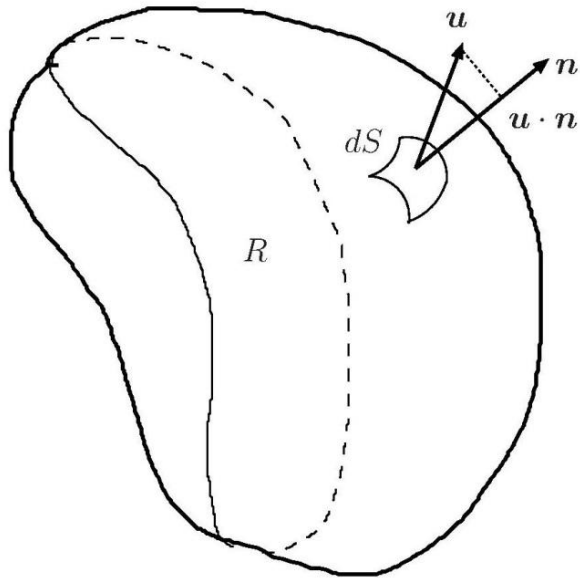


# Nonlinear PDEs

2<sup>nd</sup> lecture

# Divergence theorem

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$$\iiint_R \operatorname{div} \mathbf{u} \, dV = \iint_S \mathbf{u} \cdot \mathbf{n} \, dS$$

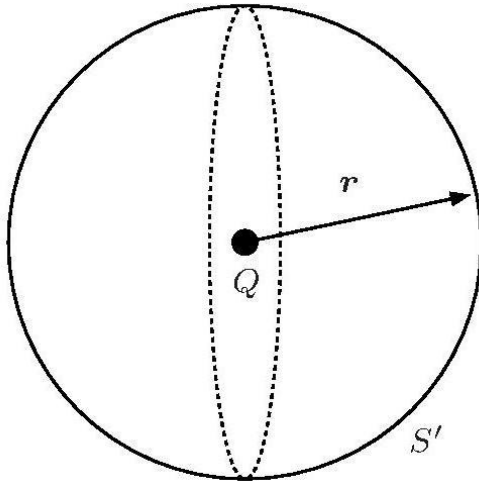
Physical meaning: the total divergence of a vector field inside a closed domain  $R$  is equal to the total of the flux through the boundary of the domain.

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# Gauss's law

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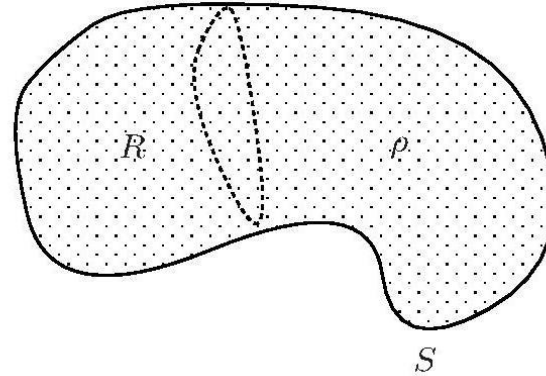


Electric flux density  $\mathbf{D}$  at any point on a spherical surface  $S'$  of radius  $r$  centered at an isolated point charge  $Q$  is:

$$\mathbf{D} = \frac{Q}{4\pi r^2} \mathbf{r} \quad [\text{C/m}^2]$$

Integrate over the sphere:

$$\int_{S'} \mathbf{D} \cdot d\mathbf{S} = \frac{Q}{4\pi r^2} 4\pi r^2 = Q$$



Similarly for any domain  $R$  with surface  $S$  and charge density  $\rho$ :

$$\iint_S \mathbf{D} \cdot d\mathbf{S} = \iiint_R \rho \, dx$$

By **divergence theorem**:

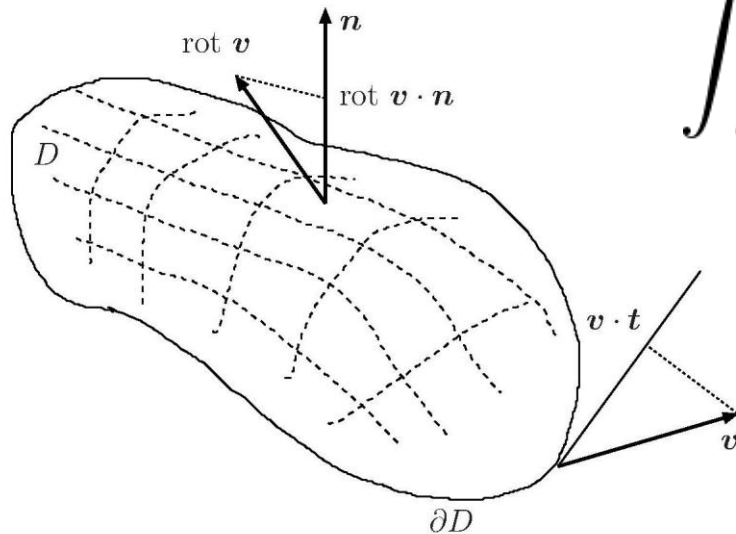
$$\iint_S \mathbf{D} \cdot d\mathbf{S} = \iiint_R \text{div} \mathbf{D} \, dx$$



Gauss's law:  $\boxed{\text{div} \mathbf{D} = \rho}$

# Stokes' theorem

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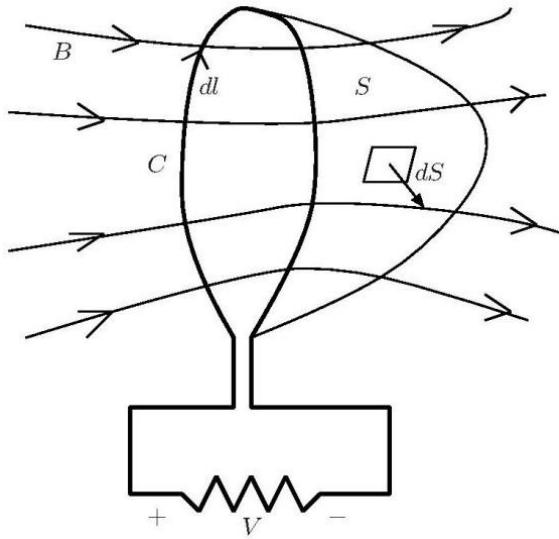
$$\iint_D (\text{rot } \mathbf{v}) \cdot \mathbf{n} \, dS = \int_{\partial D} \mathbf{v} \cdot d\mathbf{s}$$

**Physical meaning:** The total circulation inside a closed domain  $D$  is equal to the line integral along the boundary  $\partial D$  of the domain.

---



# Faraday's law



Faraday's law: The induced electromotive force in any closed circuit is equal to the time rate of change of the magnetic flux through the circuit.

$$V = -\frac{\partial}{\partial t}\psi \quad V = \int_C E \cdot dl$$
$$\psi = \int_S B \cdot dS$$

Therefore,  $\int_C E \cdot dl = -\frac{\partial}{\partial t} \int_S B \cdot dS$

By **Stokes' theorem**

$$\int_C E \cdot dl = \int_S \text{rot } E \cdot dS$$



Faraday's law:

$$\boxed{\text{rot } E = -\frac{\partial B}{\partial t}}$$

# Examples of electromagnetic devices

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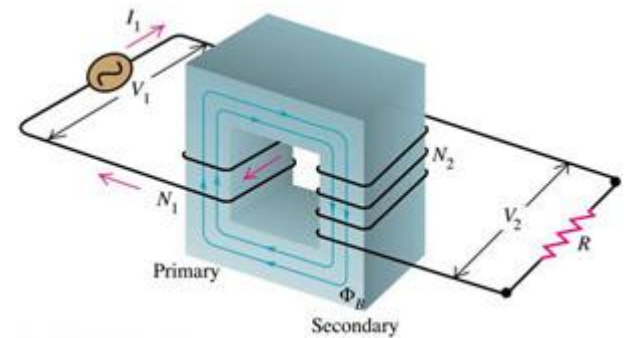
Electromagnets

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# Examples of electromagnetic devices

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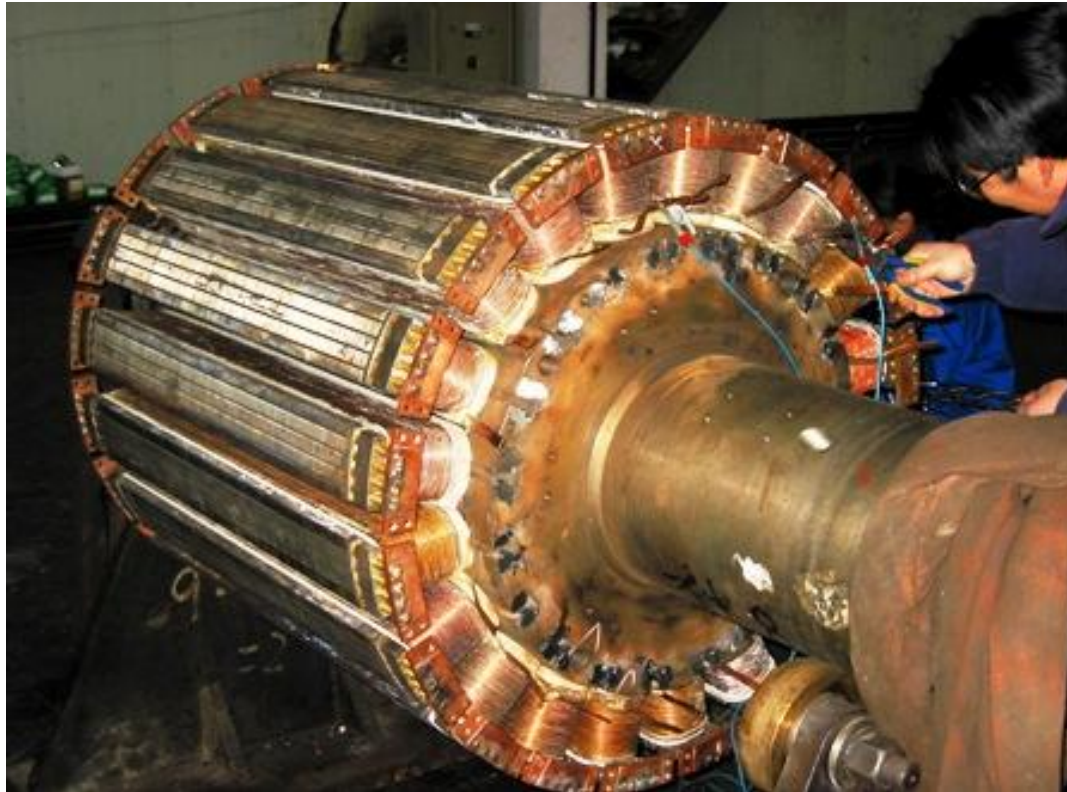
## Transformers

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# Examples of electromagnetic devices

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Synchronous rotors

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# Examples of electromagnetic devices

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Asynchronous motors

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# Examples of electromagnetic devices

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Induction coils

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# Examples of electromagnetic devices

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Magnetic heads

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# Examples of electromagnetic devices

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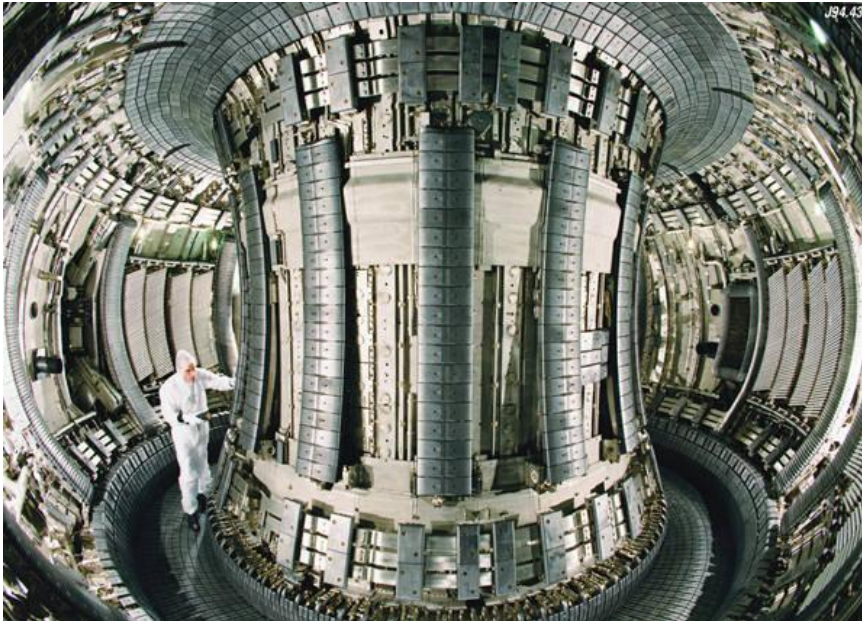
Electron microscopes

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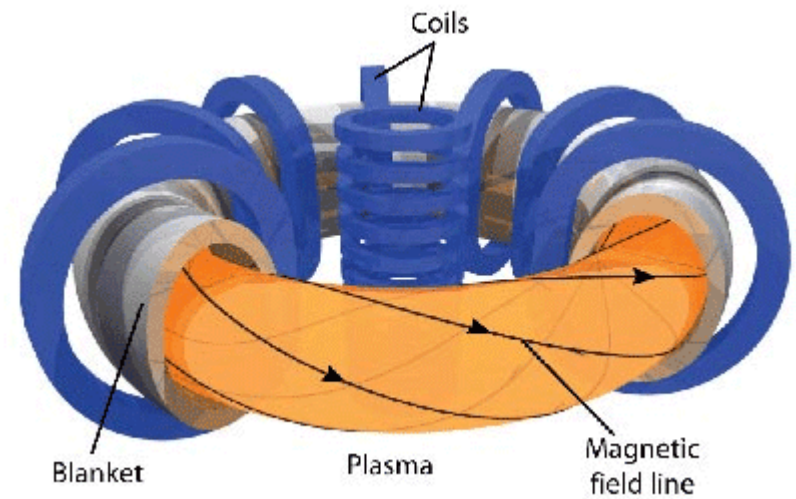


# Examples of electromagnetic devices

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Tokamaks





# Examples of electromagnetic devices

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Linear accelerators

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# Maxwell's equations

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$$\operatorname{rot} H = J + \frac{\partial D}{\partial t}, \quad (\text{Ampère's law})$$

$$\operatorname{rot} E = -\frac{\partial B}{\partial t}, \quad (\text{Faraday's law})$$

$$\operatorname{div} D = \rho, \quad (\text{Gauss's law})$$

$$\operatorname{div} B = 0, \quad (\text{Gauss's law for electromagnetism})$$

$$D = \varepsilon E, \quad (\text{constitutive relation})$$

$$B = \mu H. \quad (\text{constitutive relation})$$

$H$	...	magnetic field intensity [A/m]
$E$	...	electric field intensity [V/m]
$D$	...	electric induction (or flux density) [C/m <sup>2</sup> ]
$B$	...	magnetic induction (or flux density) [Wb/m <sup>2</sup> ]
$J$	...	current density [A/m <sup>2</sup> ]
$\rho$	...	charge density [C/m <sup>3</sup> ]
$\mu$	...	permeability
$\varepsilon$	...	permittivity .



# Constitutive equation

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$$H = \frac{1}{\mu} B \quad \Rightarrow \quad H(x) = \nu(x, \|B(x)\|^2) B(x)$$

$$\nu(x, \eta) = \begin{cases} \nu_1(\eta) & \text{for } x \in \Omega_1 = \text{ferromagnetic materials} \\ \nu_0 & \text{for } x \in \Omega_0 = \text{other materials (insulators, air, etc.)} \end{cases}$$

