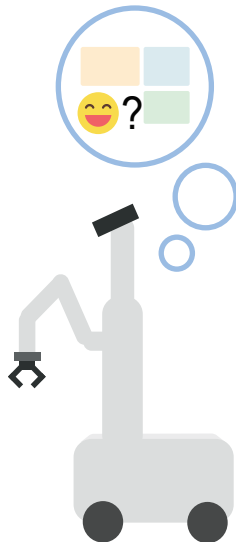


Human: {
 emotion: *neutral*,
 gesture: *sitting, holding a book*,
 eye_gaze: *looking at the book*,
 activity: *reading*,
 intention: *to gain knowledge or enjoy leisure time*,
 need: *concentration, comfortable seating*
 }

Environment: {
 location: *living room*,
 lighting: *dim*,
 objects: {
 name: *floor lamp*
 affordance: *provides lighting*
 }, ...
 }

Robot_action: {
 manipulate_environment: {
 object: {
 name: *lamp switch*,
 how: *turn on the lamp*
 }
 }
 }



Human: {
 emotion: *relaxed*,
 gesture: *lying down with hands on abdomen*,
 eye_gaze: *closed*,
 activity: *resting or napping*,
 intention: *to relax or sleep*,
 need: *comfort, possibly a blanket for warmth*,
 }

Environment: {
 location: *living room*,
 lighting: *dim*,
 objects: {
 name: *blanket*,
 affordance: *provides warmth*
 }, ...
 }

Robot_action: {
 grab: {
 objects: [blanket]
 },
 manipulate_environment: {
 object: {
 name: *lamp switch*,
 how: *turn off the lamp*
 }
 }
 }

