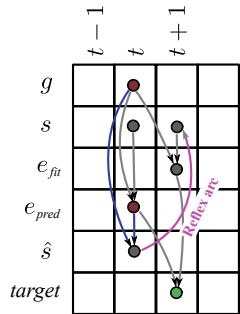


s	sensory observation	e_{pred}	error used for predicting
\hat{s}	sensory prediction	e_{fit}	error used for updating the model
m	motor command	$\{t\}$	signal flowing at time t
g	goal		



Computation	
Forward prediction	
Input for model update	
Output for model update	