

Date: 02.04.2023

$$\nabla A = \frac{1}{h_1 h_2 h_3}$$

### Divergence & Curl

3)  $\vec{A} = \hat{x}zy^3 + \hat{y}2y\sin(xy) + \hat{z}3x^2\ln z$

$$\text{dot}(\vec{A}) = \vec{\nabla} \cdot \vec{A} = \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial x} (zy^3, 1, 1) + \frac{\partial}{\partial y} (1, 2y\sin(xy), 1) + \frac{\partial}{\partial z} (1, 1, 3x^2\ln z) \right]$$

$$= 0 + 2y\cos(xy)x + \sin(xy).2 + 3x^2 \frac{1}{z}$$

$$= 2xy\cos(xy) + 2\sin(xy) + \frac{3x^2}{z}$$

$\vec{A}$  is not solenoidal

Now,

$$\text{curl } \vec{A} = \vec{\nabla} \times \vec{A}$$

$$= \frac{1}{h_1 h_2 h_3} \begin{vmatrix} \hat{h}_1 \hat{u}_1 & \hat{h}_2 \hat{u}_2 & \hat{h}_3 \hat{u}_3 \\ \frac{\partial}{\partial x_1} & \frac{\partial}{\partial x_2} & \frac{\partial}{\partial x_3} \\ h_1 A_1 & h_2 A_2 & h_3 A_3 \end{vmatrix}$$

$$= \frac{1}{h_1 h_2 h_3} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 1 \cdot zy^3 & 1 \cdot 2y\sin(xy) & 1 \cdot 3x^2\ln z \end{vmatrix}$$

$$= \hat{x}(0 - 0) - \hat{y}(6x\ln z - y^3) + \hat{z}(zy^2\cos(xy)) - 3y^2z$$

$\therefore \vec{A}$  is not conservative.

$$⑥ \bar{A} = \hat{r} \frac{\sin\varphi}{r^2} + \hat{\varphi} \frac{\cos\varphi}{r^2}, A_1 = \frac{\sin\varphi}{r^2}, A_2 = \frac{\cos\varphi}{r^2}, A_3 = 0$$

$$\nabla \cdot \bar{A} = \frac{1}{r^2} \left[ \frac{\partial}{\partial r} (\sin\varphi / r^2) + \frac{\partial}{\partial \varphi} \left( r \cdot \frac{\cos\varphi}{r^2} \right) + \frac{\partial}{\partial z} (0) \right]$$

$$= \frac{1}{r^2} \left[ 0 + \frac{1}{r^2} (-\sin\varphi) \right]$$

$$= -\frac{\sin\varphi}{r^3}$$

$\therefore A$  is not solenoidal

$$\text{Curl, } \bar{A} = \nabla \times \bar{A}$$

$$= \frac{1}{r^2} \begin{vmatrix} \hat{r} & r\hat{\varphi} & \hat{z} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \varphi} & \frac{\partial}{\partial z} \\ \frac{\sin\varphi}{r^2} & r \cdot \frac{\cos\varphi}{r^2} & 0 \end{vmatrix}$$

$$= \frac{1}{r^2} \left[ \hat{z} \left( \frac{\partial}{\partial \varphi} \left( \frac{\sin\varphi}{r^2} \right) - \hat{\varphi} \left( \frac{\partial}{\partial r} \left( \frac{\sin\varphi}{r^2} \right) \right) \right) \right]$$

$$= \frac{1}{r^2} \left[ \hat{z} \left( -\frac{1}{r^2} \cos\varphi - \frac{1}{r^3} \cos\varphi \right) \right]$$

$$= -\frac{\cos\varphi}{r^3} \hat{z}$$

$\therefore A$  is not conservative.

$$\textcircled{C} \quad \vec{A} = \hat{R} \cos\theta + \hat{\theta} (R \cdot \sin\theta)$$

$$\begin{aligned}\nabla \cdot \vec{A} &= \frac{1}{1 \cdot R \cdot R \sin\theta} \left[ \frac{\partial}{\partial R} (\cos\theta, R, R \sin\theta) + \frac{\partial}{\partial \theta} (1, (R \cdot \sin\theta), R \sin\theta) \right. \\ &\quad \left. + \frac{\partial}{\partial \phi} (1, R, 0) \right] \\ &= \frac{1}{R \sin\theta} \left[ 2R \cos\theta \sin\theta + \frac{2}{\partial \theta} (R \sin\theta - R \sin\theta) \right] \\ &= \frac{1}{R \sin\theta} \left[ 2R \cos\theta \sin\theta + R \cos\theta - R \sin\theta \cos\theta \right] \\ &= \frac{\cos\theta}{\sin\theta} \\ &= \cos\theta\end{aligned}$$

$\therefore \vec{A}$  is not solenoidal.

$$\begin{aligned}\nabla \times \vec{A} &= \frac{1}{1 \cdot R \cdot R \sin\theta} \begin{vmatrix} 1 \cdot \hat{R} & R \cdot \hat{\theta} & R \sin\theta \hat{\phi} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 1, \cos\theta & R(R \cdot \sin\theta) & 0 \end{vmatrix} \\ &= \frac{1}{R \sin\theta} \left[ \hat{R} (0 - 0) - R \hat{\theta} (0 - 0) + R \sin\theta \hat{\phi} \left( \frac{\partial}{\partial R} (R^2 - R \sin\theta) \right. \right. \\ &\quad \left. \left. - \frac{\partial}{\partial \theta} (R \cos\theta) \right) \right]\end{aligned}$$

$$= \frac{1}{R \sin\theta} \cdot R \sin\theta \hat{\phi} (2R - \sin\theta + \sin\theta)$$

$$= \frac{1}{R} \hat{\phi} 2R$$

$$\Rightarrow 2\hat{\phi}$$

$\therefore \vec{A}$  is not conservative

Q-2 Monday

Coordinate transformation  $\rightarrow 2$ 

Linear dependency

Divergence/curl

 $d\ell$  = differential length

$$d\ell = \hat{u}_1 h_1 du_1 + \hat{u}_2 h_2 du_2 + \hat{u}_3 h_3 du_3$$

(4) conservative

$$\nabla \times \vec{A} = 0 \\ \neq 0$$

$$T = \int \vec{A} \cdot d\ell$$

$$\frac{d}{dn}(T) = A$$

$$\Rightarrow \nabla \cdot T = A dx$$

$$\vec{A} = \hat{x}(\sin y + 1) + \hat{y}(2yz + x \cos y) + \hat{z}(y^2 - 3)$$

$$\therefore \nabla \times \vec{A} = \frac{1}{1.1.1} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (\sin y + 1) & 2yz + x \cos y & y^2 - 3 \end{vmatrix}$$

$$= \hat{x}[2y - 2y] - \hat{y}[0 - 0] + \hat{z}[0 + \cos y] - \cos y$$

$$= 0$$

$\therefore \vec{A}$  is a conservative vector field.

Now,

$$\nabla T = \vec{A} \Rightarrow$$

$$\Rightarrow \nabla \cdot T = \int \vec{A} \cdot d\ell$$

$$= \int [ \hat{x}(\sin y + 1) + \hat{y}(2yz + x \cos y) + \hat{z}(y^2 - 3) ] \cdot [\hat{x}dx + \hat{y}dy + \hat{z}dz ]$$

$$= \int [(\sin y + 1)dx + (2yz + x \cos y)dy + (y^2 - 3)dz]$$

$$= \int (\sin y dx + 2yz dy + x \cos y dy + y^2 dz - 3 dz)$$

$$= \int dx - \int 3 dz + \int d(x \sin y) + \int d(y^2 z)$$

$$= x - 3z + x \sin y + y^2 z + C$$

$$\begin{aligned} \int \sin y dx &\quad d(\sin y) \\ \int \sin y x &= x \cos y dy \\ &+ \sin y dy \end{aligned}$$

⑩ continuation of last class

$$\begin{aligned} \mathbf{T} &= \int \mathbf{A} \cdot d\mathbf{l} \\ &= x - 3z + x \sin y + y^2 z + C \end{aligned}$$

Work done in moving from,  $(1, -1, 5)$  to  $(2, \frac{\pi}{2}, 1)$  is

$$[x - 3z + x \sin y + y^2 z + C]_{(1, -1, 5)}^{(2, \frac{\pi}{2}, 1)}$$

$$= \left( 2 - 3 \cdot 1 + 2 \sin \frac{\pi}{2} + \frac{\pi^2}{4} \cdot 1 \right) - \left( 1 - 3 \cdot 5 + \sin(-1) + (-1)^2 \cdot 5 \right)$$

$$= 1 + \frac{\pi^2}{4} + 9 + \sin 1$$

$$= 10 + \frac{\pi^2}{4} + \sin 1$$

⑪  $\mathbf{A} = \hat{r} \left( \frac{2rz}{r^2} - \cos \varphi \right) + \hat{\theta} \sin \varphi + \hat{z} r (\tau^r)$   
 $(0, -1)$  to  $(1, \pi, 0)$

$$\nabla \times \mathbf{A} = \frac{1}{1 \cdot \pi \cdot 1} \begin{vmatrix} \hat{r} & \hat{\theta} & \hat{z} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ 1 \cdot (2rz - \cos \varphi) \sin \varphi & 1 \cdot \pi^r & \end{vmatrix}$$

$$= \frac{1}{\pi} \left[ \hat{r} \left( \frac{\partial}{\partial \theta} \pi^r - \frac{\partial}{\partial z} r \sin \varphi \right) - \hat{\theta} \pi \left( \frac{\partial}{\partial r} \pi^r - \frac{\partial}{\partial z} (2rz - \cos \varphi) \right) + \hat{z} \left( \frac{\partial}{\partial r} r \sin \varphi - \frac{\partial}{\partial \theta} (2rz - \cos \varphi) \right) \right]$$

$$= \frac{1}{\pi} \left[ \hat{r} (0 - 0) - \hat{\theta} \pi (2\pi - 2\pi) + \hat{z} (\sin \varphi - (0 + \sin \varphi)) \right]$$

$$= \frac{1}{\pi} \cdot 0 = 0$$

$\therefore \mathbf{A}$  is conservative!

$$\begin{aligned}
 T &= \int \bar{A} \cdot d\bar{l} \\
 &= \int [\hat{r}(2\pi z - \cos\varphi + \hat{\varphi} \sin\varphi) \hat{z} + (\hat{r} \cos\varphi + \hat{\varphi} \sin\varphi) \hat{\varphi}] [\hat{r} dr + \hat{\varphi} r d\varphi + \hat{z} dz] \\
 &= \int [(2\pi z - \cos\varphi) dr + r \sin\varphi d\varphi + r^2 dz] \\
 &= \int [2\pi z dr - \cos\varphi dr + r \sin\varphi d\varphi + r^2 dz] \\
 &= \int d(r^2 z) + \int d(-r \cos\varphi) \\
 &= r^2 z - r \cos\varphi + C
 \end{aligned}$$

$$\begin{aligned}
 \text{Work done} &= \left[ r^2 z - r \cos\varphi \right]_{(1, 0, -1)}^{(1, \pi, 0)} \\
 &= (1, 0 - 1 \cdot \cos 0) - (1 - 1 \cdot \cos \pi) \\
 &= (1 \cdot 0 - 1 \cdot (-1)) - (1 - 1 \cdot 1) \\
 &= 3
 \end{aligned}$$

Ex. 3.4

$$\vec{A} = \hat{R}(\sin\theta \cos\varphi) + \hat{\theta}(\cos\theta \cos\varphi) + \hat{\varphi}(-\sin\varphi)$$

$$\nabla \times \vec{A} = \frac{1}{r \cdot R \cdot R \sin\theta} \begin{vmatrix} \hat{r} \cdot \hat{R} & \hat{R} \cdot \hat{\theta} & \hat{R} \sin\theta \cdot \hat{\varphi} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \varphi} \\ \sin\theta \cos\varphi & R \cos\theta \cos\varphi & -R \sin\theta \sin\varphi \end{vmatrix}$$

$$= \frac{1}{R r \sin\theta} [\hat{R}(-R \cos\theta \sin\varphi + R \cos\theta \sin\varphi) + R \hat{\theta}(-\sin\theta \sin\varphi + \sin\theta \sin\varphi) + R \sin\theta \hat{\varphi}(\cos\theta \cos\varphi - \cos\theta \cos\varphi)]$$

$$= 0$$

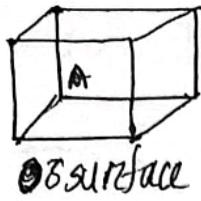
∴  $\vec{A}$  is conservative

$$\begin{aligned} T &= \int \vec{A} \cdot d\vec{T} \\ &= \int [\hat{R}(\sin\theta \cos\varphi) + \hat{\theta}(\cos\theta \cos\varphi) + \hat{\varphi}(-\sin\varphi)] \cdot [\hat{R} dR + \hat{\theta} R d\theta + \hat{\varphi} R \sin\theta d\varphi] \\ &= \int \sin\theta \cos\varphi dR + R \cos\theta \cos\varphi d\theta - R \sin\theta \sin\varphi d\varphi \\ &= \int d(R \sin\theta \cos\varphi) \\ &= R \sin\theta \cos\varphi + C \end{aligned}$$

$$\begin{aligned} \text{Work done} &= [R \sin\theta \cos\varphi]_{(0, \frac{\pi}{4}, \frac{\pi}{3})}^{(1, \frac{\pi}{2}, \pi)} \\ &= (1 \cdot \sin \frac{\pi}{2} \cdot \cos \pi) - (0 \cdot \sin \frac{\pi}{4} \cdot \cos \frac{\pi}{3}) \end{aligned}$$

4  
CHW

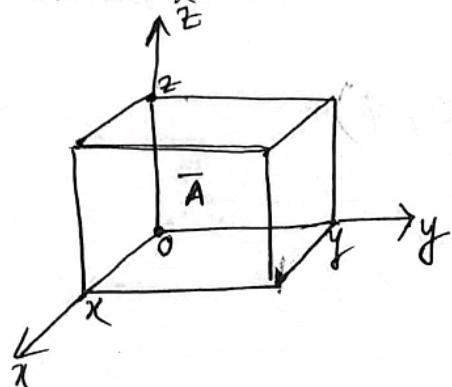
## Gauss Divergence Theorem:



$$\oint_C \bar{A} \cdot d\bar{S} = \int_V (\nabla \cdot \bar{A}) dV$$

→ It is used for closed surface

The



Top Area  $\frac{\circ}{\circ} s = xy$

$$\Rightarrow d\bar{S} = dx dy$$

$$\Rightarrow d\bar{S} = \hat{z} dx dy$$

Right Area  $\frac{\circ}{\circ} d\bar{S} = \hat{y} dx dz$

Bottom:  $d\bar{S} = -\hat{z} dx dy$

Left:  $d\bar{S} = \hat{y} dx dz$

Back:  $d\bar{S} = -\hat{x} dy dz$

Front Area  $\frac{\circ}{\circ} d\bar{S} = \hat{x} dy dz$

$$1 \quad \bar{A} = \hat{x} xy + \hat{y} yz + \hat{z} xz$$

$$\oint_C \bar{A} \cdot d\bar{S} = ?$$

Top surface:  $z=2$ , and  $d\bar{S} = \hat{z} dx dy$

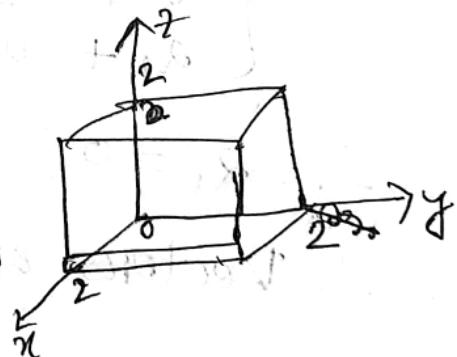
$$\therefore \bar{A} = \hat{x} xy + \hat{y} 2yz + \hat{z} 2x$$

$$\text{Now, } \bar{A} \cdot d\bar{S} = 2x dx dy$$

$$\therefore \int \bar{A} \cdot d\bar{S} = \int_0^2 \int_0^2 2x dx dy$$

$$= \int_0^2 [x^2]_0^2 dy$$

$$= 4 [y]^2 = 8$$



$$\textcircled{1} \quad (1, -1, \sqrt{2}) \rightarrow (r, \varphi, z)$$



$$r = \sqrt{1^2 + (-1)^2} = \sqrt{2}$$

$$\varphi = \tan^{-1}\left(\frac{-1}{1}\right) = -\frac{\pi}{4} + 2\pi \\ = \frac{7\pi}{4}$$

$$z = \bar{z} = \sqrt{2}$$

$$\therefore (r, \varphi, z) = (\sqrt{2}, \frac{7\pi}{4}, \sqrt{2})$$

$$\textcircled{2} \quad (1, \pi, 0) \rightarrow (r, \theta, \varphi)$$

$$r = \sqrt{1^2 + 0^2} = 1$$

$$\theta = \tan^{-1}\left(\frac{1}{0}\right) \\ = 0$$

$$\varphi = \phi = \pi$$

$$\textcircled{1} \quad v_1 = (2, 0, 1), v_2 = (3, 1, 0), v_3 = (-1, 0, -2)$$

$$\text{Let, } \alpha_1(2, 0, 1) + \alpha_2(3, 1, 0) + \alpha_3(-1, 0, -2)$$

$$\Rightarrow \begin{cases} 2\alpha_1 + 3\alpha_2 - \alpha_3 = 0 \\ 0 + \alpha_2 + 0 = 0 \\ \alpha_1 + 0 - 2\alpha_3 = 0 \end{cases}$$

$$\therefore \alpha_1 = 0, \alpha_2 = 0, \alpha_3 = 0$$

$\therefore$  Vectors are linearly independent.

$$\text{1) } T(x, y, z) = x^2y + xy + xz^2 \text{ at } (1, -1, 0), \quad d = \hat{x} - 2\hat{y} + \hat{z}$$

$$\begin{aligned}\nabla T &= \left( \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) (x^2y + xy + xz^2) \\ &= \hat{x}(x^2y + xy + xz^2) + \hat{y}(xy) + \hat{z}(xz^2) \\ &= \hat{x}(2xy + y + z^2) + \hat{y}(x^2 + x + 0) + \hat{z}(0 + 0 + 2xz) \\ &= \hat{x}(2xy + y + z^2) + \hat{y}(x^2 + x) + \hat{z}(2xz)\end{aligned}$$

at point  $(1, -1, 0)$ ,

$$\nabla T = \hat{x} \{ 2 \cdot 1 \cdot (-1)^2 + (-1) + (0)^2 \} + \hat{y} (1^2 + 1) + \hat{z} (2 \cdot 1 \cdot 0)$$

$$= \hat{x} (-2 - 1) + 2\hat{y} + 0$$

$$= -3\hat{x} + 2\hat{y}$$

$$\text{Now, } \hat{d} = \frac{d}{|d|} = \frac{\hat{x} - 2\hat{y} + \hat{z}}{\sqrt{1^2 + (-2)^2 + 1^2}}$$

$$= \frac{\hat{x} - 2\hat{y} + \hat{z}}{\sqrt{6}}$$

$$= \frac{\hat{x}}{\sqrt{6}} - \frac{2\hat{y}}{\sqrt{6}} + \frac{\hat{z}}{\sqrt{6}}$$

∴ Directional derivative,

$$(\nabla T) \cdot (\hat{d}) = (-3\hat{x} + 2\hat{y}) \left( \frac{\hat{x}}{\sqrt{6}} - \frac{2\hat{y}}{\sqrt{6}} + \frac{\hat{z}}{\sqrt{6}} \right)$$

$$= -\frac{3}{\sqrt{6}} - \frac{4}{\sqrt{6}}$$

$$(ii) A = \hat{r} 5R \sin \varphi + \hat{\theta} 10\pi^r \cos \varphi + \hat{z} z$$

$$\nabla \cdot A = \frac{1}{1.R.1} \left[ \frac{\partial}{\partial r} (5R \sin \varphi \cdot R \cdot 1) + \frac{\partial}{\partial \theta} (1. 10\pi^r \cos \varphi \cdot 1) + \frac{\partial}{\partial z} (1. R \cdot z) \right]$$

$$= \frac{1}{R} (10\pi \sin \varphi \cdot \cancel{R} - 10\pi^r \sin \varphi + R)$$

$$= \frac{1}{R} \{ 10\pi \sin \varphi \}$$

$$= \cancel{\frac{1}{R}} 10\pi \sin \varphi \left( 1 - R + \frac{1}{10\sin \varphi} \right)$$

$$= 10\sin \varphi \left( 1 - R + \frac{1}{10\sin \varphi} \right) \quad \underline{\text{Ans}}$$

$$(iii) B = \hat{r} e_r + \hat{\theta} R \sin \theta e_\theta + \hat{z} R \sin \theta \cos \theta e_z$$

$$\nabla \times B = \frac{1}{R^2 R. R \sin \theta} \begin{vmatrix} \hat{r} & \hat{\theta} & \hat{z} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ R \sin \theta e_r & R \sin \theta \cos \theta e_\theta & R \sin \theta \sin \theta e_z \end{vmatrix}$$

$$= \frac{1}{R^2 \sin \theta} [(0 - 0) - \hat{r} (\theta - \theta) + R \sin \theta \hat{\theta} (2R \sin \theta - 0)]$$

$$= \frac{1}{R^2 \sin \theta} [2R^2 \sin^2 \theta \hat{\theta}]$$

$$= \cancel{R^2 \sin \theta} 2 \sin \theta \hat{\theta}$$

$$\textcircled{1} \quad \bar{A} = \hat{x}xy + \hat{y}yz^2 + \hat{z}xz$$

6.2

Top:  $\int_S \bar{A} \cdot d\bar{S} = 8$

Bottom:  $z = 0, d\bar{S} = -\hat{z}dxdy$

$$\bar{A} = \hat{x}xy$$

$$\therefore \bar{A} \cdot d\bar{S} = 0$$

$$\therefore \int_S \bar{A} \cdot d\bar{S} = 0$$

Right surface:  $y = 2, d\bar{S} = \hat{y}dxdz$

$$\bar{A} = \hat{x}2x + \hat{y}4z + \hat{z}xz$$

$$\therefore \bar{A} \cdot d\bar{S} = 4z dxdz$$

$$\begin{aligned} \therefore \int_S \bar{A} \cdot d\bar{S} &= \int_0^2 \int_0^2 4z dxdz \\ &= 4 \int_0^2 2 [x]_0^2 dz \\ &= 8 \left[ \frac{z^2}{2} \right]_0^2 \\ &= 16 \end{aligned}$$

Left surface:  $y = 0, d\bar{S} = -\hat{y}dxdz$

$$\bar{A} = \hat{z}xz \quad \therefore \bar{A} \cdot d\bar{S} = 0$$

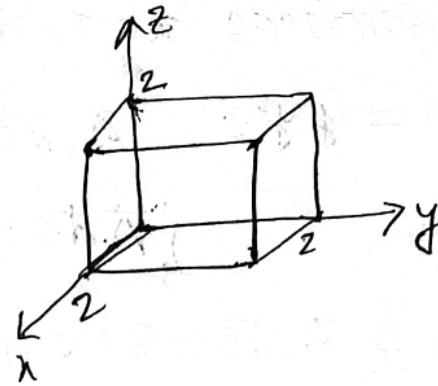
$$\therefore \int_S \bar{A} \cdot d\bar{S} = 0$$

Front surface:  $x = 2, d\bar{S} = \hat{x}dydz$

$$\bar{A} = \hat{x}2y + \hat{y}yz^2 + \hat{z}2z$$

$$\bar{A} \cdot d\bar{S} = 2y dydz$$

$$\therefore \int_S \bar{A} \cdot d\bar{S} = \int_0^2 \int_0^2 2y dydz = \int_0^2 [y^2]_0^2 dz = 4 [z]_0^2 = 8$$



Back surfaces:  $x=0$ ,  $d\vec{S} = -\hat{x} dy dz$

$$\vec{A} = \hat{y} y^2 z, \quad \vec{A} \cdot d\vec{S} = 0$$

$$\int_S \vec{A} \cdot d\vec{S} = 0$$

$$\therefore \oint_S \vec{A} \cdot d\vec{S} = 8 + 0 + 16 + 0 + 0 + 18 + 0 = 32$$

(b)  $\int_V (\nabla \cdot \vec{A}) dV = ?$

$$\text{Now, } \nabla \cdot \vec{A} = \frac{1}{1.1.1} \left[ \frac{\partial}{\partial x} (xy) + \frac{\partial}{\partial y} (yz) + \frac{\partial}{\partial z} (x - z) \right]$$

$$= y + 2xy + x$$

$$\therefore \int_V (\nabla \cdot \vec{A}) dV = \iiint_{V \cap S} (y + 2xy + x) dx dy dz$$

$$= \int_0^2 \int_0^2 \left[ xy + 2xy^2 + \frac{x^2}{2} \right]_0^2 dy dx z$$

$$= \int_0^2 \int_0^2 (2y + 8y^2 + 2) dy dz$$

$$= \int_0^2 [y^2 + 2y^3 + 2y]_0^2 dz$$

$$= \int_0^2 (4 + 16z + 4) dz$$

$$= [8z + 4z^2]_0^2$$

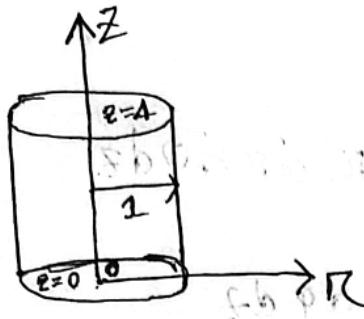
$$= 16 + 16$$

$$= 32$$

6.2

$$\overline{A} = \hat{r} r^v + \hat{z} 3z_2, \quad r=1, z=0, z=4$$

radius bottom top



Top surface:  $z=4, d\bar{s} = \hat{z} h dr h d\theta$   
 $= \hat{z} r dr d\theta$

$$\overline{A} = \hat{r} r^v + \hat{z} \cdot 3 \cdot 4$$
 $= \hat{r} r^v + \cancel{\hat{z}} \cancel{12}$

$$\therefore \overline{A} \cdot d\bar{s} = 12 dr d\theta$$

$$\begin{aligned} \int_S \overline{A} \cdot d\bar{s} &= \int_0^{2\pi} \int_0^1 12 r dr d\theta \\ &= \int_0^{2\pi} [6r^2]_0^1 d\theta \\ &= 6[\theta]_0^{2\pi} \\ &= 12\pi \end{aligned}$$



Bottom surface:  $z=0, d\bar{s} = -\hat{z} r dr d\theta$

$$\overline{A} = \hat{r} r^v \quad \therefore \int_S \overline{A} \cdot d\bar{s} = 0$$

Circular surface:  $r=1, d\bar{s} = \hat{r} r d\theta dz$   
 $= \hat{r} \cdot 1 d\theta dz$

$$\overline{A} = \hat{r} \cdot 1 + \hat{z} 3z \quad \therefore \overline{A} \cdot d\bar{s} = d\theta dz$$

$$\therefore \int_S \overline{A} \cdot d\bar{s} = \int_0^3 \int_0^{2\pi} d\theta dz$$

$$= [d\theta]_0^{2\pi} \cdot [dz]_0^3$$

$$= 8\pi$$

$$\therefore \int_S \overline{A} \cdot d\bar{s} = 12\pi + 8\pi$$

$$= \boxed{20\pi}$$

Now,

$$\begin{aligned}(\bar{\nabla} \cdot \bar{A}) &= \frac{1}{1 \cdot \pi \cdot 1} \left[ \frac{\partial}{\partial r} (r^2 \pi \cdot 1) + \frac{\partial}{\partial z} (1 \cdot \pi \cdot 3z) \right] \\ &= \frac{1}{\pi} (3r^2 + 3z)\end{aligned}$$

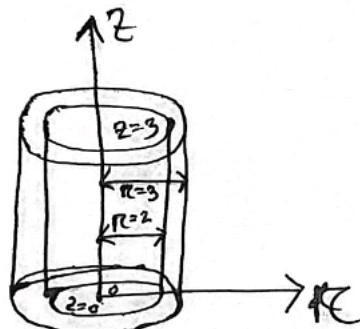
$$\therefore \int_V (\bar{\nabla} \cdot \bar{A}) dV = \int_0^4 \int_0^{2\pi} \int_0^1 \frac{1}{\pi} (3r^2 + 3z) \pi r dr dz d\phi$$

$$= \int_0^4 \int_0^{2\pi} \left[ r^3 + \frac{3}{2} r^2 \right] \Big|_0^1 d\phi dz$$

$$= \frac{5}{2} \cdot [0]_0^{2\pi} [2]_0^4$$

$$= [20\pi]$$

3.  $\bar{A} = \hat{r} r^2$



Top surface:  $z=3, d\bar{s} = \hat{z} r dr dz d\phi$

$$\bar{A} = \hat{r} r^2 \quad \therefore \int_S \bar{A} \cdot d\bar{s} = 0$$

Bottom surface:  $z=0, d\bar{s} = -\hat{z} r dr dz d\phi$

$$\bar{A} = \hat{r} r^2 \quad \therefore \int_S \bar{A} \cdot d\bar{s} = 0$$

Outer circular surface:

$$\begin{aligned}r=3, d\bar{s} &= \hat{r} r dr d\phi dz \\ &= \hat{r} 3 dr d\phi dz\end{aligned}$$

$$\therefore \bar{A} \cdot d\bar{s} = 27 d\phi dz \quad \therefore \int_S \bar{A} \cdot d\bar{s} = \int_0^3 \int_0^{2\pi} 27 d\phi dz$$

$$\begin{aligned}&= 27 [\phi]_0^{2\pi} [z]_0^3 \\ &= 162\pi\end{aligned}$$

## Inner circular surfaces

$$r=2, d\bar{s} = -\hat{r} r d\varphi dz \quad A = \hat{r} \cdot 2^r = 4$$

$$\begin{aligned}\therefore \bar{A} \cdot d\bar{s} &= 27 d\varphi dz = \int_S \bar{A} \cdot d\bar{s} = \int_0^2 \int_0^{2\pi} -8r d\varphi dz \\ &= - \int_0^2 [8\pi]_0^{2\pi} r dz \\ &= - \int_0^2 16\pi dz \\ &= -48\pi\end{aligned}$$

$$\therefore \oint_S \bar{A} \cdot d\bar{s} = 16\pi - 48\pi \\ = 114\pi$$

Now,  $\nabla \cdot \bar{A} = \frac{1}{r^2} \left[ \frac{\partial}{\partial r} (r^2, r, 1) \right]$

$$\begin{aligned}&= \frac{1}{r} \cdot 3r^2 \\&= 3r\end{aligned}$$

$$\begin{aligned}\therefore \int_V (\nabla \cdot \bar{A}) dv &= \int_0^3 \int_0^{2\pi} \int_2^3 3r r^2 dr d\varphi dz \\ &= \int_0^3 \int_0^{2\pi} [r^3]_2^3 d\varphi dz \\ &= (27-8) [\varphi]_0^{2\pi} \cdot [z]_0^3 \\ &= 19 \cdot 2\pi \cdot 3 \\ &= 114\pi\end{aligned}$$

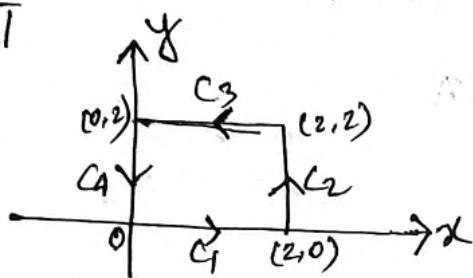
$\therefore$  Divergence theorem verified.

$$\oint_C \vec{A} \cdot d\vec{l} = \int_S (\nabla \times \vec{A}) dS$$

6.3

$$\vec{A} = \hat{x}(x^r - y^r) + \hat{y}(x^r - xy)$$

①  $\oint_C \vec{A} \cdot d\vec{l}$



②  $\int_S (\nabla \times \vec{A}) dS$

$$d\vec{l} = \hat{u}_x dx + \hat{u}_y dy$$

③  ~~$\vec{A} \cdot d\vec{l}$~~

For C<sub>1</sub>:  $y=0, dy=0 / z=0 \& dz=0$  [optimal]

Hence,  $\vec{A} = \hat{x}(x^r - y^r) + \hat{y}(x^r - xy)$

$$d\vec{l} = \hat{x} dx + \hat{y} dy + \hat{z} dz$$

$$\therefore \vec{A} \cdot d\vec{l} = (x^r - y^r) dx + (x^r - xy) dy$$

For C<sub>1</sub>:  $y=0, dy=0$

$$\therefore \vec{A} \cdot d\vec{l} = (x^r - 0) dx + (x^r - 0) \cdot 0$$

$$= x^r dx$$

$$\begin{aligned} \therefore \int_{C_1} \vec{A} \cdot d\vec{l} &= A \cdot dT = \int_0^2 x^r dx \\ &= \left[ -\frac{x^3}{3} \right]_0^2 \\ &= \frac{8}{3} \end{aligned}$$

For C<sub>2</sub>: x=2, dx=0

$$\begin{aligned}\bar{A} \cdot d\bar{l} &= (2^2 - 2y) dy \\ &= (4 - 2y) dy\end{aligned}$$

$$\begin{aligned}\therefore \int_{C_2} \bar{A} \cdot d\bar{l} &= \int_0^2 (4 - 2y) dy \\ &= [4y - y^2]_0^2 \\ &= 8 - 4 = 4\end{aligned}$$

For C<sub>3</sub>: y=2, dy=0

$$A \cdot d\bar{l} = (x^2 - 4) dx$$

$$\begin{aligned}\therefore \int_{C_3} \bar{A} \cdot d\bar{l} &= \int_2^0 (x^2 - 4) dx \\ &= \left[ \frac{x^3}{3} - 4x \right]_2^0 \\ &= 0 - \left( \frac{8}{3} - 8 \right) \\ &= \frac{16}{3}\end{aligned}$$

For C<sub>4</sub>: x=0, dx=0

$$\bar{A} \cdot d\bar{l} = (\cancel{\partial y / \partial x}) dx + 0$$

$$\therefore \int_{C_4} \bar{A} \cdot d\bar{l} = 0$$

$$\int_C \bar{A} \cdot d\bar{l} = \frac{8}{3} + 4 + \frac{16}{3} = \frac{36}{3} = 12$$