Mode: basic operation 1D M1 using soesgp (X: FM input, state pred: FM output) Proprioceptive goal 1.0 0.5 0.0 -0.550 100 150 200 250 300 350 400 Proprioceptive prediction error 0.4 0.2 0.0 -0.2-0.4-0.6-0.8-1.050 100 150 200 250 300 350 400