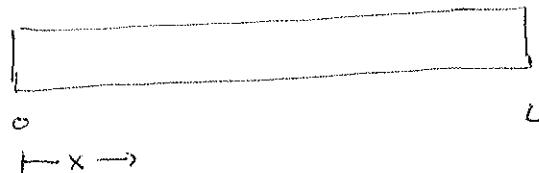


Eigenvalues and Eigenvectors of continuous systems

- Dynamic Models

example: Heat Conduction (uniform temperature)



$$\text{heat eqn: } \frac{\partial u}{\partial t} = k \frac{\partial^2 u}{\partial x^2}$$

separation of variables: look for solution $u(x,t) = y(x)e^{-\sigma t}$
(negative exponent to account for decreasing temperature)

$$u = y e^{-\sigma t}$$

$$u_t = -\sigma y e^{-\sigma t}$$

$$u_{xx} = y'' e^{-\sigma t} \quad \text{substitute into PDE} \Rightarrow k y'' e^{-\sigma t} = -\sigma y e^{-\sigma t}$$

$$\rightarrow y'' + \frac{\sigma}{k} y = 0$$

$$\text{let } \lambda = \frac{\sigma}{k} \quad \text{then} \quad y'' + \lambda y = 0$$

assume BC: ~~$y(0) = 0 \Rightarrow u(0,t) = 0$~~

$$\rightarrow \boxed{y(0) = y(L) = 0, y'' + \lambda y = 0}$$

OR assume IC: initial condition in x , not t

$$y(0) = y'(0) = 1$$

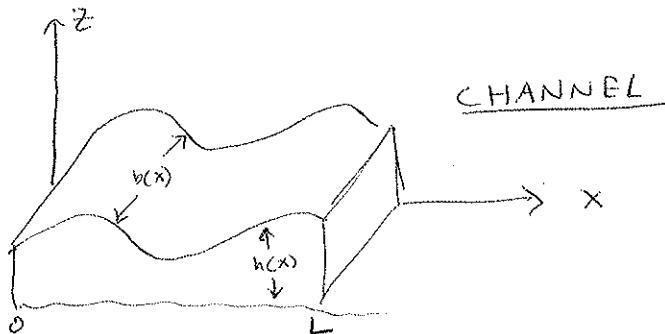
ICs are often preferred because they often lead to a unique solution. BCs often behave non-uniquely.

Reference : Cochran Chpt 2

Eigenvalue problems for differential equations

Application : Shallow Water Waves

Imagine fluid flow with free surface



$b(x)$ - breadth
 $h(x)$ - height

$u(x, t)$ is the displacement of the surface of the fluid in the channel.

By a careful analysis, Cochran shows that for small displacements (linearized equations of motion)

$$\frac{\partial^2 u}{\partial t^2} = \frac{g}{b} \frac{\partial}{\partial x} \left(b h \frac{\partial u}{\partial x} \right)$$

IF b and h are constants

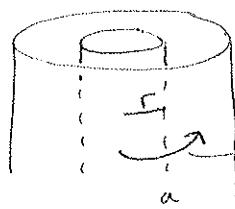
$$\frac{\partial^2 u}{\partial t^2} = gh \frac{\partial^2 u}{\partial x^2} \quad (\text{wave eqn})$$

$$\text{Note } g \sim \frac{L}{r^2}, R \sim L \rightarrow gh \sim \frac{L^2}{r^2} = \left(\frac{L}{r}\right)^2$$

$$\Rightarrow \boxed{u_{tt} = c^2 u_{xx}}$$

Rotating Flow

Rayleigh's Criterion



~~Rayleigh's flow (inviscid)~~

$\bar{v}(r)$ velocity, $\rho(r)$ density

A necessary and sufficient condition for stability is

$$\frac{d}{dr}(\bar{\rho}r^2\bar{v}^2) > 0$$

Syng (1933) proved Rayleigh's criterion by
Sturm-Liouville theory.

$$\boxed{\begin{aligned} (p(x)y')' + (\lambda r(x) - q(x))y &= 0, \quad a < x < b \\ A y(a) + B y'(a) + C y(b) + D y'(b) &= 0 \\ E y(a) + F y'(a) + G y(b) + H y'(b) &= 0 \end{aligned}}$$

Consider channel case again: $\frac{\partial^2 n}{\partial t^2} = \frac{g}{b} \frac{\partial}{\partial x} \left(b h \frac{\partial n}{\partial x} \right)$

Try $n(x,t) = y(x) \sin(\omega t + \theta)$ ω - Frequency, θ - phase angle

$$n_{tt} = -\omega^2 y \sin(\omega t + \theta)$$

$$n_x = y'(x) \sin(\omega t + \theta)$$

$$\frac{\partial}{\partial x} \left(b h \frac{\partial n}{\partial x} \right) = \frac{g}{b} (b h y')' \sin(\omega t + \theta)$$

$$\Rightarrow n_{tt} = \frac{g}{b} \frac{\partial}{\partial x} \left(b h \frac{\partial n}{\partial x} \right) \Rightarrow -\omega^2 y \sin(\omega t + \theta) = \frac{g}{b} (b h y')' \sin(\omega t + \theta)$$

$$\Rightarrow \boxed{(b h y')' + \frac{b \omega^2}{g} y = 0} \quad \text{ODE, } \omega^2 \text{ is the eigenvalue}$$

possible Boundary conditions

$$y(0) = y(L) = 0$$

bh plays the role of $p(x)$

ω^2 plays the role of λ

b/g plays the role of $r(x)$

$q(x)$ vanishes

In Cochran, page 51 #2

- Consider the general 2nd order linear ODE

$$\alpha y'' + \beta y' + \gamma y = 0, \quad \alpha \neq 0$$

let $F \neq 0$ be a multiplier

$$\alpha Fy'' + \beta Fy' + \gamma Fy = 0$$

let $\alpha F = p$ and $\beta F = p'$

$$\rightarrow \frac{p'}{p} = \frac{\beta}{\alpha} \rightarrow \frac{d}{dx} \log p = \frac{\beta}{\alpha} \rightarrow \log p = \int \frac{\beta}{\alpha} dx$$

Exponentiate $\rightarrow p(x) = e^{\int \frac{\beta}{\alpha} dx}$

$$\boxed{F = \frac{1}{\alpha} e^{\int \frac{\beta}{\alpha} dx}}$$

$$\Rightarrow \frac{d}{dx}(py') + \frac{\beta}{\alpha} \left(e^{\int \frac{\beta}{\alpha} dx} \right)_y = 0$$

Differential Operator

$$Ly \equiv (py')' - qy, \quad a < x < b$$

$p(x) > 0$ for $a \leq x \leq b$

p' and q' are continuous on $[a, b]$

$$\int_a^b (uLv - vLu) dx = [p(x)W(u, v)]_a^b, \quad W \text{ is the Wronskian of } u \text{ and } v$$

The right side depends only on the boundary values

The matrix of coefficients $\begin{bmatrix} A & B & C & D \\ E & F & G & H \end{bmatrix}$ has rank 2.

\Rightarrow the BC's are distinct.

These are the General mixed BC

$$W(u, v) = \begin{vmatrix} u & v \\ u' & v' \end{vmatrix} = uv' - u'v$$

IF $C = D = 0$ and $E = F = 0$ the BCs are called separated or unmixed.

Def: BCs of general mixed homogeneous type are called regular if for all u, v that satisfy them $\left[p(x)w(u,v) \right]_a^b = 0$

Property 1: Unmixed (separated) BCs are regular.

Property 2: Periodic BCs $y(b) = y(a)$, $y'(b) = y'(a)$ are also regular provided $p(b) = p(a)$.
The operator L with regular BCs is called self-adjoint.

Example 1: $Ly = y''$, $0 < x < \pi$, $y(0) = y(\pi) = 0$

Eigenvalue problem $y'' + \lambda y = 0$

Eigenfunctions $y_n = c \sin(\lambda_n x)$, $\lambda_n = n^2$, $n = 1, 2, 3, \dots$

Note that $\lambda = 0$ is not an eigenvalue

Normalize the eigenfunctions with the inner product $\langle f, g \rangle = \int_0^\pi f(x)g(x) dx$

$$\rightarrow y_n = \sqrt{\frac{2}{\pi}} \sin(nx)$$

$$\text{note } \langle x_n, x_n \rangle = \int_0^\pi x_n(x) x_n(x) dx = \delta_{nn}$$

$$\langle Ly, y \rangle = \int_0^\pi y''y dx = [y'y]_0^\pi - \int_0^\pi y'y' dx = - \int_0^\pi y'^2 dx \leq 0$$

Example 2 : $y'' + \lambda y = 0$, $0 < x < 1$, $y'(0) = 0$, $y(1) + y'(1) = 0$

Assume that $y = e^{mx}$

$$\Rightarrow m^2 + \lambda = 0 \Rightarrow m = \pm i\sqrt{\lambda} \text{ if } \lambda \geq 0$$

• If $\lambda = 0$: $y'' = 0 \rightarrow y = c_1 + c_2 x$

$$\boxed{y' = c_2}$$

$$y'(0) = c_2 = 0, \boxed{y = c_1}$$

↑
contradiction
↓

$$\text{and } y(1) + y'(1) = 0 \rightarrow \boxed{y'(1) = -c_1}$$

$$\Rightarrow \boxed{\lambda \neq 0}$$

• If $\lambda < 0$ take $\lambda = -k^2$, $y = c_1 e^{kx} + c_2 e^{-kx}$

$$\text{or take } y = c_1 \cosh(kx) + c_2 \sinh(kx)$$

$$y' = k(c_1 \sinh(kx) + c_2 \cosh(kx))$$

$$y'(0) = kc_2 = 0 \rightarrow \boxed{c_2 = 0}$$

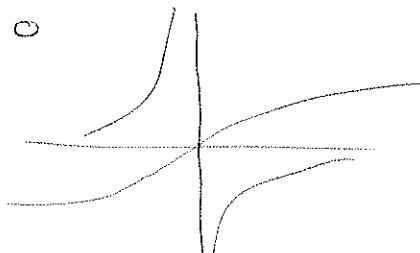
$$y(1) + y'(1) = 0 = c_1 \cosh(k) + k c_1 \sinh(k) = 0$$

$$\rightarrow \cosh(k) + k \sinh(k) = 0$$

$$\rightarrow \tanh k = -\frac{1}{k}$$

no intersection

$$\text{therefore } \boxed{\lambda < 0}$$



Now examine in more detail $\lambda > 0$

$$m = \pm i\sqrt{\lambda}$$

$$y = c_1 \cos(mx) + c_2 \sin(mx)$$

$$y' = -mc_1 \sin(mx) + mc_2 \cos(mx)$$

$$y'(0) = mc_2 = 0$$

$$\Rightarrow y = c_1 \cos(mx)$$

$$y'(1) + y(1) = -mc_1 \sin(m) + c_1 \cos(m) = 0$$

$$\rightarrow \boxed{\tan(m) = \frac{1}{m}} \quad \lambda = m^2$$

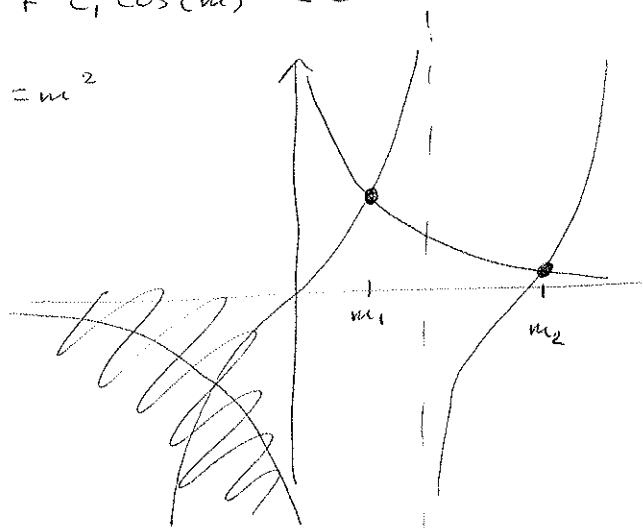
$$m_1 = 0.86033$$

$$\lambda_1 = 0.7402$$

Notice, as $n \rightarrow \infty$

$$m_n \rightarrow n \pi$$

$$\lambda_n \rightarrow n^2 \pi^2$$



Next Time: Cochran 2.3, pg 52 # 10

Eigenvalue Problems For ODE's

{ Cochran, Chpt 2
 { My notes on Eigenvalue Problems } available on line

Regular Sturm-Liouville ProblemsSeparated Boundary conditions

$$Ly + \lambda r y = (py')' + (\lambda r - q)y = 0, \quad a < x < b$$

$$A y(a) - B y'(a) = 0$$

$$C y(b) + D y'(b) = 0$$

$$\Rightarrow Ly = (py')' - qy$$

$$uLv - vLu = u[(pv')' - qv] - v[(pu')' - qu]$$

$$= u(pv')' - v(pu')' = \frac{d}{dx}(pW(u,v))$$

Wronskian: $W(u,v) = \begin{vmatrix} u & v \\ u' & v' \end{vmatrix} = uv' - u'v$

$$pW(u,v) = p(uv' - u'v)$$

$$\frac{d}{dx}(pW(u,v)) = p(uv'' - u''v) + pu'v' - (pu')v - pu''v'$$

$$= u(pv')' - v(pu')' = uLv - vLu$$

$$\int_a^b (uLv - vLu) dx = \int_a^b \frac{d}{dx} (PW(u, v)) = \left[PW(u, v) \right]_a^b = 0 \quad (\text{in the regular case})$$

Herron
- see notes

IF $Lu + \lambda rv = 0$

$Lv + \nu rv = 0$ then u and v are eigenfunctions.

multiply 1st by v , 2nd by u and subtract.

$$\Rightarrow (\lambda - \nu) rvu = \frac{d}{dx} (PW(u, v))$$

$$\Rightarrow (\lambda - \nu) \int_a^b ruv dx = 0$$

\Rightarrow Property 1 IF $\lambda = \nu$, then $W(u, v) = 0$ so u and v are linearly dependent.

\Rightarrow Property 2 IF $\lambda \neq \nu$ then $\int_a^b ruv dx = 0$ and u and v are linearly independent. That is u and v (both nonzero) are orthogonal with weight function r .

\Rightarrow Property 3 Every eigenvalue is real. Each corresponding eigenfunction can be chosen to be real.

Suppose L is symmetric ($\int_a^b (vLw - wLv) dx = 0$)

$$Ly + \lambda r y = 0$$

Suppose λ is complex then $y(x) = y_1(x) + iy_2(x)$

Take the complex conjugate: $\bar{y}(x) = y_1(x) - iy_2(x)$

$$L\bar{y} + \bar{\lambda}r\bar{y} = 0$$

Use the previous argument where $v=y$, $w=\bar{y}$

$$(\lambda - \bar{\lambda}) \int_a^b r y \bar{y} dx = 0$$

$$(\lambda - \bar{\lambda}) \int_a^b r \|y\|^2 dx = 0 \rightarrow \boxed{\lambda \text{ is real}}$$

$\hookrightarrow L$ is symmetric if $\langle Lv, v \rangle = \langle v, Lv \rangle$

Example: $y'' + \lambda y = 0$, $0 < x < 1$

$$y'(0) = 0, \quad y(1) + y'(1) = 0$$

we found last time that $y_n(x) = c_n \cos(k_n x)$, $n = 1, \dots$

$$\text{where } \tan k_n = \frac{1}{k_n}, \quad n = 1, \dots$$

orthogonality:

$$\begin{aligned} \int_0^1 \cos(k_1 x) \cos(k_2 x) dx &= \frac{1}{2} \int_0^1 [\cos((k_1 + k_2)x) + \cos((k_1 - k_2)x)] dx \\ &= \left[\frac{1}{2} \frac{\sin((k_1 + k_2)x)}{k_1 + k_2} + \frac{1}{2} \frac{\sin((k_1 - k_2)x)}{k_1 - k_2} \right]_0^1 \quad \boxed{\text{Note, } k_1 \neq k_2} \\ &= \frac{1}{2} \left(\frac{\sin(k_1 + k_2)}{k_1 + k_2} + \frac{\sin(k_1 - k_2)}{k_1 - k_2} \right) \\ &= \frac{1}{2} \left(\frac{\sin k_1 \cos k_2 + \cos k_1 \sin k_2}{k_1 + k_2} + \frac{\sin k_1 \cos k_2 - \cos k_1 \sin k_2}{k_1 - k_2} \right) \end{aligned}$$

$$\text{we know } \frac{\sin k_1}{\cos k_1} = \frac{1}{k_1}$$

$$\begin{aligned}\Rightarrow &= \frac{1}{2} \left[\frac{k_2 \sin k_1 \sin k_2}{k_1 + k_2} + \frac{k_1 \sin k_1 \sin k_2}{k_1 + k_2} + \frac{(k_2 - k_1) \sin k_1 \sin k_2}{k_1 - k_2} \right] \\ &= \frac{1}{2} \left[\frac{(k_2 + k_1) \sin k_1 \sin k_2}{k_1 + k_2} + \frac{(k_2 - k_1) \sin k_1 \sin k_2}{k_1 - k_2} \right] \\ &= \frac{1}{2} \sin k_1 \sin k_2 \left(\frac{(k_2 + k_1)(k_1 - k_2)}{(k_1 - k_2)(k_1 + k_2)} + \frac{(k_2 - k_1)(k_2 - k_1)}{(k_1 - k_2)(k_1 + k_2)} \right)\end{aligned}$$

≈ 0

Normalize the eigenfunctions: $\int_0^1 y_i(x) y_j(x) dx = \delta_{ij}$

choose c_i so that

$$\int_0^1 y_i^2 dx = 1$$

$$y_i = c_i \cos(k_i x)$$

$$\begin{aligned}c_i^2 \int_0^1 \cos^2(k_i x) dx &= \frac{1}{2} c_i^2 \int_0^1 (\cos 2k_i x + 1) dx = \left[\frac{c_i^2 \sin(2k_i x)}{4k_i} + \frac{x c_i^2}{2} \right]_0^1 \\ &= \frac{c_i^2}{4k_i} \sin 2k_i + \frac{c_i^2}{2} = 1\end{aligned}$$

$$\Rightarrow c_i^2 \left(\frac{\sin 2k_i}{2(2k_i)} + \frac{1}{2} \right) = 1 \Rightarrow c_i^2 \left(\frac{2 \sin k_i \cos k_i}{2k_i} + \frac{1}{2} \right) = 1$$

$$\text{But } \frac{\cos k_i}{k_i} = \sin k_i \Rightarrow c_i^2 \left(\frac{\sin^2 k_i}{2} + \frac{1}{2} \right) = 1$$

$$\Rightarrow c_i = \sqrt{\frac{2}{\sin^2 k_i + 1}}$$

the normalized constant depends on the eigenvalue.

Example: $y'' + \lambda y = 0$, $0 < x < \pi$

$$y(0) = y(\pi) = 0$$

$$\lambda_n = n^2, n=1,$$

Cochran pg 52 #10 a

$$Ly + \lambda r y = (py')' + (\lambda r - q)y = 0$$

reality holds

$$\int_a^b y Ly dx + \lambda \int_a^b ry^2 dx = 0$$

$$\begin{aligned} \int_a^b y Ly dx &= \int_a^b y(py')' dx - \int_a^b qy^2 dx \\ &= [pyy']_a^b - \int_a^b (py'^2 + qy^2) dx \end{aligned}$$

$$\rightarrow \lambda \int_a^b ry^2 dx = \int_a^b (py'^2 + qy^2) dx + p(a)y'(a)y(a) - p(b)y'(b)y(b)$$

$$\left. \begin{aligned} \text{By assumption, } y(a) &= \frac{B}{A} y'(a) \\ y(b) &= \frac{-H}{G} y'(b) \end{aligned} \right\}$$

$$\rightarrow = \int_a^b (py'^2 + qy^2) dx + p(a)(y'(a))^2 \frac{B}{A} + p(b)(y'(b))^2 \frac{H}{G}$$

$$\text{If } q(x) \geq 0, AB \geq 0, GH \geq 0$$

$$\text{Hence } \lambda > 0$$

Cochran pg 52 #10b

Show that a similar conclusion is valid if $p(a) = p(b)$,

$$y(a) = y(b), \quad y'(a) = y'(b)$$

(Cochran pg 52 #10c)

Are there mixed homogeneous BCs other than periodic ones for which the eigenvalues of the associated Sturm-Liouville problem are non-negative?

Yes need real eigenvalues

Ex: $y'' + \lambda y = 0, \quad 0 \leq x \leq 1$

$$y'(1) = y'(0)$$

$$y'(1) - y(1) + y(0) = 0$$

The previous analyses do not apply since the BCs are neither separated or periodic.

Let $\lambda = k^2$

Then ~~$y = c_1 \cos kx + c_2 \sin kx$~~

~~$y' = -c_1 k \sin kx + c_2 k \cos kx$~~

$$y = c_1 \cos kx + c_2 \sin kx$$

$$y' = -c_1 k \sin kx + c_2 k \cos kx$$

$$y'(1) = y'(0) \Rightarrow -c_1 k \sin k + c_2 k \overset{\cos k}{=} c_2 k$$

$$y'(1) - y(1) + y(0) = 0 \Rightarrow -c_1 k \sin k + c_2 k \cos k - c_1 \cos k - c_2 \sin k + c_1 = 0$$

$$\begin{cases} -c_1 k \sin k + c_2(k \cos k - k) = 0 \\ c_1(-k \sin k - \cos k + 1) + c_2(k \cos k - \sin k) = 0 \end{cases}$$

Is $k=0$ an eigenvalue? IF it is, $y'' \neq 0 \Rightarrow y = ax + b$

$y(0) = y'(1)$ is satisfied

$$y'(1) - y(1) + y(0) = a - (a+b) + b = 0, \text{ so satisfied}$$

Hence, corresponding to $\lambda = 0$, $y = 1$ and $y = x$ are both eigenfunctions.

4/4

cancel out the k :

$$-c_1 \sin k + c_2 (\cos k - 1) = 0$$

$$c_1 (-k \sin k - \cos k + 1) + c_2 (k \cos k - \sin k) = 0$$

Require that determinant of coefficients vanish:

$$\begin{vmatrix} \text{Eigenvk} & \begin{vmatrix} -\sin k & \cos k - 1 \\ -k \sin k - \cos k + 1 & k \cos k - \sin k \end{vmatrix} = 0 \end{vmatrix}$$

$$\Rightarrow \cancel{-k \sin k \cos k + \sin^2 k} + \cancel{k \sin k \cos k} - k \sin k + \cancel{\cos^2 k} - \cos k - \cos k + 1 = 0$$

$$2 - k \sin k - 2 \cos k = 0$$

$$\cancel{+ 2 \cos^2 \frac{k}{2}} = \sin k \quad 1 - 2 \sin^2 \frac{k}{2} = \cos(k)$$

$$2 \sin \frac{k}{2} \cos \frac{k}{2} = \sin k$$

$$\cancel{2 - 2 k \sin \frac{k}{2} \cos \frac{k}{2} - 2} + 4 \sin^2 \frac{k}{2} = 0$$

$$2 \sin \frac{k}{2} \left(2 \sin \frac{k}{2} - k \cos \frac{k}{2} \right) = 0$$

$$\Rightarrow 2 \sin \frac{k}{2} = 0, \quad 2 \sin \frac{k}{2} - k \cos \frac{k}{2} = 0$$

$$\Rightarrow \frac{k}{2} = n\pi, n=1, 2, \dots, \quad \tan \frac{k}{2} = \frac{k}{2}$$

or use the type of argument developed so far:

$$Lu + \lambda u = 0$$

$$Lv + \nu v = 0$$

show that $\int_0^l (\lambda v) uv dx = 0$ and that if $v = \bar{v}$, $\lambda = \bar{\lambda}$

then λ is real. Accept the reality of the eigenvalue.

$$\int_0^l (y'' + \lambda y) y dx = 0$$

$$\text{integrate by parts: } [y'y]_0^l - \int_0^l y'^2 dx + \lambda \int_0^l y^2 dx = 0$$

$$\text{Examine: } [y' y]_0^1 = y'(1)y(1) - y'(0)y(0)$$

The BCs were $y'(1) = y'(0)$ and $y'(1) + y(1) + y(0) = 0$

$$\Rightarrow [y' y]_0^1 = y'(1)y(1) + y'(1)(y'(1) - y(1)) \\ = (y'(1))^2$$

$$\Rightarrow \lambda \int_0^1 y^2 dx = \int_0^1 (y')^2 dx - (y'(1))^2$$

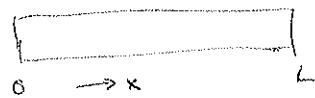
$$\text{If } y = 1, y' = 0 \rightarrow \lambda = 0$$

$$\text{If } y = x, y' = 1 \rightarrow \lambda = 0$$

Now if you take $\lambda = -n^2$, you find that there are no negative eigenvalues.

Motivation: Heat conduction in a non-uniform medium

one-dimensional, $u(x, t)$, temperature



~~$\rho c \frac{\partial u}{\partial t} = \frac{\partial}{\partial x} (k_0(x) \frac{\partial u}{\partial x})$~~

where ρ = density, c = thermal capacity, $k_0(x)$ conductivity
 ρ, c, k_0 time-independent

Let $u(x, t) = \varphi(x) e^{-\lambda t}$, separation of variables

$$\rho c (-\lambda) \varphi e^{-\lambda t} = \frac{d}{dx} (k_0(x) \varphi') e^{-\lambda t}, e^{-\lambda t} \neq 0$$

$$\rightarrow (k_0(x) \varphi')' + \lambda \rho c \varphi = 0$$

typical boundary conditions, temp given at the ends

Regular Sturm-Liouville

Model Example, $L = 1$

$$k_0(x) = \frac{1}{(1+x)^2}, \rho c = \frac{1}{(1+x)^2}$$

we arrive at

$$\left(\frac{1}{(1+x)^2} \varphi' \right)' + \frac{\lambda}{(1+x)^2} \varphi = 0$$

Boundary condition: $\varphi(0) = \varphi(1) = 0$

Since this is a regular Sturm-Liouville problem and because of the boundary conditions all eigenvalues are non-negative.

$$\text{Set } \lambda = k^2 \rightarrow \sqrt{\lambda} = k$$

$$\left(\frac{\varphi'}{(1+x)^2} \right)' + \frac{\lambda}{(1+x)^2} \varphi = 0$$

$$\frac{\varphi''}{(1+x)^2} - \frac{2\varphi'}{(1+x)^3} + \frac{\lambda}{(1+x)^2} \varphi = 0$$

General solution:

$$\varphi(x) = c_1(K(1+x)\cos(kx) - \sin(kx)) + c_2(K(1+x)\sin(kx) + \cos(kx))$$

Apply BCs

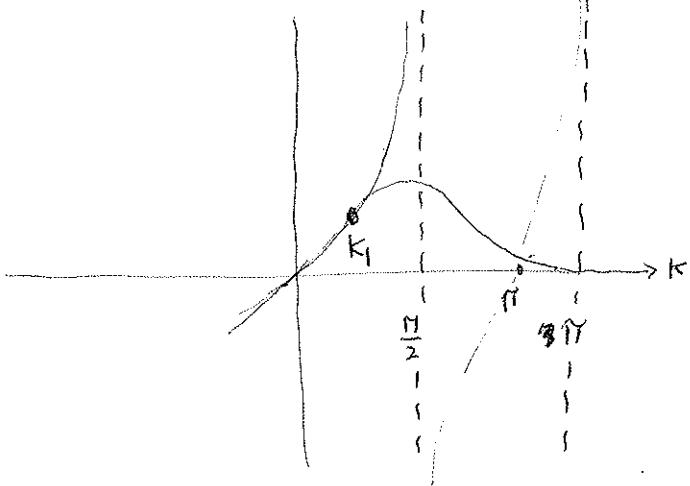
$$\varphi(0) = c_1K + c_2(1) = 0 \Rightarrow c_2 = -Kc_1$$

$$\varphi(1) = c_1(2K\cos k - \sin k) + c_2(2K\sin k + \cos k) = 0$$

$$\Rightarrow c_1(2K\cos k - \sin k) - Kc_1(2K\sin k + \cos k) = 0$$

For non-trivial solution, $c_1 \neq 0$

$$K\cos k - (1+2K^2)\sin k = 0 \rightarrow \tan k = \frac{k}{1+k^2}$$



$$k_1 \approx 3.286 \rightarrow \lambda_1 \approx 10.80$$

notice, as $n \rightarrow \infty$, the eigenvalues look more and more like $\tan(nk) = 0$
 $\Rightarrow k_n \sim n\pi$ as $n \rightarrow \infty$

Is $\lambda = 0$ an eigenvalue?

$$\left(\frac{\varphi'}{(1+x)^2} \right)' = 0 \rightarrow \varphi = c_2 + \frac{c_1}{3}(1+x)^3$$

$$\text{apply BCs: } \begin{cases} \varphi(0) = \frac{c_1}{3} + c_2 = 0 \\ \varphi(1) = \frac{8}{3}c_1 + c_2 = 0 \end{cases} \quad \left. \begin{array}{l} c_1 = c_2 = 0 \end{array} \right\}$$

$$\boxed{\lambda \neq 0}$$

Last period we solved Cochran, pg 52 # 10(a)

$$(py')' + (\lambda r - g)y = 0$$

$$Ay(a) + By'(a) = 0$$

$$gy(b) - Hy'(b) = 0$$

IF $g(x)$ as well as AB and GH are nonnegative,
show that all eigenvalues are nonnegative.

Cochran section 2.5

Eigenfunction Expansions

Flow in a channel. Sought $n(x,t)$ - wave height.

$$\frac{\partial^2 n}{\partial t^2} = \frac{g}{b} \frac{\partial}{\partial x} \left(b h \frac{\partial n}{\partial x} \right), \quad t > 0, \quad a < x < c$$

Initial value problem:

$$n(x,0) = n_0(x), \quad n_t(x,0) = 0, \quad n(a,t) = n(c,t) = 0$$

Look for solutions $n(x,t) = F(x)G(t)$, obtain two equations.

• $(bh F')' + \frac{\lambda b}{g} F = 0$ - Sturm-Liouville equation

$$F(0) = F(c)$$

• $\frac{G''}{G} = -\lambda_n \rightarrow G'' + \lambda_n G = 0$ - time-dependent problem, $G = G(t)$

Suppose $n(x,t) = \sum_{n=1}^{\infty} F_n(x) G_n(t)$

$$n(a,t) = n(c,t) = 0 \Rightarrow F_n(a) = F_n(c) = 0, \forall n$$

$$n(x,0) = \sum_{n=1}^{\infty} F_n(x) G_n(0) = n_0(x)$$

$$n_t(x,0) = \sum_{n=1}^{\infty} F_n(x) G'_n(0) = 0$$

Thus $G_n(t) = \cos(\omega_n t)$, where $\omega_n = \sqrt{\lambda_n}$

$$\rightarrow u_n(x) = \sum_{n=1}^{\infty} F_n(x)$$

Take $F_n(x) = c_n y_n(x)$ where the y_n are the eigenfunctions of $(bhy')' + \frac{\omega^2 b}{3} y = 0$

Questions:

① What are the constants c_n ?

② What about the convergence of the series?

Return to Example ①: $Ly = y''$, $0 < x < \pi$
 $y(0) = y(\pi) = 0$

- solved $y'' + \lambda y = 0$

- find that eigenfunction $y = c \sin(\sqrt{\lambda} x)$, $\lambda = n^2$

$\rightarrow y_n = \int_0^{\pi} \sin(nx) dx$, - normalized coefficient from $\int_0^{\pi} y_n^2 dx = 1$

$$\int_0^{\pi} y_n(x) y_m(x) dx = S_{mn} = \begin{cases} 1, & m=n \\ 0, & m \neq n \end{cases}$$

To make use of this in describing a function $(0, \pi)$
we make use of theory of Fourier series,

$$f(x) = \sum_{n=1}^{\infty} a_n \sin(nx)$$

Multiply by $\sin(mx)$, integrate from 0 to π

$$\int_0^{\pi} f(x) \sin(mx) dx = \int_0^{\pi} \sum_{n=1}^{\infty} a_n \sin(nx) \sin(mx) dx = \underbrace{\int_0^{\pi} a_m \sin^2(mx) dx}_{\text{only 1 term survived}}$$

$$= \int_0^{\pi} \left(\frac{a_m}{2} - \frac{a_m}{2} \cos 2x \right) dx$$

$$= \left[\frac{a_m x}{2} - \frac{a_m}{4} \sin 2x \right]_0^{\pi}$$

$$= \frac{M a_m}{2}$$

$$\Rightarrow a_m = \frac{2}{\pi} \int_0^{\pi} f(x) \sin(mx) dx$$

$$\cos^2 x - \sin^2 x = \cos 2x$$

$$1 - 2 \sin^2 x = \cos 2x$$

$$\sin^2 x = \frac{1}{2} - \frac{1}{2} \cos 2x$$

The equality $f(x) = \sum_{n=1}^{\infty} a_n \sin(nx)$

is to be understood in the sense that

$$\lim_{N \rightarrow \infty} \int_0^{\pi} \left[f(x) - \sum_{n=1}^N a_n \sin(nx) \right]^2 dx = 0$$

The sine functions are complete in the sense that any square integrable f can be written in such a series and the series converges to f in the above sense.

Cochran 2.5

Property 2: The eigenfunction of the Sturm-Liouville problem form a complete set.

Property 3: If $f(x)$ is continuous on $[a, b]$ and $\{y_i\}$ is the orthonormal sequence of eigenfunctions associated with the eigenvalue problem (2.3-1), then

Generalized Fourier Series

$$f = \sum_{n=1}^{\infty} \langle f, y_n \rangle y_n$$

where the equality is meant in the sense that

$$\lim_{N \rightarrow \infty} \| f - \sum_{n=1}^N \langle f, y_n \rangle y_n \| = 0$$

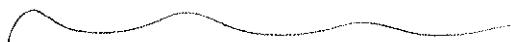
Parseval's Equality is valid:

$$\sum_{n=1}^{\infty} \langle f, y_n \rangle^2 = \| f \|^2$$

Fourier sine series, $y_n = \sqrt{\frac{2}{\pi}} \sin(nx)$

$$\langle f, y_n \rangle = \int_0^{\pi} f(x) \sin(nx) dx$$

$$f = \sum_{n=1}^{\infty} \langle f, y_n \rangle y_n = \sum_{n=1}^{\infty} \sqrt{\frac{2}{\pi}} \int_0^{\pi} f(x) \sin(nx) dx \sqrt{\frac{2}{\pi}} \sin(nx)$$



Example: $x^2 y'' + xy' + \lambda y = 0$, $1 < x < e$

a) Given that the eigenvalues and eigenfunctions

are $\lambda_n = n^2 \pi^2$, $y_n = \sin(n \pi \ln x)$, $n = 1, 2, \dots$

b) If $f(x)$ is piecewise differentiable in the interval $(1, e)$ and if

$$f(x) = \sum_{n=1}^{\infty} x_n \sin(n \pi \ln x)$$

then show that

$$x_n = \frac{\int_1^e f(x) \sin(n \pi \ln x) \frac{1}{x} dx}{\int_1^e \sin^2(n \pi \ln x) \frac{1}{x} dx}$$

Divide diff equation by x : $x y'' + y' + \frac{\lambda}{x} y = 0$

$$\rightarrow (xy')' + \frac{\lambda}{x} y = 0, \text{ so } p(x) = x, q(x) = 0, r(x) = \frac{1}{x}$$

Normalize the eigenfunctions:

Begin with assumed form for $f(x)$, multiply both sides by $y_n(x)$ and integrate.

$$\int_1^e f(x) \frac{1}{x} \sin(n\pi \ln x) dx = \int_1^e \sum_{n=1}^{\infty} d_n \sin(n\pi \ln x) \frac{1}{x} \underbrace{\sin(m\pi \ln x)}_m dx$$

we know $\int_1^e \sin(n\pi \ln x) \frac{1}{x} \sin(m\pi \ln x) dx = 0$, $m \neq n$

$$\text{then } \int_1^e f(x) \frac{1}{x} \sin(m\pi \ln x) dx = d_m \int_1^e \frac{\sin^2(m\pi \ln x)}{x} dx$$

$$\Rightarrow d_m = \frac{\int_1^e f(x) \frac{1}{x} \sin(m\pi \ln x) dx}{\int_1^e \frac{\sin^2(m\pi \ln x)}{x} dx}$$

By introducing an appropriate change of variables, reduce this result to form

$$d_m = 2 \int_0^1 f(e^t) \sin(m\pi t) dt$$

$$\text{Let } x = e^t, t = \ln x$$

$$dx = e^t dt$$

$$\text{From } [1, e] \rightarrow [0, 1]$$

$$d_m = \frac{\int_0^1 f(e^t) e^{-t} \sin(m\pi t) e^t dt}{\int_0^1 \sin^2(m\pi t) dt} = 2 \int_0^1 f(e^t) \sin(m\pi t) dt$$

Evaluate d_n when $f(x) = 1$ and when $f(x) = x$

$$d_n = 2 \int_0^1 f(e^t) \sin(n\pi t) dt$$

$$f=1 \Rightarrow d_n = 2 \int_0^1 \sin(n\pi t) dt = \left[-\frac{2}{n\pi} \cos(n\pi t) \right]_0^1$$

$$d_n = \frac{2}{n\pi} (1 - (-1)^n)$$

$$\text{when } F(x) = x \quad \text{then} \quad d_n = 2 \int_0^1 e^t \sin(n\pi t) dt$$

$$d_n = \frac{e}{1+n^2\pi^2} \left(\sin(n\pi) - n\pi \cos(n\pi) \right) \Big|_0^1$$

$$\boxed{d_n \approx \frac{n\pi}{1+n^2\pi^2} \left(1 - e(-1)^n \right)}$$

Next time: More discussion of convergence

Special Functions (Cochran, Chpt 3)

Last time - Heat Conduction $\rho c v_x = (k_0(x)v_x)_x$

1/6

where ρ = density, c = specific heat

Sturm-Liouville problem obtained by setting $v(x,t) = e^{xt} \varphi(x)$
 $\Rightarrow (k_0(x)\varphi')' + \rho c \lambda \varphi = 0$, with boundary conditions.

In general, if the ODE is written

$$(P(x)y')' + (\lambda R(x) - Q(x))y = 0 \quad , \quad a < x < b$$

may be transformed "Liouville Normal Form"

$$v''(t) + (\lambda - q(t))v(t) = 0 \quad ,$$

which is advantageous because reduced problem with
 three coefficients (functions) to one function coeff ($q(t)$).
 Change independent and dependent variables:

$$\text{Let } y(x) = \frac{v(t)}{\sqrt[4]{P(x)R(x)}} \quad , \quad t = \int_a^x \sqrt{R(x)/P(x)} dx \quad , \quad 0 \leq t \leq 1$$

See details in Courant & Hilbert, vol I

~~we can~~

Example: $\left(\frac{\varphi'}{(1+x)^2}\right)' + \frac{\lambda}{(1+x)^2} \varphi = 0 \quad , \quad 0 < x < 1$

$$\Rightarrow P(x) = \frac{1}{(1+x)^2} \quad , \quad R(x) = \frac{1}{(1+x)^2} \quad , \quad Q(x) = 0$$

$$\Rightarrow t = \frac{\int_0^x \sqrt{\frac{(1+x)^2}{(1+x)^2}} dx}{\int_0^1 dx} = \int_0^x dx = x \Rightarrow t = x$$

$$\varphi(x) = \frac{v(x)}{\sqrt[4]{\frac{1}{(1+x)^4}}} = v(x)(1+x)$$

$$v(x) = \frac{\varphi(x)}{1+x}$$

$$\begin{aligned} \varphi'(x) &= (1+x)v' + v \\ \frac{\varphi'(x)}{(1+x)^2} &= \frac{v'}{1+x} + \frac{v}{(1+x)^2} \\ \left(\frac{\varphi'(x)}{(1+x)^2}\right)' &= \frac{v''}{1+x} \end{aligned}$$

see next

The ODE becomes:

$$v'' + \left(\lambda - \frac{2}{(1+x)^2}\right)v = 0 \quad , \quad 0 < x < 1$$

SEE NEXT PAGE

$$\begin{aligned} \frac{d}{a} \mp &= m''(p) \\ \frac{d^2}{a^2} \mp &= m'''(p) \end{aligned}$$

The third derivatives are, from the 1 and 2-rarefactions:

$$\begin{aligned} m''(p) &= \pm \frac{2\phi_2}{a} \\ \left(\frac{\phi_2 \wedge \phi_2 / \phi_2}{\phi_2 - p} + \frac{6\phi_2 \wedge \phi_2}{a(p)} \right) \mp &= m'''(p) \end{aligned}$$

The third derivative is, from the Hugoniot locus:

$$\begin{aligned} \frac{d}{a} &= m''(p) \\ \frac{d}{a} &= m''(p) \\ \frac{d}{a} + \frac{p_1}{m} &= m'(p) \\ \frac{d}{a} + \frac{p_1}{m} + ap \log \frac{p}{p_1} &= m(p) \end{aligned}$$

From exercise 8.1, the 2-rarefactions are given by:

$$\begin{aligned} \frac{d}{a} &= m''(p) \\ \frac{d}{a} &= m''(p) \\ \frac{d}{a} - a - \frac{p_1}{m} &= m'(p) \\ \frac{d}{a} - a - ap \log \frac{p}{p_1} &= m(p) \end{aligned}$$

From example 8.1, the 1-rarefactions are given by:

$$\begin{aligned} \frac{d}{a} \mp &= m''(p) \\ \left(\frac{2\phi_2 \wedge \phi_2}{a} + \frac{2\phi_2 \wedge \phi_2}{a} - \frac{4\phi_2 \wedge \phi_2}{a(\phi_2 - p)} \right) \mp &= m''(p) \\ \left(\frac{2\phi_2 \wedge \phi_2}{a(\phi_2 - p)} + \frac{d}{a} \wedge \frac{d}{a} \right) \mp &= m'(p) \\ m(p) &= pm/a \mp a(p - \phi_2) \end{aligned}$$

From the Hugoniot locus we have:

Also verify that the third derivatives are not equal.

$$m(p) = \frac{p_1}{m} - ap \log \frac{p}{p_1} \quad \text{or} \quad m(p) = pm/a \mp a(p - \phi_2)$$

and for the integral curves from

$$m = pm/a \mp a(p - \phi_2)$$

for the Hugoniot locus from

Verify that the curvature of the integral curves and the Hugoniot locus are the same by computing $m''(p)$

Exercise 8.3, page 86

$$\left(\frac{\varphi'(x)}{(1+x)^2} \right)' = \frac{v''}{1+x} - \frac{v'}{(1+x)^2} + \frac{v'}{(1+x)^2} = \frac{2v}{(1+x)^3}$$

$$\frac{\lambda \varphi}{(1+x)^2} = \frac{\lambda(1+x)v}{(1+x)^2}$$

$$\Rightarrow \left(\frac{\varphi'(x)}{(1+x)^2} \right)' + \frac{\lambda \varphi}{(1+x)^2} = \frac{v''}{1+x} - \frac{2v}{(1+x)^3} + \frac{\lambda(1+x)v}{(1+x)^2} = 0$$

$$\Rightarrow \frac{v''}{1+x} - \frac{2v}{(1+x)^3} + \frac{\lambda v}{1+x} = 0$$

$$\Rightarrow v'' + \left(\lambda - \frac{2v}{(1+x)^2} \right) v = 0$$

Bari's Thm: (1960s) Let $\{\varphi_k\}$ be any complete sequence of orthonormal functions in an inner product space E and let $\{\psi_k\}$ be any sequence of orthonormal vectors in E which satisfy the inequality $\sum_{k=1}^{\infty} \|\varphi_k - \psi_k\|^2 < \infty$

Then $\{\psi_k\}$ is complete in E .

In the notes, looking at $(Py')' + (\lambda R - Q)y = 0$
with BCs $\alpha y(a) + \beta_1 y'(a) = 0$, $\beta_2 y(b) + \beta_1 y'(b) = 0$,

specific example: $v'' + (\lambda - q(t))v = 0$

• If $\alpha, \beta_i \neq 0 \rightarrow v_n(t) \sim \sqrt{2} \cos(n\pi t) + O(\frac{1}{n})$ as $n \rightarrow \infty$
↳ eigenfunctions corresponding to the higher eigenvalues

• If $(\alpha, \beta_i) = 0 \rightarrow v_n(t) \sim \sqrt{2} \sin(n\pi t) + O(\frac{1}{n})$ as $n \rightarrow \infty$

Note - ~~geometric~~ trigonometric sequences are complete

so $\varphi_n = \sqrt{2} \sin(n\pi t)$, $\|v_n - \varphi_n\|^2 = O(\frac{1}{n^2})$

$$\begin{aligned}
 m(u) &= \chi(p_i) \\
 u + \frac{p_i}{m} &= m(p_i) \\
 \frac{p_i}{d} + a + a \log \frac{p_i}{m} &= m(p_i) \\
 \frac{p_i}{d} + a p_i \log \frac{p_i}{m} &= m(p_i)
 \end{aligned}$$

From exercise 8.1, the 2-rarefactions are given by:

$$\begin{aligned}
 \chi(u) &= m(p_i) \\
 u - \frac{p_i}{m} &= m(p_i) \\
 u - a - a \log \frac{p_i}{m} &= m(p_i) \\
 u - a p_i \log \frac{p_i}{m} &= m(p_i)
 \end{aligned}$$

From example 8.1, the 1-rarefactions are given by:

Verify that $m'(p_i) = \chi'(u_i)$ and explain why this should be so.

Exercise 8.2, Page 85

Example from last time

$$\left(\frac{\varphi'}{(1+x)^2} \right)' + \frac{\lambda}{(1+x)^2} \varphi = 0, \quad 0 < x < 1, \quad \varphi(0) = \varphi(1) = 0$$

General solution: $\varphi(x) = c_1 (\cos(kx) + k(1+x) \sin(kx))$
 $+ c_2 (\sin(kx) - k(1+x) \cos(kx))$

$$\Rightarrow v = c_1 \left(\frac{\cos kx}{1+x} + k \sin(kx) \right) + c_2 \left(\frac{\sin kx}{1+x} - k \cos(kx) \right)$$

$$v(0) = v(1) = 0$$

$$\Rightarrow c_1 - kc_2 = 0$$

$$v = c_2 \left(\frac{k \cos kx}{1+x} + k^2 \sin kx + \frac{\sin kx}{1+x} - k \cos kx \right)$$

dominant term for large k

Related problem: $y'' + \lambda y, \quad 0 < x < 2\pi$

$$y(0) = y(2\pi)$$

$$y'(0) = y'(2\pi), \quad \text{periodic BCs}$$

We can show that all eigenvalues are real and nonnegative.

We can show that all eigenvalues are real and nonnegative.

$$y = c_1 \cos \sqrt{\lambda} x + c_2 \sin \sqrt{\lambda} x, \quad \sqrt{\lambda} = k$$

$$y(0) = c_1, \quad y(2\pi) = c_1 \cos(2\pi k) + c_2 \sin(2\pi k)$$

$$y'(0) = c_2 k, \quad y'(2\pi) = -k c_1 \sin(2\pi k) + k c_2 \cos(2\pi k)$$

$$\Rightarrow c_1 (\cos 2\pi k - 1) + c_2 \sin(2\pi k) = 0$$

$$-c_1 \sin 2\pi k + c_2 (\cos 2\pi k - 1) = 0$$

For non-trivial solution

$$\Rightarrow \begin{vmatrix} \cos 2\pi k - 1 & \sin 2\pi k \\ -\sin 2\pi k & \cos 2\pi k - 1 \end{vmatrix} = 0$$

$$\Rightarrow (\cos 2\pi k - 1)^2 + \sin^2(2\pi k) = 0 \Rightarrow \cos^2(2\pi k) - 2\cos(2\pi k) + 1 + \sin^2(2\pi k) = 0$$

$$\Rightarrow \cos 2\pi k = 1 \Rightarrow \boxed{\lambda_n = (2\pi k)^2 n^2} \Rightarrow y_n = c_1 \cos(nx) + c_2 \sin(nx)$$

$$\Rightarrow \lambda_n = (2\pi k)^2 n^2 \Rightarrow y'' = 0, \quad y = c_1 + c_2 x$$

$$y(0) = y(2\pi) \Rightarrow c_1, \quad y'(0) = y'(2\pi)$$

$$\frac{d}{d} \log \frac{d}{d} + a \log \frac{d}{d} = (d) m$$

Substitute $\xi_1 = m/d - a$ to find:

$$\frac{d}{d} \log \frac{d}{d} + (a - \xi_1) d = (d) m$$

Substitute for ξ in the expression for $m(\xi)$ to solve for $m(d)$:

$$\xi = \xi_1 + a \log \frac{d}{d}$$

Now solve for ξ in terms of d :

$$m(\xi) = d(\xi - \xi_1/a)^{d/(d-\xi_1)}$$

We solve this to find:

$$m = (\xi) d^{d/(d-\xi_1)} + \frac{v}{(\xi) d} = (\xi) m$$

The second equation becomes:

$$m = (\xi) d^{d/(d-\xi_1)}$$

Solving the first equation we obtain:

$$\frac{(\xi) d/v}{v + (\xi) d/(\xi) m} = (\xi) m$$

$$\frac{v}{(\xi) d} = (\xi) d$$

For the 2-rarefaction, we use $p = 2$ and so the system of equations becomes

$$\frac{((\xi)x)^d \Delta}{((\xi)m)^d} = (\xi) \chi^d$$

Therefore substituting into the system of ordinary differential equations for $w(\xi)$ with boundary conditions $w(\xi_1) = u_1$ we have

$$\frac{d}{d} = (n) \chi_1 \cdot (n) \chi_1 \Delta$$

$$\frac{d}{d} = (n) \chi_2 \cdot (n) \chi_2 \Delta$$

The eigenvalues and eigenvectors for the isothermal equations are

Determine the expressions for 2-rarefactions for the isothermal equations.

Exercise 8.1, page 85

(41/6)

The relevant expansion is the Full range Fourier Series, $f(x)$ square integrable

on $[0, 2\pi]$, $f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos(nx) + b_n \sin(nx))$

• Boyce & DiPrima:

Suppose f and f' are piecewise continuous on $-L < x < L$.

Suppose f is defined outside to be periodic with period $2L$.

$$f(x) = \frac{a_0}{2} + \sum_{m=1}^{\infty} \left(a_m \cos\left(\frac{m\pi x}{L}\right) + b_m \sin\left(\frac{m\pi x}{L}\right) \right)$$

where $a_m = \frac{1}{\pi} \int_{-L}^L \cos\left(\frac{m\pi x}{L}\right) f(x) dx$

$$b_m = \frac{1}{\pi} \int_{-L}^L \sin\left(\frac{m\pi x}{L}\right) f(x) dx$$

The Fourier series converges to $f(x)$ at all points where f is continuous, and to $\frac{f(x^+) + f(x^-)}{2}$ at all points where $f(x)$ is discontinuous.

~~for check see Cochran Text~~ Appendix 3 - Series solutions of ODEs
see also Chpt 3: introduces solving Maxwell's eqns in a cylindrical geometry.

Many of the important special functions are defined as solutions to ODEs.

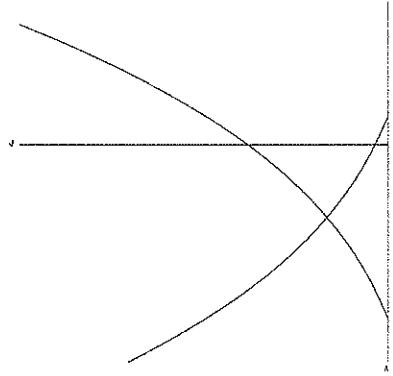
For example, solution by power series:

$$y'' + f(x)y' + g(x)y = 0$$

seek solutions of the form: $y = \sum_{k=0}^{\infty} c_k (x-x_0)^k$, $|x-x_0| < R$

Def: A point x_0 is an ordinary point of the diff eqn if there is an interval $|x-x_0| < R$ in which

$$f(x) = \sum_{k=0}^{\infty} d_k (x-x_0)^k, \quad g(x) = \sum_{k=0}^{\infty} e_k (x-x_0)^k \text{ both converge.}$$



The hysteresis loop is plotted below for $u = 1$,

$$\begin{aligned} (\eta; 0)^d \chi &= s \quad \text{for } d = 1, 2 \\ (\eta; 0)^d \phi &= \eta^d \frac{\partial \chi}{\partial u} \end{aligned}$$

Notice that

$$\begin{aligned} s_2(\xi; u) &= \left(\frac{\xi + \phi}{\phi + \xi + 2\phi} \right) \\ s_1(\xi; u) &= \left(\frac{\xi - \phi}{\phi + \xi + 2\phi} \right) \end{aligned}$$

Therefore we have

$$\begin{aligned} \frac{\xi + 2\phi}{2} \mp \eta &= s \\ \frac{\xi + 2\phi}{2} \mp \eta &= \eta \end{aligned}$$

We pick the parameterization $\phi = \phi + \xi$ and obtain

$$\begin{aligned} \frac{\phi + \phi}{2} \mp \eta &= s \\ \frac{\phi + \phi}{2} \mp \eta &= \eta \end{aligned}$$

Therefore we have

$n = \text{constant}$

MOAM 9/17/02

For example, $y'' + n^2 y = 0$ - Every point is an ordinary point. Every solution can be written as a convergent power series about any point. The radius of convergence $R = \infty$ for all these solutions.

5/6)

For example: $y'' + xy = 0$, Airy's equation

Chebyshev's Eqn: $(1-x^2)y'' - xy' + p^2 y = 0$, $-1 < x < 1$

where $p = \text{constant}$

it is known that $x=0$ is an ordinary point.

$$\Rightarrow \text{assume } y = \sum_{n=0}^{\infty} c_n x^n = c_0 + c_1 x + c_2 x^2 + \dots + c_n x^n + \dots$$

substitute into ODE

$$y'(x) = c_1 + 2c_2 x + \dots + n c_n x^{n-1} = \sum_{n=1}^{\infty} n c_n x^{n-1}$$

$$y''(x) = 2c_2 + \dots + n(n-1)c_n x^{n-2} = \sum_{n=2}^{\infty} n(n-1)c_n x^{n-2}$$

$$0 = (1-x^2)y'' - xy' + p^2 y$$

$$= (1-x^2) \sum_{n=2}^{\infty} n(n-1)c_n x^{n-2} - x \sum_{n=1}^{\infty} n c_n x^{n-1} + p^2 \sum_{n=0}^{\infty} c_n x^n$$

$$= \sum_{n=2}^{\infty} n(n-1)c_n x^{n-2} - \sum_{n=2}^{\infty} n(n-1)c_n x^n - \sum_{n=1}^{\infty} n c_n x^n + p^2 \sum_{n=0}^{\infty} c_n x^n$$

$$\begin{aligned} &\stackrel{\text{change}}{\downarrow} \quad \stackrel{\text{no change}}{\downarrow} \\ &= \sum_{n=0}^{\infty} (n+2)(n+1)c_{n+2} x^n - \sum_{n=0}^{\infty} (n+2)(n+1)c_n x^n - \sum_{n=0}^{\infty} n c_n x^n + p^2 \sum_{n=0}^{\infty} c_n x^n \end{aligned}$$

$$= \sum_{n=0}^{\infty} [(n+2)(n+1)c_{n+2} + (-n^2 + n + n + p^2)c_n] x^n$$

each power must vanish separately for ODE to be satisfied:

$$(n+2)(n+1)c_{n+2} + (p^2 - n^2)c_n = 0, n=0, 1, 2, \dots$$

$$\Rightarrow \boxed{c_{n+2} = \frac{(n^2 - p^2)c_n}{(n+2)(n+1)}} \quad \left\{ \begin{array}{l} \text{two-term recurrence formula} \end{array} \right.$$

Example 7.1, page 71

The isothermal equations of gas dynamics with momentum $m = \rho v$ are

$$\begin{aligned}\rho_t + m_x &= 0 \\ m_t + (m^2/\rho + a^2\rho)_x &= 0\end{aligned}$$

or $u_t + f(u)_x = 0$ where $u = u(\rho, m)$. The Jacobian matrix is

$$f'(u) = \begin{bmatrix} 0 & 1 \\ a^2 - m^2/\rho^2 & 2m/\rho \end{bmatrix}$$

Calculate eigenvalues:

$$\begin{aligned}\left| \begin{array}{cc} 0 - \lambda & 1 \\ a^2 - m^2/\rho^2 & 2m/\rho - \lambda \end{array} \right| = 0 &\rightarrow -\lambda \left(\frac{2m}{\rho} - \lambda \right) - a^2 + \frac{m^2}{\rho} = 0 \\ \rightarrow \lambda^2 - \frac{2m}{\rho}\lambda - a^2 + \frac{m^2}{\rho} = 0 &\rightarrow \lambda = \frac{2m}{2\rho} \pm \sqrt{\frac{4m^2}{\rho} + 4a^2 - \frac{4m^2}{\rho}} \rightarrow \lambda = \frac{m}{\rho} \pm a\end{aligned}$$

Calculate corresponding eigenvectors:

$$\begin{aligned}\lambda = \frac{m}{\rho} + a : \quad \begin{bmatrix} -\frac{m}{\rho} - a & 1 \\ a^2 - \frac{m^2}{\rho^2} & \frac{m}{\rho} - a \end{bmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0 &\rightarrow \begin{aligned} -\left(\frac{m}{\rho} + a\right)v_1 + v_2 &= 0 \\ \left(\frac{m}{\rho} + a\right)v_1 - v_2 &= 0 \end{aligned} \rightarrow v = \begin{pmatrix} 1 \\ \frac{m}{\rho} + a \end{pmatrix} \\ \lambda = \frac{m}{\rho} - a : \quad \begin{bmatrix} -\frac{m}{\rho} + a & 1 \\ a^2 - \frac{m^2}{\rho^2} & \frac{m}{\rho} + a \end{bmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0 &\rightarrow \begin{aligned} \left(-\frac{m}{\rho} + a\right)v_1 + v_2 &= 0 \\ \left(-\frac{m}{\rho} + a\right)v_1 + v_2 &= 0 \end{aligned} \rightarrow v = \begin{pmatrix} 1 \\ \frac{m}{\rho} - a \end{pmatrix}\end{aligned}$$

Fix a state \hat{u} and determine the set of states \tilde{u} that can be connected by a discontinuity. The Rankine-Hugoniot condition for the system is

$$f(\tilde{u}) - f(\hat{u}) = s(\tilde{u} - \hat{u}) \rightarrow (\tilde{m}^2/\tilde{\rho} + a^2\tilde{\rho}) - (\hat{m}^2/\hat{\rho} + a^2\hat{\rho}) = s(\tilde{m} - \hat{m})$$

This gives two equations in three unknowns $\tilde{\rho}$, \tilde{m} and s . Solve for \tilde{m} in terms of $\tilde{\rho}$:

$$\begin{aligned}\frac{\tilde{m}^2}{\tilde{\rho}} + a^2\tilde{\rho} - \frac{\hat{m}^2}{\hat{\rho}} - a^2\hat{\rho} &= \frac{(\tilde{m} - \hat{m})^2}{\tilde{\rho} - \hat{\rho}} \\ \frac{\tilde{m}^2}{\tilde{\rho}} - \frac{\hat{m}^2}{\hat{\rho} - \hat{\rho}} + \frac{2\tilde{m}\hat{m}}{\tilde{\rho} - \hat{\rho}} - \frac{\hat{m}^2}{\hat{\rho} - \hat{\rho}} + a^2(\tilde{\rho} - \hat{\rho}) - \frac{\hat{m}^2}{\hat{\rho}} &= 0 \\ -\tilde{m}^2\frac{\hat{\rho}}{\tilde{\rho}} + 2\tilde{m}\hat{m} - \hat{m}^2\frac{\tilde{\rho}}{\hat{\rho}} + a^2(\tilde{\rho} - \hat{\rho}) &= 0 \rightarrow \tilde{m}^2\frac{\hat{\rho}}{\tilde{\rho}} - 2\tilde{m}\hat{m} + \left(\hat{m}\frac{\tilde{\rho}}{\hat{\rho}} - a^2(\tilde{\rho} - \hat{\rho})\right) = 0 \\ \tilde{m} = \frac{2\hat{m}\tilde{\rho}}{2\hat{\rho}} \pm \frac{\tilde{\rho}}{2\hat{\rho}}\sqrt{4\hat{m}^2 - 4\frac{\tilde{\rho}}{\hat{\rho}}\hat{m}^2\frac{\hat{\rho}}{\tilde{\rho}} + 4\frac{\hat{\rho}}{\tilde{\rho}}a^2(\tilde{\rho} - \hat{\rho})^2} &\rightarrow \tilde{m} = \frac{\hat{m}\tilde{\rho}}{\hat{\rho}} \pm \frac{\tilde{\rho}}{\hat{\rho}}a(\tilde{\rho} - \hat{\rho})\sqrt{\frac{\hat{\rho}}{\tilde{\rho}}} \\ \tilde{m} = \frac{\hat{m}\tilde{\rho}}{\hat{\rho}} \pm a(\tilde{\rho} - \hat{\rho})\sqrt{\frac{\hat{\rho}}{\tilde{\rho}}} &\end{aligned}$$

Solve for s in terms of $\tilde{\rho}$:

$$\begin{aligned}\frac{(\hat{m} + s(\tilde{\rho} - \hat{\rho}))^2}{\tilde{\rho}} + a^2\tilde{\rho} - \frac{\hat{m}^2}{\hat{\rho}} - a^2\hat{\rho} &= s^2(\tilde{\rho} - \hat{\rho}) \\ \frac{\hat{m}^2}{\tilde{\rho}} + \frac{2\hat{m}s(\tilde{\rho} - \hat{\rho})}{\tilde{\rho}} + \frac{s^2(\tilde{\rho} - \hat{\rho})^2}{\tilde{\rho}} + a^2(\tilde{\rho} - \hat{\rho}) - \frac{\hat{m}^2}{\hat{\rho}} &= s^2(\tilde{\rho} - \hat{\rho}) \\ \frac{s^2(\tilde{\rho} - \hat{\rho})}{\tilde{\rho}} - s^2 + \frac{2\hat{m}}{\tilde{\rho}}s + a^2 - \frac{\hat{m}^2}{\hat{\rho}\tilde{\rho}} &= 0 \rightarrow \frac{s^2\hat{\rho}}{\tilde{\rho}} - \frac{2\hat{m}}{\tilde{\rho}}s + \left(\frac{\hat{m}^2}{\hat{\rho}\tilde{\rho}} - a^2\right) = 0 \\ s = \frac{2\hat{m}}{\tilde{\rho}}\frac{\tilde{\rho}}{2\hat{\rho}} \pm \frac{\tilde{\rho}}{2\hat{\rho}}\sqrt{\frac{4\hat{m}^2}{\tilde{\rho}^2} - \frac{4\hat{\rho}}{\tilde{\rho}}\left(\frac{\hat{m}^2}{\hat{\rho}\tilde{\rho}} - a^2\right)} &\rightarrow s = \frac{\hat{m}}{\hat{\rho}} \pm \frac{a\tilde{\rho}}{\hat{\rho}}\sqrt{\frac{\hat{\rho}}{\tilde{\rho}}} \rightarrow s = \frac{\hat{m}}{\hat{\rho}} \pm a\sqrt{\frac{\tilde{\rho}}{\hat{\rho}}}\end{aligned}$$

Normally take c_0 and c_1 as the arbitrary constants.

IF p is an integer, then one series terminates at c_p .

\Rightarrow these are called the Chebyshev polynomials.

Herron's Theorem :

American Mathematical Monthly 1989
824-827

IF the recurrence formula is of the form

$$c_{n+s} = f(n) c_n, n = 0, 1, 2, \dots, s > 0 \quad (s = \text{integer})$$

then the radius of convergence is

$$R = \left[\lim_{n \rightarrow \infty} |f(sn)| \right]^{-1/s}$$

In our case: $f(n) = \frac{n^2 - p^2}{(n+2)(n+1)}$ For any p

and $R = 1$.

This mirrors the general theory that

$$y'' + f(x)y' + g(x)y = 0$$

has two solutions which converge on the intersection of the intervals of $f(x)$ and $g(x)$

Exercise 7.1, page 73

Calculate the Hugoniot locus for the shallow water equations.

$$\left(\begin{array}{c} v \\ \varphi \end{array} \right)_t + \left(\begin{array}{c} v^2/2 + \varphi \\ v\varphi \end{array} \right)_x = 0 \quad \rightarrow \quad \left(\begin{array}{c} v \\ \varphi \end{array} \right)_t + \left[\begin{array}{cc} v & 1 \\ \varphi & v \end{array} \right] \left(\begin{array}{c} v \\ \varphi \end{array} \right)_x$$

The eigenvalues and corresponding eigenvectors are

$$\lambda_1 = v - \sqrt{\varphi} \quad r_1 = \left(\begin{array}{c} -\sqrt{\varphi} \\ 1 \end{array} \right)$$

$$\lambda_2 = v + \sqrt{\varphi} \quad r_2 = \left(\begin{array}{c} \sqrt{\varphi} \\ 1 \end{array} \right)$$

Fix a state $\hat{u} = \left(\begin{array}{c} \hat{v} \\ \hat{\varphi} \end{array} \right)$ and determine states $\tilde{u} = \left(\begin{array}{c} \tilde{v} \\ \tilde{\varphi} \end{array} \right)$ that can be connected by a discontinuity.

The Rankine-Hugoniot condition $f(\tilde{u}) - f(\hat{u}) = s(\tilde{u} - \hat{u})$ becomes

$$\begin{aligned} \left(\frac{\tilde{v}^2}{2} + \tilde{\varphi} \right) - \left(\frac{\hat{v}^2}{2} + \hat{\varphi} \right) &= s(\tilde{v} - \hat{v}) \\ \tilde{v}\tilde{\varphi} - \hat{v}\hat{\varphi} &= s(\tilde{\varphi} - \hat{\varphi}) \end{aligned}$$

Solve for s in terms of $\tilde{\varphi}$

$$\begin{aligned} \tilde{v} &= \frac{s(\tilde{\varphi} - \hat{\varphi}) + \hat{v}\hat{\varphi}}{\tilde{\varphi}} \quad \rightarrow \\ \frac{s^2(\tilde{\varphi} - \hat{\varphi})^2}{2\tilde{\varphi}^2} + \frac{2s(\tilde{\varphi} - \hat{\varphi})\hat{v}\hat{\varphi}}{2\varphi^2} + \frac{\hat{v}^2\hat{\varphi}^2}{2\tilde{\varphi}^2} + (\tilde{\varphi} - \hat{\varphi}) - \frac{\hat{v}^2}{2} &= \frac{s^2(\tilde{\varphi} - \hat{\varphi})}{\tilde{\varphi}} + \frac{s\hat{v}\hat{\varphi}}{\tilde{\varphi}} - s\hat{v} \\ \frac{s^2(\tilde{\varphi} - \hat{\varphi})}{\tilde{\varphi}^2} \left(\frac{\tilde{\varphi} - \hat{\varphi}}{2} - \tilde{\varphi} \right) + \frac{s\hat{v}(\tilde{\varphi} - \hat{\varphi})}{\varphi} \left(\frac{\hat{\varphi}}{\tilde{\varphi}} + 1 \right) + (\tilde{\varphi} - \hat{\varphi}) + \frac{\hat{v}^2}{2} \left(\frac{\hat{\varphi}^2 - \tilde{\varphi}^2}{\tilde{\varphi}^2} \right) &= 0 \\ \frac{s^2(\tilde{\varphi} - \hat{\varphi})(\tilde{\varphi} + \hat{\varphi})}{2\tilde{\varphi}^2} - \frac{s\hat{v}(\tilde{\varphi} - \hat{\varphi})(\tilde{\varphi} + \hat{\varphi})}{\varphi^2} - (\tilde{\varphi} - \hat{\varphi}) - \frac{\hat{v}^2(\hat{\varphi} - \tilde{\varphi})(\tilde{\varphi} + \hat{\varphi})}{2\tilde{\varphi}^2} &= 0 \\ s^2 - 2\hat{v}s - \frac{2\tilde{\varphi}^2}{\tilde{\varphi} + \hat{\varphi}} + \hat{v}^2 &= 0 \quad \rightarrow \quad s = \hat{v} \pm \frac{1}{2} \sqrt{4\hat{v}^2 - 4\hat{v}^2 + 4 \left(\frac{2\tilde{\varphi}^2}{\tilde{\varphi} + \hat{\varphi}} \right)} \\ &\rightarrow \quad s = \hat{v} \pm \tilde{\varphi} \sqrt{\frac{2}{\tilde{\varphi} + \hat{\varphi}}} \end{aligned}$$

Solve for \tilde{v} in terms of $\tilde{\varphi}$

$$\begin{aligned} s &= \frac{\tilde{v}\tilde{\varphi} - \hat{v}\hat{\varphi}}{\tilde{\varphi} - \hat{\varphi}} \quad \rightarrow \\ \frac{\tilde{v}^2}{2} - \frac{\hat{v}^2}{2} + \tilde{\varphi} - \hat{\varphi} &= \frac{(\tilde{v} - \hat{v})(\tilde{v}\tilde{\varphi} - \hat{v}\hat{\varphi})}{\tilde{\varphi} - \hat{\varphi}} \\ \frac{\tilde{v}^2}{2}(\tilde{\varphi} - \hat{\varphi}) - \frac{\hat{v}^2}{2}(\tilde{\varphi} - \hat{\varphi}) + (\tilde{\varphi} - \hat{\varphi})^2 &= \tilde{v}^2\tilde{\varphi} - \tilde{v}\hat{v}\tilde{\varphi} - \tilde{v}\hat{v}\hat{\varphi} + \hat{v}^2\hat{\varphi} \\ -\frac{\hat{v}^2}{2}(\tilde{\varphi} + \hat{\varphi}) + \tilde{v}\hat{v}(\tilde{\varphi} + \hat{\varphi}) - \frac{\hat{v}^2}{2}(\tilde{\varphi} + \hat{\varphi}) + (\tilde{\varphi} - \hat{\varphi})^2 &= 0 \\ \tilde{v}^2 - 2\tilde{v}\hat{v} + \hat{v}^2 - \frac{(\tilde{\varphi} - \hat{\varphi})^2}{\tilde{\varphi} + \hat{\varphi}} &= 0 \quad \rightarrow \quad \tilde{v} = \hat{v} \pm \frac{1}{2} \sqrt{4\hat{v}^2 - 4 \left(\hat{v}^2 - \frac{(\tilde{\varphi} - \hat{\varphi})^2}{\tilde{\varphi} + \hat{\varphi}} \right)} \\ &\rightarrow \quad \tilde{v} = \hat{v} \pm (\tilde{\varphi} - \hat{\varphi}) \sqrt{\frac{2}{\tilde{\varphi} + \hat{\varphi}}} \end{aligned}$$

Topics

Eigenvectors & Eigenvalues - finite dimensional

Eigenvalue Problems for ODEs

Special Functions - defined by diff eqns

Keener { Green's Functions } Hildebrand (bookstore)

{ Calculus of Variations } special function: Gamma Function (App B in Cockran)
- defined by an integral

$y'' + f(x)y' + g(x)y = 0$ (standard form - determines if pt is ordinary or singular)

power series approach

- When f and g are analytic at a point, this is an ordinary point.

Last time $(1-x^2)y'' - xy' + p^2y = 0$, $p = \text{constant}$

$$y'' - \frac{x}{1-x^2}y' + \frac{p^2}{1-x^2}y = 0$$

hence f and g are analytic on $-1 < x < 1$

If either f or g fails to be analytic at $x = x_0$

then x_0 is a singular point.

- In the example, $x = \pm 1$ are singular points of the Chebyshev equation.

• $y'' + \lambda y$ has no singular points on $-\infty < x < \infty$

Def: A point x_0 is termed a regular singular point of the diff eqn if there exists an interval $|x - x_0| < R$ in which both $(x - x_0)f(x)$ and $(x - x_0)^2g(x)$ have converging power series representations.

Theorem

Example: $y'' + \frac{x}{x^2-1}y' - \frac{p^2}{x^2-1}y = 0$

$$\rightarrow y'' + \frac{x}{(x-1)(x+1)}y' + \frac{p^2}{(x-1)(x+1)}y = 0$$

$$(x-1)P(x) = \frac{(x-1)x}{(x-1)(x+1)} = \frac{x}{x+1} = P(x)$$

$$(x-1)^2 Q(x) = (x-1)^2 \left[\frac{-p^2}{(x-1)(x+1)} \right] = \frac{-p^2(x-1)}{x+1} = Q(x)$$

Both power series have convergent power series about $x=1$.

$$P(x) = P(1) + P'(1)(x-1) + \dots$$

$$Q(x) = Q(1) + Q'(1)(x-1) + \dots$$

Theorem 2: Let x_0 be a regular singular point. In this case, \exists at least one solution which has the

representation

$$y(x) = \sum_{k=0}^{\infty} c_k (x-x_0)^{k+d_0}$$

$$= (x-x_0)^{d_0} \sum_{k=0}^{\infty} c_k (x-x_0)^k$$

converges for $0 < |x-x_0| < R$

The constant d is a root of the

initial equation

$$d^2 + d(a_0 - 1) + b_0 = 0,$$

$$a(x) = \sum_{k=0}^{\infty} a_k (x-x_0)^k, \quad b(x) = \sum_{k=0}^{\infty} b_k (x-x_0)^k$$

Simple prototype - Euler-Cauchy Equation

$$x^2 y'' + a_0 x y' + b_0 y = 0, \quad x > 0$$

Try $y = x^m$, $y' = mx^{m-1}$, $y'' = m(m-1)x^{m-2}$

$$x^2 (m(m-1)x^{m-2}) + a_0 x (mx^{m-1}) + b_0 x^m = 0$$

$$x^m (m(m-1) + a_0 m + b_0) = 0$$

$$\Rightarrow m^2 + (a_0 - 1)m + b_0 = 0$$

In general, $y = \sum_{k=0}^{\infty} c_k (x-x_0)^{k+\alpha}$ the coefficients

are expressed in terms of the a_k and b_k .

If the roots are complex, or if both are real and do not differ by an integer, then there are two solutions of the assumed form.

These two solutions are independent.

The exceptional case is a repeated root $\alpha = \alpha_1, \alpha_1$ or $\alpha_2 = \alpha_1$. The second solution may be shown to be of the form:

$$y_2(x) = B y_1(x) \ln(x-x_0) + \sum_{k=0}^{\infty} c_k (x-x_0)^{k+\alpha_2}$$

Many of the special functions solve ODE's with regular singular points.

Example :

Cochran in chpt 3 solves the hypergeometric eqn.

$$x(1-x)y'' + (c - (a+b+1)x)y' - aby = 0$$

a, b, c constants.

First general solution is called ${}_2F_1(a, b, c, x)$

$${}_2F_1(a, b; c; x) = \frac{\Gamma(c)}{\Gamma(a)\Gamma(b)} \sum_{k=0}^{\infty} \frac{\Gamma(a+k)\Gamma(b+k)}{\Gamma(c+k)} \frac{x^k}{k!}, \quad |x| < 1$$

about $x=0$

- Assume $y = \sum_{k=0}^{\infty} A_k x^{k+\alpha}$, singular point at $x=0$

$$y' = \sum_{k=0}^{\infty} (\alpha+k) A_k x^{\alpha+k-1}$$

$$y'' = \sum_{k=0}^{\infty} (\alpha+k)(\alpha+k-1) A_k x^{\alpha+k-2}$$

$$0 = x(1-x)y'' + (c - (a+b+1)x)y' - aby$$

$$= x(1-x) \sum_{k=0}^{\infty} (\alpha+k)(\alpha+k-1) A_k x^{\alpha+k-2} + [c - (a+b+1)x] \sum_{k=0}^{\infty} (\alpha+k) A_k x^{\alpha+k-1} - ab \sum_{k=0}^{\infty} A_k x^{\alpha+k}$$

$$= \sum_{k=0}^{\infty} (\alpha+k)(\alpha+k-1) A_k (x^{\alpha+k-1} - x^{\alpha+k}) + \sum_{k=0}^{\infty} (\alpha+k) A_k (cx^{\alpha+k-1} - (a+b+1)x^{\alpha+k}) - ab \sum_{k=0}^{\infty} A_k x^{\alpha+k}$$

• leading term

$$k=0 : x^{\alpha-1}$$

$$: \boxed{\alpha(\alpha-1) A_0 + \alpha A_0 c = 0 \quad \text{Initial Eqn, } A_0 \neq 0}$$

$$\alpha^2 - \alpha + dc = 0 \Rightarrow \alpha = 0, \alpha = 1-c$$

• next term, $k=1 \rightarrow x^\alpha$

3/4

$$L_0 + d = 0$$

$$\begin{aligned} 0 &= \sum_{k=0}^{\infty} k(k-1) A_k (x^{k-1} - x^k) + \sum_{k=0}^{\infty} k A_k (c x^{k-1} - (a+b+1)x^k) - ab \sum_{k=0}^{\infty} A_k x^k \\ &= \sum_{k=0}^{\infty} (k(k-1) + kc) A_k x^{k-1} - \sum_{k=0}^{\infty} [k(k-1) + k(a+b+1) + ab] A_k x^k \\ &\Rightarrow \sum_{k=0}^{\infty} [(k+1)(k+c) A_{k+1} - (k(k-1) + k(a+b+1) + ab) A_k] x^k \end{aligned}$$

Require the coefficients of x^k to vanish for each k :

$$(k+1)(k+c) A_{k+1} - (k-a)(a+b) A_k = 0 \quad (\text{recursive formula})$$

$$\left| \frac{A_{k+1}}{A_k} \right| = \left| \frac{(a+k)(b+k)}{(c+k)(k+1)} \right| \rightarrow 1 \text{ as } k \rightarrow \infty$$

This series converges for $|x| < 1$.

What happens at $x = \pm 1$?

Weierstrass Convergence criteria

Suppose $\sum c_k z^k$ has a unit radius of convergence.

$$\text{Let } \frac{c_{k+1}}{c_k} = 1 - \frac{\beta}{k} + \frac{B(k)}{k^\lambda}$$

where β is a complex constant, $\lambda > 1$, $B(k)$ is bounded as $k \rightarrow \infty$. Then for points on the circle of convergence $|z| = 1$, the series will:

- ① converge absolutely if $\operatorname{Re}(\beta) > 1$,
- ② diverge if $\operatorname{Re}(\beta) \leq 0$;
- ③ converge but not absolutely if $0 < \operatorname{Re}(\beta) \leq 1$ except at $z = 1$ where it will diverge.

Simple Example: $\sum \frac{z^k}{k}$

Converges everywhere on the unit circle except at $z = 1$

$$\frac{c_{k+1}}{c_k} = \frac{k+1}{k} = 1 + \frac{1}{k}$$

Back to hypergeometric series

$$\begin{aligned}\frac{A_{k+1}}{A_k} &= \frac{k^2 + (a+b)k + ab}{k^2 + (c+1)k + c} \\ &= 1 + \frac{(a+b-c-1)k + ab - c}{k^2 + (c+1)k + c} \\ &= 1 + \frac{a+b-c-1}{k} + \frac{B(k)}{k^2} \quad \boxed{B = c+1-a-b}\end{aligned}$$

(1) Series converges on $|z| = 1$ if $\operatorname{Re}(c-a-b) > 0$

(2) Series diverges if $\operatorname{Re}(c-a-b) \leq -1$

(3) converges conditionally if $0 < \operatorname{Re}(c-a-b+1) \leq 1$

$$A_{k+1} = \frac{(a+k)(b+k)}{(c+k)(k+1)} A_k, \quad k \geq 0 \quad - \text{RECURRANCE RELATION}$$

• Gamma function is a generalization of the factorial function.

It can be defined by $\Gamma(a+1) = a \Gamma(a)$ for $\operatorname{Re}(a) > 0$

$$A_k = \frac{(a+k-1)(b+k-1)}{(c+k-1)k} A_{k-1}$$

Substitute

$$\Rightarrow A_k = A_0 \frac{a(a+1) \cdots (a+k-1) b(b+1) \cdots (b+k-1)}{c(c+1) \cdots c(c+k-1) \cdot 1 \cdot 2 \cdots k}$$

$$A_k = \frac{A_0 \Gamma(a+k) \Gamma(b+k) \Gamma(c)}{\Gamma(a) \Gamma(b) \Gamma(c+k) \cdot k!}$$

$$\Rightarrow {}_2F_1(a; b; c; x) = \frac{\Gamma(c)}{\Gamma(a)\Gamma(b)} \sum_{k=0}^{\infty} \frac{\Gamma(a+k)\Gamma(b+k)}{\Gamma(c+k)} \frac{x^k}{k!}$$

Euler's formula

$$= \frac{\Gamma(c)}{\Gamma(a)\Gamma(b)} \int_0^1 (1-xt)^{-b} t^{a-1} (1-t)^{c-a-1} dt$$

since $(1-xt)^{-b} = \sum_{k=0}^{\infty} \frac{(-xt)^k}{k!} \frac{\Gamma(-b+1)}{\Gamma(-b-k+1)}$

and $\int_0^1 t^{z-1} (1-t)^{w-1} dt = \frac{\Gamma(z)\Gamma(w)}{\Gamma(z+w)}$

~~REVIEW OF HYPERGEOMETRIC FUNCTIONS~~

Confluent hypergeometric eqn

$$xy'' + (c-x)y' - ay = 0$$

Sometimes called Kummer's eqn

$$M(a; c; x) = {}_1F_1(a; c; x) = \frac{\Gamma(c)}{\Gamma(a)} \sum_{k=0}^{\infty} \frac{\Gamma(a+k)}{\Gamma(c+k)} \frac{x^k}{k!}$$

The second solution to the hypergeometric eqn:

$$\text{write } y = x^{1-c} w$$

substitute into hypergeometric eqn

$$\Rightarrow x(1-x)w'' + [(z-c)-(a+b-2c+3)x] w' - (a-c+3)(b-c+1)w = 0$$

$$w = {}_2F_1(a-c+1, b-c+1; 2-c; x)$$

$$y = {}_2F_1(a; b; c; x), \quad c \neq 1$$

■ Cochran treats the Hypergeometric Diff Eqn

$$x(1-x)y'' + [c - (a+b+1)x]y' - aby = 0$$

- Many important eqns can be transformed to or from the hypergeometric equation.

■ Chebyshev's Eqn

$$(1-x^2)y'' - xy' + p^2y = 0, \quad -1 < x < 1, \quad p = \text{constant}$$

We found the solution in series about $x=0$

It may also be transformed to the hypergeometric DE.
Let the independent variable be $z = \frac{1-x}{2}$

$$\frac{dy}{dx} = \frac{dy}{dz} \frac{dz}{dx} = -\frac{1}{2} \frac{dy}{dz}$$

$$\frac{d^2y}{dx^2} = \left(-\frac{1}{2}\right)^2 \frac{d^2y}{dz^2} = \frac{1}{4} \frac{d^2y}{dz^2}$$

$$\Rightarrow \left(1 - (1-2z)^2\right) \frac{1}{4} \frac{d^2y}{dz^2} - (1-2z)\left(-\frac{1}{2} \frac{dy}{dz}\right)' + p^2y(z) = 0$$

$$\frac{2z(2-2z)}{4} y''(z) + \left(\frac{1}{2} - z\right) y'(z) + p^2y(z) = 0$$

$$z(1-z)y''(z) + \left(\frac{1}{2} - z\right) y'(z) + p^2y(z) = 0$$

hypergeometric eqn with: $c = \frac{1}{2}$, $a+b=0$, $-ab=p^2$, $x=z$

take $a=-p$, $b=p$

$$\Rightarrow y(z) = {}_2F_1(-p; p; \frac{1}{2}; z) = T_p(z)$$

$${}_2F_1(a, b; c; x) = \frac{\Gamma(c)}{\Gamma(a)\Gamma(b)} \sum_{k=0}^{\infty} \frac{\Gamma(a+k)\Gamma(b+k)}{\Gamma(c+k)} \frac{x^k}{k!}$$

$${}_2F_1(-p; p; \frac{1}{2}; z) = T_p(z) = \frac{\Gamma(\frac{1}{2})}{\Gamma(-p)\Gamma(p)} \sum_{k=0}^{\infty} \frac{\Gamma(-p+k)\Gamma(p+k)}{\Gamma(\frac{1}{2}+k)} \frac{z^k}{k!}$$

◆ IF p is an integer, the series terminates..

$$\Rightarrow T_p(x) = \cancel{\frac{\Gamma(\frac{1}{2})}{\Gamma(-p)\Gamma(p)}} \sum_{k=0}^{\infty} \cancel{k!}$$

$${}_2F_1(-p, p; \frac{1}{2}; \frac{1-x}{2}) = T_p(x) = \frac{\Gamma(\frac{1}{2})}{\Gamma(-p)\Gamma(p)} \sum_{k=0}^{\infty} \frac{\Gamma(-p+k)\Gamma(p+k)}{\Gamma(\frac{1}{2}+k)} \left(\frac{1-x}{2}\right)^k \cdot \frac{1}{k!}$$

at $x = 1$, this becomes Finite

what happens at $x = -1$? Does the series converge, or converge absolutely?

$$\text{Notice } A_k = \frac{\Gamma(-p+k)\Gamma(p+k)}{\Gamma(\frac{1}{2}+k)} \cdot \frac{1}{k!}$$

$$\frac{A_{k+1}}{A_k} = \frac{\cancel{\Gamma(\frac{1}{2}+k+1)(k+1)!}}{\cancel{\Gamma(-p+k+1)\Gamma}} \cdot \frac{\Gamma(-p+k+1)\Gamma(p+k+1)}{\Gamma(\frac{1}{2}+k+1)(k+1)!} \cdot \frac{\Gamma(\frac{1}{2}+k) k!}{\Gamma(-p+k)\Gamma(p+k)}$$

From definition of gamma function, $\Gamma(a+1) = a\Gamma(a)$

$$\Rightarrow \frac{A_{k+1}}{A_k} = \frac{(-p+k)\cancel{\Gamma(p+k)}(p+k)\cancel{\Gamma(p+k)}}{\left(\frac{1}{2}+k\right)\Gamma\left(\frac{1}{2}+k\right)(k+1)} \cdot \frac{\Gamma\left(\frac{1}{2}+k\right)}{\Gamma\left(-p+k\right)\Gamma(p+k)}$$

$$= \frac{k^2 - p^2}{(k+1)\left(\frac{1}{2}+k\right)} \rightarrow 1 \text{ as } k \rightarrow \infty \quad \left(\begin{array}{l} \text{ratio test inconclusive} \\ \text{if } \lim = 1 \end{array} \right)$$

Use the Weierstrass criterion since that is inconclusive

$$\frac{A_{k+1}}{A_k} = \frac{\cancel{k^2 - p^2}}{\cancel{k^2 + \frac{3}{2}k + \frac{1}{2}}} = 1 - \frac{\frac{3}{2}}{k} + \frac{B(k)}{k^2} \quad \begin{array}{l} \text{B}(k) \text{ is bounded} \\ \text{as } k \rightarrow \infty \end{array}$$

Long Division

$\beta = \frac{3}{2} > 1 \Rightarrow$ Converges
Absolutely

(2/3)

Direct Treatment of Chebyshev's Eqn

$$(1-x^2)y'' - xy' + p^2y = 0, \quad -1 < x < 1$$

expand about $x=1$, set $t = x-1$ (transformation)
 $(x=1$ is a singular point) \downarrow
 $y'(t) = y'(x)$

$$\Rightarrow (1-(1+t)^2)y''(t) - (t+1)y'(t) + p^2y(t) = 0$$

$$-t(t+2)y''(t) - (t+1)y'(t) + p^2y(t) = 0$$

$$t(t+2)y''(t) + (t+1)y'(t) - p^2y(t) = 0$$

◆ Frobenius:

assume $y = \sum_{n=0}^{\infty} c_n t^{n+\alpha}$ where α is to be determined

$$y'(t) = \sum_{n=0}^{\infty} c_n(n+\alpha) t^{n+\alpha-1}, \quad y''(t) = \sum_{n=0}^{\infty} c_n(n+\alpha)(n+\alpha-1) t^{n+\alpha-2}$$

◆ substitute into Diff Eqn

$$0 = \sum_{n=0}^{\infty} (t^2 + 2t) t^{n+\alpha-2} (n+\alpha)(n+\alpha-1) c_n + \sum_{n=0}^{\infty} (t+1) t^{n+\alpha-1} (n+\alpha) c_n - \sum_{n=0}^{\infty} p^2 t^{n+\alpha} c_n$$

$$n=0 : t^{\alpha-1} : 2\alpha(\alpha-1)c_0 + \alpha c_0 = 0 \Rightarrow c_0(2\alpha^2 - \alpha) = 0 \Rightarrow c_0\alpha(2\alpha-1) = 0$$

we have $\alpha = 0, 1/2$

$$\hookrightarrow 0 = \sum_{n=0}^{\infty} c_n t^{n+\alpha} ((n+\alpha)^2 - p^2) + \sum_{n=0}^{\infty} (n+\alpha)(2n+2\alpha-1) c_n t^{n+\alpha-1} = 0$$

$$\alpha=0 : c_{n+1} [(n-1)^2 - p^2] + n(2n-1) c_n = 0$$

$$\Rightarrow c_{n+1} = \frac{-(n+p)(n-p)}{(n+1)(2n+1)} c_n$$

$$\left| \frac{c_{n+1}}{c_n} \right| \rightarrow \frac{1}{2} \text{ as } n \rightarrow \infty \Rightarrow \text{Radius of convergence} = 2$$

◆ Bessel Functions : arise when there is a circular or cylindrical geometry

motivation: vibrating circular drum

displacement: $v(r, \theta, t)$

$$\text{wave eqn: } \frac{\partial^2 v}{\partial t^2} = c^2 \nabla^2 v = c^2 \left(\frac{\partial^2 v}{\partial r^2} + \frac{1}{r} \frac{\partial v}{\partial r} + \frac{1}{r^2} \frac{\partial^2 v}{\partial \theta^2} \right)$$

$$\text{Ansatz: } v(r, \theta, t) = \varphi(r, \theta) h(t) \Rightarrow \frac{\partial^2 h}{\partial t^2} = -\lambda c^2 h$$

$$\varphi(r, \theta) = f(r) g(\theta)$$

$$\text{Reduced to: } \frac{d^2 g}{d\theta^2} = -\lambda g$$

$$\frac{d^2 F}{dr^2} + \frac{1}{r} \frac{dF}{dr} + \left(\lambda - \frac{n}{r^2} \right) F = 0$$

$$r F''(r) + F'(r) + \left(\lambda r - \frac{n}{r} \right) F = 0$$

$$r \frac{d}{dr} \left(r \frac{dF}{dr} \right) + (\lambda r^2 - m^2) F = 0, \quad m^2 = n$$

general solution of $r^2 F''(r) + r F'(r) + (\lambda r^2 - m^2) F = 0$

$$\text{is } F(r) = c_1 J_m(\sqrt{\lambda} r) + c_2 Y_m(\sqrt{\lambda} r)$$

◆ Let z be the independent variable, $z = \sqrt{\lambda} r$

$$\Rightarrow \frac{dF}{dr} = \frac{dF}{dz} \frac{dz}{dr} = \sqrt{\lambda} F'(z)$$

$$\frac{d^2 F}{dr^2} = \lambda F''(z)$$

$$\Rightarrow \cancel{r F''(r) + F'(r)} \frac{z^2 \lambda F''(z)}{\lambda} + \frac{z}{\sqrt{\lambda}} \sqrt{\lambda} F'(z) + (z^2 - m^2) F(z) = 0$$

$$\Rightarrow \boxed{z^2 F''(z) + z F'(z) + (z^2 - m^2) F(z) = 0} \quad \begin{matrix} \text{Standard Form of} \\ \text{Bessel's Eqn} \end{matrix}$$

◆ Note, $z=0$ is a ^{regular} singular point

$$F''(z) + \frac{1}{z} F'(z) + \left(1 - \frac{m^2}{z^2}\right) F(z) = 0$$

◆ Assume $F(z) = \sum_{n=0}^{\infty} c_n z^{n+\alpha}$, determine α (Frobenius Method)

Previously, $x^2 y''(x) + x a(x) y'(x) + b(x) y(x) = 0$

if $x_0 = 0$ is a regular singular point

$$a(x) = \sum_{n=0}^{\infty} a_n x^n, \quad b(x) = \sum_{n=0}^{\infty} b_n x^n$$

◆ For Bessel's equation ◆ Initial Eqn: $\lambda^2 + \lambda(a_0 - 1) + b_0 = 0$

$$a_0 = -1, \quad b_0 = -m^2 \Rightarrow \lambda^2 = m^2 \Rightarrow \lambda = \pm m$$

◆ Good reference: Bessel Functions by G.N. Watson

For $\lambda = m$: $J_m(z) = \sum_{k=0}^{\infty} \frac{(-1)^k (z/2)^{2k+m}}{k! (k+m)!}$ (assumes $m = \text{integer}$)

~~if m is not an integer~~

For $\lambda = -m$: $J_{-m}(z) = \sum_{k=m}^{\infty} \frac{(-1)^k (\frac{z}{2})^{2k-m}}{k! (k-m)!}$

Since m is an integer: let $n = k - m \Rightarrow k = n + m$

$$J_{-m}(z) = \sum_{n=0}^{\infty} \frac{(-1)^{n+m} (z/2)^{2n+m}}{n! (n+m)!} = (-1)^m J_m(z)$$

Therefore linearly dependent (assuming m is an integer).

$$J_m^{(m)}(0) = \frac{1}{2^m} \quad (m^{\text{th}} \text{ derivative})$$

$$J_0(z) = 1 - \frac{z^2}{2!} + \frac{z^4}{2^2 \cdot 4^2} - \frac{z^6}{2^2 \cdot 4^2 \cdot 6^2} + \dots$$

$$J_0'(z) = -J_1(z)$$

There exist many such relationships between the integer order Bessel Functions of consecutive order.

The particular choice of the constants is actually dictated by integral representations of the Bessel functions.

$$J_n(x) = \frac{1}{\pi} \int_0^\pi \cos(x \sin \theta - n\theta) d\theta \quad \text{where } n \text{ is an integer}$$

Special Functions - mainly defined by differential equations. Many are also defined by integrals.

The Gamma Function

$$\Gamma(x) = \int_0^\infty t^{x-1} e^{-t} dt, \quad x > 0$$

Complex form is sometimes useful

$$\Gamma(1) = \int_0^\infty e^{-t} dt = 1$$

$$\Gamma(2) = \int_0^\infty t e^{-t} dt = [t e^{-t}]_0^\infty + \int_0^\infty e^{-t} dt = 1$$

$$\Gamma(3) = 2$$

$$\Gamma(n) = (n-1)!, \quad n=1, 2, 3, \dots$$

Use $\Gamma(x+1) = x \Gamma(x)$ as a way of extending
the definition

Bessel Function

$$J_m(z) = \sum_{k=0}^{\infty} \frac{(-1)^k \left(\frac{z}{2}\right)^{2k+m}}{k! (m+k)!}, \quad m \text{ is an integer}$$

$$J_v(z) = \sum_{k=0}^{\infty} \frac{(-1)^k \left(\frac{z}{2}\right)^{2k+v}}{k! \Gamma(v+k+1)}, \quad v \text{ is a real number}$$

we say that

$$J_m(z) = (-1)^m J_{-m}(z)$$

Then a 2nd linearly independent solution is Y_m

$$\text{Define } Y_v(z) = \frac{J_v(z) \cos(\pi v) - J_{-v}(z)}{\sin(\pi v)}$$

As $v \rightarrow m$ an integer,

$$Y_m(z) \rightarrow \frac{J_m(z) \cos(\pi m) - J_{-m}(z)}{\sin(\pi m)} = \frac{J_m(z) (-1)^m - J_{-m}(z)}{0} = \frac{0}{0}$$

use L'Hopital's rule ← Indeterminate form ←

$$Y_m(z) = \lim_{v \rightarrow m} \frac{\frac{d}{dv} (J_v(z) \cos(\pi z) - J_{-v}(z))}{\pi \cos(\pi m)}$$

The derivative of $\Gamma(z)$ is needed to evaluate this expression

$$\Gamma(x) = \int_0^\infty t^{x-1} e^{-t} dt, x > 0$$

$$= \int_0^\infty e^{(x-1)\ln t} e^{-t} dt.$$

$$\Rightarrow \Gamma'(x) = \int_0^\infty \ln t e^{(x-1)\ln t} e^{-t} dt = \int_0^\infty t^{x-1} \ln t e^{-t} dt$$

Therefore the expression involves natural logarithms;
it is given in Cochran Chpt 3.

◆ $x^2 R(x) y'' + x P(x) y' + Q(x) y = 0 \rightarrow x=0$ is a regular singular point

First solution $y_1(x)$

Second solution $y_2(x)$

$$y_2(x) = y_1(x) \int \frac{e^{-\int \frac{P(x)}{x R(x)} dx}}{(y_1(x))^2} dx$$

This is advantageous if only a few terms of a series expansion of the solution are needed.

◆ Possibilities: Bessel's equation may be solved on a membrane



$$\frac{\partial^2 u}{\partial t^2} = c^2 \left(\frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} \right)$$

Bounded solutions are expected physically at $r=0$. The solutions involving $J_m(\sqrt{\lambda}r)$ are not needed. They are unbounded as $r \rightarrow 0$.

The introduction of terms involving $\ln r$ are acceptable and necessary to compute the solution.

Back to the separated form of Bessel's eqn:

$$(r F'(r))' + \left(\lambda r - \frac{m^2}{r}\right) F = 0 \quad *$$

Boundary condition for clamped edges: $u(a, \theta, t) = 0$

$\Rightarrow f(a) = 0$ (is a possibility)

Due to homogeneity of *, $f=0$ is a possible solution, and so $F \neq 0$ has eigenfunctions, $F_n(r)$, $n=1, 2, \dots$

$F(r) = J_m(\sqrt{\lambda_n}r)^{\alpha}$ (we exclude $J_m(\sqrt{\lambda_n}r)$ - unbounded at $r=0$)
 in general we would need the 2-linearly independent solutions, but not in this case

The eigenvalues are given by $\text{Im}(\sqrt{\lambda_n}r) = 0$

the zeros of $\text{Im}(z)$ are given by $\text{Im } z_n = j_{m,n}$

$$\Rightarrow \sqrt{\lambda_n}r = j_{m,n} \Rightarrow \boxed{\lambda_n = \frac{j_{m,n}^2}{\alpha^2} \text{ eigenvalues}}$$

If the solution of a problem is desired in which θ is absent, axisymmetric, then $m=0$

IF θ is absent : $\frac{\partial^2 v}{\partial t^2} = c^2 \left(\frac{\partial^2 v}{\partial r^2} + \frac{1}{r} \frac{\partial v}{\partial r} \right)$ ASIDE

$$\text{let } v(r,t) = F(r)g(t)$$

$$Fg'' = c^2 \left(F''g + \frac{1}{r} F'g \right)$$

$$\frac{g''}{c^2 g} = \frac{F'' + \frac{1}{r} F'}{F} = -\lambda \Rightarrow \boxed{F'' + \frac{1}{r} F' + \lambda F = 0}$$

hence m is absent

$$(r F'(r))' + \left(\lambda r - \frac{m^2}{r} \right) F = 0$$

Let λ_1 and λ_2 be two different eigenvalues,

then solutions will have $F_1 = \text{Im}(\sqrt{\lambda_1}r)$ and $F_2 = \text{Im}(\sqrt{\lambda_2}r)$ as corresponding eigenvalues

$$\Rightarrow (r F'_1)' + \left(\lambda_1 r - \frac{m^2}{r} \right) F_1 = 0 \quad ①$$

$$(r F'_2)' + \left(\lambda_2 r - \frac{m^2}{r} \right) F_2 = 0 \quad ②$$

The eigenvalues are real. Suppose they are different.

$$\text{Choose inner product } \langle F, g \rangle = \int_0^a r F(r) g(r) dr$$

where the weight function r is based on coeff of λ_1, λ_2

Multiply (1) by \bar{F}_2 , (2) by \bar{F}_1 and subtract, and integrate

$$(r F_1')' \bar{F}_2 + (\lambda_1 r - \frac{m^2}{r}) F_1 \bar{F}_2 = 0$$

$$(r F_2')' \bar{F}_1 + (\lambda_2 r - \frac{m^2}{r}) \bar{F}_2 F_1 = 0$$

$$\Rightarrow \int_0^a [(r F_1')' \bar{F}_2 - (r F_2')' \bar{F}_1] dr + (\lambda_1 - \lambda_2) \int_0^a r F_1 \bar{F}_2 dr = 0$$

$$[r F_1' \bar{F}_2]_0^a - [r F_2' \bar{F}_1]_0^a + \int_0^a r F_1' \bar{F}_2 - r F_2' \bar{F}_1 dr + (\lambda_1 - \lambda_2) \int_0^a r F_1 \bar{F}_2 dr = 0$$

$$\text{Need } \lim_{r \rightarrow 0^+} [r(F_1'(r) \bar{F}_2(r) - F_2'(r) \bar{F}_1(r))] = 0$$

$$\text{so that } (\lambda_1 - \lambda_2) \int_0^a r F_1 \bar{F}_2 dr = 0$$

$$\lambda_1 \neq \lambda_2 \text{ by assumption then } \int_0^a r F_1 \bar{F}_2 dr = 0 = \langle F_1, F_2 \rangle$$

This is an example of a singular Sturm-Liouville problem $(p(x)y')' + (\lambda R(x) - q(x))y = 0$, $a < x < b$

where $p(x)$ has a zero at the end point.

Expand a function in a series of Bessel Functions

$$F(r) = \sum_{n=1}^{\infty} c_n J_m(\sqrt{\lambda_n} r), \quad 0 < r < a$$

$$J_m(\sqrt{\lambda_n} a) = 0$$

$$\text{To find } c_n, \int_0^a F(r) r J_n(\sqrt{\lambda_n} r) dr = \int_0^a \sum_{n=1}^{\infty} c_n J_m(\sqrt{\lambda_n} r) r J_n(\sqrt{\lambda_n} r) dr$$

$$= c_p \int_0^a J_m(\sqrt{\lambda_p} r) J_m(\sqrt{\lambda_p} r) r dr$$

$$= c_p \int_0^a r J_m^2(\sqrt{\lambda_p} r) dr$$

Find $\int_0^a r J_m^2(\sqrt{\lambda}r) dr$ from the ODE

~~$$r^2 J_m'' + r J_m' + (\lambda r^2 - m^2) J_m = 0$$~~

for $J_m(\sqrt{\lambda}r)$

~~$$\text{and } r^2 J_m'' + r J_m' + (nr^2 - m^2) J_m = 0$$~~

for $J_m(nr)$

$$r^2 J_m'' + r J_m' + (nr^2 - m^2) J_m = 0 \quad \text{For } J_m(nr)$$

$$\text{and } r^2 J_m'' + r J_m' + (nr^2 - m^2) J_m = 0 \quad \text{for } J_m(nr)$$

For $\int_0^a J_m^2(\sqrt{\lambda}r) dr$, set $x = \frac{r}{a}$, $\rightarrow a \int_0^1 J_m^2(\sqrt{\lambda}ax) dx$

so we're considering $\int_0^1 x J_m^2(nx) dx$ where $n = \sqrt{\lambda}a$

$$\lim_{n \rightarrow \infty} \frac{n J_m(n) J_m'(n) - n J_m(n) J_m''(n)}{n^2}$$

L'Hopital's rule necessary

$$= 2n \int_0^1 x J_m^2(nx) dx$$

$$2 \int_0^1 x J_m^2$$

Normalization of Eigenfunctions

$$(P\varphi')' + (\lambda r - q)\varphi = 0 \quad \text{eigenfunction } \varphi, \text{ eigenvalue } \lambda$$

$$(P\psi')' + (\nu r - q)\psi = 0 \quad \text{eigenfunction } \psi, \text{ eigenvalue } \nu$$

both for $a < x < b$

$$\int_a^b ((P\varphi')'\psi - (P\psi')'\varphi) dx + (\lambda - \nu) \int_a^b \psi r \varphi dx = 0$$

integrate by parts, boundary terms remain

$$\frac{[P(\varphi'\psi - \varphi\psi')]_a^b}{\nu - \lambda} = \int_a^b r \psi \varphi dx$$

Let $\nu \rightarrow \lambda$, have to apply l'Hopital's rule
since φ, ψ solutions to differential equation, then
assume differential

For $\varphi(r, \lambda), \psi(r, \lambda)$ assume $\varphi \rightarrow \varphi$

Invoking continuity and differentiability of the solutions

with the parameter

$$\lim_{\nu \rightarrow \lambda} \frac{\partial}{\partial \nu} \left[P(b) \left(\varphi'(b, \lambda) \psi(b, \nu) - \varphi(b, \lambda) \psi'(b, \nu) \right) - P(a) \left(\varphi'(a, \lambda) \psi(a, \nu) - \varphi(a, \lambda) \psi'(a, \nu) \right) \right] = \lim_{\nu \rightarrow \lambda} \int_a^b r(x) \varphi(x, \lambda) \psi(x, \nu) dx$$

$$\Rightarrow P(b) \varphi'(b, \lambda) \frac{\partial \psi(b, \lambda)}{\partial \lambda} - P(b) \frac{\partial \varphi'(b, \lambda)}{\partial \lambda} \psi'(b, \lambda) + P(a) \varphi'(a, \lambda) \frac{\partial \psi(a, \lambda)}{\partial \lambda}$$

$$+ P(a) \varphi(a, \lambda) \frac{\partial \varphi'(a, \lambda)}{\partial \lambda} = \int_a^b r(x) [\varphi(x, \lambda)]^2 dx$$

◆ Apply appropriate BC in x :

For example: consider BC $\varphi(a) = \varphi(b) = 0$

$$\Rightarrow \int_a^b r(x)(\varphi(x, \lambda))^2 dx = p(b)\varphi'(b, \lambda) \frac{\partial \varphi}{\partial \lambda}(b, \lambda) - p(a)\varphi'(a, \lambda) \frac{\partial \varphi}{\partial \lambda}(a, \lambda)$$

Further evaluation depends on your actual knowledge of the behavior of the solutions.

Bessel Functions:

Bessel's equation: $xy'' + xy' + (x^2 - \nu^2)y = 0$

Liouville transformation: let $y(x) = v(x)^{-\nu_2}$

$$\text{then find: } v'' + \left(1 - \frac{\nu^2 - \nu_2}{x^2}\right)v = 0$$

Notice that if $\nu^2 = \nu_2$ then $v'' + v = 0$

$$\Rightarrow v = c_1 \cos x + c_2 \sin x$$

$$\Rightarrow y(x) = \frac{c_1 \cos x}{\sqrt{x}} + \frac{c_2 \sin x}{\sqrt{x}}, \text{ general solution}$$

This is a member of the family of spherical Bessel functions

$$\nu = n + \frac{1}{2}, n = 0, \pm 1, \pm 2, \dots$$

See Handbook of Mathematical Functions by Abramowitz & Stegan

The Liouville transformation is valuable in approximating

$$J_\nu(x)$$

Modified Bessel Functions

They do not oscillate

Start with Bessel's equation. Set $z = ix \Rightarrow x^2 = -z^2$
or $x = -iz$

call $w(z) = y(ix)$

$$\frac{dw}{dz} = \frac{dy}{dx} \frac{dx}{dz} = -i \frac{dy}{dx} \Rightarrow \frac{dy}{dx} = i \frac{dw}{dz}$$

$$x^2 y'' + xy' + (x^2 - v^2) y = 0$$

$$-z^2 \left(i^2 \frac{d^2 w}{dz^2} \right) + (-iz) i \frac{dw}{dz} - (z^2 + v^2) w = 0$$

$$\Rightarrow z^2 w''(z) + zw'(z) - (z^2 + v^2) w = 0$$

This problem occurs in heat conduction in a cylinder.
It arises naturally through separation of variables.

Basic pair: $I_v(z)$, $K_v(z)$ where

$$I_v(z) = \left(\frac{1}{2}z\right)^v \sum_{k=0}^{\infty} \frac{\left(\frac{1}{2}z^2\right)^k}{k! \Gamma(v+k+1)}$$

$$K_v(z) = \frac{1}{2} \pi \left[\frac{I_{-v}(z) - I_v(z)}{\sin(\pi v)} \right]$$

If v is an integer, K_v has natural logarithms

Green's Functions

Kreysler Section 4.2

Hildebrand chpt 3

Motivation: used in solving non-homogeneous problems

$$(p(x)u'(x))' + (\lambda r(x) - q(x))u = f(x), \text{ with boundary problems}$$

Example: $u''(x) = f(x)$, $0 < x < L$, $u(0) = u(L) = 0$

solve by integration $(p(x)=1, r(x)=q(x)=0)$

$$\Rightarrow u'(x) = \int f(x) dx + c_1$$

$$u'(x) = \int_0^x f(t) dt + c_1$$

To find the answer and to apply BCs, integrate again

$$\Rightarrow u(x) = \int_0^x \int_0^y f(t) dt dy + c_1 x + c_2$$

$$u(0) = 0 \Rightarrow \int_0^0 f(t) dt dy + c_1(0) + c_2 = 0 \Rightarrow c_2 = 0$$

$$\Rightarrow u(x) = \int_0^x \int_0^y f(t) dt dy + c_1 x$$

$$u(L) = \int_0^L \int_0^y f(t) dt dy + c_1 L = 0 \Rightarrow c_1 = -\frac{1}{L} \int_0^L \int_0^y f(t) dt dy$$

$$\Rightarrow \boxed{u(x) = \int_0^x \int_0^y f(t) dt dy - \frac{x}{L} \int_0^L \int_0^y f(t) dt dy}$$

The solution clearly satisfies the boundary conditions

why is this example beneficial to explain
Green's Functions

Rewrite the solution using integration by parts

$$\text{Name: } F(y) = \int_0^y f(t) dt \quad \rightarrow \quad F'(y) = f(y)$$

$$\begin{aligned} \text{Then } u(x) &= \int_0^x F(y) dy - \frac{x}{L} \int_0^L F(y) dy \\ &= \left[y F(y) \right]_0^x - \int_0^x y F'(y) dy - \frac{x}{L} \left[\left[y F(y) \right]_0^L - \int_0^L y F'(y) dy \right] \\ &= x F(x) - \int_0^x y F(y) dy - \frac{x}{L} \left[L F(L) - \int_0^L y F'(y) dy \right] \\ &= x \int_0^x F(y) dy - \int_0^x y F(y) dy - \frac{x}{L} \left[L \int_0^L F(y) dy - \int_0^L y F(y) dy \right] \\ &= \int_0^x (x-y) F(y) dy - x \int_0^L F(y) dy + \frac{x}{L} \int_0^L y F(y) dy \\ &= \int_0^x (x-y) F(y) dy + \int_0^L \left(\frac{xy - xL}{L} \right) F(y) dy \\ &= \int_0^L g(x,y) F(y) dy \\ &= u(x) \end{aligned}$$

$$\begin{aligned} \text{where } g(x,y) &= \begin{cases} x-y + \frac{xy - xL}{L}, & 0 < y < x \\ \frac{xy - xL}{L}, & x < y < L \end{cases} \\ &= \begin{cases} \frac{y}{L}(x-L), & 0 < y < x \\ \frac{x}{L}(y-L), & x < y < L \end{cases} \end{aligned}$$

Krener in section 4.2 outlines "every thing"

$$L u = a_2(x) u'' + a_1(x) u' + a_0(x) u = f(x), \text{ with BC's}$$

$$u(x) = \int_a^b g(x,y) f(y) dy$$

so $g(x,y)$ behaves as an "inverse"

$$\text{symbolically, } L u = L \left(\int_a^b g(x,y) f(y) dy \right) = \int_a^b L_x g(x,y) f(y) dy$$

where L_x denotes differentiation wrt x .

$$L_x g = a_2(x) \frac{\partial^2 g}{\partial x^2} + a_1(x) \frac{\partial g}{\partial x} + a_0(x) g$$

$$\Rightarrow \int_a^b L_x g(x,y) f(y) dy = f(x)$$

then $L_x g(x,y)$ behaves like a delta function

$$L_x g(x,y) = \delta(x-y)$$

$$\text{so that } \int_a^b \delta(x-y) f(y) dy = f(x)$$

Back to the example,

$$g(x,y) = \begin{cases} \frac{y}{L}(x-L), & 0 < y < x \\ \frac{x}{L}(y-L), & x < y < L \end{cases}$$

$$g_x(x,y) = \begin{cases} \frac{y}{L}, & 0 < y < x \\ \frac{y}{L}-L, & x < y < L \end{cases}$$

$$\text{Notice } \lim_{x \uparrow y} g(x,y) = \frac{y^2 - yL}{L}, \quad \lim_{x \downarrow y} g(x,y) = \frac{y^2 - yL}{L}$$

therefore $g(x,y)$ is ~~weakly~~ continuous in both arguments

However, g_x has discontinuity at $x=y$

$$\lim_{x \uparrow y} g_x(x,y) = \frac{y}{L} - L, \quad \lim_{x \downarrow y} g_x(x,y) = \frac{y}{L}$$

- ◆ Therefore, in this example, $g(x,y)$ has a jump discontinuity in its first derivative.

$$\left[g_x(x,y) \right]_{x=y^-}^{x=y^+} = \frac{y}{L} - \left(\frac{y}{L} - 1 \right) = +1$$

- ◆ Notice additionally, in this example, $g(x,y)$ is symmetric:

$$g(x,y) = g(y,x)$$

- ◆ The text has a picture of this Green's function for $0 < x < L$ ($L=1$), on page 146, but there is a small typo: It should be written as the plot of $g(x,y)$ for $L=2$. (a question of negatives.)

Variation of Parameters to derive Green's Functions

$$L_v = a_2(x)v'' + a_1(x)v' + a_0(x)v = F(x)$$

Assume v_1 and v_2 are known solutions of the homogeneous equation. Now look for another solution of the form: $v_p(x) = c_1(x)v_1(x) + c_2(x)v_2(x)$

$$\text{Find that } c_1'(x)v_1(x) + c_2'(x)v_2(x) = 0$$

$$c_1'(x)v_1'(x) + c_2'(x)v_2'(x) = \frac{F(x)}{a_2(x)}$$

$$c_1'(x) = \frac{\begin{vmatrix} 0 & v_2(x) \\ \frac{F(x)}{a_2(x)} & v_2'(x) \end{vmatrix}}{\begin{vmatrix} v_1(x) & v_2(x) \\ v_1'(x) & v_2'(x) \end{vmatrix}} = \frac{-\frac{F(x)}{a_2(x)}v_2(x)}{v_1(x)v_2'(x) - v_1'(x)v_2(x)}$$

$$\text{Similarly, } c_2'(x) = \frac{\frac{F(x)}{a_2(x)}v_1(x)}{v_1(x)v_2'(x) - v_1'(x)v_2(x)}$$

\Rightarrow particular solution \Rightarrow

$$v(x) = -v_1(x) \int \frac{F(x) v_2(x)}{a_2(x) W(x)} dx + v_2(x) \int \frac{F(x) v_1(x)}{a_2(x) W(x)} dx$$

$$\text{where } W(x) = v_1(x) v_2'(x) - v_1'(x) v_2(x)$$

\blacktriangleleft Let us assume separated or regular BCs:

$$B_1 v(a) = d_0 v(a) + x_1 v'(a) = 0$$

$$B_2 v(b) = B_2 v(b) + \beta_1 v'(b) = 0$$

If $\lambda = 0$ is not an eigenvalue, there is no eigenfunction that is a solution to $Lv = 0$.

$$B_1 v(a), B_2 v(b) = 0$$

$$\text{choose } B_1 v_1(a) = 0, B_2 v_2(b) = 0$$

for linearly independent v_1 and v_2

$$v_1 L v_2 - v_2 L v_1 = \frac{d}{dx} a_2(x) W(v_1, v_2) = 0$$

$$\Rightarrow a_2(x) W(v_1, v_2) = \text{constant}$$

$$\begin{aligned} \Rightarrow v(x) &= -v_1(x) \int_b^x \frac{F(y) v_2(y)}{a_2(y) W(y)} dy + v_2(x) \int_a^x \frac{F(y) v_1(y)}{a_2(y) W(y)} dy \\ &= \int_a^b g(x, y) F(y) dy \end{aligned}$$

$$\Rightarrow g(x, y) = \begin{cases} \frac{v_1(x) v_2(y)}{a_2(y) W(y)}, & x < y < b, \\ \frac{v_1(y) v_2(x)}{a_2(y) W(y)}, & a < y < x \end{cases}$$

symmetric: $g(x, y) = g(y, x)$

MOAM
10/8/02
154

Additional reference book now on reserve:

Principles & Techniques of Applied Mathematics
by Bernard Friedman
(available in Dover paperback),

Green's Functions

$$(pu')' + (\lambda r(x) - q(x))u = f(x) \quad , \quad a < x < b$$

λ is not an eigenvalue

boundary conditions: $B_1 u(a) = 0$, $B_2 u(b) = 0$ (separated BCs)

developed in detail in Sec 4.2 Keener

we found that

$$u(x) = \int_a^b g(x,y) F(y) dy$$

$$\text{with } g(x,y) = \begin{cases} \frac{v_1(x)v_2(y)}{pw} & , x < y \\ \frac{v_1(y)v_2(x)}{pw} & , x > y \end{cases}$$

$$\text{where } W(v_1, v_2) = v_1 v_2' - v_1' v_2 \quad , \quad L v_1 = 0 \quad , \quad L v_2 = 0$$

$$\text{notice the symmetry: } g(x,y) = g(y,x)$$

If $Lu = F$ then we can think that

$$u(x) = \int_a^b g(x,y) F(y) dy = L^{-1} F(x)$$

Example : Keener pg 156

$$L\psi = \psi'' + k^2\psi, \quad k \neq 0, \quad \psi(0) = \psi(1) = 0$$

Show that $\psi(x,y) = \begin{cases} \frac{\sin kx \sin(k(y-1))}{k \sin k}, & 0 \leq x < y < 1 \\ \frac{\sin ky \sin(k(x-1))}{k \sin k}, & 0 \leq y < x < 1 \end{cases}$

General solution to $L\psi = 0, 0 < x < 1$ is $\psi = c_1 \cos kx + c_2 \sin kx$

$$\psi_1(0) = 0 \Rightarrow B_1 \psi_1(0) = 0, \quad \psi_1 = \sin(kx)$$

$$B_2 \psi_2(1) = \psi_2(1) = 0 \Rightarrow \psi_2 = \sin(k(x-1))$$

We assume that k is not an eigenvalue so ψ_1 and ψ_2 are independent.

$$W = \begin{vmatrix} \sin kx & \sin(k(x-1)) \\ k \cos kx & k \cos(k(x-1)) \end{vmatrix} = k \sin kx \cos(k(x-1)) - k \cos kx \sin(k(x-1)) = k \sin(kx - k(x-1)) = k \sin k$$

Notice :

$$\phi_x = \begin{cases} \frac{\cos kx \sin(k(y-1))}{\sin k} & x < y \\ \frac{\sin ky \cos(k(x-1))}{\sin k} & y < x \end{cases}$$

As expected,

$$\left. g_x \right|_{x=y^+} = \frac{\sin ky \cos(k(y-1)) - \cos ky \sin(k(y-1))}{\sin k} = \frac{\sin(ky - k(y-1))}{\sin k}$$

$$= \frac{\sin k}{\sin k} = 1$$

Alternatively, by trig identity

$$g(x,y) = \frac{\cos[k(1-|x-y|)] - \cos[k(1+x+y)]}{2k \sin k}$$

Example: Non-separated BCs

$$Lu = u'' = f(x), \quad 0 < x < 1$$

$$2u(0) + u(1) = 0$$

$$2u'(0) + u'(1) = 0$$

From Assignment #2, we know that $\lambda = 0$ is NOT eigenvalue of $u'' + \lambda u = 0$, with these boundary conditions.

Since $\lambda = 0$ is NOT an eigenvalue, we expect L^{-1} to exist.

Theorem 4.2 (Keener)

For L order n ,

① $L_x g = 0$, For $x \neq y$

② $g(x, y)$ is $n-2$ continuous in x at $x = y$

③
$$\left. \frac{\partial^{n-1} g(x, y)}{\partial x^{n-1}} \right|_{x=y^-}^{x=y^+} = -\frac{1}{a_n(y)}$$

④ g must satisfy the BCs in x

In the example, $g_{xx} = 0$ For $x \neq y$

$$\Rightarrow g(x) = \begin{cases} a_1 + a_2 x, & x < y \\ b_1 + b_2 x, & x > y \end{cases}$$

where $g(0, y) = a_1$, $g(1, y) = b_1 + b_2$ } four conditions to find
 $g_x(0, y) = a_2$, $g_x(1, y) = b_2$ } the four unknowns

note

$g(x, y)$ is continuous at $x = y$

$$a_1 + a_2 y = b_1 + b_2 y$$

jump:
$$g_x(x, y) \Big|_{x=y^-}^{x=y^+} = b_2 - a_2 = 1$$

BC: $2a_1 + b_1 + b_2 = 0$

$$2a_2 + b_2 = 0$$

subtract \Rightarrow

$$\begin{aligned} 3a_2 &= 1 \\ a_2 &= \frac{1}{3} \end{aligned}$$

$$b_2 = \frac{2}{3}, \quad a_1 = \frac{-2}{9} + \frac{1}{3}, \quad b_1 = \frac{9}{9} - \frac{2}{3} - \frac{1}{3}$$

$$g(x,y) = \begin{cases} -\frac{2}{9} + \frac{y}{3} - \frac{x}{3}, & x \leq y \\ -\frac{2}{9} - \frac{2}{3}y + \frac{2}{3}x, & x > y \end{cases}$$

or equivalently

$$g(x,y) = -\frac{2}{9} + (y-x)H(y-x) - \frac{2}{3}(y-x)$$

Use Keener pg 173 # 11

$$(xv')' - \frac{n^2}{x}v' + xv = F(x), \quad 0 < x < 1$$

$$v(0) = \text{finite}, \quad v(1) = 0$$

- For general λ this could be solved in terms of Bessel Functions, assuming λ is not an eigenvalue

- Convert this to an integral equation of the form

$$y = \lambda \int_0^1 k(x,y) v(y) dy + F(y)$$

$$\text{Solve } L v = 0 \Rightarrow (xv')' + \frac{n^2}{x}v = 0 \rightarrow \text{Laplace transform}$$

$$x'' + n^2 \left(\frac{n^2}{x}\right)v = 0, \quad n > 0 \rightarrow \boxed{v_1 = x^n, \quad v_2 = x^n - x^{-n}}$$

satisfies LFT BC

satisfies BC at right

Same recipe for separated BCs

$$g(x,y) = \begin{cases} \frac{v_1(x)v_2(y)}{PW}, & x < y \\ \frac{v_1(y)v_2(x)}{bW}, & y < x \end{cases}$$

$$\text{where } W = \boxed{\frac{x^n}{n x^{n-1}} \times \frac{x^n - x^{-n}}{n x^{n-1} + n x^{-n-1}}} = \frac{x^{n+1} - x^{-n-1}}{x^{n+1} + x^{-n-1}} (n - n^{-1}) =$$

$$\text{When } W = \boxed{\frac{x^n - x^{-n-1}}{n x^{n-1} + n x^{-n-1}}} = n x^{2n-1} + n x^{-1} - n x^{2n-1} + n x^{-1} = \frac{2n}{x}$$

$$\Rightarrow \boxed{g(x,y) = \frac{1}{2n} x^n (y^n - y^{-n}), \quad 0 < x < y \leq 1, \quad g(x,y) = g(y,x)}$$

Green's Functions - Hildebrand

$$Ly + \Phi(x) = 0, \quad \Phi(x) = \Phi(x, y(x))$$

$$\text{where } L = \frac{d}{dx} \left(P \frac{dy}{dx} \right) + q$$

homogeneous BCs $\alpha y(x) + \beta y'(x) = 0$ for $x \in [a, b]$.

Determine a Green's function G given by

$$G(x) = \begin{cases} G_1(x), & x < \xi \\ G_2(x), & x > \xi \end{cases}$$

with the following four properties:

$$\textcircled{1} \quad L G_1 = 0 \quad \text{for } x < \xi$$

$$L G_2 = 0 \quad \text{for } x > \xi$$

$$\textcircled{2} \quad G_1 \text{ satisfies BC at } x = a$$

$$G_2 \text{ satisfies BC at } x = b$$

$$\textcircled{3} \quad G_1(\xi) = G_2(\xi) \quad \text{- continuity at } x = \xi$$

$$\textcircled{4} \quad G_2'(\xi) - G_1'(\xi) = \frac{-L}{P(\xi)} \quad (\text{jump discontinuity in derivative})$$

where $p(x)$ is the coefficient of the 2nd order derivative of L

Then the solution is given by:

$$y(x) = \int_a^b G(x, \xi) \Phi(\xi) d\xi$$

Let $y = u(x)$ be a non-trivial solution to $Lv = 0$ with $Lu(a) + \beta u'(a) = 0$ and let $y = v(x)$ be a non-trivial solution to $Lv = 0$, $\alpha v(b) + \beta v'(b) = 0$.

Then $G_1 = c_1 u(x)$ and $G_2 = c_2 v(x)$

$$\Rightarrow G = \begin{cases} c_1 u(x), & x < \xi \\ c_2 v(x), & x > \xi \end{cases}$$

From continuity at $x = \xi$: $c_2 v(\xi) - c_1 u(\xi) = 0 \quad (1)$

From jump in derivative at ξ : $c_2 v'(\xi) - c_1 u'(\xi) = \frac{-1}{p(\xi)} \quad (2)$

This system of solution possesses a unique solution

if $W[u(\xi), v(\xi)] \neq 0 \Rightarrow \begin{vmatrix} u(\xi) & v(\xi) \\ u'(\xi) & v'(\xi) \end{vmatrix} = u(\xi)v'(\xi) - u'(\xi)v(\xi) \neq 0$

Notice

$$Lv = 0 \Rightarrow (pv')' + qv = 0$$

$$Lu = 0 \Rightarrow (pu')' + qu = 0$$

$$\begin{aligned} vL_u - uLv &= v(pu')' + \cancel{yqv} - u(pv')' - \cancel{yqu} \\ &= vp'u' + vpv'' - up'u' - upv'' + (pu'v' - pv'u') \\ &= [p(uv' - v'u')]' = 0 \end{aligned}$$

$$\Rightarrow p(uv' - v'u') = A, \text{ } A \text{ is constant}$$

$$\boxed{uv' - v'u' = \frac{A}{p}} \quad (3)$$

In ① solve for c_2 : $c_2 = \frac{c_1 v(\xi)}{v(\xi)}$

substitute into ② :

$$\frac{c_1}{v(\xi)} v'(\xi) - c_1 v'(\xi) = \frac{-1}{p(\xi)}$$

$$\Rightarrow v(\xi) v'(\xi) - v'(\xi) v(\xi) = \frac{-v(\xi)}{c_1 p(\xi)}$$

From this and ③ we have

$$c_1 = -\frac{v(\xi)}{A} \quad \text{and so} \quad c_2 = -\frac{v(\xi)}{A}$$

$$\Rightarrow G = \begin{cases} -\frac{1}{A} v(x) v(\xi), & x < \xi \\ -\frac{1}{A} v(\xi) v(x), & x > \xi \end{cases}$$

Note if $A=0$ then v and v' are linearly independent.

Keener, Section 4.2 #2

$$v''(x) = f(x), v(0) = 0, v'(1) = v(1)$$

$$G(x,y) = \begin{cases} ax+b, & x < y \\ cx+d, & x > y \end{cases}$$

- BCs: $v(0) = 0 \rightarrow \boxed{b=0}$, $v'(1) = v(1) \rightarrow a = c + d \rightarrow \boxed{d=0}$
- continuity at $x=y$: $ay = cy \rightarrow a=c$

$$\Rightarrow G(x,y) = \begin{cases} ax, & x < y \\ ax, & x > y \end{cases}$$

- jump in derivative: $\left. \frac{dG}{dx} \right|_{y^-}^{y^+} = a - a = 0 \neq 1$

Green's Function does not exist!!

Note: Wronskian: $\begin{vmatrix} ax+b & cx+d \\ a & c \end{vmatrix} = acx + cd - acx - ad = d(c-a)$

From BC, $d=0$ therefore $|W(g_1(x), g_2(x))| = 0$ and so $g_1(x), g_2(x)$ linearly dependent

Keener, Example pg 145

$$\text{Let } v \equiv v''(x) = F(x), v(0) = v(1) = 0$$

$$G(x,y) = \begin{cases} g_1(x), & x \leq y \\ g_2(x), & x > y \end{cases} \quad \text{where } Lg_1 = 0, Lg_2 = 0$$

$$\Rightarrow G(x,y) = \begin{cases} ax+b, & x \leq y \\ cx+d, & x > y \end{cases}$$

$$\underline{\text{BCs}}: g_1(0) = g_2(1) = 0 \Rightarrow b=0, c=-d$$

$$\Rightarrow G(x,y) = \begin{cases} ax, & x \leq y \\ cx - c, & x > y \end{cases}$$

$$\underline{\text{jump in derivative}}: c-a = f \rightarrow a = c-1$$

$$G(x,y) = \begin{cases} (c-1)x, & x \leq y \\ (x-1)c, & x > y \end{cases}$$

$$\underline{\text{continuity}}: (c-1)y = (y-1)c \rightarrow cy - y = cy - c \rightarrow c = y$$

$$\Rightarrow \boxed{G(x,y) = \begin{cases} x(y-1), & x \leq y < 1 \\ y(x-1), & 0 < y \leq x \end{cases}}$$

BCs: $g_1(0) = g_2(1) = 0$ ✓
 continuity: $y(y-1) = y(y-1)$ ✓
 derivative: $y - (y-1) = 1$ ✓

$$H(x) = \begin{cases} 1, & x > 0 \\ 0, & x \leq 0 \end{cases}, \quad H(y-x) = \begin{cases} 1, & y > x \\ 0, & y \leq x \end{cases} = \begin{cases} 1, & x < y < 1 \\ 0, & 0 \leq y \leq x \end{cases}$$

$$\begin{aligned} G(x,y) &= (y-x)H(y-x) + y(x-1) = \begin{cases} y-x + xy - y^2, & x < y < 1 \\ 0 + y(x-1), & 0 \leq y \leq x \end{cases} \\ &= \begin{cases} x(y-1), & x < y < 1 \\ y(x-1), & 0 < y \leq x \end{cases} \end{aligned}$$

$$\Rightarrow \boxed{G(x,y) = (y-x)H(y-x) + y(x-1)}$$

Keener Section 4, 2 #1

$$v'' = f(x) \quad v(0) = 0 \quad v'(1) = 0$$

Method ①

$$v'(x) = \int_0^x F(y) dy + c_1, \quad v'(1) = 0 \Rightarrow c_1 = - \int_0^1 F(y) dy$$

$$v'(x) = \int_0^x F(y) dy - \int_0^1 F(y) dy$$

$$v(x) = \int_0^x \int_0^y f(s) ds - x \int_0^1 F(y) dy + c_2, \quad v(0) = 0 \Rightarrow c_2 = 0$$

$$\text{Let } \int_0^y f(s) ds = R(y) \rightarrow R'(y) = f(y)$$

$$\rightarrow v(x) = \int_0^x R(y) dy - x \int_0^1 F(y) dy = y R(x) \Big|_0^x - \int_0^x R'(y) y dy - x \int_0^1 F(y) dy$$

$$v(x) = x R(x) - \int_0^x y F(y) dy - x \int_0^1 F(y) dy = \int_0^x x F(y) dy - \int_0^x y F(y) dy - x \int_0^1 F(y) dy$$

$$v(x) = -x \int_x^0 f(y) dy - x \int_0^1 f(y) dy - \int_0^x y F(y) dy$$

$$v(x) = -x \int_x^0 f(y) dy - \int_0^x y F(y) dy = \int_0^1 g(x, y) f(y) dy$$

$$g(x, y) = \begin{cases} -y, & 0 < y < x \\ -x, & x < y < 1 \end{cases}$$

Method ②

$$v''(x) = 0, \quad v(0) = 0 \rightarrow v'(x) = a_1, \quad v(x) = a_1 x + a_2$$

$$v''(x) = 0, \quad v'(1) = 0 \rightarrow v'(x) = b_1, \quad v(x) = b_1 x + b_2$$

$$G = \begin{cases} c_1 v(x), & x < \xi \\ c_2 v(x), & x > \xi \end{cases} \quad \begin{array}{l} \text{From continuity } c_2 v(\xi) = c_1 v(\xi) \\ \text{From jump in derivatives: } c_2 v'(\xi) - c_1 v'(\xi) \end{array}$$

$$\begin{array}{l} \text{From BCs: } v(0) = 0 \Rightarrow v(x) = a_1 x, \quad v'(1) = 0 \Rightarrow v(x) = b_2 \end{array}$$

$$W = \begin{vmatrix} v(x) & v(x) \\ v'(x) & v'(x) \end{vmatrix} = \begin{vmatrix} a_1 x & b_2 \\ a_1 & 0 \end{vmatrix} = -a_1 b_2 \quad G = \begin{cases} \frac{-1}{a_1 b_2} a_1 x b_2, & x < \xi \\ \frac{-1}{a_1 b_2} a_1 \xi b_2, & x > \xi \end{cases} \Rightarrow G = \begin{cases} -x, & 0 < x < \xi \\ -\xi, & \xi < x < 1 \end{cases}$$

Kreysig Section 4.2 #2

Non-Separated Boundary Conditions

(problem done in class)

$$L_0 \equiv u'' = f(x), \quad 0 < x < 1$$

$$\begin{aligned} 2u(0) + u(1) &= 0 \\ 2u'(0) + u'(1) &= 0 \end{aligned} \quad (\text{It is known that } \lambda \neq 0, \text{ therefore a Green's function } G.)$$

$$\text{Let } G(x, y) = \begin{cases} g_1(x), & x < y \\ g_2(x), & x > y \end{cases}$$

$$\text{where } Lg_1(x) = 0, Lg_2(x) = 0 \Rightarrow g_1(x) = ax + b, g_2(x) = cx + d$$

$$\Rightarrow G(x, y) = \begin{cases} ax + b, & x < y \\ cx + d, & x > y \end{cases}$$

- continuity at $x = y$: $ay + b = cy + d$ ①

- jump in derivative at $x = y$: $c - a = 1$ ②

- BCs: $2b + c + d = 0$ ③
 $2a + c = 0$ ④

$$\begin{array}{l} \text{④} \quad c + 2a = 0 \rightarrow 3c = 2 \rightarrow c = \frac{2}{3}, a = -\frac{1}{3} \\ \text{②} \quad c - a = 1 \end{array}$$

$$\begin{array}{l} \text{③} \quad 2b + d = -\frac{2}{3} \\ \text{⑤} \quad b - d = y\left(\frac{2}{3} + \frac{1}{3}\right) \end{array} \rightarrow 3b = y - \frac{2}{3} \rightarrow \boxed{b = \frac{y}{3} - \frac{2}{9}, d = -\frac{2}{3}y - \frac{2}{9}}$$

$$\Rightarrow G = \begin{cases} -\frac{x}{3} + \frac{y}{3} - \frac{2}{9}, & x < y < 1 \\ \frac{2x}{3} - \frac{2y}{3} - \frac{2}{9}, & 0 < x < y \end{cases}$$

$$\text{BCs: } \frac{2y}{3} - \frac{2}{9} + \frac{2}{3} - \frac{2}{3} - \frac{2}{9} = \frac{2}{3} - \frac{6}{9} = 0$$

$$\text{diff: } \frac{2}{3} - \left(-\frac{1}{3}\right) = 1$$

$$\text{cont: } -\frac{2}{9} = -\frac{2}{9}$$

$$\boxed{G(x, y) = (y-x)H(y-x) + \frac{2}{3}(x-y) - \frac{2}{9}}$$

$$\Downarrow \begin{cases} y-x + \frac{2}{3}x - \frac{2}{3}y - \frac{2}{9} \\ 0 + \frac{2}{3}x - \frac{2}{3}y - \frac{2}{9} \end{cases} = \begin{cases} \frac{y}{3} - \frac{x}{3} - \frac{2}{9}, & x < y < 1 \\ \frac{2}{3}x - \frac{2}{3}y - \frac{2}{9}, & 0 < y < x \end{cases}$$

Green
Modified ~~Blended~~ Functions, Keener Example
"Generalized"

page 159

4/4

personal notes

$$Lu = u'' , \quad u'(0) = 0$$

$$u'(1) = 0$$

Null space spanned by $\phi_0 = 1$.

$$L g_j(x, y) = -w(y) \sum_{i=1}^K \psi_i(x) \psi_i(y) , \quad x \neq y$$

$$\Rightarrow L g_j(x, y) = -1$$

$$\Rightarrow g'' = -1 , \quad g'(0) = 0 , \quad g'(1) = 0$$

$$g(x, y) = \begin{cases} a_1 + a_2 x - \frac{1}{2} x^2 , & x < y \\ b_1 + b_2 x - \frac{1}{2} x^2 , & x > y \end{cases}$$

- continuity at $x=y$: $a_1 + a_2 y = b_1 + b_2 y$

- jump-discontinuity in derivative: $\left. \frac{dg}{dx} \right|_{x=y^-}^{x=y^+} = b_2 - y - (a_2 - y) = b_2 - a_2 = 1$

• BC

$$g'(0) = 0 \Rightarrow a_2 = 0$$

$$g'(1) = 0 \Rightarrow b_2 = 1$$

- From continuity: $a_1 = b_1 + y$

$$\Rightarrow g(x, y) = \begin{cases} b_1 + y - \frac{1}{2} x^2 , & x < y \\ b_1 + x - \frac{1}{2} x^2 , & x > y \end{cases}$$

- solve for b_1 by requirement that $\int_0^y g(x, y) dx = 0$

$$\int_0^y b_1 + y - \frac{1}{2} x^2 dx + \int_y^1 b_1 + x - \frac{1}{2} x^2 dx = \frac{y^2}{2} + b_1 + \frac{1}{3} = 0 \Rightarrow b_1 = -\frac{y^2}{2} - \frac{1}{3}$$

$$g(x, y) = -\frac{1}{3} - \left(\frac{y^2}{2} + \frac{x^2}{2} \right) + \begin{cases} y , & 0 \leq x < y \\ x , & y < x \leq 1 \end{cases}$$

Chpt 14 Green's Function

14.1 Boundary Value Problems for ODEs

- linear, homogeneous self-adjoint differential operator

$$Lu = pu'' + p'u' - qu , \quad x_0 \leq x \leq x_1 , \quad p > 0$$

- associated non-homogeneous diff eq

$$Lu = -\phi(x)$$

- we desire a solution of the form

$$u(x) = \int_{x_0}^{x_1} K(x, \xi) \phi(\xi) d\xi$$

where $K(x, \xi)$ is called the Influence Function of Green's Function.

$K(x, \xi)$ satisfies the BCs at x_0 and x_1 , from which it follows that $u(x)$ will satisfy those BCs.

$K(x, \xi)$ satisfies $LK(x, \xi) = 0 , \quad x \neq \xi$

$K(x, \xi)$ must satisfy the following requirements

1) $K(x, \xi)$ is continuous

2) $K(x, \xi)$ satisfies BC

$$\Rightarrow \left. \frac{dK(x, \xi)}{dx} \right|_{x=\xi^-}^{x=\xi^+} = \frac{-1}{p(\xi)}$$

4) $LK = 0$, except at $x = \xi$

— Green's Function of a self-adjoint differential operator is a symmetric function of the parameter ξ and the argument x , that is $K(x, \xi) = K(\xi, x)$

" If the force A , applied at the point ξ , produces the result $K(x, \xi)$ at the point x , then the force A acting at x produces the same result at ξ ."

Construction of Green's Functions:

$$Lu = 0$$

$v = c_0 v_0(x)$ satisfies BC at $x = x_0$

$v = c_1 v_1(x)$ satisfies BC at $x = x_1$

Two cases: v_0 and v_1 are linearly independent or
 v_0 and v_1 are linearly dependent

(1) v_0 and v_1 are linearly independent

$$v_0 v_0' - v_1' v_1 \neq 0$$

(2) v_0 and v_1 differ only by a constant factor

$v_0(x)$ satisfies BC at x_0 and x_1

$$\lambda = 0, \text{ where } Lv + \lambda v = 0$$

$$u(x) = \int_0^1 g(x,y) f(y) dy - \lambda \int_0^1 g(x,y) u(y) dy$$

3/4

- Integral eqns are usually easier to solve than differential equations.

Section 4.3 Differential Operators

- Domain of an operator

- Linear operator

- $Lu = F$

- Important Questions: inverse problem well posed
the adjoint operator exists
the Fredholm theorem applies

Domain ① The domain of L is given by all $v \in L^2[a, b]$

for which $Lu \in L^2[a, b]$, with inner product

$$\langle u, v \rangle = \int_a^b u(x) v(x) dx$$

② The domain of L is given by all v which satisfy the homogeneous boundary conditions

\Rightarrow if $v \in \text{Domain of } L$, $F \in \text{Range of } L$.

This definition of domain is highlighted by the use of the Green's function, so that for example, Dirichlet problem

$$v'' = F, \quad 0 < x < 1, \quad v(0) = v(1) = 0$$

$$v = \int_0^1 g(x,y) F(y) dy, \quad g(x,y) = \begin{cases} x(1-y), & x < y \\ y(1-x), & y < x \end{cases}$$

Adjoint of an Operator

Def: The adjoint of a differential operator L is defined to be the operator L^* for which $\langle Lu, v \rangle = \langle u, L^*v \rangle$ for all u in the domain of L and v in the domain of L^* .

This definition of the adjoint arises by integration by parts:

$$Lu = (pu')' + qu, \quad a < x < b, \quad + \text{BCs}$$

$$\langle u, v \rangle = \int_a^b u(x)v(x) dx$$

$$\begin{aligned} \langle Lu, v \rangle &= \int_a^b ((pu')' + qu)v dx = [pu'v]_a^b - \int_a^b pu''v dx + \int_a^b quv dx \\ &= [pu'v - puv']_a^b + \int_a^b u(pv')' dx + \int_a^b quv dx \end{aligned}$$

$$= \mathcal{J}(u, v) + \int_a^b ((pv')' + qv)u dx$$

$$= \mathcal{J}(u, v) + \int_a^b u L^*v dx$$

$$\text{we require } \mathcal{J}(u, v) \Big|_a^b = 0$$

For instance, Dirichlet BCs $u(0) = u(1) = 0$, $Lu = u''$, $x \in [0, 1]$

$$p(b)u'(b)v'(b) - p(a)u'(a)v(a) + p(a)u'(b)v'(a) = 0$$

$$p(b)u'(b)v'(b) - p(a)u'(a)v(a) = 0$$

$$\text{we require } v(b) = v(a) = 0$$

Example : $Lv = v''$, $0 < x < 1$, $v(0) = v(1) = 0$

$$p = 1$$

$$\begin{aligned}\langle Lv, v \rangle &= \int_0^1 v''(x)v(x) dx = [v'v - vv']_0^1 + \int_0^1 vv''(x) dx \\ &= v'(1)v(1) - v'(0)v(0) + \int_0^1 v L^* v dx\end{aligned}$$

$$\text{Force } v(1) = v(0) = 0$$

$$\Rightarrow \langle Lv, v \rangle = \langle v, Lv \rangle \text{ because } L \text{ is self-adjoint}$$

Example : $Lv = v''$, $0 < x < 1$, $2v(0) + v(1) = 0$
 $2v'(0) + v'(1) = 0$

$$\langle Lv, v \rangle = [v'v - vv']_0^1 + \int_0^1 vv'' dx$$

Force boundary terms to zero

$$v'(1)v(1) - v(1)v'(1) - v'(0)v(0) + v(0)v'(0) = 0$$

$$-2v'(0)v(1) + 2v(0)v'(1) - v'(0)v(0) + v(0)v'(0) = 0$$

$$\Rightarrow v'(0)(-2v(1) - v(0)) + v(0)(2v'(1) + v'(0)) = 0$$

$$\Rightarrow L^* v = v'', \quad 0 < x < 1$$

$$2v(1) + v(0) = 0$$

$$2v'(1) + v'(0) = 0$$

Study these eigenvalue problems and find that they must be complex conjugate (The complex inner product shows this).

Formally self-adjoint, the operators of L and L^* are the same, though the boundary conditions may be different.

Calculus of Variations

Ref: • F. B. Hildebrand, Methods of Applied Mathematics
 (2nd edition), chapter 2

1/5

- Kerner
- Cochran
- Courant-Hilbert, Vol 1

Motivation

• Ordinary Calculus - the problem of finding the max or min of a function $f(x)$.

• Multivariable calculus - max or min of $f(x)$ subject to constraints, x lies on $g(x) = c$

• Variational Calculus

~~solve $Ax = b$~~

• Differentiable operator

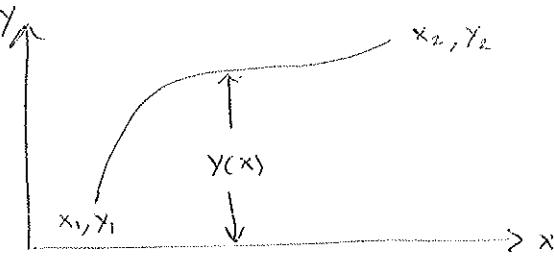
$Lv = f$, minimize $\|Lv - f\|$

minimize $\|v\|$, v a function

• solve $Ax = b$, A non-invertible, minimize $\|Ax - b\|$,
 minimize $\|x\|$, x a vector

The resolution of these last two minimization problems is by linear equations. In general the Calculus of Variations may lead to non-linear problems.

Example



Rotate $y(x)$ about the x -axis

- Determine the function which minimizes the surface area ,

$$S(y) = 2\pi \int_{x_1}^{x_2} y \sqrt{1 + [y'(x)]^2} dx$$

with $y(x_1) = y_1$, $y(x_2) = y_2$, $y_1 \geq 0$, $y_2 \geq 0$

IF there is a minimum the smooth curve which generates it is a catenary. This is one of the classical problems of the calculus of variations.

Consider

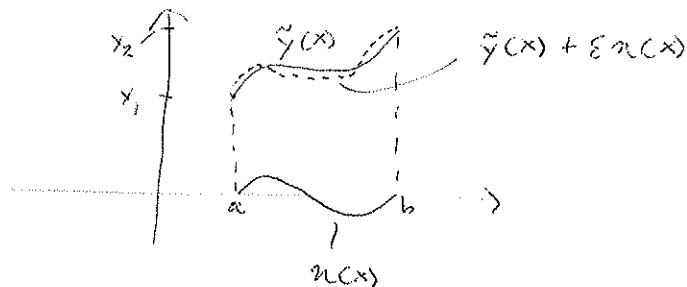
$$I(y) = \int_a^b F(x, y, y') dx , \quad y(a) = y_1 , \quad y(b) = y_2$$

where F is a known function of three variables.

Assume $F \in C^2$ with respect to its arguments.

We will relax the condition (of smoothness) later.

To fix ideas, suppose $I(y)$ is to be minimized (or maximized) by C^1 functions. Let $\tilde{y}(x)$ be the minimizing function. Choose any C^1 function $n(x)$ which vanishes at the endpoints, such that $n(a) = 0$, $n(b) = 0$.



Then for any ϵ , $\tilde{y}(x) + \epsilon n(x)$ is a C^2 function satisfying the boundary conditions

$$y(a) = y_a \text{ and } y(b) = Y_b$$

The integral $I(\tilde{y} + \epsilon n)$ is a function of ϵ , when \tilde{y} and n are fixed. It takes its minimum when $\epsilon = 0$. This is possible only if $\frac{d}{d\epsilon} I(\tilde{y} + \epsilon n) = 0$ when $\epsilon = 0$.

$$\text{Call } \tilde{F} = F(x, \tilde{y} + \epsilon n, \tilde{y}' + \epsilon n')$$

$$\text{then } \frac{d\tilde{F}}{d\epsilon} = \frac{\partial \tilde{F}}{\partial y} n + \frac{\partial \tilde{F}}{\partial y'} n'$$

$$\text{Note } \tilde{F} \rightarrow F \text{ as } \epsilon \rightarrow 0, \quad \frac{\partial \tilde{F}}{\partial y} \rightarrow \frac{\partial F}{\partial y}, \quad \frac{\partial \tilde{F}}{\partial y'} \rightarrow \frac{\partial F}{\partial y'}$$

The necessary condition for $\epsilon = 0$ to be a stationary point is $\left. \frac{dI}{d\epsilon} \right|_{\epsilon=0} = 0$

$$\left. \frac{dI}{d\epsilon} \right|_{\epsilon=0} = \int_a^b \left(\frac{\partial F}{\partial y} n + \frac{\partial F}{\partial y'} n' \right) dx = 0 \quad \left. \begin{array}{l} \text{the first variation} \\ \text{of } y, \text{ or } \delta I(y) \end{array} \right\}$$

To expand the integral employ integration by parts

$$\text{Consider } \int_a^b \frac{\partial F}{\partial y'} n' dx = \left[\frac{\partial F}{\partial y'} n \right]_{x=a}^{x=b} - \int_a^b \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) n dx$$

$\downarrow 0 \text{ because } n(a) = n(b) = 0$

$$\left. \frac{dI}{d\epsilon} \right|_{\epsilon=0} = \int_a^b \left[\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) \right] n dx - \left[\frac{\partial F'}{\partial y'} n \right]_a^{b=0}$$

$$\left. \frac{dI}{d\varepsilon} \right|_{\varepsilon=0} = \int_a^b \left[\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y} \right) \right] n \, dx + \left[\frac{\partial F}{\partial y} \right]_a^b = 0$$

Since the bracket

Because $n(a) = n(b) = 0$, the bracketed term vanishes.

Since $n(x)$ is arbitrary we conclude that the integrand must vanish identically otherwise we could choose a $c^1 n$ which vanishes at the end points, which is a contradiction.

The space of admissible variations:

$$\text{class } N(a,b) = \{n \mid n(a) = n(b) = 0, n \in C^1[a,b]\}$$

Fundamental Lemma

Suppose $g(x)$ is continuous on (a, b) and

$$\int_a^b g(x) n(x) \, dx = 0,$$

for each $n \in N(a,b)$. Then $g(x) \equiv 0$.

Proof : If $g(x) \neq 0$, $g(x)$ must be positive or negative, say positive at $x = x_0 \in (a, b)$.

Since $g(x)$ is continuous \exists an interval (x_1, x_2) , $x_1 < x_0 < x_2$ where $g(x)$ is positive.

$$\text{Let } n = \begin{cases} 0 & , x \notin (x_1, x_2) \\ (x-x_1)^2(x-x_2)^2 & , x \in (x_1, x_2) \end{cases}$$

For this choice of $n \in N(a,b)$ we get

$$\int_a^b g(x) n(x) \, dx > 0. \text{ This is a contradiction}$$

$$\therefore g(x) \equiv 0. \quad \blacksquare$$

Therefore a necessary condition is:

$$\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) = 0, \text{ Euler's equation}$$

Example: Cochran, pg 122, # 2a

(a) Determine the 1st variation of the functional

$$I(y) = \int_0^1 (y^2 + 2xy + y'^2) dx$$

$$\rightarrow \delta I(y) = \int_0^1 \left[(2y + 2x)n + 2y' \frac{dn}{dx} \right] dx \quad \left. \begin{array}{l} \text{1st variation} \\ \text{ } \end{array} \right\}$$

(b) What is the relevant Euler-Lagrange equation?

Integrate by parts:

$$\delta I(y) = \int_0^1 (2y + 2x)n + [2y'n]_0^1 - \int_0^1 2y''n dx$$

$$\delta I(y) = [2y'n]_0^1 + \int_0^1 (2y + 2x - 2y'')n dx$$

$$\Rightarrow 2y + 2x - 2y'' = 0$$

• Suppose $y(0) = 0, y(1) = 0$

then we have: $\left. \begin{array}{l} y'' = y + x \\ y(0) = 0, y(1) = 0 \end{array} \right\}$ has a unique solution

Some simplifications

$$\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) = 0$$

Suppose $F(x, y, y') = f(y, y')$

(F does not depend on x)

then the Euler-Lagrange equation reduces to $\frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) = 0$
this can be integrated

$$\frac{\partial F}{\partial y'} = c_1 \quad \text{- 1st order ODE}$$

Suppose $F(x, y, y') = f(y, y')$

leads to an autonomous equation,

First integral: $t - y' \frac{\partial F}{\partial y} = c_1$, First order ODE.

Notice that the Euler-Lagrange equation is
2nd order even if the functional only involves
 y' . In general, we have

$$\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) = 0 \quad , \quad F = f(x, y, y')$$

$$\text{let } \frac{\partial F}{\partial y} = g(x, y, y') \quad , \quad \frac{\partial F}{\partial y'} = h(x, y, y')$$

$$\frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) = \frac{dh}{dx}(x, y, y') = \frac{\partial h}{\partial x} + \frac{\partial h}{\partial y} \frac{dy}{dx} + \frac{\partial h}{\partial y'} \frac{dy'}{dx}$$

$$\Rightarrow g - h_x - h_y y_x - h_{y'} y'' = 0$$

In general this is a second order ODE.

This is linear only if F is quadratic
in y and y' .

Integrating the Euler-Lagrange equation when x is absent:

$$F_x = 0 \Rightarrow$$

$$\text{Let } y' = v, y'' = v' = \frac{dv}{dx} = \frac{dv}{dy} \frac{dy}{dx} = v \frac{dv}{dy}$$

then $g - h_x - h_y y' - h_{yy} y'' = 0$ in terms of v, y becomes

$$g(y, v) - h_y v - h_{vv} v \frac{dv}{dy} = 0$$

separate variables and show that the resulting ODE is exact:

$$\frac{\partial}{\partial v} (g - h_y v) dy = g_v - h_y - h_{vv} v$$

$$\frac{\partial}{\partial y} (-v h_{vv}) = -v h_{yv} - v_y h_v$$

$$\Rightarrow \text{Recall } g_v = \frac{\partial^2 F}{\partial y \partial v} \quad \text{and } h_{vv} = \frac{\partial^2 F}{\partial v^2}$$

$$\rightarrow \text{Total derivative: } d(F - v F_v) = 0$$

$$\Rightarrow F - v F_v = c_1 \Rightarrow \boxed{F - y' \frac{\partial F}{\partial y'} = c_1}$$

Cochran, pg 122 # 4

$$S(y) = 2\pi \int_a^b y \sqrt{1+y'^2} dx = 2\pi I(y), \quad y(a) = A, \quad y(b) = B$$

(a) Solve for $y(x)$, stationary function,

(b) specialize to the case where $a = -b$, $A = B$

Show that depending on the relative size of b, B

there may be ^{none} one or two candidate curves
that satisfy the end point candidates

$$F = y \sqrt{1+y'^2} \text{ independent of } x$$

First integral

$$F - y' \frac{\partial F}{\partial y'} = y(1+y'^2)^{1/2} - \frac{(y'^2)y}{(1+y'^2)^{1/2}} = c_1$$

Find

$$\frac{y(1+y'^2 - y'^2)}{(1+y'^2)^{1/2}} = c_1 \rightarrow \frac{y}{(1+y'^2)^{1/2}} = c_1$$

solve for y'

$$\frac{dy}{dx} = \left(\frac{y^2}{c_1^2} - 1 \right)^{1/2} \Rightarrow \frac{dy}{\sqrt{\frac{y^2}{c_1^2} - 1}} = dx$$

integrate both sides

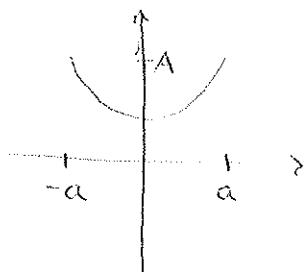
$$x = c_1 \cosh^{-1}\left(\frac{y}{c_1}\right) + c_2 \rightarrow \frac{x - c_2}{c_1} = \cosh^{-1}\left(\frac{y}{c_1}\right)$$

$$\rightarrow y = c_1 \cosh\left(\frac{x - c_2}{c_1}\right)$$

$$y(a) = A = c_1 \cosh\left(\frac{a - c_2}{c_1}\right)$$

$$y(-a) = A = c_1 \cosh\left(\frac{-a - c_2}{c_1}\right) = c_1 \cosh\left(\frac{a + c_2}{c_1}\right)$$

$$\Rightarrow y(x) = c_1 \cosh\left(\frac{x}{c_1}\right)$$



$$\left. \begin{array}{l} \\ \end{array} \right\} c_2 = 0$$

$$y(a) = A = c_1 \cosh\left(\frac{a}{c_1}\right)$$

Thus c_1 is to be determined

$$\text{set } k = \frac{c_1}{a}, h = \frac{A}{a}$$

$$\Rightarrow \frac{h}{k} = \cosh\left(\frac{1}{k}\right) \rightarrow h = k \cosh\left(\frac{1}{k}\right)$$

the value of h is known and the value of k is then determined.

Consider the function $w(k) = k \cosh\left(\frac{1}{k}\right), k > 0$

$$\text{Notice } \lim_{k \rightarrow 0^+} k \cosh\left(\frac{1}{k}\right) = \lim_{n \rightarrow +\infty} \frac{\cosh n}{n} = +\infty \quad \left(\frac{1}{k} = n \right)$$

$$w'(k) = \cosh\left(\frac{1}{k}\right) - \frac{1}{k} \sinh\left(\frac{1}{k}\right) \stackrel{?}{=} 0$$

Yes, there is one point where $w'(k) = 0 \Leftrightarrow \tanh(k) = k$

$$\text{where } k = k_0 = 0.833556$$

$$\text{concavity? } w''(k) = -\frac{1}{k^2} \sinh k + \frac{1}{k^2} \sinh k + \frac{1}{k^3} \cosh\left(\frac{1}{k}\right) > 0$$

Thus $w(k)$ is concave up $\forall k$, and

$w''(k_0) > 0$, so $w(k_0)$ is a minimum.

$$\Rightarrow w_0(k_0) = k_0 \cosh\frac{1}{k_0} \approx 1.508$$

Thus if $h < w_0$ there is no value of k such that

$h = k \cosh\frac{1}{k}$. IF $h = w_0$, \exists is exactly one value of k .

IF $h > w_0$, there are two values of k .

Calculus of Variations

1/4

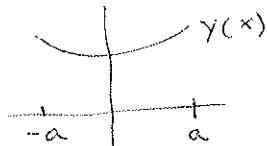
$$I(y) = \int_a^b f(x, y, y') dx \quad - \text{ Functionals}$$

$\delta I = 0 \Rightarrow$ Euler equation (nonlinear 2nd order ODE)

$$\frac{\partial F}{\partial y} - \frac{d}{dx} \frac{\partial F}{\partial y'} = 0 \quad (y(a) = y_1, y(b) = y_2)$$

Example: Minimal surface of Revolution

$$S(y) = 2\pi \int_{-a}^a y \sqrt{1 + (y')^2} dx$$



we found $y(x) = ak \cosh\left(\frac{x}{ak}\right)$

$$k = \frac{c_1}{a}, \quad h = \frac{A}{a} \quad \text{where } y(-a) = y(a) = A$$

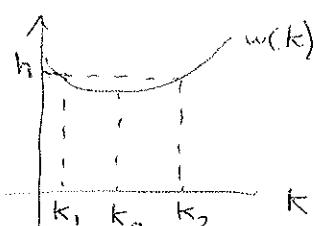
with this we found $w_k = k_0 \cosh \frac{1}{k_0} \approx 1.5088796$

k_0 is the point where $w(k_0) = h$ and $w(k) = k \cosh\left(\frac{1}{k}\right)$

If h is too small, no solution.

If $w(k_0) = h$, exactly one solution

If $w(k_0) < h$, two solutions.



If turns out that $h = k_2$ provides the smallest surface area.

$$S(\tilde{y}) = 2\pi \int_{-a}^a \tilde{y} \sqrt{1 + (\tilde{y}')^2} dx$$

$$= 2\pi \int_{-a}^a ak \cosh\left(\frac{x}{ak}\right) \left[1 + \sinh^2\left(\frac{x}{ak}\right) \right]^{1/2} dx$$

$$= 2\pi \int_{-a}^a ak \left(\cosh\left(\frac{x}{ak}\right) \right)^2 dx = ak \pi \int_{-a}^a \left(\cosh \frac{2x}{ak} + 1 \right) dx$$

$$S(\tilde{y}) \approx \pi a k \left[\frac{ak}{2} \sinh\left(\frac{2x}{ak}\right) + x \right]_a^a$$

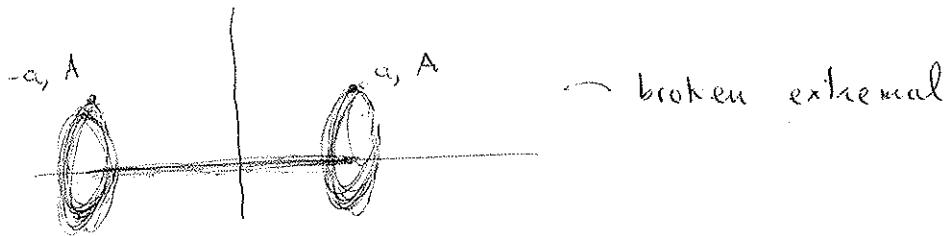
$$S(\tilde{y}) = \pi a^2 k \left[k \sinh \frac{2}{k} + 2 \right] \text{ not monotonic in } k$$

$$S(y) = \pi a^2 k \left[2k \cosh \frac{1}{k} \sinh \frac{1}{k} + 2 \right]$$

$S(\tilde{y}) = \pi a^2 k \left(2k \sinh \frac{1}{k} + 2 \right)$ This solution is monotonic decreasing in k for fixed a . Hence $k = k_2$ provides the smaller value of S .

What happens if $h = w_c$?

There is no catenary passing through $(-a, A)$ and (a, A) .
The minimal surface consists of two wheels.



$$S = 2\pi A^2 = 2\pi a^2 h^2$$

This area is smaller than that generated by any curve lying about the axis and passing through $(-a, A)$ and (a, A)

$$I(y) = \int_a^b F(x, y, y') dx \quad \text{with either } y(a) \text{ and/or} \\ y(b) \text{ not given}$$

As previously, suppose $\tilde{y}(x)$ is a minimizing function
consider variations $n(x)$

~~$I(\tilde{y} + \epsilon n)$~~

evaluate $\frac{d}{d\epsilon} I(\tilde{y} + \epsilon n) \Big|_{\epsilon=0} = 0$

$$\int_a^b \left[\frac{\partial F}{\partial y} n + \frac{\partial F}{\partial y'} n' \right] dx = 0$$

integrate by parts

$$\left[\frac{\partial F}{\partial y} n \right]_a^b + \int_a^b \left[\frac{\partial F}{\partial y'} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) \right] n dx = 0$$

This is true for the extremal function \tilde{y} for all

thus is true for the extremal function \tilde{y} for all $n \in N[a, b]$,

$y \in C^2[a, b]$ and in particular for $n \in N[a, b]$,

since $N[a, b] \subseteq C^1[a, b]$.

$$\text{Thus } \left[\frac{\partial F}{\partial y'} n \right]_a^b = 0 \quad \text{and} \quad \int_a^b \left[\frac{\partial F}{\partial y'} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) \right] n dx = 0, \text{ separately}$$

Fundamental lemma gives $\frac{\partial F}{\partial y'} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) = 0$ Euler Eqn

By a simple argument, consider C^2 variations that vanish at one endpoint say $x=a$ but not at $x=b$.

$$\text{Then at } x=b, \left. \frac{\partial F}{\partial y'} \right|_{x=b} = 0$$

Likewise, consider C^2 variations which vanish at $x=b$ but not at $x=a$, then at $x=a$, $\left. \frac{\partial F}{\partial y'} \right|_{x=a} = 0$

normal boundary conditions: If no boundary conditions are given at the end points then $\frac{\partial F}{\partial y'} = 0$ at the end points

Example: Cochran pg 123 #10

Determine the function $y(x)$ that minimizes

$I(y) = \int_0^{\pi} (2y \sin x + (y')^2) dx$ subject to the single condition $y(0) = 0$. Do first using the natural boundary condition and compare with the solution procedure that neglects to apply that auxiliary condition.

part a $f = (y')^2 + 2y \sin x$

$$\text{Euler eqn: } \frac{\partial F}{\partial y} - \frac{d}{dx} \frac{\partial F}{\partial y'} = 0$$

$$\Rightarrow 2 \sin x - \frac{d}{dx}(2y') = 0 \Rightarrow \text{Ansatz } y''(x) = \sin x$$

$$\text{solve by integration: } y'(x) = c_1 \cos x, \quad y(x) = c_2 + c_1 x - \sin x$$

$$y(0) = 0 \Rightarrow c_2 = 0 \Rightarrow y(x) = c_1 x - \sin x$$

To define c_1 use natural boundary condition at π :

$$\left. \frac{\partial F}{\partial y'} \right|_{x=\pi} = 0 \Rightarrow 2y'(\pi) = 0$$

$$y'(\pi) = c_1 - \cos \pi \quad 2y'(\pi) = 2c_1 - 2 \cos \pi = 2 + 2c_1 = 0$$

$$\Rightarrow c_1 = -1 \Rightarrow \boxed{y(x) = -x - \sin x}$$

part b



part b Evaluate $I(c_1 x - \sin x)$

$$I(c_1 x - \sin x) = \int_0^{\pi} [2 \sin x (c_1 x - \sin x) + (c_1 - \cos x)^2] dx$$

$$= \int_0^{\pi}$$

$$\frac{1}{2}$$

$$I(c_1) = \pi(c_1^2 + 2c_1 - \frac{1}{2})$$

$$\frac{dI}{dc_1} = \pi(2c_1 + 2) = 0 \Rightarrow c_1 = -1 \text{, as before}$$

How does the minimum in (a) compare with the minimum for $I(y)$ that results when the additional restriction $y(\pi) = 0$ is included?

$$y = c_1 x - \sin x \text{ from part a}$$

$$y(\pi) = c_1 \pi - \sin \pi = 0 \Rightarrow c_1 = 0 \Rightarrow \boxed{y = -\sin x}$$

$$I(-\sin x) = \int_0^{\pi} [-2 \sin^2 x + \cos^2 x] dx = -\frac{\pi}{2}$$

$$\text{from part (b)} \quad I(-x - \sin x) = \pi(1 - 2 - \frac{1}{2}) = -\frac{3\pi}{2}$$

The natural boundary condition provides the "smaller" minimum.

see Hildebrand examples.

Transition Conditions (see Hildebrand text)

In some cases the integrand F or its derivatives are discontinuous inside (a, b) but on subintervals $F \in C^2$.

$$\text{Still consider } I(y) = \int_a^b F(x, y, y') dx$$

Consider a single discontinuity at $x=c$, $a < c < b$

$$I(y) = \int_a^c F(x, y, y') dx + \int_{c+}^b F(x, y, y') dx$$

All of the steps involving $\tilde{y} + \epsilon n$ may be repeated except that each has 2 parts

$$\begin{aligned} & \int_a^c \left[\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) \right] n dx + \int_{c+}^b \left[\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) \right] n dx \\ & + \left[\frac{\partial F}{\partial y'} n(x) \right]_a^{c-} + \left[\frac{\partial F}{\partial y'} n(x) \right]_{c+}^b = 0 \end{aligned}$$

We require that $y(x)$ be continuous at $x=c$,
 $n(x) \in C[a, b]$, then $n(c+) = n(c-) = n(c)$

Then $S I = 0$ becomes

$$\begin{aligned} & \int_a^{c-} \left[\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) \right] n dx + \int_{c+}^b \left[\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) \right] n dx + \frac{\partial F}{\partial y'} \Big|_b n(b) - \frac{\partial F}{\partial y'} \Big|_a n(a) \\ & - \left[\frac{\partial F}{\partial y'} \Big|_{c+} - \frac{\partial F}{\partial y'} \Big|_{c+} \right] n(c) = 0 \end{aligned}$$

The Fundamental lemma can be modified to continuous variations. Then the Euler equation is satisfied on each subinterval (a, c) , (c, b) , $\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) = 0$ and $\frac{\partial F}{\partial y'}$ must vanish at an end-point where n is not given.

Thence $\left. \frac{\partial F}{\partial y'} \right|_{c+} = 0 \Rightarrow \frac{\partial F}{\partial y'} \text{ is continuous} \Rightarrow \boxed{\text{Transition condition}}$

Example

The input-output relationship of a continuous system is defined by $y''(t) + c(t)y'(t) + 6y(t) = 30e^{-4t}$

$$\text{where } c(t) = \begin{cases} 5, & t < 1 \\ 7, & t \geq 1 \end{cases}$$

$$y(0) = y(0^+) \quad y'(0) = 1, \quad y'(0^-) = -1.$$

Find $y(t)$.

$$\text{Define } p(t) = e^{\int c(u)du} = \begin{cases} e^{5t}, & t < 1 \\ e^{7t}, & t \geq 1 \end{cases}$$

Multiply by $p(t)$ and integrate from $t=0$ to $t=\infty$

$$(e^{\int c(u)du} y')' + 6e^{\int c(u)du} y = 30 e^{\int c(u)du} e^{-4t}$$

Multiply by $y(t)$ and then integrate

$$\int_0^\infty [(p(t)y')' y + 6p(t)y^2] dt = \int_0^\infty 30e^{-4t} p(t) dt$$

Integrate by parts

$$\int_0^\infty [-p(t)y^2 + 6p(t)y^2] dt = 30 \int_0^\infty e^{-4t} p(t) dt$$

$$\Rightarrow 8 \int_0^\infty [-p(t)y^2 + 6p(t)y^2 - 30e^{-4t} p(t)] dt = 0$$

Assume $y, y' \rightarrow 0$ as $t \rightarrow \infty$

transition conditions

$$y(1^-) = y(1^+)$$

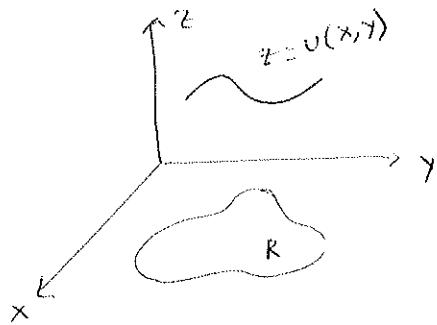
$$\frac{d}{dt} \left[y' \right]_{t=1^-}^{t=1^+} = [-2y'(t)p(t)]_{1^-}^{1^+} = 0$$

$$\lim_{t \rightarrow 1^+} p(t)y'(t) = \lim_{t \rightarrow 1^-} p(t)y'(t)$$

$$e^r y'(1^-) = e^r y'(1^+)$$

Functions of more than one ^{independent} variable

Minimal surface



$$I(v) = \iint_R \sqrt{1 + \left(\frac{\partial v}{\partial x}\right)^2 + \left(\frac{\partial v}{\partial y}\right)^2} dx dy$$

Analogous to our earlier definitions
consider functionals $\tilde{F}(x, y, v, v_x, v_y, v_{xx}, v_{xy})$

For functions $v(x, y)$, $v(x, y)$. Now we can vary v and v holding both x and y fixed. Variations
 $v + \varepsilon \xi$, where $\varepsilon \xi = \varepsilon \xi(x, y)$ and
 $\delta v = \varepsilon \eta(x, y)$

$$\Delta F = \frac{\partial F}{\partial v} \varepsilon \xi + \frac{\partial \tilde{F}}{\partial v} \varepsilon \eta + \frac{\partial F}{\partial v_x} \varepsilon \xi_x + \frac{\partial \tilde{F}}{\partial v_x} \varepsilon \eta_x + \frac{\partial F}{\partial v_y} \varepsilon \xi_y + \frac{\partial \tilde{F}}{\partial v_y} \varepsilon \eta_y$$

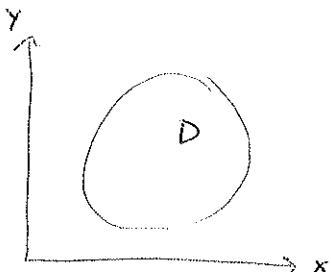
+ higher order terms - F

$$\Delta F = \delta F + \text{higher order terms} - F$$

Example:

$$I(v) = \iint_D F(x, y, v_x, v_y, v_{xx}, v_{xy}, v, v) dx dy$$

D is a region for which Green's Theorem is true



Blah Blah Blah

Example: Find the minimum of the functional

$$I(v) = \iint_G \left[\|\nabla v\|^2 + \frac{4v}{\sqrt{x^2+y^2}} \right] dx dy$$

among functions belonging to the class $C^1(G)$

where $G = \{x = (x, y) \mid 1 < \|x\| < 3\}$ and $v=0$ on ∂G .

$$f = \|\nabla v\|^2 + \frac{4v}{\sqrt{x^2+y^2}} = v_x^2 + v_y^2 + \frac{4v}{\sqrt{x^2+y^2}}$$

$$\frac{\partial F}{\partial v} - \frac{d}{dx}\left(\frac{\partial F}{\partial v_x}\right) - \frac{d}{dy}\left(\frac{\partial F}{\partial v_y}\right) = 0 \quad \text{Euler Lagrange}$$

$$\frac{4}{\sqrt{x^2+y^2}} - \frac{d}{dx}(2v_x) - \frac{d}{dy}(2v_y) = 0$$

$$\Rightarrow v_{xx} + v_{yy} = \frac{2}{\sqrt{x^2+y^2}}$$

polar coordinates: $x = r\cos\theta, y = r\sin\theta$

$$w(r, \theta) = v(x, y)$$

$$\frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} + \frac{1}{r^2} \frac{\partial^2 w}{\partial \theta^2} = \frac{2}{r}$$

A solution is independent of $\theta \Rightarrow \frac{\partial w}{\partial \theta} = 0$

$$\text{ODE: } w_{rr} + \frac{1}{r} w_r = \frac{2}{r}$$

$$\Rightarrow rw''(r) + w'(r) = 2 \rightarrow (rw')' = 2$$

$$rw' = 2r + c_1 \rightarrow w' = 2 + \frac{c_1}{r} \rightarrow \boxed{w(r) = 2r + c_1 \ln r + c_2}$$

$$w(1) = 2 + c_2 = 0 \Rightarrow c_2 = -2$$

$$w(3) = 6 + c_1 \ln 3 = 2 \Rightarrow c_1 = \frac{-4}{\ln 3}$$

$$\Rightarrow \boxed{w(r) = 2r - \frac{4 \ln r}{\ln 3} - 2}$$

Generalized Green's Functions

Cochran - Chpt on Green's Functions

$$\textcircled{1} \quad L g(x, y) = -\omega(y) \sum_{i=1}^k \psi_i(x) \psi_i(y), \quad x \neq y$$

where $\{\psi_i(x)\}_{i=1}^k$ is an orthonormal basis

For the null space of L^* with homogeneous boundary conditions $B^* \psi_i = 0$

$$v'' = f(x), \quad v(0) = 0, \quad v(L) = v'(L)$$

$L = v'' = L^*$ - self adjoint, $B = B^*$, $i = L$ in this case

$$\psi_i = \phi_i$$

\textcircled{2} g is continuous at $x=y$

$$\textcircled{3} \quad \frac{\partial g}{\partial x} \Big|_{x=y^-} - \frac{\partial g}{\partial x} \Big|_{x=y^+} = \frac{1}{\omega(y)} \quad \text{jump condition}$$

$$\textcircled{4} \quad \int_a^b g(x, y) \phi_i(x) w(x) dx = 0$$

$$i=L$$

$$\omega=1$$

$\phi_i(x)$ is the basis for the null space of L
with $B \phi_i = 0$

Assignment 4, problem 2

reference: "New directions in Linear Differential Equas"

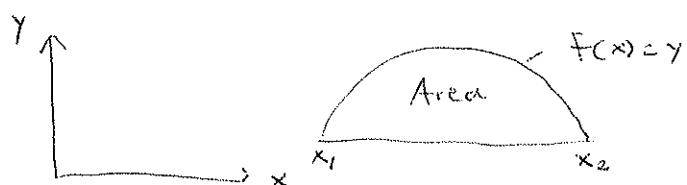
SIAM Review, vol 21, 1979, pg 57-70

Exam 2 - November 15

- Special Functions
- Green's Functions
- Calculus of variations (without constraints)

Calculus of Variations with Constraints

Classical problem: "Isoperimetric Problem"



For all curves with a fixed perimeter L , maximize area A

$$\text{maximize } A = \int_{x_1}^{x_2} y \, dx \quad \text{given} \quad L = \int_{x_1}^{x_2} \sqrt{1+y'^2} \, dx + x_2 - x_1 \text{ is fixed}$$

$$y(x_1) = 0, y(x_2) = 0$$

this problem is done in Hildebrand

General situation

$$I = \int_{x_1}^{x_2} F(x, y, y') \, dx = \max \text{ or min} , \quad y(x_1) = y_1 , \quad y(x_2) = y_2$$

$$\text{given} \quad J = \int_{x_1}^{x_2} G(x, y, y') \, dx = K \text{ is fixed}$$

Since there are two functionals, introduce two variations

$$\delta y = \epsilon_1 n_1(x) + \epsilon_2 n_2(x)$$

$$I(\epsilon_1, \epsilon_2) = \int_{x_1}^{x_2} F(x, y + \epsilon_1 n_1(x), y')$$

$$I(\epsilon_1, \epsilon_2) = \int_{x_1}^{x_2} F(x, y + \epsilon_1 n_1(x) + \epsilon_2 n_2(x), y' + \epsilon_1 n'_1(x) + \epsilon_2 n'_2(x)) dx$$

$$J(\epsilon_1, \epsilon_2) = \int_{x_1}^{x_2} G(x, y + \epsilon_1 n_1 + \epsilon_2 n_2, y' + \epsilon_1 n'_1 + \epsilon_2 n'_2) dx = k$$

Introduce a Lagrange multiplier λ

$$\frac{\partial}{\partial \epsilon_1} [I(\epsilon_1, \epsilon_2) + \lambda J(\epsilon_1, \epsilon_2)] = 0$$

$$\frac{\partial}{\partial \epsilon_2} [I(\epsilon_1, \epsilon_2) + \lambda J(\epsilon_1, \epsilon_2)] = 0 \quad \Rightarrow \quad \nabla_{\epsilon} I \parallel \nabla_{\epsilon} J$$

Variational notation: $\delta(I + \lambda J) = 0$

\Rightarrow Euler-Lagrange equation

$$\left. \frac{\partial}{\partial y} (F + \lambda G) - \frac{d}{dx} \frac{\partial}{\partial y'} (F + \lambda G) = 0 \right\}$$

$$\text{BCs: } y(x_1) = y_1, \quad y(x_2) = y_2$$

$$J = \int_{x_1}^{x_2} G(x, y, y') dx = k$$

Example (Hildebrand) pg 142-144

$$x_1 = 0, x_2 = L$$

The solutions satisfy $(x-c_1)^2 + (y-c_2)^2 = \lambda^2$

which can be found by requiring the circle to pass through the end-points. If $L > \pi/2$, the solution will not determine y as a single-valued function of x .

Blah Blah Blah Blah
- see Hildebrand

Sturm-Liouville Theory - Variational problems pg 145

Blah

Blah

$$Ax = t$$

Blah

Back \Rightarrow

One-dimensional Poincaré inequality

- consider Functions $f(x) \in L^2[0, L]$, $f(0) = f(L) = 0$
with $f'(x) \in L^2[0, L]$

$$\text{then } \left[\frac{\pi^2}{L^2} \int_0^L [f(x)]^2 dx \leq \int_0^L [f'(x)]^2 dx \right]$$

this relates to the Sturm-Liouville problem

$$y'' + \lambda y = 0, \quad 0 < x < L, \quad y(0) = y(L) = 0$$

$$\text{let } \phi_n(x) = \sin\left(\frac{n\pi}{L}x\right), \quad \lambda_n = \frac{n\pi}{L}$$

$$\text{minimize } \frac{\int_0^L f'^2 dx}{\int_0^L f^2 dx} \geq \lambda_n = \frac{n\pi}{L}$$

Hence the Poincaré inequality follows.

Wirtinger Inequality

If $f'(0) = f'(L) = 0$, $f' \in L^2[0, L]$ and $\int_0^L f dx = 0$ then

$$\frac{\pi^2}{L^2} \int_0^L f'^2 dx \leq \int_0^L f'^2 dx$$

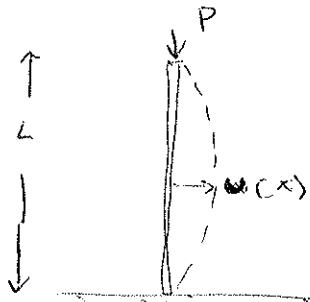
The associated Sturm-Liouville problem: $y'' + \lambda y = 0$, $0 < x < L$

$$y'(0) = y'(L) = 0, \quad \phi_n(x) = \cos\left(\frac{n\pi}{L}x\right), \quad \lambda_n = \left(\frac{n\pi}{L}\right)^2$$

$\phi_0(x) = 1$, $\lambda_0 = 0$ here $\langle \bar{y}, \phi_0 \rangle = 0$, f satisfies the B.C.s

Courant - Hilbert VOL 1, pg 272-274

Vibrational problem of buckling



A rod is compressed by a loading force P .
 (Rigid) (P is constant at both ends)

potential energy

$$v(0) = v(L) = 0$$

$$V = \frac{1}{2} \int_0^L EI v'' dx - \frac{P}{2} \int_0^L v'^2 dx$$

for sufficiently small values of P

the minimum of V is zero

on the other hand, for sufficiently large P , V can be negative

For any admissible v we need only choose

$$P > \frac{\int_0^L EI v'' dx}{\int_0^L (v')^2 dx} \quad \text{for buckling to occur.}$$

the buckling force P_0 is the largest value of P for which

$$\min V = 0.$$

$$\frac{\int_0^L EI v'' dx}{\int_0^L (v')^2 dx} = \lambda$$

$$\text{let } \delta \lambda = 0$$

$$\begin{aligned} \frac{I_1}{I_2} \left(\frac{S(I_1)}{I_2} \right) &= \frac{(SI_1)I_2 - I_1(SI_2)}{(I_2)^2} = 0 \\ S(I_1 - 2I_2) &= 0 \end{aligned}$$

$$\Rightarrow \text{Euler-Lagrange equations: } v'' + \frac{\lambda}{EI} v''' = 0$$

$$\text{natural boundary conditions: } v''(0) = v''(L) = 0$$

$$\text{we already have: } v(0) = v(L) = 0$$

non-standard
eigenvalue
problem

$$v'' + k^2 v'' = 0 \quad , \quad k = \frac{\lambda}{EI}$$



$$v = c_1 + c_2 x + c_3 \cos kx + c_4 \sin kx$$

$$\left. \begin{array}{l} v(0) = c_1 + c_3 = 0 \\ v'(0) = c_2 + \cancel{c_3 \cos 2\theta} - k^2 c_3 = 0 \end{array} \right\} c_1 = c_3 = 0$$

$$v(L) = c_2 L + c_4 \sin kL = 0$$

$$v''(L) = -k^2 c_4 \sin kL = 0$$

$$\Rightarrow k_n L = n\pi \quad \Rightarrow \quad k_n = \frac{n\pi}{L} \quad , \quad c_2 = 0$$

$$\Rightarrow \left. \begin{array}{l} v(x) = \sin \frac{n\pi}{L} x \end{array} \right\}$$

Green's Functions for Initial Value Problems

$$Lg = S \quad (L - \text{second order})$$

$$g(0) = 0, g'(0) = 0$$

$$g = \begin{cases} c_1 u_1 + c_2 u_2, & x < y \\ k_1 u_1 + k_2 u_2, & x > y \end{cases}, \quad L u_1 = 0, \quad L u_2 = 0$$

$$c_1 u_1(0) + c_2 u_2(0) = 0$$

$$c_1 u_1'(0) + c_2 u_2'(0) = 0$$

$$\Rightarrow c_1 = c_2 = 0 \quad \text{unless} \quad \begin{vmatrix} u_1(0) & u_2(0) \\ u_1'(0) & u_2'(0) \end{vmatrix} = 0 = |W(u_1, u_2)|$$

but $|W(u_1, u_2)| \neq 0$ because u_1 and u_2 are linearly independent

$$\Rightarrow g = \begin{cases} 0, & x < y \\ k_1 u_1 + k_2 u_2, & x > y \end{cases}$$

apply jump condition, continuity

$$\left. \frac{dg(x,y)}{dx} \right|_{x=y^-}^{x=y^+} = \frac{1}{a_2(y)} \quad \left. g(x,y) \right|_{x=y^-}^{x=y^+} = 0$$

$$\Rightarrow k_1 u_1'(y) + k_2 u_2'(y) = \frac{1}{a_2(y)} \quad \Rightarrow k_1 u_1(y) + k_2 u_2(y) = 0$$

Now solve for k_1 and k_2

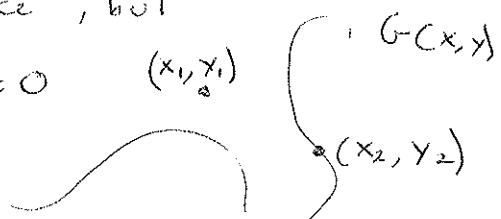
Calculus of Variations

- ◆ variable endpoints : Transversality condition
 - the upper limit of the integral

$$I = \int_{x_1}^{x_2} F(x, y, y') dx , \quad y(x_1) = y_1$$

and $y(x_2)$ is not given in advance, but

(x_2, y_2) lies on a curve $G(x, y) = 0$



In Cochran, Hildebrand this problem is treated and also in Courant-Hilbert, Vol I.

Introduce a parameter t , $t_1 \leq t \leq t_2$.

The extremizing curve is $(x(t), y(t))$. Let

$$\tilde{F}(x, y, \dot{x}, \dot{y}) = \dot{x} F(x, y, \frac{\dot{y}}{\dot{x}})$$

$$\text{where } \dot{x} = \frac{dx}{dt}, \quad \dot{y} = \frac{dy}{dt}$$

The boundary conditions are $x(t_1), y(t_1)$ fixed

$$\text{and } G(x(t_2), y(t_2)) = 0$$

The variability of the upper limit is eliminated.

Also this will handle the case where it is inconvenient to solve G explicitly for y .

$$I = \int_{t_1}^{t_2} F(x, y, \dot{x}, \dot{y}) dt \quad , \quad x(t_1) = x_i, \quad y(t_1) = y_i$$

constraint $G(x(t_2), y(t_2)) = 0$

Introduce two variations $\xi(t)$, $n(t)$ and two parameters ϵ_1, ϵ_2 such that $\xi(t_1) = 0, n(t_1) = 0$

$$\Psi(\epsilon_1, \epsilon_2) = G[x(t_2) + \epsilon_1 \xi(t_2), y(t_2) + \epsilon_2 n(t_2)] = 0$$

$$\Phi(\epsilon_1, \epsilon_2) = \int_{t_1}^{t_2} F(x + \epsilon_1 \xi, y + \epsilon_2 n, \dot{x} + \epsilon_1 \dot{\xi}, \dot{y} + \epsilon_2 \dot{n}) dt$$

is stationary at $\epsilon_1 = \epsilon_2 = 0$.

Introduce a Lagrange multiplier λ

$$\left. \frac{\partial}{\partial \epsilon_1} (\Phi + \lambda \Psi) \right|_{\epsilon_1 = \epsilon_2 = 0} = 0 \quad , \quad \left. \frac{\partial}{\partial \epsilon_2} (\Phi + \lambda \Psi) \right|_{\epsilon_1 = \epsilon_2 = 0} = 0$$

Since $(x(t), y(t))$ must satisfy the Euler-Lagrange

equation

$$\int_{t_1}^{t_2} [F_x \dot{\xi} + F_{\dot{x}} \ddot{\xi}] dt + \lambda G_x(x(t_2), y(t_2)) \xi(t_2) = 0$$

$$\int_{t_1}^{t_2} [F_y \dot{n} + F_{\dot{y}} \ddot{n}] dt + \lambda G_y(x(t_2), y(t_2)) n(t_2) = 0$$

Integrate by parts:

$$[(F_{\dot{x}} + \lambda G_x) \dot{\xi}]_{t=t_2} + \int_{t_1}^{t_2} [-\frac{d}{dt} F_{\dot{x}} + F_x] \dot{\xi} dt = 0$$

$$[(F_{\dot{y}} + \lambda G_y) \dot{n}]_{t=t_2} + \int_{t_1}^{t_2} [-\frac{d}{dt} F_{\dot{y}} + F_y] \dot{n} dt = 0$$

Transversality conditions are obtained by eliminating λ .

$$(F_x + \lambda G_x)_{t=t_2} = 0$$

$$(F_y + \lambda G_y)_{t=t_2} = 0$$

$$\Rightarrow \lambda = -\frac{F_x}{G_x} = -\frac{F_y}{G_y}$$

Assume G_y and G_x do not both vanish at $t=t_2$

$$F_x G_y - F_y G_x = 0 \quad \boxed{\text{II}}$$

Go back to the original variables.

$$F_x = f(x, y, \dot{x}) + \dot{x} \frac{\partial f}{\partial y'}(x, y, \dot{x}) \left(-\frac{y'}{\dot{x}^2} \right)$$

$$F_y = f(x, y, \dot{x}) + y' \frac{\partial f}{\partial y'}(x, y, \dot{x})$$

$$F_y = \dot{x} \frac{\partial f}{\partial y'}(x, y, \dot{x}) \left(\frac{1}{\dot{x}} \right) = \frac{\partial f}{\partial y'}(x, y, \dot{x})$$

Substitute into $\boxed{\text{II}}$

$$\left(f + y' \frac{\partial f}{\partial y'} \right) G_y - \frac{\partial f}{\partial y'} G_x = 0 \quad \Rightarrow \left[f G_y + \frac{\partial f}{\partial y'} \left(y' G_y - G_x \right) = 0 \right]$$

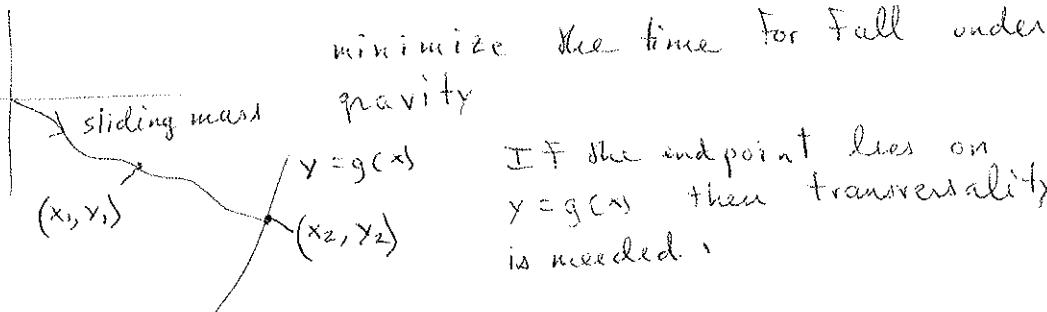
on the extremizing curve $y(x) = \tilde{y}$.

IF $G(x, y) = y - g(x)$, $G_x = -g'(x)$, $G_y = 1$

$$\Rightarrow \left[f + f_y \cancel{y' + g'} = 0 \right] \quad \left[f + f_y (-y' + g') = 0 \right]$$

Classical Example: Brachistochrone problem

pg 196 # 15, 49



If the endpoint lies on $y = g(x)$ then transversality is needed.

Example:

Minimize $\int_0^b (y')^2 dx$ with $y(0) = 0$, where $(b, y(b))$ lies on the hyperbola $y^2 - x^2 = 1$, $y > 0$

$$\text{so } G(x, y) = y^2 - x^2 - 1 = 0$$

transversality condition

$$(\bar{F} - y' F_{y'}) G_y - F_y G_x = 0$$

$$\Rightarrow (y'^2 - y'(2y)) 2y - 2y'(-2x) = 0 \Rightarrow \boxed{yy' - 2x = 0, x=b, y=y(b)}$$

Euler-Lagrange Eqn

$$\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) = 0 \Rightarrow -2y'' = 0 \Rightarrow y(x) = Ax + B$$

$$y(0) = 0 \Rightarrow \boxed{y(x) = Ax}$$

$$(Ab)A - 2b = 0 \Rightarrow A^2 = 2 \Rightarrow A = \pm \sqrt{2}$$

$$\boxed{y(x) = \pm \sqrt{2}x}$$

Finite Constraints (Holonomic Constraints)

Render $I = \int_{t_1}^{t_2} F(t, x, y, z, \dot{x}, \dot{y}, \dot{z}) dt$

stationary, given $G(x, y, z) = 0$, the stationary curve $(x(t), y(t), z(t))$ lies entirely on the surface. (Example, geodesic problem.)

Introduce Lagrange Multiplier $\lambda(t)$

$$SI = 0, SG = 0 \quad G_x \delta x + G_y \delta y + G_z \delta z = 0$$

multiply by $\lambda(t)$ and integrate.

$$\int_{t_1}^{t_2} \left[\left(\frac{\partial F}{\partial x} - \frac{d}{dt} \left(\frac{\partial F}{\partial \dot{x}} \right) + \lambda(t) G_x \right) \delta x + \left(\frac{\partial F}{\partial y} - \frac{d}{dt} \left(\frac{\partial F}{\partial \dot{y}} \right) + \lambda(t) G_y \right) \delta y + \left(\frac{\partial F}{\partial z} - \frac{d}{dt} \left(\frac{\partial F}{\partial \dot{z}} \right) + \lambda(t) G_z \right) \delta z \right] dt = 0$$

\Rightarrow 3 Euler-Lagrange equations + constraint

Example: $G = x^2 + y^2 + z^2 - a^2 = 0$ sphere

$$L = \int_{t_1}^{t_2} \sqrt{\dot{x}^2 + \dot{y}^2 + \dot{z}^2} dt, \quad G_x = 2x, \quad G_y = 2y, \quad G_z = 2z, \quad F = (\dot{x}^2 + \dot{y}^2 + \dot{z}^2)^{1/2}$$

Euler-Lagrange Eqs.

$$\lambda G_x - \frac{d}{dt} \left(\frac{\dot{x}}{F} \right) = 0, \quad \lambda G_y - \frac{d}{dt} \left(\frac{\dot{y}}{F} \right) = 0, \quad \lambda G_z - \frac{d}{dt} \left(\frac{\dot{z}}{F} \right) = 0$$

Eliminate λ

$$\frac{\frac{d}{dt} \left(\frac{\dot{x}}{F} \right)}{G_x} = \frac{\frac{d}{dt} \left(\frac{\dot{y}}{F} \right)}{G_y} = \frac{\frac{d}{dt} \left(\frac{\dot{z}}{F} \right)}{G_z} \Rightarrow \frac{F \ddot{x} - \dot{x} \dot{F}}{2x F^2} = \frac{F \ddot{y} - \dot{y} \dot{F}}{2y F^2} = \frac{F \ddot{z} - \dot{z} \dot{F}}{2z F^2}$$

$$\frac{F\ddot{z} - \dot{z}\dot{F}}{z} = \frac{F\ddot{y} - \dot{y}\dot{F}}{y}$$

$$\Rightarrow \frac{\ddot{z} - \dot{z}\dot{F}}{z} = \frac{\ddot{y} - \dot{y}\dot{F}}{y} \Rightarrow y\left(\ddot{z} - \dot{z}\frac{\dot{F}}{F}\right) = z\left(\ddot{y} - \dot{y}\frac{\dot{F}}{F}\right)$$

~~$$\Rightarrow \ddot{y} - \dot{y}\frac{\dot{F}}{F} = \ddot{z} - \dot{z}\frac{\dot{F}}{F}$$~~

$$\Rightarrow \frac{\dot{F}}{F} = \frac{\ddot{y} - \dot{y}\ddot{z}}{\ddot{z} - \dot{z}\dot{y}} \quad \text{exact?} \quad \frac{d}{dt}(z\dot{y} - y\dot{z}) = \dot{y}\dot{z} - \dot{y}\dot{z}$$

$$\Rightarrow \ln(y\dot{x} - x\dot{y}) \approx \log(z\dot{y} - y\dot{z}) + \log c_1$$

$$\Rightarrow y\dot{x} - x\dot{y} = c_1(z\dot{y} - y\dot{z})$$

$$\frac{\dot{x} + c_1 z}{x + c_1 z} = \frac{y}{y}$$

integrate again $\ln(x + c_1 z) = \ln y + \log c_2$

$$\Rightarrow x - c_2 y + c_1 z = 0 \quad \text{plane through origin}$$

intersection with sphere $x^2 + y^2 + z^2 = a^2$ gives a great circle.

Extension

Differential equations as constraints: Non-holonomic

Example: $\delta \int_{t_1}^{t_2} F(t, x, y, z, \dot{x}, \dot{y}, \dot{z}) dt = 0 \quad \text{given } G(x, y, z, \dot{x}, \dot{y}, \dot{z}) = 0$

Introduce $\lambda(t)$

$$\delta G = G_x \delta_x + G_y \delta_y + G_z \delta_z + G_{x'} \delta_{x'} + G_{y'} \delta_{y'} + G_{z'} \delta_{z'} = 0$$

Find $\int_{t_1}^{t_2} \delta F + \lambda \delta G \ dt = 0$

Transversality:

$$I = \int_{x_1}^{x_2} f(x, y, y') dx , \quad y(x_1) = y_1 , \quad x_2 \text{ lies on } G(x, y) = 0$$

Necessary condition

$$(F - y' F_y) G_y = F_y G_x \quad \text{for } x = x_2$$

We saw the special case: $y = g(x)$

Now consider $x = b$, b constant

Free boundary $G = x - b$, $G_x = 1$, $G_y = 0$

natural boundary condition: $F_y = 0$ as before.

Differential Equations as constraints

Optimal control - Cochran Chpt 4

$$I(\underline{x}, \underline{u}) = \underline{\text{functional}} = \int_{t_1}^{t_2} f(t, \underline{x}, \underline{u}) dt , \quad \underline{x}(t_1) = \underline{x}^{(0)} \text{ known}$$

where $\dot{\underline{x}}(t) = \underline{G}(t, \underline{x}, \underline{u})$, system of ODE's

$$\underline{x} = \begin{pmatrix} x_1(t) \\ x_2(t) \\ \vdots \\ x_n(t) \end{pmatrix} \quad \text{state vector}$$

$$\underline{u} = \begin{pmatrix} u_1(t) \\ u_2(t) \\ \vdots \\ u_m(t) \end{pmatrix} \quad \text{control vector}$$

Ideally we could eliminate \underline{u} otherwise we solve
keeping \underline{u} in the system.

Consider the case $n=1, m=1$ (one state vector, one control vector).

$$I(x, u) = \int_{t_1}^{t_2} F(t, x, u) dt$$

$$\Rightarrow I(x, u) = \int_{t_1}^{t_2} F(t, x, u) dt, \quad x(t_1) = x^{(0)}$$

$\dot{x} = g(t, x, u)$ - This is like a non-holonomic constraint

Introduce a Lagrange multiplier $\lambda(t)$.

$$\dot{x} - g(t, x, u) = 0 \quad (\text{non-holonomic constraint})$$

$$\delta(\dot{x} - g(t, x, u)) = 0$$

$$\delta \dot{x} - g_x \delta x - g_u \delta u = 0$$

Multiply by $\lambda(t)$ and integrate:

$$\int_{t_1}^{t_2} F_x \delta_x + F_u \delta_u + \lambda [\delta \dot{x} - g_x \delta x - g_u \delta u] dt = 0$$

integrate by parts

$$\int_{t_1}^{t_2} [F_x + \lambda g_x] \delta x + [F_u + \lambda g_u] \delta u dt - \int_{t_1}^{t_2} \dot{\lambda} \delta x dt = 0$$

require $\lambda(t_2) \delta(t_2) - \lambda(t_1) \delta(t_1) = 0$

hence $\lambda(t_2) = 0$

Euler equations

$$\begin{cases} F_x - \lambda g_x - \dot{\lambda} = 0 \\ F_u - \lambda g_u = 0 \\ \dot{x} = g(t, x, u) \end{cases}$$

Note it is possible to eliminate λ , but retaining λ may be the best strategy at times.

to eliminate λ (Cochran)

$$\dot{x} + \lambda g_x = f_x$$

integrating Factor, $n = e^{\int g_x dt}$ $\Rightarrow \frac{d}{dt}(\lambda e^{\int g_x dt}) = f_x e^{\int g_x dt}$

$$\Rightarrow \lambda e^{\int g_x dt} = \int f_x e^{\int g_x dt} dt + c$$

~~$\lambda(t) = e^{-\int_{t_0}^t g_x dt}$~~ ~~$f_x e^{\int g_x dt}$~~ ~~$\int f_x e^{\int g_x dt} dt$~~ ~~$c$~~ , (bc satisfies $\lambda(t_2) = 0$)

we need $\lambda(t_2) = 0$, so for bounds of integration

$$\lambda(t) = e^{-\int_{t_0}^t g_x dt} \int_{t_0}^{t_2} f_x e^{\int g_x dt} dt + c$$

$$\lambda(t_2) = e^{-\int_{t_0}^{t_2} g_x dt} \int_{t_0}^{t_2} f_x e^{\int g_x dt} dt + c$$

$$\Rightarrow c = - \left[\int_{t_0}^{t_2} f_x e^{\int g_x dt} dt \right] e^{-\int_{t_0}^{t_2} g_x dt}$$

$$\Rightarrow \lambda(t) = e^{-\int_{t_0}^t g_x dt} \left[\int_{t_0}^t f_x e^{\int g_x dt} dt - \int_{t_0}^{t_2} f_x e^{\int g_x dt} dt \right]$$

Take $t_0 = t_2$

$$\lambda(t) = e^{-\int_{t_2}^t g_x dt} \int_{t_2}^t f_x e^{\int g_x dt} dt$$

This may be substituted back into the system
to find $x(t), u(t)$.

For more general case :

$$I(x, u) = \int_{t_1}^{t_2} F(t, x, u) dt , \quad \dot{x} = G(t, x, u)$$

$$\therefore x(t_1) = x^{(0)}$$

Introduce $\lambda(t) = \begin{pmatrix} \lambda_1(t) \\ \lambda_2(t) \\ \vdots \\ \lambda_n(t) \end{pmatrix}$

$$\dot{x}_i = G_i(t, u, x) , \quad i = 1, 2, \dots, n$$

$$\delta \dot{x}_i = \delta G_i = \sum_{j=1}^n \frac{\partial G_i}{\partial x_j} \delta x_j + \sum_{k=1}^m \frac{\partial G_i}{\partial u_k} \delta u_k$$

$$\sum_{i=1}^n \lambda_i(t) \delta \dot{x}_i(t) = \sum_{i=1}^n \left(\sum_{j=1}^n \lambda_i \frac{\partial G_i}{\partial x_j} \delta x_j + \sum_{k=1}^m \lambda_i \frac{\partial G_i}{\partial u_k} \delta u_k \right)$$

$$\delta I + (\quad) = 0$$

Einstein summation notation (repeated indices)

$$\int_{t_1}^{t_2} \left(\frac{\partial F}{\partial x_j} \delta x_j + \frac{\partial F}{\partial u_k} \delta u_k + \lambda_i \delta \dot{x}_i - \lambda_i \frac{\partial G_i}{\partial x_j} \delta x_j - \lambda_i \frac{\partial G_i}{\partial u_k} \delta u_k \right) dt = 0$$

integrate by parts

$$[\lambda_i \delta x_i]_{t_1}^{t_2} + \int_{t_1}^{t_2} \left(\left[\frac{\partial F}{\partial x_j} - \lambda_i \frac{\partial G_i}{\partial x_j} \right] \delta x_j + \left(\frac{\partial F}{\partial u_k} - \lambda_i \frac{\partial G_i}{\partial u_k} \right) \delta u_k \right) dt = 0$$

$\Rightarrow \delta x_i(t_1) = 0 , \lambda_i(t_2) = 0$, natural boundary conditions

System

$$\left\{ \begin{array}{l} \frac{\partial F}{\partial x_j} - \sum_{i=1}^n \lambda_i \frac{\partial G_i}{\partial x_j} - \dot{\lambda}_j = 0 \quad j = 0, 1, 2, \dots, n \\ \frac{\partial F}{\partial u_k} - \sum_{i=1}^n \lambda_i \frac{\partial G_i}{\partial u_k} = 0 \quad k = 1, 2, \dots, m \\ x(t_1) = x^{(0)} \\ \lambda(t_2) = 0 \end{array} \right.$$

Rayleigh-Ritz Method

Solve $Ly = F$, $a < x < b$, $Ly = (Py')' - Py$

The eigenfunctions are ϕ_n

Approximate $y_n = c_1 \phi_1 + \dots + c_n \phi_n = \sum_{k=1}^n c_k \phi_k$

Suppose $y_n \rightarrow y$

variational formulation:

$$\int_a^b (Ly - F) \delta y \, dx = 0$$

$$\Rightarrow \int (Ly - F)(\phi_1 \delta c_1 + \phi_2 \delta c_2 + \dots + \phi_n \delta c_n) \, dx = 0$$

~~$\int (\sum c_k L \phi_k - F) \delta y \, dx = 0$~~

$$\Rightarrow \int \left(\sum c_k L \phi_k - F \right) (\phi_1 \delta c_1 + \dots + \phi_n \delta c_n) \, dx = 0$$

for each term

$$\int (\sum c_k L \phi_k - F) \phi_j \, dx = 0, \quad j = 1, 2, \dots, n$$

what has been minimized is $\int (Ly - F) \, dx$

Galerkin method

impose from the beginning: $y_n = \sum_{k=1}^n c_k \phi_k$

choose c_k such that $\int (Ly_n - F) \phi_k \, dx = 0, \quad k = 1, \dots, n$

ϕ_k forms an orthogonal set "weak formulation" of the solution

If the trial functions $\{\phi_n\}$ are complete as $n \rightarrow \infty$
 the Galerkin approximation converges in the weak sense
 to the solution of $Ly = F$.

Keener, section 5.3 : Approximate Methods, Review

Example pg 196

Solve $v' = v$ on $[0, 1]$ with $v(0) = a$ by

$$\text{minimizing } F(v, v') = \int_0^1 (v' - v)^2 dx$$

$$\text{assume } v = B_0 + B_1 x + B_2 x^2$$

$$v(0) = a \Rightarrow B_0 = a \Rightarrow v = a + B_1 x + B_2 x^2$$

$$\begin{aligned} F(v, v') &= \int_0^1 (B_1 + 2B_2 x - a - B_1 x - B_2 x^2)^2 dx \\ &= \int_0^1 ((B_1 - a) + (2B_2 - B_1)x - B_2 x^2)^2 dx \end{aligned}$$

$$F(v, v') = \int_0^1 \left\{ (B_1 - a)^2 + (2B_2 - B_1)^2 x^2 + B_2^2 x^4 + 2(B_1 - a)(2B_2 - B_1)x \right. \\ \left. + 2(B_1 - a)(-B_2 x^2) + 2(2B_2 - B_1)x(-B_2 x^2) \right\} dx$$

$$F(v, v') = \int_0^1 \left\{ (B_1 - a)^2 + (2B_2 - B_1)^2 x^2 + B_2^2 x^4 + 2(2B_1 B_2 - B_1^2 - 2a B_2 + a B_1)x \right. \\ \left. - 2(B_1 - a)B_2 x^2 - 2(2B_2 - B_1)B_2 x^3 \right\} dx$$

$$F(v, v') = (B_1 - a)^2 + \frac{1}{3}(2B_2 - B_1)^2 + \frac{B_2^2}{5} + (2B_1 B_2 - B_1^2 - 2a B_2 + a B_1) - \frac{2}{3}(B_1 - a)B_2 - \frac{1}{2}(2B_2 - B_1)B_2$$

$$\frac{\partial F}{\partial B_1} = 2(B_1 - a) - \frac{2}{3}(B_2 - B_1) + 2B_2 - 2B_1 + a - \frac{2}{3}B_2 + \frac{B_2}{2} = \frac{2}{3}B_1 - \frac{4}{3}B_2 + 2B_2 - \frac{2}{3}B_2 + \frac{B_2}{2} - a$$

$$\frac{\partial F}{\partial B_1} = 0 \Rightarrow \boxed{\frac{2}{3}B_1 + \frac{B_2}{2} = a}$$

$$\frac{\partial F}{\partial B_2} = \frac{2}{3}(2B_2 - B_1)(2) + \frac{2}{5}B_2 + 2B_1 - 2a - \frac{2}{3}(B_1 - a) - B_2 - \frac{1}{2}(2B_2 - B_1)$$

$$= B_1 \left(-\frac{4}{3} + 2 - \frac{2}{3} + \frac{1}{2} \right) + B_2 \left(\frac{8}{3} + \frac{2}{5} - 1 - 1 \right) + a \left(-2 + \frac{2}{3} \right) = \frac{B_1}{2} + \frac{16}{15}B_2 - \frac{4}{3}a$$

$$\frac{\partial F}{\partial B_2} = 0 \Rightarrow \boxed{\frac{B_1}{2} + \frac{16}{15}B_2 = \frac{4}{3}a}$$

$$\frac{\partial F}{\partial B_1} = 0 \Rightarrow \left[\begin{array}{l} \frac{2}{3} B_1 + \frac{B_2}{2} = a \\ \frac{B_1}{2} + \frac{16}{15} B_2 = \frac{4}{3} a \end{array} \right]$$

$$\begin{aligned} 4B_1 + 3B_2 &= 6a \\ 15B_1 + 32B_2 &= 40a \end{aligned} \Rightarrow \begin{aligned} 60B_1 + 45B_2 &= 90a \\ 60B_1 + 128B_2 &= 160a \end{aligned} \Rightarrow 83B_2 = 70a \Rightarrow B_2 = \frac{70}{83}a$$

$$B_1 = \frac{3}{2}a - \frac{3}{4}B_2 = \left(\frac{3}{2} - \frac{3}{4}\left(\frac{70}{83}\right)\right)a = \left(\frac{249}{2 \cdot 83} - \frac{105}{2 \cdot 83}\right)a = \frac{144}{2 \cdot 83}a = \frac{72}{83}a$$

$$\Rightarrow \boxed{B_1 = \frac{72}{83}a, B_2 = \frac{70}{83}a}$$

$$v(x) = a + B_1 x + B_2 x^2$$

$$v(x) = a + \frac{72}{83}ax + \frac{70}{83}ax^2$$

$$\boxed{v(x) = \frac{a}{83}(83 + 72x + 70x^2), x \in [0,1]}$$

Least squares approximation
of exact solution $u(x) = ae^x$ on $[0, 1]$

to $u' = u$, $u(0) = a$

~~Interpolation~~ is an orthonormalize the basis $(1, x, x^2)$
using Gram Schmidt method:

$$\boxed{e_1 = 1}$$

$$\tilde{e}_2 = x - \langle x, 1 \rangle = x - \frac{1}{2}, \quad \langle x, 1 \rangle = \int_0^1 x dx = \left[\frac{x^2}{2} \right]_0^1 = \frac{1}{2}$$

$$\|\tilde{e}_2\| = \sqrt{\langle \tilde{e}_2, \tilde{e}_2 \rangle} = \sqrt{\int_0^1 \left(x - \frac{1}{2}\right)^2 dx} = \sqrt{\int_0^1 \left(x^2 - x + \frac{1}{4}\right) dx} = \sqrt{\left[\frac{x^3}{3} - \frac{x^2}{2} + \frac{x}{4} \right]_0^1} \\ = \sqrt{\frac{1}{3} - \frac{1}{2} + \frac{1}{4}} = \sqrt{\frac{1}{12}} = \frac{1}{2\sqrt{3}}$$

$$\Rightarrow \boxed{e_2 = \frac{\tilde{e}_2}{\|\tilde{e}_2\|} = 2\sqrt{3}\left(x - \frac{1}{2}\right)}$$

$$\tilde{e}_3 = x^2 - \langle x^2, 1 \rangle - \langle x^2, 2\sqrt{3}\left(x - \frac{1}{2}\right) \rangle \left(x - \frac{1}{2}\right) 2\sqrt{3}$$

$$\langle x^2, 1 \rangle = \int_0^1 x^2 dx = \frac{1}{3}$$

$$\langle x^2, 2\sqrt{3}\left(x - \frac{1}{2}\right) \rangle = 2\sqrt{3} \int_0^1 x^2 \left(x - \frac{1}{2}\right) dx = 2\sqrt{3} \int_0^1 \left(x^3 - \frac{x^2}{2}\right) dx = 2\sqrt{3} \left[\frac{x^4}{4} - \frac{x^3}{6} \right]_0^1 = \frac{\sqrt{3}}{6}$$

$$\Rightarrow \tilde{e}_3 = x^2 - \frac{1}{3} - \left(x - \frac{1}{2}\right) \left(2\sqrt{3}\right) \frac{\sqrt{3}}{6} = x^2 - x + \frac{1}{6}$$

$$\|\tilde{e}_3\| = \sqrt{\langle \tilde{e}_3, \tilde{e}_3 \rangle} = \sqrt{\int_0^1 \left(x^2 - x + \frac{1}{6}\right)^2 dx} = \sqrt{\int_0^1 \left(x^4 - 2x^3 + \frac{4}{3}x^2 - \frac{x}{3} + \frac{1}{36}\right) dx} \\ = \sqrt{\frac{1}{5} - \frac{1}{2} + \frac{4}{9} - \frac{1}{6} + \frac{1}{36}} = \sqrt{\frac{1}{5} + \frac{-18+16-6+1}{36}} = \sqrt{\frac{1}{5} - \frac{7}{36}} = \sqrt{\frac{1}{680}} = \frac{1}{6\sqrt{5}}$$

$$\Rightarrow \boxed{e_3 = \frac{\tilde{e}_3}{\|\tilde{e}_3\|} = 6\sqrt{5}\left(x^2 - x + \frac{1}{6}\right)}$$

If (e_1, \dots, e_n) is an orthonormal basis of a vector space V

then for all $w \in V$, $w = \langle w, e_1 \rangle e_1 + \dots + \langle w, e_n \rangle e_n$.

If $w = ae^x$

$$\Rightarrow w = \langle ae^x, 1 \rangle + \langle ae^x, 2\sqrt{3}(x - \frac{1}{2}) \rangle + 2\sqrt{3}(x - \frac{1}{2}) + \langle ae^x, 6\sqrt{5}(x^2 - x + \frac{1}{6}) \rangle + 6\sqrt{5}(x^2 - x + \frac{1}{6})$$

$$w = a \langle e^x, 1 \rangle + a \langle e^x, x - \frac{1}{2} \rangle (12x - 6) + a \langle e^x, x^2 - x + \frac{1}{6} \rangle (180(x^2 - x + \frac{1}{6}))$$

$$\text{Note: } \int_0^1 xe^x - x e^x \Big|_0^1 - \int_0^1 e^x dx = e - (e - 1) = 1$$

$$\int_0^1 x^2 e^x dx - x^2 e^x \Big|_0^1 - \int_0^1 2xe^x dx = e - 2(1) = e - 2$$

$$\langle e^x, 1 \rangle = \int_0^1 e^x dx = e - 1$$

$$\langle e^x, x - \frac{1}{2} \rangle = \int_0^1 (xe^x - \frac{e^x}{2}) dx = 1 - (\frac{e}{2} - \frac{1}{2}) = \frac{1}{2}(3 - e)$$

$$\langle e^x, x^2 - x + \frac{1}{6} \rangle = \int_0^1 (x^2 e^x - xe^x + \frac{e^x}{6}) dx = (e - 2) - 1 + \frac{1}{6}(e - 1) = \frac{7e}{6} - 3 - \frac{1}{6} = \frac{1}{6}(7e - 19)$$

$$\Rightarrow w = a(e - 1) + \frac{a}{2}(3 - e)(12x - 6) + \frac{a}{6}(7e - 19)(180(x^2 - x + \frac{1}{6}))$$

$$w = a \left[e - 1 + (3 - e)6x - (3 - e)3 + 30(7e - 19)x^2 - 30(7e - 19)x + 5(7e - 19) \right]$$

$$w = a \left[e - 1 - 9 + 3e + (35e - 75) + 588x - 216ex + 30(7e - 19)x^2 \right]$$

$$\boxed{w = a \left(13(3e - 35) + 12(49 - 18e)x + 30(7e - 19)x^2 \right), x \in [0, 1]}$$

Approximate Methods (Keener, Cockran, Hillebrand)

Problem (Keener pg 196)

$$\text{solve } \begin{cases} v' = v \\ v(0) = a \end{cases} \quad v = ae^x$$

approximation: minimize $F(v, v') = \int_0^1 (v' - v)^2 dx$, $v(0) = a$

use quadratic polynomials

possibilities - Least squares, Taylor Polynomial

assume: $v(x) = \beta_0 + \beta_1 x + \beta_2 x^2$, $v(0) = a$

minimize: $F(\beta_0, \beta_1, \beta_2)$, take $\beta_0 = a$

$$\Rightarrow v(x) = a + \beta_1 x + \beta_2 x^2, \quad v'(x) = \beta_1 + 2\beta_2 x$$

$$F(v, v') = \int_0^1 [(a - \beta_1) + (\beta_1 - 2\beta_2)x + \beta_2 x^2]^2 dx$$

$$\downarrow \quad \text{let } \beta_1 = \alpha_1 a, \quad \beta_2 = \alpha_2 a$$

$$= a \int_0^1 [(1 - \alpha_1) + (\alpha_1 - 2\alpha_2)x + \alpha_2 x^2]^2 dx$$

MAPLE

$$\text{set } \frac{\partial F}{\partial \alpha_1} = 0 \Rightarrow \frac{1}{2} \alpha_2 + \frac{2}{3} \alpha_1 - 1 = 0$$

$$\frac{\partial F}{\partial \alpha_2} = 0 \Rightarrow \frac{16}{15} \alpha_2 + \frac{1}{2} \alpha_1 - \frac{4}{3} = 0$$

$$\Rightarrow \alpha_1 = \frac{72}{83}, \quad \alpha_2 = \frac{70}{83}$$

$$\Rightarrow v = \frac{a}{83} (83 + 72x + 70x^2)$$

text: plot of exact solution versus several polynomial approximations

$$\Rightarrow \left[2y''\delta y' \right]_0^\infty - \int_0^\infty 2y''' \delta y' dx + \left[4y'\delta y \right]_0^\infty - \int_0^\infty 4y'' \delta y dx + \int_0^\infty 2y \delta y dx - 3y(0) \delta y(0)$$

$$\Rightarrow -2y''(0) \delta y'(0) - \left[2y'' \delta y \right]_0^\infty + \int_0^\infty 2y''' \delta y dx + 4y'(0) \delta y(0) - \int_0^\infty 4y'' \delta y dx + \int_0^\infty 2y \delta y dx - 3y(0) \delta y(0)$$

$$\Rightarrow -2y''(0) \delta y'(0) + 2y'''(0) \delta y(0) + \int_0^\infty (2y''' - 4y'' + 2y) \delta y dx - 3y(0) \delta y(0) = 0 \\ + 4y'(0) \delta y(0)$$

Natural BCs:

$$-2y'''(0) \delta y(0) + 4y'(0) \delta y(0) - 3y(0) \delta y(0) = 0 \quad , \quad y''(0) = 0$$

$$\Rightarrow -2y'''(0) - 4y'(0) - 3y(0) = 0$$

$$\Rightarrow \text{Euler-Lagrange} : y''' - 2y'' + y = 0$$

$$\text{Try } y = e^{mx} \quad ; \quad m^3 - 2m^2 + 1 = 0 \rightarrow (m^2 - 1)^2 = 0$$

$$m = \pm 1, \pm i$$

$$\Rightarrow y(x) = (c_1 x + c_2) e^x + (c_3 x + c_4) e^{-x}$$

$$y, y' \rightarrow 0 \text{ as } x \rightarrow \infty \Rightarrow c_1 = 0, c_2 = 0$$

$$\text{the other two conditions fix } c_3 = \frac{c_4}{2} = c$$

An alternative way of solving for \tilde{y} is to let $y(0) = k$

$$\text{minimizing } \int_0^\infty y''^2 + 2y'^2 + y^2 dx, \quad \tilde{y} = ce^{-x}(x+2)$$

$$I(\tilde{y}) = \int_0^\infty (\tilde{y}'^2 + 2\tilde{y}^2 + \tilde{y}^2) dx = 6c^2$$

$$\text{If } y = \tilde{y} + z, \quad z(0) = 0, \quad z''(0) = 0, \quad z \neq 0$$

$$I(y) = I(\tilde{y}) + \int_0^\infty (z''^2 + 2z'^2 + z^2) dx > I(\tilde{y})$$

$-\dot{g} = 0$ except at $x=y$

For a 2nd order case

two boundary conditions must be satisfied

continuity must be satisfied

jump in 1st derivative

$$g(x,y) = \begin{cases} \frac{u_1(x) u_2(y)}{p w}, & x < y \\ \frac{u_1(y) u_2(x)}{p w}, & x > y \end{cases} \quad \text{for separated BCs}$$

u_1 satisfies left BC

u_2 satisfies right BC

$$\begin{aligned} & \left\{ \int_0^y 2y' \delta y' dx + 2y^{(1)} \delta y^{(1)} = 0 \right. \\ & \left. \int_0^y 2y'' \delta y dx + 2y^{(1)} \delta y^{(1)} = 0 \right. \\ & = \left\{ 2y' \delta y \right\}_0^y - \left\{ 2y'' \delta y \right\}_0^y + \left\{ 2y'' \delta x \delta y \right\}_0^y + 2y^{(1)} \delta y^{(1)} = 0 \\ & = 2y^{(1)} \delta y^{(1)} - 2y^{(0)} \delta y^{(0)} - \left\{ 2y'' \delta x \delta y \right\}_0^y = 0 \\ & \quad 2y^{(1)} + 2y^{(0)} = 0 \\ & \quad y^{(1)} = -y^{(0)} \end{aligned}$$

$$y = 1 - \frac{1}{2}x$$

$$y^{(0)} = 0 + b = b$$

$$y^{(0)} = 0 = b$$

$$y^{(0)} = a + b = a$$

$$y^{(0)} = b = 3$$

$$a = -1$$

$$y^{(0)} = 1 - x$$

Systems of ODEs

Boyce & Diprima

Chpt 7 - linear

Chpt 9 - non linear

Autonomous Systems

$$\frac{d\vec{x}}{dt} = \vec{F}(x) \quad \text{or} \quad \frac{dx}{dt} = f(x, y)$$

$$\frac{dy}{dt} = g(x, y)$$

Linear and Autonomous

\Rightarrow constant coefficient

$$\frac{dx}{dt} = ax + by$$

$$\frac{dy}{dt} = cx + dy, \quad a, b, c, d - \text{constant}$$

$$\frac{d\vec{x}}{dt} = A\vec{x} \quad \text{so it's all about eigenvalues and eigenvectors}$$

critical point occurs where $\vec{F}(x) = \vec{0}$

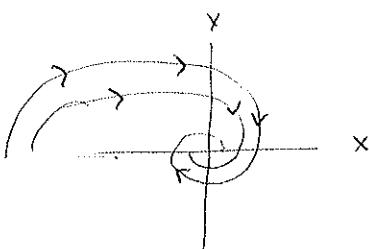
linear case implies $x = 0$

Two-dimensions; $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$

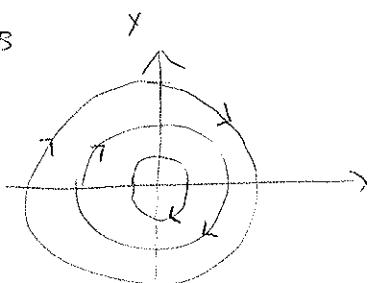
$$\begin{vmatrix} a-\lambda & b \\ c & d-\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 - (a+d)\lambda + ad - bc = 0$$

$\lambda = 0$ is NOT an eigenvalue of A

(a) spiral point: $\lambda = \alpha \pm i\beta$



(b) center: $\lambda = \pm i\beta$



General Results on Critical points

(Plane Hamiltonian systems)

Suppose (ξ, η) is the critical point.

The gradient of the Hamiltonian must be 0 there,

$$\nabla H = 0$$

$$\begin{aligned} \text{Write } H(x, y) &= H(\xi, \eta) + H_x(\xi, \eta)(x - \xi) + H_y(\xi, \eta)(y - \eta) \\ &\quad + \frac{a_{11}}{2}(x - \xi)^2 + a_{12}(x - \xi)(y - \eta) + \frac{a_{22}}{2}(y - \eta)^2 + \dots \end{aligned}$$

$$\text{where } a_{11} = H_{xx}(\xi, \eta)$$

$$a_{12} = H_{xy}(\xi, \eta) = H_{yx}(\xi, \eta)$$

$$a_{22} = H_{yy}(\xi, \eta)$$

Thus

$$\frac{\partial H}{\partial y} = a_{12}(x - \xi) + a_{22}(y - \eta) + \dots$$

$$-\frac{\partial H}{\partial x} = -[a_{11}(x - \xi) + a_{12}(y - \eta)] + \dots$$

The linearized Hamiltonian system is:

$$\frac{d}{dt} \begin{pmatrix} x - \xi \\ y - \eta \end{pmatrix} = \begin{pmatrix} a_{12} & a_{22} \\ -a_{11} & -a_{12} \end{pmatrix} \begin{pmatrix} x - \xi \\ y - \eta \end{pmatrix}$$

$$\text{The eigenvalues are } \begin{vmatrix} a_{12} - \lambda & a_{22} \\ -a_{11} & -a_{12} - \lambda \end{vmatrix} = 0$$

$$\Rightarrow \lambda^2 - a_{12}^2 + a_{11}a_{22} = 0 \Rightarrow \lambda^2 = -\det \begin{bmatrix} a_{11} & a_{12} \\ a_{12} & a_{22} \end{bmatrix}$$

Thm: A nondegenerate critical point of a smooth plane Hamiltonian system is a center if $a_{11}a_{22} - a_{12}^2 > 0$ and is a saddle point if $a_{11}a_{22} - a_{12}^2 < 0$. When $a_{11}a_{22} = a_{12}^2$, the local behavior is indeterminate.

Hopf Bifurcation

Example

system: $\dot{x} = -y - x(x^2 + y^2 - n)$
 $\dot{y} = x - y(x^2 + y^2 - n), n = \text{constant}$

linearized system about (0,0) $\dot{x} = -y + xn$
 $\dot{y} = x + yn$

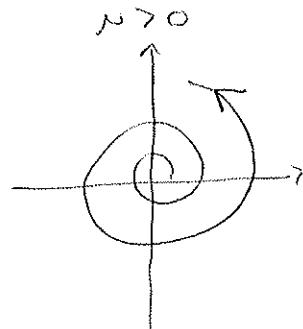
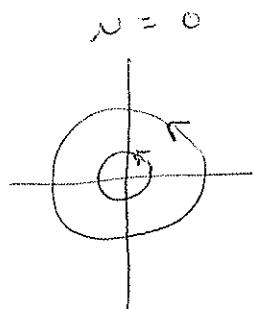
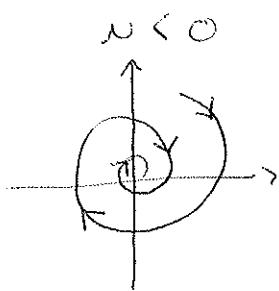
$$\Rightarrow A = \begin{pmatrix} 0 & -1 \\ 1 & n \end{pmatrix} \Rightarrow (n-\lambda)^2 = -1 \Rightarrow \lambda = n \pm i$$

If $n < 0$ then $\operatorname{Re}(\lambda) < 0$ then stable spiral

If $n = 0$ then $\operatorname{Re}(\lambda) = 0$ then center

If $n > 0$ then $\operatorname{Re}(\lambda) > 0$ then unstable spiral

"increasing n leads to instability"



This is a useful example because it can be integrated for an exact solution. Transform to polar coordinates.

$$x = r \cos \theta, y = r \sin \theta, r = r(t), \theta = \theta(t)$$

Desire a system for $r(t), \theta(t)$.

Multiply 1st eqn by x and 2nd by y .

$$x\dot{x} = -xy - x^2(x^2 + y^2 - n)$$

$$y\dot{y} = xy - y^2(x^2 + y^2 - n)$$

Add

$$x\dot{x} + y\dot{y} = -(x^2 + y^2)(x^2 + y^2 - n)$$

$$x\dot{x} + y\dot{y} = -(x^2 + y^2)(x^2 + y^2 - n)$$

$$\text{Notice } \frac{d}{dt}\left(\frac{x^2 + y^2}{2}\right) = x\dot{x} + y\dot{y}$$

$$x^2 + y^2 = r^2$$

$$\Rightarrow \frac{d}{dt}\left(\frac{r^2}{2}\right) = -r^2(r^2 - n)$$

$$\theta = \tan^{-1}\left(\frac{y}{x}\right) \Rightarrow \dot{\theta} = \frac{xy - yx'}{r^2}$$

Substitute $\dot{y} = x - y(x^2 + y^2 - n)$ and $\dot{x} = -y - x(x^2 + y^2 - n)$ into $\frac{d\theta}{dt}$

$$\Rightarrow \frac{d\theta}{dt} = \frac{x^2 - xy(x^2 + y^2 - n) + y^2 + xy(x^2 + y^2 - n)}{r^2} = \frac{r^2}{r^2} = 1$$

$$\Rightarrow \frac{d\theta}{dt} = 1 \Rightarrow \boxed{\theta = t + t_0}$$

$$\frac{d}{dt}\left(\frac{r^2}{2}\right) = -r^2(r^2 - n) \quad \text{Let } s(t) = (r(t))^2 \Rightarrow \boxed{\frac{ds}{dt} = 2s(s-n)}$$

$$\Rightarrow \boxed{\frac{ds}{dt} = -2st + 2n} \Rightarrow r \frac{dr}{dt} = -r^2(r^2 - n)$$

$$\frac{dr}{dt} = -r(r^2 - n) = -r^3 + nr \Rightarrow \cancel{\frac{dr}{dt}}$$

$$\frac{dr}{dt} = -r^3 + nr \quad \text{let } w = r^{1-n} = r^{1-3} = r^{-2}$$

$$\Downarrow \qquad \Rightarrow w = r^{-2}, \quad \dot{w} = -2r^{-3} \dot{r}$$

$$-2r^{-3} \frac{dr}{dt} = 2 - 2nr^{-2} \Rightarrow \cancel{\frac{dw}{dt}} = 2 - 2nw$$

$$\downarrow$$

$$\frac{d(r^{-2})}{dt} + 2nr^{-2} = 2 \quad \text{integrating factor: } e^{2nt}$$

$$\Rightarrow \frac{d}{dt}(e^{2nt}r^{-2}) = 2e^{2nt} \Rightarrow e^{2nt}r^{-2} = \frac{e^{2nt}}{n} + r_0$$

$$\Rightarrow r^{-2} = \frac{1}{n} + r_0 e^{-2nt} \Rightarrow \boxed{r^2 = \frac{n}{1 + nr_0 e^{2nt}}}$$

$$\theta = t + t_0, \quad r^2 = \frac{n}{1+n r_0 e^{-2n(t-t_0)}}$$

For $n > 0$

$$\text{Let } r_0 n e^{-2n(t-t_0)} = 1 \Rightarrow r = \frac{\sqrt{n}}{\sqrt{1+e^{-2n(t-t_0)}}} \quad \text{for } r_0 > N$$

notice, $r \rightarrow \sqrt{n}$ as $t \rightarrow \infty$: Limit Cycle

The limit cycle exists for $n > 0$ as well.

The ODE can be integrated when $n = 0$.

$$\text{You will find that } r(t) = \frac{1}{\sqrt{2t+C}}, \quad \theta(t) = t - t_0.$$

What about $n < 0$?

$$\text{Let } k^2 = -n > 0$$

$$\frac{ds}{dt} = -2s(k^2 + s) \quad \text{where } s(t) = r^2(t)$$

separation of variables

$$\frac{ds}{s(k^2+s)} = -2dt \Rightarrow \text{partial fractions: } \frac{1}{s(k^2+s)} = \frac{1/k^2}{s} - \frac{1/k^2}{k^2+s}$$

$$\text{integrating: } \frac{1}{k^2} \ln \left| \frac{s}{k^2+s} \right| = -2(t-t_0)$$

$$\text{exponentiate: } \frac{s}{k^2+s} = \alpha e^{-2k^2(t-t_0)}, \quad \text{where } \alpha = \pm 1 \text{ due to absolute value}$$

$$\text{solve for } s: \quad s = \frac{k^2 \alpha e^{-2k^2(t-t_0)}}{1 - \alpha e^{-2k^2(t-t_0)}} = r^2, \quad \theta = t - t_0.$$

this is a spiral, approaching origin as $t \rightarrow \infty$

As n passes through the bifurcation point $n=0$, the origin changes from a stable spiral point to an unstable spiral point and there appears a time-periodic solution (limit cycle). Hopf Bifurcation

Keener, Theorem L1.3

Suppose that for $n \times n$ matrix $A(n)$ has

eigenvalues $\lambda_1 = \lambda_1(n)$ and that for $x=x_0$,

$\lambda_1(n_0) = i\beta$, $\lambda_2(n_0) = -i\beta$ and that $\operatorname{Re}(\lambda_i) \neq 0$

for $i > 2$. Suppose Furthermore that $\operatorname{Re} \frac{d\lambda_1(n_0)}{dn} \neq 0$

then the system of differential equations $\frac{d\vec{x}}{dt} = A(n)\vec{x} + \vec{f}(\vec{x})$
 where $\vec{f}(\vec{0}) = \vec{0}$, $\vec{f}(\vec{x})$ is a smooth function of \vec{x} ,
 then \vec{x} has a branch (continuum) of period solutions
 emanating from $\vec{x} = \vec{0}$, $n = n_0$.

In the previous example :

$$A = \begin{pmatrix} n & -1 \\ 1 & n \end{pmatrix}, \quad \lambda = n \pm i$$

$$\vec{f}(\vec{x}) = \begin{pmatrix} -x(x^2 + y^2) \\ -y(x^2 + y^2) \end{pmatrix}, \quad \operatorname{Re} \frac{d\lambda}{dn} = 1 \neq 0$$

Vander Pol eqn (Nonlinear Circuit Eqn)

$$\ddot{x} + \varepsilon \dot{x}(x^2 - 1) + x = 0$$

This eqn has a limit cycle

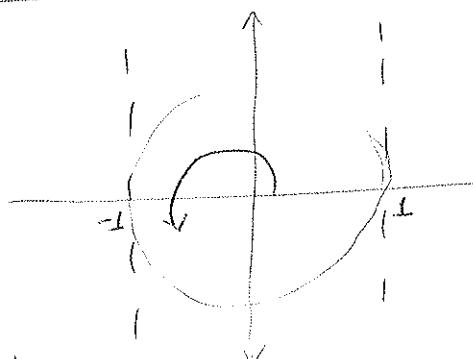
$$\text{let } \dot{x} = y$$

$$\dot{y} = -x - \varepsilon y(x^2 - 1)$$

$$\text{As before: } \frac{d}{dt} \left(\frac{x^2 + y^2}{2} \right) = -\varepsilon y^2(x^2 - 1)$$

$|x| = 1$ is a delimiter if (x_0, y_0) is inside the strip $|x| < 1$.

There is a limit cycle inside the strip.



Verhulst pg 200 (Bifurcations)

By a change of variables (dependent variables) obtain

$$\dot{v} + v(v^2 - \nu) + \nu = 0$$

Advantage: ν occurs only in the linear part, which is what Keener's Theorem "talks" about. Write this ODE as a system:

$$\dot{v} = v$$

$$\dot{v} = -v(v^2 - \nu) - \nu$$

$$\Rightarrow \frac{d}{dt} \begin{pmatrix} v \\ v \end{pmatrix} = \underbrace{\begin{bmatrix} 0 & 1 \\ -1 & \nu \end{bmatrix}}_{\text{linear}} \begin{pmatrix} v \\ v \end{pmatrix} + \underbrace{\begin{pmatrix} 0 \\ -\nu v^2 \end{pmatrix}}_{\text{non-linear}}$$

$$A = \begin{bmatrix} 0 & 1 \\ -1 & \nu \end{bmatrix} \rightarrow |A - \lambda I| = \begin{vmatrix} -\lambda & 1 \\ -1 & \nu - \lambda \end{vmatrix} \rightarrow \lambda^2 - \nu \lambda + 1 = 0$$

$$\rightarrow \lambda = \frac{\nu \pm \sqrt{\nu^2 - 4}}{2}$$

$$\text{when } \nu = 0, \lambda = \pm i$$

$$\frac{d\lambda}{d\nu} = \frac{1}{2} \pm \frac{1}{2} \frac{\nu}{\sqrt{\nu^2 - 4}} \quad \operatorname{Re}\left(\frac{d\lambda}{d\nu}\right) = \frac{1}{2} \neq 0$$

Final Exam: Amos Eaton 215
 Thursday Dec 12th
 11:30 - 2:30 pm
 open book, open notes

Past Final Problems

① Let $A^{(n \times n)}$ be a real antisymmetric matrix ($A^T = -A$).

i) Prove or disprove the assertion that every eigenvalue of A has zero real part.

ii) Show that $I-A$ is nonsingular and that $B = (I-A)^{-1}(I+A)$ is orthogonal.

iii) Example of real antisymmetric matrix

$$A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, A^T = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = -A$$

If λ is an eigenvalue and x an eigenvector then

$$Ax = \lambda x \quad \langle Ax, x \rangle = \underbrace{\langle \lambda x, x \rangle}_{\text{II}} = \lambda \langle x, x \rangle$$

Take inner product:

$$\langle x, A^* x \rangle$$

$$\underbrace{-\langle x, Ax \rangle}_{\text{II}}$$

$$\underbrace{-\langle x, \lambda x \rangle}_{\text{II}}$$

$$-\bar{\lambda} \langle x, x \rangle$$

$$\Rightarrow \lambda \langle x, x \rangle = -\bar{\lambda} \langle x, x \rangle \Rightarrow \lambda = -\bar{\lambda}$$

$$\Rightarrow \lambda + \bar{\lambda} = 0 \Rightarrow 2 \operatorname{Re}(\lambda) = 0 \Rightarrow \boxed{\operatorname{Re}(\lambda) = 0}$$

iii Show that $I-A$ is nonsingular

$$\operatorname{Re}(\lambda) = 0 \Rightarrow Ax = x \Rightarrow x = 0$$

$$\Rightarrow (I-A)x = 0 \text{ only if } x = 0$$

therefore $I-A$ is nonsingular

iv B is orthogonal if $B^{-1} = B^T$

$$BB^{-1} = BB^T = I$$

$$B = (I-A)^{-1}(I+A)$$

$(I+A)^{-1}$ exists by the same reasoning in part iii

$$\begin{aligned} B^T &= [(I-A)^{-1}(I+A)]^T \\ &= (I+A)^T((I-A)^{-1})^T \quad \text{inverse and transpose commute} \\ &= (I+A^T)(I-A^T)^{-1} \\ &= (I-A)(I+A)^{-1} \end{aligned}$$

$$\begin{aligned} BB^T &= (I-A)^{-1}(I+A)(I-A)(I+A)^{-1} \quad (I+A)(I-A) = (I-A)(I+A) \\ &= (I-A)^{-1}(I-A)(I+A)(I+A)^{-1} \\ &= I \quad \blacksquare \end{aligned}$$

Problem

Describe an orthogonal transformation that will diagonalize

$$A = \begin{bmatrix} 1 & 4 \\ 4 & 5 \end{bmatrix}$$

Problem Identify the eigenfunctions and eigenvalues of the boundary value problem

$$\left(\frac{1}{x} y'(x)\right)' + \frac{\lambda}{x} y(x) = 0, \quad 0 < x < 1$$

$$\lim_{x \rightarrow 0^+} \frac{y}{x} \text{ Finite}, \quad 2y(1) - y'(1) = 0$$

From a past assignment, $y_n = cx J_1(\sqrt{\lambda}x)$, $\lambda \neq 0$

$$\text{when } \lambda c x = 0 \Rightarrow \left(\frac{1}{x} y'(x)\right)' = 0$$

$$\Rightarrow \frac{1}{x} y'(x) = a \Rightarrow y(x) = \frac{ax^2}{2} + b$$

$$\lim_{x \rightarrow 0^+} \frac{y(x)}{x} \text{ Finite} \Rightarrow b = 0$$

$$2y(1) - y'(1) = 2\left(\frac{a}{2}\right) - a = 0 \Rightarrow \text{let } a = 2$$

then when $\lambda = 0$, ~~DK~~ $y_0(x) = x^2$

Hence applying boundary condition at $x=1$

$\sqrt{\lambda} J_0(\sqrt{\lambda}) - 2J_1(\sqrt{\lambda}) = 0$ defines the other eigenvalues.

Ques

Consider the boundary/eigenvalue problem

$$y'' + 2y' + \lambda x y = 0, \quad 0 < x < 1, \quad y(0) = y'(1) = 0$$

convert it to a Sturm-Liouville problem

- (a) convert it to a Sturm-Liouville problem
- (b) Determine the weight function $r(x)$ such that

$$\int_0^1 r(x) y_n(x) y_m(x) dx = 0$$

- (c) Prove without explicitly finding them, that all eigenvalues are real and positive.

Sturm-Liouville standard form

$$(p(x)y'(x))' + (\lambda r(x) - q(x))y(x) = 0$$

$$p(x)y''(x) + p'(x)y'(x) + (\lambda r(x) - q(x))y(x) = 0$$

$$\Rightarrow y'' + \frac{p'(x)}{p(x)}y' + \left(\lambda \frac{r(x)}{p(x)} - \frac{q(x)}{p(x)}\right)y(x) = 0$$

$$y'' + 2y' + \lambda xy = 0$$

$$\Rightarrow \frac{p'(x)}{p(x)} = 2 \Rightarrow p' = 2p \Rightarrow p = e^{2x}$$

Multiply through by e^{-2x}

$$e^{2x}y'' + 2e^{2x}y' + \lambda xy = 0$$

$$\cancel{(e^{2x}y'(x))'} + \lambda xy = 0 \Rightarrow (e^{2x}y'(x))' + (\lambda x e^{2x})y(x) = 0$$

$$\text{hence } \boxed{r(x) = x e^{2x}}$$

use complex inner product

$$\int_0^L [(e^{2x}y')'\bar{y} + \lambda x e^{2x}y\bar{y}] dx = 0$$

$$\left[e^{2x}y'\bar{y} \right]_0^L - \int_0^L e^{2x}y'\bar{y}' dx + \lambda \int_0^L x e^{2x}|y|^2 dx = 0$$

$$\text{since } y(0) = 0 \Rightarrow \bar{y}(0) = 0$$

hence BC terms drop out

$$\Rightarrow - \int_0^L e^{2x}|y'|^2 dx + \lambda \int_0^L x e^{2x}|y|^2 dx = 0$$

$$\Rightarrow \boxed{\lambda \text{ must be real}}$$

IF $\lambda = 0$ is an eigenvalue then $|y'|^2 = 0$

$$\Rightarrow y(x) = \text{constant} \quad \text{so } y(0) = 0 \Rightarrow y(x) = 0$$

so $\lambda = 0$ is NOT an eigenvalue

so we have shown that $\lambda \neq 0$

$$\Rightarrow \lambda = \frac{\int_0^1 e^{2x} |y'|^2 dx}{\int_0^1 x e^{2x} |y'|^2 dx} > 0$$

The entropy of a certain gas might be defined as

$$H = - \int_{-\infty}^{\infty} F \log F dv$$

where ~~pres~~ $F = F(v) \geq 0$ is the velocity distribution function. Writing $F = y^2$ for convenience ~~which maximizes~~ determines $F(v)$ which maximizes H for prescribed values of "density" and "temperature"

$$\int_{-\infty}^{\infty} F dv = 1, \quad \int_{-\infty}^{\infty} F v^2 dv = 1$$

$$\text{Let } F = y^2 : \quad H = - \int_{-\infty}^{\infty} y^2 \log y^2 dv = -2 \int_{-\infty}^{\infty} y^2 \log y dv$$

$$I_1 = \int_{-\infty}^{\infty} y^2 dv = 1, \quad I_2 = \int_{-\infty}^{\infty} y^2 v^2 dv = 1$$

Need two Lagrange multipliers λ_1, λ_2

$$\delta F = \delta (H + \lambda_1 I_1 + \lambda_2 I_2) = 0$$

Euler-Lagrange equations (notice: no dependence on y')

$$\frac{d}{dy} (-2y^2 \log y + \lambda_1 y^2 + \lambda_2 y^2 v^2) = 0$$

$$\Rightarrow -4y \log y - \frac{2y^2}{y} + 2\lambda_1 y + 2\lambda_2 y v^2 = 0$$

$$y \neq 0, \quad -4 \log y - 2 + 2\lambda_1 + 2\lambda_2 v^2 = 0$$

$$\Rightarrow \log y = -\frac{1}{2} + \frac{\lambda_1}{2} + \frac{\lambda_2}{2} v^2$$

$$\Rightarrow y = e^{\left(-\frac{1}{2} + \frac{\lambda_1}{2} + \frac{\lambda_2}{2} v^2\right)}$$

The optimal function is an exponential function

$$y = e^{\left(\frac{-1}{2} + \frac{\lambda_1}{2} + \frac{\lambda_2}{2}v^2\right)}$$

We require $\int_{-\infty}^{\infty} y^2 dv = 1$ and $\int_{-\infty}^{\infty} y^2 v^2 dv = 1$

$$y^2 = e^{-1 + \lambda_1 + \lambda_2 v^2} \Rightarrow \int_{-\infty}^{\infty} e^{\lambda_1 - 1 + \lambda_2 v^2} dv = 1$$

requires $\lambda_2 = -\nu_2^2 < 0$ for convergence

$$\int_{-\infty}^{\infty} y^2 v^2 dv = \int v^2 e^{\lambda_1 - 1 - \nu_2^2 v^2} dv = 1$$

Calculate the smallest value of k^2 st

$$\int_0^1 (y')^2 dx + (y(1))^2 \geq k^2 \int_0^1 y^2 dx \quad \forall y \in C^1[0,1], y(0) = 0$$

Minimize $\frac{\int_0^1 (y')^2 dx + (y(1))^2}{\int_0^1 y^2 dx}$ where $y(0) = 0$

Euler-Lagrange

$$s \left\{ \int_0^1 (y')^2 dx + (y(1))^2 - \lambda \int_0^1 y^2 dx \right\} = 0$$

$$\Rightarrow y'' + \lambda y = 0, y'(1) + y(1) = 0, y(0) = 0$$

$$\Rightarrow y = c \sin(\sqrt{\lambda}x) = c \sin kx$$

$$\Rightarrow k \cos k + \sin k = 0 \Rightarrow k + \tan k = 0$$

