30/11/22

Week : 4 : A* algorithm for 8 puzzle.

Aim :- To implement A* algorithm for 8 puzzle problem.

```
class Node:
    def __init__(self, data, level, fval):
        self.data = data
        self.level = level
        self.fval = fval

    def generate_child(self):

        x, y = self.find(self.data, '_')
        val_list = [[x, y-1], [x, y+1], [x-1, y], [x+1, y]]
        children = []
        for i in val_list:
            child = self.shuffle(self.data, x, y, i[0], i[1])
            if child is not None:
                child_node = Node(child, self.level+1, 0)
                children.append(child_node)
        return children

    def shuffle(self, puz, x1, y1, x2, y2):

        if x2>=0 and x2 < len(self.data) and
           y2>=0 and y2 < len(self.data):

            temp_puz = []
            temp_puz = self.copy(puz)
            temp = temp_puz[x1][y1]
            temp_puz[x1][y1] = temp_puz[x2][y2]
            temp_puz[x2][y2] = temp
            return temp_puz
        else:
```

```
        return None

    def copy(self, root):
        temp=[]
        for i in root:
            t = []
            for j in i:
                t.append(j)
            temp.append(t)
        return temp

    def find(self, puz, x):
        for i in range(0, len(self.data)):
            for j in range(0, len(self.data)):
                if puz[i][j] == x:
                    return i,j

class Puzzle:
    def __init__(self, size):
        self.n = size
        self.open = []
        self.closed = []

    def accept(self):
        puz = []
        for i in range(0, self.n):
            temp = input().split(" ")
            puz.append(temp)
        return puz

    def f(self, start, goal):
```

```
        return self.h(start.data, goal) + start.level

    def h(self, start, goal):

        temp = 0
        for i in range(0, self.n):
            for j in range(0, self.n):
                if start[i][j] != goal[i][j] and
                        start[i][j] != '_':
                    temp += 1
        return temp

    def process(self):

        print("Enter the start state matrix \n")
        start = self.accept()
        print("Enter the goal state matrix \n")
        goal = self.accept()

        start = Node(start, 0, 0)
        start.fval = self.f(start, goal)

        self.open.append(start)
        print("\n\n")
        while True:
            cur = self.open[0]
            print("  ")
            print("  |  ")
            print(" \|/ ")
            print(" \\\' / \n")
            for i in cur.data:
                for j in i:
                    print(j, end=" ")
                print("")
```

```
if (self.h(cur.data, goal) == 0):
    break
for i in cur.generate_child():
    i.fval = self.f(i, goal)
    self.open.append(i)
self.closed.append(cur)
del self.open[0].

self.open.sort(key = lambda x:x.fval,
               reverse = False)

puz = Puzzle(3)
puz.process().
```

O/P:

Enter start state

1	2	3
4	5	6
_	7	8

↓

1	2	3
4	5	6
7	_	8

↓

1	2	3
4	5	6
7	8	_

Enter goal state.

1	2	3
4	5	6
7	8	_

Date
Page

A* Algorithm :

$f(n) = g(n) + h(n)$.

$g(n)$ = sum of edge costs from start to n.

$h(n)$ = estimate of least cost path from n to goal.

$f(n)$ = actual distance so far + estimated distance remaining.

function A* search (problem) returns a solution or failure

node ← a node n with n.state = problem.initial state

frontier ← a priority Queue ordered by ascending g th. only element n.

loop do

if empty ? (frontier) then return failure.

n ← pop (frontier)

if problem.goalTest (n.state) then return solution

for each action a in problem.actions (n.state) do

n' ← childNode (problem, n, a)

insert (n', g(n') + h(n'), frontier)

State space tree: