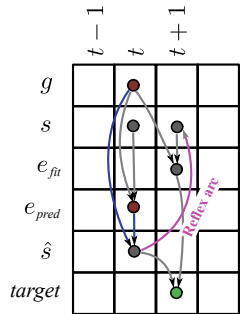


| | | | |
|-----------|---------------------|------------|-----------------------------------|
| s | sensory observation | e_{pred} | error used for predicting |
| \hat{s} | sensory prediction | e_{fit} | error used for updating the model |
| m | motor command | $\{t\}$ | signal flowing at time t |
| g | goal | | |



| | |
|-------------------------|--|
| Computation | |
| Forward prediction | |
| Input for model update | |
| Output for model update | |