

# Adolfo Tec

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EDUCATION	<b>University of California, Berkeley</b>	Berkeley, CA
	Bachelor of Science, Mechanical Engineering	Aug. 2015 - Dec. 2017
	Coursework: Dynamic Feedback Control Systems, Microprocessor-Based Mechanical Systems, Rigid Body Dynamics, Lagrangian Mechanics, Continuum Mechanics, Advanced Engineering Graphics, Measurement and Instrumentation, Manufacturing and Tolerance	
SKILLS	<b>CAD/CAM:</b> PTC Creo/Pro-E, SolidWorks, AutoCAD, Autodesk 3DS Max	
	<b>Software/Programming:</b> MATLAB, Simulink, LabVIEW, C++, Arduino, JavaScript, Visual Studio, MS Office	
	<b>Equipment:</b> 3-axis Mill, Lathe, Sheet Metal Bending, 3D Printing, Laser Cutting, CFRP (Carbon Fiber Reinforced Polymer) Fabrication, Test Bench Equipment (e.g. Oscilloscopes, Multimeters, Soldering Iron, etc.)	
	<b>Languages:</b> Spanish, French	
EXPERIENCE	<b>Human-Assistive Robotic Technologies Laboratory</b>	Oct. 2016 - July 2017
	<i>Undergraduate Research Assistant</i>	Berkeley, CA
	<ul style="list-style-type: none"><li>• Conducted research on the efficacy of a pneumatically actuated active-passive exoskeleton to be used for upper limb assistance.</li><li>• Performed system identification and developed mathematical models for nonlinear stiffness control of pneumatic cylinders on testing workbench.</li><li>• Fabricated key circuit boards for actuating test rig and performing data acquisition.</li><li>• Created and maintained documents pertaining to data collection processes, testing, and procedures.</li></ul>	
	<b>UC Berkeley Human Powered Vehicle Team</b>	Aug. 2015 - Dec. 2017
	<i>Drivetrain Member (2015-2016); Suspension Member (2016-2017)</i>	Berkeley, CA
	<ul style="list-style-type: none"><li>• Collaborated in a team of two to design and manufacture an innovative, compact front suspension system responsible for clearing obstacles and maintaining stability.</li><li>• Consulted in creating finite element models for analysis and simulation under various loading conditions.</li><li>• Fabricated aerodynamic carbon fiber fairing using wet layup processes and hand-machined vehicle components.</li></ul>	
PROJECTS	<b>Siesta Drink Dispenser</b>	Aug. 2017 - Dec. 2017
	<ul style="list-style-type: none"><li>• Collaborated in a team of five to create a touchscreen-based automatic drink dispenser.</li><li>• Developed and integrated control systems for volume control of an array of diaphragm pumps and temperature control for a custom heating element.</li><li>• Manufactured key product components using bending machines, mills, and water jets.</li><li>• Secured the Frank Jarrett Machine Design Prize due to its functionality, aesthetics, and refinement.</li></ul>	
	<b>CASE Steam Engine Animation</b>	Oct. 2017 - Dec. 2017
	<ul style="list-style-type: none"><li>• Led a team of three students to create an animation accurately depicting the assembly and functionality of a CASE steam traction engine.</li><li>• Modeled over 50 unique parts along with all material properties for rendering production in PTC Creo Parametric and 3DS Max.</li></ul>	
	<b>Inverted Pendulum Controller</b>	Aug. 2016 - Dec. 2016
	<ul style="list-style-type: none"><li>• Developed equations of motion for a rectilinear dynamic cart and pendulum system and ran hardware-in-the-loop (HIL) simulations with Simulink.</li><li>• Designed and implemented a state feedback controller to stabilize and self erect an inverted pendulum capable of disturbance rejection.</li><li>• Implemented a Luenberger observer scheme to estimate parameters, such as velocities.</li></ul>	