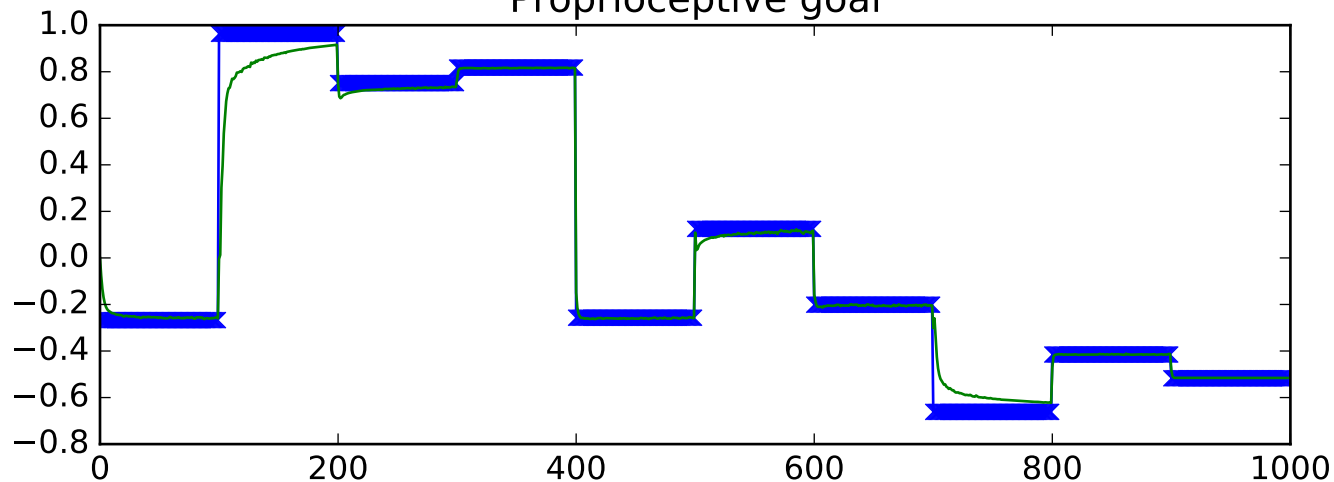Mode: basic_operation_1D_M1 using soesgp (X: FM input, state pred: FM output)

Proprioceptive goal

Proprioceptive prediction error