Mode: basic_operation_1D_M1 using soesgp (X: FM input, state pred: FM output) Proprioceptive goal 1.0 8.0 0.6 0.4 0.2 0.0 50 100 Proprioceptive prediction error 200 150 0.2 0.0 -0.2-0.4-0.6-0.8-1.0

100

150

200

50