

Progress Report

Name: Adrian Marrero Pagan
Course: Control Design Onramp with Simulink
Progress: **100%** complete (as of 24 June 2025)

Chapters

1. Course Overview **100%**
2. Control System Plants **100%**
3. Linearizing the Plant with Model Linearizer **100%**
4. Feedback Control with PID **100%**
5. PID Tuning **100%**
6. Project - Robotic Leg Control **100%**
7. Conclusion **100%**