Introduction to Online Learning Algorithms

Yoav Freund

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Outline

expert1

expert2

expert3

expert4

expert5

expert6

expert7

expert8

alg.

```
expert1
```

expert2

expert3

expert4

expert5

expert6

expert7

expert8

alg.

outcome

```
t = 1
expert1
expert2
expert3
expert4
expert5
expert6
expert7
expert8
alg.
```

alg. outcome Halving Algorithm

```
t = 1
expert1
expert2
expert3
expert4
expert5
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expert7
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alg.
outcome
```

```
t = 1
expert1
expert2
expert3
expert4
expert5
expert6
expert7
expert8
alg.
outcome
```

```
t = 1 t = 2
expert1
expert2
expert3
expert4
expert5
expert6
expert7
expert8
alg.
outcome
```

	t = 1	<i>t</i> = 2
expert1	1	1
expert2	1	0
expert3	0	-
expert4	1	0
expert5	1	0
expert6	0	-
expert7	1	1
expert8	1	1
alg.	1	0
outcome	1	

	t = 1	<i>t</i> = 2
expert1	1	1
expert2	1	0
expert3	0	-
expert4	1	0
expert5	1	0
expert6	0	-
expert7	1	1
expert8	1	1
alg.	1	0
outcome	1	1

```
t = 1 t = 2 t = 3
expert1
expert2
expert3
expert4
expert5
expert6
expert7
expert8
alg.
outcome
```

	t = 1	<i>t</i> = 2	<i>t</i> = 3
expert1	1	1	1
expert2	1	0	-
expert3	0	-	-
expert4	1	0	-
expert5	1	0	-
expert6	0	-	-
expert7	1	1	1
expert8	1	1	1
alg.	1	0	1
outcome	1	1	

	t = 1	<i>t</i> = 2	<i>t</i> = 3
expert1	1	1	1
expert2	1	0	-
expert3	0	-	-
expert4	1	0	-
expert5	1	0	-
expert6	0	-	-
expert7	1	1	1
expert8	1	1	1
alg.	1	0	1
outcome	1	1	1

	t = 1	t = 2	t = 3	t = 4
expert1	1	1	1	1
expert2	1	0	-	-
expert3	0	-	-	-
expert4	1	0	-	-
expert5	1	0	-	-
expert6	0	-	-	-
expert7	1	1	1	1
expert8	1	1	1	0
alg.	1	0	1	
outcome	1	1	1	

	t = 1	<i>t</i> = 2	t = 3	<i>t</i> = 4
expert1	1	1	1	1
expert2	1	0	-	-
expert3	0	-	-	-
expert4	1	0	-	-
expert5	1	0	-	-
expert6	0	-	-	-
expert7	1	1	1	1
expert8	1	1	1	0
alg.	1	0	1	1
outcome	1	1	1	

	t = 1	t = 2	t = 3	<i>t</i> = 4
expert1	1	1	1	1
expert2	1	0	-	-
expert3	0	-	-	-
expert4	1	0	-	-
expert5	1	0	-	-
expert6	0	-	-	-
expert7	1	1	1	1
expert8	1	1	1	0
alg.	1	0	1	1
outcome	1	1	1	0

	t = 1	t = 2	t = 3	t = 4	<i>t</i> = 5
expert1	1	1	1	1	-
expert2	1	0	-	-	-
expert3	0	-	-	-	-
expert4	1	0	-	-	-
expert5	1	0	-	-	-
expert6	0	-	-	-	-
expert7	1	1	1	1	0
expert8	1	1	1	0	-
alg.	1	0	1	1	
outcome	1	1	1	0	

	t = 1	<i>t</i> = 2	t = 3	t = 4	<i>t</i> = 5
expert1	1	1	1	1	-
expert2	1	0	-	-	-
expert3	0	-	-	-	-
expert4	1	0	-	-	-
expert5	1	0	-	-	-
expert6	0	-	-	-	-
expert7	1	1	1	1	0
expert8	1	1	1	0	-
alg.	1	0	1	1	0
outcome	1	1	1	0	

	t = 1	<i>t</i> = 2	t = 3	t = 4	<i>t</i> = 5
expert1	1	1	1	1	-
expert2	1	0	-	-	-
expert3	0	-	-	-	-
expert4	1	0	-	-	-
expert5	1	0	-	-	-
expert6	0	-	-	-	-
expert7	1	1	1	1	0
expert8	1	1	1	0	-
alg.	1	0	1	1	0
outcome	1	1	1	0	0

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- Each time algorithm makes a mistakes, the pool of perfect experts is halved (at least).
- We assume that at least one expert is perfect.
- Number of mistakes is at most log₂ N.
- No stochastic assumptions whatsoever.
- Proof is based on combining a lower and upper bounds on the number of perfect experts.

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- Here we have stochasticity but only in algorithm, not in outcome
- Fits nicely in game theory

Hedging vs. Halving

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- Like halving we want to zoom into best action (expert).
- Unlike halving no action is perfect.
- Basic idea reduce probability of lossy actions, but not all the way to zero.
- Modified Goal: minimize difference between expected total loss and minimal total loss of repeating one action.

Consider action i at time t

Total loss:

$$L_i^t = \sum_{s=1}^{t-1} \ell_i^s$$

Consider action i at time t

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Weight:

$$W_i^t = e^{-\eta L_i^t}$$

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▶ $\eta > 0$ is the learning rate parameter. Halving: $\eta = \infty$

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Total loss:

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Weight:

$$W_i^t = e^{-\eta L_i^t}$$

- ▶ $\eta > 0$ is the learning rate parameter. Halving: $\eta = \infty$
- Probability:

$$P_i^t = \frac{W_i^t}{\sum_{i=1}^N W_i^t}$$

$$\eta = 1$$

```
\eta = 1
```

expert1 expert2 expert3 expert4 expert5 expert6 expert7 expert8

alg.

```
\eta = 1
                     \vec{W}^1
expert1
expert2
expert3
expert4
expert5
expert6
expert7
expert8
```

alg.

$\eta = 1$		
,	$ec{W}^1$	$ar{\ell}^{\dagger}$
expert1	1	.1
expert2	1	.8
expert3	1	.3
expert4	1	.1
expert5	1	.9
expert6	1	0
expert7	1	1
expert8	1	.8

alg.

$\eta = 1$		
,	$ec{W}^1$	$ar{\ell}^{\dagger}$
expert1	1	.1
expert2	1	8.
expert3	1	.3
expert4	1	.1
expert5	1	.9
expert6	1	0
expert7	1	1
expert8	1	.8
ala.		.5

$\eta = 1$			
,	$ec{W}^1$	$ar{\ell}^{\dagger}$	\vec{W}^2
expert1	1	.1	.90
expert2	1	.8	.45
expert3	1	.3	.74
expert4	1	.1	.90
expert5	1	.9	.41
expert6	1	0	1
expert7	1	1	.37
expert8	1	.8	.45
alg.		.5	

$\eta=1$				
·	\vec{W}^1	$ec{\ell}^{ extsf{1}}$	\vec{W}^2	ℓ^2
expert1	1	.1	.90	.1
expert2	1	.8	.45	.5
expert3	1	.3	.74	.2
expert4	1	.1	.90	.7
expert5	1	.9	.41	1
expert6	1	0	1	.1
expert7	1	1	.37	.5
expert8	1	.8	.45	.2
alg.		.5		

$\eta=1$				
,	\vec{W}^1	$ec{\ell}^{ exttt{1}}$	$ec{W}^2$	$ar{\ell}^{2}$
expert1	1	.1	.90	.1
expert2	1	.8	.45	.5
expert3	1	.3	.74	.2
expert4	1	.1	.90	.7
expert5	1	.9	.41	1
expert6	1	0	1	.1
expert7	1	1	.37	.5
expert8	1	.8	.45	.2
alg.		.5		.36

$\eta=1$					
·	$ec{W}^1$	$ec{\ell}^{ exttt{1}}$	\vec{W}^2	$ar{\ell}^{2}$	\vec{W}^3
expert1	1	.1	.90	.1	0.82
expert2	1	.8	.45	.5	0.27
expert3	1	.3	.74	.2	0.61
expert4	1	.1	.90	.7	0.45
expert5	1	.9	.41	1	0.15
expert6	1	0	1	.1	0.91
expert7	1	1	.37	.5	0.22
expert8	1	.8	.45	.2	0.37
alg.		.5		.36	

$\eta=1$						
·	\vec{W}^1	$ec{\ell}^{ exttt{1}}$	\vec{W}^2	$ar{\ell}^{2}$	\vec{W}^3	$ar{\ell}^{ar{3}}$
expert1	1	.1	.90	.1	0.82	0
expert2	1	.8	.45	.5	0.27	.2
expert3	1	.3	.74	.2	0.61	.2
expert4	1	.1	.90	.7	0.45	8.
expert5	1	.9	.41	1	0.15	8.
expert6	1	0	1	.1	0.91	.2
expert7	1	1	.37	.5	0.22	.4
expert8	1	.8	.45	.2	0.37	.6
alg.		.5		.36		

$\eta=1$						
·	$ec{W}^1$	$ec{\ell}^{\dagger}$	$ec{W}^2$	$ar{\ell}^{2}$	\vec{W}^3	$ar{\ell}^{ar{3}}$
expert1	1	.1	.90	.1	0.82	0
expert2	1	.8	.45	.5	0.27	.2
expert3	1	.3	.74	.2	0.61	.2
expert4	1	.1	.90	.7	0.45	.8
expert5	1	.9	.41	1	0.15	.8
expert6	1	0	1	.1	0.91	.2
expert7	1	1	.37	.5	0.22	.4
expert8	1	.8	.45	.2	0.37	.6
alg.		.5		.36		.30

$\eta=1$							
,	$ec{W}^1$	$ec{\ell}^{\dagger}$	\vec{W}^2	$ar{\ell}^{2}$	\vec{W}^3	$ar{\ell}^{f 3}$	total
expert1	1	.1	.90	.1	0.82	0	.2
expert2	1	.8	.45	.5	0.27	.2	1.5
expert3	1	.3	.74	.2	0.61	.2	.7
expert4	1	.1	.90	.7	0.45	.8	1.6
expert5	1	.9	.41	1	0.15	.8	2.7
expert6	1	0	1	.1	0.91	.2	.3
expert7	1	1	.37	.5	0.22	.4	1.9
expert8	1	.8	.45	.2	0.37	.6	1.6
alg.		.5		.36		.30	

$\eta=$ 1							
•	$ec{W}^1$	$ar{\ell}^{\dagger}$	\vec{W}^2	$ar{\ell}^{2}$	\vec{W}^3	$ar{\ell}^{f 3}$	total
expert1	1	.1	.90	.1	0.82	0	.2
expert2	1	.8	.45	.5	0.27	.2	1.5
expert3	1	.3	.74	.2	0.61	.2	.7
expert4	1	.1	.90	.7	0.45	.8	1.6
expert5	1	.9	.41	1	0.15	.8	2.7
expert6	1	0	1	.1	0.91	.2	.3
expert7	1	1	.37	.5	0.22	.4	1.9
expert8	1	.8	.45	.2	0.37	.6	1.6
alg		5		36		.30	1.16

 $ightharpoonup L_{\mathsf{Hedge}}^t$: Expected total loss of Hedge algorithm for time $1, 2, \dots, t$

▶ L_{Hedge}^t : Expected total loss of Hedge algorithm for time 1, 2, . . . , t

$$\forall t, i, \quad L_{\mathsf{Hedge}} \leq \frac{\mathsf{In}\, \mathsf{N} + \eta L_i^t}{1 - e^{-\eta}}$$

► L^t_{Hedge}: Expected total loss of Hedge algorithm for time 1.2....*t*

$$\forall t, i, \quad L_{\mathsf{Hedge}} \leq \frac{\mathsf{In}\, N + \eta L_i^t}{1 - e^{-\eta}}$$

Which implies

$$\forall t, \quad L_{\mathsf{Hedge}} \leq \min_{i} \left(\frac{\ln N + \eta L_{i}^{t}}{1 - e^{-\eta}} \right)$$

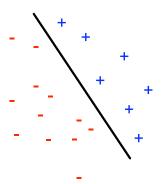
► L^t_{Hedge}: Expected total loss of Hedge algorithm for time 1,2,...,t

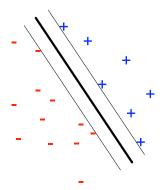
$$\forall t, i, \quad L_{\mathsf{Hedge}} \leq \frac{\ln N + \eta L_i^t}{1 - e^{-\eta}}$$

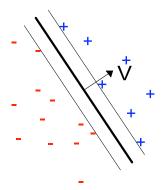
Which implies

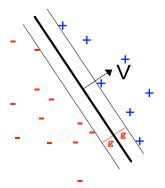
$$\forall t, \quad L_{\mathsf{Hedge}} \leq \min_{i} \left(\frac{\ln N + \eta L_{i}^{t}}{1 - e^{-\eta}} \right)$$

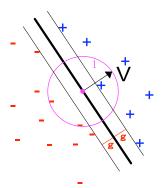
▶ Proof and choice of η : next class.

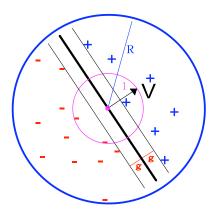


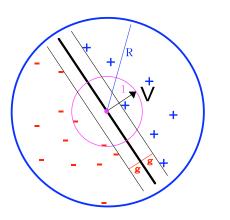




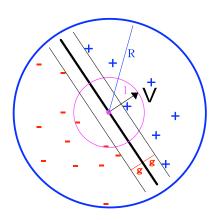




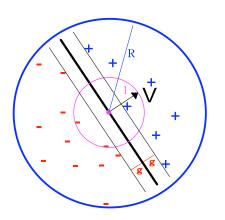




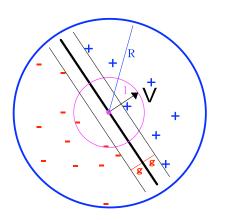
$$||\vec{V}|| = 1$$



- ▶ $\|\vec{V}\| = 1$
- ► Example = (\vec{X}, y) , $y \in \{-1, +1\}.$



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- $\blacktriangleright \ \forall \vec{X}, \ \|\vec{X}\| \leq R.$



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- ► Example = (\vec{X}, y) , $y \in \{-1, +1\}.$
- $\blacktriangleright \ \forall \vec{X}, \ \|\vec{X}\| \leq R.$
- $\forall (\vec{X}, y), \\ y(\vec{X} \cdot \vec{V}) \geq g$

The Perceptron learning algorithm

► An online algorithm. Examples presented one by one.

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- start with $\vec{W}_0 = \vec{0}$.

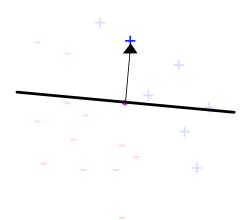
The Perceptron learning algorithm

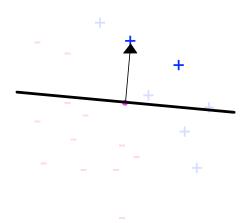
- An online algorithm. Examples presented one by one.
- start with $\vec{W}_0 = \vec{0}$.
- If mistake: $(\vec{W}_i \cdot \vec{X}_i)y_i \leq 0$

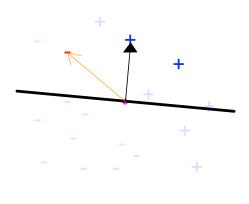
The Perceptron learning algorithm

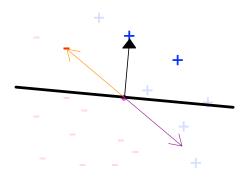
- An online algorithm. Examples presented one by one.
- start with $\vec{W}_0 = \vec{0}$.
- ▶ If mistake: $(\vec{W}_i \cdot \vec{X}_i)y_i \leq 0$
 - Update $\vec{W}_{i+1} = \vec{W}_i + y_i X_i$.

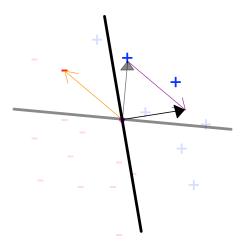












Bound on number of mistakes

The number of mistakes that the perceptron algorithm can make is at most $\left(\frac{R}{g}\right)^2$.

Bound on number of mistakes

- The number of mistakes that the perceptron algorithm can make is at most $\left(\frac{R}{g}\right)^2$.
- ▶ Proof by combining upper and lower bounds on $\|\vec{W}\|$.

Pythagorian Lemma

If $(\vec{W}_i \cdot X_i)y < 0$ then

Pythagorian Lemma

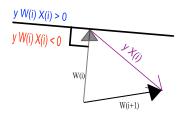
If
$$(\vec{W}_i \cdot X_i)y < 0$$
 then

$$\|\vec{W}_{i+1}\|^2 = \|\vec{W}_i + y_i \vec{X}_i\|^2 \le \|\vec{W}_i\|^2 + \|\vec{X}_i\|^2$$

Pythagorian Lemma

If
$$(\vec{W}_i \cdot X_i)y < 0$$
 then

$$\|\vec{W}_{i+1}\|^2 = \|\vec{W}_i + y_i \vec{X}_i\|^2 \le \|\vec{W}_i\|^2 + \|\vec{X}_i\|^2$$



Upper bound on $\|\vec{W}_i\|$

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Proof by induction

► Claim: $\|\vec{W}_i\|^2 \le iR^2$

Upper bound on $\|\vec{W}_i\|$

Proof by induction

- ► Claim: $\|\vec{W}_i\|^2 \le iR^2$
- ▶ Base: i = 0, $\|\vec{W}_0\|^2 = 0$

Upper bound on $\|\hat{W}_i\|$

Proof by induction

- ► Claim: $\|\vec{W}_i\|^2 < iR^2$
- ► Base: i = 0, $\|\vec{W}_0\|^2 = 0$
- ▶ Induction step (assume for i and prove for i + 1):

$$\|\vec{W}_{i+1}\|^2 \le \|\vec{W}_i\|^2 + \|\vec{X}_i\|^2 \le \|\vec{W}_i\|^2 + R^2 \le (i+1)R^2$$

$$\leq \|\vec{W}_i\|^2 + R^2 \leq (i+1)R^2$$

$$\|\vec{W}_i\| \ge \vec{W}_i \cdot \vec{V}$$
 because $\|\vec{V}\| = 1$.

 $\|\vec{W}_i\| \ge \vec{W}_i \cdot \vec{V}$ because $\|\vec{V}\| = 1$. We prove a lower bound on $\vec{W}_i \cdot \vec{V}$ using induction over i

► Claim: $\vec{W}_i \cdot \vec{V} \ge ig$

 $\|\vec{W}_i\| \ge \vec{W}_i \cdot \vec{V}$ because $\|\vec{V}\| = 1$.

- ► Claim: $\vec{W}_i \cdot \vec{V} \ge ig$
- ▶ Base: i = 0, $\vec{W}_0 \cdot \vec{V} = 0$

 $\|\vec{W}_i\| \geq \vec{W}_i \cdot \vec{V}$ because $\|\vec{V}\| = 1$.

- ► Claim: $\vec{W}_i \cdot \vec{V} \ge ig$
- ▶ Base: i = 0, $\vec{W}_0 \cdot \vec{V} = 0$
- Induction step (assume for i and prove for i+1): $\vec{W}_{i+1} \cdot \vec{V} = (\vec{W}_i + \vec{X}_i y_i) \vec{V}$

 $\|\vec{W}_i\| \geq \vec{W}_i \cdot \vec{V}$ because $\|\vec{V}\| = 1$.

- ► Claim: $\vec{W}_i \cdot \vec{V} \ge ig$
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$$\geq ig + g = (i + 1)g$$

Combining the upper and lower bounds

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Thus:

$$i \leq \left(\frac{R}{g}\right)^2$$

Estimating the bias of a coin

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Estimating the bias of a coin

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- Natural Answer:

$$\frac{\#\mathbf{H}}{n} = \frac{4}{9}$$

We observe a bf sequence of coin flips, and have to predict the probability of Head at each step:
p₀

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$$\frac{\# \mathbf{H} + 1}{n+2}$$

- We observe a bf sequence of coin flips, and have to predict the probability of **H**ead at each step: $p_0, \mathbf{H}, p_1, \mathbf{T}, p_2, \dots$
- ▶ What would be a good value for p_0 ?
- For p₁?
- Laplace Law of succession

$$\frac{\#\mathbf{H}+1}{n+2}$$

Turns out that a better rule is

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Krichevsky and Trofimov, 1981

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Why?

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Turns out that a better rule is

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Krichevsky and Trofimov, 1981

- ► Why?
- What does "better" mean?

Please

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Laplace law of succession

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- See you on Thursday!