

# Stochastic gradient Langevin dynamics

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## 1 SGD-like updates

The Langevin MC method is an HMC method with  $T = 1$ ; i.e., with a single leapfrog iteration. In fact, in the uncorrected version of Langevin MC (all candidates accepted) there is no need of the two-step procedure of HMC and no need for explicitly representing the momentum at all; one stochastic differential equation (Langevin equation) is used for picking new values of  $\mathbf{w}$ . For the  $t$ -th state, the Langevin equation is given as (see Eq. (5.28) in Neal, 1993)

$$\mathbf{w}^{(t+1)} - \mathbf{w}^{(t)} = -\frac{\lambda^2}{2} \nabla_{\mathbf{w}} \mathcal{L}(\mathbf{w}^{(t)}) + \lambda \mathbf{n} \quad (1)$$

where  $\mathbf{n} = [n_1, \dots, n_k]^T$  and  $n_j \sim \mathcal{N}(0, 1)$  for all  $j$ . Also, recall that  $\mathcal{L}(\mathbf{w}^{(t)}) = -\log p(\mathcal{D}|\mathbf{w}^{(t)}, \mathcal{H}) - \log p(\mathbf{w}^{(t)}|\mathcal{H})$ . By writing  $\lambda = \sqrt{\epsilon}$ , Eq. (1) becomes

$$\mathbf{w}^{(t+1)} - \mathbf{w}^{(t)} = \frac{\epsilon}{2} \left[ \nabla_{\mathbf{w}} \sum_{i=1}^N \log p(y_i|\mathbf{w}^{(t)}, x_i, \mathcal{H}) + \nabla_{\mathbf{w}} \log p(\mathbf{w}^{(t)}|\mathcal{H}) \right] + \boldsymbol{\eta} \quad (2)$$

where  $\boldsymbol{\eta} = [\eta_1, \dots, \eta_k]^T$  and  $\eta_j \sim \mathcal{N}(0, \epsilon)$  for all  $j$ .

If at each iteration only a subset (mini-batch) of the available data is used, Eq. (2) becomes (Welling and Teh, 2011)

$$\mathbf{w}^{(t+1)} - \mathbf{w}^{(t)} = \frac{\epsilon}{2} \left[ \nabla_{\mathbf{w}} \sum_{i \in S} \frac{N}{|S|} \log p(y_i|\mathbf{w}^{(t)}, x_i, \mathcal{H}) + \nabla_{\mathbf{w}} \log p(\mathbf{w}^{(t)}|\mathcal{H}) \right] + \boldsymbol{\eta} \quad (3)$$

This is the same as the SGD update step with added Gaussian noise.

## References

- Neal, R. M. (1993). *Probabilistic Inference Using Markov Chain Monte Carlo Methods*.  
Department of Computer Science, University of Toronto Toronto, Ontario, Canada.
- Welling, M. and Teh, Y. W. (2011). “Bayesian Learning via Stochastic Gradient Langevin Dynamics”. *Proceedings of the 28th International Conference on Machine Learning (ICML-11)*, pp. 681–688.