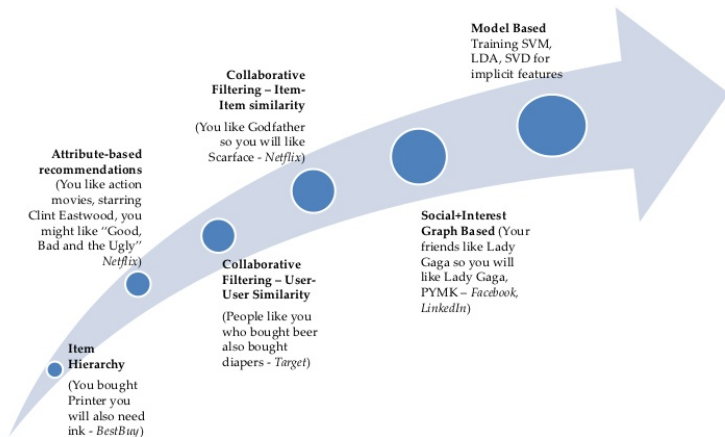


Know your customers

Aris Tritas Laurent Cetinsoy

13 décembre 2016

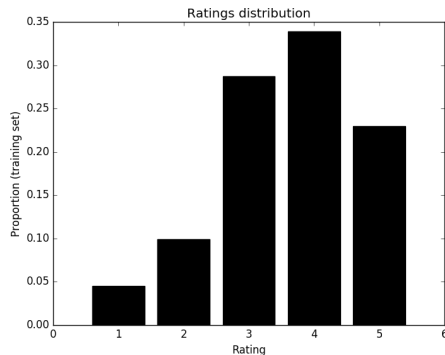
Recommender Approaches



Customer affinity dataset

Courtesy AlixML

- More than 2 millions of ratings of 3560 items from 93705 users
- Sparsity : $< 1\%$ of matrix filled
- Split in 2.5M train & 1.3M test examples
- $\#\{\text{Ratings/Item}\}$: median=71, mean=712
- $\#\{\text{Ratings/User}\}$: median=13, mean=28



Collaborative filtering

Non negative factorization

$$R = \begin{pmatrix} n_{11} & n_{12} & \cdots & n_{1i} \\ n_{21} & n_{22} & \cdots & n_{2i} \\ \vdots & \vdots & \vdots & \vdots \\ n_{u1} & n_{u2} & \cdots & n_{ui} \end{pmatrix} = \overbrace{\begin{pmatrix} n_{11} & \cdots & n_{1k} \\ n_{21} & \cdots & n_{2k} \\ n_{31} & \cdots & n_{3k} \\ \vdots & \vdots & \vdots \\ n_{u1} & \cdots & n_{uk} \end{pmatrix}}^U \cdot \overbrace{\begin{pmatrix} n_{11} & n_{12} & \cdots & n_{1i} \\ n_{21} & n_{22} & \cdots & n_{2i} \\ \vdots & \vdots & \vdots & \vdots \\ n_{k1} & n_{k2} & \cdots & n_{ki} \end{pmatrix}}^{V^T}$$

A new rating is computed as follows :

$$\tilde{r}_{ij} := u_i \cdot v_j^T = \sum_{p=1}^k u_{ip} v_{pj}$$

Collaborative filtering

Non Negative Matrix Factorization

$$U^*, V^* = \arg \min_{U, V} \frac{1}{2} \|R - UV^T\|^2 + \lambda \cdot \Omega(U, V)$$

$$R \in \mathbb{R}^{n \times m}, U \in \mathbb{R}^{n \times k}, V \in \mathbb{R}^{m \times k}$$

Collaborative filtering

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Usual regularization : $\Omega(U, V) = \|U\|^2 + \|V\|^2$

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Usual regularization : $\Omega(U, V) = \|U\|^2 + \|V\|^2$

Tikhonov regularization : $\Omega(U, V) = \sum_i \mathcal{J}(i) \|U_i\|^2 + \sum_i \mathcal{I}(j) \|V_i\|^2$

NNMF

Gradient Descent optimization

Update rule using prediction error $e_{ij} = r_{ij} - \tilde{r}_{ij}$:

- $u_i \leftarrow u_i + \gamma \cdot (e_{ij} \cdot v_j - \lambda \cdot u_i)$
- $v_j \leftarrow v_j + \gamma \cdot (e_{ij} \cdot u_i - \lambda \cdot v_j)$

avec $\gamma > 0$ le taux d'apprentissage, $\lambda > 0$ le coef. de régularisation

Algorithm 1 ALS-WR

```
1: while not happy do
2:   for  $i \in [n]$  do
3:      $\hat{U}_i \leftarrow \arg \min_U \sum_{j \in \mathcal{J}(i)} (r_{ij} - U \hat{V}_j^T) + \lambda \cdot \#\mathcal{J}(i) \|U\|$ 
4:   end for
5:   for  $j \in [m]$  do
6:      $\hat{V}_j \leftarrow \arg \min_U \sum_{i \in \mathcal{I}(j)} (r_{ij} - \hat{U}_i V^T) + \lambda \cdot \#\mathcal{I}(j) \|V\|$ 
7:   end for
8: end while
```

Results

NMF

$$k = 15$$

Model	ratings	k	lambda	RMSE
GD	500k	15	0.02	0.863
GD	All	15	0.02	0.951
ALS	500k	15	0.03	0.877
ALS	All	15	0.03	0.925
ALS	All	30	0.03	0.923
ALS	All	100	0.1	0.934

Results

Gradient descent

$$k = 15, \lambda = 0.02$$

Ratings	Left deletion	Righ deletion	RMSE
500k	0	0	0.863
500k	0	0.2	0.879
All	0	0	0.898
All	0	0.2	0.911

NMF - Results

ALS-WR

NMF optimized with ALS-WR

$k = 15$

Rating	Left deletion	right deletion	RMSE
500k	0	0	0.877
500k	0.2	0	0.8867
500k	0.15	0.15	0.895
All	0	0	
All	0	0.2	0.939
All*	0	0	RMSE = 0.934

* $k = 30, \lambda = 0.03$

Collaborative Filtering Networks

[Salakhutdinov et al. 06]

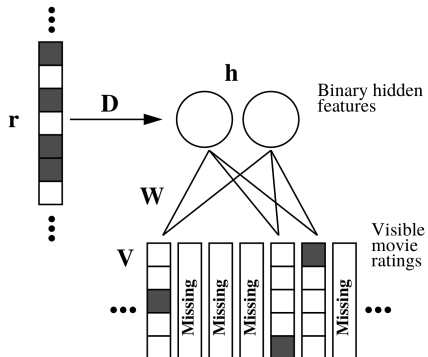


Figure 2. Conditional RBM. The binary vector \mathbf{r} , indicating rated/unrated movies, affects binary states of the hidden units.

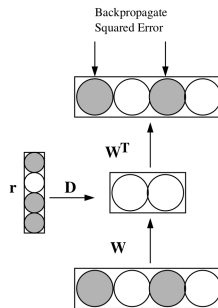


Figure 5. The “unrolled” RBM used to create an autoencoder network which is then fine-tuned using backpropagation of error derivatives.

Hybrid collaborative Filtering with Autoencoders

[Strub2016]

$$f(\mathbf{x}) = \sigma(\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1), \quad g(\mathbf{y}) = \sigma(\mathbf{W}_2 \mathbf{y} + \mathbf{b}_2) \quad nn(\mathbf{x}) = g(f(\mathbf{x}))$$

$$L_{2,\alpha,\beta} = \alpha \left(\sum_{j \in \mathcal{C}(\tilde{x})} [nn(\tilde{x}_j) - x_j]^2 \right) + \beta \left(\sum_{j \notin \mathcal{C}(\tilde{x})} [nn(\tilde{x}_j) - x_j]^2 \right)$$

avec $\tilde{x} \in \mathbb{R}^N, W_1 \in \mathbb{R}^{K \times n}, W_1 \in \mathbb{R}^{n \times K}, b_1 \in \mathbb{R}^k, b_2 \in \mathbb{R}^N$

Hybrid collaborative Filtering with Autoencoders

[Strub2016]

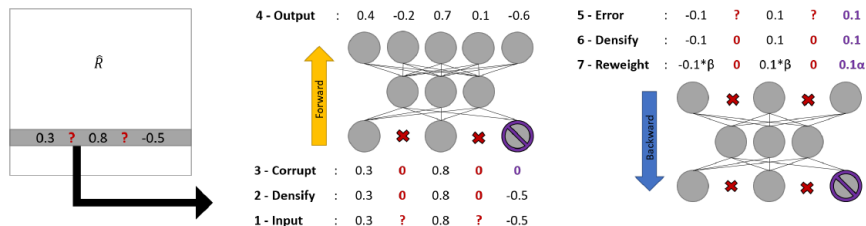
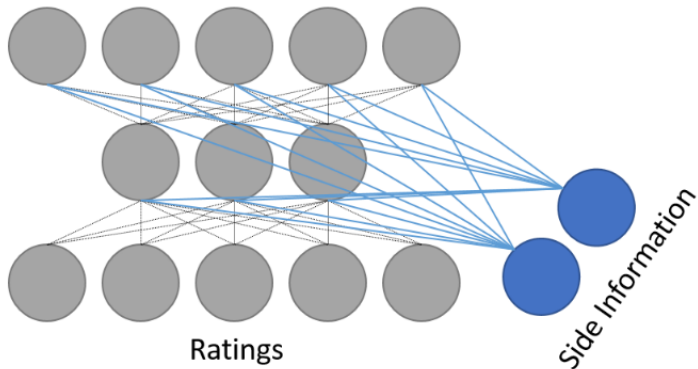


FIGURE – On the forward pass the sparse input vector is densified and then corrupted. Before backpropagation, the error is reweighted and missing values are put to zero.

Injecting side-information



Results

Hybrid collaborative filtering with Autoencoders

Model	Rating	Left removal	right removal	RMSE
AE Item Vector	2M	0	0	0.938
AE User Vector	2M	0	0	0.913
AE User Vector	2M	0	0.2	0.947

Results

Comparison between ALS and autoencoder networks.

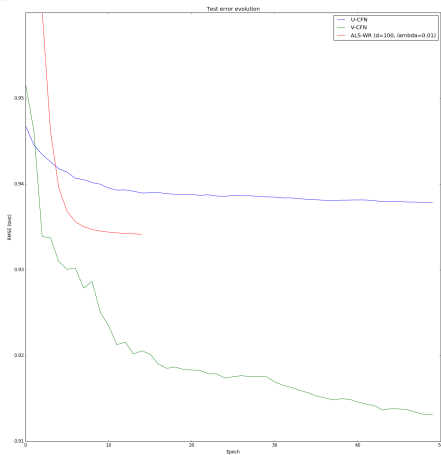


FIGURE – Test error evolution

Conclusion, further work and ideas

- Add terms accounting for bias or temporal dynamics [Koren2009]

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- Add terms accounting for bias or temporal dynamics [Koren2009]
- Further investigate dependency on succession
- Hyperparameter tuning, better validation, effect of expert polling ?



Y. Koren, R. Bell, C. Volinsky - Matrix factorization techniques for recommender systems. 2009 IEEE Computer Society



F. Strub, J. Mary, R. Gaudel - Hybrid Collaborative Filtering with Auto-Encoders. Arxiv



F. Strub, J. Mary, R. Gaudel -

https://github.com/fstrub95/Autoencoders_cf



[https:](https://github.com/lcetinsoy/collaborative-filtering)

[//github.com/lcetinsoy/collaborative-filtering](https://github.com/lcetinsoy/collaborative-filtering)