

"SAPIENZA" UNIVERSITY OF ROME FACULTY OF INFORMATION ENGINEERING, INFORMATICS AND STATISTICS DEPARTMENT OF COMPUTER SCIENCE

Models of Computation

Lecture notes integrated with the book TODO

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Information and Contacts

Personal notes and summaries collected as part of the *Models of Computation* course offered by the degree in Computer Science of the University of Rome "La Sapienza".

Further information and notes can be found at the following link:

https://github.com/aflaag-notes. Anyone can feel free to report inaccuracies, improvements or requests through the Issue system provided by GitHub itself or by contacting the author privately:

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The notes are constantly being updated, so please check if the changes have already been made in the most recent version.

Suggested prerequisites:

- Linguaggi di Programmazione
- Tecniche di Programmazione Funzionale ed Imperativa

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1 TODO

1.1 λ -caluclus

In this first section, examples will be omitted from this notes, refer to the notes of the "Linguaggi di Programmazione" course for further details.

Definition 1.1: λ -calculus

Let Var be the set of all possible variables; thus, the set Λ of all possible λ -terms is defined by the following rules:

$$[var] \frac{x \in \text{Var}}{x \in \Lambda}$$

$$[appl] \frac{M \in \Lambda \quad N \in \Lambda}{MN \in \Lambda}$$

$$[abs] \ \frac{x \in \text{Var} \quad M \in \Lambda}{\lambda x. M \in \Lambda}$$

The terms of the form $\lambda x.M$ are called λ -abstractions, and MN is the function application of M to N. Note that function application associates to the left, therefore

$$MNL = (MN)L \neq M(NL)$$

Lambda calculus can be alternatively defined with the Backus Normal Form (BNF), as follows:

$$M, N ::= x \mid \lambda x.M \mid MN$$

Although all functions in lambda calculus are unary, the following definition can expand

this concept.

Definition 1.2: Currying

Currying (named after Haskell Curry) is defined as follows:

$$\lambda x_1.(\dots(\lambda x_n.y)) \equiv \lambda x_1\dots x_n.y$$

Additionally, the following notation

$$\lambda \overrightarrow{x} \cdot f \overrightarrow{x}$$

will denote **vectors** in place of

$$\lambda x_1 \dots x_n \cdot f \ x_1 \dots x_n$$

Definition 1.3: Boundness

A variable is said to be **bound** if it is declared in a λ -abstraction, otherwise it is said to be **free**.

A term that has no free variables is said to be **closed** or **combinator**.

Example 1.1 (Boundness). Consider the following term:

$$\lambda x.xy$$

In this example, x is bound, and y is free.

Definition 1.4: Notable combinators

The following are some of the **notable combinators**:

$$I \equiv \lambda x.x$$

$$K \equiv \lambda xy.x$$

$$O \equiv \lambda xy.y$$

$$S \equiv \lambda xyz.xz(yz)$$

$$B \equiv \lambda f g x. f(g x)$$

$$C \equiv \lambda abc.acb$$

$$W \equiv \lambda xy.xyy$$

In particular

- I stands for "Identity", in fact it is the identity function
- K stands for "Konstant", meaning *constant* in german, and in fact K yields a constant function

- S stands for "Satz", which translates to *substitution* in german, and plays a central role in Section 1.1.5
- B stands for "Belegung", meaning binding in german, in fact B is the composition operator
- C stands for "Commutator", which is precisely what the C combinator performs
- W is the duplicating combinator, and it is called W because the letter W resambles the shape of two V's placed side by side

Definition 1.5: Free variables

Given a λ -term, the function

free :
$$\Lambda \to \mathcal{P}(Var)$$

returns the set of free variables in M, and it is defined recursively as follows:

$$\begin{cases} \operatorname{free}(x) := \{x\} \\ \operatorname{free}(MN) := \operatorname{free}(M) \cup \operatorname{free}(N) \\ \operatorname{free}(\lambda x.M) := \operatorname{free}(M) - \{x\} \end{cases}$$

1.1.1 β -reduction

Definition 1.6: Substitution

The **substitution** operation is recursively defined by the following rules:

$$x[N/x] = N$$

$$y[N/x] = y$$

$$(PQ)[N/x] = P[N/x] \ Q[N/x]$$

$$(\lambda y.P)[N/x] = \lambda y.(P[N/x]) \text{ if } y \neq x$$

$$(\lambda x.P)[N/x] = \lambda x.P$$

where M[N/x] means that each instance of x in M is replaced with N. Note that only free variables may be substituted.

Lemma 1.1: Substitution lemma

Let $M, N, L \in \Lambda$; if $x \neq y$ and $x \notin \text{free}(L)$, then

$$M[M/x][L/y] \equiv M[L/y][N[L/y]/x]$$

Proof. By induction on the structure of M, the details are omitted.

Definition 1.7: Inference rules

The following are the **inference rules** for the lambda caluclus:

$$(\alpha) \ \lambda x.M \equiv (\lambda y.M)[y/x]$$

$$(\beta) \ (\lambda x.M)N \ \stackrel{\beta}{\longrightarrow} \ M[N/x]$$

$$(\mu) \ \frac{M \ \stackrel{\beta}{\longrightarrow} \ M'}{NM \ \stackrel{\beta}{\longrightarrow} \ NM'}$$

$$(\nu) \ \frac{M \ \stackrel{\beta}{\longrightarrow} \ M'}{MN \ \stackrel{\beta}{\longrightarrow} \ M'N}$$

$$(\xi) \ \frac{M \ \stackrel{\beta}{\longrightarrow} \ M'}{\lambda x.M \ \stackrel{\beta}{\longrightarrow} \ \lambda x.M'}$$

Note that the β -rule is effectively one step of the computation described by the λ -term.

If $M \equiv N$ is provable in the λ -caluclus, it will be written as

$$\lambda \vdash M \equiv N$$

Additionally, if a term N can be derived from M through β -reductions

$$M \xrightarrow{\beta} \dots \xrightarrow{\beta} N$$

it will be written as $M \rightsquigarrow N$.

Definition 1.8: Normal form

If a term can be β -reduced, it is called β -redex, or simply redex (reducible expression), and the reduced term is called β -reduct, or simply reduct.

If a term has no redexes, it is said to be in **normal form**.

Observation 1.1: Variable capture

Consider the following λ -term:

$$(\lambda x t.tx)(\lambda t.y) \xrightarrow{\beta} \lambda t.t(\lambda t.y)$$

Note that the two ts are different. In fact, underlining the λ -abstractions to which they are bounded to can help clarifying their distinction:

$$(\lambda x \underline{t}.\underline{t}x)(\lambda t.y) \xrightarrow{\beta} \lambda \underline{t}.\underline{t}(\lambda t.y)$$

Now, consider the following λ -term, similar to the previous one:

$$(\lambda xy.yx)(\lambda t.y) \xrightarrow{\beta} \lambda y.y(\lambda t.y)$$

This β -reduction created a problem, because now the two ys are the same, even though they were not originally. In fact, the previous term can be relabeled as follows:

$$(\lambda xy.yx)(\lambda t.y) \xrightarrow{\beta} \lambda y.y(\lambda t.y)$$

This happened because

free
$$(\lambda t.y) = \{y\} - \{t\} = \{y\}$$

therefore y was **captured** by the y that was already present in the leftmost λ -abstraction. This phenomena is called **variable capturing**, and constitutes a problem when reducing β -redexes. In particular, to reduce this second λ -abstraction, it is necessary to apply a substitution, by using the α rule (refer to Definition 1.7):

$$\lambda xy.yx = \lambda x(\lambda y.yx) = \lambda x.((\lambda y.yx)[u/y]) = \lambda x.(\lambda u.ux) = \lambda xu.ux$$

which means that the β -reduction can now be performed without any issue:

$$(\lambda x u.ux)(\lambda t.y) \xrightarrow{\beta} \lambda u.u(\lambda t.y)$$

where y is still free. Note that it would not have been safe to rename the other (free) y, because in general renaming free variables can create capturing problems as well. For example, y could have not been substituted with t, as it would otherwise be captured by the t in the λ -term $\lambda t.y$, as follows:

$$(\lambda t.y)[t/y] = \lambda t.t$$

Fortunately, variable capturing can be solved by employing the following *variable naming* convention.

Definition 1.9: Variable naming convention

To avoid variable capturing problems, it is sufficient to follow this **variable naming convention**: bound and free variables must have different names between them.

From now on, it will be assumed that any β -reduction is performed by renaming opportunely the **bound** variables, such that in each step of the computation the naming convention is followed.

1.1.2 Data structures

Definition 1.10: Tuples

A **tuple** of the form

$$(M_1,\ldots,M_k)$$

can be represented in λ -calculus as follows:

$$\lambda x.xM_1...M_k$$

In λ -caluclus, tuples will be represented as follows

$$[M_1,\ldots,M_k]$$

To access the elements of a tuple, projectors are used, which are defined below.

Definition 1.11: Projector

A **projector** has the following form

$$\lambda x.x\pi_j^k$$

where

$$\pi_j^k \equiv \lambda x_1 \dots x_k . x_j$$

Example 1.2 (Projectors). Given a tuple $\lambda x.xM_1...M_k$, its *j*-th element can be accessed as follows:

$$\lambda x.x\pi_j^k(\lambda x.xM_1...M_k) \stackrel{\beta}{\longrightarrow} (\lambda x.xM_1...M_k)\pi_j^k \stackrel{\beta}{\longrightarrow} \pi_j^kM_1...M_k \stackrel{\beta}{\longrightarrow} M_j$$

Definition 1.12: Booleans

Booleans can be defined in λ -calculus as follows:

$$T \equiv \lambda xy.x$$

$$F \equiv \lambda xy.y$$

Definition 1.13: Conditionals

Conditionals can be defined in λ -calculus as follows:

ite =
$$\lambda xyz.xyz$$

Note that ite stands for "if-then-else", and in fact, the term behaves exactly like a condition when used in conjunction with the λ -booleans.

Observation 1.2: Conditionals

The term ite correctly behaves as a *conditional* when used with T and F. In fact, when used in an term such as

if C is a λ -boolean, the term with be β -reduced to A if C \equiv T, and it will be evaluated to B if C \equiv F. Indeed

ite T A B
$$\equiv (\lambda xyz.xyz)$$
 T A B
$$\stackrel{\beta}{\longrightarrow} \text{T A B}$$

$$\equiv (\lambda xy.x) \text{ A B}$$

$$\stackrel{\beta}{\longrightarrow} \text{ A}$$

and

ite F A B
$$\equiv (\lambda xyz.xyz)$$
 F A B
$$\xrightarrow{\beta}$$
 F A B
$$\equiv (\lambda xy.y)$$
 A B
$$\xrightarrow{\beta}$$
 B

Additionally, it is possible to define the logical **not** operator, as follows:

$$not \equiv \lambda t.tFT$$

which clearly negates the boolean given as input

not
$$T \equiv (\lambda t. tFT) T \xrightarrow{\beta} F$$

not $F \equiv (\lambda t. tFT) F \xrightarrow{\beta} T$

Definition 1.14: Church numerals

The **Church numerals** are defined by a mapping between natural numbers \mathbb{N} and λ -abstractions:

$$\varphi: \mathbb{N} \to \Lambda: n \mapsto \lambda xy.\underbrace{x(\dots(xy))}_{n \text{ times}}$$

The Church numeral corresponding to $n \in \mathbb{N}$ will be represented as $\underline{n} \in \Lambda$.

Example 1.3 (Church numerals). For example, the number $\underline{0}$ is represented as

$$\varphi(0) = 0 = \lambda xy.y \equiv F \equiv O$$

number $\underline{1}$ as

$$\varphi(1) = \underline{1} = \lambda xy.xy \equiv T \equiv K$$

and number 2 as

$$\varphi(2) = \underline{2} = \lambda xy.x(xy)$$

and so on.

Observation 1.3: Church numerals are iterators

Note that Church numerals are **iterators**, in the sense that \underline{n} replicates any input function f for n times

$$\underline{n} \ f \ \chi \equiv (\lambda x y. \underbrace{x(\dots(x \ y))}_{n \text{ times}}) f \ \chi$$

$$\xrightarrow{\beta} \underbrace{f(\dots(f \ \chi))}_{n \text{ times}}$$

The following are some important λ -functions for Church numerals:

• successor function:

$$\underline{s} \equiv \lambda xyz.xy(yz)$$

which given a Church numeral \underline{n} , it returns n+1, which is easy to show

$$\underline{s} \ \underline{n} \equiv (\lambda abc.ab(bc)) \ (\lambda xy.\underbrace{x(\dots(x\,y))}_{n \text{ times}})$$

$$\xrightarrow{\beta} \lambda bc.(\lambda xy.\underbrace{x(\dots(x\,y))}_{n \text{ times}} b \ (bc))$$

$$\xrightarrow{\beta} \lambda bc.(\lambda y.\underbrace{b(\dots(b\,y))}_{n \text{ times}} (bc))$$

$$\xrightarrow{\beta} \lambda bc.\underbrace{b(\dots(b\,c))}_{n+1 \text{ times}}$$

• is-zero function:

$$z \equiv \lambda f. f(\lambda t. F) T$$

which given a Church numeral \underline{n} , it returns T if and only if \underline{n} is $\underline{0}$, and it can be proven at follows

$$\underline{z} \ \underline{0} \equiv (\lambda f. f(\lambda t. F) T) \ (\lambda xy. y)$$

$$\xrightarrow{\beta} \ (\lambda xy. y) (\lambda t. F) T$$

$$\xrightarrow{\beta} \ T$$

and

$$\underline{z} \ \underline{n} \equiv (\lambda f. f(\lambda t. F) T) \ (\lambda xy. \underbrace{x(\dots(x \ y))}_{n \text{ times}})$$

$$\xrightarrow{\beta} \ (\lambda xy. \underbrace{x(\dots(x \ y))}_{n \text{ times}}) (\lambda t. F) T$$

$$\xrightarrow{\beta} \ \underbrace{(\lambda t. F)(\dots((\lambda t. F)}_{n \text{ times}} T))$$

$$\xrightarrow{\beta} F$$

• addition function:

$$add \equiv \lambda ab.a \ s \ b$$

a proof of this function is omitted, but it can be intuitively explained by using Observation 1.3, which suggests that if \underline{a} and \underline{b} are two Church numerals, then $\underline{a} \underline{s} \underline{b}$ is the repeated application of \underline{s} exactly a times to \underline{b}

• predecessor function:

$$P \equiv \lambda x. x(\lambda abz. zb(\underline{s}\ b))$$

which is a term such that

$$P [\underline{m}, \underline{n}] \equiv (\lambda x. x(\lambda abz. zb(\underline{s}\ b))) (\lambda u. u \ \underline{m}\ \underline{n})$$

$$\xrightarrow{\beta} (\lambda u. u \ \underline{m}\ \underline{n})(\lambda abz. zb(\underline{s}\ b))$$

$$\xrightarrow{\beta} (\lambda abz. zb(\underline{s}\ b)) \ \underline{m}\ \underline{n}$$

$$\xrightarrow{\beta} \lambda z. z \ \underline{n}\ (\underline{s}\ \underline{n})$$

$$\equiv [\underline{n}, n+1]$$

therefore

$$\underline{n} \ P \ [\underline{0}, \underline{0}] \xrightarrow{\beta} \underbrace{P(\dots(P \ [\underline{0}, \underline{0}]))}_{n \text{ times}}$$

$$\xrightarrow{\beta} \underbrace{P(\dots(P \ [\underline{0}, \underline{1}]))}_{n-1 \text{ times}}$$

$$\xrightarrow{\beta} \underbrace{P(\dots(P \ [\underline{1}, \underline{2}]))}_{n-2 \text{ times}}$$

$$\xrightarrow{\beta} \dots$$

$$\xrightarrow{\beta} [n-1, \underline{n}]$$

which means that the following term

$$\underline{p} \equiv \lambda x.(x P [\underline{0}, \underline{0}])T$$

is such that

$$\underline{p} \ \underline{n} \leadsto \underline{n-1}$$

Church numerals are not the only way to define a system of numerals in λ -calculus. In fact, Hank Barendregt proposed the following system in 1976.

Definition 1.15: Barendregt numerals

The Barendregt numerals are defined inductively as follows:

$$\lceil 0 \rceil \equiv \mathbf{I}$$

$$\lceil n + 1 \rceil \equiv [\mathbf{F}, \lceil n \rceil]$$

Therefore, we have that

$$\lceil n \rceil \equiv \underbrace{[F, \dots, [F, I]]}_{n \text{ times}}, I$$

From this definition, the following λ -function for Barendregt numerals can be defined:

• successor function:

$$\mathbf{s} \equiv \lambda x.x[\mathbf{F}, x]$$

• predecessor function:

$$\mathbf{f} \equiv \lambda x.x \ F$$

which consumes the outermost tuple

• is-zero function:

$$\mathbf{z} \equiv \lambda x.x \mathrm{T}$$

because it returns F, the first element of any tuple, for any Barendregt numeral, except when the input is not a tuple but I itself, which is precisely '0'

1.1.3 Recursion

Definition 1.16: Fixed point

Given a function $f: X \to Y$, an element $x \in X$ is said to be a **fixed point of** f if and only if f(x) = x.

Example 1.4 (Fixed points). Given a function $f(x) = x^2 - 3x + 4$, x = 2 is a fixed point of f, because

$$f(x) = 2^2 - 3 \cdot 2 + 4 = 4 - 6 + 4 = 2 = x$$

and thus f(x) = x.

Example 1.5 (Functions are fixed points). Consider the following function

$$F(g) :\equiv h(x) = \begin{cases} 1 & x = 0 \\ x \cdot g(x - 1) & x > 0 \end{cases}$$

that takes a function as input, an returns a function h; for instance, plugging in the following function

$$\mathrm{succ}: x \to x + 1$$

we get that F returns the following function

$$F(\text{succ}) \equiv h(x) = \begin{cases} 1 & x = 0\\ x \cdot \text{succ}(x-1) = x \cdot x = x^2 & x > 0 \end{cases}$$

which is the function that returns 1 if x = 0, and x^2 otherwise.

It's easy to check that the *fixed point* of F is the following function:

$$fact(x) := \begin{cases} 1 & x = 0 \\ x \cdot fact(x-1) & x > 0 \end{cases}$$

which computes the factorial of x, because

$$F(\text{fact}) \equiv h(x) = \begin{cases} 1 & x = 0 \\ x \cdot \text{fact}(x - 1) & x > 0 \end{cases} \equiv \text{fact}$$

Definition 1.17: Kleene's combinator

The fixed point operator, Y combinator or Kleene's combinator (named after Stephen Kleene) is defined as follows:

$$Y \equiv \lambda f.(\lambda x. f(xx))(\lambda x. f(xx))$$

The Y combinator can be alternatively defined as follows:

$$Y \equiv (\lambda xy.y(xxy))(\lambda xy.y(xxy))$$

Proposition 1.1: Fixed point operator

Given a function, Kleene's combinator returns its fixed point.

Proof. If the Kleene's combinator can return the fixed point of a given function h, it means that Yh is h's fixed point. Therefore, the statement that has to be proved is that

$$h(Yh) = Yh$$

This can be proved for both formulations of the Y combinator, as follows:

$$Yh \xrightarrow{\beta} (\lambda f.(\lambda x.f(xx))(\lambda x.f(xx)))h$$

$$\xrightarrow{\beta} (\lambda x.h(xx))(\lambda x.h(xx))$$

$$\xrightarrow{\beta} h(\lambda x.h(xx)\lambda x.h(xx))$$

$$\xrightarrow{\beta} h(Yh)$$

and for the alternative formulation

$$\begin{array}{ccc} \mathbf{Y}h & \stackrel{\beta}{\longrightarrow} & ((\lambda xy.y(xxy))(\lambda xy'.y'(xxy')))h \\ & \stackrel{\beta}{\longrightarrow} & (\lambda y.y((\lambda xy'.y'(xxy'))(\lambda xy''.y''(xxy''))y))h \\ & \stackrel{\beta}{\longrightarrow} & h((\lambda xy'.y'(xxy'))(\lambda xy''.y''(xxy''))h) \\ & \stackrel{\beta}{\longrightarrow} & h(\mathbf{Y}h) \end{array}$$

Note that the Y combinator can be used to perform recursion inside λ -calculus, because of the following property:

$$h(Yh) = Yh$$

$$h(h(Yh)) = h(Yh) = Yh$$

$$\vdots$$

$$h(\dots(h(Yh))) = Yh$$

1.1.4 Recursive functions

Definition 1.18: Numeric function

A numeric function is a map $f: \mathbb{N}^p \to \mathbb{N}$ for some p.

Definition 1.19: λ -definable function

A function is said to be λ -definable if there exists a closed term F such that

$$F \ \underline{n_1} \dots \underline{n_p} \equiv \underline{f(n_1, \dots, n_p)}$$

If that is the case, f is said to be λ -defined by F.

Definition 1.20: Initial functions

The following are the so called **initial functions**:

$$U_r^i(x_1, \dots, x_r) = x_i, \quad 1 \le i \le r$$

 $\operatorname{succ}(n) = n + 1$
 $\operatorname{zero}(n) = 0$

In particular, the first equations are called **projection functions**, the second is the **successor function** and the last is called **constant function**.

Definition 1.21: Composition

Given an m-ary function $h(x_1, \ldots, x_m)$ and k m-ary functions

$$g_1(x_1,\ldots,x_k),\ldots,g_m(x_1,\ldots,x_k)$$

, the **composition operator** is defined as follows:

$$f := h \circ (g_1, \dots, g_m)$$

where

$$f(\overrightarrow{x}) = h(g_1(\overrightarrow{x}), \dots, g_m(\overrightarrow{x}))$$

Lemma 1.2: Composition

The λ -definable functions are closed under *composition*.

Proof. Let h, g_1, \ldots, g_m be defined by the λ -terms H, G_1, \ldots, G_m respectively. Then

$$F \equiv \lambda \overrightarrow{x} \cdot H(G_1 \overrightarrow{x}) \dots (G_m \overrightarrow{x})$$

 λ -defines $h \circ (g_1, \ldots, g_m)$.

Definition 1.22: Primitive recursion

Given a k-ary function $g(x_1, ..., x_k)$ and a (k+2)-ary function $h(y, z, x_1, ..., x_k)$, the **primitive recursion operator** is a (k+1)-ary function ρ is defined as follows:

$$f := \rho(q, h)$$

where

$$f(0, \overrightarrow{n}) = g(\overrightarrow{x})$$

$$f(\operatorname{succ}(n), \overrightarrow{x}) = h(y, f(y, \overrightarrow{x}), \overrightarrow{x})$$

Lemma 1.3: Primitive recursion

The λ -definable functions are closed under *primitive recursion*.

Proof. Let f be a function such that

$$f(0) = g$$

$$f(k+1) = h(f(k), k)$$

which is a weaker version of the *primitive recursion operator*, but the proof for general \overrightarrow{n} is similar (details are omitted).

Consider the following term

$$T \equiv \lambda p.[\underline{s}(p T), H(p F)(p T)]$$

where H λ -defines h, and note how it computes over the following input

$$T [\underline{k}, \underline{f(x)}] \leadsto [\underline{s} \underline{k}, H \underline{f(x)} \underline{k}]$$

$$\stackrel{\beta}{\longrightarrow} [\underline{k+1}, H \underline{f(x)} \underline{k}]$$

$$\equiv [\underline{k+1}, f(k+1)]$$

(the last step follows from f's definition) therefore, T describes the following function

$$t: \mathbb{N} \times \mathbb{N} \to \mathbb{N} \times \mathbb{N} : (k, f(k)) \mapsto (k+1, f(k+1))$$

Hence, by induction, it follows that

$$[\underline{k},\underline{f(k+1)}] \equiv T^k \ [\underline{0},\underline{f(0)}]$$

and because Church numerals are iterators (as shown in Observation 1.3), it follows that

$$f(k) \equiv \underline{k} T [\underline{0}, f(0)] F$$

Finally, f can be λ -defined by the following term

$$F \equiv \lambda k.k \ T \ [\underline{0},\underline{G}] \ F$$

where G λ -defines g.

Definition 1.23: Minimalization

Given a (k+1)-ary function $f(y, x_1, \ldots, x_k)$, the **minimization operator** is a k-ary function $\mu(f)$ defined as follows:

$$\mu(f)(\overrightarrow{x}) = z \iff \forall i \in [0, z - 1] \quad f(i, \overrightarrow{x}) > 0 \land f(z, \overrightarrow{x}) = 0$$

In other words, that minimization operator seeks the smallest argument that causes the function to return zero. If there is no such argument, or if an argument is encountered for which f is not defined, then the search never terminates, and $\mu(f)$ is not defined for \overrightarrow{x} .

Lemma 1.4: Minimalization

The λ -definable functions are closed under minimalization

Proof. TODO

Definition 1.24: Recursive functions

The class \mathcal{R} is the smallest class of numeric functions that contains all initial functions, and is closed under composition, primitive recursion and minimization.

Theorem 1.1: Recursive functions

All recursive functions are λ -definable, therefore

$$\mathcal{R} \subsetneq \Lambda$$

Proof. The following terms λ -define initial functions:

$$U_p^i \equiv \pi_j^k$$

$$\operatorname{succ} \equiv \underline{s}$$

$$\operatorname{zero} \equiv \underline{0}$$

Thus, the theorem follows directly from Lemma 1.2, Lemma 1.3 and Lemma 1.4. \Box

1.1.5 Combinatory Logic

Definition 1.25: Combinatory Logic

Combinatory Logic is a simplified model of computation, related to λ -calculus, defined as follows:

$$[var] \frac{x \in \text{Var}}{x \in \text{CL}}$$

$$[appl] \ \frac{U \in \Lambda \quad V \in \Lambda}{UV \in \mathsf{CL}}$$

$$[const] \frac{x \in Const}{x \in CL}$$

where the set Const is defined by the following **constants**:

$$Const := \{S, K, I, B, C\}$$

Association rules are the same as the ones for λ -calculus. Note that, in combinatory logic, there are **no abstractions**, therefore *all variables are free*. To compute with CL, **reductions** are defined as follows:

$$Sxys \triangleright xy(yz)$$

$$Kxy \triangleright x$$

$$Ix \triangleright x$$

$$Bxyz \triangleright x(yz)$$

$$Cxyz \triangleright xzy$$

Theorem 1.2: Equivalence of λ -calculus and CL

Every λ -term can be written as a CL term, and viceversa.

Proof. Given a CL term $U \in CL$:

- if $U \in CL$ because $U \in Var$, then $U \in \Lambda$ by definition of Λ
- if $U \in CL$ because $U \equiv (MN)$ where $M, N \in CL$, then $(MN) \in \Lambda$ because applications are defined in λ -caluclus as well, and $M, N \in \Lambda$ inductively
- finally, if $U \in CL$ because $U \in Const$, then simply convert the CL constant into a λ -combinator (refer to Definition 1.4)

This proves that $CL \subseteq \Lambda$. To show the other inclusion, a similar reasoning can be applied, except for λ -abstractions, which do not exist in CL. Nevertheless, the following recursive algorithm returns a CL term equivalent to any given λ -abstraction. Let the swap operation be defined as follows:

swap:
$$\Lambda_{abstr} \to \mathrm{CL} : \lambda x.P \mapsto [x]P$$

then, the conversion algorithm defines additional rules to the *swap* operation as follows:

$$[x]Ux = U$$

$$[x]x = I$$

$$[x]U = KU$$

$$[x]UW = BU([x]W)$$

$$[x]VU = C([x]V)U$$

$$[x]VW = S([x]V)([x]W)$$

where $U, V, W \in CL$ are three CL terms such that $x \notin free(U)$ and $x \in free(V)$, free(W).

An intuition of the correctness of the algorithm can be provided as follows (bounded variables are renamed differently from Definition 1.4, to match the definitions in the algorithm):

- the first rule is a special case
- $\operatorname{swap}(I) = \operatorname{swap}(\lambda x.x) = [x]x$
- $\operatorname{swap}(KU) = \operatorname{swap}(\lambda x.U) = [x]U$
- $\operatorname{swap}(\mathrm{B}U(\lambda a.W)) = \operatorname{swap}(\lambda x.U(\lambda a.W)x) = [x]UW$
- $\operatorname{swap}(C(\lambda a.V)U) = \operatorname{swap}(\lambda x.(\lambda a.V)xU) = [x]VU$
- $\operatorname{swap}(S(\lambda a.V)(\lambda b.W)) = \operatorname{swap}(\lambda x.(\lambda a.V)x(\lambda(b.W)x)) = [x]VW$

Chapter 1. TODO

Example 1.6 (Conversion Λ to CL). Consider the following λ -term

$$\lambda xy.ytx$$

it can be converted into a CL term as follows

$$swap(\lambda xy.ytx) = swap([x](\lambda y.ytx))$$

$$= [x]([y](yt)x)$$

$$= [x](C([y]yt)x)$$

$$= [x](C(C([y]y)t)x)$$

$$= [x]C(CIt)x$$

$$= C(CIt)$$

and in fact

$$C(CIt)xy \triangleright CItyx$$

$$\triangleright Iyt$$

$$\triangleright ytx$$

Because CL and Λ are equivalent, Church numerals can be defined in CL as well:

- $\operatorname{swap}(\underline{0}) = \operatorname{swap}(\lambda xy.y) = [x][y]y = [x]I = KI \text{ and in fact } KIxy \triangleright Iy \triangleright y$
- $\operatorname{swap}(\underline{1}) = \operatorname{swap}(\lambda xy \cdot xy) = [x][y]xy = [x]x = I$ and in fact $Ixy \triangleright xy$
- $\operatorname{swap}(\underline{2}) = \operatorname{swap}(\lambda xy.x(xy)) = [x][y]x(xy) = [x]\operatorname{B}x([y]xy) = [x]\operatorname{B}xx = \operatorname{S}([x]\operatorname{B}x)([x]x) = \operatorname{SBI}$ and in fact $\operatorname{SBI}xy \triangleright \operatorname{B}x(\operatorname{I}x)y \triangleright \operatorname{B}xxy \triangleright x(xy)$
- in general, we have that

$$\operatorname{swap}(\underline{n}) = \underbrace{\operatorname{SB}(\dots(\operatorname{SB}I))}_{n-1 \text{ times}}$$

1.2 Exercises

Problem 1.1: Solve for X

Find X such that

$$Xx = \lambda t.t(Xx)$$

Solution. The term is

$$X \equiv (\lambda fbt.t(fb))X \implies X \equiv Y(\lambda fbt.t(fb))$$

because

$$\begin{array}{ccc} Xx & \stackrel{\beta}{\longrightarrow} & (\lambda fbt.t(fb))Xx \\ & \stackrel{\beta}{\longrightarrow} & (\lambda bt.t(Xb))x \\ & \stackrel{\beta}{\longrightarrow} & \lambda t.t(Xx) \end{array}$$

Problem 1.2: Solve for H

Find H such that

$$H(\lambda x_1 x_2 x_3.P) = \lambda x_3 x_2 x_1.P$$

Solution. The term is

$$H \equiv \lambda f x_3 x_2 x_1 . f x_1 x_2 x_3$$

because

$$H(\lambda x_1 x_2 x_3.P) \xrightarrow{\beta} (\lambda f x_3 x_2 x_1. f x_1 x_2 x_3)(\lambda x_1 x_2 x_3.P)$$

$$\xrightarrow{\beta} \lambda x_3 x_2 x_1. (\lambda x_1 x_2 x_3.P) x_1 x_2 x_2$$

$$\xrightarrow{\beta} \lambda x_3 x_2 x_1.P$$

Problem 1.3: Solve for X

Find X such that

$$Xxyz = Xz(uv)$$

Solution. The term is

$$X \equiv (\lambda tabc.tc(uv))X \implies X \equiv Y(\lambda tabc.tc(uv))$$

because

$$(\lambda tabc.tc(uv))Xxyz \xrightarrow{\beta} (\lambda abc.Xc(uv))xyz$$
$$\xrightarrow{\beta} Xz(uv)$$

Problem 1.4: Solve for Δ

Find Δ such that

$$\begin{cases} \Delta S = y_1 \\ \Delta K = y_2 \\ \Delta I = y_3 \end{cases}$$

Solution. Assume that

$$\Delta \equiv \lambda x. x P_1 P_2 P_3$$

for some λ -terms P_1 , P_2 and P_3 ; then

$$\begin{cases} \Delta S \xrightarrow{\beta} S P_1 P_2 P_3 \xrightarrow{\beta} P_1 P_3 (P_2 P_3) \\ \Delta K \xrightarrow{\beta} K P_1 P_2 P_3 \xrightarrow{\beta} P_1 P_3 \\ \Delta I \xrightarrow{\beta} I P_1 P_2 P_3 \xrightarrow{\beta} P_1 P_2 P_3 \end{cases}$$

However, this cannot be a correct assumption, because if

$$\Delta K \xrightarrow{\beta} P_1 P_3 = y_2$$

then

$$\Delta S \xrightarrow{\beta} P_1 P_3 (P_2 P_3) = y_2 (P_2 P_3) \neq y_1$$

which means that ΔS cannot be evaluated to y_1 . This issue can be solved by assuming that

$$\Delta \equiv \lambda x. x P_1 P_2 P_3 P_4$$

for some other term λ -term P_4 , in fact

$$\begin{cases} \Delta S \xrightarrow{\beta} S P_1 P_2 P_3 P_4 \xrightarrow{\beta} P_1 P_3 (P_2 P_3) P_4 \\ \Delta K \xrightarrow{\beta} K P_1 P_2 P_3 P_4 \xrightarrow{\beta} P_1 P_3 P_4 \\ \Delta I \xrightarrow{\beta} I P_1 P_2 P_3 P_4 \xrightarrow{\beta} P_1 P_2 P_3 P_4 \end{cases}$$

and if $P_1 = \lambda xy.y$ then

$$\Delta K \xrightarrow{\beta} P_1 P_3 P_4 \xrightarrow{\beta} (\lambda xy.y) P_3 P_4 \xrightarrow{\beta} P_4$$

which means that P_4 must be y_2 . Moreover

$$\Delta I \xrightarrow{\beta} P_1 P_2 P_3 P_4 \equiv (\lambda x y. y) P_2 P_3 y_2 \xrightarrow{\beta} P_3 y_2 = y_3 \iff P_3 = \lambda t. y_3$$

and finally

$$\Delta S \stackrel{\beta}{\longrightarrow} P_1 P_3 (P_2 P_3) P_4 \equiv (\lambda x y. y) (\lambda t. y_3) (P_2 (\lambda t. y_3)) y_2 \iff P_2 = \lambda a b. y_1$$

Problem 1.5: Solve for Δ

Find Δ such that

$$\begin{cases} \Delta(\lambda xyz.x(xyI)x) = y_1\\ \Delta(\lambda xyz.x(xyz)x) = y_2 \end{cases}$$

Solution. Let flip $\equiv \lambda xy.yx$; Δ can be defined as follows:

$$\Delta \equiv \lambda x.x$$
 flip T not $(\lambda x.xy_1y_2)$

in fact

$$(\lambda x.x \text{ flip T not } (\lambda x.xy_1y_2))(\lambda xyz.x(xyI)x) \rightsquigarrow \text{flip(flip T I)flip } (\lambda x.xy_1y_2)$$

$$\stackrel{\beta}{\longrightarrow} \text{ flip T flip } (\lambda x.xy_1y_2)$$

$$\stackrel{\beta}{\longrightarrow} \text{ flip T } (\lambda x.xy_1y_2)$$

$$\stackrel{\beta}{\longrightarrow} (\lambda x.xy_1y_2) \text{ T}$$

$$\stackrel{\beta}{\longrightarrow} y_1$$

and

$$(\lambda x.x \text{ flip T not } (\lambda x.xy_1y_2))(\lambda xyz.x(xyz)x) \rightsquigarrow \text{flip(flip T not)flip } (\lambda x.xy_1y_2)$$

$$\stackrel{\beta}{\longrightarrow} \text{ flip(not T) flip } (\lambda x.xy_1y_2)$$

$$\stackrel{\beta}{\longrightarrow} \text{ flip F } (\lambda x.xy_1y_2)$$

$$\stackrel{\beta}{\longrightarrow} (\lambda x.xy_1y_2) \text{ F}$$

$$\stackrel{\beta}{\longrightarrow} y_2$$

Problem 1.6: Solve for Δ

Find $\Delta = \lambda x.xUV$ such that

$$\begin{cases} \Delta \Delta = K \\ \Delta K = S \end{cases}$$

Solution. From the second equation we get that

$$\Delta \mathbf{K} \equiv (\lambda x. xUV) \mathbf{K}$$

$$\xrightarrow{\beta} \mathbf{K}UV$$

$$\xrightarrow{\beta} U$$

therefore

$$U = S$$

Hence, from the first equation

$$\Delta\Delta \equiv (\lambda x.xSV)(\lambda x.xSV)$$

$$\xrightarrow{\beta} (\lambda x.xSV)SV$$

$$\xrightarrow{\beta} SSVV$$

$$\xrightarrow{\beta} SV(VV)$$

$$\equiv (\lambda xyz.xz(yz))V(VV)$$

$$\xrightarrow{\beta} \lambda z.Vz(VVz)$$

therefore

$$\lambda z.Vz(VVz)K$$

for which it is sufficient to choose

$$V = \lambda uvt.u$$

in fact

$$\begin{split} \lambda z. Vz(VVz) &\equiv \lambda z. (\lambda uvt.u) z((\lambda uvt.u)(\lambda uvt.u)z) \\ &\stackrel{\beta}{\longrightarrow} \ \lambda z. (\lambda t.z) \\ &\equiv \mathbf{K} \end{split}$$

Problem 1.7: From Λ to CL

Convert the following λ -term into CL

 $\lambda uv.uuvv$

and verify the solution.

Solution. The solution can be found by applying the swap algorithm

$$swap(\lambda uv.uuvv) = [u][v](uuv)v$$

$$= [u]S([v](uu)v)([v]v)$$

$$= [u]S(B(uu)([v]v))I$$

$$= [u]S(B(uu)I)I$$

$$= C([u]S(B(uu)I))I$$

$$= C(BS([u]B(uu)I))I$$

$$= C(BS(C([u]B(uu)I))I$$

$$= C(BS(C(BB([u]uu)I))I$$

$$= C(BS(C(BB(S([u]u)([u]u))I))I$$

$$= C(BS(C(BB(SII)I)I)I$$

and it can be verified as follows

```
C(BS(C(BB(SII))I))Iuv \triangleright BS(C(BB(SII))I)uIv
\triangleright S(C(BB(SII))Iu)Iv
\triangleright S(BB(SII)uI)Iv
\triangleright S(B(SIIu)I)Iv
\triangleright S(B(Iu(Iu))I)Iv
\triangleright S(B(uu)I)Iv
\triangleright S(B(uu)I)v(Iv)
\triangleright B(uu)Ivv
\triangleright (uu)(Iv)v
\triangleright uuvv
```