

Adolfo Tec

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| EDUCATION | University of California, Berkeley | Berkeley, CA |
| | Bachelor of Science, Mechanical Engineering | Aug. 2015 - Dec. 2017 |
| | Coursework: Microprocessor-Based Mechanical Systems, Dynamic Feedback Control Systems, Rigid Body Dynamics, Lagrangian Mechanics, Advanced Engineering Graphics, Measurement and Instrumentation, Manufacturing and Tolerance, Product Development | |
| SKILLS | CAD/CAM: PTC Creo/Pro-E, SolidWorks, AutoCAD, Autodesk 3DS Max | |
| | Software/Programming: MATLAB, Simulink, ANSYS, LabVIEW, C++, Arduino, JavaScript, Visual Studio, MS Office | |
| | Equipment: 3-axis Mill, Lathe, Sheet Metal Bending, 3D Printing, Laser Cutting, CFRP (Carbon Fiber Reinforced Polymer) Fabrication, Test Bench Equipment (e.g. Oscilloscopes, Multimeters, Soldering Iron, etc.) | |
| | Languages: Spanish, French | |
| EXPERIENCE | Cod.Ed Education Corporation | May 2018 - Present |
| | <i>Engineering Instructor</i> | Fullerton, CA |
| | <ul style="list-style-type: none">• Mentor and teach students fundamentals in computer science, programming, and information technology using C++, JavaScript, and Cisco equipment.• Oversee and manage staff members to ensure a successful introductory engineering course involving 3D printing, programming, and electronics to create a small robot.• Pioneering an amateur rocketry program to research and develop a LOX-LNG propelled rocket. | |
| | Human-Assistive Robotic Technologies Laboratory | Oct. 2016 - June 2017 |
| | <i>Undergraduate Research Assistant</i> | Berkeley, CA |
| | <ul style="list-style-type: none">• Conducted research on the efficacy of a pneumatically actuated active-passive exoskeleton to be used for upper limb assistance.• Performed system identification and developed mathematical models for nonlinear stiffness control of pneumatic cylinders on testing workbench.• Fabricated key circuit boards for actuating test rig and performing data acquisition.• Created and maintained documents pertaining to data collection processes, testing, and procedures. | |
| | UC Berkeley Human Powered Vehicle Team | Aug. 2015 - Dec. 2017 |
| | <i>Drivetrain Member (2015-2016); Suspension Member (2016-2017)</i> | Berkeley, CA |
| | <ul style="list-style-type: none">• Co-led suspension sub-team to design and manufacture an innovative, compact front suspension system responsible for clearing obstacles and maintaining stability.• Created finite element models and performed FEA for simulation and analysis under various loading conditions.• Fabricated aerodynamic carbon fiber fairing using wet layup processes and hand-machined vehicle components. | |
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| PROJECTS | Siesta Drink Dispenser | Aug. 2017 - Dec. 2017 |
| | <ul style="list-style-type: none">• Collaborated in a team of five to create a touchscreen-based automatic drink dispenser.• Developed and integrated control systems for volume control of an array of diaphragm pumps and temperature control for a custom-designed heating element.• Manufactured key product components using bending machines, mills, and water jets.• Secured the Frank Jarrett Design Prize for the department's most outstanding project in machine design due to its functionality, aesthetics, and refinement. | |
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| | Inverted Pendulum Controller | Aug. 2016 - Dec. 2016 |
| | <ul style="list-style-type: none">• Developed equations of motion for a rectilinear dynamic cart and pendulum system and ran hardware-in-the-loop (HIL) simulations with Simulink.• Designed and implemented a state feedback controller to stabilize and self erect an inverted pendulum capable of disturbance rejection. | |