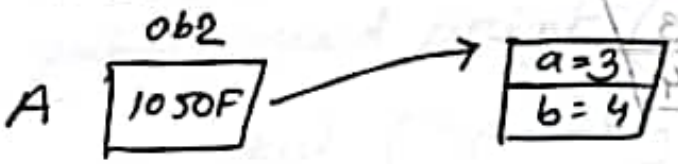
SP-20

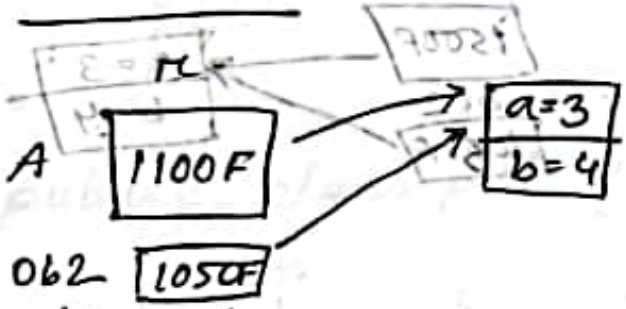
(3) b)

Line-1

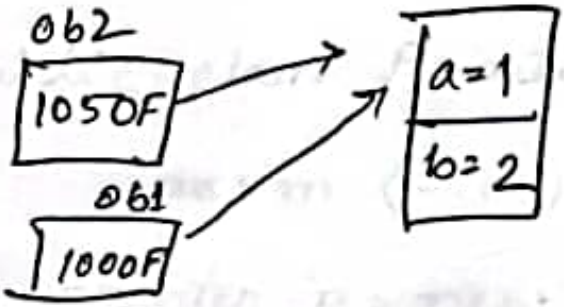
Line-2



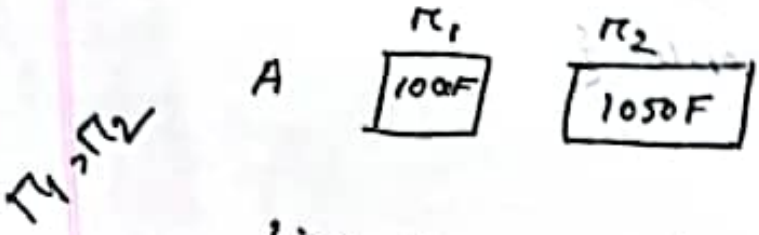
Line-3



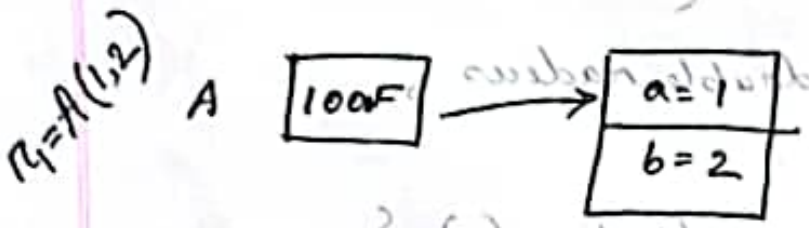
Line-4



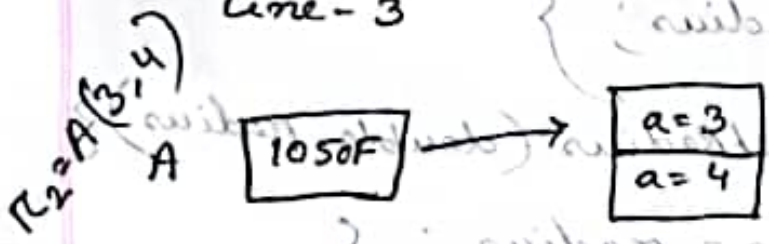
③ ~~b)~~ c) Line - 1



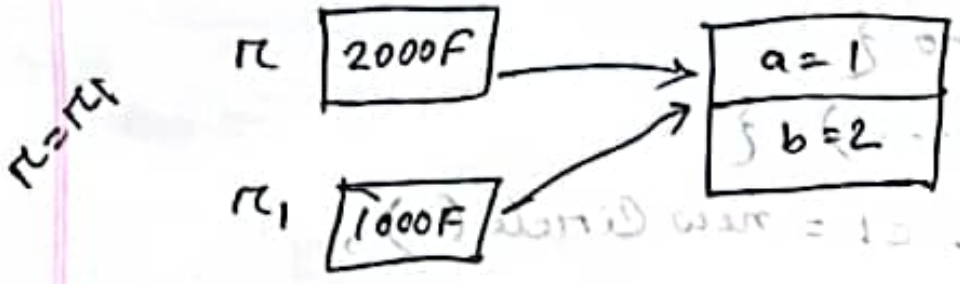
Line - 2



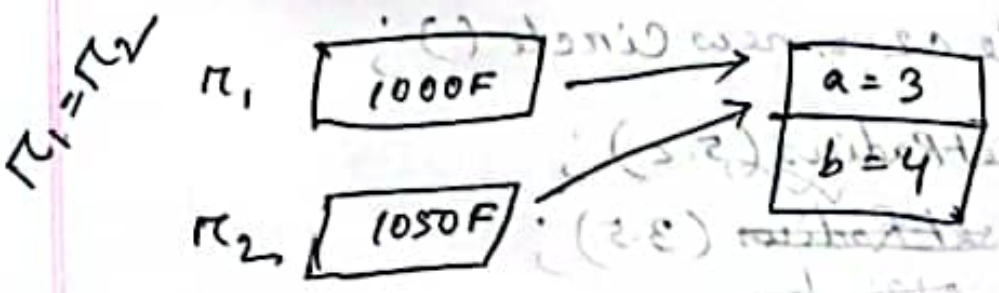
Line - 3



Line - 4

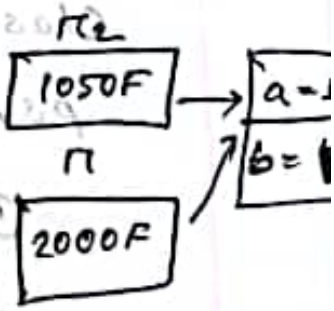


Line - 5



$\pi_2 = \pi$

Line - 6



3. b)

Line # 1 : r, r_1, r_2

Line # 2 :

$r_1 \longrightarrow$ (a = 1 b = 2)

Line # 3 :

$r_2 \longrightarrow$ (a = 3 b = 4)

Line # 4 :

$r \longrightarrow$ (a = 3 b = 4)

$r_2 \nearrow$

Here, r, r_1, r_2 are the object of class A.

CamScanner