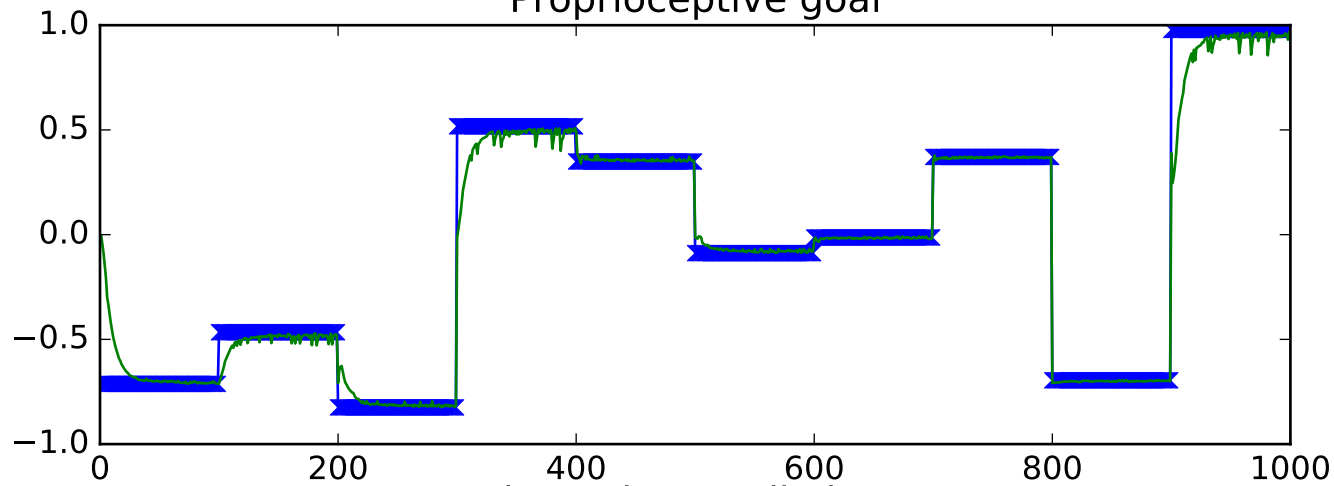


Mode: basic_operation_1D_M1 using knn (X: FM input, state pred: FM output)

Proprioceptive goal



Proprioceptive prediction error

