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[ INFO ] After kernelUpdate kernel argument settings.
[ INFO ] After kernelUpdate kernel enqueue.
[ INFO ] After clFinish.
Agent 0's current position = (45.538387,46.431271) at time 7.799999 - Goal at (-51.000000, -52.000000) - Velocity = (-0.700209, -0.713938)
Agent 1's current position = (-55.446392,50.000000) at time 7.799999 - Goal at (50.000000, -50.000000) - Velocity = (-0.689543, 0.000000)
Agent 2's current position = (-44.484581,-44.484581) at time 7.799999 - Goal at (50.000000, 50.000000) - Velocity = (0.707107, 0.707107)
Agent 3's current position = (55.446392,-50.000000) at time 7.799999 - Goal at (-50.000000, 50.000000) - Velocity = (0.689543, 0.000000)
Agent 4's current position = (45.539749,56.701942) at time 7.799999 - Goal at (-61.000000, -52.000000) - Velocity = (-0.699968, -0.714174)
Agent 5's current position = (-55.190376,60.000000) at time 7.799999 - Goal at (60.000000, -50.000000) - Velocity = (-0.691929, 0.000000)
Agent 6's current position = (-44.490807,-54.746620) at time 7.799999 - Goal at (60.000000, 50.000000) - Velocity = (0.706242, 0.707971)
Agent 7's current position = (55.190376,-60.000000) at time 7.799999 - Goal at (-60.000000, 50.000000) - Velocity = (0.691929, 0.000000)
Agent 8's current position = (45.537399,66.820045) at time 7.799999 - Goal at (-71.000000, -52.000000) - Velocity = (-0.700216, -0.713931)
Agent 9's current position = (-55.195042,70.000000) at time 7.799999 - Goal at (70.000000, -50.000000) - Velocity = (-0.693169, 0.000000)
Agent 10's current position = (-44.492481,-64.857643) at time 7.799999 - Goal at (70.000000, 50.000000) - Velocity = (0.705980, 0.708232)
Agent 11's current position = (55.195042,-70.000000) at time 7.799999 - Goal at (-70.000000, 50.000000) - Velocity = (0.693169, 0.000000)
Agent 12's current position = (45.533409,76.823402) at time 7.799999 - Goal at (-81.000000, -52.000000) - Velocity = (-0.700737, -0.713419)
Agent 13's current position = (-55.199013,80.000000) at time 7.799999 - Goal at (80.000000, -50.000000) - Velocity = (-0.694222, 0.000000)
Agent 14's current position = (-44.491859,-74.858231) at time 7.799999 - Goal at (80.000000, 50.000000) - Velocity = (0.706067, 0.708145)
Agent 15's current position = (55.199013,-80.000000) at time 7.799999 - Goal at (-80.000000, 50.000000) - Velocity = (0.694222, 0.000000)
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[ INFO ] After clFinish.
Agent 0's current position = (45.538387,46.431271) at time 7.799999 - Goal at (-51.000000, -52.000000) - Velocity = (-0.700209, -0.713938)
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Agent 3's current position = (44.484581,-44.484581) at time 7.799999 - Goal at (-50.000000, 50.000000) - Velocity = (-0.707107, 0.707107)
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Agent 13's current position = (-44.491859,74.858231) at time 7.799999 - Goal at (80.000000, -50.000000) - Velocity = (0.706067, -0.708145)
Agent 14's current position = (-44.491859,-74.858231) at time 7.799999 - Goal at (80.000000, 50.000000) - Velocity = (0.706067, 0.708145)
Agent 15's current position = (44.491859,-74.858231) at time 7.799999 - Goal at (-80.000000, 50.000000) - Velocity = (-0.706067, 0.708145)
Agent 16's current position = (45.529957,86.826340) at time 7.799999 - Goal at (-91.000000, -52.000000) - Velocity = (-0.701185, -0.712979)
Agent 17's current position = (-44.491367,84.858734) at time 7.799999 - Goal at (90.000000, -50.000000) - Velocity = (0.706142, -0.708071)
Agent 18's current position = (-44.491367,-84.858734) at time 7.799999 - Goal at (90.000000, 50.000000) - Velocity = (0.706142, 0.708071)
Agent 19's current position = (44.491367,-84.858734) at time 7.799999 - Goal at (-90.000000, 50.000000) - Velocity = (-0.706142, 0.708071)
Agent 20's current position = (45.526985,96.828857) at time 7.799999 - Goal at (-101.000000, -52.000000) - Velocity = (-0.701575, -0.712596)
Agent 21's current position = (-44.490875,94.859154) at time 7.799999 - Goal at (100.000000, -50.000000) - Velocity = (0.706206, -0.708006)
Agent 22's current position = (-44.490875,-94.859154) at time 7.799999 - Goal at (100.000000, 50.000000) - Velocity = (0.706206, 0.708006)
Agent 23's current position = (44.490875,-94.859154) at time 7.799999 - Goal at (-100.000000, 50.000000) - Velocity = (-0.706206, 0.708006)
Agent 24's current position = (45.524361,106.831123) at time 7.799999 - Goal at (-111.000000, -52.000000) - Velocity = (-0.701916, -0.712260)
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Step 13 (top nalla, bottom emulated): Note that y velocity is 0 – could possibly due to the differing signs in the position/goal ? Although this might be a coincidence as it is every other agent.

Frame 200 in both simulations. Nalla left, emulated right.

