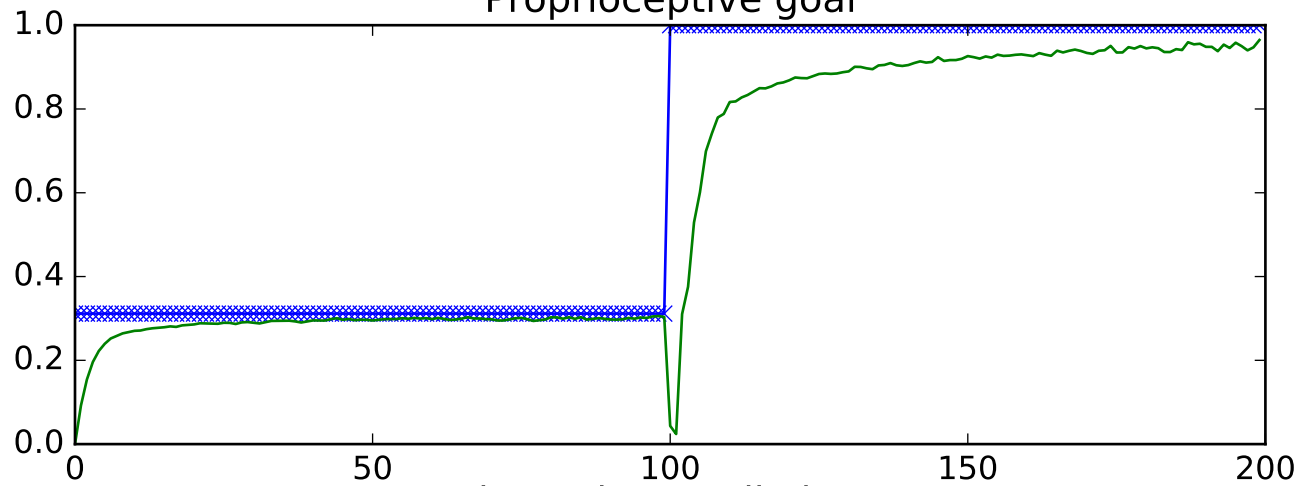Mode: basic_operation_1D_M1 using soesgp (X: FM input, state pred: FM output)
Proprioceptive goal
Proprioceptive prediction error