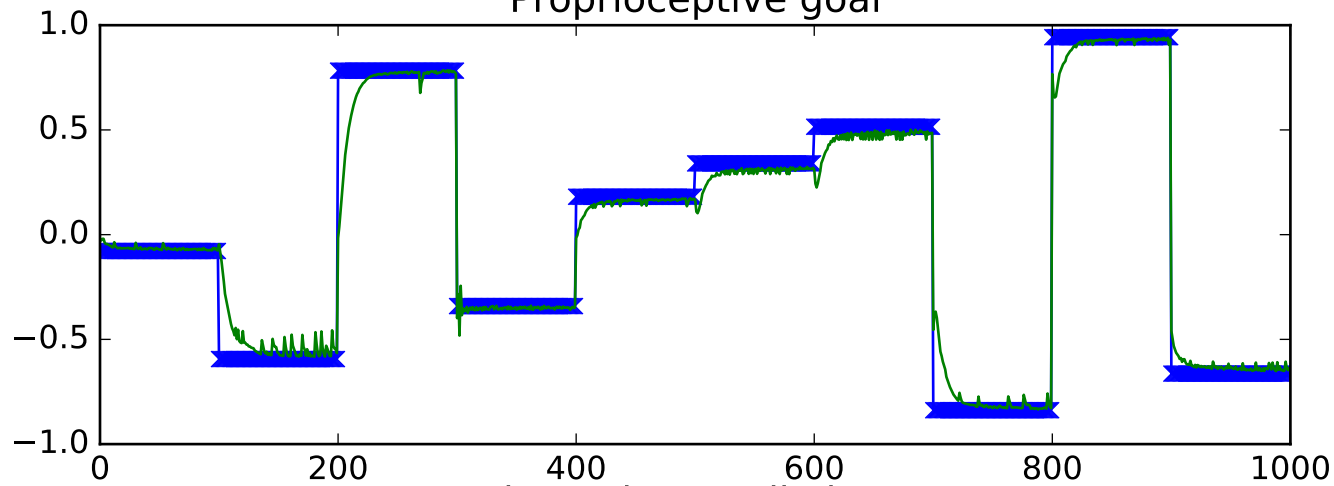


Mode: basic\_operation\_1D\_M1 using knn (X: FM input, state pred: FM output)

Proprioceptive goal



Proprioceptive prediction error

