# Counting complexity and oracles and oracles in natural computing

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https://aeporreca.org

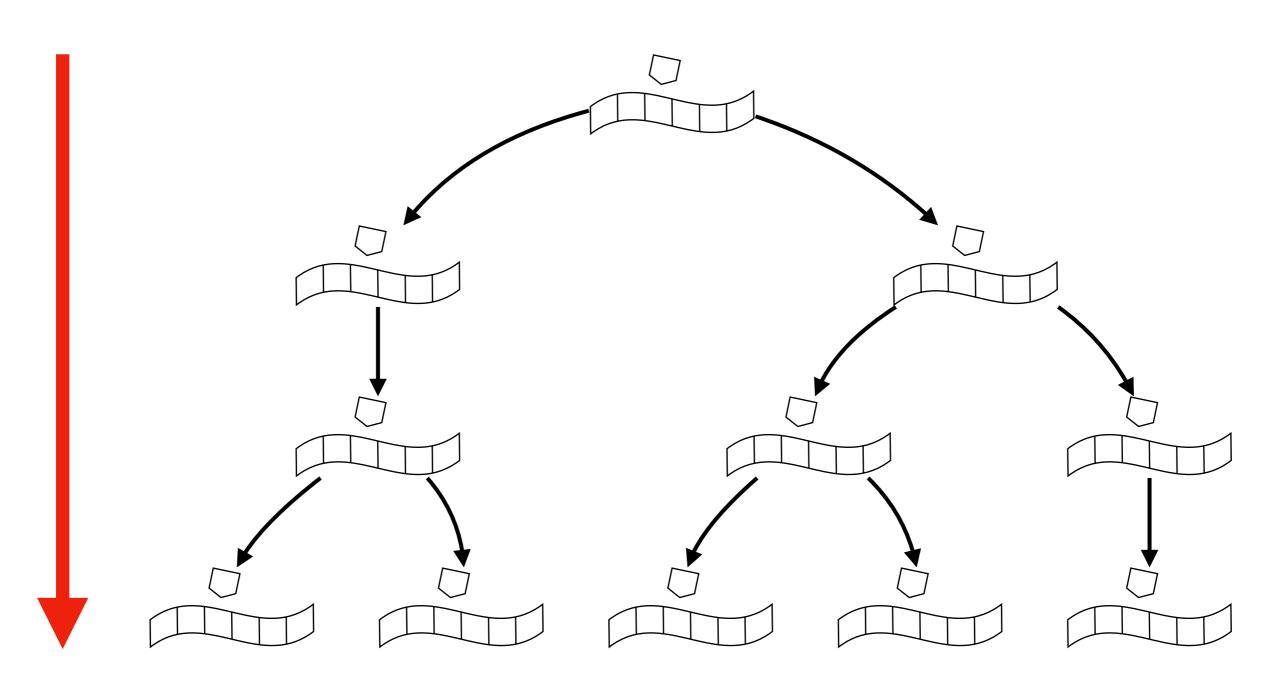
# The first and second machine classes

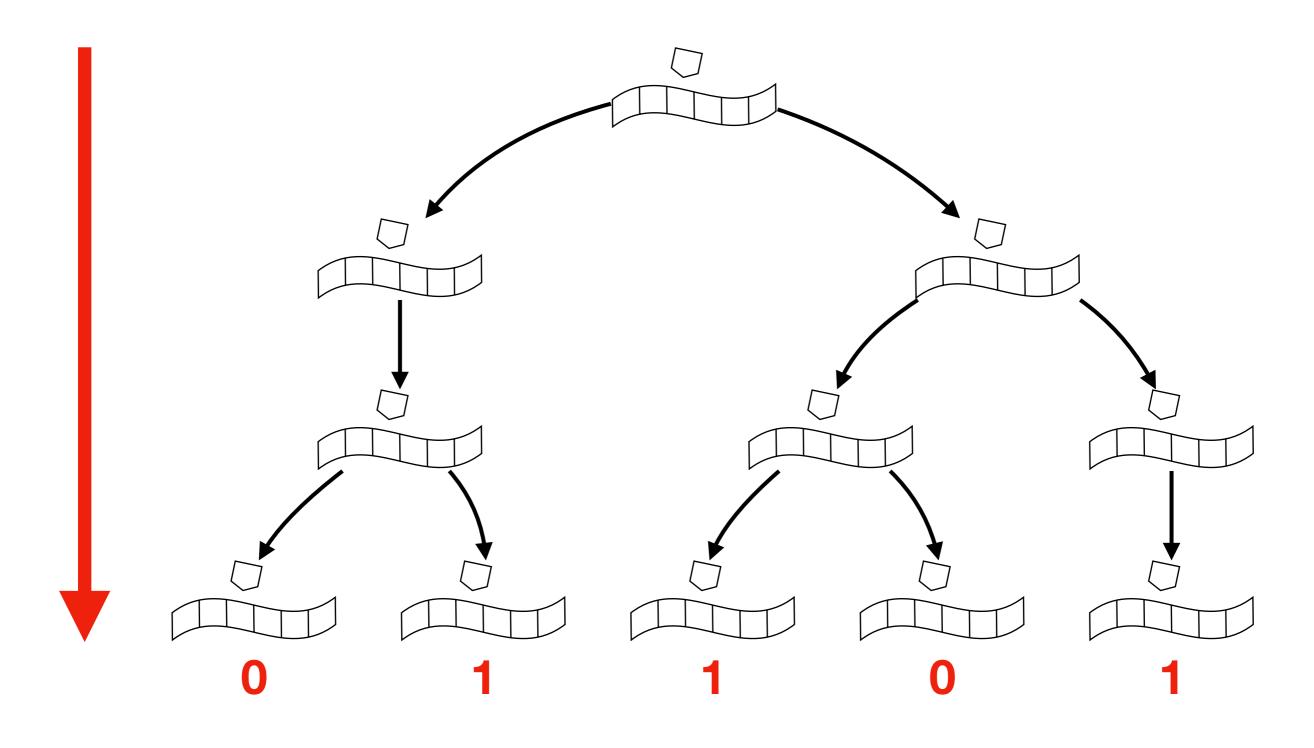
#### The first machine class and P

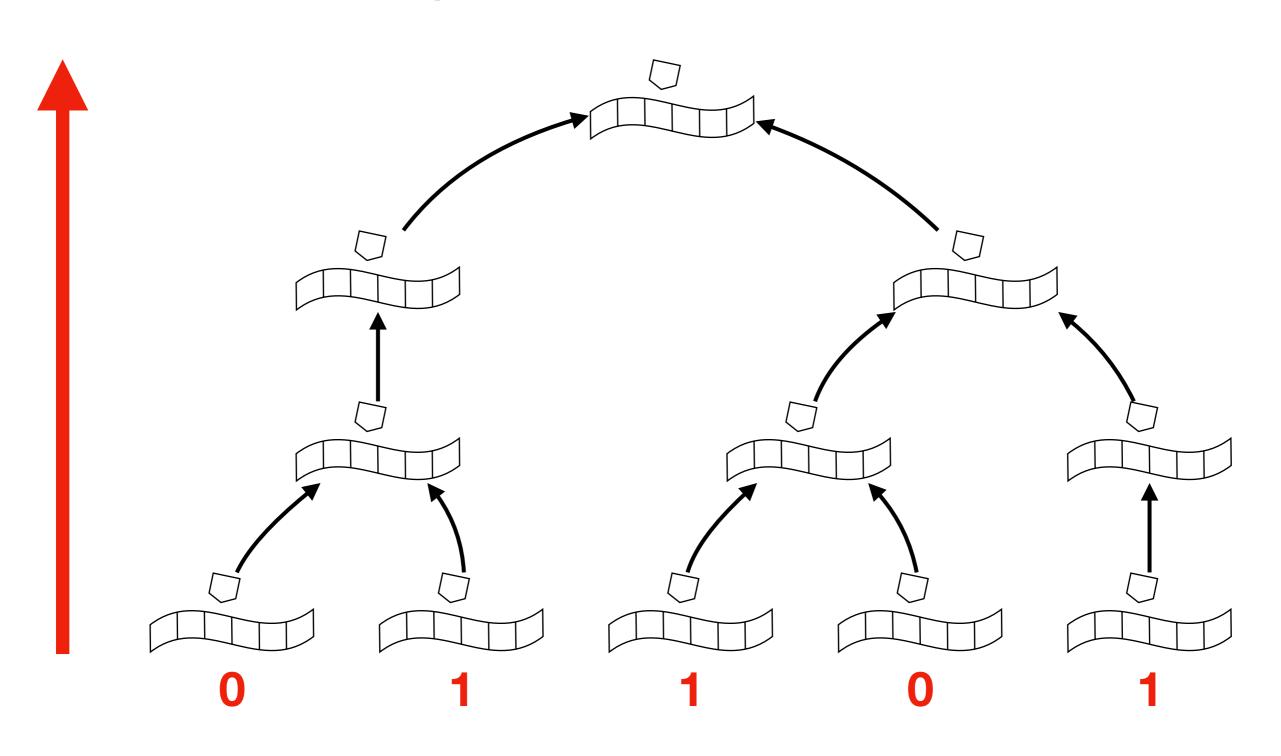
- Includes the deterministic Turing machine and all models that simulate and are simulated by it efficiently:
  - Random access machines (RAM) with constant-time addition and subtraction
  - Cellular automata with a finite initial configuration

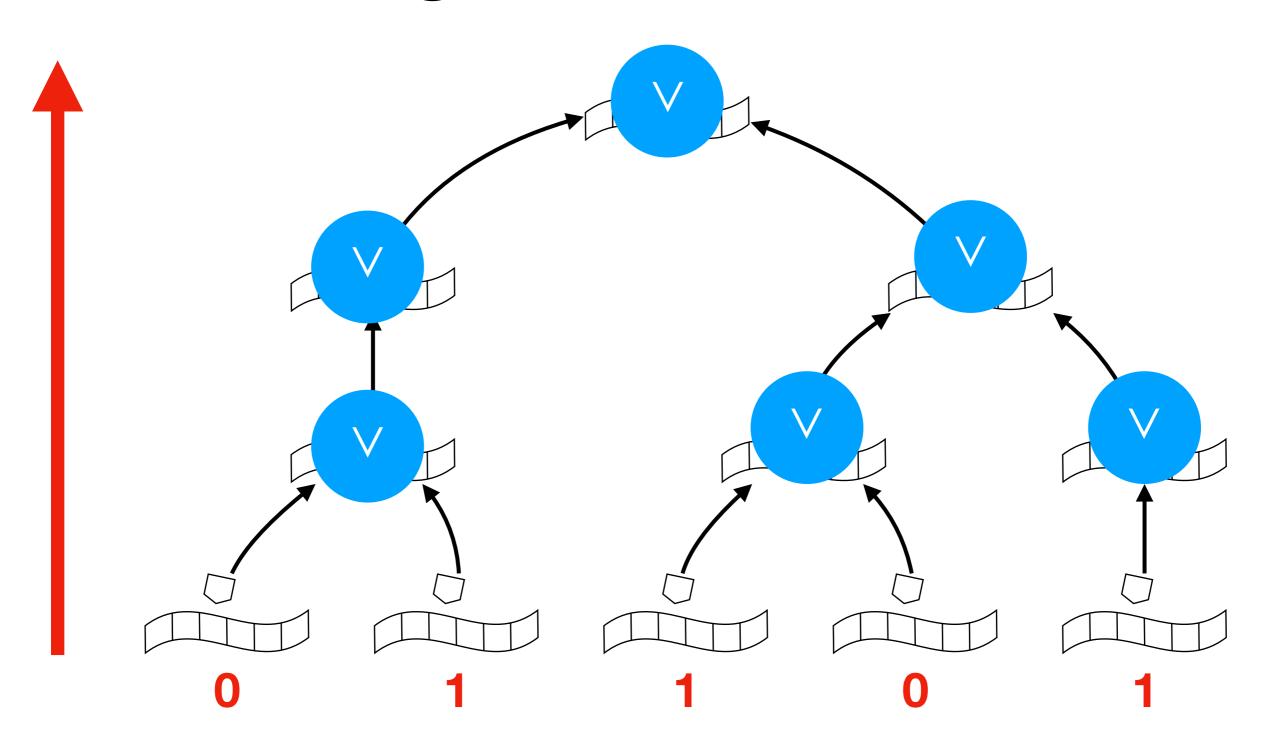
### The second machine class and PSPACE

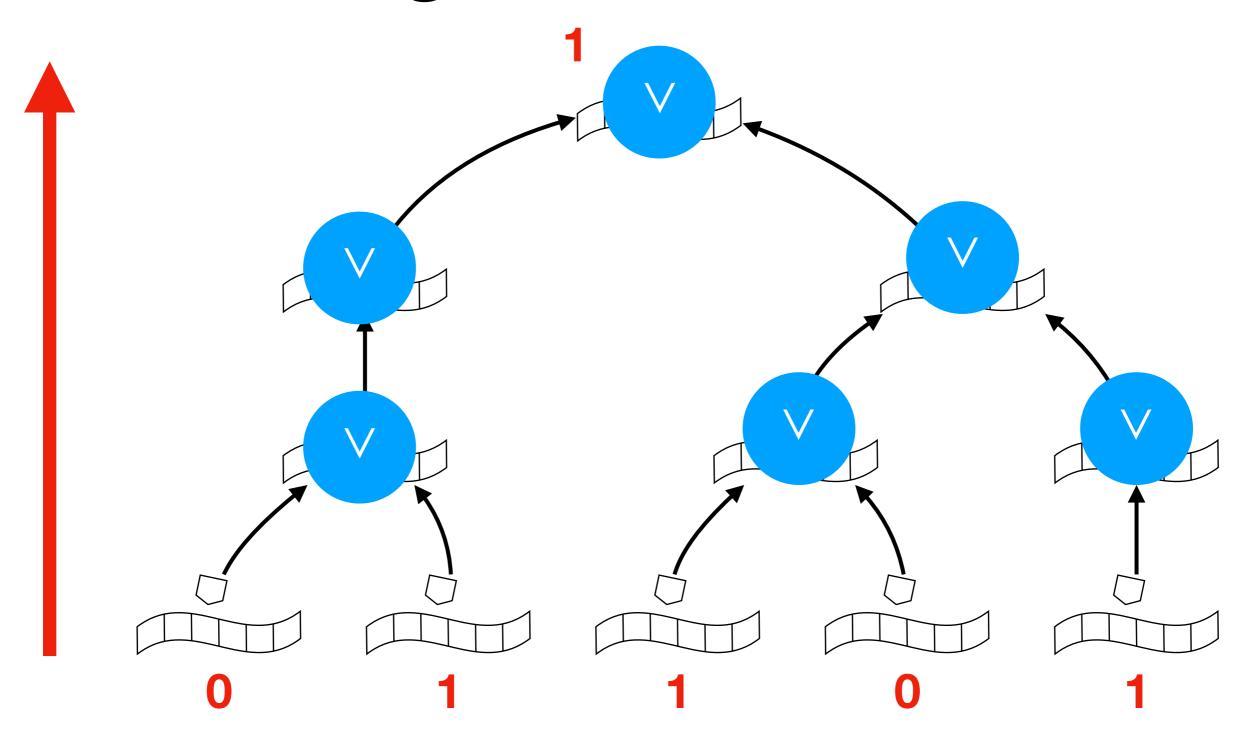
- Includes models of computation that solve in polynomial time what a Turing machine solves in polynomial space:
  - Alternating Turing machines
  - Random access machines including constant time multiplication and division
  - Parallel processes generated by fork(2)
     running on an unbounded number of processors
  - Cellular automata over hyperbolic grids



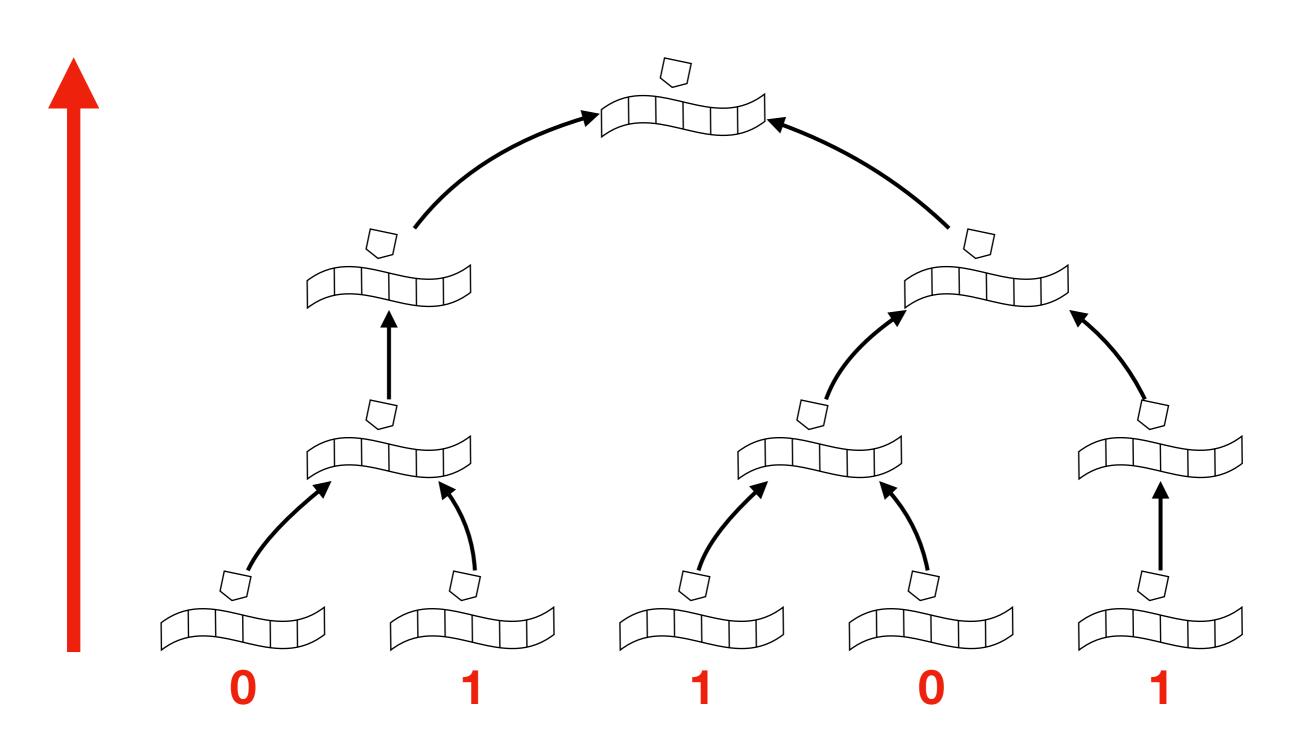




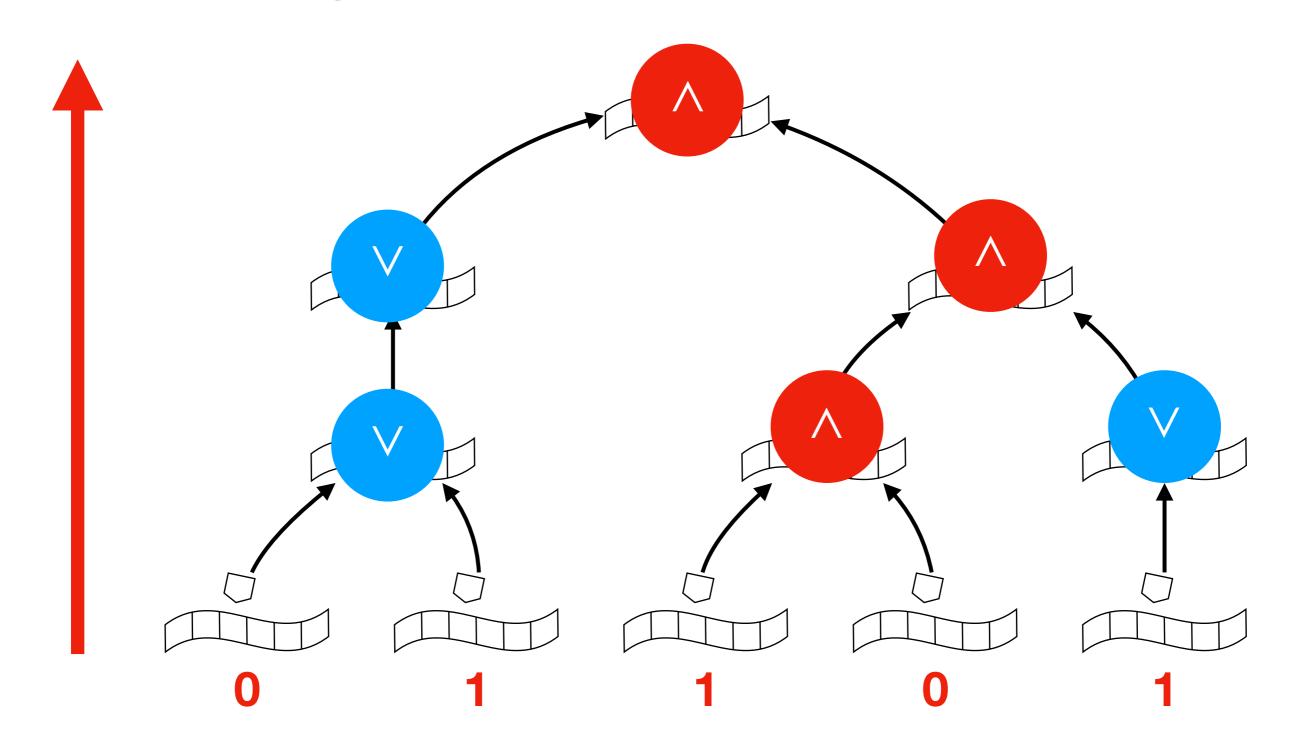




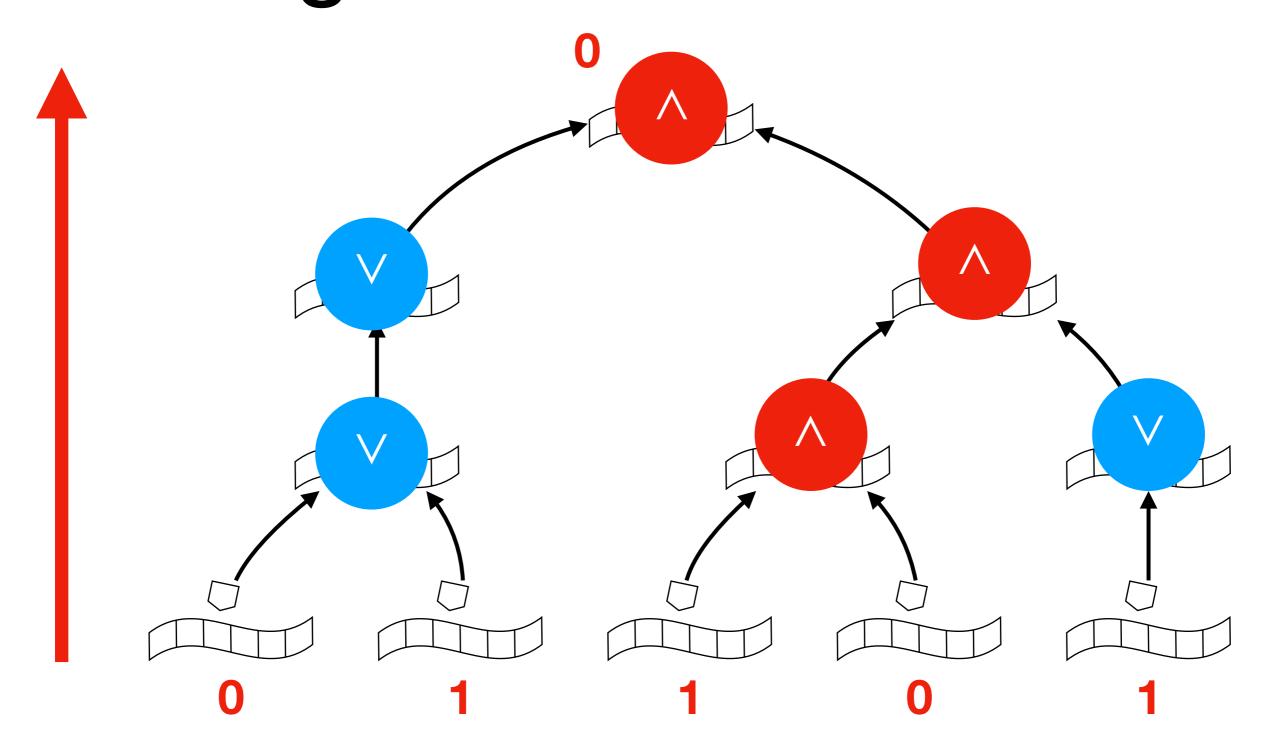
# Alternating Turing machines: PSPACE



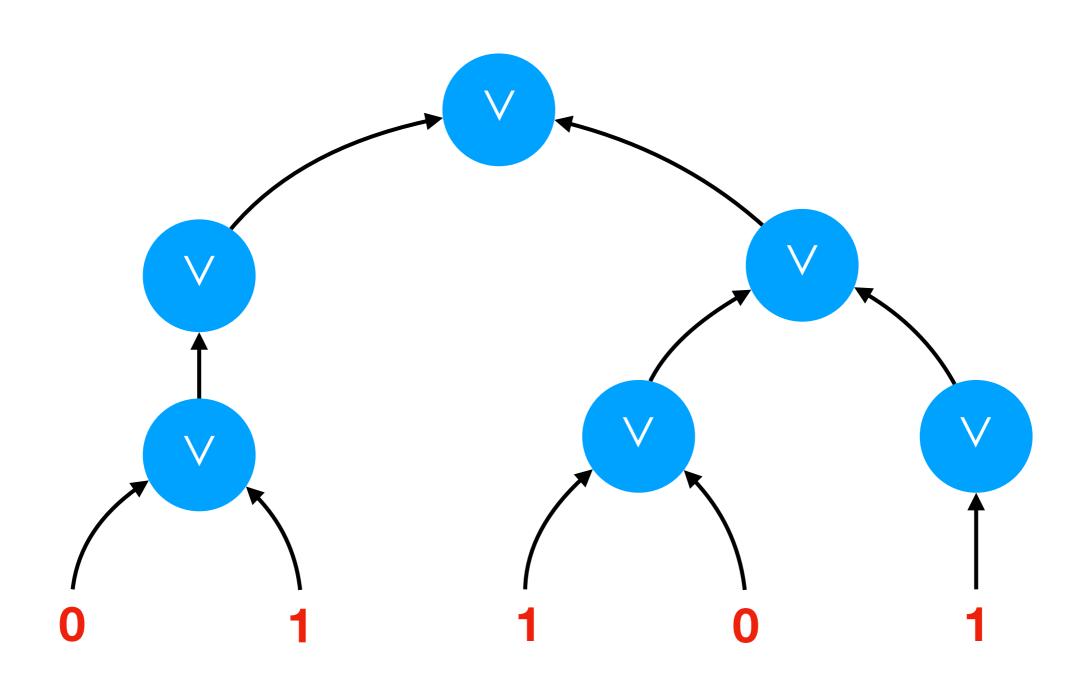
# Alternating Turing machines: PSPACE



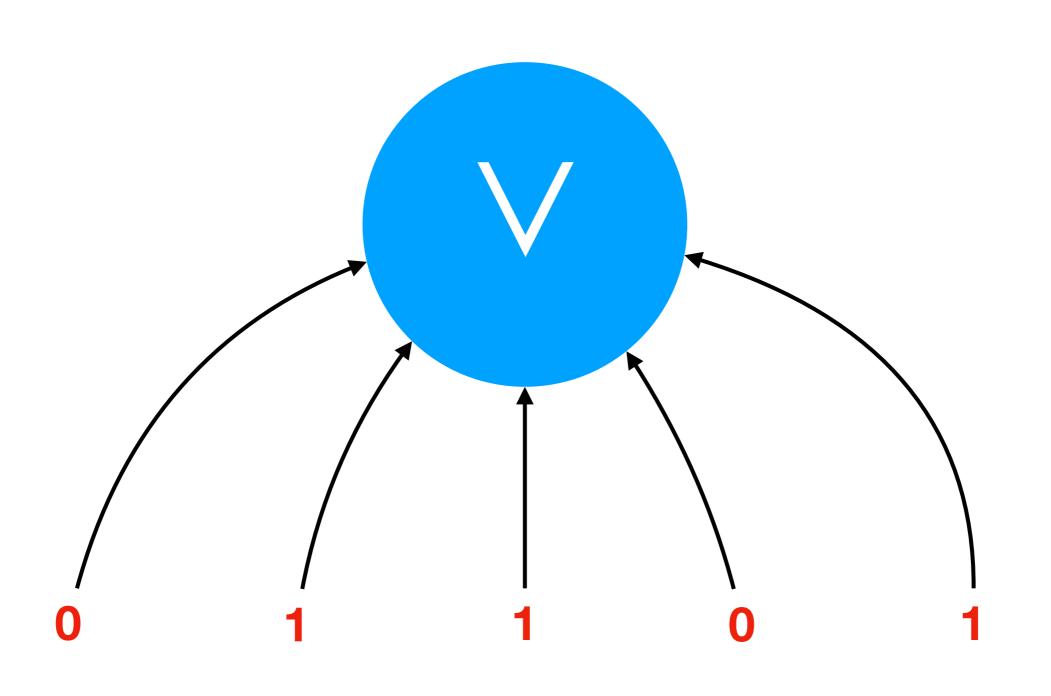
# Alternating Turing machines: PSPACE



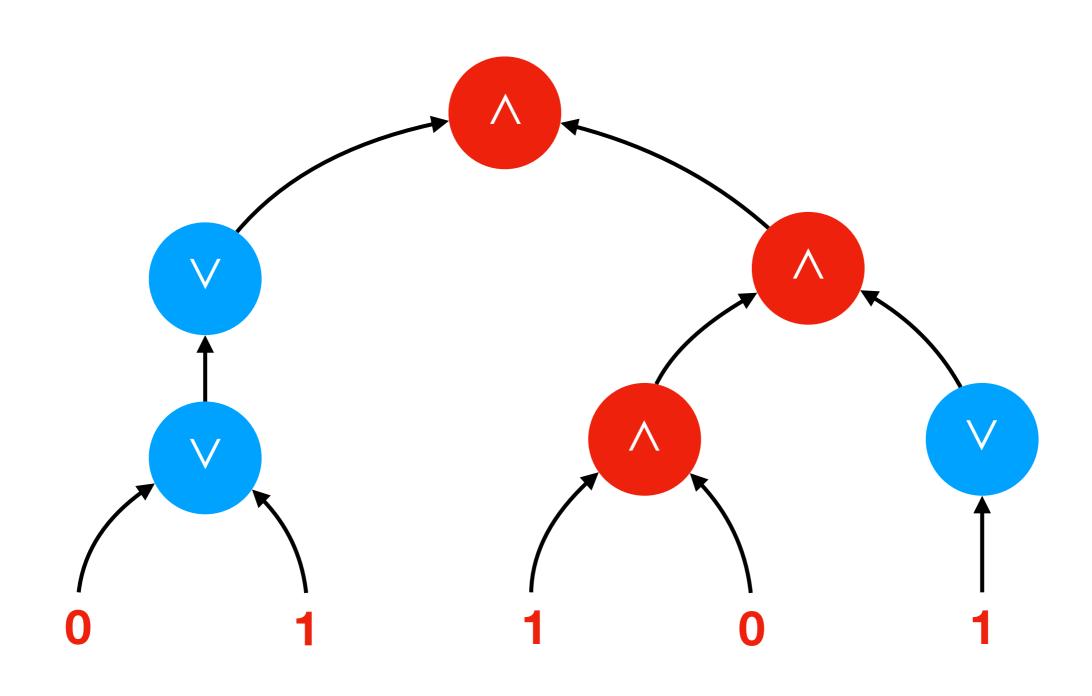
#### Flattening v-circuits



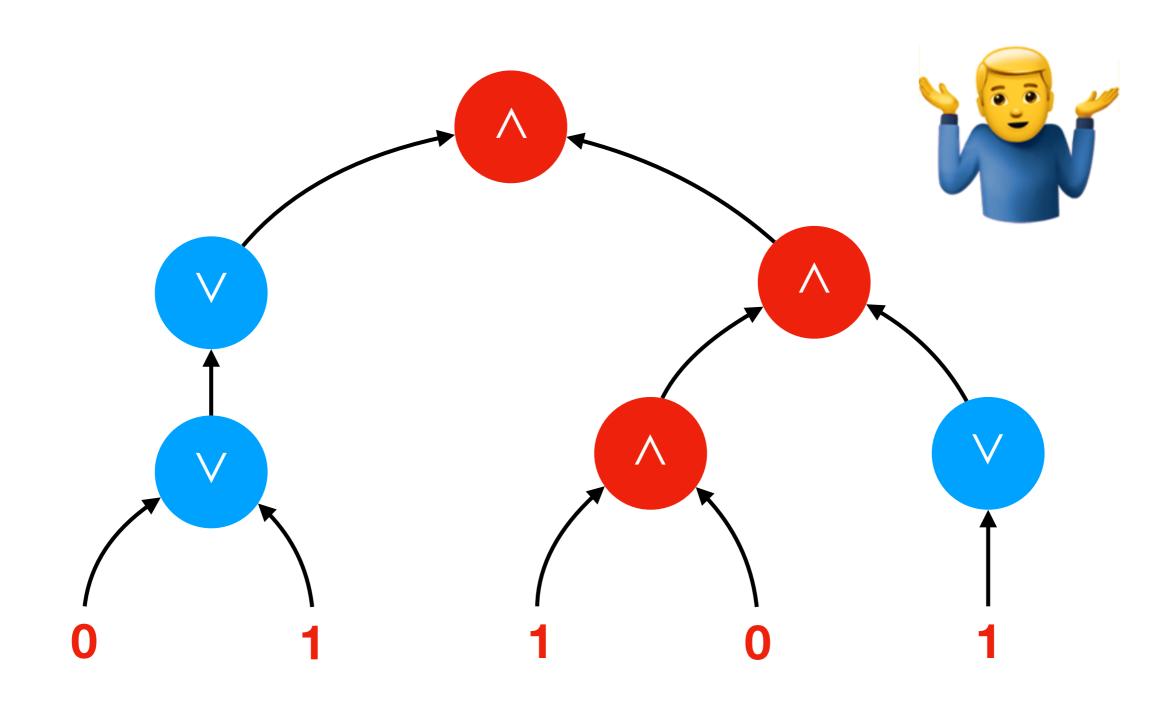
#### Flattening v-circuits



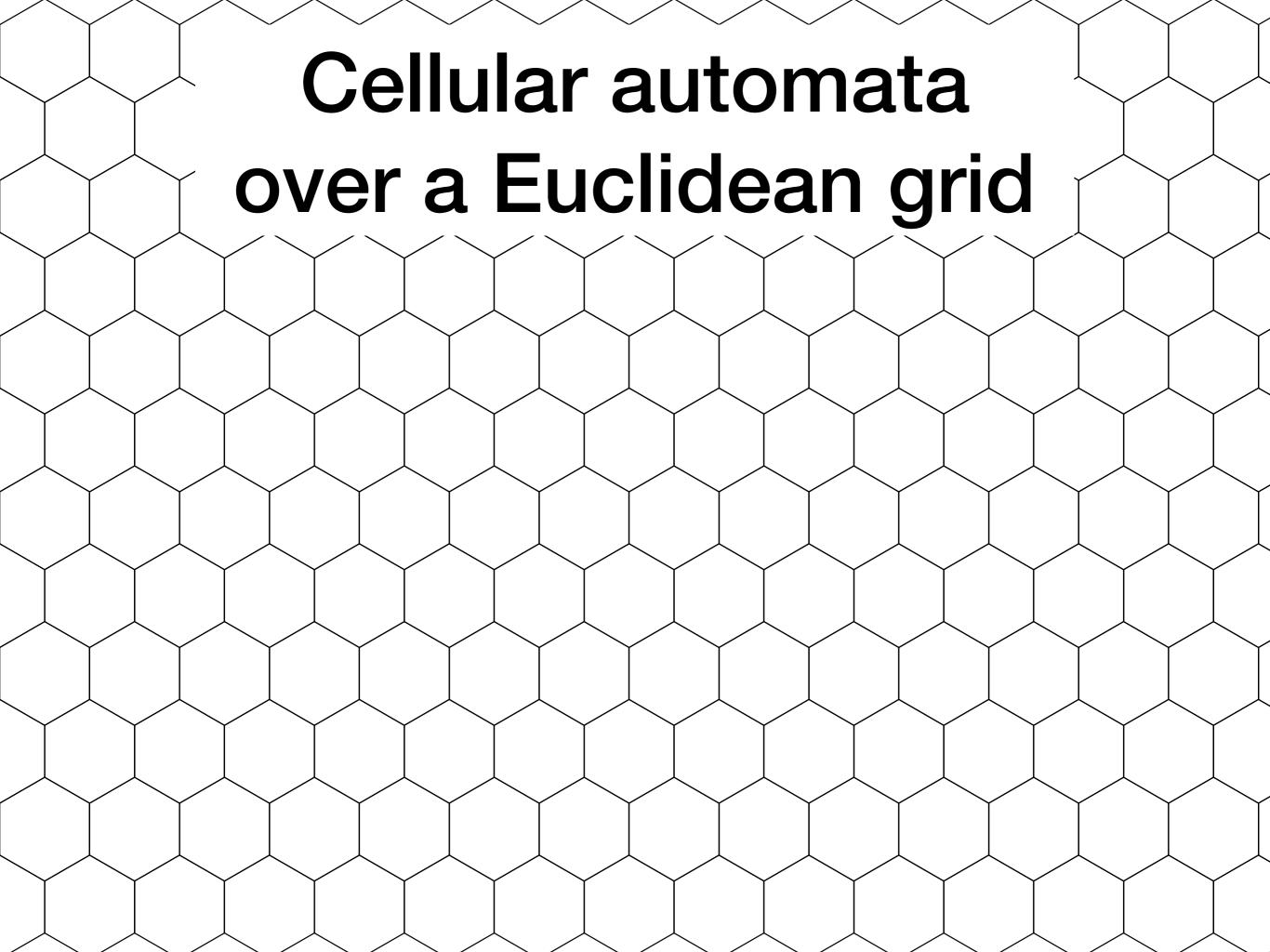
#### Flattening <a href="#">\</a>-circuits?

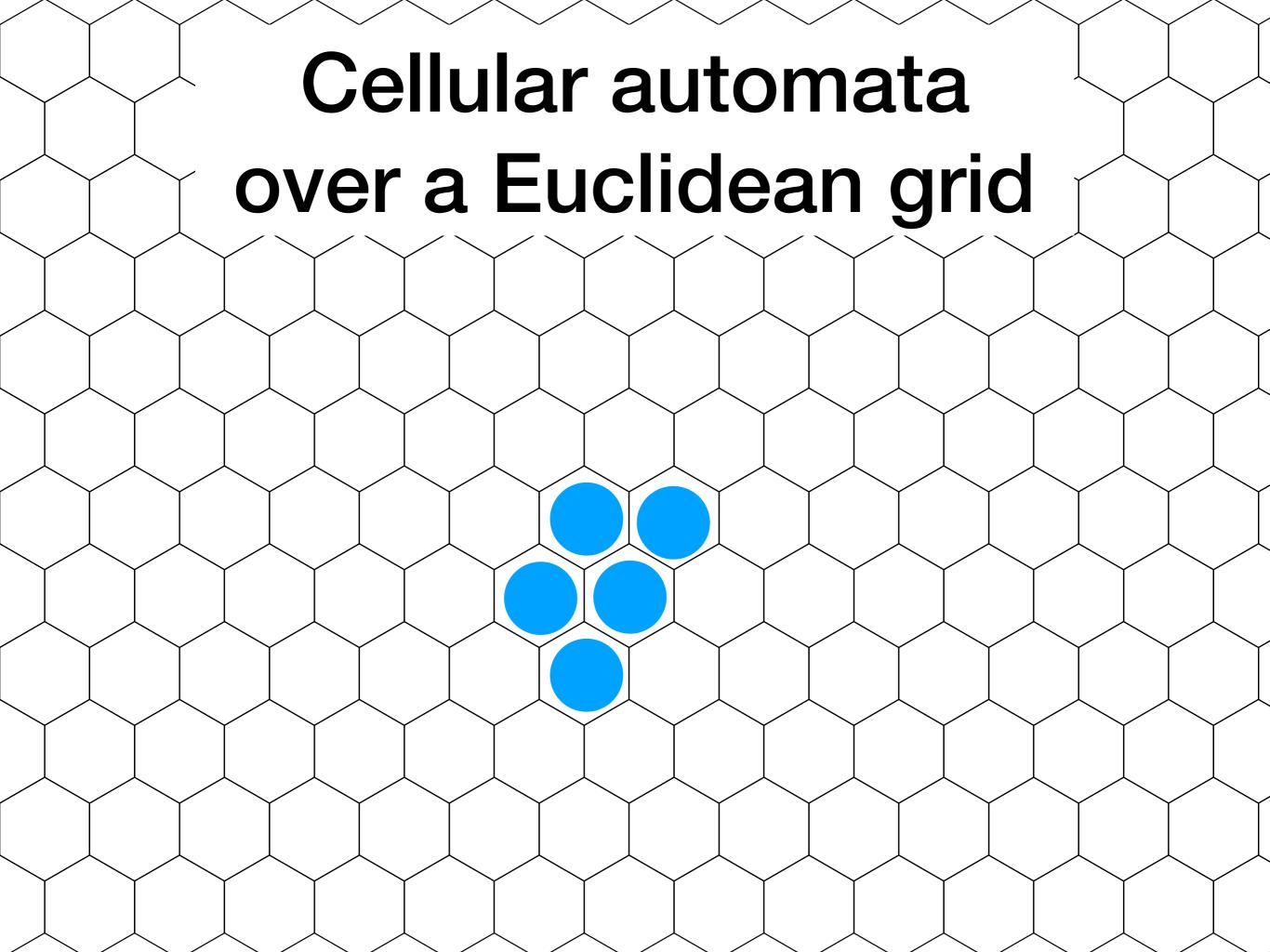


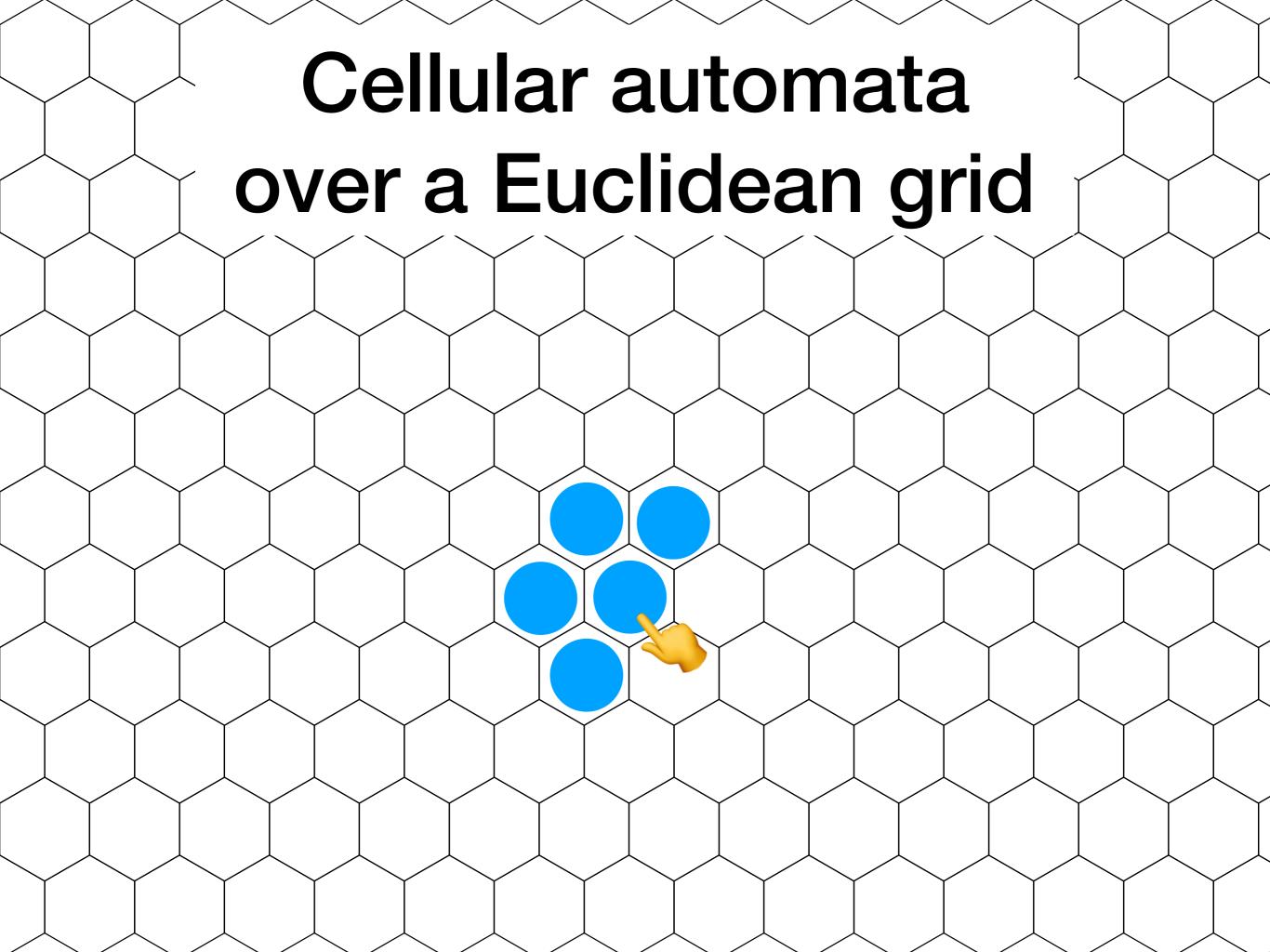
#### Flattening <a href="#">\</a>-circuits?

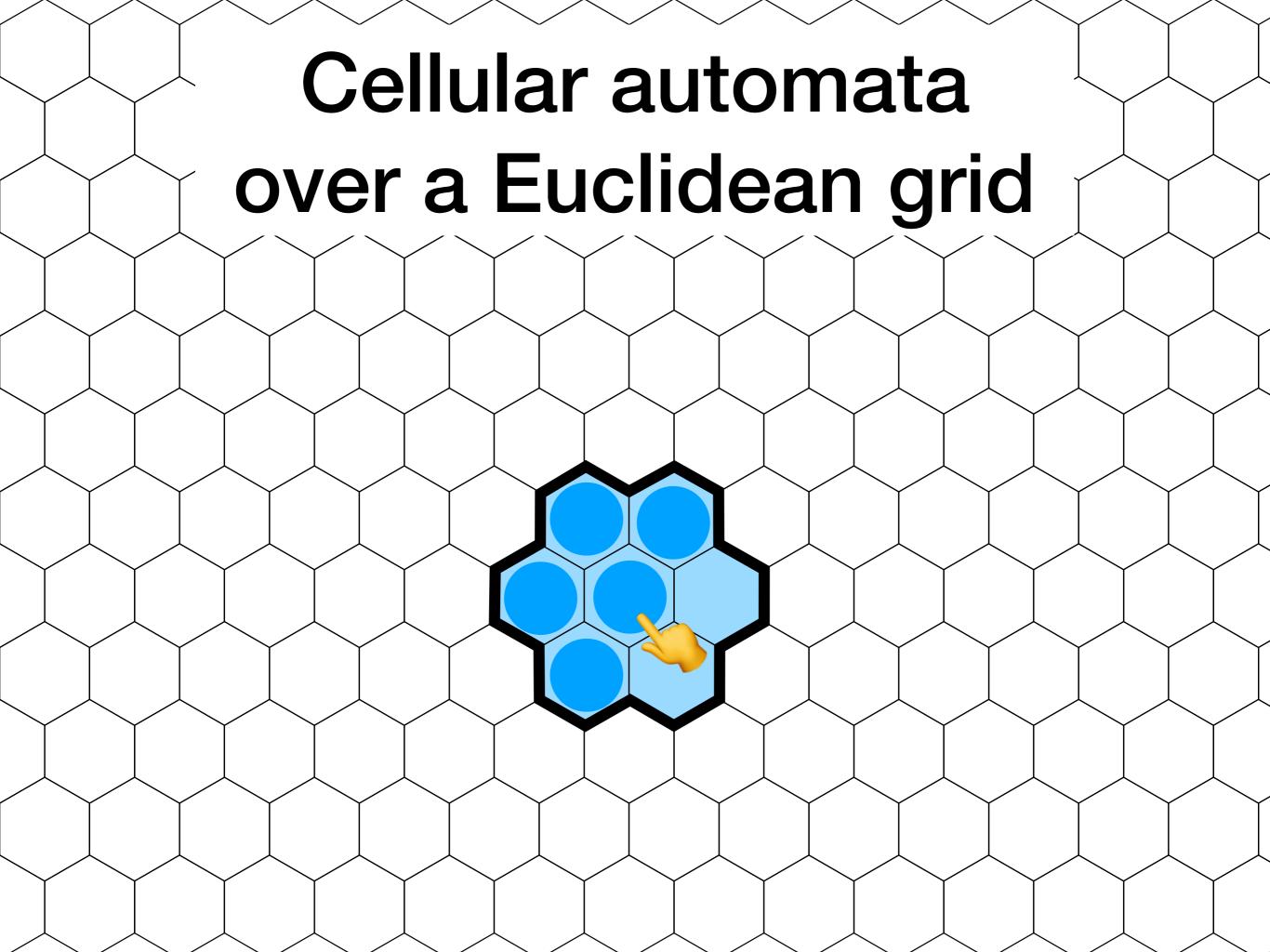


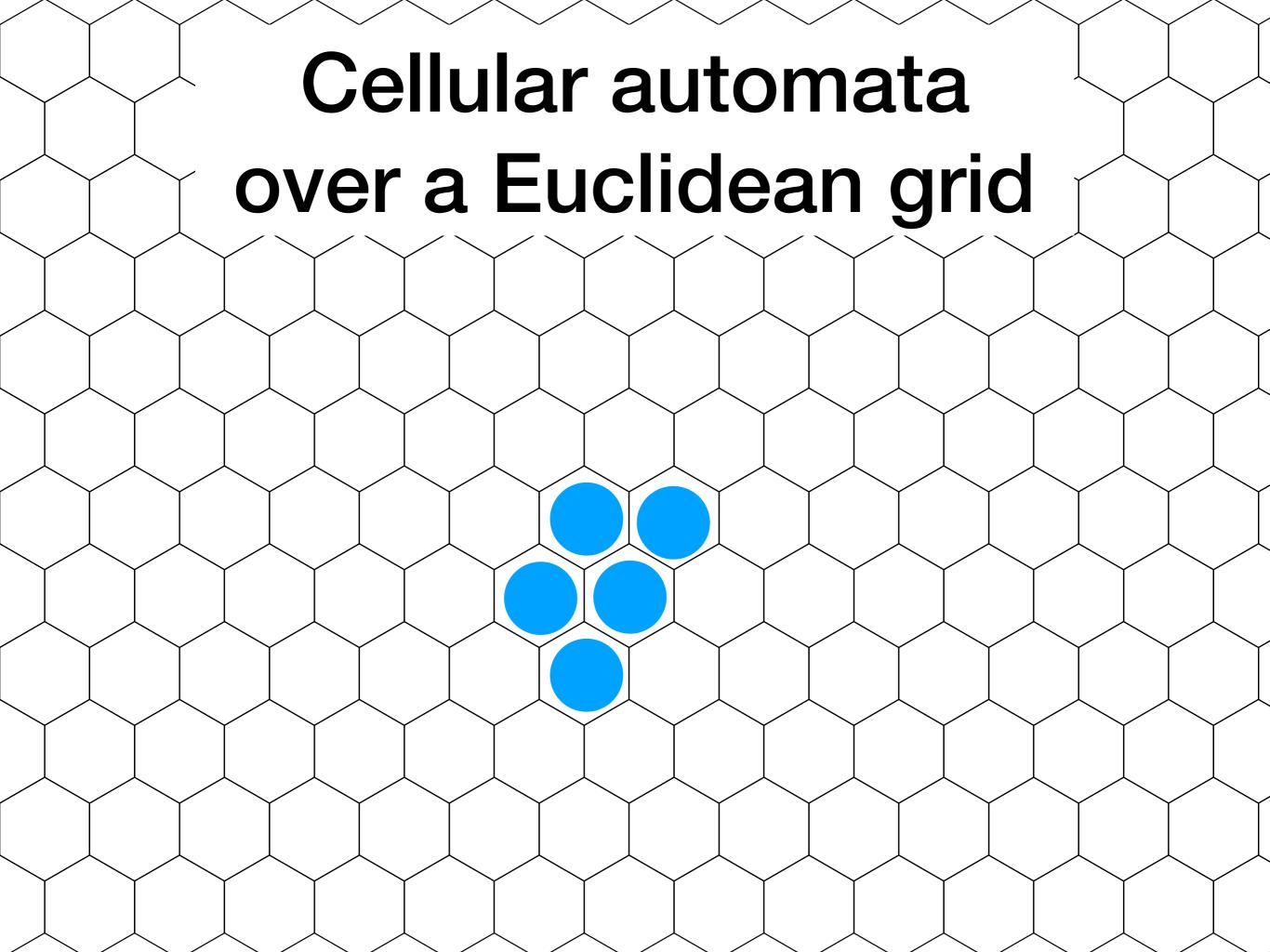
# Computation space vs computation efficiency

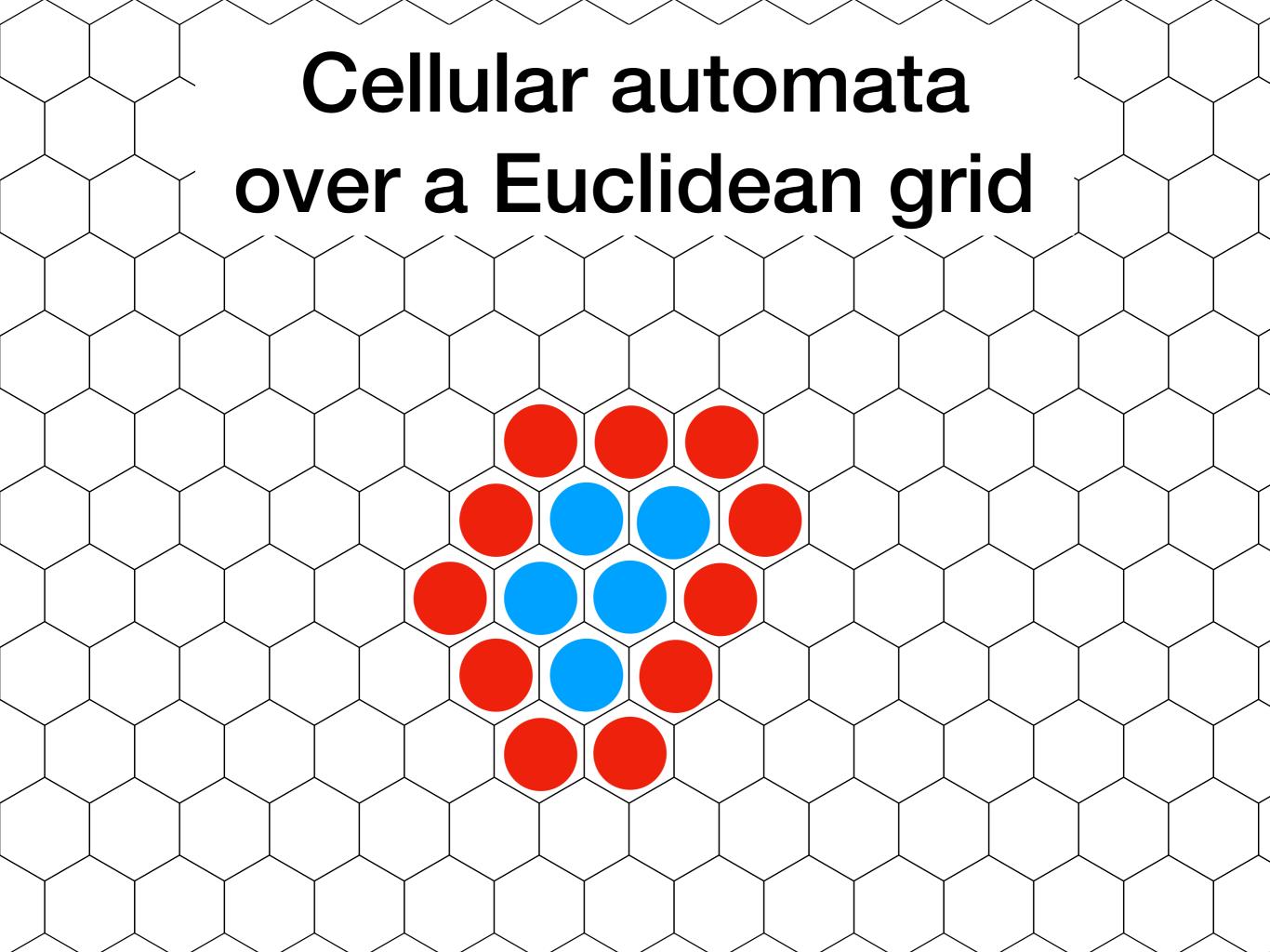


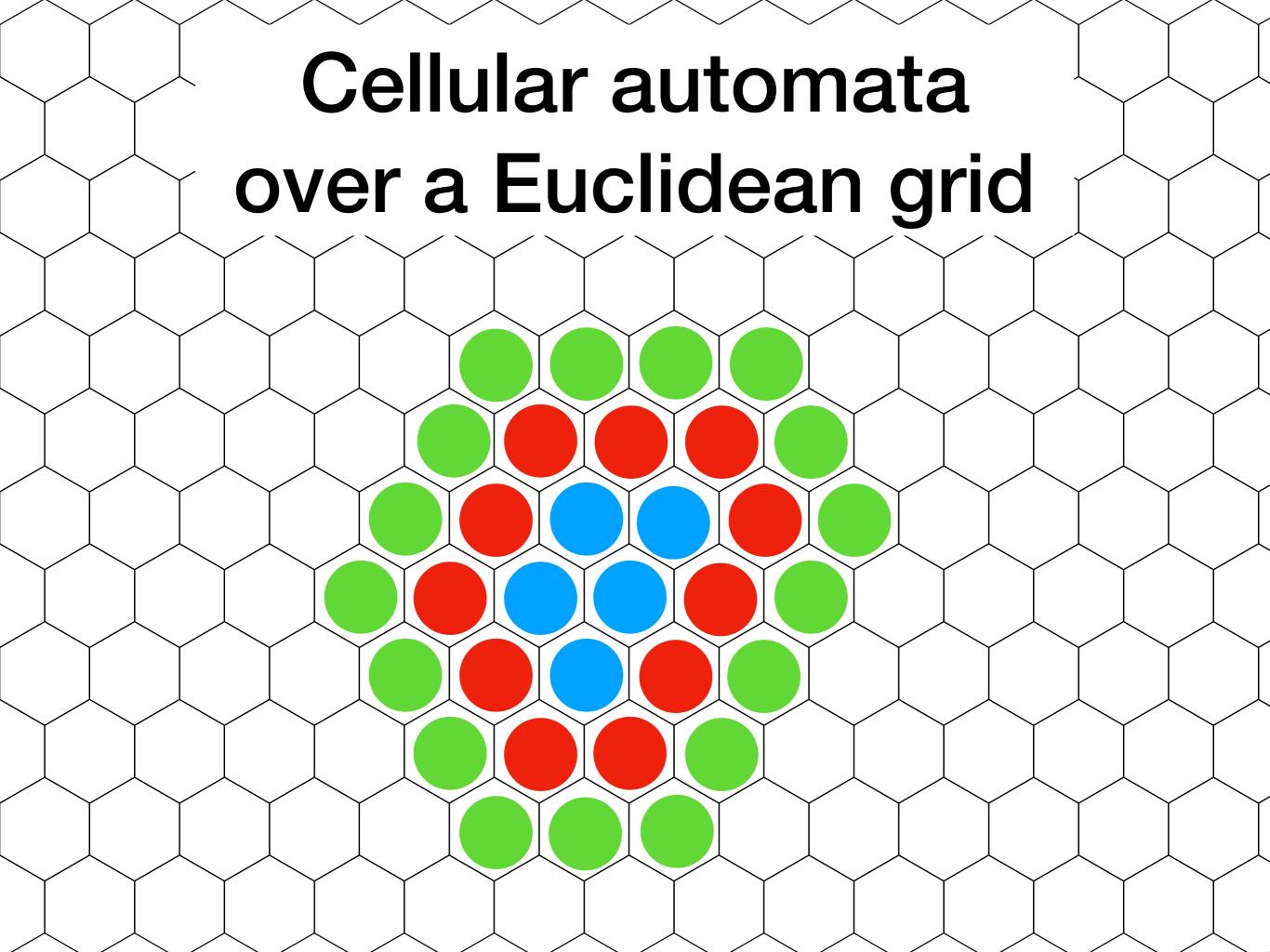


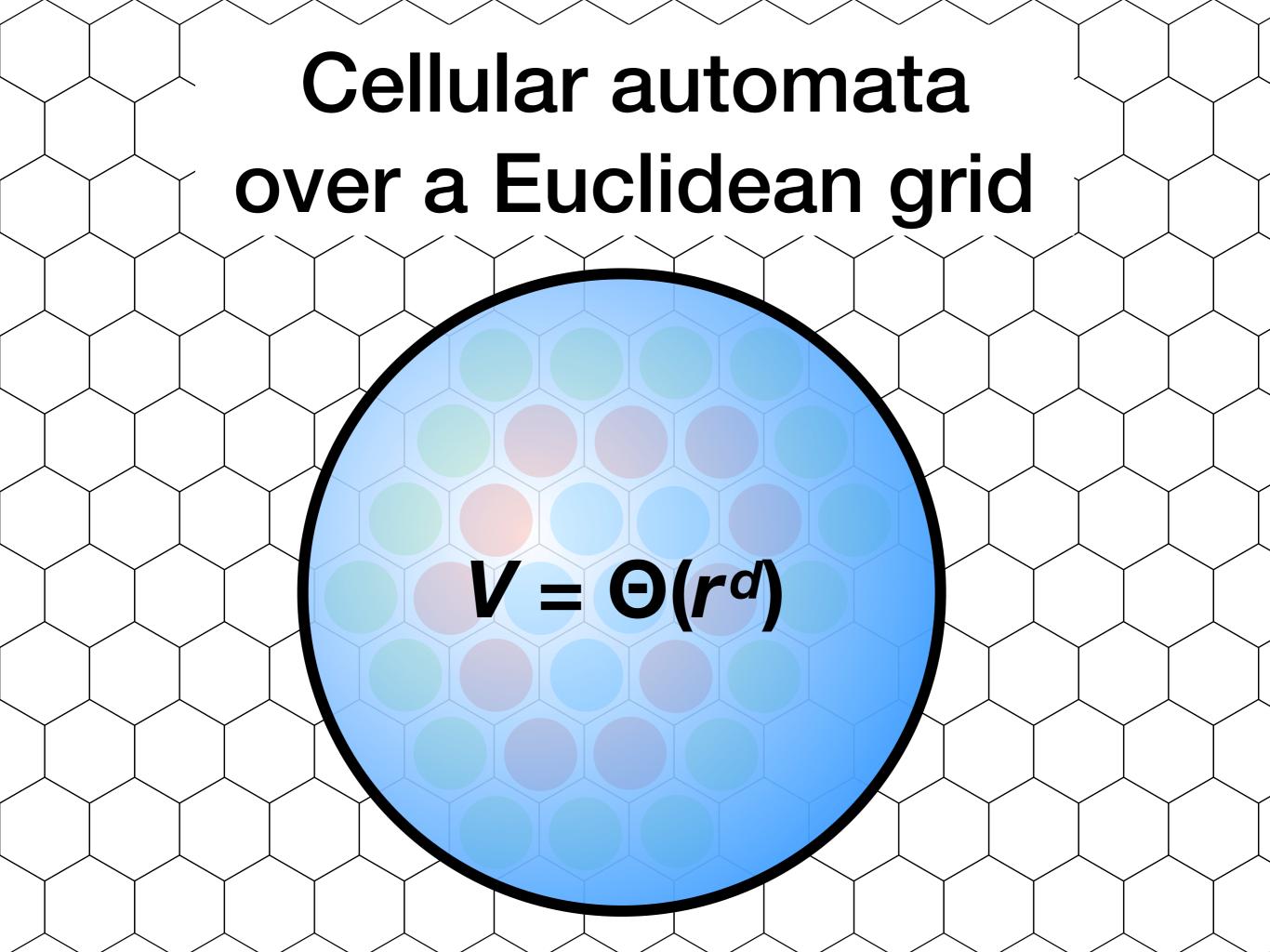


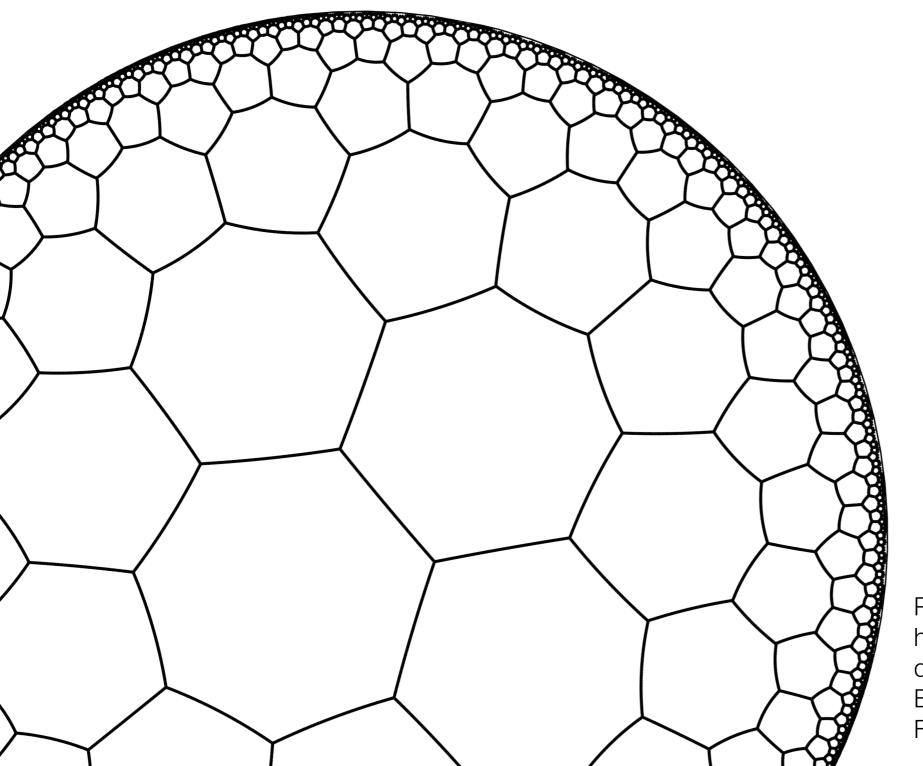


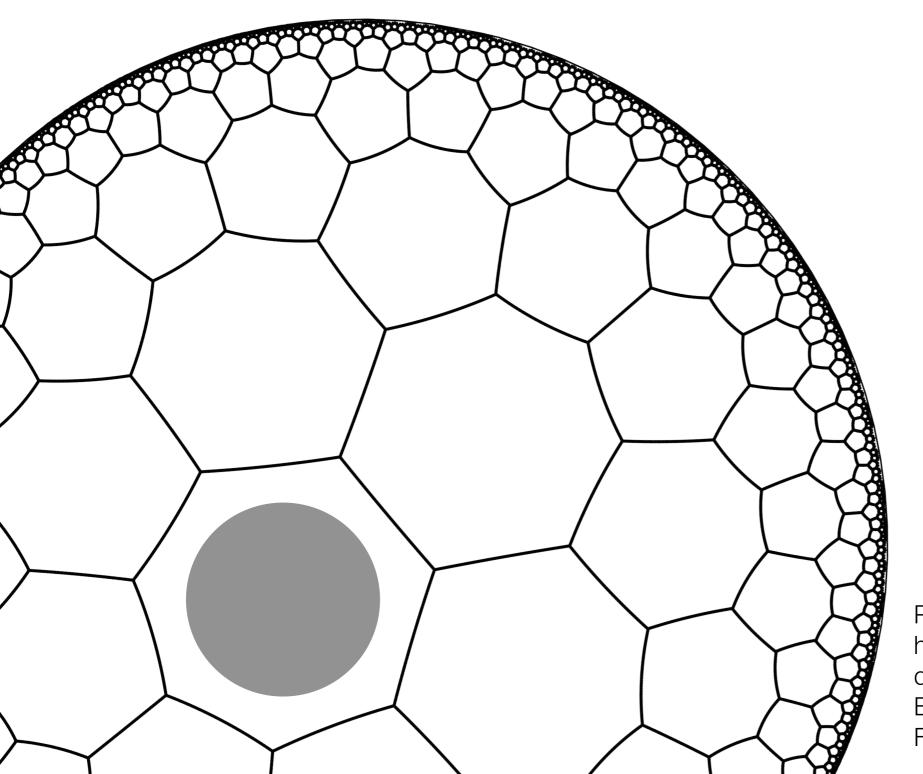


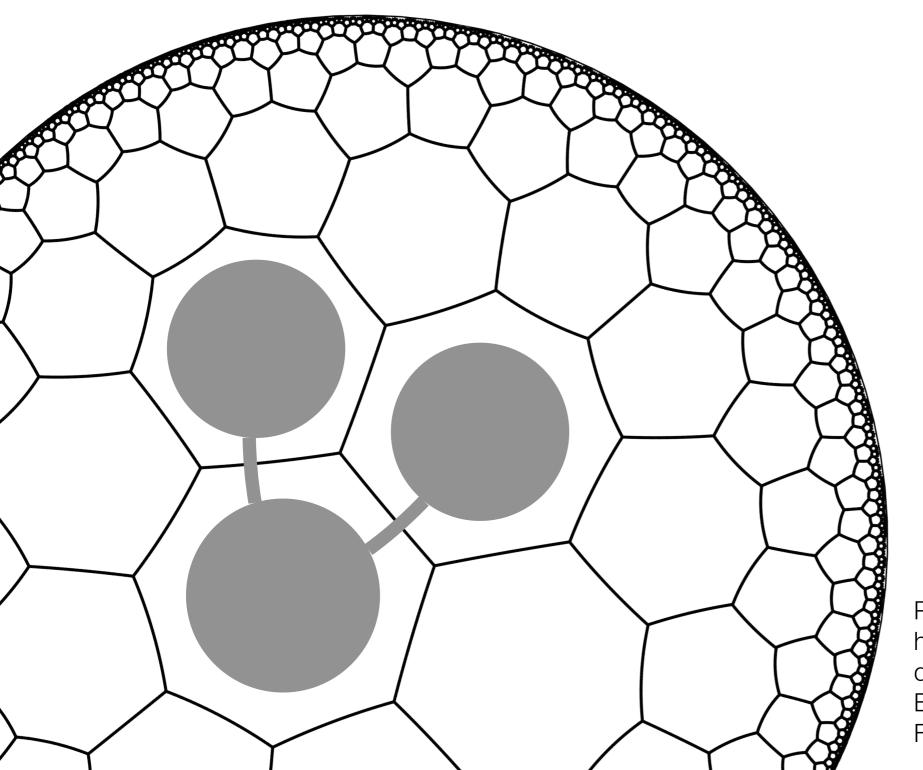


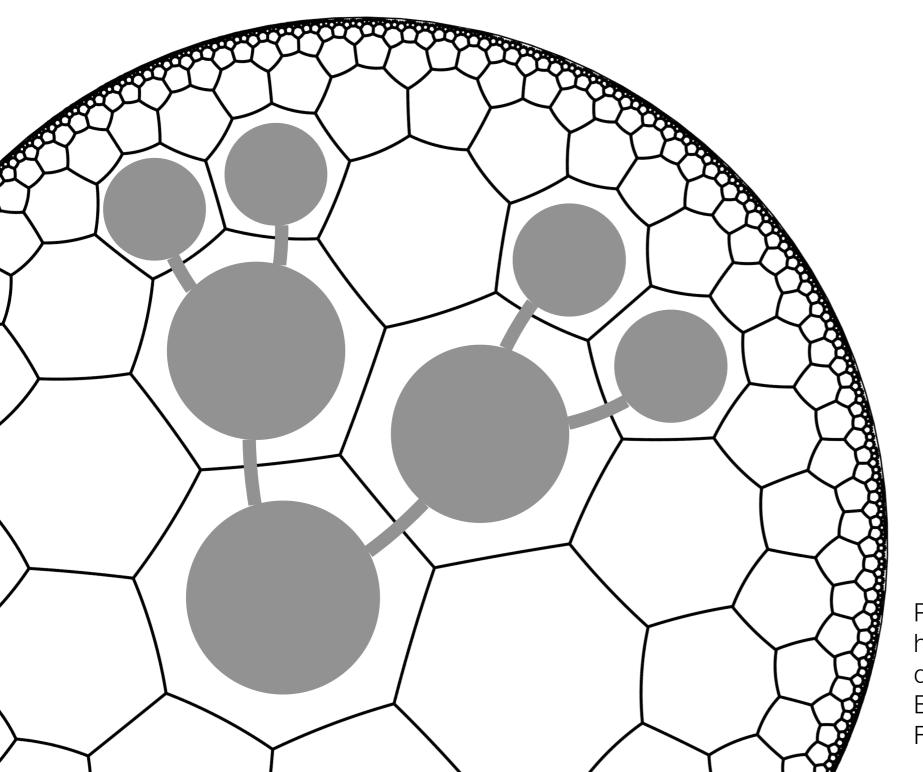


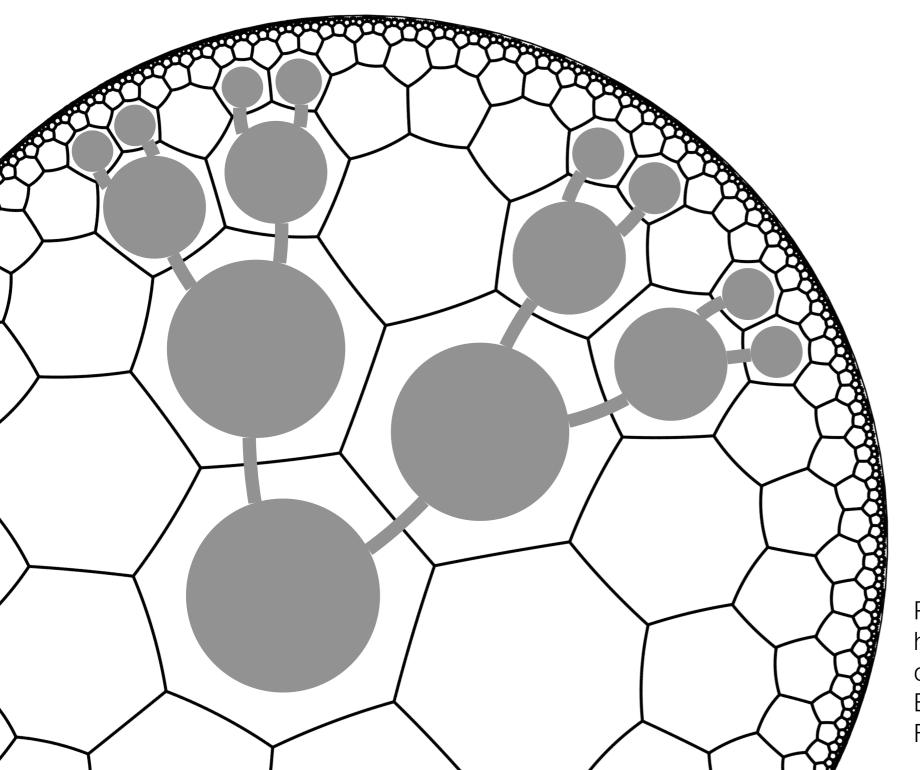


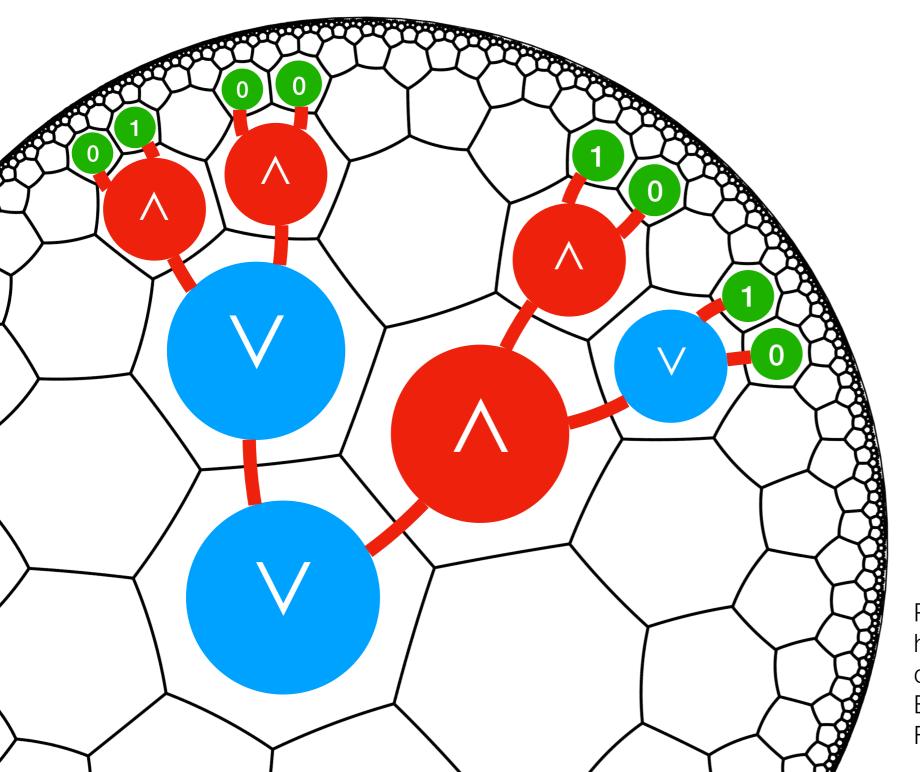


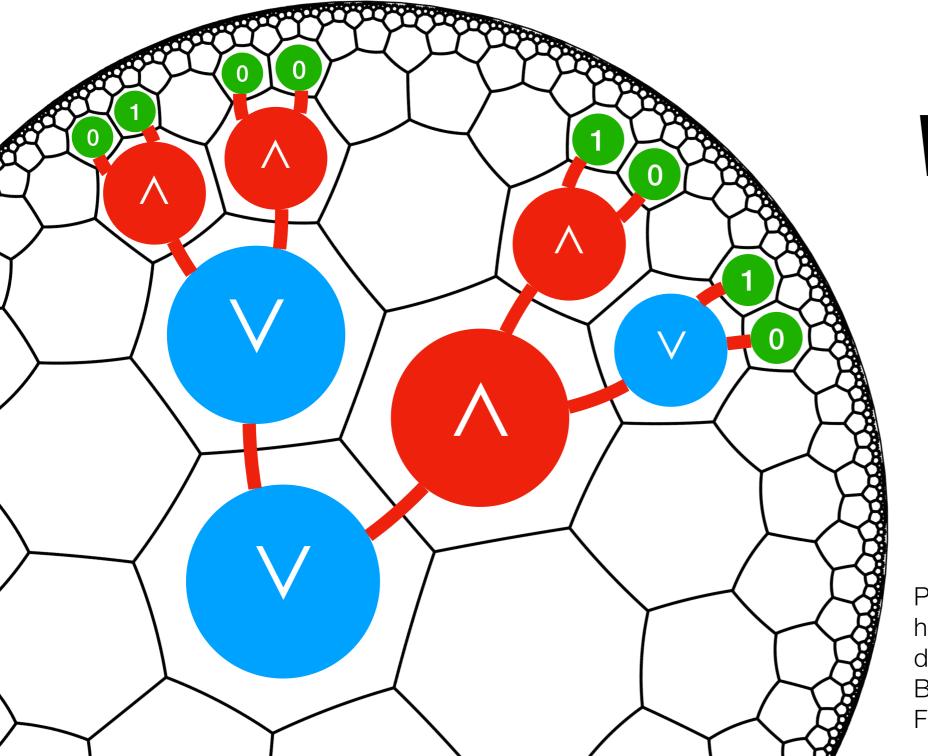












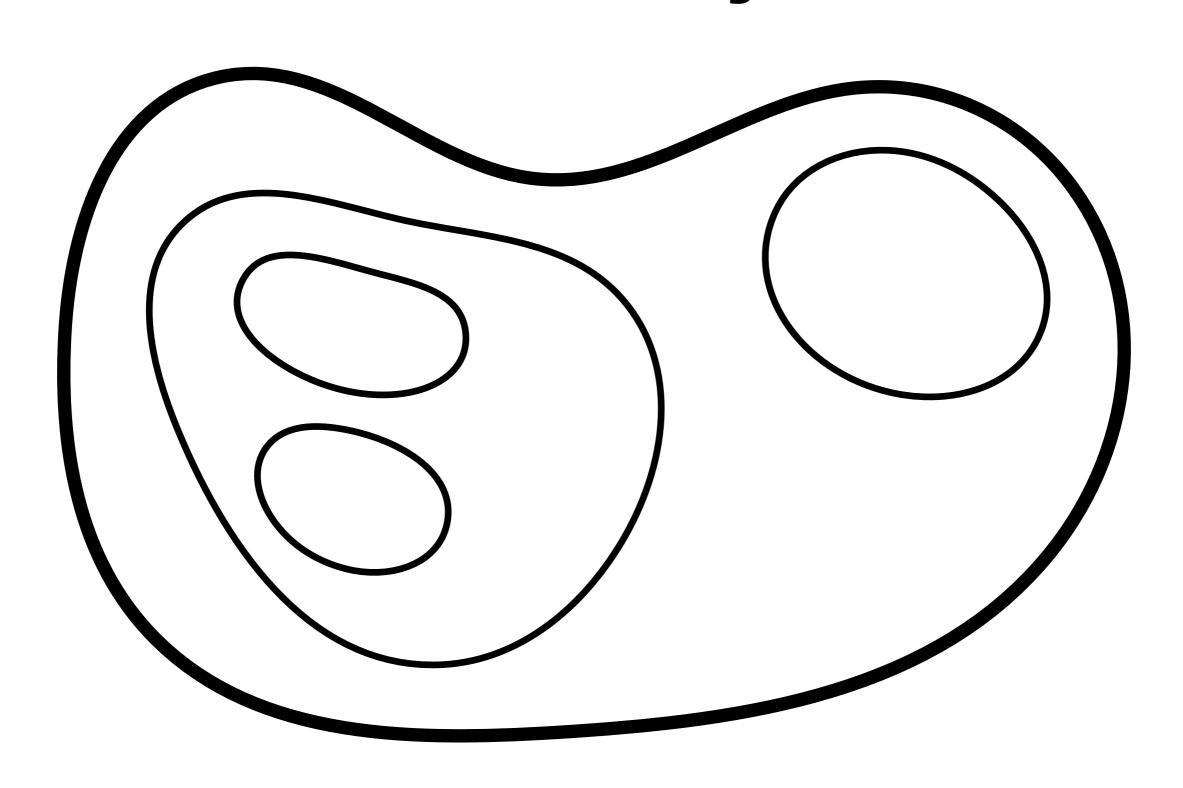
$$V = \Omega(2^r)$$

#### Rule of thumb

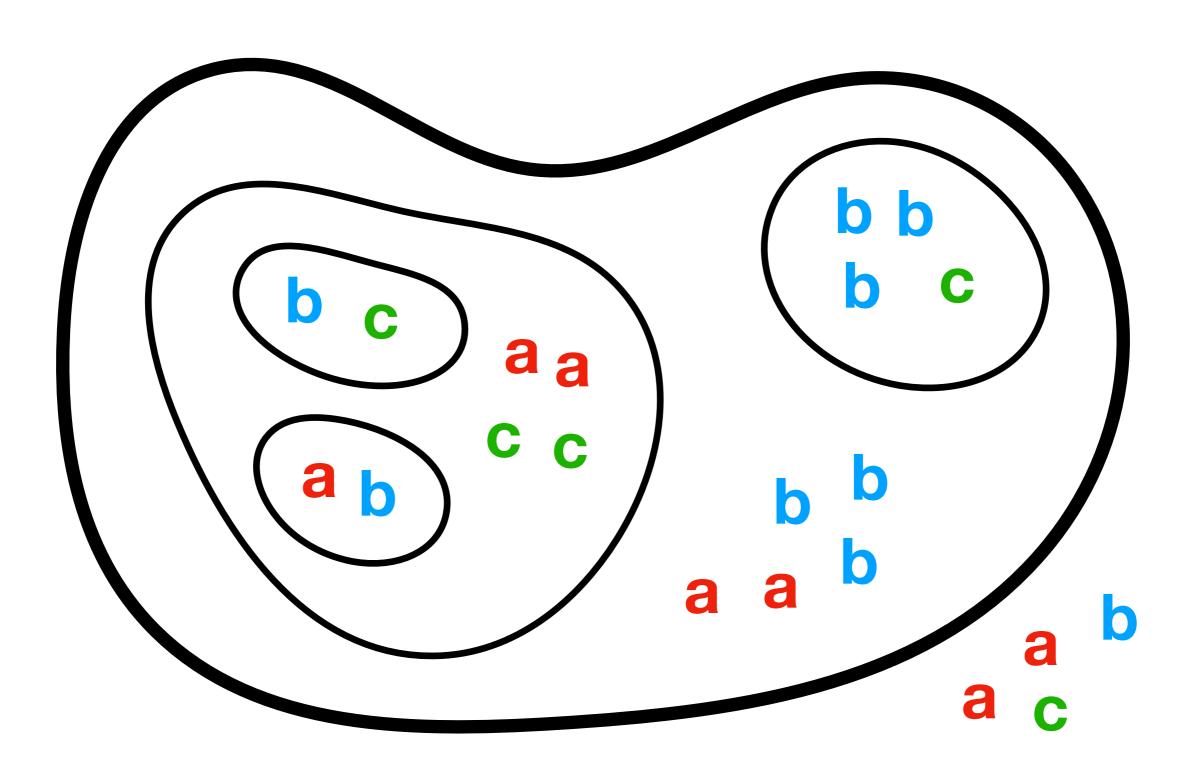
- Sequential machines are first class
- (Constant or polynomial) bounded parallel machines are also first class
- Unbounded (or exponential bounded) parallel machines are second class
- Apparently, this holds even for unconventional computing models

# A "more unconventional" model of computation: membrane systems

#### Membrane systems

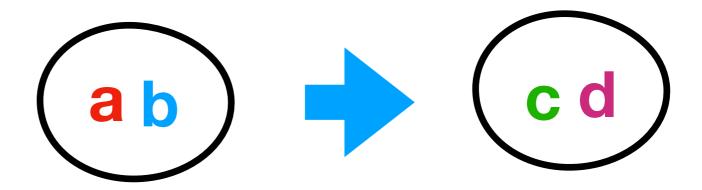


#### Membrane systems



$$[ab \rightarrow cd]$$

$$[a] \rightarrow [] b$$



$$[a] \rightarrow [] b$$

$$[ab \rightarrow cd]$$

$$[a] \rightarrow [] b$$

$$[a] \rightarrow [] b$$

$$[ab \rightarrow cd]$$

$$[a] \rightarrow []b$$

$$[a] \rightarrow [b]$$

$$[b]$$

$$[ab \rightarrow cd] \qquad ab \qquad cd$$

$$[a] \rightarrow []b \qquad a \qquad b$$

$$a[] \rightarrow [b] \qquad a \qquad b$$

$$[a] \rightarrow [b] [c] \qquad a \qquad b$$

$$[ab \rightarrow cd] \qquad ab \qquad cd$$

$$[a] \rightarrow []b \qquad a \qquad b$$

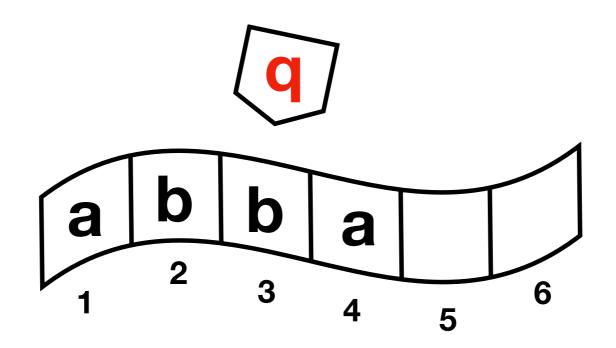
$$a[] \rightarrow [b] \qquad b$$

$$"monodirectional"$$

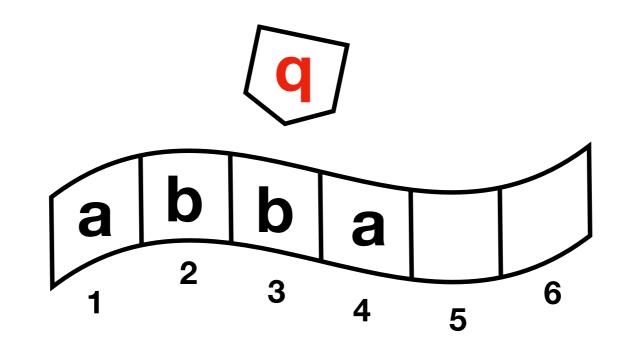
$$[a] \rightarrow [b] \qquad a \qquad b \qquad c$$

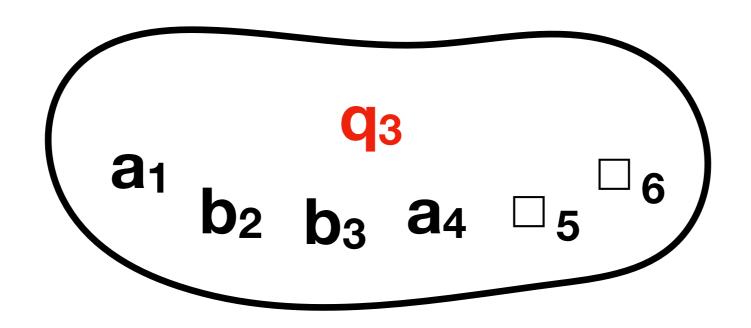
# Simulating Turing machines with membrane systems

### Encoding the configuration

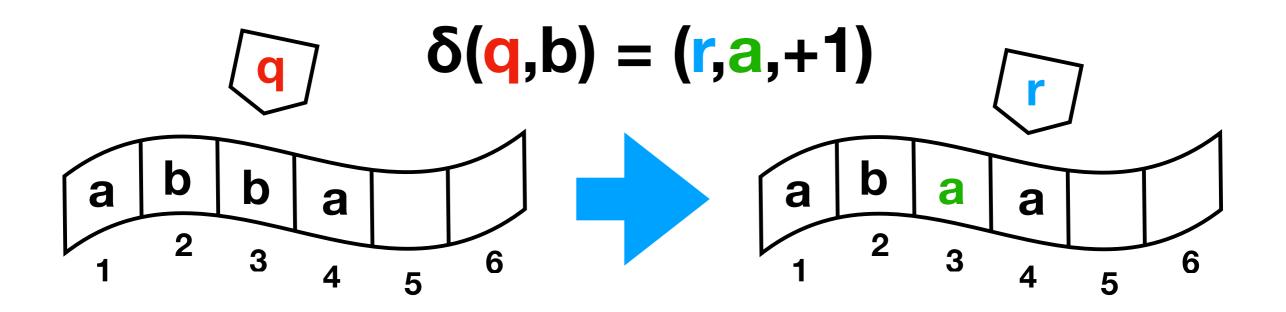


### Encoding the configuration

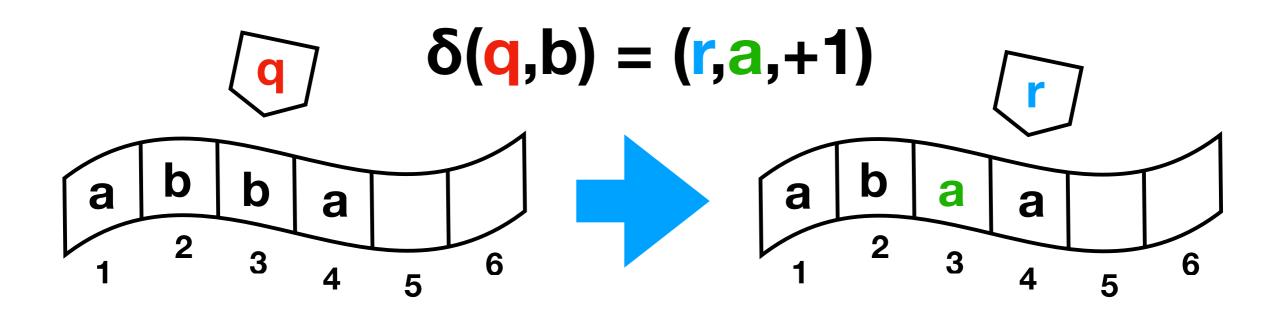


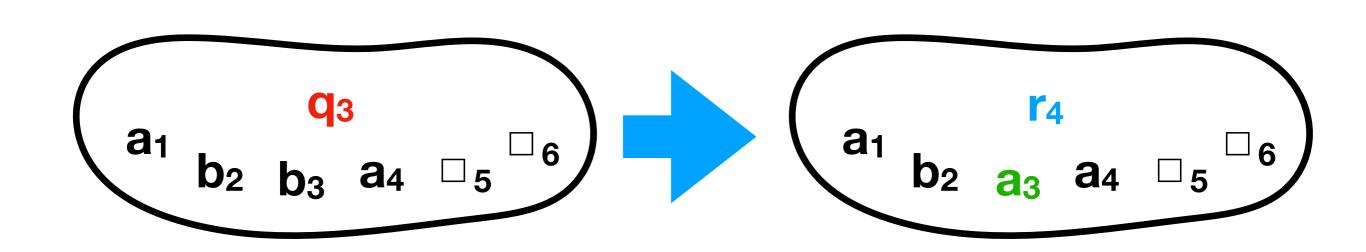


# Simulating transitions

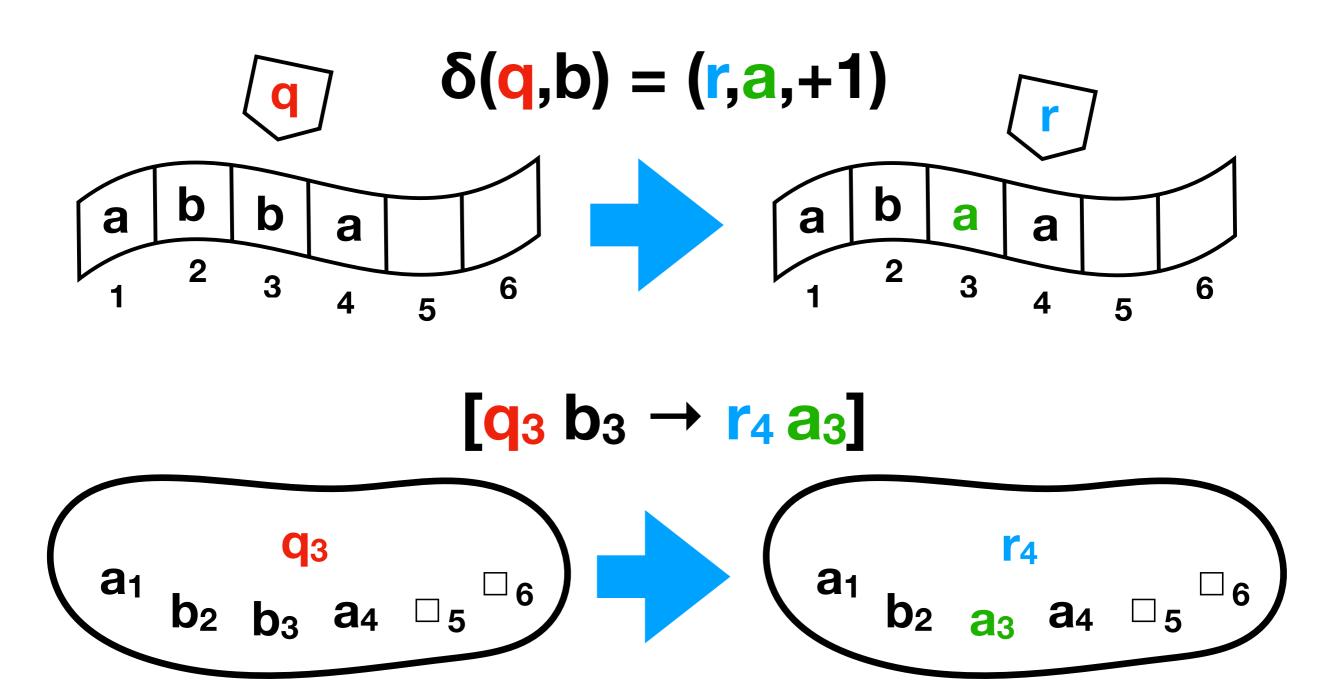


# Simulating transitions





# Simulating transitions



#### Simulating nondeterminism

$$\delta(q,b) = \begin{cases} (r,a,+1) \\ (s,b,-1) \end{cases}$$

$$\begin{vmatrix} a & b & a & a \\ 1 & 2 & 3 & 4 & 5 & 6 \\ \end{vmatrix}$$

$$\begin{vmatrix} a & b & b & a \\ 1 & 2 & 3 & 4 & 5 & 6 \\ \end{vmatrix}$$

#### Simulating nondeterminism

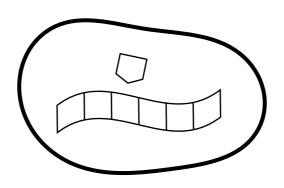
$$\delta(\mathbf{q},\mathbf{b}) = \begin{cases} (\mathbf{r},\mathbf{a},+1) \\ (\mathbf{s},\mathbf{b},-1) \end{cases}$$

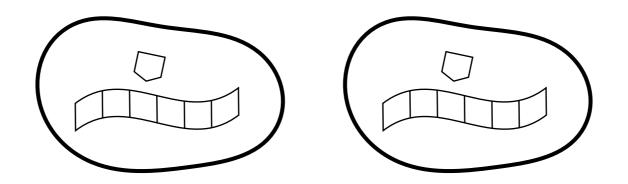
$$\begin{bmatrix} \mathbf{q}_{3} \\ \mathbf{a}_{1} \\ \mathbf{b}_{2} \\ \mathbf{b}_{3} \\ \mathbf{a}_{4} \\ \mathbf{b}_{5} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{3} \\ \mathbf{a}_{1} \\ \mathbf{b}_{2} \\ \mathbf{a}_{3} \\ \mathbf{a}_{4} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{3} \\ \mathbf{a}_{1} \\ \mathbf{b}_{2} \\ \mathbf{a}_{3} \\ \mathbf{a}_{4} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{3} \\ \mathbf{a}_{1} \\ \mathbf{b}_{2} \\ \mathbf{a}_{3} \\ \mathbf{a}_{4} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{3} \\ \mathbf{a}_{1} \\ \mathbf{b}_{2} \\ \mathbf{a}_{3} \\ \mathbf{a}_{4} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{3} \\ \mathbf{a}_{1} \\ \mathbf{b}_{2} \\ \mathbf{a}_{3} \\ \mathbf{a}_{4} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{3} \\ \mathbf{a}_{1} \\ \mathbf{b}_{2} \\ \mathbf{a}_{3} \\ \mathbf{a}_{4} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{3} \\ \mathbf{a}_{1} \\ \mathbf{b}_{2} \\ \mathbf{a}_{3} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{3} \\ \mathbf{a}_{4} \\ \mathbf{a}_{5} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{3} \\ \mathbf{q}_{4} \\ \mathbf{a}_{5} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{4} \\ \mathbf{q}_{5} \\ \mathbf{a}_{5} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{4} \\ \mathbf{q}_{5} \\ \mathbf{q}_{5} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{4} \\ \mathbf{q}_{5} \\ \mathbf{q}_{5} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{4} \\ \mathbf{q}_{5} \\ \mathbf{q}_{5} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{5} \\ \mathbf{q}_{5} \\ \mathbf{q}_{$$

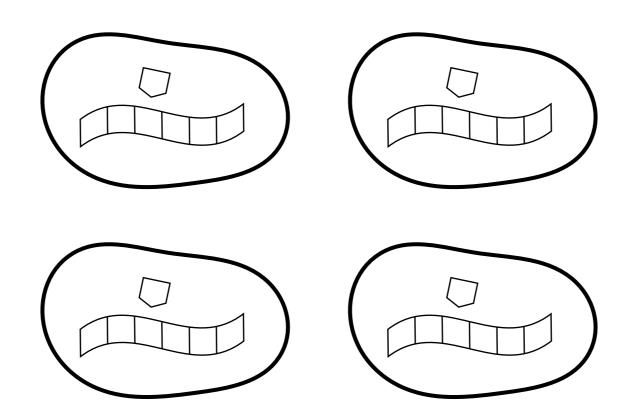
#### Simulating nondeterminism

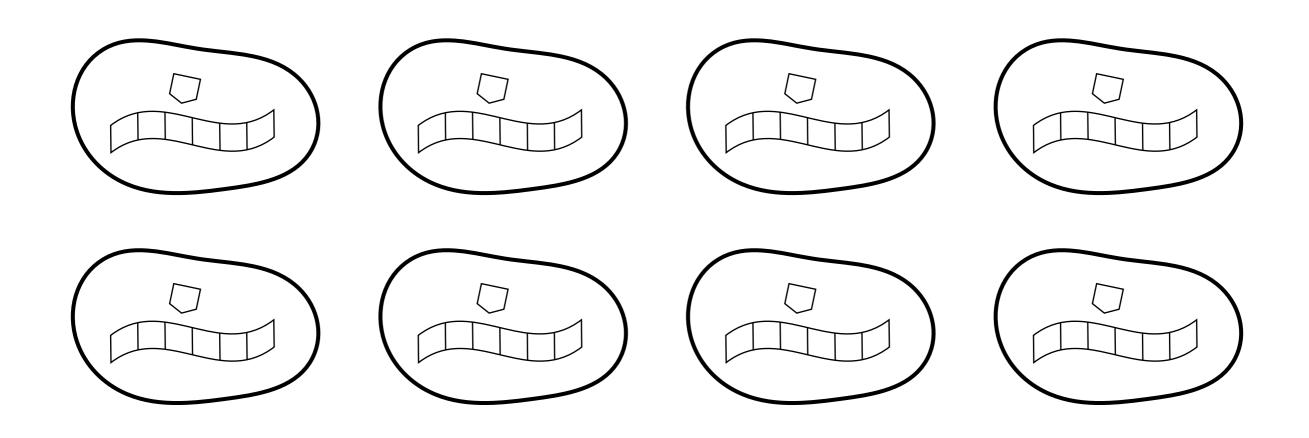
$$\delta(\mathbf{q},\mathbf{b}) = \begin{cases} (\mathbf{r},\mathbf{a},+1) \\ (\mathbf{s},\mathbf{b},-1) \end{cases} \quad [\mathbf{q}_3\mathbf{b}_3] \to [\mathbf{r}_4\mathbf{a}_3] \begin{bmatrix} \mathbf{s}_2\mathbf{b}_3 \end{bmatrix}$$

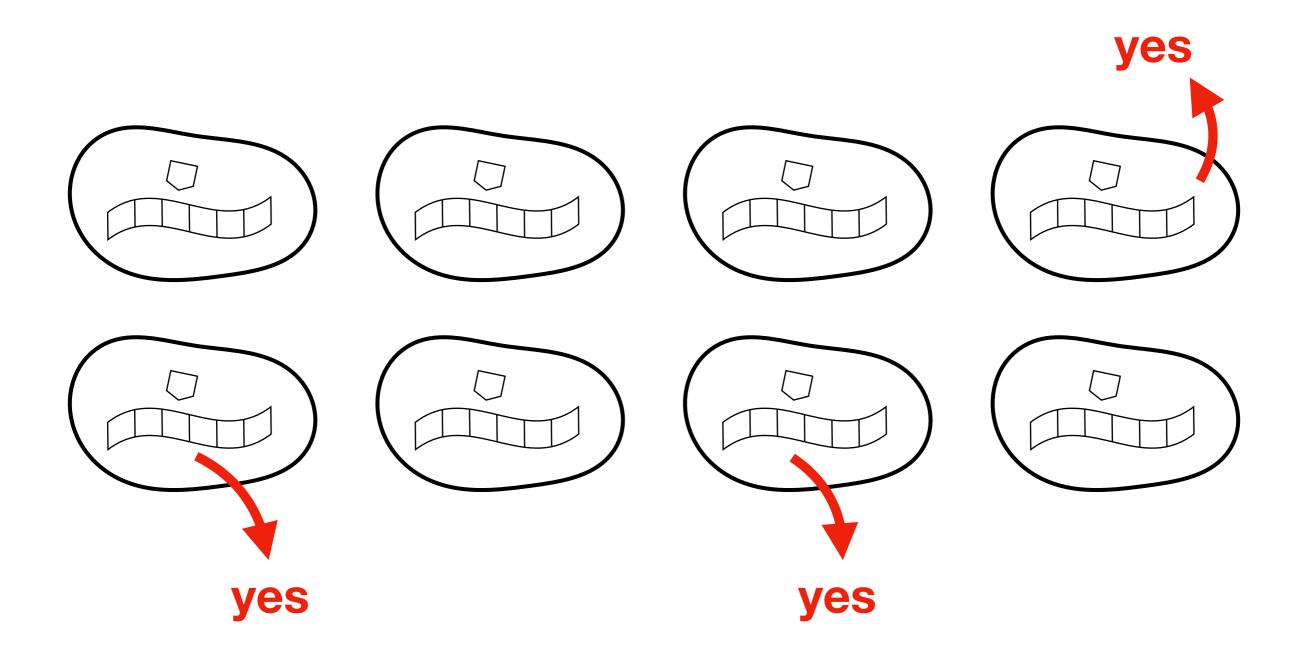
$$\begin{vmatrix} \mathbf{q}_3 \\ \mathbf{a}_1 \\ \mathbf{b}_2 \\ \mathbf{a}_3 \end{vmatrix} \begin{vmatrix} \mathbf{q}_3 \\ \mathbf{a}_4 \end{vmatrix} \begin{vmatrix} \mathbf{q}_5 \\ \mathbf{a}_5 \end{vmatrix} \begin{vmatrix} \mathbf{q}_3 \\ \mathbf{a}_1 \end{vmatrix} \begin{vmatrix} \mathbf{q}_3 \\ \mathbf{b}_2 \end{vmatrix} \begin{vmatrix} \mathbf{q}_3 \\ \mathbf{a}_3 \end{vmatrix} \begin{vmatrix} \mathbf{q}_4 \\ \mathbf{a}_5 \end{vmatrix} \begin{vmatrix} \mathbf{q}_5 \\ \mathbf{a}_1 \end{vmatrix} \begin{vmatrix} \mathbf{q}_5 \\ \mathbf{q}_1 \end{vmatrix} \end{vmatrix} \begin{vmatrix} \mathbf{q}_5 \\ \mathbf{q}_1 \end{vmatrix} \end{vmatrix} \begin{vmatrix} \mathbf{q}_5 \\ \mathbf{q}_1 \end{vmatrix} \begin{vmatrix} \mathbf{q}_5 \\ \mathbf{q}_1 \end{vmatrix} \end{vmatrix} \begin{vmatrix} \mathbf{q}_5 \\ \mathbf{q}_1 \end{vmatrix} \begin{vmatrix} \mathbf{q}_5 \\ \mathbf{q}_1 \end{vmatrix} \begin{vmatrix} \mathbf{q}_5 \\ \mathbf{q}_$$

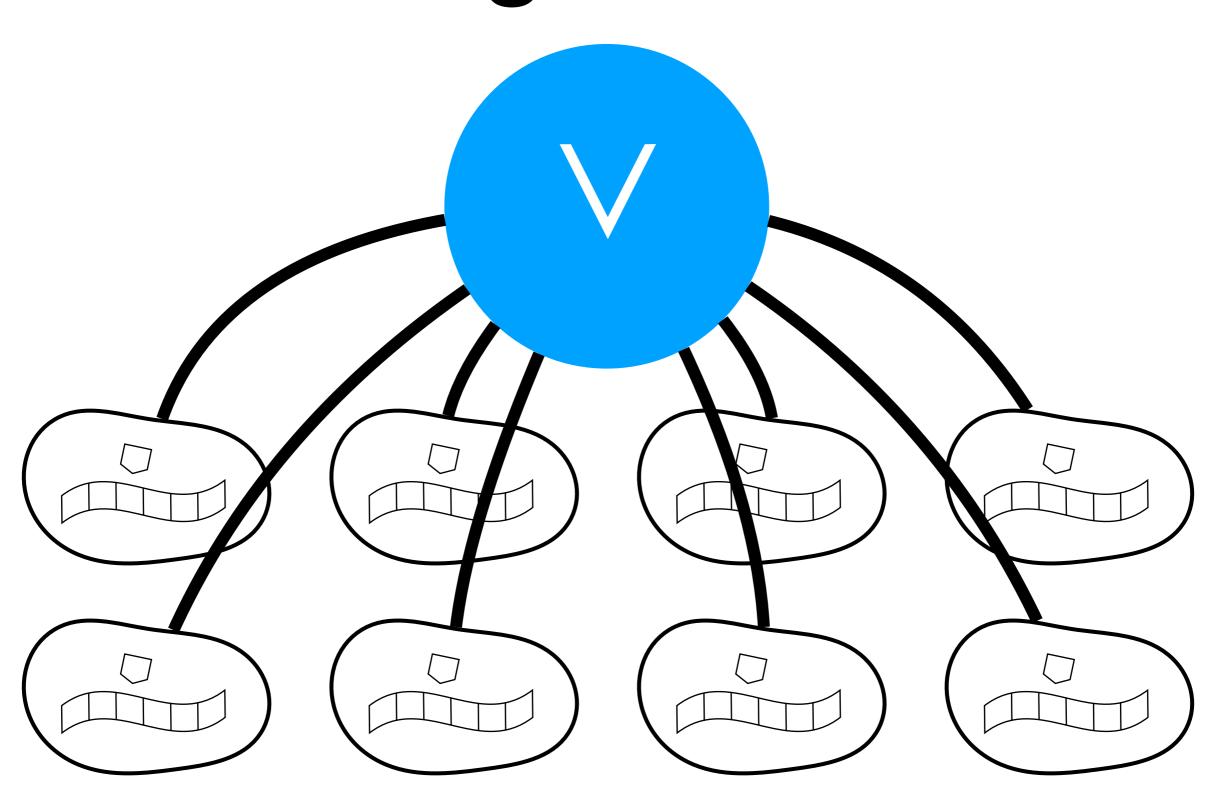






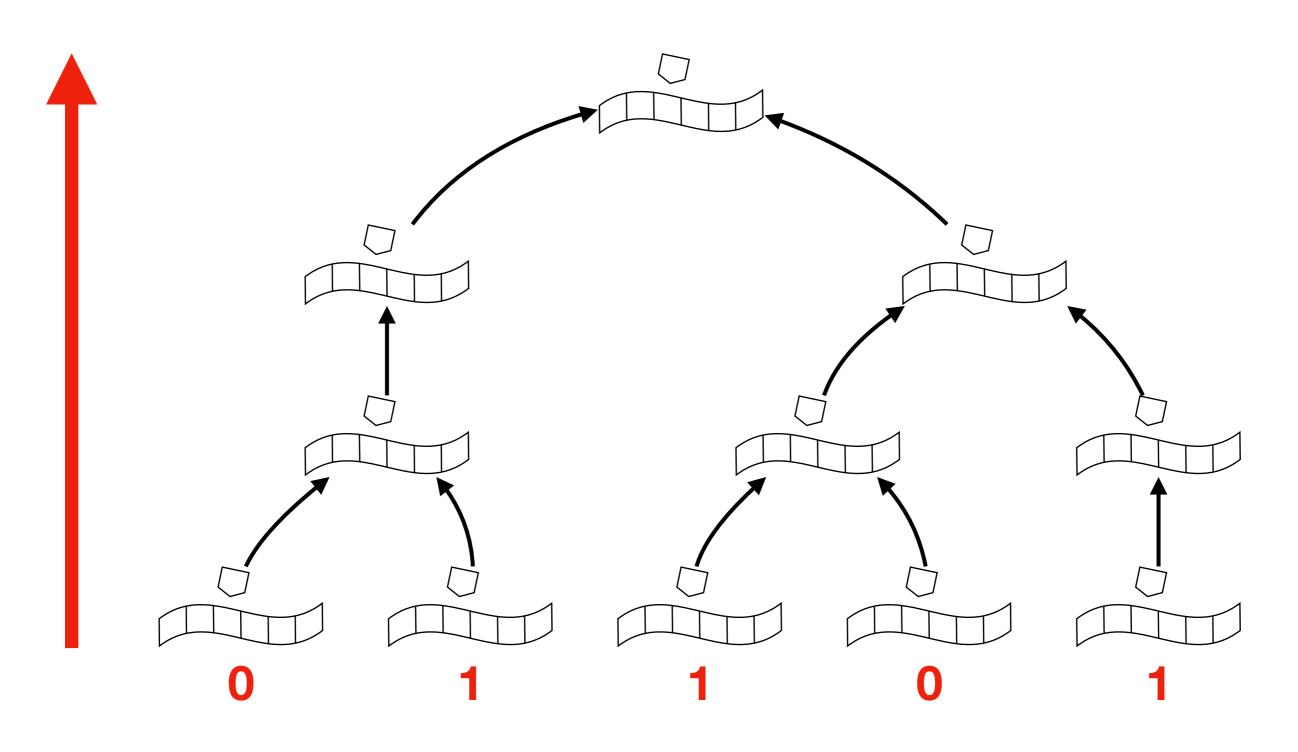




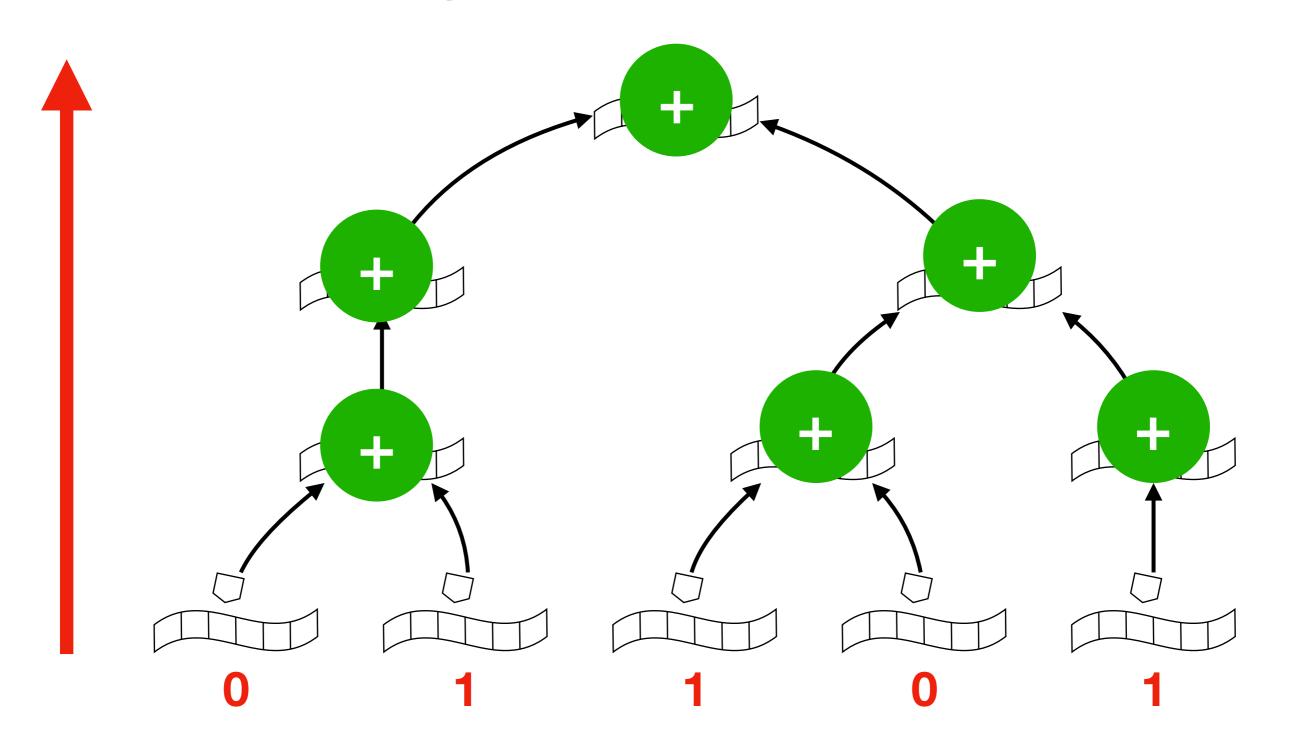


# Counting complexity

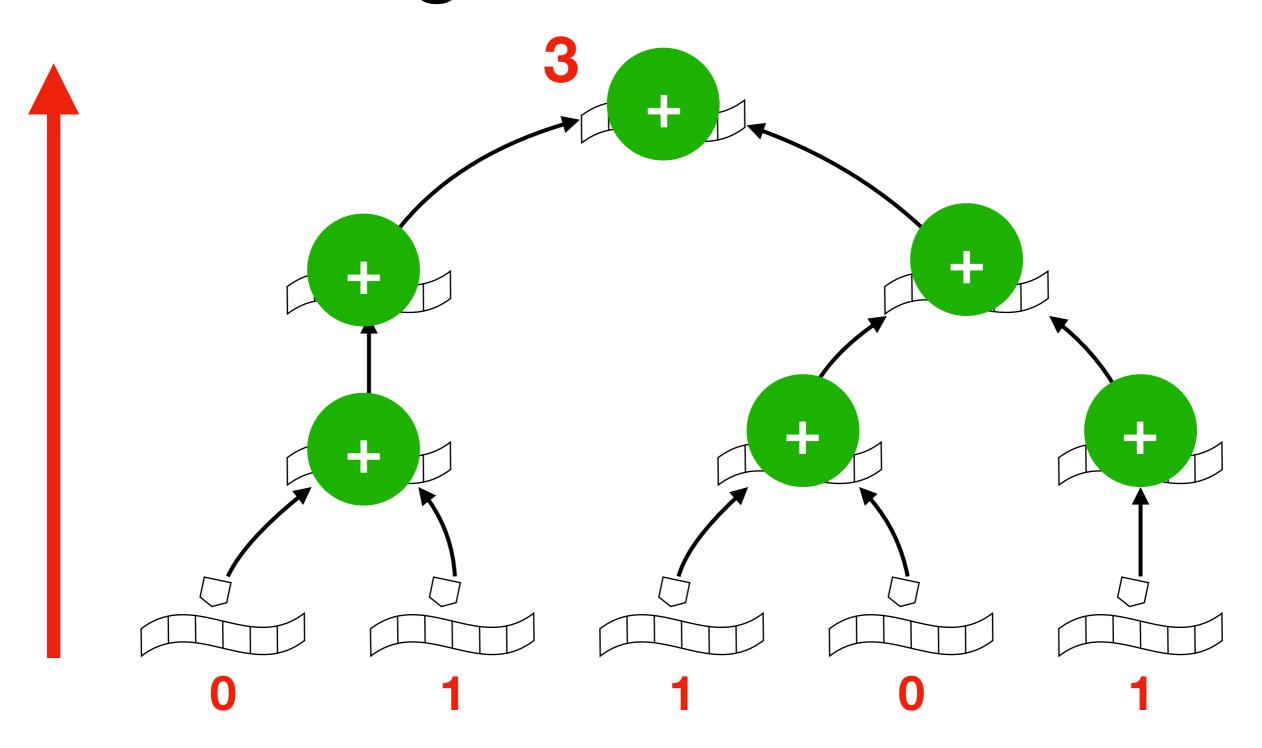
# Counting Turing machines: #P



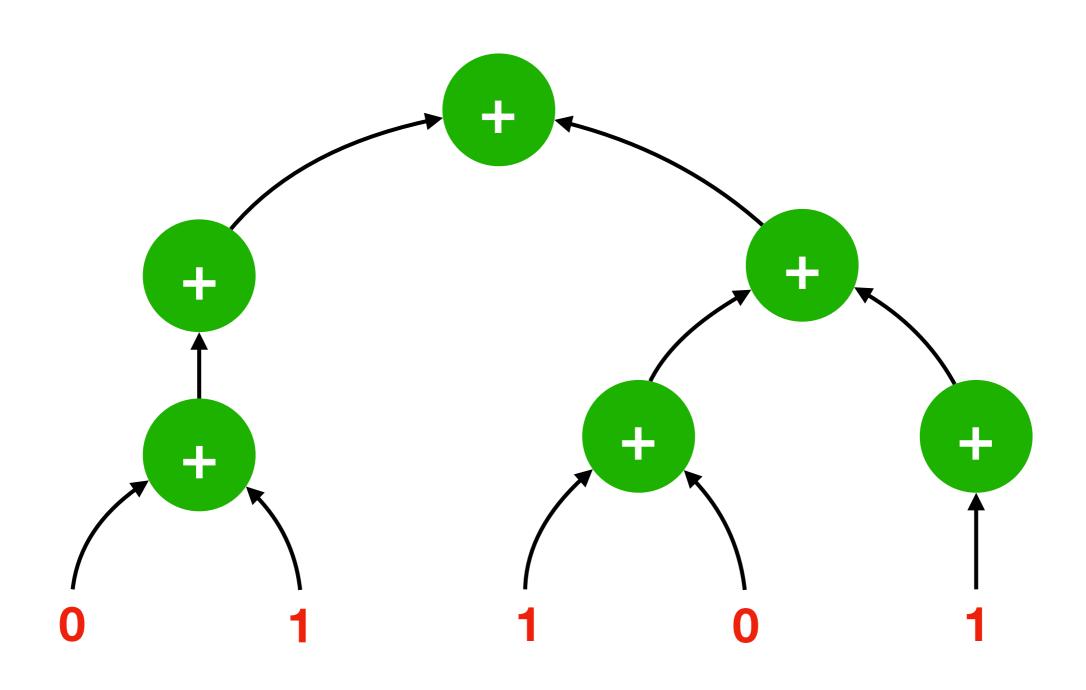
# Counting Turing machines: #P



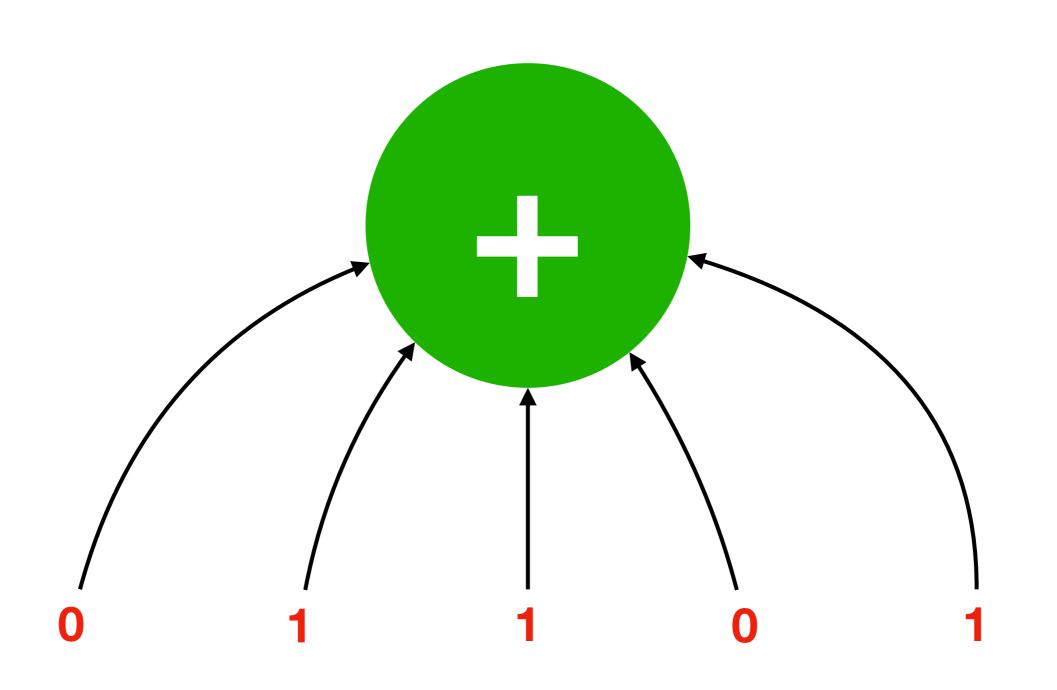
# Counting Turing machines: #P



# Flattening -circuits

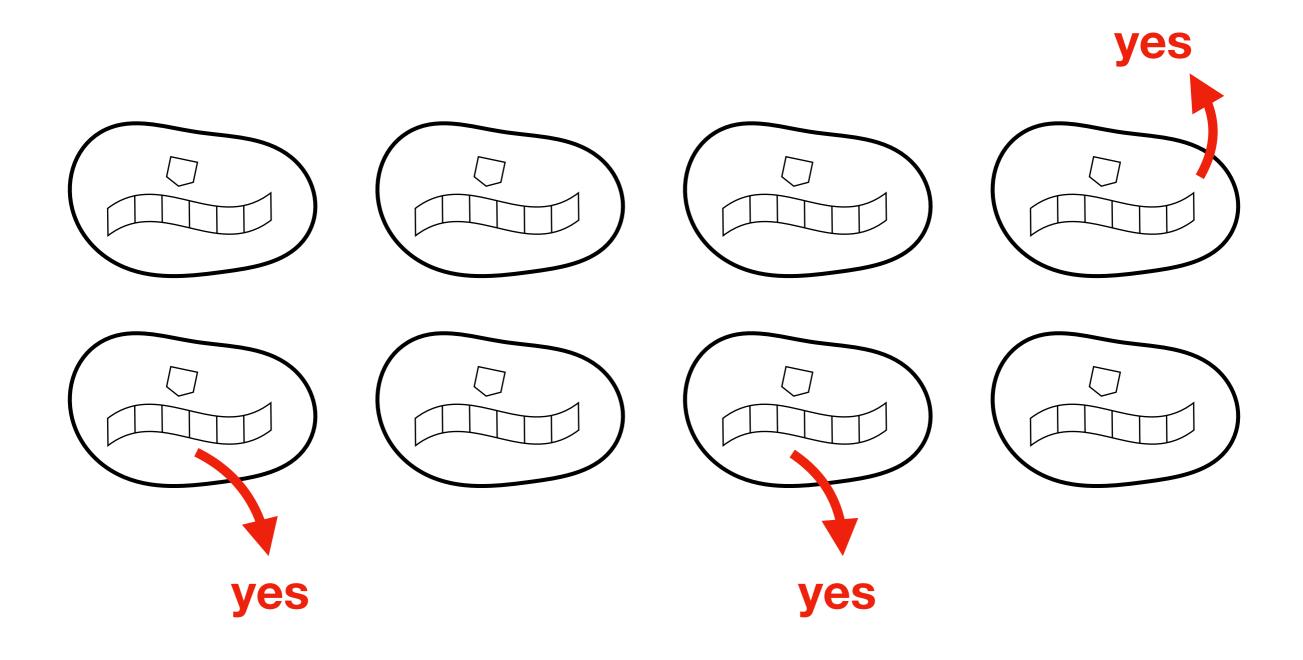


# Flattening -circuits

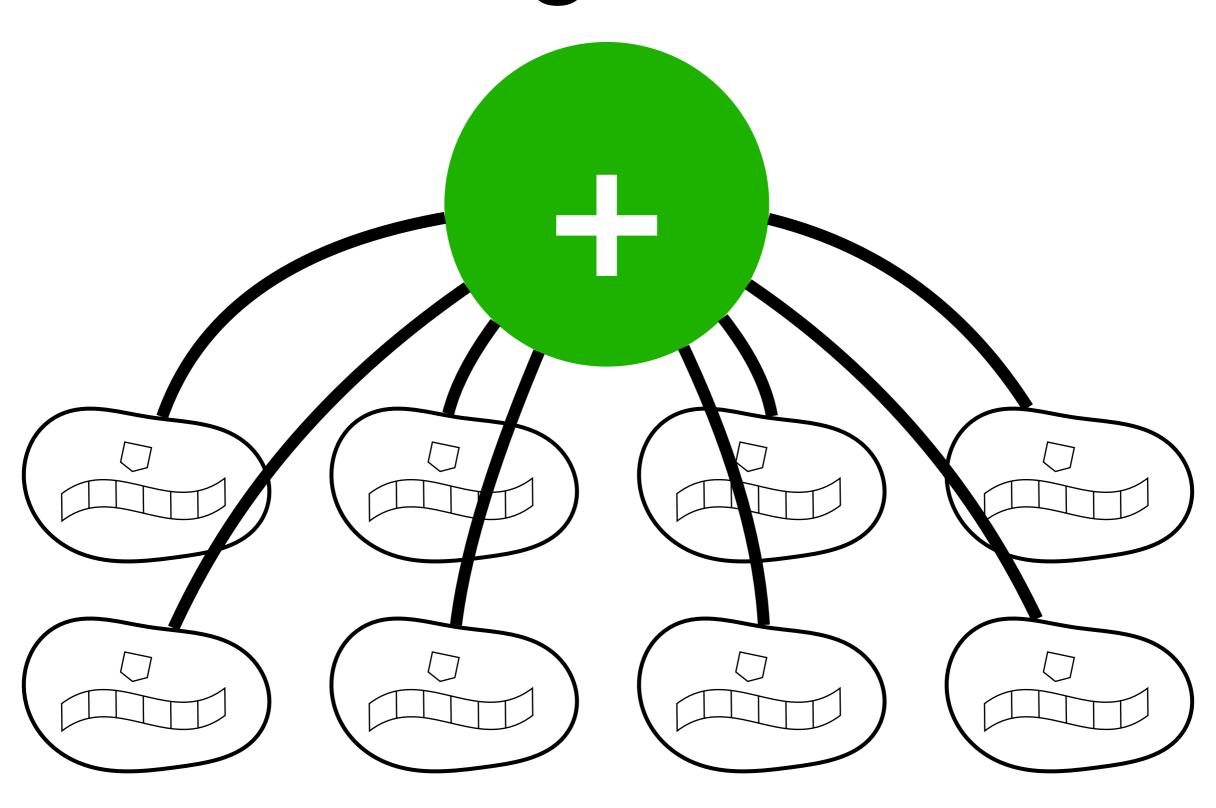


# Counting with membrane systems

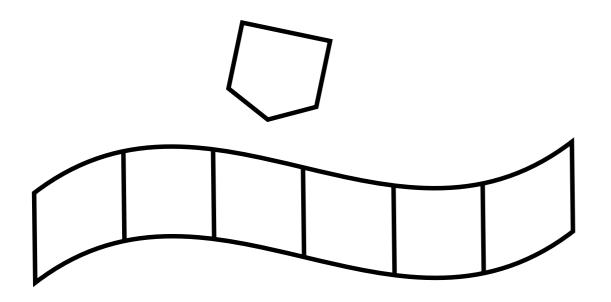
# Simulating CTM ⇒ #P

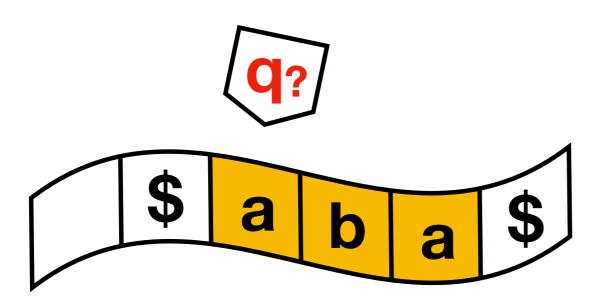


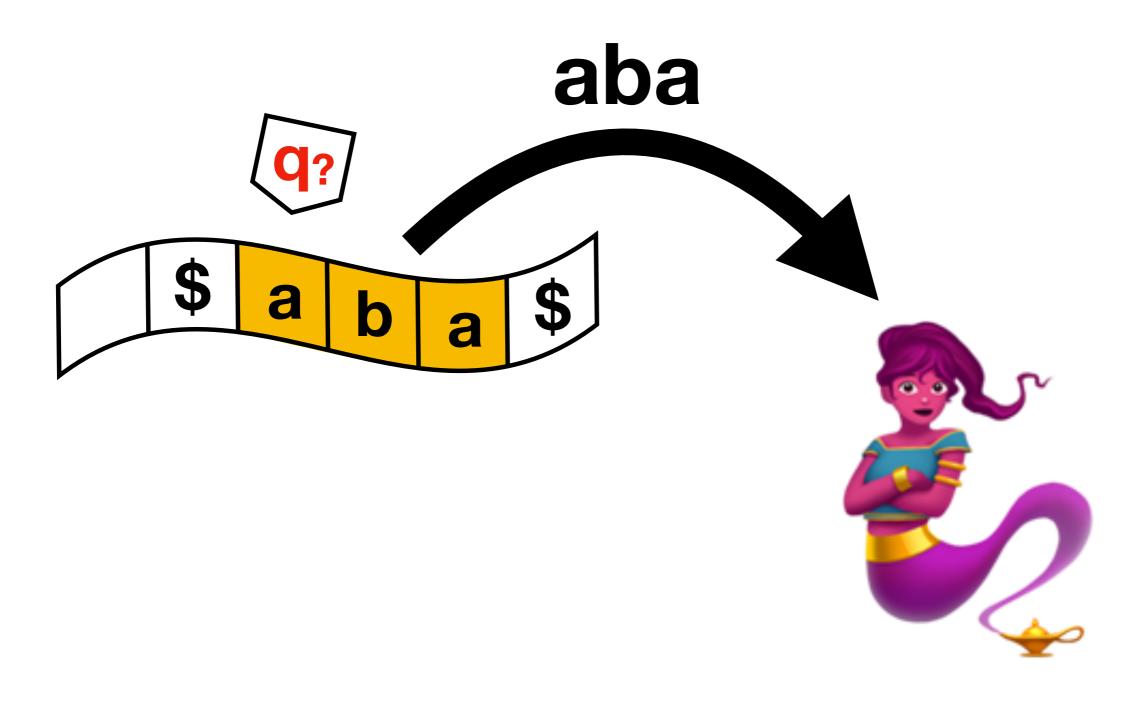
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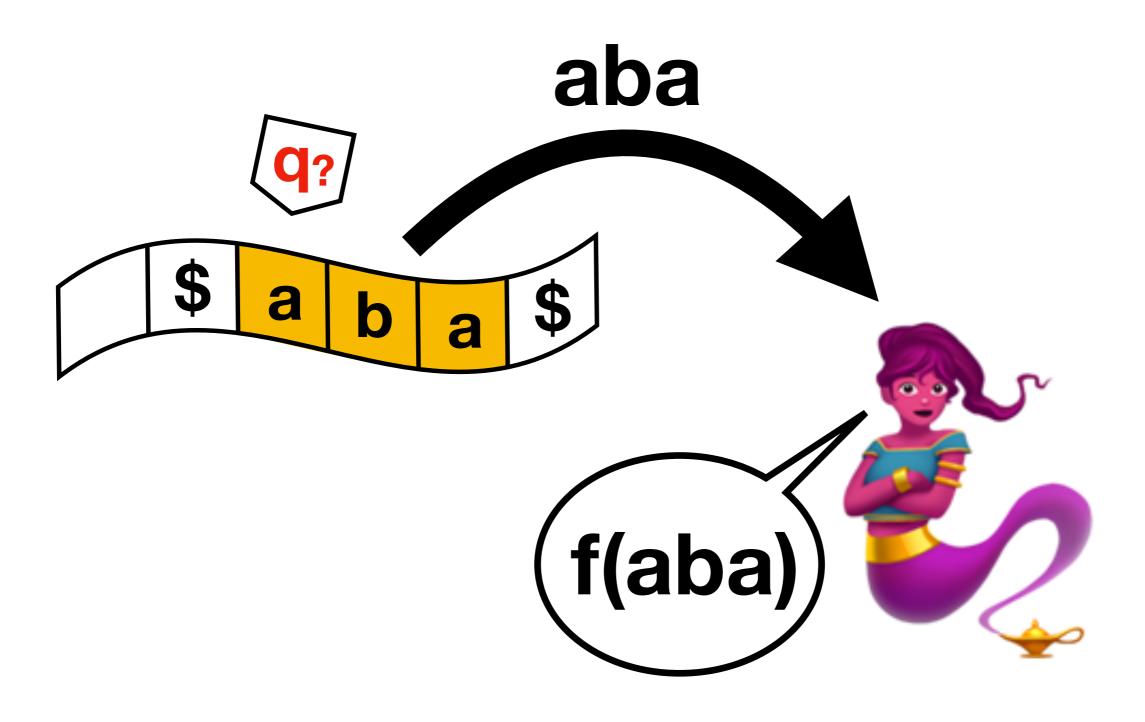


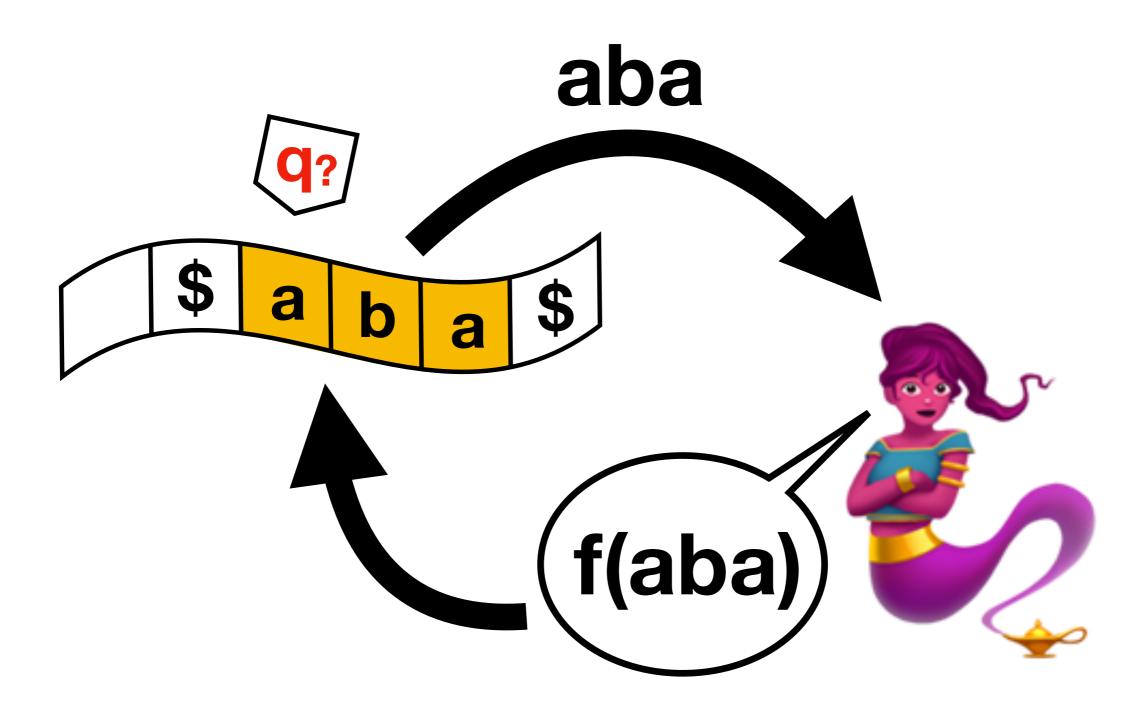
# Oracles &





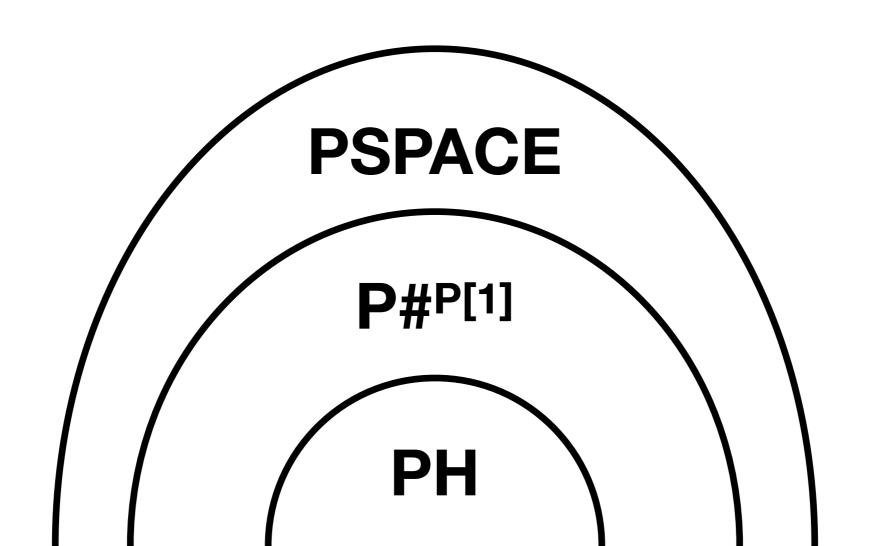






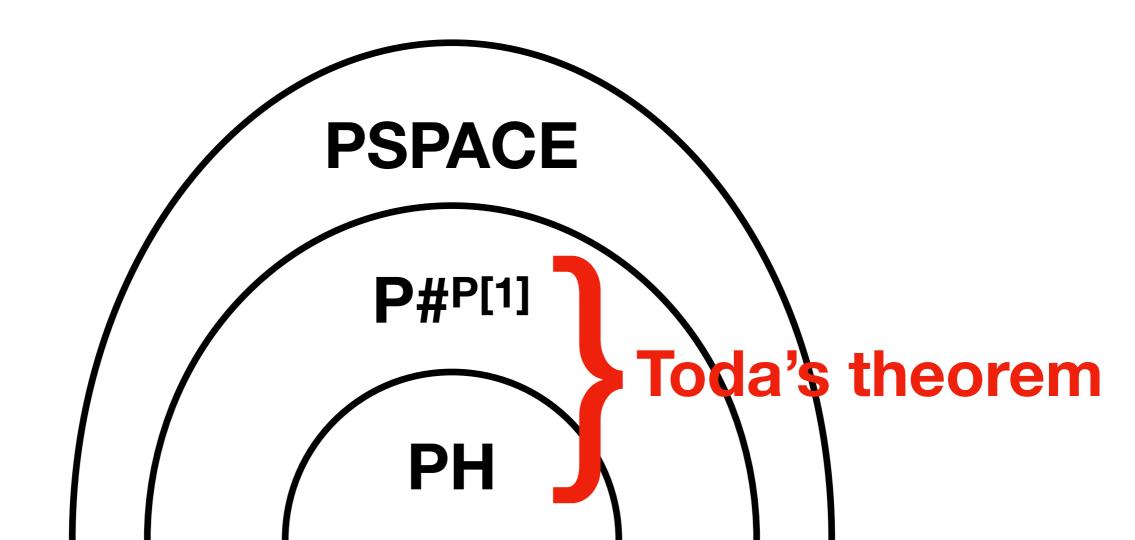
### The complexity class P#P[1]

The class of problems solved by polynomial-time Turing machines with a single query to an oracle for a #P-complete problem



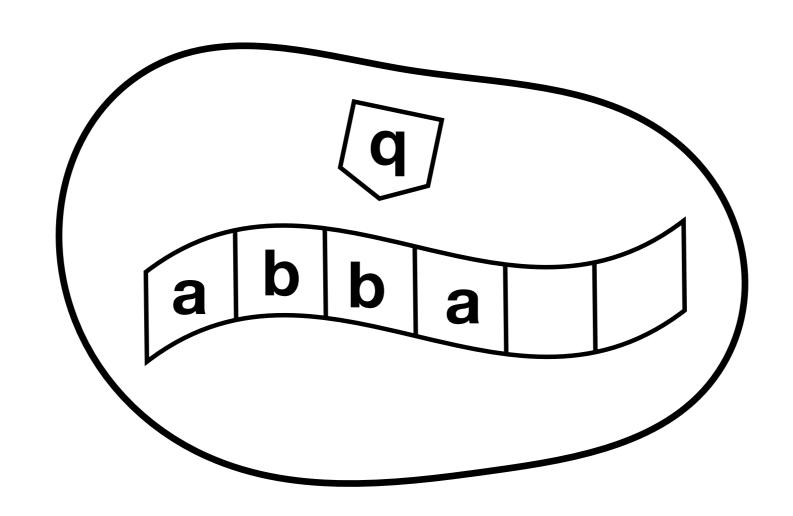
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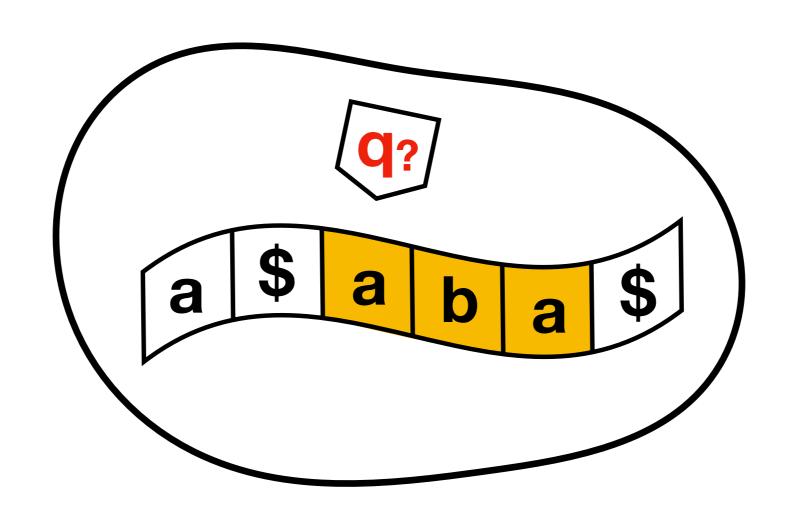


# Solving P<sup>#P[1]</sup> with (monodirectional, shallow) membrane systems

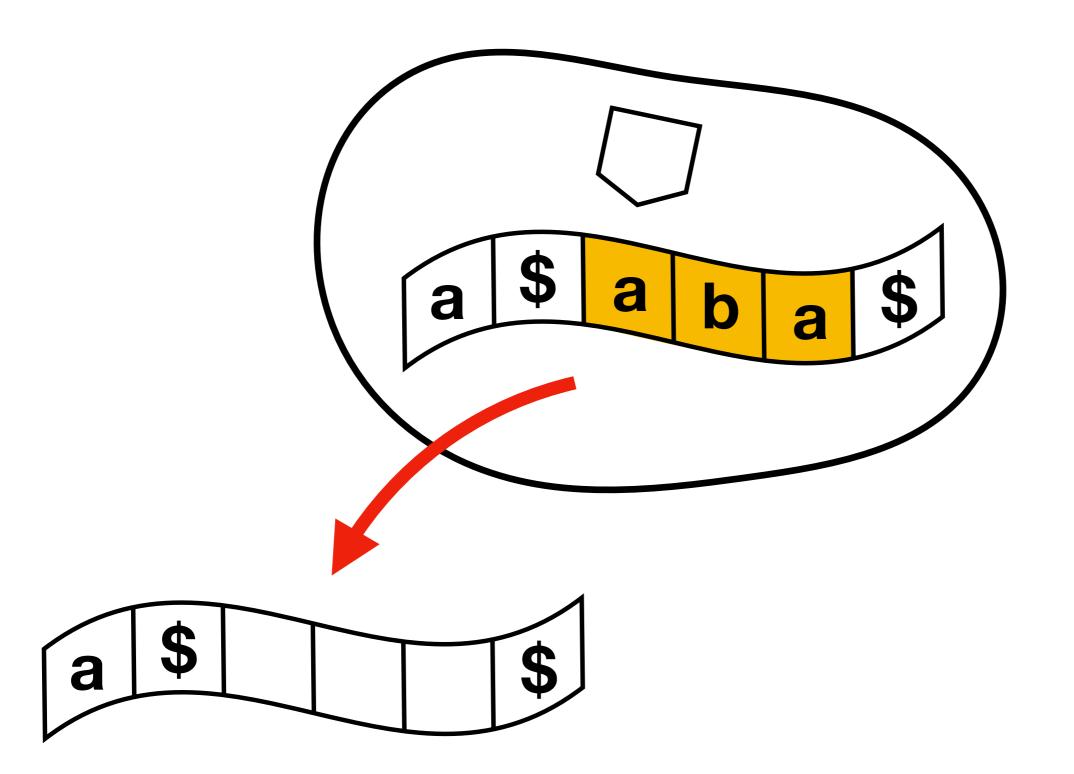
## Pre-query computation



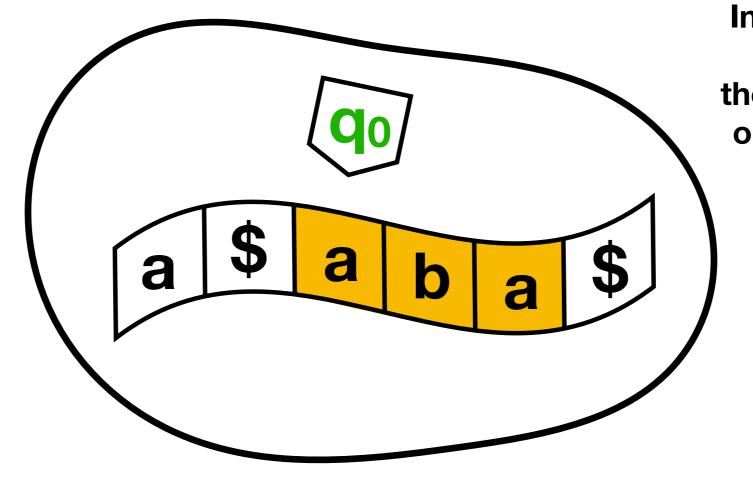
## Entering the query state



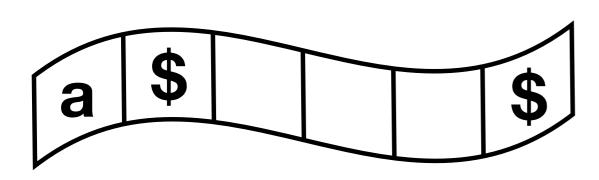
## Entering the query state

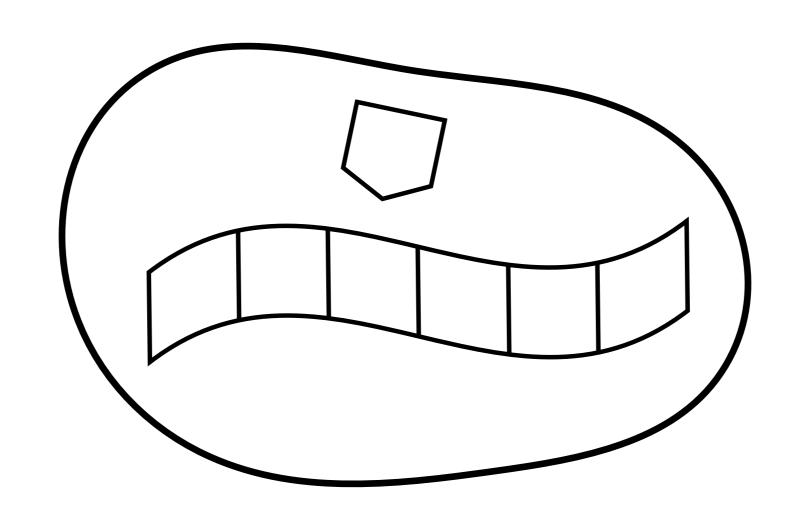


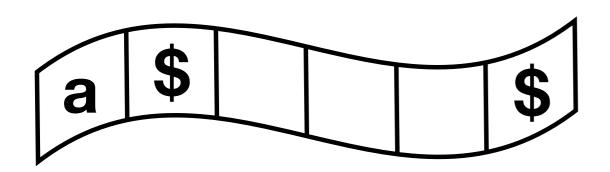
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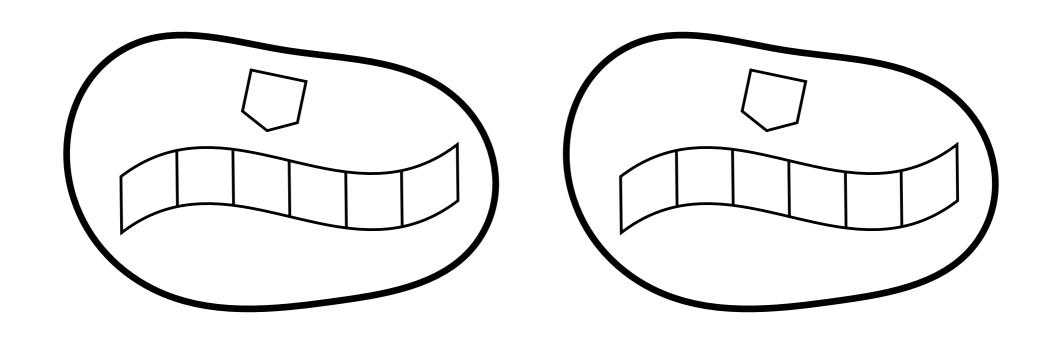


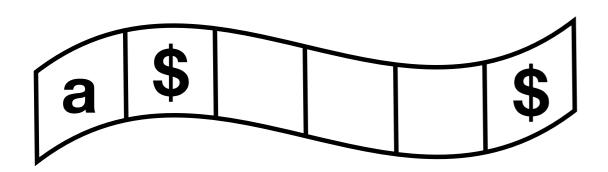
Initial state of a TM solving the #P-complete oracle problem

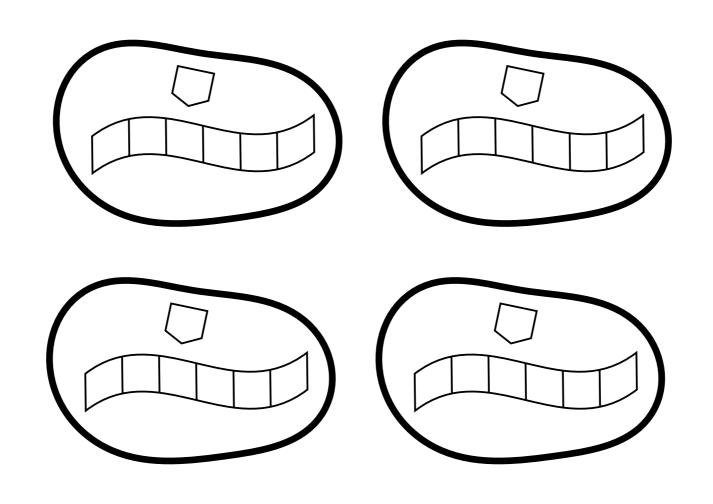


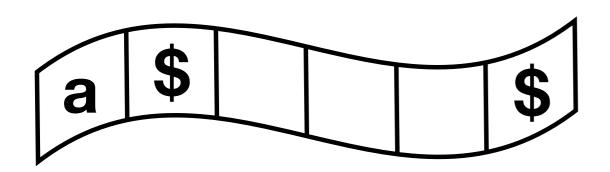


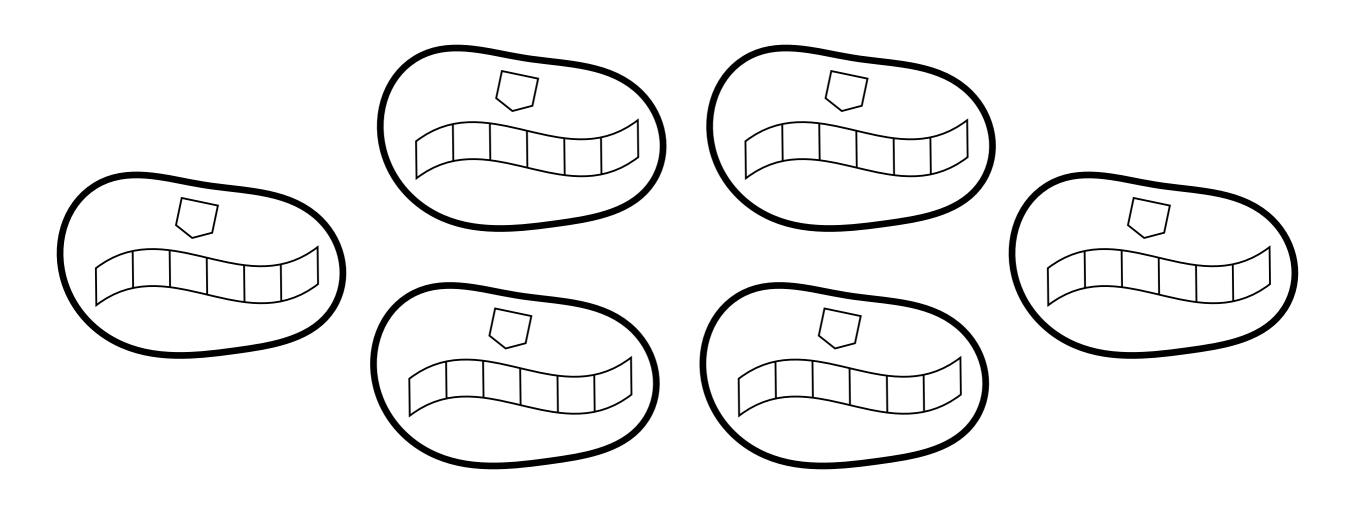


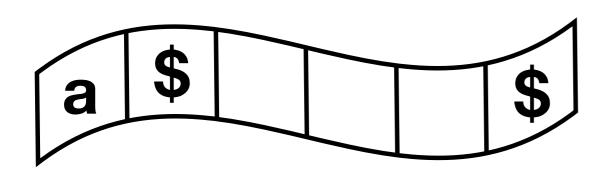




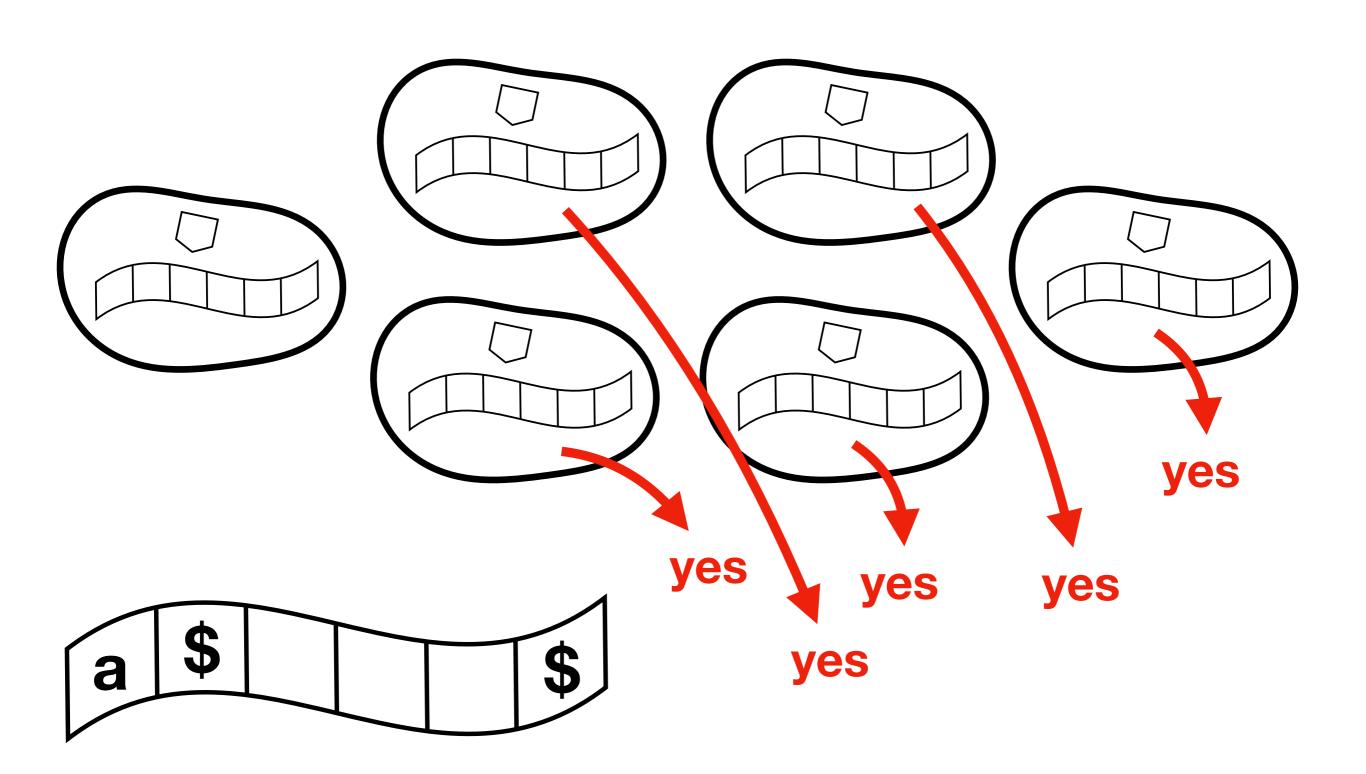


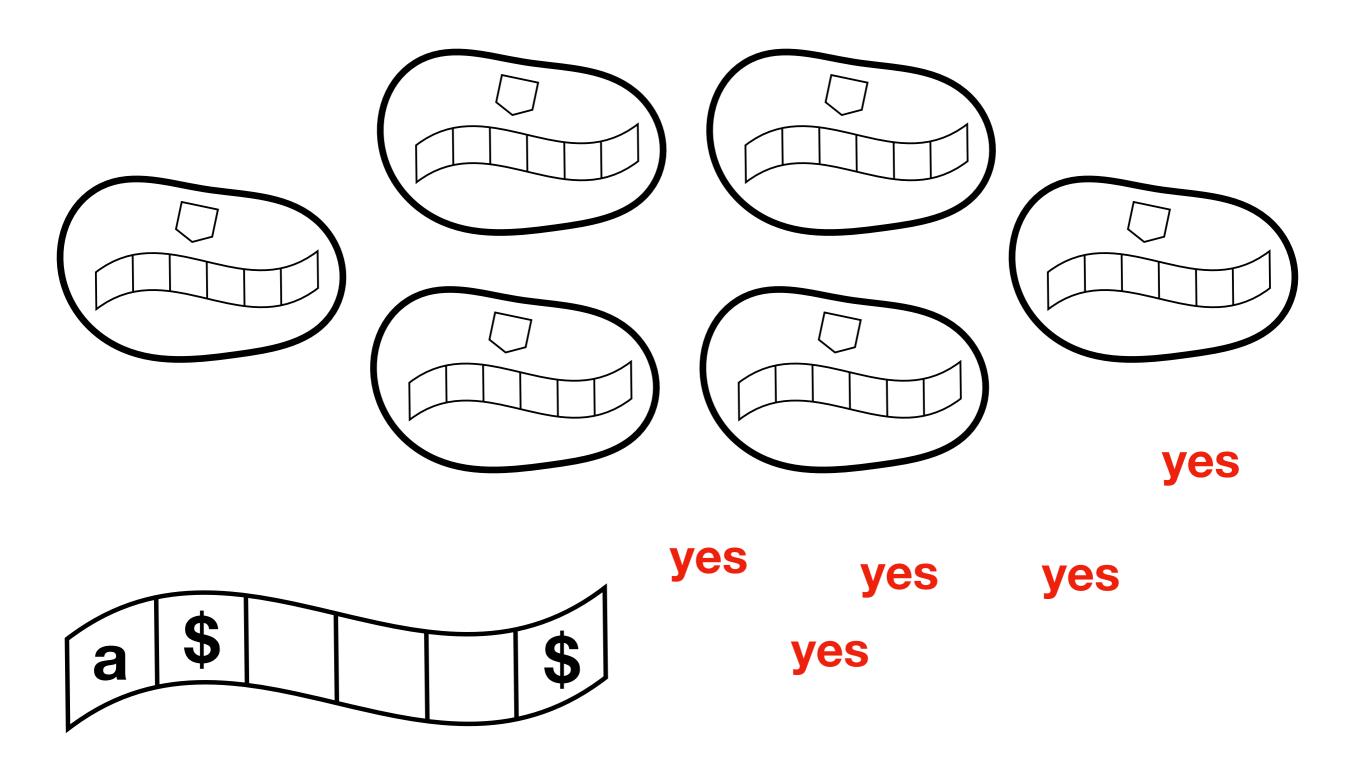


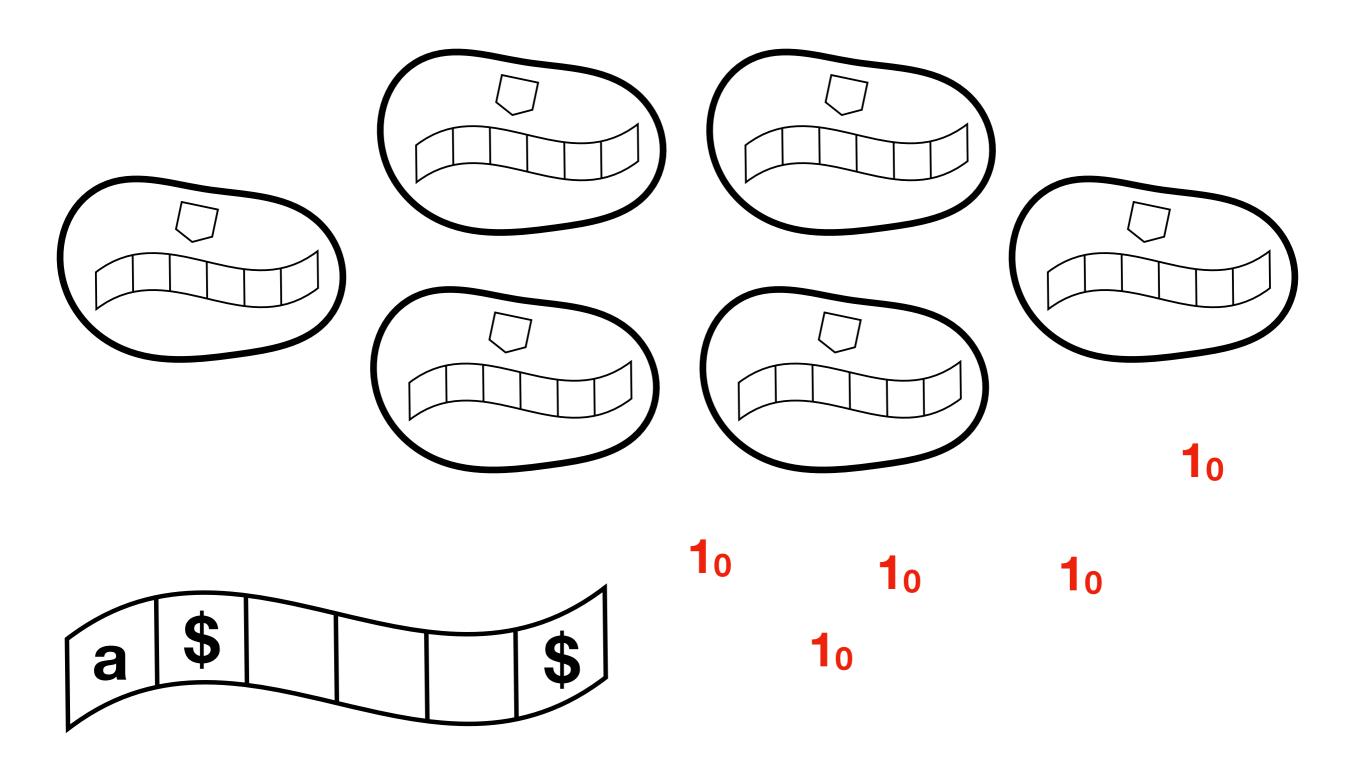


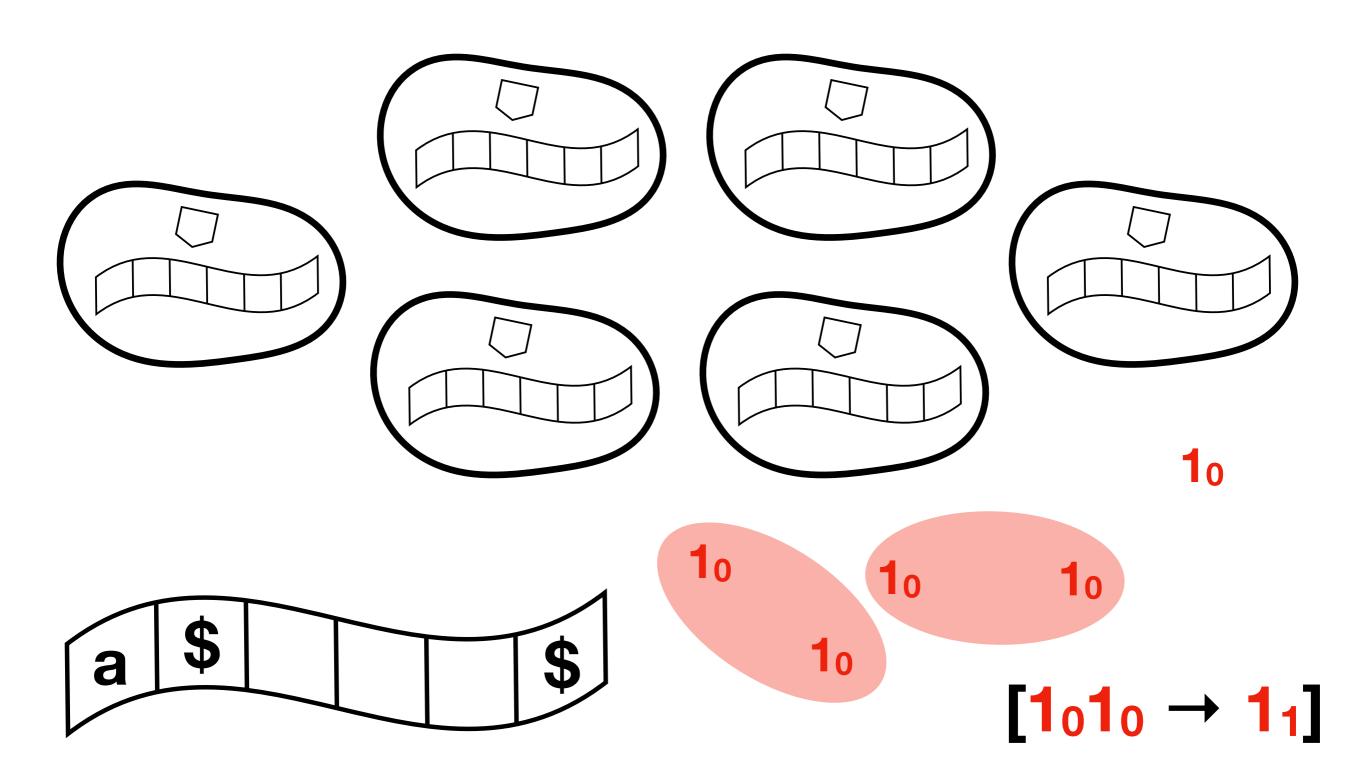


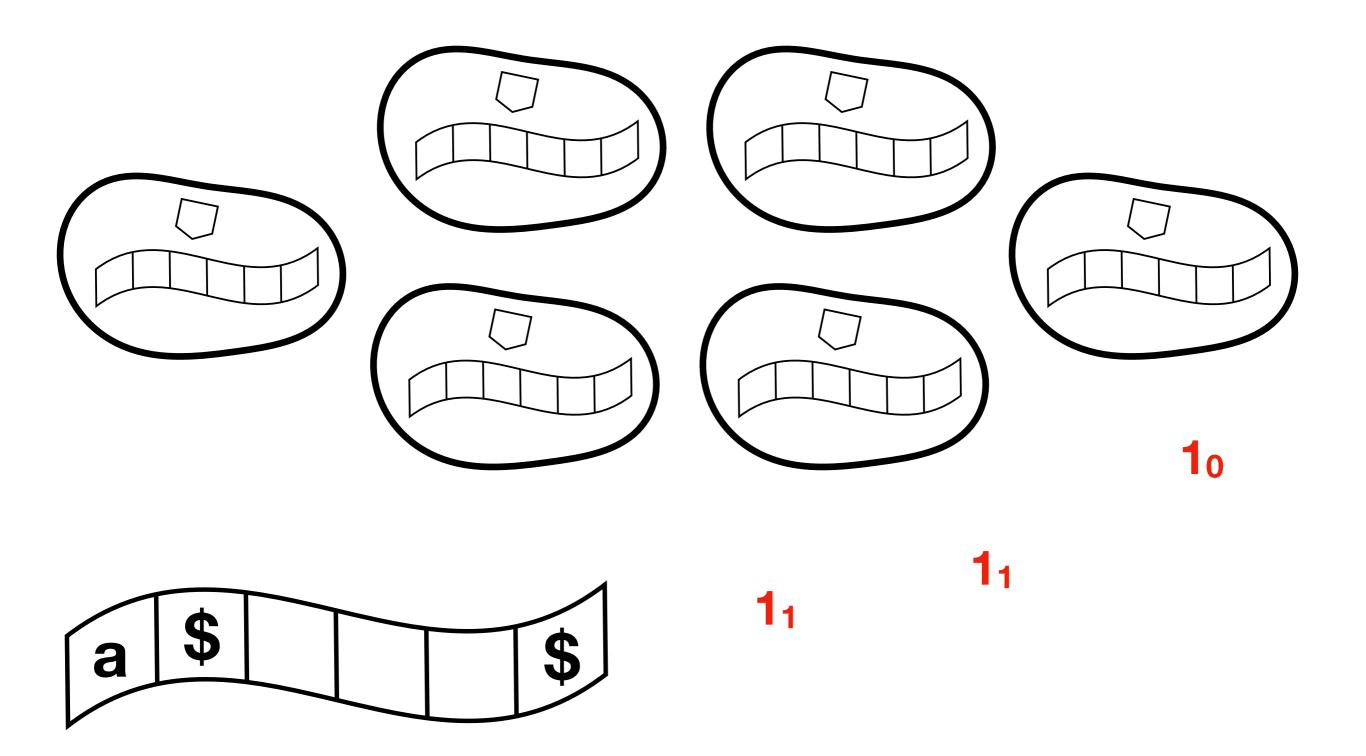
## Collecting the output

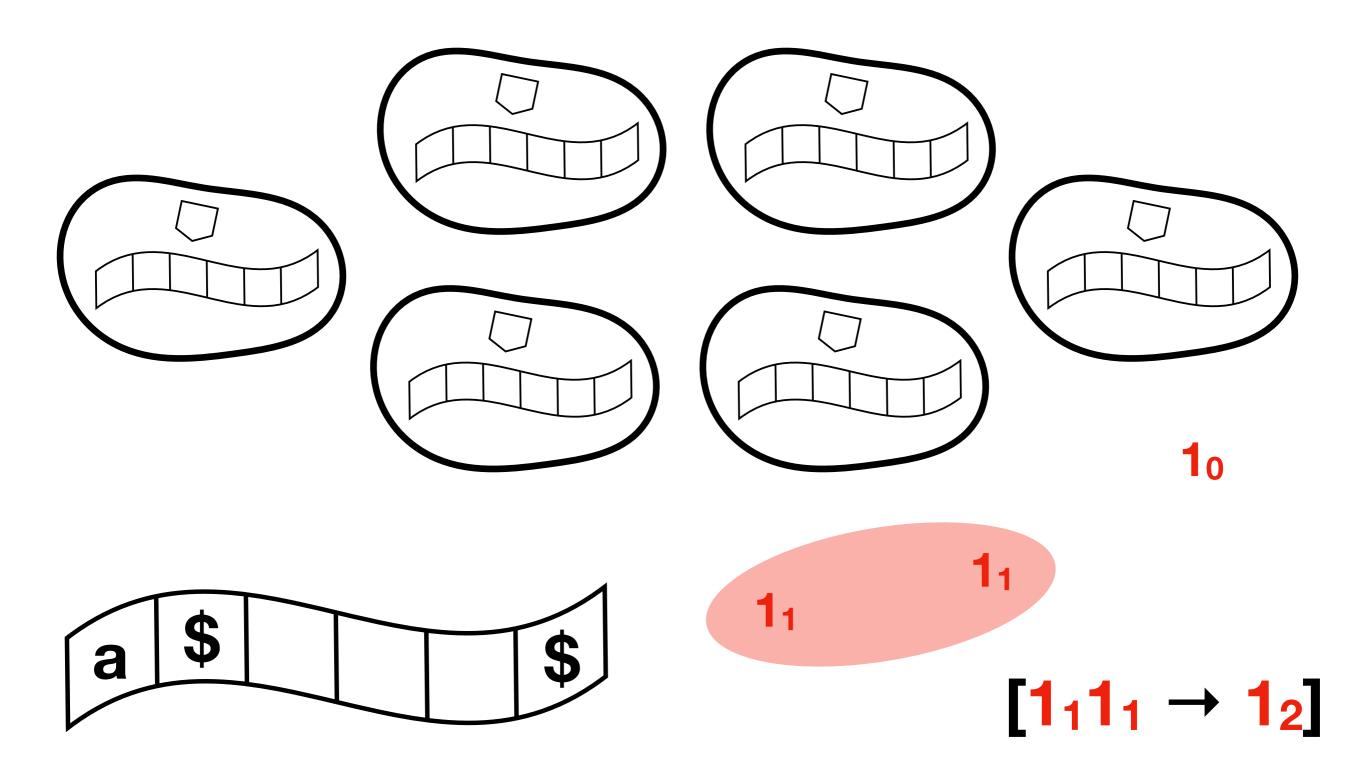


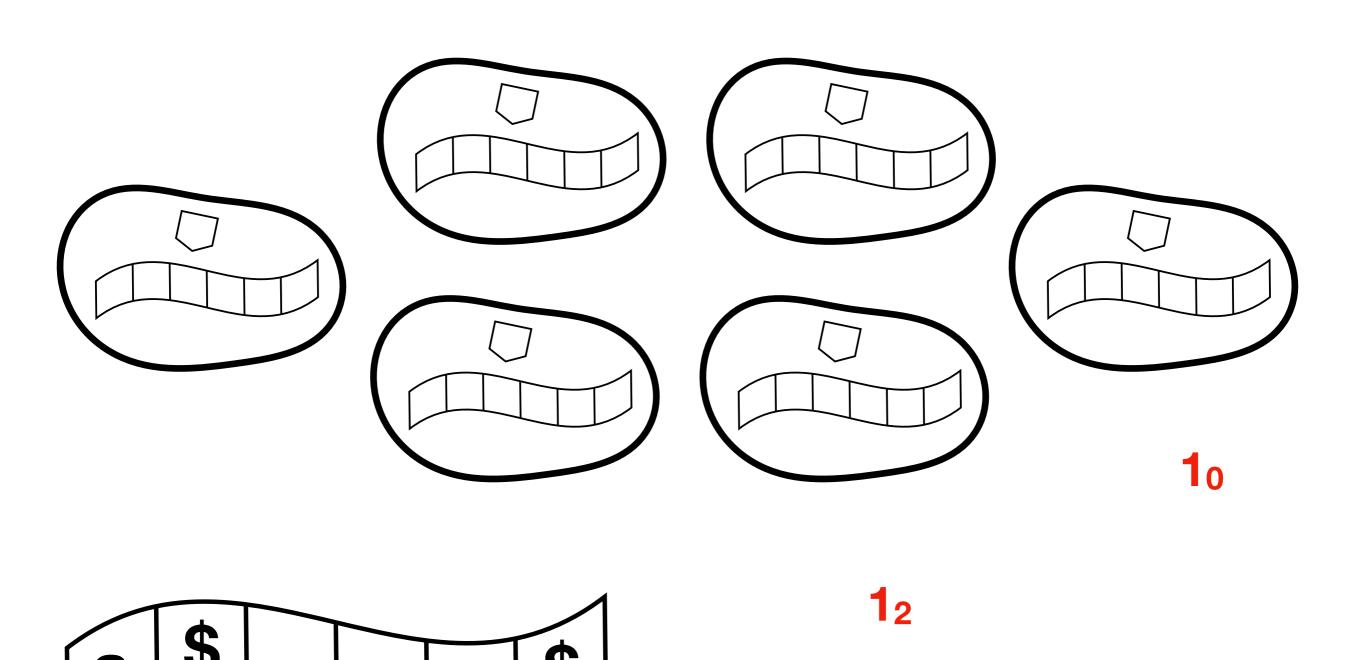




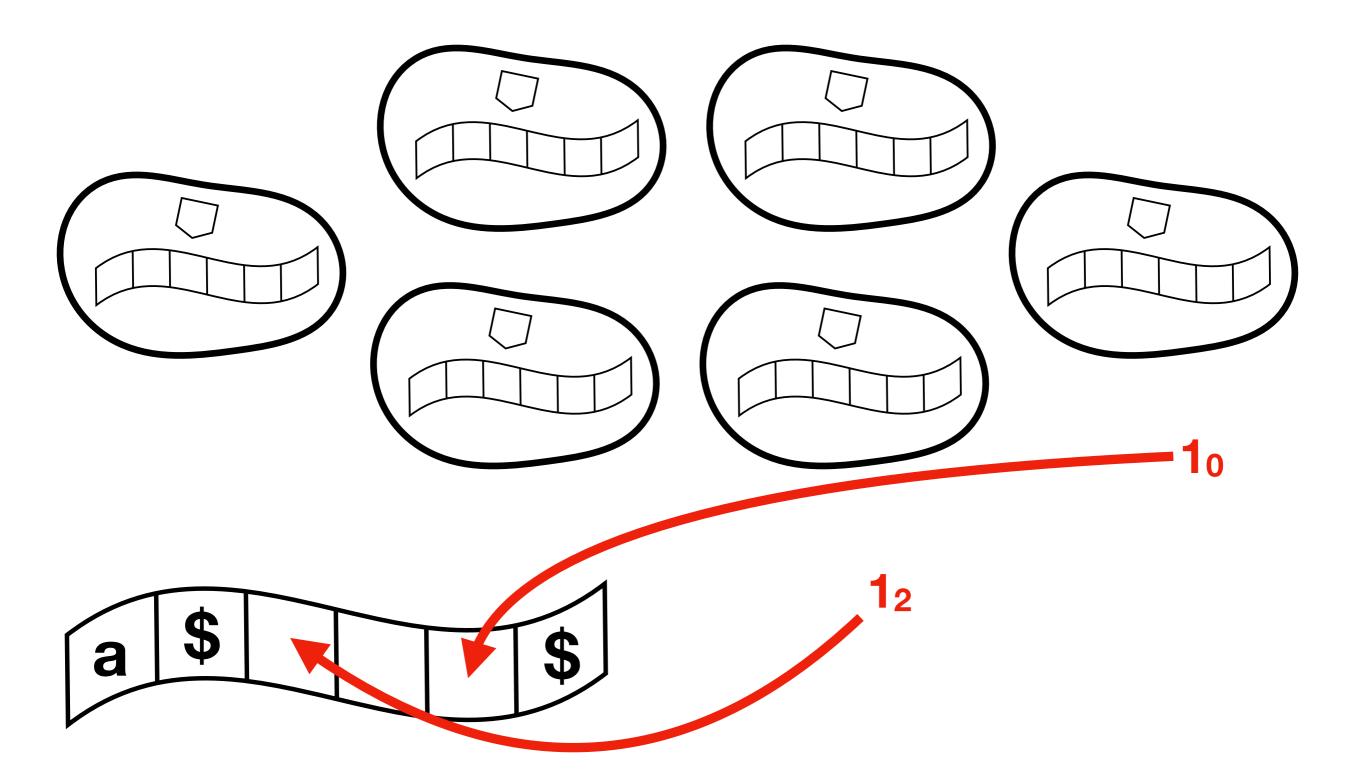




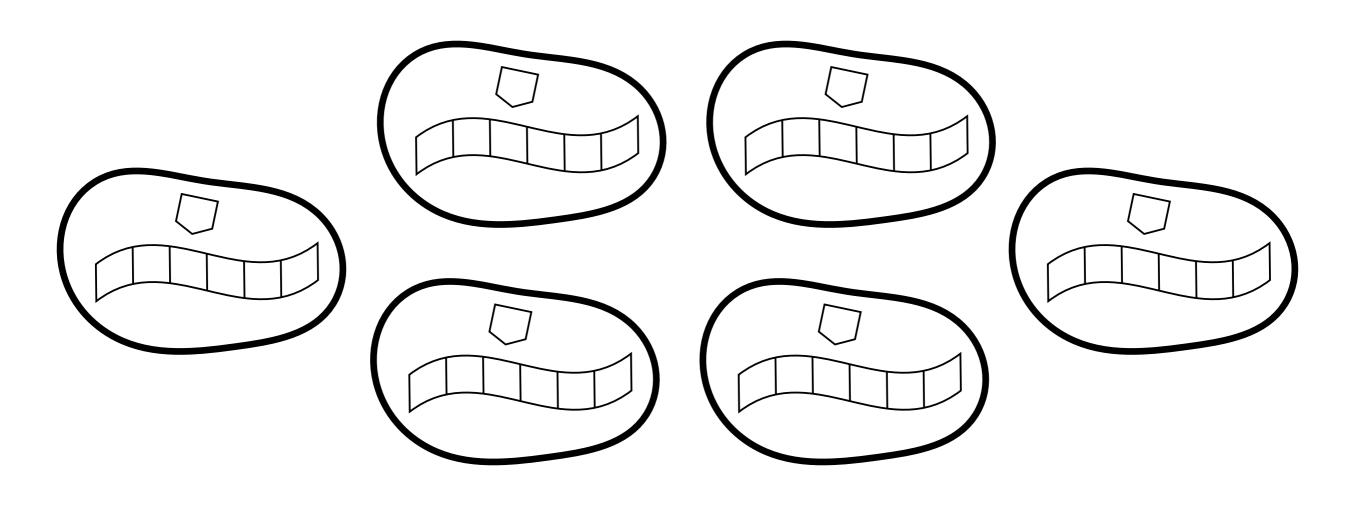


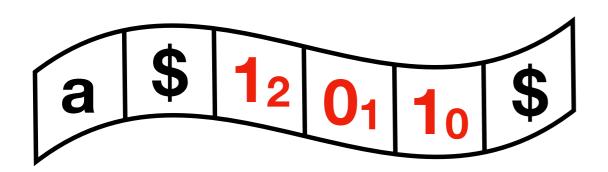


## Answer on the tape

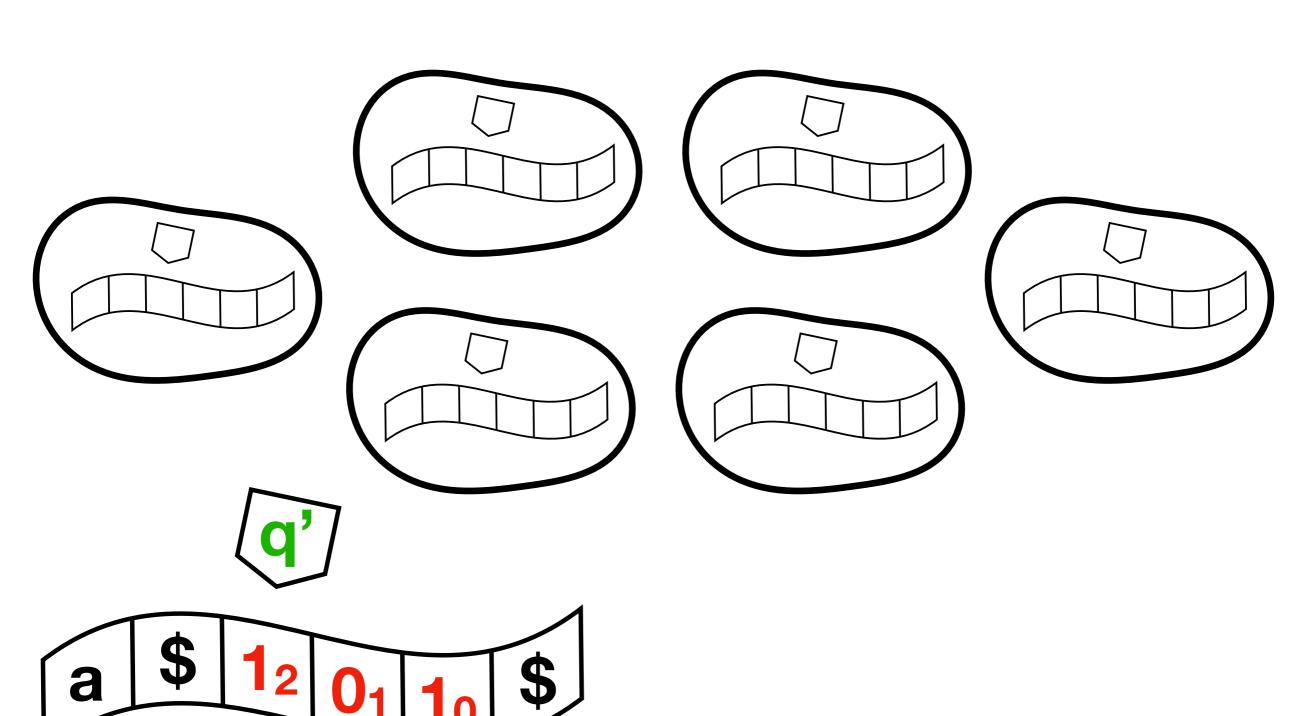


## Answer on the tape

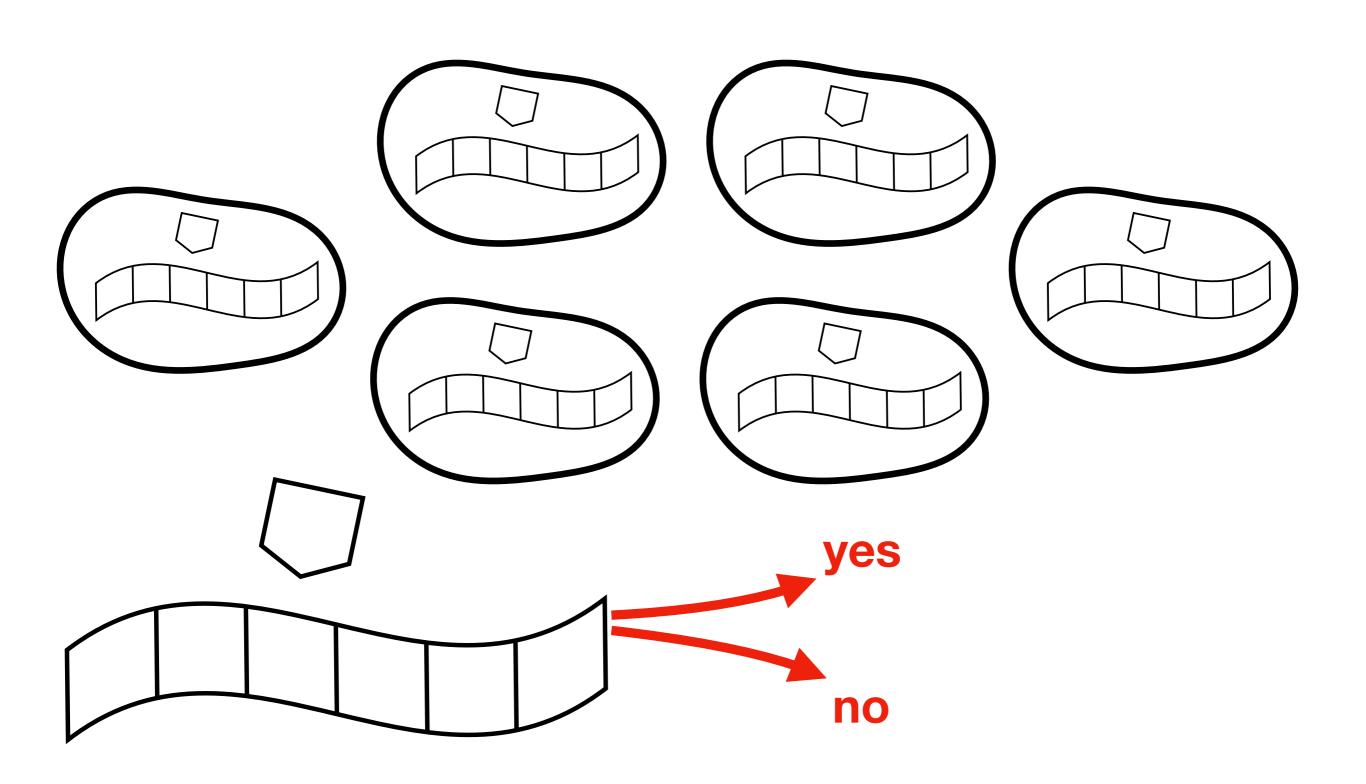




## Resuming the simulation of the main TM



## Final answer



# Simulating (monodirectional, shallow) membrane systems is in P#P[1]

## Counting the number of objects a sent out by a membrane at time t is in #P

- for i := 0 to t do
  - deterministically choose a maximal multisite of rules to apply inside the simulated membrane
  - apply all the rules except membrane division in deterministic polynomial time ("Milano Theorem")
  - if applying membrane division, nondeterministically choose whether to simulate the left or the right resulting membrane
- if an object a was sent out in the last step then accept, otherwise reject

## Lemma: $P^{\#P[1]} = parallel P^{\#P[1]}$

- Trivially P<sup>#P[1]</sup> ⊆ parallel P<sup>#P</sup>
- A polynomial number of queries f(x<sub>1</sub>), ..., f(x<sub>m</sub>)
  can be replaced by a single query to

$$g(x_1 \$ x_2 \$ \cdots \$ x_m) = \sum_{i=1}^n B^i \times f(x_i) \qquad \Rightarrow \qquad f(x_i) = \left\lfloor \frac{g(x_1 \$ x_2 \$ \cdots \$ x_m)}{B^{i-1}} \right\rfloor$$

 The function g is also in #P because this class is closed under sums and products

## Simulating (shallow, omnidirectional) membrane systems in P#P[1]

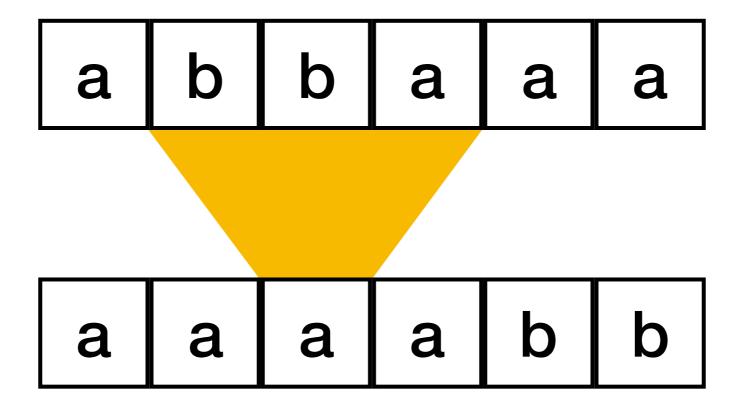
- for each membrane in the initial configuration, for each object type a and for each time step t, ask the oracle how many objects of type a are sent out by the membrane at time t (note: polynomial number of parallel queries!)
- while the system has not produced the answer object do
  - simulate one step of the external environment deterministically (Milano Theorem)
  - add the objects sent out from the membranes (according to the queries asked) to the environment
- accept or reject according to the answer of the system simulated

## Computational complexity of membrane systems

- No membranes (only environment) → P
- Shallow, monodirectonal → P<sup>#P[1]</sup> = parallel P<sup>#P</sup>
- Shallow, bidirectional → P\*P
- Constant depth k, bidirectional → PCkP
   where C<sub>0</sub>P = P, C<sub>1</sub>P = PP, C<sub>2</sub>P = PP<sup>PP</sup>, C<sub>k</sub>P = PP<sup>Ck-1P</sup>
   is the counting hierarchy [work in progress]
- Unbounded depth, bidirectional → PSPACE

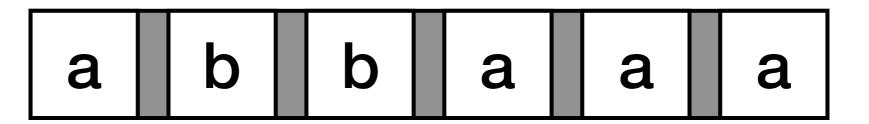
# Expanding cellular automata (XCA)

a b b a a a

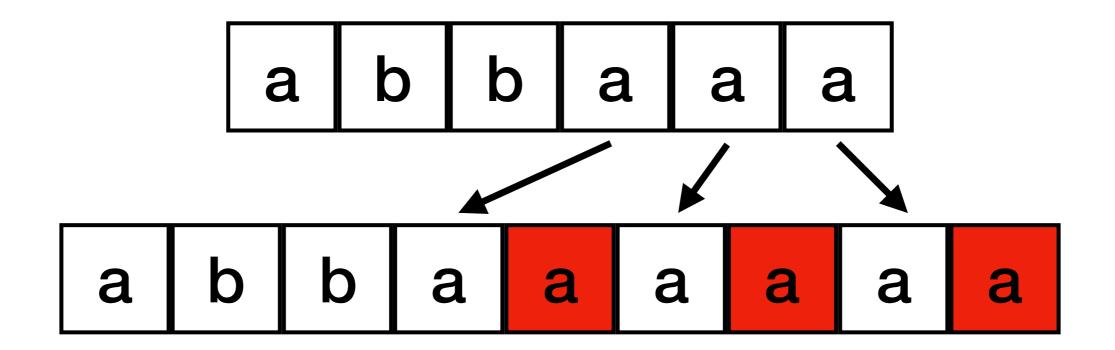


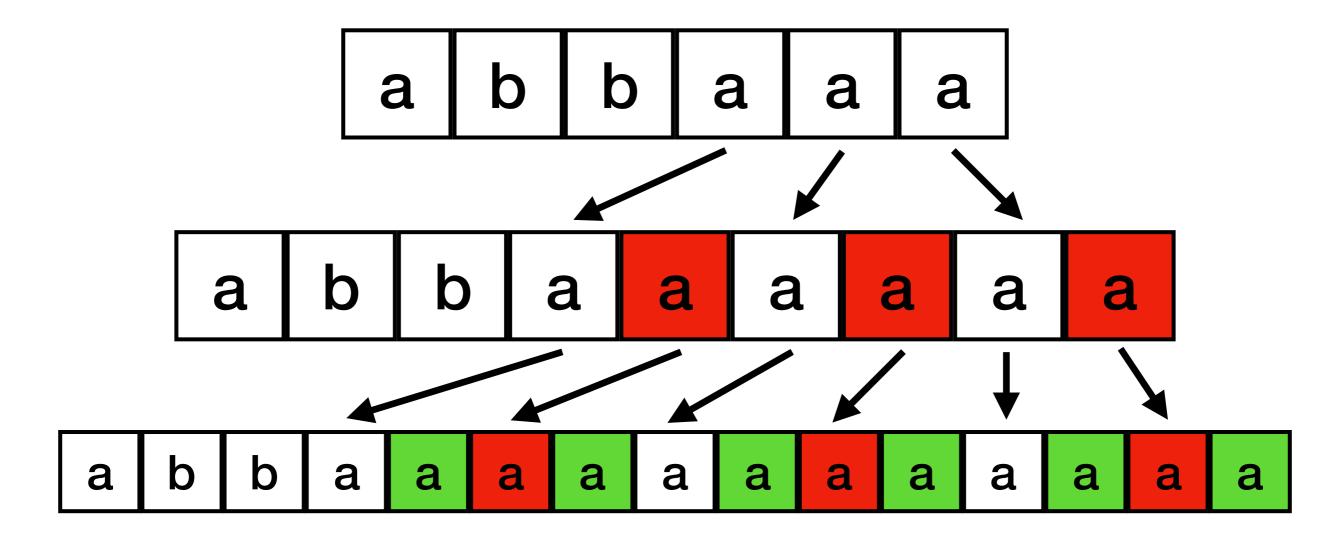
a b b a a a

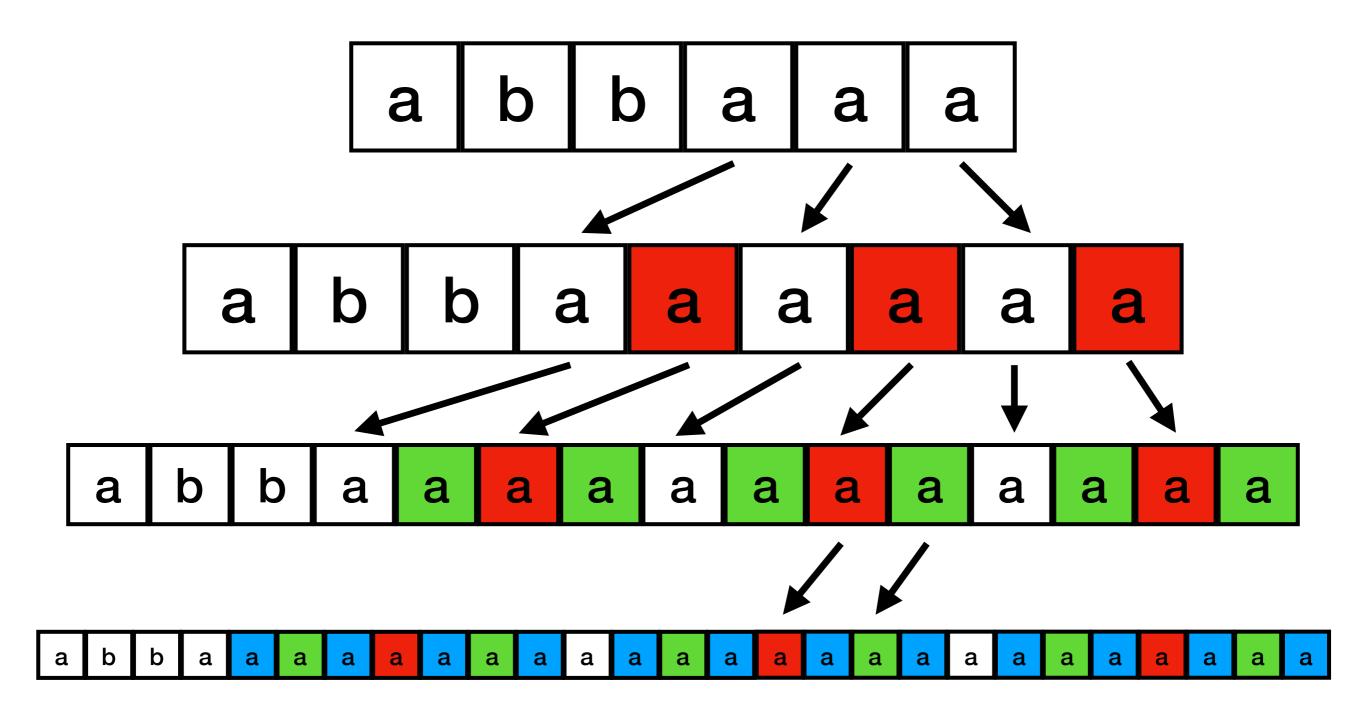
a b b a a a



a b b a a a







### Complexity results on XCA

- The class of problems solved in polynomial time by XCA is exactly the class of problems truth-table reducible to NP
- If shrinking (deleting cells) is also allowed, then the class becomes PSPACE

# Conclusions and future work

## Summary of results

- A lot of parallels computing models characterise either P or PSPACE when working in polynomial time
- Some variants of membrane systems characterise more "exotic" complexity classes with oracles, like P\*P[1], P\*P, PNP
- Expanding CA characterise the class of problems truth-table reducible to NP, which is somehow similar to oracle complexity classes

#### Conjectures and future work

- Find out why these models happen to characterise these exotic complexity classes
- Find out how the topology of the parallel computing units influences the efficiency:
  - Trees or stars for membrane systems
  - Linear or Euclidean grid for CA
  - Linear but expanding for XCA

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## Thanks for your attention! Merci de votre attention!