

Fundamental Perspectives

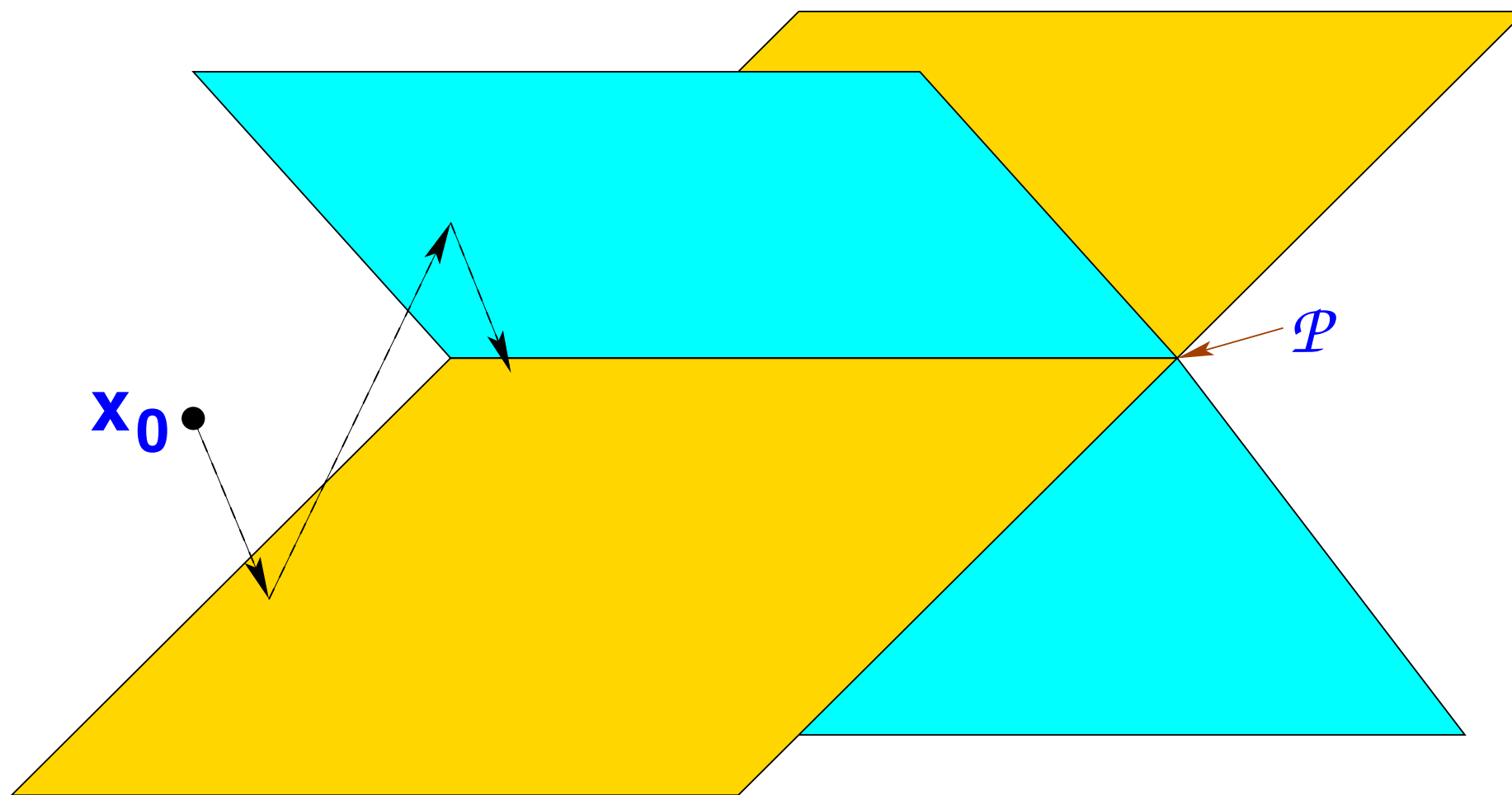
- game theory
- loss minimization
- an information-geometric view

A Dual Information-Geometric Perspective

- loss minimization focuses on **function** computed by AdaBoost (i.e., weights on **weak classifiers**)
- **dual view**: instead focus on **distributions** D_t (i.e., weights on **examples**)
- dual perspective combines **geometry** and **information theory**
- exposes underlying mathematical **structure**
- basis for proving **convergence**

An Iterative-Projection Algorithm

- say want to find point closest to \mathbf{x}_0 in set $\mathcal{P} = \{ \text{intersection of } N \text{ hyperplanes} \}$
- **algorithm:** [Bregman; Censor & Zenios]
 - start at \mathbf{x}_0
 - repeat: pick a hyperplane and **project** onto it



- if $\mathcal{P} \neq \emptyset$, under general conditions, will converge correctly

AdaBoost is an Iterative-Projection Algorithm

[Kivinen & Warmuth]

- points = distributions D_t over training examples
- distance = relative entropy:

$$\text{RE}(P \parallel Q) = \sum_i P(i) \ln \left(\frac{P(i)}{Q(i)} \right)$$

- reference point \mathbf{x}_0 = uniform distribution
- hyperplanes defined by all possible weak classifiers g_j :

$$\sum_i D(i) y_i g_j(x_i) = 0 \Leftrightarrow \Pr_{i \sim D} [g_j(x_i) \neq y_i] = \frac{1}{2}$$

- intuition: looking for “hardest” distribution

AdaBoost as Iterative Projection (cont.)

- algorithm:
 - start at $D_1 = \text{uniform}$
 - for $t = 1, 2, \dots$:
 - pick hyperplane/weak classifier $h_t \leftrightarrow g_j$
 - $D_{t+1} = (\text{entropy})$ projection of D_t onto hyperplane
$$= \arg \min_{D: \sum_i D(i) y_i g_j(x_i) = 0} \text{RE}(D \parallel D_t)$$
- claim: **equivalent** to AdaBoost
- further: choosing h_t with minimum error \equiv choosing **farthest** hyperplane

Boosting as Maximum Entropy

- corresponding optimization problem:

$$\min_{D \in \mathcal{P}} \text{RE}(D \parallel \text{uniform}) \leftrightarrow \max_{D \in \mathcal{P}} \text{entropy}(D)$$

- where

$$\begin{aligned} \mathcal{P} &= \text{feasible set} \\ &= \left\{ D : \sum_i D(i) y_i g_j(x_i) = 0 \quad \forall j \right\} \end{aligned}$$

- $\mathcal{P} \neq \emptyset \Leftrightarrow$ weak learning assumption does **not** hold
 - in this case, $D_t \rightarrow$ (unique) solution
- if weak learning assumption **does** hold then
 - $\mathcal{P} = \emptyset$
 - D_t can **never** converge
 - dynamics are fascinating but unclear in this case

Unifying the Two Cases

[Schapire Collins & Singer]

- two distinct cases:
 - weak learning assumption holds
 - $\mathcal{P} = \emptyset$
 - dynamics unclear
 - weak learning assumption does **not** hold
 - $\mathcal{P} \neq \emptyset$
 - can prove convergence of D_t 's
- to **unify**: work instead with **un**normalized versions of D_t 's
 - standard AdaBoost: $D_{t+1}(i) = \frac{D_t(i) \exp(-\alpha_t y_i h_t(x_i))}{\text{normalization}}$
 - instead:

$$d_{t+1}(i) = d_t(i) \exp(-\alpha_t y_i h_t(x_i))$$

$$D_{t+1}(i) = \frac{d_{t+1}(i)}{\text{normalization}}$$

- algorithm is **unchanged**

Reformulating AdaBoost as Iterative Projection

- points = nonnegative vectors \mathbf{d}_t
- distance = unnormalized relative entropy:

$$\text{RE}(\mathbf{p} \parallel \mathbf{q}) = \sum_i \left[p(i) \ln \left(\frac{p(i)}{q(i)} \right) + q(i) - p(i) \right]$$

- reference point $\mathbf{x}_0 = \mathbf{1}$ (all 1's vector)
- hyperplanes defined by weak classifiers g_j :

$$\sum_i d(i) y_i g_j(x_i) = 0$$

- resulting iterative-projection algorithm is again equivalent to AdaBoost

Reformulated Optimization Problem

- optimization problem:

$$\min_{\mathbf{d} \in \mathcal{P}} \text{RE}(\mathbf{d} \parallel \mathbf{1})$$

- where

$$\mathcal{P} = \left\{ \mathbf{d} : \sum_i d(i) y_i g_j(x_i) = 0 \quad \forall j \right\}$$

- note: feasible set \mathcal{P} **never** empty (since $\mathbf{0} \in \mathcal{P}$)

Exponential Loss as Entropy Optimization

- all vectors \mathbf{d}_t created by AdaBoost have form:

$$d(i) = \exp \left(-y_i \sum_j \lambda_j g_j(x_i) \right)$$

- let $\mathcal{Q} = \{ \text{all vectors } \mathbf{d} \text{ of this form} \}$
- can rewrite exponential loss:

$$\begin{aligned} \inf_{\lambda} \sum_i \exp \left(-y_i \sum_j \lambda_j g_j(x_i) \right) &= \inf_{\mathbf{d} \in \mathcal{Q}} \sum_i d(i) \\ &= \min_{\mathbf{d} \in \overline{\mathcal{Q}}} \sum_i d(i) \\ &= \min_{\mathbf{d} \in \overline{\mathcal{Q}}} \text{RE}(\mathbf{0} \parallel \mathbf{d}) \end{aligned}$$

- $\overline{\mathcal{Q}}$ = closure of \mathcal{Q}

Duality

[Della Pietra, Della Pietra & Lafferty]

- presented two optimization problems:
 - $\min_{\mathbf{d} \in \mathcal{P}} \text{RE}(\mathbf{d} \parallel \mathbf{1})$
 - $\min_{\mathbf{d} \in \overline{\mathcal{Q}}} \text{RE}(\mathbf{0} \parallel \mathbf{d})$
- which is AdaBoost solving? Both!
- problems have **same** solution
- moreover: solution given by **unique** point in $\mathcal{P} \cap \overline{\mathcal{Q}}$
- problems are **convex duals** of each other

Convergence of AdaBoost

- can use to prove AdaBoost **converges** to common solution of both problems:
 - can argue that $\mathbf{d}^* = \lim \mathbf{d}_t$ is in \mathcal{P}
 - vectors \mathbf{d}_t are in \mathcal{Q} always $\Rightarrow \mathbf{d}^* \in \overline{\mathcal{Q}}$
 - $\therefore \mathbf{d}^* \in \mathcal{P} \cap \overline{\mathcal{Q}}$
 - $\therefore \mathbf{d}^*$ solves both optimization problems
- so:
 - AdaBoost **minimizes** exponential loss
 - exactly **characterizes** limit of unnormalized “distributions”
 - likewise for normalized distributions when weak learning assumption does not hold
- also, provides additional link to **logistic regression**
 - only need slight change in optimization problem

[Schapire, Collins, Singer; Lebannon & Lafferty]

Conclusions

- from different perspectives, AdaBoost can be interpreted as:
 - a method for **boosting** the accuracy of a weak learner
 - a procedure for **maximizing margins**
 - an algorithm for playing **repeated games**
 - a numerical method for **minimizing exponential loss**
 - an **iterative-projection** algorithm based on an information-theoretic geometry
- none is entirely satisfactory by itself, but each useful in its own way
- taken together, create rich theoretical understanding
 - connect boosting to other learning problems and techniques
 - provide foundation for versatile set of methods with many extensions, variations and applications

References

Coming soon:

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