Know The Complexities!

The Ultimate Cheat-Sheet for **Design and Analysis of Computer Algorithms**

Heaps

Heaps	Time Complexity						
	Heapify	Find Max	Extract Max	Increase Key	Insert	Delete	Merge
<u>Linked List (sorted)</u>	-	O(1)	O(1)	O(n)	O(n)	O(1)	O(m+n)
<u>Linked List (unsorted)</u>	-	O(n)	O(n)	O(1)	O(1)	O(1)	O(1)
Binary Heap	O(n)	O(1)	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(m+n)
Binomial Heap	-	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))
<u>Fibonacci Heap</u>	-	O(1)	O(log(n))*	O(1)*	O(1)	O(log(n))*	O(1)

Graphs

Node / Edge Management	Storage	Add Vertex	Add Edge	Remove Vertex	Remove Edge	Query
Adjacency list	O(V + E)	O(1)	O(1)	O(V + E)	O(E)	O(V)
<u>Incidence list</u>	O(V + E)	O(1)	O(1)	O(E)	O(E)	O(E)
Adjacency matrix	O(V ^2)	O(V ^2)	O(1)	O(V ^2)	O(1)	O(1)
Incidence matrix	O(V · E)	O(V · E)	O(E)			

Searching

Algorithm	Data Structure	Time Complexity	Space Complexity	
		Average	Worst	Worst
Depth First Search (DFS)	Graph of V vertices and E edges	-	O(E + V)	O(V)
Breadth First Search (BFS)	Graph of V vertices and E edges	-	O(E + V)	O(V)
Binary search	Sorted array of n elements	O(log(n))	O(log(n))	O(1)
<u>Linear (Brute Force)</u>	Array	O(n)	O(n)	O(1)
Shortest path by Dijkstra, using a Min-heap as priority queue	Graph with V vertices and E edges	O((V + E) log V)	O((V + E) log V)	O(V)
Shortest path by Dijkstra, using an unsorted array as priority queue	Graph with V vertices and E edges	O(V ^2)	O(V ^2)	O(V)
Shortest path by Bellman-Ford	Graph with V vertices and E edges	O(V E)	O(V E)	O(V)

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Sorting

Algorithm	Data	Time Complexit	ty	Worst Case Auxiliary Space Complexity	
	Structure				
		Best	Average	Worst	Worst
Quicksort	Array	O(n log(n))	O(n log(n))	O(n^2)	O(n)
Mergesort	Array	O(n log(n))	O(n log(n))	O(n log(n))	O(n)
<u>Heapsort</u>	Array	O(n log(n))	O(n log(n))	O(n log(n))	O(1)
Bubble Sort	Array	O(n)	O(n^2)	O(n^2)	O(1)
<u>Insertion Sort</u>	Array	O(n)	O(n^2)	O(n^2)	O(1)
Select Sort	Array	O(n^2)	O(n^2)	O(n^2)	O(1)
Bucket Sort	Array	O(n+k)	O(n+k)	O(n^2)	O(nk)
Radix Sort	Array	O(nk)	O(nk)	O(nk)	O(n+k)

Data Structures

Data Structure	Time Complexity								Space Complexity
	Average								Worst
	Indexing	Search	Insertion	Deletion	Indexing	Search	Insertion	Deletion	
Basic Array	O(1)	O(n)	-	-	O(1)	O(n)	-	-	O(n)
<u>Dynamic Array</u>	O(1)	O(n)	O(n)	O(n)	O(1)	O(n)	O(n)	O(n)	O(n)
Singly-Linked List	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)
Doubly-Linked List	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)
Skip List	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n log(n))
<u>Hash Table</u>	-	0(1)	0(1)	O(1)	-	O(n)	O(n)	O(n)	O(n)
Binary Search Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n)
<u>Cartresian Tree</u>	-	O(log(n))	O(log(n))	O(log(n))	-	O(n)	O(n)	O(n)	O(n)
<u>B-Tree</u>	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)
Red-Black Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)
<u>Splay Tree</u>	-	O(log(n))	O(log(n))	O(log(n))	-	O(log(n))	O(log(n))	O(log(n))	O(n)
<u>AVL Tree</u>	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)

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