

Reinforcement Learning Based Routing in Networks: Review and Classification of Approaches

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Q-routing

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Most of the existing RL-based routing protocols today are extensions of their work.

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1: function QROUTING( )
2:   Initialize  $Q_i$  matrix randomly
3:   while termination condition holds do
4:     if packet  $P$  is ready to be sent to  $d$  then
5:       Determine node  $j^* \leftarrow \arg \min_{j \in \mathcal{N}(i)} Q_i(d, j)$ 
6:       Send packet to node  $j^*$ 
7:       Collect estimate  $\theta_{j^*}(d)$  from node  $j^*$ 
8:       Update  $Q_i(d, j^*) \leftarrow (1 - \alpha) \cdot Q_i(d, j^*) + \alpha \cdot [W_i^q(P) + T_{ij^*} + \theta_{j^*}(d)]$ 
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- ▶ i is the node that is currently running the algorithm
- ▶ P is a packet that node i needs to forward to destination d
- ▶ $Q_i(d, j)$ is the *delivery delay* that i estimates it takes, for node j , to deliver the packet P at destination i
- ▶ $\mathcal{N}(j)$ is the set of j 's neighbors
- ▶ $\theta_j(d)$ is j 's estimate for the time remaining in the trip to destination d of packet P
- ▶ $W_i^q(P)$ is the time spent by packet P in node i 's queue
- ▶ T_{ij} is the transmission time between nodes i and j

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Upon sending packet P to node j^* , node i receives back from node j^* the estimate

$$\theta_{j^*}(d) = \min_{k \in \mathcal{N}(j^*)} Q_{j^*}(d, k)$$

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Then, node i updates $Q_i(d, j^*)$ based on the *update formula* for Q-learning:

$$Q(s_t, a_t) = (1 - \alpha) \cdot Q(s_t, a_t) + \alpha \cdot \left[R_{t+1} + \gamma \cdot \max_{a \in \mathcal{A}} Q(s_{t+1}, a) \right]$$

Q-learning

Despite the wide adoption, Q-routing has some flaws. Some problems are direct consequences of Q-learning such as

- ▶ *slow convergence*
- ▶ *high parameter setting sensitivity*

However, there are also problems arising from the algorithm itself.

Q-learning

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However, there are also problems arising from the algorithm itself.

For instance the **Q-value freshness**: $\theta_j(d)$ is evaluated only upon packet transmission on a route, therefore if a route is not used for a long time its estimate becomes *outdated*.

Classification criteria

To their knowledge, the authors state that their work is the first in the literature that proposed **classification criteria** to help comparing all available RL-based routing protocols in the literature.

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These criteria are divided into 3 groups:

1. **Context of use:** criteria based on the *target applications*
2. **Design characteristics:** criteria based on the *design* of the protocols
3. **Performance:** criteria based on qualitative evaluation on *overhead* and *metrics*

Context of use — Network class and assumptions

TODO

Context of use — Routing optimization context

A *good* protocol should be able to determine and select the optimal paths to convey data from sources to destinations. This can be TODO

Context of use – Unicast or Multicast

Categorizing between **unicast** or **multicast** approaches is a natural choice, given the inherent *overhead* that multicast routing protocols require.

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Indeed, RL should be applied in multicasting scenarios only when links are sufficiently stable and/or partial delivery is allowed, otherwise convergence may be outright *impossible*.

Context of use — QoS metrics for optimization

The choice of the metrics is one of the most important aspects of a protocol. When multiple metrics are utilized, they are *weighted* based on the importance — which depends on the target application.

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Quality of Service (QoS) metrics that have been addressed as objectives for RL-based routing include:

- ▶ **delivery rate**: average time to deliver a packet
- ▶ **delivery ratio**: proportion of packets successfully delivered
- ▶ **hop count**: average number of hops from source to destination
- ▶ **loss ratio**: proportion of packets not delivered

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Quality of Service (QoS) metrics that have been addressed as objectives for RL-based routing include:

- ▶ **bandwidth:** average bandwidth provided to sources
- ▶ **throughput:** average amount of bytes delivered in the entire network per time unit
- ▶ **path stability:** it indicates how a path between source and destination changes over time
- ▶ **energy consumption:** average energy consumption of the network

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Quality of Service (QoS) metrics that have been addressed as objectives for RL-based routing include:

- ▶ **network lifetime**: average time over which the network is still alive
- ▶ **transmission power**: power for performing a transmission
- ▶ **hit delay**: average delay to return requested data in peer-to-peer networks
- ▶ **hit ratio**: proportion of satisfied requests in peer-to-peer networks

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Quality of Service (QoS) metrics that have been addressed as objectives for RL-based routing include:

- ▶ **gain**: average revenue (in \$) received by the agent — in business contexts
- ▶ **overhead**: average *cost* to deliver data packets at destination — the *cost* definition depends on the application

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Lastly, a few routing protocols are aimed at providing QoS guarantees, regarding delivery delay to meet some requirements of **delay-sensitive applications**.

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For instance, this is essential in *multimedia applications*.