# Exponential Weights Algorithms for Online Learning

Yoav Freund

January 11, 2018

The Halving Algorithm

The Halving Algorithm

 ${f Hedge}(\eta) {f Algorithm}$  Hedging vs. Halving

#### The Halving Algorithm

 $Hedge(\eta)$ Algorithm Hedging vs. Halving

#### Bound on total loss

Upper bound on  $\sum_{i=1}^{N} w_i^{T+1}$ Lower bound on  $\sum_{i=1}^{N} w_i^{T+1}$ Combining Upper and Lower bounds

#### The Halving Algorithm

 ${f Hedge}(\eta) {f Algorithm}$  Hedging vs. Halving

#### Bound on total loss

Upper bound on  $\sum_{i=1}^{N} w_i^{T+1}$ Lower bound on  $\sum_{i=1}^{N} w_i^{T+1}$ Combining Upper and Lower bounds

tuning  $\eta$ 

#### The Halving Algorithm

 ${f Hedge}(\eta) {f Algorithm}$ Hedging vs. Halving

#### Bound on total loss

Upper bound on  $\sum_{i=1}^{N} w_i^{T+1}$ Lower bound on  $\sum_{i=1}^{N} w_i^{T+1}$ Combining Upper and Lower bounds

tuning  $\eta$ 

Lower Bounds

N possible actions

- N possible actions
- At each time step t = 1, 2, ..., T:

- N possible actions
- At each time step t = 1, 2, ..., T:
  - Algorithm chooses a distribution p<sup>t</sup> over actions.

- N possible actions
- At each time step t = 1, 2, ..., T:
  - Algorithm chooses a distribution p<sup>t</sup> over actions.
  - ▶ Losses  $0 \le \ell_i^t \le 1$  of all actions i = 1, ..., N are revealed.

- N possible actions
- At each time step t = 1, 2, ..., T:
  - Algorithm chooses a distribution p<sup>t</sup> over actions.
  - ▶ Losses  $0 \le \ell_i^t \le 1$  of all actions i = 1, ..., N are revealed.
  - Algorithm suffers expected loss p<sup>t</sup> · l<sup>t</sup>

- N possible actions
- At each time step t = 1, 2, ..., T:
  - Algorithm chooses a distribution p<sup>t</sup> over actions.
  - ▶ Losses  $0 \le \ell_i^t \le 1$  of all actions i = 1, ..., N are revealed.
  - ▶ Algorithm suffers **expected** loss  $\mathbf{p}^t \cdot \boldsymbol{\ell}^t$
- Goal: minimize total expected loss

- N possible actions
- At each time step t = 1, 2, ..., T:
  - Algorithm chooses a distribution p<sup>t</sup> over actions.
  - ▶ Losses  $0 \le \ell_i^t \le 1$  of all actions i = 1, ..., N are revealed.
  - ▶ Algorithm suffers expected loss p<sup>t</sup> · ℓ<sup>t</sup>
- Goal: minimize total expected loss
- Here we have stochasticity but only in algorithm, not in outcome

- N possible actions
- At each time step t = 1, 2, ..., T:
  - Algorithm chooses a distribution p<sup>t</sup> over actions.
  - ▶ Losses  $0 \le \ell_i^t \le 1$  of all actions i = 1, ..., N are revealed.
  - ▶ Algorithm suffers expected loss p<sup>t</sup> · ℓ<sup>t</sup>
- Goal: minimize total expected loss
- Here we have stochasticity but only in algorithm, not in outcome
- Fits nicely in game theory

Like halving - we want to zoom into best action (expert).

- Like halving we want to zoom into best action (expert).
- Unlike halving no action is perfect.

#### Hedging vs. Halving

- Like halving we want to zoom into best action (expert).
- Unlike halving no action is perfect.
- Basic idea reduce probability of lossy actions, but not all the way to zero.

- Like halving we want to zoom into best action (expert).
- Unlike halving no action is perfect.
- Basic idea reduce probability of lossy actions, but not all the way to zero.
- Modified Goal: minimize difference between expected total loss and minimal total loss of repeating one action.

$$\sum_{t=1}^{T} \mathbf{p}^{t} \cdot \ell^{t} - \min_{i} \left( \sum_{t=1}^{T} \ell_{i}^{t} \right)$$

Suppose that there is no perfect expert.

- Suppose that there is no perfect expert.
- action i = use prediction of expert i

- Suppose that there is no perfect expert.
- action i = use prediction of expert i
- Now each iteration of game consistst of three steps:

- Suppose that there is no perfect expert.
- action i = use prediction of expert i
- Now each iteration of game consistst of three steps:
  - ▶ Experts make predictions  $e_i^t \in \{0, 1\}$

- Suppose that there is no perfect expert.
- action i = use prediction of expert i
- Now each iteration of game consistst of three steps:
  - ▶ Experts make predictions  $e_i^t \in \{0, 1\}$
  - ► Algorithm predicts 1 with probability  $\sum_{i:e^t=1} p_i^t$ .

- Suppose that there is no perfect expert.
- action i = use prediction of expert i
- Now each iteration of game consistst of three steps:
  - ▶ Experts make predictions  $e_i^t \in \{0, 1\}$
  - ▶ Algorithm predicts 1 with probability  $\sum_{i:e_i^t=1} p_i^t$ .
  - outcome  $o_i^t$  is revealed.  $\ell_i^t = 0$  if  $e_i^t = o_i^t$ ,  $\ell_i^t = 1$  otherwise.

Consider action i at time t

► Total loss:

$$L_i^t = \sum_{s=1}^{t-1} \ell_i^s$$

Consider action *i* at time *t* 

► Total loss:

$$L_i^t = \sum_{s=1}^{t-1} \ell_i^s$$

Weight:

$$\mathbf{w}_i^t = \mathbf{w}_i^1 \mathbf{e}^{-\eta L_i^t}$$

Consider action *i* at time *t* 

► Total loss:

$$L_i^t = \sum_{s=1}^{t-1} \ell_i^s$$

Weight:

$$w_i^t = w_i^1 e^{-\eta L_i^t}$$

Note freedom to choose initial weight  $(w_i^1) \sum_{i=1}^n w_i^1 = 1$ .

▶  $\eta > 0$  is the learning rate parameter. Halving:  $\eta \to \infty$ 

Consider action *i* at time *t* 

► Total loss:

$$L_i^t = \sum_{s=1}^{t-1} \ell_i^s$$

Weight:

$$w_i^t = w_i^1 e^{-\eta L_i^t}$$

- ▶  $\eta$  > 0 is the learning rate parameter. Halving:  $\eta \to \infty$
- Probability:

$$p_i^t = \frac{w_i^t}{\sum_{i=1}^N w_i^t},$$

Consider action *i* at time *t* 

► Total loss:

$$L_i^t = \sum_{s=1}^{t-1} \ell_i^s$$

Weight:

$$w_i^t = w_i^1 e^{-\eta L_i^t}$$

- ▶  $\eta$  > 0 is the learning rate parameter. Halving:  $\eta \to \infty$
- Probability:

$$p_i^t = \frac{w_i^t}{\sum_{i=1}^N w_i^t},$$

Consider action *i* at time *t* 

► Total loss:

$$L_i^t = \sum_{s=1}^{t-1} \ell_i^s$$

Weight:

$$w_i^t = w_i^1 e^{-\eta L_i^t}$$

- ▶  $\eta > 0$  is the learning rate parameter. Halving:  $\eta \to \infty$
- Probability:

$$p_i^t = rac{w_i^t}{\sum_{j=1}^N w_i^t}, \ \mathbf{p}^t = rac{\mathbf{w}^t}{\sum_{j=1}^N w_i^t}$$

Giving an action high initial weight makes alg perform well if that action performs well.

- Giving an action high initial weight makes alg perform well if that action performs well.
- If good action has low initial weight, our total loss will be larger.

- Giving an action high initial weight makes alg perform well if that action performs well.
- If good action has low initial weight, our total loss will be larger.
- As  $\sum_{i=1}^{n} w_i^1 = 1$  increasing one weight implies decreasing some others.

- Giving an action high initial weight makes alg perform well if that action performs well.
- If good action has low initial weight, our total loss will be larger.
- As  $\sum_{i=1}^{n} w_i^1 = 1$  increasing one weight implies decreasing some others.
- Plays a similar role to prior distribution in Bayesian algorithms.

## Bound on the loss of $Hedge(\eta)$ Algorithm

#### Bound on the loss of $Hedge(\eta)$ Algorithm

Theorem (main theorem)
For any sequence of loss vectors ℓ¹,...,ℓ<sup>T</sup>, and for any
i ∈ {1,...,N}, we have

$$L_{\mathsf{Hedge}(\eta)} \leq \frac{-\mathsf{In}(w_i^1) + \eta L_i}{1 - e^{-\eta}}.$$

## Bound on the loss of **Hedge**( $\eta$ )Algorithm

Theorem (main theorem)
For any sequence of loss vectors ℓ¹,...,ℓ<sup>T</sup>, and for any
i ∈ {1,...,N}, we have

$$L_{\mathsf{Hedge}(\eta)} \leq rac{-\ln(w_i^1) + \eta L_i}{1 - e^{-\eta}}.$$

► Proof: by combining upper and lower bounds on  $\sum_{i=1}^{N} w_i^{T+1}$ 

# Upper bound on $\sum_{i=1}^{N} w_i^{T+1}$

Lemma (upper bound)

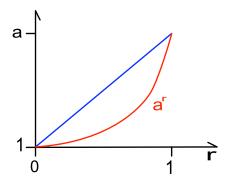
For any sequence of loss vectors  $\ell^1, \dots, \ell^T$  we have

$$\ln\left(\sum_{i=1}^N w_i^{T+1}\right) \leq -(1-e^{-\eta})L_{\mathsf{Hedge}(\eta)}.$$

▶ If  $a \ge 0$  then  $a^r$  is convex.

- If a > 0 then  $a^r$  is convex.
- ► For  $r \in [0, 1]$ ,  $a^r \le 1 (1 a)r$

- If a > 0 then  $a^r$  is convex.
- ► For  $r \in [0, 1]$ ,  $a^r \le 1 (1 a)r$



Upper bound on  $\sum_{i=1}^{N} w_i^{T+1}$ 

## Proof of upper bound (slide 2)

Applying 
$$a^r \le 1 - (1 - a)^r$$
 where  $a = e^{-\eta}, r = \ell_i^t$ 

$$\sum_{i=1}^{N} w_i^{t+1} = \sum_{i=1}^{N} w_i^t e^{-\eta \ell_i^t}$$

Applying 
$$a^r \le 1 - (1 - a)^r$$
 where  $a = e^{-\eta}, r = \ell_i^t$ 

$$\sum_{i=1}^{N} w_i^{t+1} = \sum_{i=1}^{N} w_i^t e^{-\eta \ell_i^t}$$

$$\leq \sum_{i=1}^{N} w_i^t \left( 1 - (1 - e^{-\eta}) \ell_i^t \right)$$

Applying 
$$a^r \le 1 - (1 - a)^r$$
 where  $a = e^{-\eta}, r = \ell_i^t$ 

$$\sum_{i=1}^{N} w_i^{t+1} = \sum_{i=1}^{N} w_i^t e^{-\eta \ell_i^t} 
\leq \sum_{i=1}^{N} w_i^t \left( 1 - (1 - e^{-\eta}) \ell_i^t \right) 
= \left( \sum_{i=1}^{N} w_i^t \right) \left( 1 - (1 - e^{-\eta}) \frac{\mathbf{w}^t}{\sum_{i=1}^{N} w_i^t} \cdot \ell^t \right)$$

Applying  $a^r \le 1 - (1 - a)^r$  where  $a = e^{-\eta}, r = \ell_i^t$ 

$$\sum_{i=1}^{N} w_i^{t+1} = \sum_{i=1}^{N} w_i^t e^{-\eta \ell_i^t} 
\leq \sum_{i=1}^{N} w_i^t \left( 1 - (1 - e^{-\eta}) \ell_i^t \right) 
= \left( \sum_{i=1}^{N} w_i^t \right) \left( 1 - (1 - e^{-\eta}) \frac{\mathbf{w}^t}{\sum_{i=1}^{N} w_i^t} \cdot \ell^t \right) 
= \left( \sum_{i=1}^{N} w_i^t \right) \left( 1 - (1 - e^{-\eta}) \mathbf{p}^t \cdot \ell^t \right)$$

$$\sum_{i=1}^{N} w_i^{t+1} \le \left(\sum_{i=1}^{N} w_i^{t}\right) \left(1 - (1 - e^{-\eta}) \mathbf{p}^{t} \cdot \ell^{t}\right)$$

Combining

$$\sum_{i=1}^N w_i^{t+1} \leq \left(\sum_{i=1}^N w_i^t\right) \left(1 - (1 - e^{-\eta}) \mathbf{p}^t \cdot \ell^t\right)$$

 $\blacktriangleright$  for  $t=1,\ldots,T$ 

$$\sum_{i=1}^{N} w_i^{t+1} \leq \left(\sum_{i=1}^{N} w_i^t\right) \left(1 - (1 - e^{-\eta})\mathbf{p}^t \cdot \ell^t\right)$$

- ightharpoonup for  $t = 1, \dots, T$
- yields

$$\sum_{i=1}^{N} w_i^{T+1} \leq \prod_{t=1}^{T} (1 - (1 - e^{-\eta}) \mathbf{p}^t \cdot \ell^t)$$

$$\sum_{i=1}^{N} w_i^{t+1} \leq \left(\sum_{i=1}^{N} w_i^t\right) \left(1 - (1 - e^{-\eta})\mathbf{p}^t \cdot \ell^t\right)$$

- ightharpoonup for  $t = 1, \dots, T$
- yields

$$\sum_{i=1}^{N} w_i^{T+1} \leq \prod_{t=1}^{T} (1 - (1 - e^{-\eta}) \mathbf{p}^t \cdot \ell^t)$$

$$\sum_{i=1}^N w_i^{t+1} \leq \left(\sum_{i=1}^N w_i^t\right) \left(1 - (1 - e^{-\eta})\mathbf{p}^t \cdot \ell^t\right)$$

- ightharpoonup for  $t = 1, \dots, T$
- yields

$$\sum_{i=1}^{N} w_i^{T+1} \leq \prod_{t=1}^{I} (1 - (1 - e^{-\eta}) \mathbf{p}^t \cdot \ell^t)$$

$$\leq \exp \left( -(1 - e^{-\eta}) \sum_{t=1}^{T} \mathbf{p}^t \cdot \ell^t \right)$$

since 
$$1 + x \le e^x$$
 for  $x = -(1 - e^{-\eta})$ .

# Lower bound on $\sum_{i=1}^{N} w_i^{T+1}$

For any 
$$j = 1, \ldots, N$$
:

$$\sum_{i=1}^{N} w_i^{T+1} \ge w_j^{T+1} = w_j^{1} e^{-\eta L_j}$$

## Combining Upper and Lower bounds

► Combining bounds on  $\ln \left( \sum_{i=1}^{N} w_i^{T+1} \right)$ 

$$\ln w_j^1 - \eta L_j \le \ln \sum_{i=1}^N w_i^{T+1} \le -(1 - e^{-\eta}) \sum_{t=1}^T \mathbf{p}^t \cdot \ell^t$$

## Combining Upper and Lower bounds

► Combining bounds on  $\ln \left( \sum_{i=1}^{N} w_i^{T+1} \right)$ 

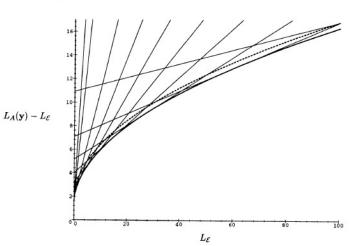
$$\ln w_j^1 - \eta L_j \le \ln \sum_{i=1}^N w_i^{T+1} \le -(1 - e^{-\eta}) \sum_{t=1}^T \mathbf{p}^t \cdot \ell^t$$

► Reversing signs, using  $L_{\text{Hedge}(\eta)} = \sum_{t=1}^{T} \mathbf{p}^t \cdot \boldsymbol{\ell}^t$  and reorganizing we get

$$L_{\mathsf{Hedge}(\eta)} \leq \frac{-\ln(w_i^1) + \eta L_i}{1 - e^{-\eta}}$$

How to Use Expert Advice

451



▶ Suppose  $\min_i L_i \leq \tilde{L}$ 

- ▶ Suppose  $\min_i L_i \leq \tilde{L}$
- set

$$\eta = \ln\left(1 + \sqrt{\frac{2\ln N}{\tilde{L}}}\right) \approx \sqrt{\frac{2\ln N}{\tilde{L}}}$$

- ▶ Suppose  $\min_i L_i \leq \tilde{L}$
- set

$$\eta = \ln\left(1 + \sqrt{\frac{2 \ln N}{\tilde{L}}}\right) \approx \sqrt{\frac{2 \ln N}{\tilde{L}}}$$

▶ use uniform initial weights  $\mathbf{w}^1 = \langle 1/N, \dots, 1/N \rangle$ 

- ► Suppose  $\min_i L_i \leq \tilde{L}$
- set

$$\eta = \ln\left(1 + \sqrt{\frac{2 \ln N}{\tilde{L}}}\right) \approx \sqrt{\frac{2 \ln N}{\tilde{L}}}$$

- ▶ use uniform initial weights  $\mathbf{w}^1 = \langle 1/N, \dots, 1/N \rangle$
- Then

$$L_{\mathsf{Hedge}(\eta)} \leq \frac{-\ln(w_i^1) + \eta L_i}{1 - e^{-\eta}} \leq \min_i L_i + \sqrt{2\tilde{L} \ln N} + \ln N$$

### Tuning $\eta$ as a function of T

▶ trivially  $\min_i L_i \leq T$ , yielding

$$L_{\mathsf{Hedge}(\eta)} \leq \min_i L_i + \sqrt{2T \ln N} + \ln N$$

### Tuning $\eta$ as a function of T

▶ trivially  $\min_i L_i \leq T$ , yielding

$$L_{\mathsf{Hedge}(\eta)} \leq \min_i L_i + \sqrt{2T \ln N} + \ln N$$

per iteration we get:

$$\frac{L_{\mathsf{Hedge}(\eta)}}{T} \leq \min_{i} \frac{L_{i}}{T} + \sqrt{\frac{2 \ln N}{T}} + \frac{\ln N}{T}$$

## How good is this bound?

Very good! There is a closely matching lower bound!

#### How good is this bound?

- Very good! There is a closely matching lower bound!
- There exists a stochastic adversarial strategy such that with high probability for any hedging strategy S after T trials

$$L_S - \min_i L_i \geq (1 - o(1))\sqrt{2T \ln N}$$

## How good is this bound?

- Very good! There is a closely matching lower bound!
- There exists a stochastic adversarial strategy such that with high probability for any hedging strategy S after T trials

$$L_{S} - \min_{i} L_{i} \geq (1 - o(1))\sqrt{2T \ln N}$$

The adversarial strategy is random, extremely simple, and does not depend on the hedging strategy!

Adversary sets each loss  $\ell_i^t$  indepedently at random to 0 or 1 with equal probabilities (1/2, 1/2).

- Adversary sets each loss  $\ell_i^t$  indepedently at random to 0 or 1 with equal probabilities (1/2, 1/2).
- ► Obviously, nothing to learn !  $L_S \approx T/2$ .

- Adversary sets each loss  $\ell_i^t$  independently at random to 0 or 1 with equal probabilities (1/2, 1/2).
- ► Obviously, nothing to learn!  $L_S \approx T/2$ .
- ▶ On the other hand  $\min_i L_i \approx T/2 \sqrt{2T \ln N}$

- Adversary sets each loss  $\ell_i^t$  independently at random to 0 or 1 with equal probabilities (1/2, 1/2).
- ▶ Obviously, nothing to learn !  $L_S \approx T/2$ .
- ▶ On the other hand  $\min_i L_i \approx T/2 \sqrt{2T \ln N}$
- ► The difference L<sub>S</sub> min<sub>i</sub> L<sub>i</sub> is due to unlearnable random fluctuations!

- Adversary sets each loss  $\ell_i^t$  independently at random to 0 or 1 with equal probabilities (1/2, 1/2).
- ▶ Obviously, nothing to learn !  $L_S \approx T/2$ .
- ▶ On the other hand  $\min_i L_i \approx T/2 \sqrt{2T \ln N}$
- ► The difference L<sub>S</sub> min<sub>i</sub> L<sub>i</sub> is due to unlearnable random fluctuations!
- Detailed proof quite involved. See games paper.

#### Summary

▶ Given learning rate  $\eta$  the **Hedge**( $\eta$ )algorithm satisfies

$$L_{\mathsf{Hedge}(\eta)} \leq rac{\ln N + \eta L_i}{1 - e^{-\eta}}$$

#### **Summary**

▶ Given learning rate  $\eta$  the **Hedge**( $\eta$ )algorithm satisfies

$$L_{\mathsf{Hedge}(\eta)} \leq rac{\ln N + \eta L_i}{1 - e^{-\eta}}$$

▶ Setting  $\eta \approx \sqrt{\frac{2 \ln N}{T}}$  guarantees

$$L_{\mathsf{Hedge}(\eta)} \leq \min_i L_i + \sqrt{2T \ln N} + \ln N$$

### Summary

▶ Given learning rate  $\eta$  the **Hedge**( $\eta$ )algorithm satisfies

$$L_{\mathsf{Hedge}(\eta)} \leq rac{\ln N + \eta L_i}{1 - e^{-\eta}}$$

▶ Setting  $\eta \approx \sqrt{\frac{2 \ln N}{T}}$  guarantees

$$L_{\mathsf{Hedge}(\eta)} \leq \min_i L_i + \sqrt{2T \ln N} + \ln N$$

► A trivial random data, in which there is nothing to be learned forces any algorithm to suffer this total loss

Total Loss of best action usually scales linearly with time T, but we need to know the horizon T ahead of time to choose η correctly.

- Total Loss of best action usually scales linearly with time T, but we need to know the horizon T ahead of time to choose η correctly.
- T is tight only when the loss of experts at each iteration is either 0 or 1. If the loss of the best expert is o(T) then we would like to have a tighter bound.

- Total Loss of best action usually scales linearly with time T, but we need to know the horizon T ahead of time to choose η correctly.
- T is tight only when the loss of experts at each iteration is either 0 or 1. If the loss of the best expert is o(T) then we would like to have a tighter bound.
- Observing only the loss of chosen action the multi-armed bandit problem. Will get to that later in the course.

- Total Loss of best action usually scales linearly with time T, but we need to know the horizon T ahead of time to choose η correctly.
- T is tight only when the loss of experts at each iteration is either 0 or 1. If the loss of the best expert is o(T) then we would like to have a tighter bound.
- Observing only the loss of chosen action the multi-armed bandit problem. Will get to that later in the course.
- Register to the class on the google drive.