

# Adán Flores Ramírez

408-312-1647 | [afr102903@gmail.com](mailto:afr102903@gmail.com) | [linkedin.com/in/adanfr](https://www.linkedin.com/in/adanfr) | [github.com/afr2903](https://github.com/afr2903) | [adanfr.com/](https://adanfr.com/)

## EDUCATION

<b>Instituto Tecnológico y de Estudios Superiores de Monterrey</b> <i>B.S. in Mechatronics Engineering — GPA: 95/100</i> Relevant coursework: Data Structures and Algorithms, Industrial Automation, Design & Development of Robots	Nuevo León, Mexico Aug. 2021 – Jun. 2025
<b>Massachusetts Institute of Technology</b> <i>Data Science and Machine Learning program: Making Data Driven Decisions</i>	Cambridge, MA Dec. 2024 – Feb. 2025

## WORK EXPERIENCE

<b>AI &amp; VR/AR Research Assistant</b> <i>Massachusetts Institute of Technology - Department of Mechanical Engineering</i> <ul style="list-style-type: none"><li>Led research project to generate a publication at peer-reviewed journal: Production &amp; Manufacturing Research.</li><li>Filled gaps in interactivity and upper automation pyramid layers of simulators, empowering factory personnel.</li><li>Developing a VR environment to enhance the performance of factory operations as measured by KPIs, implementing relational DBs, neural networks, and a fine-tuned SLM as support decision, within Unity.</li></ul>	Sep. 2024 – Present Cambridge, MA
<b>Software Engineer Intern</b> <i>Google - Cloud AI &amp; Industry solutions</i> <ul style="list-style-type: none"><li>Developed core C++ components for a distributed data processing pipeline, increasing data synchronization efficiency and contributing to improved search platform performance.</li><li>Optimized resource consumption for data ingestion processes by refining critical C++ components and implementing rigorous SQL-based end-to-end testing, leading to a more scalable and reliable data infrastructure.</li></ul>	June 2024 – Sep. 2024 Sunnyvale, CA
<b>Robotics Engineer Intern</b> <i>ITESM - Smart Factory</i> <ul style="list-style-type: none"><li>Developed and deployed robotic automation solutions within a simulated digital twin factory environment, demonstrating proficiency in C++ and Python for robotics applications.</li><li>Led a team in developing and integrating behavior coordination algorithms for multi-robot systems using ROS and Python, demonstrating experience in building complex robotics systems and collaborative software development.</li></ul>	Jan. 2023 – May 2024 Monterrey, Mexico
<b>Software Engineer - AI Integration</b> <i>Imatix Robotics</i> <ul style="list-style-type: none"><li>Developed and deployed a high-performance, real-time voice assistant platform using Python, showcasing experience in building and deploying AI-driven solutions and integrating with cloud services.</li><li>Optimized the platform's response times, achieving a 25% reduction in latency by implementing efficient data transfer techniques and multithreading in Python, demonstrating a focus on performance optimization.</li></ul>	Aug. 2023 – Mar. 2024 Remote
<b>Unity Developer</b> <i>Catapulta Academy</i> <ul style="list-style-type: none"><li>Developed and debugged complex game features within a resource-constrained Unity environment, demonstrating proficiency in C#, Javascript, and cross-platform development.</li><li>Successfully reduced application load times by 80% through data-driven analysis and optimizations.</li></ul>	Nov. 2020 – Aug. 2023 Remote

## PROJECTS

<b>RoboCup @HOME - Robot Development</b>   C++, Python, ROS <ul style="list-style-type: none"><li>Contributed to the development and deployment of an autonomous service robot, gaining practical experience in robotics, software integration, and working in a collaborative, fast-paced environment.</li><li>Designed and implemented a hierarchical state machine to manage complex robot behaviors, demonstrating proficiency in software design principles and state management techniques within a robotics context.</li></ul>	Nov. 2022 – Present
<b>IEEE LARC Open Challenge - Robot Development</b>   C++, Python, ROS <ul style="list-style-type: none"><li>Led a team in developing and deploying a robot control system for warehouse automation, showcasing experience in collaborative project leadership, systems integration, and problem-solving within a dynamic robotics challenge.</li></ul>	Jan. 2023 – Oct. 2023

## TECHNICAL SKILLS

**Languages:** C++, Python, C#, Java, Javascript  
**Frameworks:** ROS, Unity, TensorFlow, PyTorch, JAX, Node.js, Laravel, Borg  
**Tools:** Git, Google Cloud Platform, Docker, Linux, Jira, Postman