Assignment 3

Digital Signal Analysis and Applications (DSAA) - IEC 239

Deadline: 9 March

April 2, 2016

1. Implement the following functions:

- (a) create_mat_dct(), which outputs the spoint 2D-DCT basis function F. The function for computing the basis is given as: $F(v,u) = r \cos\{\frac{2\pi(2u+1)v}{2N}\}$, where $r = \sqrt{1/N}$ if v = 0 and $r = \sqrt{2/N}$, otherwise (verify your result using dctmtx() function in Matlab).
- (b) myDCT(im,F), which takes as input any given 8×8 image im and the basis matrix F. The output of this function is the DCT transformed image.
- (c) myIDCT(im,F), which computes the inverse DCT transform
- (d) myDCT_quantization(imDCT,qm,c), which takes as input the DCT transformed block imDCT, the quantization matrix qm and the compression factor c (divide image by c times the quantization matrix). Output is the quantized DCT image (imqDCT).
- (e) $myDCT_dequantization(imqDCT,qm,c)$, which de-quantizes the quantized DCT image
- (f) RMSE(im1,im2), which computes RMSE error between two images of arbitrary size
- (g) My_entropy(im), which computes the entropy of a given image (you can use the imhist() function in Matlab to do it efficiently)
- 2. Observe the DCT, quantized DCT and reconstructed image for the 8×8 subwindows extracted from the LAKE image and whose top left corners are at the coordinates: (420,45), (427,298) and (30,230). For that you will use the classical quantization matrix for luminance and c=2. Comment on the observations.
- 3. Apply the DCT transform (and quantization) to all 8×8 sub windows of the LAKE

- image and create an image with all the resulted DCT images at the same positions as their corresponding image. Comment on your observations.
- 4. Reconstruct the image. Find the highest value of c so that the distortions of the reconstructed image are just perceptible. Give the corresponding entropy and RMSE for each case (for different values of c). Explain the results obtained with c=10.
- 5. By varying the value of c, observe the evolutions of the entropy and of the RMSE. Plot entropy versus RMSE.