# **Hazard Analysis & Risk Assessment**

	Situational Analysis							
Hazard ID	Operational Mode	Operational Scenario	Environmental Details	Situation Details	Other Details (optional)	Item Usage (function)	Situation Description	
HA-001	OM03 - Normal Driving	OS03 - Country Road	EN01 - Normal conditions	SD02 - High speed	N/A	IU02 - Incorrectly used	Normal driving on country roads during normal conditions with high speed.	
HA-002	OM03 - Normal Driving	OS03 - Country Road	EN01 - Normal conditions	SD02 - High speed	N/A	IU02 - Incorrectly used	Normal driving on country roads during normal conditions with high speed.	
HA-003	OM03 - Normal Driving	OS03 - Country Road	EN01 - Normal conditions	SD02 - High speed	N/A	IU01 - Correctly used	Normal driving on country roads during normal conditions with high speed.	
HA-004	OM04 - Backward Driving	OS02 - City Road	EN01 - Normal conditions	SD01 - Low speed	N/A	IU03 - N/A	Backwards driving on city roads during normal driving conditions with low speed.	

Updated: 8/24/2017

		Ha	azard Identification			
Hazard ID	Function	Deviation	Deviation Details	Hazardous Event (resulting effect)	Event Details	Hazardous Event Description
HA-001	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver with haptic feedback.	DV04 - Actor effect is too much	The LDW function applies an oscillating torque with very high torque (above limit)	EV00 - Collision with other vehicle	High haptic feedback can affect driver's ability to steer as intended. The driver could lose control of the vehicle and collide with another vehicle or road infrastructure.	The LDW function applies too high an oscillating torque to the steering wheel (above limit).
HA-002	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane.	DV03 - Function always activated	The driver is misusing the system by exploiting the LKA function as a fully autonomous function.	EV00 - Collision with other vehicle	The driver takes both hands off the wheel indefinitely and cannot react to other vehicles on the road that are merging or turning into the current lane, causing a collision.	The LKA function has no time limit so the driver misinterprets and misuses the function to be fully autonomous.
HA-003	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane.	DV03 - Function always activated	The LKA function does not deactivate when the driver regains control of the steering wheel.	EV00 - Collision with other vehicle	Changing lanes may cause the vehicle to unexpectedly jerk in an attempt to perform the LKA function and collide with another vehicle or road infrastructure.	The LKA function never deactivates when the driver regains control of the steering wheel and therefore continues to operate in an improper state.
HA-004	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane.	DV19 - Sensor detection is wrong	The LKA function detects the sidewalk as the current lane when backing out of a parking space that backs up to a city road.		The LKA function takes over control of the vehicle unexpectedly from the driver's perspective and corrects the vehicle to the sidewalk (the current lane), bumping into a pedestrian at low speed.	The LKA function actuates as expected but identifies and corrects to the wrong lane due to inaccurate sensor data.

# **Hazard Analysis & Risk Assessment**

Hazard ID			Hazardous Event Classif	ication		
ID	Exposure (of situation)	Rationale (for exposure)	Severity (of potential harm)	Rationale (for severity)	Controllability (of hazardous event)	Rationale (for controllability)
HA-001	E2 - Low probability	Driver does not live near country roads. Limited country road driving.	S3 - Life-threatening or fatal injuries	Driver is travelling at high speed.	C3 - Difficult to control or uncontrollable	Driver cannot control vehicle while LKA function is operating.
HA-002	E2 - Low probability	Driver does not live near country roads. Limited country road driving.	S3 - Life-threatening or fatal injuries	Driver is travelling at high speed.	C3 - Difficult to control or uncontrollable	Driver cannot control vehicle while LKA function is operating.
HA-003	E2 - Low probability	Driver does not live near country roads. Limited country road driving.	S3 - Life-threatening or fatal injuries	Driver is travelling at high speed.	C3 - Difficult to control or uncontrollable	Driver cannot control vehicle while LKA function is operating.
HA-004	E2 - Low probability	Situation dependent on uncommon parking lot design.	S1 - Light and moderate injuries	Dependent on pedestrian response.	C3 - Difficult to control or uncontrollable	Driver cannot control vehicle while LKA function is operating.

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Hazard ID	Determination of	ASIL and Safety Goals
ID	ASIL Determination	Safety Goal
HA-001	ASIL B	The LKA function shall end after a given time interval to prevent over applying torque.
HA-002	ASIL B	The LKA function shall be time limited so that the driver cannot misuse the system for autonomous driving.
HA-003	ASIL B	The LKA function shall be time limited and the additional steering torque shall end after a given time interval so that the system cannot maintain an improper state.
HA-004	QM	Sensors shall maintain a high quality of readings.

# **Appendix**

# **Situational Analysis Definitions**

## Operational Mode

ID	Mode		Reference
OM01			OM01 - Parked
OM02		Car is parked, ignition is on	OM02 - Ignition on
			OM03 - Normal driving
		Car is driving	OM04 - Backward driving
OM05	Degraded driving		OM05 - Degraded driving
OM06			OM06 - Towing (active)
OM07	Towing (passive)	Beeing towed by another car	OM07 - Towing (passive)
OM08			OM08 - Service
OM09	N/A	not applicable or not relevant	OM09 - N/A

### Operational Scenario

ID	Scenario	Remarks	Reference			
OS01	Any Road		OS01 - Any Road			
OS02	City Road		OS02 - City Road			
OS03	Country Road	road type	OS03 - Country Road			
OS04			OS04 - Highway			
OS05	Mountain Pass		OS05 - Mountain Pass			
OS06			OS06 - Off Road			
OS07	Road with gradient		OS07 - Road with gradient			
OS08			OS08 - Road with bump			
OS09			OS09 - Road tunnel			
OS10	Road with construction site		OS10 - Road with construction site			
OS11	N/A	not applicable or not relevant	OS11 - N/A			

## Situation Details

ID	Scenario	Remarks	Reference
SD01	Low speed		SD01 - Low speed
SD02	High speed	driving attribute	SD02 - High speed
SD03			SD03 - Normal acceleration
SD04	High acceleration	driving attribute	SD04 - High acceleration
SD05			SD05 - Normal braking
SD06	High braking	driving attribute	SD06 - High braking
SD07	N/A	not applicable or not relevant	SD07 - N/A

### Item Usage

ID	Mode	Remarks	Reference
IU01	Correctly used	Intended usage	IU01 - Correctly used
IU02	Incorrectly used	Unintended usage (foreseeable)	IU02 - Incorrectly used
IU03	N/A	not applicable or not relevant	IU03 - N/A

## **Environmental Details**

ID	Scenario		Reference			
EN01	Normal conditions	weather attribute	EN01 - Normal conditions			
EN02	Sun blares (degraded view)		EN02 - Sun blares (degraded view)			
			EN03 - Fog (degraded view)			
EN04	Snowfall (degraded view)	weather attribute	EN04 - Snowfall (degraded view)			
EN05	Cross-wind (lateral force)	weather attribute	EN05 - Cross-wind (lateral force)			
EN06	Rain (slippery road)	road attribute	EN06 - Rain (slippery road)			
EN07	Snow (slippery road)		EN07 - Snow (slippery road)			
EN08	Glace (slippery road)	road attribute	EN08 - Glace (slippery road)			
EN09	N/A	not applicable or not relevant	EN09 - N/A			

# **Hazard Analysis Definitions**

### Deviation

ID	Deviation (Guideword)	Remarks	Reference
DV01	Function not activated	Activation error	DV01 - Function not activated
DV02	Function unexpectedly activated	Activation error	DV02 - Function unexpectedly activated
DV03	Function always activated	Activation error	DV03 - Function always activated
DV04	Actor effect is too much	Quantitative error	DV04 - Actor effect is too much
DV05	Actor effect is too less	Quantitative error	DV05 - Actor effect is too less
DV06	Actor action too early	Timing error	DV06 - Actor action too early
DV07	Actor action too late	Timing error	DV07 - Actor action too late
DV08	Actor action before		DV08 - Actor action before
DV09	Actor action after	Sequence error	DV09 - Actor action after
DV10	Actor effect is reverse		DV10 - Actor effect is reverse
DV11	Actor effect is wrong		DV11 - Actor effect is wrong
DV12			DV12 - Sensor sensitivity is too high
DV13	Sensor sensitivity is too low		DV13 - Sensor sensitivity is too low
DV14	Sensor detection too early		DV14 - Sensor detection too early
DV15	Sensor detection too late	Timing error	DV15 - Sensor detection too late
DV16	Sensor detection before		DV16 - Sensor detection before
DV17	Sensor detection after	Sequence error	DV17 - Sensor detection after
DV18	Sensor detection is reverse		DV18 - Sensor detection is reverse
DV19	Sensor detection is wrong	Logical error	DV19 - Sensor detection is wrong
DV20	N/A	not applicable or not relevant	DV20 - N/A

Hazardous Events (possibe effects)

ID	Hazardous Event	Remarks	Reference
EV-07	None		EV-07 - None
EV-06	Front collision with oncoming traffic		EV-06 - Front collision with oncoming traffic
EV-05	Front collision with ahead traffic		EV-05 - Front collision with ahead traffic
EV-04	Front collision with obstacle		EV-04 - Front collision with obstacle
EV-03	Rear collision with trailing traffic		EV-03 - Rear collision with trailing traffic
EV-02	Side collision with other traffic		EV-02 - Side collision with other traffic
EV-01	Side collision with obstacle		EV-01 - Side collision with obstacle
EV00	Collision with other vehicle		EV00 - Collision with other vehicle
EV01	Collision with train		EV01 - Collision with train
EV02	Collision with pedestrian		EV02 - Collision with pedestrian
EV03	Car spins out of control		EV03 - Car spins out of control
EV04	Car comes off the road		EV04 - Car comes off the road
EV05	Car catches file		EV05 - Car catches file
EV06	N/A		EV06 - N/A

# **Risk Assessment Definitions**

### Exposure

ID	Description	Duration (of situation)	Frequency (of situation)	Reference
E0	Incredible			E0 - Incredible
E1	Very low probability	Not specified	Occurs less often than once a year for the great majority of drivers	E1 - Very low probability
E2	Low probability	<1 % of average operating time	Occurs a few times a year for the great majority of drivers	E2 - Low probability
E3	Medium probability	1 % to 10 % of average operating time	Occurs once a month or more often for an average driver	E3 - Medium probability
E4	High probability	>10 % of average operating time	Occurs during almost every drive on average	E4 - High probability

#### Severity

OCTO	octomy								
	ID	Description	Remarks	Probability of Injuries	Reference				
	S0	No injuries	No injuries	AIS 0 and less than 10 % probability of AIS 1-6	S0 - No injuries				
	S1	Light and moderate injuries	Light and moderate injuries	More than 10 % probability of AIS 1-6 (and not S2 or S3)	S1 - Light and moderate injuries				
	S2	Severe and life-threatening injuries	Severe and life-threatening injuries (survival probable)	More than 10 % probability of AIS 3-6 (and not S3)	S2 - Severe and life-threatening injuries				
	S3	Life-threatening or fatal injuries	Life-threatening injuries (survival uncertain), fatal injuries	More than 10 % probability of AIS 5-6	S3 - Life-threatening or fatal injuries				

## Controllability

ID	Description	Remarks	Reference
C0	Controllable in general	Controllable in general	C0 - Controllable in general
C1	Simply controllable	99 % or more of all drivers or other traffic participants are usually able to avoid harm	C1 - Simply controllable
C2	Normally controllable	90 % or more of all drivers or other traffic participants are usually able to avoid harm	C2 - Normally controllable
C3	Difficult to control or uncontrollable	Less than 90 % of all drivers or other traffic participants are usually able, or barely able, to avoid harm	C3 - Difficult to control or uncontrollable

**ASIL Table** 

Cantuallabilita	Exposure	Severity			
Controllability		S0	S1	S2	S3
	E1	QM	QM	QM	QM
C1	E2	QM	QM	QM	QM
C1	E3	QM	QM	QM	Α
	E4	QM	QM	Α	В
	E1	QM	QM	QM	QM
C2	E2	QM	QM	QM	Α
C2	E3	QM	QM	Α	В
	E4	QM	Α	В	С
	E1	QM	QM	QM	Α
C3	E2	QM	QM	Α	В
C3	E3	QM	Α	В	С
	E4	QM	В	С	D