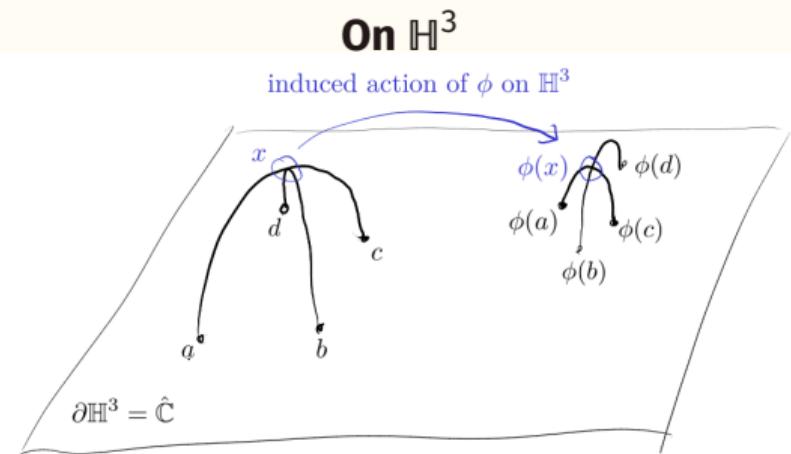
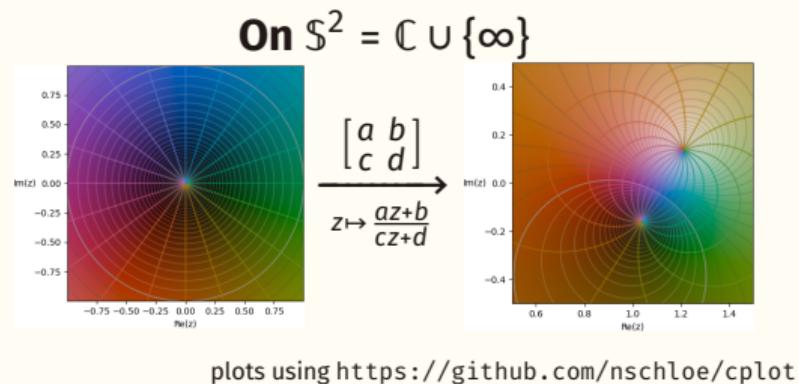
Embedded torus



Embedded annulus

Thurston, Bull. AMS (1982)
images by George Francis

PSL(2, \mathbb{C})-ACTIONS



E., J. Schillewaert, G.J. Martin, 2021-22 MATRIX annals, Springer (2024).

Meaning of traces. If $g \in \pi_1(\mathbb{S}^3 \setminus k)$ is homotopic to a loop on a component of k (e.g. a meridian or longitude), then tr^2 of the image is 4. The image of every other element has a positive minimal translation length in \mathbb{H}^3 and corresponds to a geodesic loop of positive length, $\text{tr}^2 \notin [0, 4]$.

3-elements. Let E_3 be the one which contains t . Then c_1 is transformed into a segment by the deformation

$$S \rightarrow S + (E_3).$$

In this way all the circuits in $S \cdot E_3$ can be eliminated.

When the circuits have been eliminated there will be at least one segment in $S \cdot E_3$, say u , which, together with a segment of m , bounds a 2-element C_2 , on E_3 , containing no other component of S . If E_3 is defined as before, with $N(C_2, M)$ and $N(u, S)$ taking the place of $N(t, M)$ and $N(p, S)$, the segment u is eliminated from $S \cdot E_3$ by the deformation

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Reiterating this process, we obtain a non-singular deformation of



S into a surface S^1 , which does not meet E_3 except in t , and this deformation leaves c unaltered. It is now obvious that the first step in the deformation $c \rightarrow c'$ can be realized by a non-singular deformation of S^1 , and the lemma follows from induction on the number of steps in $c \rightarrow c'$.

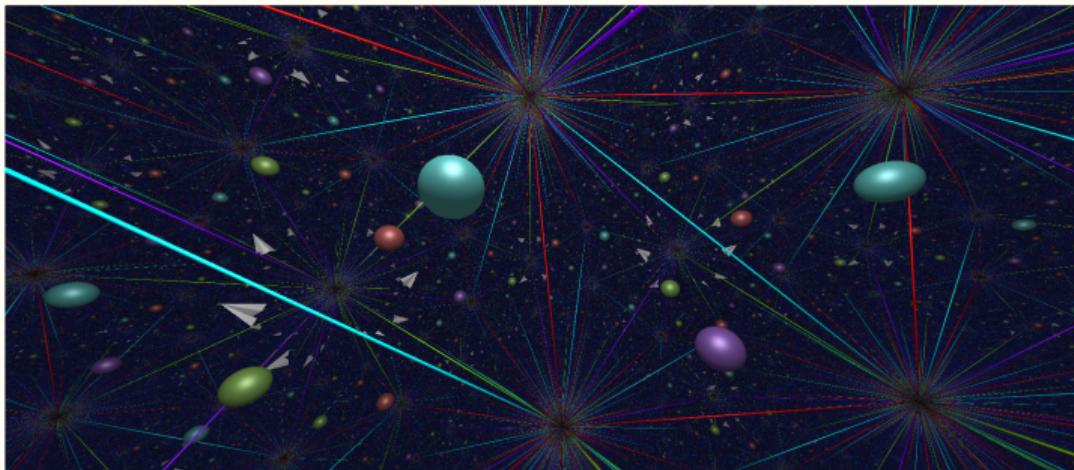
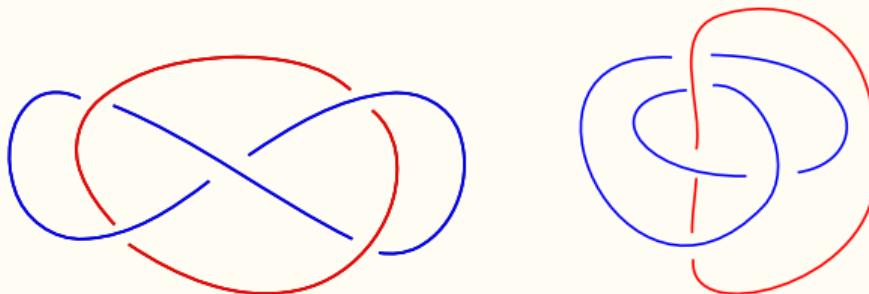
If a circuit in M is contained in a 3-element in M it will be called an *elementary circuit*. A circuit which bounds a (singular) 2-cell but which is not an elementary circuit will be called a *self-linking* circuit. The simplest type of self-linking circuit is illustrated by the diagram, the manifold being the residual space of a circuit m in Euclidean space, and s being a self-linking circuit.

We shall need two lemmas about punctured spheres.[†] We first recall from T.M. pp. 319–20, that any two punctured spheres are equivalent if they have the same number of boundary 2-spheres.[‡]

[†] Cf. T.M. § 2. When we refer to a punctured sphere or to any other bounded manifold, it is to be assumed that the boundary is non-singular.

[‡] The argument used in T.M. is valid in virtue of Alexander's theorem about the separation of a 3-sphere by a 2-spheres (*Proc. National Ac. of Sci.* 10 (1924), 6–8).

J.H.C. Whitehead, "A certain open manifold whose group is unity". *Quart. J. Math.*, 1935.



M. Culler, N. M. Dunfield, M. Goerner, and J. R. Weeks, *SnapPy, a computer program for studying the geometry and topology of 3-manifolds*, <http://snappy.computop.org>

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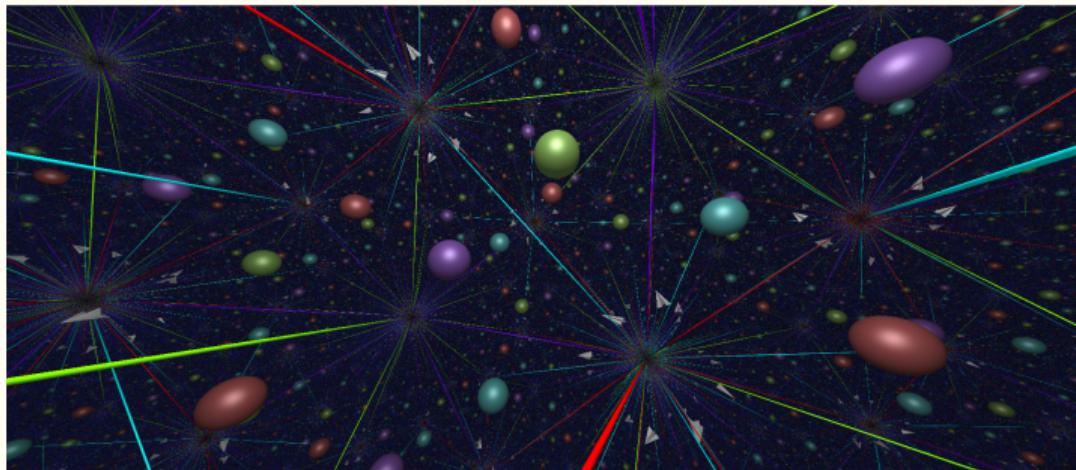
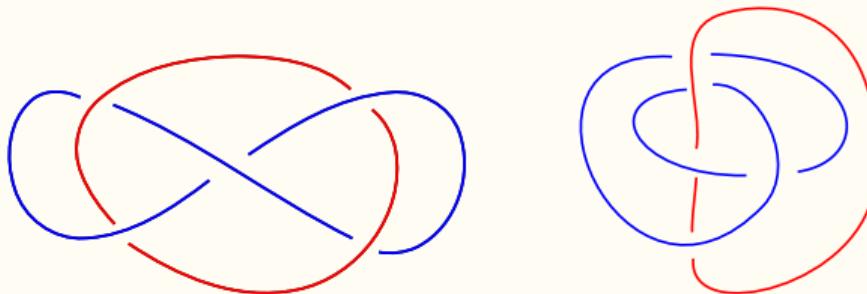
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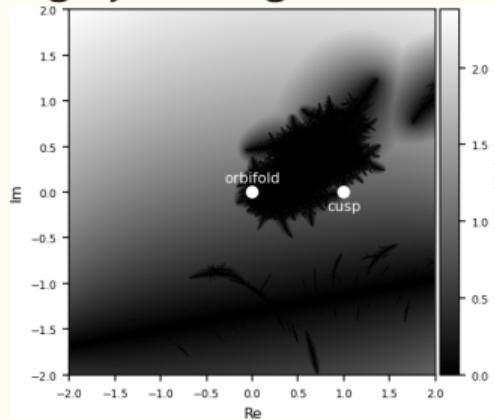


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- Knot complements are one important class of geometric structures with interesting groups.
 - ▶ **Mostow rigidity theorem:** the corresponding subgroups of $\mathrm{PSL}(2, \mathbb{C})$ are rigid—if $\mathbb{S}^3 \setminus k = \mathbb{H}^3/G$, and $H < \mathrm{PSL}(2, \mathbb{C})$ is isomorphic to G , then $\mathbb{H}^3/G = \mathbb{H}^3/H$ (up to isometry).

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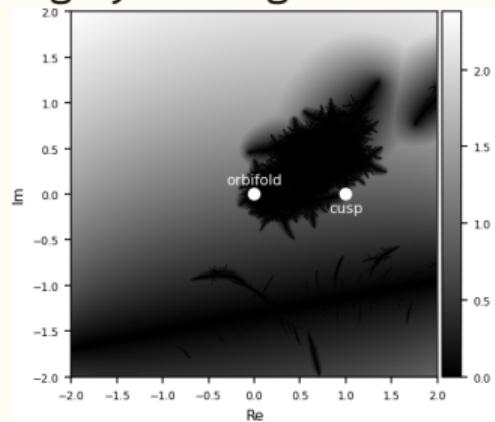
- Surface groups are important classes of geometric structures, but now are highly non-rigid:



← A linear slice through different geometric structures $\pi_1(S_{2,0}) \rightarrow \text{PSL}(2, \mathbb{C})$ where $S_{2,0}$ is the genus 2 surface.

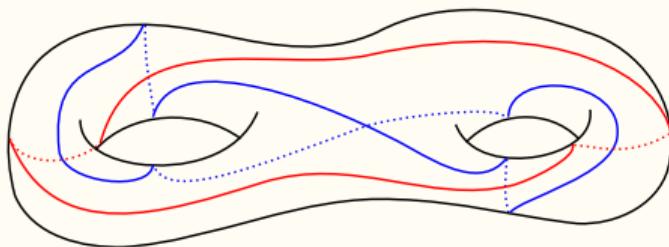
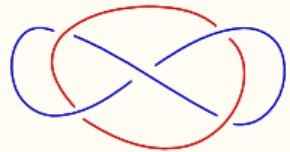
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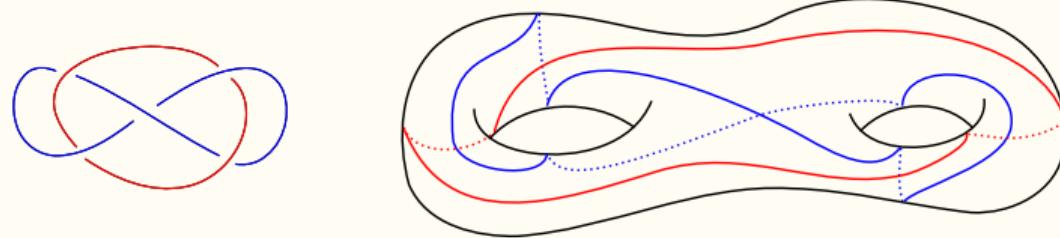
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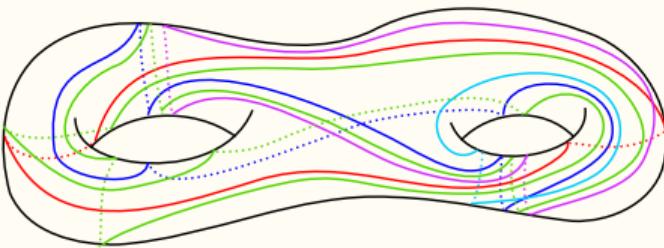
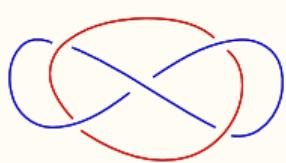
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- How do these different kinds of $\mathrm{PSL}(2, \mathbb{C})$ -representations fit together?
Consider embeddings $k \rightarrow S_{2,0}$.





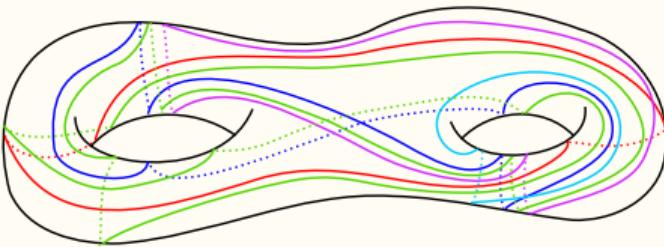
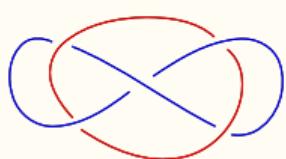
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dual graph:
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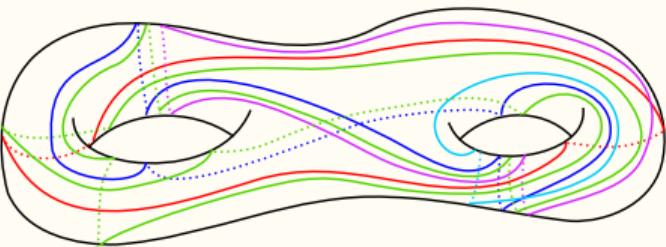
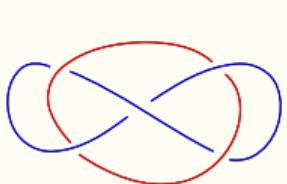


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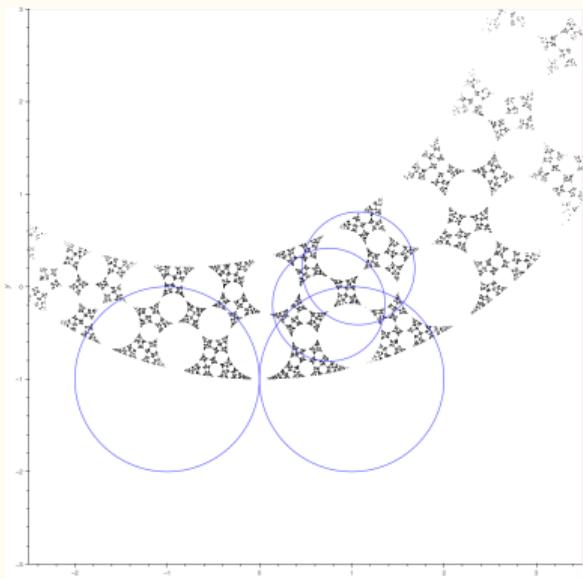
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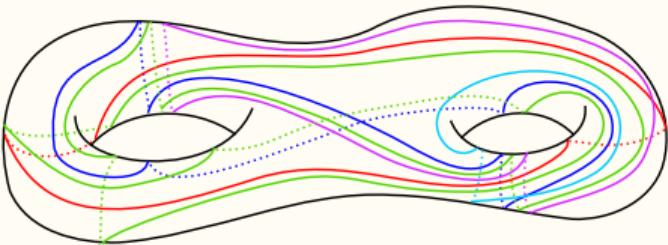
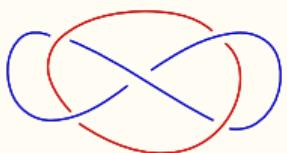
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$$\rho(Y) = \begin{bmatrix} 1 - i & 1 \\ 1 & 1 + i \end{bmatrix}$$





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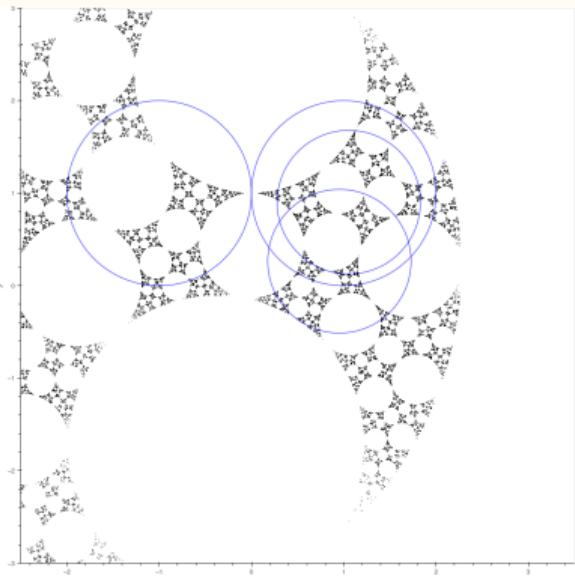
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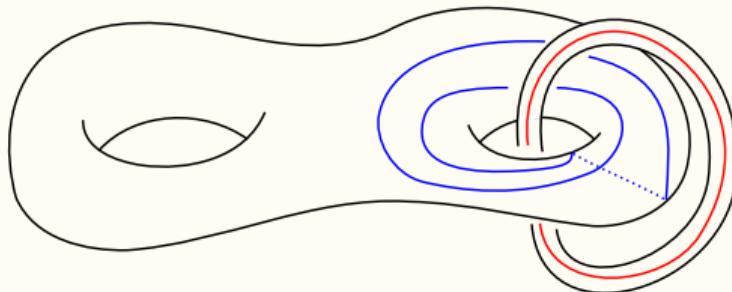
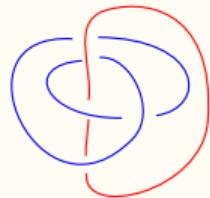
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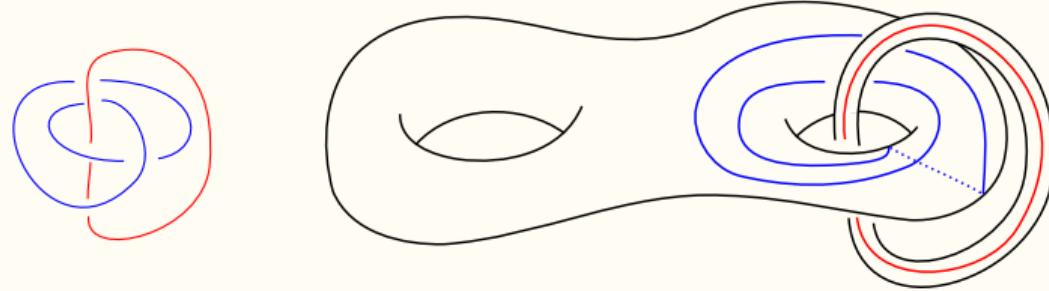
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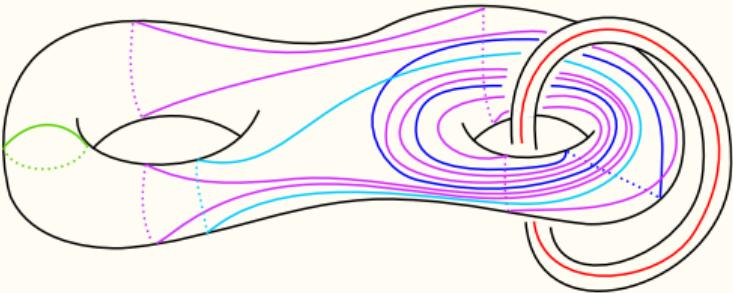
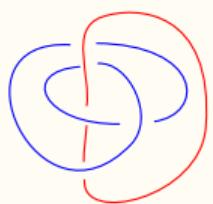
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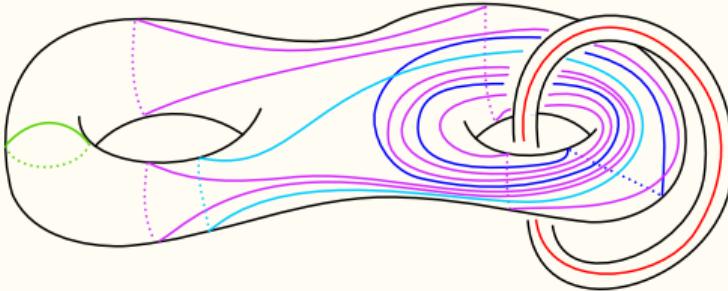
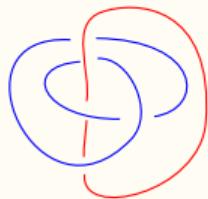
$$\pi_1(\text{compr. body}) = (\mathbb{Z} \oplus \mathbb{Z}) * \mathbb{Z} = \langle P, Q, M : [P, Q] = 1 \rangle$$



dual graph:
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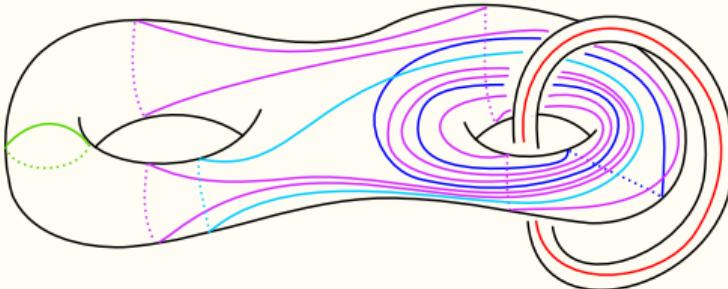
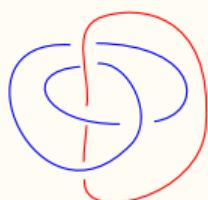
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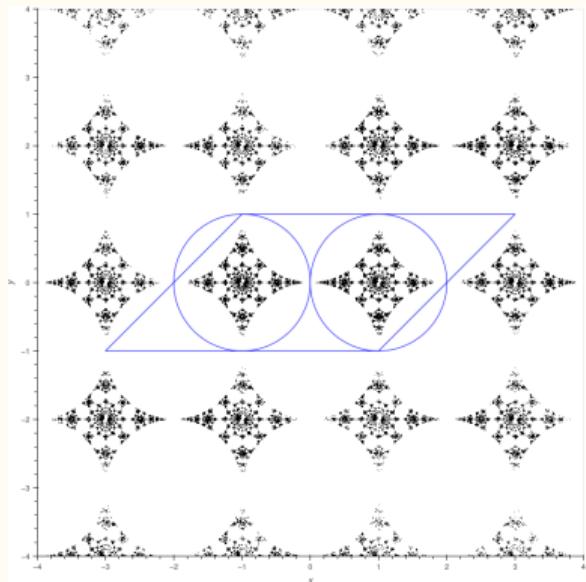
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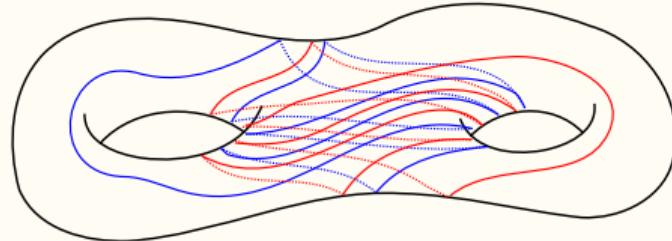
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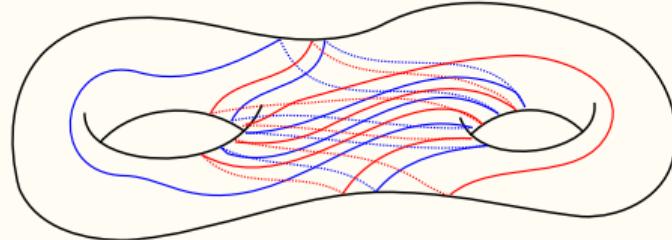
$$\rho(P) = \begin{bmatrix} 1 & 10 + 2i \\ 0 & 1 \end{bmatrix}, \quad \rho(Q) = \begin{bmatrix} 1 & -4 \\ 0 & 1 \end{bmatrix}, \quad \rho(M) = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$$



3/8 braid
embedding
(as per Jeroen's talk)

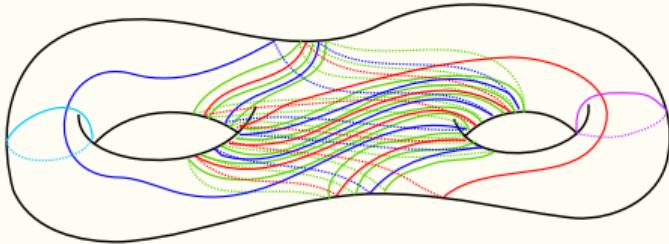


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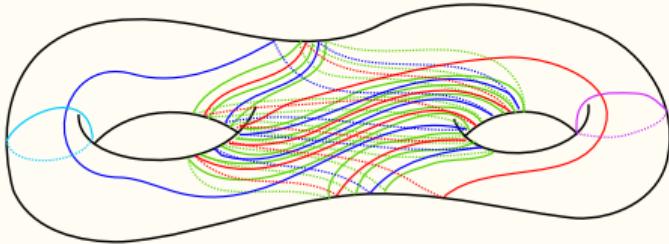


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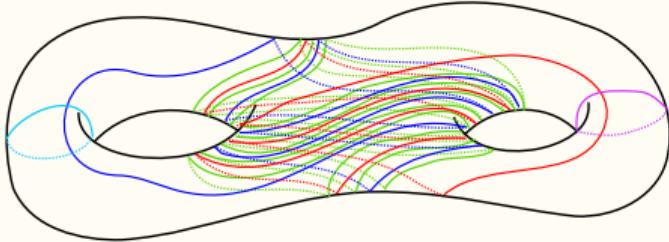
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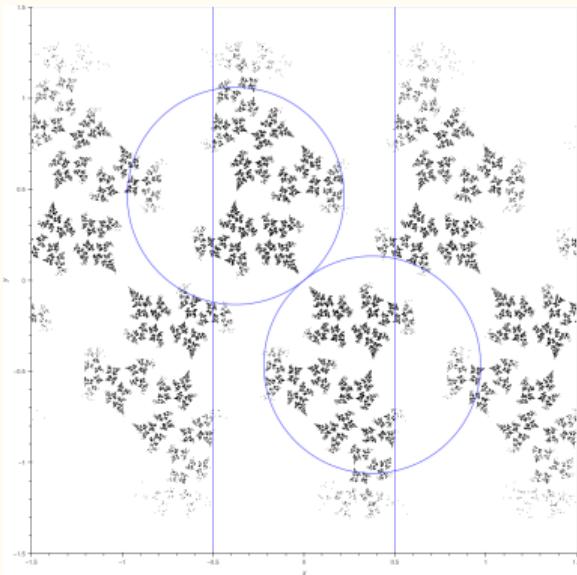
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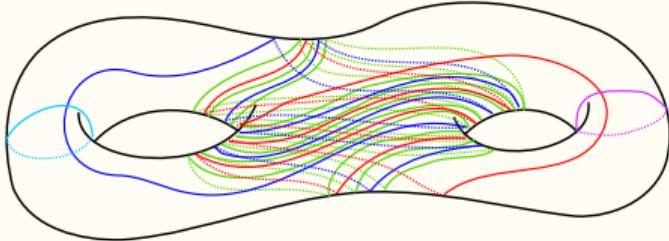
\exists 2 discrete reps $\rho : \langle X, Y \rangle \rightarrow \text{PSL}(2, \mathbb{C})$ so that
 $\text{tr}^2 = 4$ for all these words.

$$\rho(X) = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$\rho(Y) = \begin{bmatrix} 1 & 0 \\ 1.05642 + 1.30324i & 1 \end{bmatrix}$$



3/8 braid
embedding
(as per Jeroen's talk)



dual graph:
3 non-intersecting
curves, each meet-
ing the knot at
most once

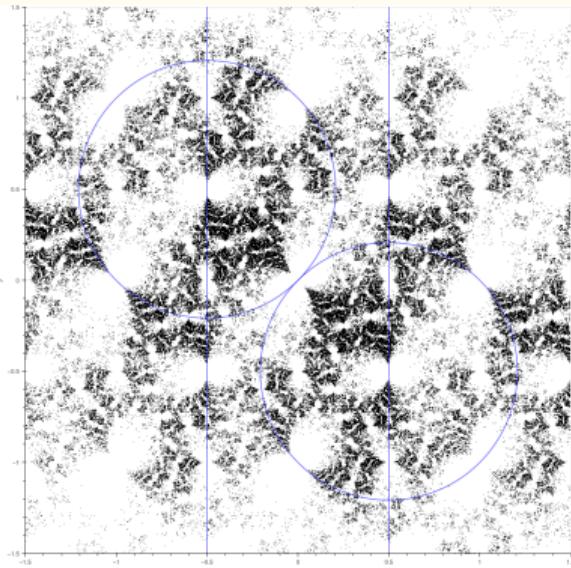
$$\pi_1(\text{genus 2 handlebody}) = \mathbb{Z} * \mathbb{Z} = \langle X, Y \rangle$$

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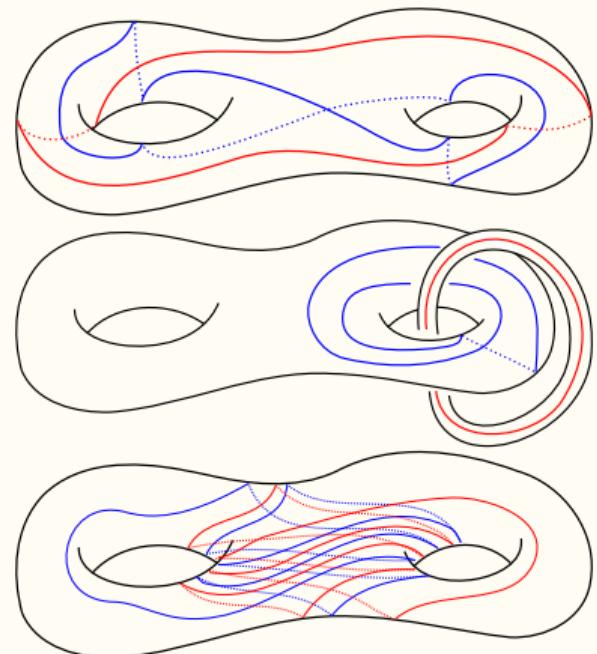
$$\rho(X) = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$\rho(Y) = \begin{bmatrix} 1 & 0 \\ 1+i & 1 \end{bmatrix}$$

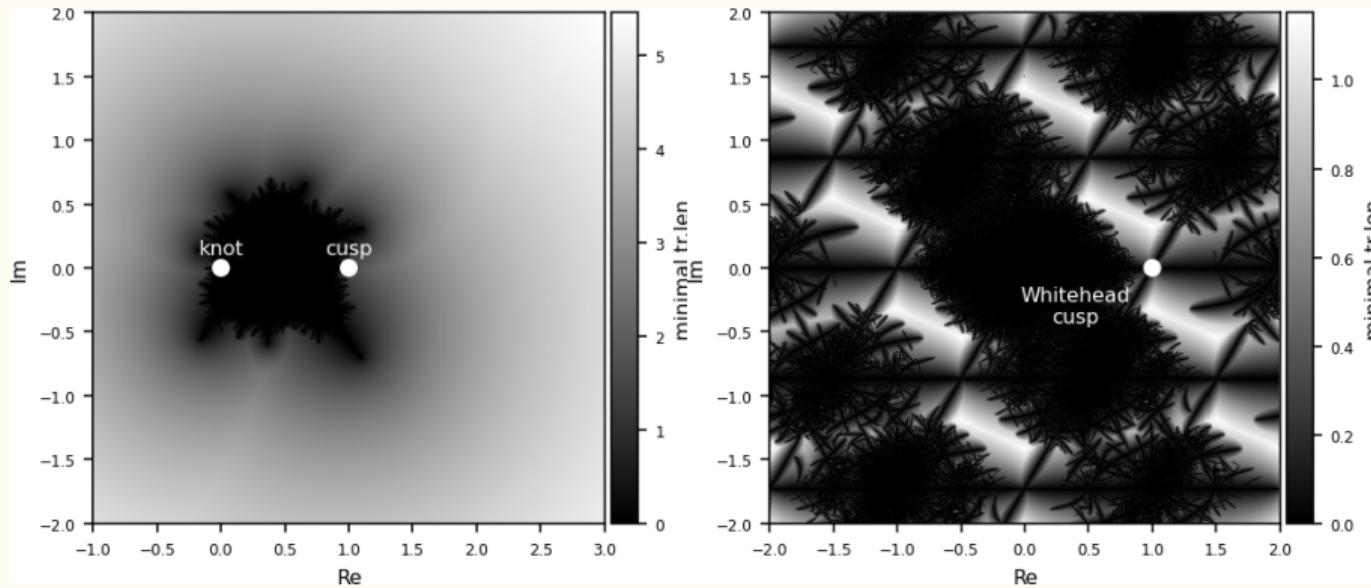


WHAT IS THE BEST CHOICE OF EMBEDDING?

- Out of the 3, only 1 embedding of the Whitehead link into $S_{2,0}$ gave us the link group back as a representation: the braid embedding.
- Necessary (but not sufficient) condition: the dual curves to the embedding need to bound embedded discs in the complement handlebody.
- When this condition is not satisfied, if k is complicated (many crossings) then we still get lattices as well as cusp groups.
- *Open question:* characterise the lattices obtained topologically in terms of the combinatorics of k .



These methods give us reps. $G \rightarrow \text{PSL}(2, \mathbb{C})$ that capture the combinatorics of knots (so nice geometry) & are *extremal* in representation spaces.



Two slices through $\text{Hom}((\mathbb{Z} \oplus \mathbb{Z}) * \mathbb{Z}, \text{PSL}(2, \mathbb{C}))$. The ‘cusp’ point is the same group in each picture.

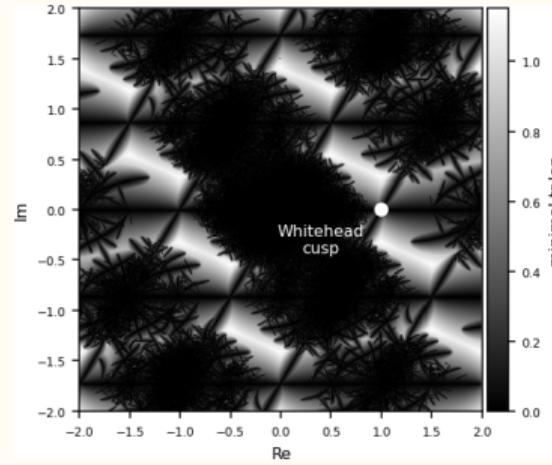
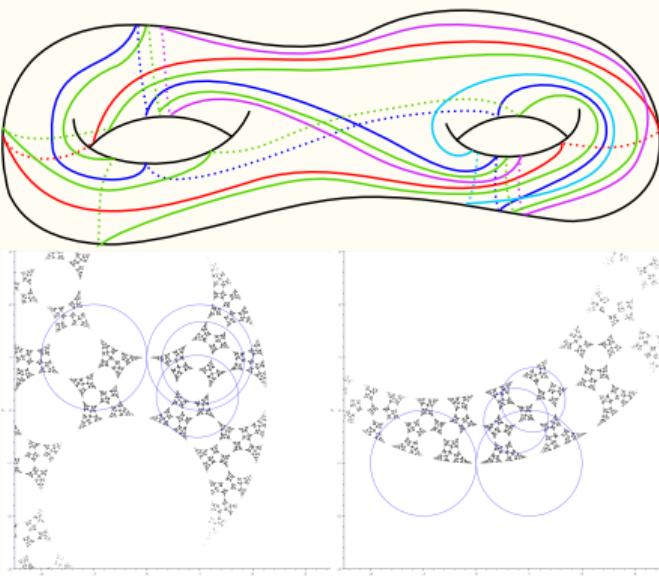
E., “From disc patterns in the plane to character varieties of knot groups”, arXiv:2503.13829 [math.GT]

Problem

If G is a group and $\rho_0, \rho_1 : G \rightarrow \mathrm{PSL}(2, \mathbb{C})$ are reps, can you find a path of reps ρ_t with actions that ‘smoothly interpolate’ from ρ_0 to ρ_1 ?

The obstruction is an understanding of paths of *indiscrete* reps. The extremal groups we discussed (called ‘cusp groups’) can act as nice endpoints for smooth curves of indiscrete representations. We have constructed such paths in a few settings, using a variety of geometric techniques:

- between compression body groups with different numbers of handles
arXiv:2411.17940 [math.GT], video
- between ‘fully augmented link groups’ which are rigid, and cusp groups which lie on the boundary of a big deformation space (to appear shortly)
- between 2-bridge link groups and the holonomy groups of manifolds where an upper unknotting tunnel has been drilled (joint with Chesebro and Purcell, in preparation)



- E., *From disc patterns in the plane to character varieties of knot groups.* arXiv:2503.13829 [math.GT]
- E., *Changing topological type of compression bodies through cone manifolds.* arXiv:2411.17940 [math.GT]
- J. Purcell, *Hyperbolic knot theory.* AMS, 2020.
- A. Marden, *Hyperbolic manifolds.* Cambridge, 2016.
- D. Mumford, C. Series, D. Wright, *Indra's pearls.* Cambridge, 2002.