

# 1 18-04-18

This research is collaboration with Prof. Yoneda from University of Tokyo.

Main equation discussed is **Navier-Stokes equation** that usually discusses in fluid, for example air.

## 1.1 Navier-Stokes Equation

### 1.1.1 General Problem

For dimension  $d = 2, 3, \dots$  (usually 2 or 3) and  $T > 0$ , we want to find

$$(u, p) : \Omega \times (0, T) \rightarrow \mathbb{R}^d \times \mathbb{R}$$

where  $u$  is unknown velocity and  $p$  is unknown pressure such that

$$\begin{cases} \frac{\partial u}{\partial t} + (u \cdot \nabla)u - \nu \Delta u + \nabla p = f & \text{in } \Omega \times (0, T) \\ \nabla \cdot u = 0 & \text{in } \Omega \times (0, T) \\ u = 0 & \text{on } \partial\Omega \times (0, T) \\ u = u^0 & \text{in } \Omega, \text{ at } t = 0 \end{cases} \quad (1)$$

where  $f : \Omega \times (0, T) \rightarrow \mathbb{R}^d$  and  $u^0 : \Omega \rightarrow \mathbb{R}^d$  are given functions,  $\nu > 0$  is a viscosity.

From equation (1) we can see that  $\frac{\partial u}{\partial t} + (u \cdot \nabla)u$  is the **convection part** that explain the movement of fluid. This part, contain **nonlinear term**  $(u \cdot \nabla)u$ . We can also see, that  $\nu \Delta u$  (similar to Heat equation) is the **diffusion part**. In the second equations,  $\nabla \cdot u = 0$  explained the **incompressible condition** of fluid.

**Incompressible condition :**

$$\nabla \cdot u = \text{div } u = 0 \Leftrightarrow \text{fluid is incompressible}$$

means that the total amount of body does not change. By

$$0 = \int_V \nabla \cdot u \, dx = \int_{\partial V} u \cdot n \, ds$$

means that the energy that comes in and comes out is same and the normal component of velocity is  $0 = \int_{\partial V} u \cdot n \, ds$  where  $n$  is the normal vector works on boundary.

**Convection effect :**

[**simple explanation.**] Let  $\phi^0(x), c > 0$  is given. Consider  $\phi(x, t) = \phi^0(x - ct)$ , that represent the movement of function without changing the shape.

at  $t = 0$  we have  $\phi(x, 0) = \phi^0(x)$  ; at  $t = 1$  we have  $\phi(x, 1) = \phi^0(x - c)$  ; at  $t = 2$  we have  $\phi(x, 2) = \phi^0(x - 2c)$  as shown above.

### 1.1.2 3D Problem

For  $d = 3$ , then  $u = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$  such that for  $(i = 1, 2, 3)$  we have

$$\frac{\partial u_i}{\partial t} + (u \cdot \nabla)u_i - \nu \Delta u_i + [\nabla p]_i = f_i$$

where

$$\begin{aligned}(u \cdot \nabla)u_i &= \left( \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \cdot \begin{bmatrix} \partial_1 \\ \partial_2 \\ \partial_3 \end{bmatrix} \right) u_i \\ &= (u_1 \partial_1 + u_2 \partial_2 + u_3 \partial_3) u_i \\ &= u_1 \frac{\partial u_i}{\partial x_1} + u_2 \frac{\partial u_i}{\partial x_2} + u_3 \frac{\partial u_i}{\partial x_3}\end{aligned}$$

and

$$\Delta u_i = \frac{\partial^2 u_i}{\partial x_1^2} + \frac{\partial^2 u_i}{\partial x_2^2} + \frac{\partial^2 u_i}{\partial x_3^2}.$$

**Note :**we have  $u_1, u_2, u_3, p$  as four unknown functions and four equations (as first equation defined for three  $u$  and second equation), then we could find the solution.