ECO 317 – Economics of Uncertainty – Fall Term 2009 Slides to accompany 20. Incentives for Effort - One-Dimensional Cases

1. Linear Incentive Schemes

Agent's effort x, principal's outcome y. Agent paid w.

$$y = x + \epsilon$$
 where $\mathsf{E}[\epsilon] = 0$), $\mathsf{V}[\epsilon] = v$.

(Note: x is not random; it is chosen by the agent.)

Agent's outside opportunity utility U_A^0 . In this job,

$$U_A = \mathsf{E}[w] - \frac{1}{2} \; \alpha \; \mathsf{V}[w] - \frac{1}{2} \, k \; x^2$$

Principal's utility $U_P = \mathsf{E}[y-w]$.

Hypothetical Ideal or First-Best

x verifiable. Principal chooses contract (x, w) to max

$$U_P = \mathsf{E}[y - w] = \mathsf{E}[x + \epsilon - w] = x - \mathsf{E}[w],$$

subject only to the agent's participation constraint (PC)

$$U_A = \mathsf{E}[w] - \frac{1}{2} \; \alpha \; \mathsf{V}[w] - \frac{1}{2} \, k \; x^2 \ge U_A^0 \, .$$

Obviously V[w] = 0 and E[w] lowest to meet PC. Then

$$U_P = x - \frac{1}{2} k x^2 - U_A^0$$
.

Optimal x from FOC $1 - \frac{1}{2} 2kx = 0$, so x = 1/k.

Result

$$w = U_A^0 + \frac{1}{2} k x^2 = U_A^0 + \frac{1}{2 k},$$

 $U_A = U_A^0, \qquad U_P = \frac{1}{2 k} - U_A^0.$

Second-Best Linear Incentive Schedules

x unverifiable (y verifiable, but can't infer x precisely from y). Consider linear (really, affine) contract with payment

$$w = h + s y = h + s (x + \epsilon) = (h + s x) + s \epsilon,$$

Then

$$\mathsf{E}[w] = h + s x \,, \qquad \mathsf{V}[w] = s^2 \; \mathsf{V}[\epsilon] = s^2 \; v \,,$$

and

$$U_A = h + s x - \frac{1}{2} \alpha v s^2 - \frac{1}{2} k x^2$$
.

Agent chooses x to max this. FOC s-k x=0, so x=s/k. s is a measure of the implied "power of incentive".

Substituting for x, agent's maximized or "indirect utility" function:

$$U_A^* = h + s \frac{s}{k} - \frac{1}{2} \alpha v s^2 - \frac{1}{2} k \left(\frac{s}{k}\right)^2 = h + \frac{s^2}{2k} - \frac{1}{2} \alpha v s^2.$$

Principal's utility

$$U_P = \mathsf{E}[y - h - s y] = (1 - s) x - h = (1 - s) \frac{s}{k} - h.$$

The principal chooses contract (h,s) to max this, subject to the agent's PC $U_A^* \geq U_A^0$. (IC used in choice of x).

$$h + \frac{s^2}{2k} - \frac{1}{2} \alpha v s^2 \ge U_A^0$$
.

Obviously optimal to keep h as low as feasible:

$$h = U_A^0 - \frac{s^2}{2k} + \frac{1}{2} \alpha v s^2$$
.

and

$$U_P = \frac{s(1-s)}{k} + \frac{s^2}{2k} - \frac{1}{2}\alpha v s^2 - U_A^0$$
$$= \frac{s}{k} - \frac{s^2}{2k} - \frac{1}{2}\alpha v s^2 - U_A^0.$$

Choosing s to maximize this, FOC

$$\frac{1}{k} - \frac{s}{k} - \frac{1}{2} \alpha v (2s) = 0;$$

$$s = \frac{1}{1 + \alpha v k}.$$

Intuition and interpretation:

- [1] 0 < s < 1. First-best risk-sharing would make s = 0, but when x is unverifiable, moral hazard requires s > 0. First-best effort incentive would be s = 1, but that puts too much risk on agent. Second best balances these two. The choice of h arranges split of surplus between parties.
- [2] The higher is α , the lower is s. When agent more risk-averse, giving more powerful incentive makes his income too risky; must increase h to maintain PC.
- [3] The higher is v, the lower is s. A high v means less accurate inference of x from y. Powerful incentive wasted.

[4] Utilities in second-best optimum:

$$U_P = \frac{1}{2 k (1 + \alpha v k)} - U_A^0, \qquad U_A = U_A^0.$$

lf

$$\frac{1}{2k(1+\alpha v k)} < U_A^0 < \frac{1}{2k},$$

contract should be made under first best but not second-best.

[5] Order of magnitude from John Garen (JPE December 1994):

Data on large U.S. corporations during 1970-1988.

Median market value \$2 billion 2×10^9 , median variance $v \approx 2 \times 10^{17}$.

CEOs median income \$1 million (1×10^6) .

Coefficient of relative risk aversion 2, absolute $\alpha = 2 \times 10^{-6}$.

Then

$$\mathsf{E}[y] = x = s/k = 2 \times 10^9, \quad s = 1/(1 + \alpha \, v \, k) = 1/(1 + 4 \times 10^{11} \, k)$$
.

Eliminating k between the two equations,

$$s = 1/(1+200 s)$$
, or $200 s^2 + s - 1 = 0$, $s \approx 0.0683$.

Actual values are much smaller, averaging 0.0142.

Other considerations can explain lower power.

2. Nonlinear Incentive Schedules

Agent chooses effort x, cost K(x).

Principal's outcome: Values y_i increasing, probabilities $\pi_i(x)$.

Higher x shifts distribution FOSD to the right.

Utilities

$$EU_A = \sum_{i=1}^{n} \pi_i(x) \ u_a(w_i) - K(x) ,$$

$$EU_P = \sum_{i=1}^{n} \pi_i(x) \ u_p(y_i - w_i).$$

Ideal first-best

Contract (x, w_i) to max EU_P subject to $EU_A \ge U_A^0$.

$$\mathcal{L} = \sum_{i=1}^{n} \pi_i(x) \ u_p(y_i - w_i) + \lambda \left\{ \sum_{i=1}^{n} \pi_i(x) \ u_a(w_i) - K(x) - U_A^0 \right\}.$$

FOCs for payments w_j

$$\frac{\partial \mathcal{L}}{\partial w_j} = \pi_j(x) \left[-u'_p(y_j - w_j) + \lambda u'_a(w_j) \right] = 0,$$

or, as in Arrow-Debreu theory (Handout 13 pp. 6-7):

$$\frac{u_p'(y_j - w_j)}{u_a'(w_j)} = \lambda \qquad \text{for all } j.$$

Moral hazard

Agent chooses unverifiable x to maximize EU_A . FOC

$$\frac{\partial EU_A}{\partial x} = \sum_{i=1}^n \pi'_i(x) \ u_a(w_i) - K'(x) = 0.$$

Here assume that solution to FOC yields true optimum

That is actually problematic; more advanced treatments discuss this.

That FOC becomes the IC in principal's choice.

$$\mathcal{L} = \sum_{i=1}^{n} \pi_{i}(x) u_{p}(y_{i} - w_{i}) + \lambda \left\{ \sum_{i=1}^{n} \pi_{i}(x) u_{a}(w_{i}) - K(x) - U_{A}^{0} \right\}$$
$$+ \mu \left\{ \sum_{i=1}^{n} \pi'_{i}(x) u_{a}(w_{i}) - K'(x) \right\}.$$

FOCs for the w_i

$$\frac{\partial \mathcal{L}}{\partial w_i} = \pi_j(x) \left[-u_p'(y_j - w_j) + \lambda u_a'(w_j) \right] + \mu \pi_j'(x) u_a'(w_j) = 0,$$

or

$$\frac{u_p'(y_j - w_j)}{u_a'(w_j)} = \lambda + \mu \frac{\pi_j'(x)}{\pi_j(x)} \quad \text{for all } j.$$

Then w_j high if $\pi'_j(x) / \pi_j(x) = d \ln [\pi_j(x)] / dx$ high.

Such states are most informative about slackening of effort.

So high payments in them give best incentives.

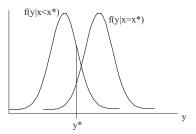
Special Case - Quotas

Choose threshold y^* and w_L , w_H in contract:

$$w(y) = \begin{cases} w_L & \text{if } y < y^*, \\ w_H & \text{if } y \ge y^*, \end{cases}$$

This works well if, for x slightly smaller than principal's optimal x^* ,

$$\mathsf{Prob}\{\,y \geq y^* \mid x\,\} << \mathsf{Prob}\{\,y \geq y^* \mid x^*\,\}$$



Special case - Efficiency Wage

Repeated interaction. Agent's action observable with delay.

Contract: agent paid each period more than outside opportunity,

but fired if he is ever caught shirking.

Example: Effort binary (good or bad). Cost of good C.

Outside wage in non-moral-hazard jobs W_0 .

Contract: Suppose the agent is paid W when not detected shirking.

Probability of detection P. Discount factor δ .

Expected present value of cost of shirking

$$P(W - W_0) (\delta + \delta^2 + \delta^3 + \dots) = P(W - W_0) \delta/(1 - \delta).$$

Keep this $\geq C$ to deter shirking. So "efficiency wage"

$$W \ge W_0 + \frac{1 - \delta}{\delta} \frac{C}{P}.$$