

## Chapter 13

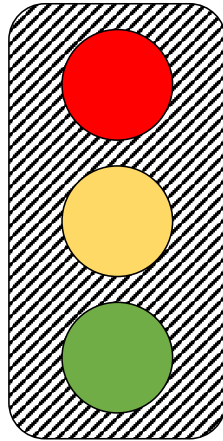
# Imperative programming

**Abstract** Imperative programming is both an overarching term for a collection of programming paradigms and the name for a specific paradigm. Here we will discuss the specific paradigm, and in Chapters 15 to 17 we will discuss another imperative paradigm called the object-oriented paradigm. When programming using the imperative paradigm, the programmer specifies a number of steps which to manipulate the state of the computer for a desired result. Key features of this paradigm are *mutable values* also known as *variables* and `for`- and `while`-loops. In this chapter, you will learn

- How to define and use variables
- How to make loops using the `for`- and `while`-keywords as an alternative to recursive functions
- How to use arrays as an alternative to lists
- How to trace-by-hand imperative programs

### 13.1 Variables

A state is a value that may change over time. E.g., a traffic light as shown in Figure 13.1, consists of 3 colored lamps: red (top), yellow (middle), and green (bottom), and typically cycles through the cyclic sequence red, red+yellow, green, yellow. A simple model of this could be to represent the state of each lamp as being



**Fig. 13.1** For a traffic light, the different state of the coloured lamps can be modelled as different states of the lighth. Top lamp is red, middle is yellow, and bottom is green.

on or off. This can be done with a mutable boolean value. To create a mutable value, we initially declare and identifier using the *mutable* keyword with the following syntax:

**Listing 13.1:** Syntax for defining mutable values with an initial value.

```
1 let mutable <ident> = <expr>
```

Changing the value of an identifier is called *assignment* and is done using the “<-” lexeme. Assignments have the following syntax:

**Listing 13.2:** Value reassignment for mutable variables.

```
1 <ident> <- <expr>
```

*Mutable values* is synonymous with the term *variable*. A variable is an area in the computer’s working memory associated with an identifier and a type, and this area may be read from and written to during program execution, see Listing 13.3 for an example. Here, an area in memory was denoted *x*, initially assigned the integer value 5, hence the type was inferred to be *int*. Later, this value of *x* was replaced with another integer using the “<-” lexeme. The “<-” lexeme is used to distinguish

**Listing 13.3 mutableAssignReassingShort.fsx:**  
A variable is defined and later reassigned a new value.

```
1 let mutable x = 5
2 printfn "%d" x
3 x <- -3
4 printfn "%d" x
```

---

```
1 $ dotnet fsi mutableAssignReassingShort.fsx
2 5
3 -3
```

the assignment from the comparison operator. For example, the statement `a = 3` in Listing 13.4 is not an assignment but a comparison which is evaluated to be false.

**Listing 13.4:** It is a common error to mistake “=” and “<-” lexemes for mutable variables.

```
1
2 > let mutable a = 0
3 a = 3;;
4 val mutable a: int = 0
5 val it: bool = false
```

Assignment type mismatches will result in an error, as demonstrated in Listing 13.5. I.e., once the type of an identifier has been declared or inferred, it cannot be changed.

**Listing 13.5 mutableAssignReassingTypeError.fsx:**  
Assignment type mismatching causes a compile-time error.

```
1 let mutable x = 5
2 printfn "%d" x
3 x <- -3.0
4 printfn "%d" x
```

---

```
1 $ dotnet fsi mutableAssignReassingTypeError.fsx
2
3
4 mutableAssignReassingTypeError.fsx(3,6): error FS0001: This
   expression was expected to have type
5     'int'
6 but here has type
7     'float'
```

A typical variable is a counter of type integer, and a typical use of counters is to increment them, see Listing 13.6 for an example. Using variables in expressions, as opposed to the left-hand-side of an assignment operation, reads the value of the variable. Thus, when using a variable as the return value of a function, then the value

**Listing 13.6 mutableAssignIncrement.fsx:**  
Variable increment is a common use of variables.

```
1 let mutable x = 5 // Declare a variable x and assign the
    value 5 to it
2 printfn "%d" x
3 x <- x + 1 // Increment the value of x
4 printfn "%d" x
```

---

```
1 $ dotnet fsi mutableAssignIncrement.fsx
2 5
3 6
```

is copied from the local scope of the function to the scope from which it is called. This is demonstrated in Listing 13.7. In the example, we see that the type is a value,

**Listing 13.7: Returning a mutable variable returns its value.**

```
1 > let g () =
2     let mutable y = 0
3     y
4 let y' = g();;
5 val g: unit -> int
6 val y': int = 0
```

and not mutable.

In F# it is possible to encapsulate a mutable value. For example, consider a counter function `inc: unit->int`, which increments a counting state and returns its present value, every time we call it, i.e., calling `inc ()` the first time should return the value 1, the second time the value 2, and so on. A first attempt could be as shown in Listing 13.8. Even though `inc` has an internal state, the identifier “s” is reset

**Listing 13.8 inc.fsx:**  
A failed version of the a counter function `inc`.

```
1 let inc () =
2     let mutable s = 0
3     s <- s + 1
4     s
5
6 printfn "%A" (inc ())
7 printfn "%A" (inc ())
8 printfn "%A" (inc ())
```

---

```
1 $ dotnet fsi inc.fsx
2 1
3 1
4 1
```

to 0 every time the function is called. However, in F# it is possible to solve this problem by using a side-effect as shown in Listing 13.9. The reason this works is

**Listing 13.9 makeCounter.fsx:**

Returning a counter function with a side-effect. Compare with Listing 13.8.

```

1 let makeCounter () =
2     let mutable s = 0
3     fun () ->
4         s <- s + 1
5         s
6
7 let inc = makeCounter ()
8 printfn "%A" (inc ())
9 printfn "%A" (inc ())
10 printfn "%A" (inc ())

```

---

```

1 $ dotnet fsi makeCounter.fsx
2 1
3 2
4 3

```

that `makeCounter` returns a closure that includes the environment of the anonymous function at the point where it is defined. Hence, this closure includes a mutable value but does not reset it, every time it is called.

Variables implement dynamic scope, that is, the value of an identifier depends on *when* it is used. This is in contrast to lexical scope, where the value of an identifier depends on *where* it is defined. As an example, consider the script in Listing 4.16 which defines a function using lexical scope and returns the number 6.0, however, if `a` is made `mutable`, then the behavior is different, as shown in Listing 13.10. Here,

**Listing 13.10 dynamicScopeNFunction.fsx:**

Mutual variables implement dynamic scope rules. Compare with Listing 4.16.

```

1 let testScope x =
2     let mutable a = 3.0
3     let f z = a * z
4     a <- 4.0
5     f x
6 printfn "%A" (testScope 2.0)

```

---

```

1 $ dotnet fsi dynamicScopeNFunction.fsx
2 8.0

```

the response is 8.0, since the value of `a` changed before the function `f` was called.

## 13.2 While and For Loops

This book has previously emphasized recursion as a structure to encapsulate and repeat code. In the imperative paradigm, often *for*- and *while*-loops are preferred. A *while*-loop has the following syntax:

### Listing 13.11: While loop.

```
1 while <condition> do
2   <expr>
```

The *condition* `<condition>` is an expression that evaluates to true or false. A *while*-loop repeats the `<expr>` expression as long as the condition is true. The *do* keyword is mandatory and the body of the loop is indicated by indentation as usual. The return value of the *while* expression is “()”.

The program in Listing 13.14 is an example of a while-loop which counts from 1 to 10. Since the variable *i* is used for counting, it is often called the counter variable.

### Listing 13.12 countWhile.fsx: Count to 10 with a counter variable.

```
1 let mutable i = 1
2 while i <= 10 do
3   printf "%d " i
4   i <- i + 1
5 printf "\n"

-----

1 $ dotnet fsi countWhile.fsx
2 1 2 3 4 5 6 7 8 9 10
```

The counting is done by performing the following computation: In line 1, the counter variable is first given an initial value of 1. Then in line 2, the head of the while-loop and examines the condition. Since `1 <= 10`, the condition is true, and execution enters the body of the loop starting in line 3. The body prints the value of the counter to the screen and increases the counter by 1. Then execution returns to the head of the while-loop and reexamines the condition. Now the condition is `2 <= 10`, which is also true, and so execution enters the body and so on until the counter has reached the value 11, in which case the condition `11 <= 10` is false, and execution continues in line 5.

Counters are so common that a special syntax has been reserved for loops using counters. These are called *for-to*-loops. For-loops come in several variants, and here we will focus on the one using an explicit counter. Its syntax is:

**Listing 13.13: For loop.**

```

1 for <ident> = <firstExpr> to <lastExpr> do
2   <expr>

```

A for-loop initially binds the counter identifier `<ident>` to be the value `<firstExpr>`. Then execution enters the body, and `<bodyExpr>` is evaluated. Once done, the counter is increased, and execution evaluates `<bodyExpr>` once again. This is repeated as long as the counter is not greater than `<lastExpr>`. Again, the `do` keyword is mandatory and the body of the loop is indicated by indentation as usual. The return value of the `for` expression is “()”.

The counting example from Listing 13.12 using a `for`-loop is shown in Listing 13.14. As this interactive script demonstrates, the identifier `i` takes all the values between

**Listing 13.14 count.fsx:**  
 Counting from 1 to 10 using a `for`-loop.

```

1 for i = 1 to 10 do printf "%d " i done
2 printfn ""

-----

1 $ dotnet fsi count.fsx
2 1 2 3 4 5 6 7 8 9 10

```

1 and 10, but in spite of its changing state, it is not mutable.

Counting backwards is sufficiently common that F# has a `for-downto` structure, which works exactly like a `for-to`-loop except that the counter is decreased by 1 in each iteration. An example of this is shown in Listing 13.15.

**Listing 13.15 countBackwards.fsx:**  
 Counting from 10 to 1 using a `for-downto`-loop.

```

1 for i = 10 downto 1 do
2   printf "%d " i
3 printfn ""

-----

1 $ dotnet fsi countBackwards.fsx
2 10 9 8 7 6 5 4 3 2 1

```

There is also a customized syntax for indexing lists as shown in Listing 13.16. This particular syntax for sequentially indexing into lists using a for loop is to be preferred, since it completely avoids index-out-of-bound errors.

**Listing 13.16** listFor.fsx:Iterating over elements of a list with the `for-in`-loop.

```

1 for elm in [3..2..9] do
2   printf "%A " elm
3 printfn ""

```

---

```

1 $ dotnet fsi listFor.fsx
2 3 5 7 9

```

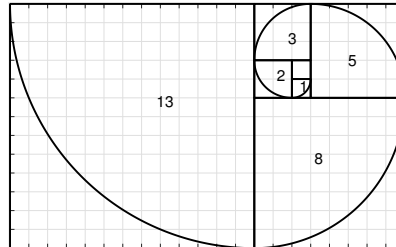
**13.3 Programming Intermezzo: Imperative Fibonacci numbers**

To further compare `for`- and `while`-loops, consider the following problem.

**Problem 13.1**

Write a program that calculates the  $n$ 'th Fibonacci number.

Fibonacci numbers is a sequence of numbers starting with 1, 1, and where the next number is calculated as the sum of the previous two. Hence the first ten numbers are: 1, 1, 2, 3, 5, 8, 13, 21, 34, 55. Fibonacci numbers are related to Golden spirals shown in Figure 13.2. Often the sequence is extended with a preceding number 0, to be



**Fig. 13.2** The Fibonacci spiral is an approximation of the golden spiral. Each square has side lengths of successive Fibonacci numbers, and the curve in each square is the circular arc with a radius of the square it is drawn in.

0, 1, 1, 2, 3, ..., which we will do here as well.

In Listing 8.5 we gave a solution using recursion. Here we will first use a `for`-loop, as shown in Listing 13.17. The basic idea of the solution is that if we are given the  $(n-1)$ 'th and  $(n-2)$ 'th numbers, the  $n$ 'th number is trivial to compute. And assuming that `fib(1)` and `fib(2)` are given, then it is trivial to calculate `fib(3)`. For `fib(4)`, we only need `fib(3)` and `fib(2)`, hence we may disregard `fib(1)`. Thus, we realize that we can cyclicly update the previous, current, and next values by shifting values until we have reached the desired `fib(n)`. This is implemented in Listing 13.17 as the function `fib`, which takes an integer `n` as argument and returns the  $n$ 'th Fibonacci number. The function does this iteratively using a `for`-loop, where `i` is the counter value, and `pair` is the pair of the  $i-1$ 'th and  $i$ 'th Fibonacci numbers. In the body of the



**Listing 13.17 fibFor.fsx:**  
**The  $n$ 'th Fibonacci number calculated using a for-loop.**

```

1 let fib n =
2   let mutable pair = (0, 1)
3   for i = 2 to n do
4     pair <- (snd pair, (fst pair) + (snd pair))
5   snd pair
6
7 printfn "fib(1) = %d" (fib 1)
8 printfn "fib(2) = %d" (fib 2)
9 printfn "fib(3) = %d" (fib 3)
10 printfn "fib(10) = %d" (fib 10)

```

---

```

1 $ dotnet fsi fibFor.fsx
2 fib(1) = 1
3 fib(2) = 1
4 fib(3) = 2
5 fib(10) = 55

```

loop, the  $i$ 'th and  $i + 1$ 'th numbers are assigned to `pair`. The `for`-loop automatically updates `i` for next iteration. When  $n < 2$  the body of the for-loop is not evaluated, and 1 is returned. This is of course wrong for  $n < 1$ , but we will ignore this for now.

Listing 13.18 shows a program similar to Listing 13.17 using a while-loop instead of for-loop. The programs are almost identical. In this case, the `for`-loop is to

**Listing 13.18 fibWhile.fsx:**  
**The  $n$ 'th Fibonacci number calculated using a while-loop.**

```

1 let fib (n : int) : int =
2   let mutable pair = (0, 1)
3   let mutable i = 1
4   while i < n do
5     pair <- (snd pair, fst pair + snd pair)
6     i <- i + 1
7   snd pair
8
9 printfn "fib(1) = %d" (fib 1)
10 printfn "fib(2) = %d" (fib 2)
11 printfn "fib(3) = %d" (fib 3)
12 printfn "fib(10) = %d" (fib 10)

```

---

```

1 $ dotnet fsi fibWhile.fsx
2 fib(1) = 1
3 fib(2) = 1
4 fib(3) = 2
5 fib(10) = 55

```

be preferred, since more lines of code typically mean more chances of making a mistake. However, while-loops are somewhat easier to argue correctness about.

While-loops also allow for logical structures other than for-loops, such as the case when the number of iteration cannot easily be decided when entering the loop. As an example, consider a slight variation of the above problem, where we wish to find the largest Fibonacci number less or equal some number. A solution to this problem is shown in Listing 13.19. The strategy here is to iteratively calculate Fibonacci

**Listing 13.19** `fibWhileLargest.fsx`:

Search for the largest Fibonacci number less than a specified number.

```

1 let largestFibLeq n =
2   let mutable pair = (0, 1)
3   while snd pair <= n do
4     pair <- (snd pair, fst pair + snd pair)
5     fst pair
6
7 for i = 1 to 10 do
8   printfn "largestFibLeq(%d) = %d" i (largestFibLeq i)

```

---

```

1 $ dotnet fsi fibWhileLargest.fsx
2 largestFibLeq(1) = 1
3 largestFibLeq(2) = 2
4 largestFibLeq(3) = 3
5 largestFibLeq(4) = 3
6 largestFibLeq(5) = 5
7 largestFibLeq(6) = 5
8 largestFibLeq(7) = 5
9 largestFibLeq(8) = 8
10 largestFibLeq(9) = 8
11 largestFibLeq(10) = 8

```

numbers until we've found one larger than the argument `n`, and then return the previous. This could not be calculated with a for-loop.

## 13.4 Arrays

One dimensional *arrays*, or just arrays for short, are mutable lists of the same type and follow a similar syntax as lists. Arrays can be stated as a *sequence expression*,

**Listing 13.20:** The syntax for an array using the sequence expression.

```

1 [| [<expr>{; <expr>}] |]

```

E.g., `[1; 2; 3]` is an array of integers, `[|"This"; "is"; "an"; "array"|]` is an array of strings, `[|(fun x -> x); (fun x -> x*x)|]` is an array of functions, `[]` is the empty array. Arrays may also be given as ranges,

**Listing 13.21:** The syntax for an array using the range expression.

```
1 [|<expr> .. <expr> [|.. <expr>]|]
```

but arrays of *range expressions* must be of `<expr>` integers, floats, or characters. Examples are `[1 .. 5]`, `[|-3.0 .. 2.0|]`, and `[|'a' .. 'z'|]`. Range expressions may include a step size, thus, `[1 .. 2 .. 10]` evaluates to `[1; 3; 5; 7; 9]`.

The array type is defined using the `array` keyword or alternatively the `[]` lexeme. Like strings and lists, arrays may be indexed using the `[]` notation. Arrays cannot be resized, but are mutable, as shown in Listing 13.22. Notice that in spite of

**Listing 13.22** `arrayReassign.fsx`:

Arrays are mutable in spite of the missing `mutable` keyword.

```
1 let square (a : int array) =
2     for i = 0 to a.Length - 1 do
3         a[i] <- a[i] * a[i]
4
5 let A = [| 1; 2; 3; 4; 5 |]
6 printfn "%A" A
7 square A
8 printfn "%A" A
-----
1 $ dotnet fsi arrayReassign.fsx
2 [|1; 2; 3; 4; 5|]
3 [|1; 4; 9; 16; 25|]
```

the missing `mutable` keyword, the function `square` still has the *side-effect* of squaring all entries in `A`. F# implements arrays as chunks of memory and indexes arrays via address arithmetic. I.e., element  $i$  in an array, whose first element is in memory address  $\alpha$  and whose elements fill  $\beta$  addresses each, is found at address  $\alpha + i\beta$ . Hence, indexing has computational complexity of  $O(1)$ , but appending and prepending values to arrays and array concatenation requires copying the new and existing values to a fresh area in memory and thus has computational complexity  $O(n)$ , where  $n$  is the total number of elements. Thus, **indexing arrays is fast, but cons and concatenation is slow and should be avoided.** ★

Arrays support *slicing*, that is, indexing an array with a range result in a copy of the array with values corresponding to the range. This is demonstrated in Listing 13.23.

As illustrated, the missing start or end index imply from the first or to the last element, respectively.

**Listing 13.23:** Examples of array slicing. Compare with Listing 7.3 and Listing 3.27.

```

1 > let arr = [|'a' .. 'g'|];;
2 val arr: char[] = [|'a'; 'b'; 'c'; 'd'; 'e'; 'f'; 'g'|]
3
4 > arr[0];;
5 val it: char = 'a'
6
7 > arr[3];;
8 val it: char = 'd'
9
10 > arr[3..];;
11 val it: char[] = [|'d'; 'e'; 'f'; 'g'|]
12
13 > arr[..3];;
14 val it: char[] = [|'a'; 'b'; 'c'; 'd'|]
15
16 > arr[1..3];;
17 val it: char[] = [|'b'; 'c'; 'd'|]
18
19 > arr[*];;
20 val it: char[] = [|'a'; 'b'; 'c'; 'd'; 'e'; 'f'; 'g'|]

```

Arrays do not have explicit operator support for appending and concatenation, instead the `Array` namespace includes an `Array.append` function, as shown in Listing 13.24.

**Listing 13.24** `arrayAppend.fsx`:  
Two arrays are appended with `Array.append`.

```

1 let a = [|1; 2;|]
2 let b = [|3; 4; 5|]
3 let c = Array.append a b
4 printfn "%A, %A, %A" a b c

```

---

```

1 $ dotnet fsi arrayAppend.fsx
2 [|1; 2|], [|3; 4; 5|], [|1; 2; 3; 4; 5|]

```

Arrays are *reference types*, meaning that identifiers are references and thus suffer from aliasing, as illustrated in Listing 13.25.

**Listing 13.25 arrayAliasing.fsx:**

Arrays are reference types and suffer from aliasing.

```
1 let a = [|1; 2; 3|];
2 let b = a
3 a[0] <- 0
4 printfn "a = %A, b = %A" a b;;

-----

1 $ dotnet fsi arrayAliasing.fsx
2 a = [|0; 2; 3|], b = [|0; 2; 3|]
```

### 13.4.1 Array Properties and Methods

Some important properties and methods for arrays are:

**Clone():** 'T [].

Returns a copy of the array.

#### Listing 13.26: Clone

```
1 > let a = [|1; 2; 3|];
2 let b = a.Clone()
3 a[0] <- 0
4 printfn "a = %A, b = %A" a b;;
5 a = [|0; 2; 3|], b = [|1; 2; 3|]
6 val a: int[] = [|0; 2; 3|]
7 val b: obj = [|1; 2; 3|]
8 val it: unit = ()
```

**Length:** int.

Returns the number of elements in the array.

#### Listing 13.27: Length

```
1 > [|1; 2; 3|].Length;;
2 val it: int = 3
```

### 13.4.2 The Array Module

There are quite a number of built-in procedures for arrays in the **Array** module, and many of them are almost identical to those in the **List** module, discussed in Section 7.1. However, a few additional functions are noted below:

**Array.append:** arr1:'T [] -> arr2:'T [] -> 'T [].

Creates a new array whose elements are a concatenated copy of arr1 and arr2.

#### Listing 13.28: Array.append

```
1 > Array.append [|1; 2;|] [|3; 4; 5|];;
2 val it: int[] = [|1; 2; 3; 4; 5|]
```

**Array.copy:** 'T [] -> 'T [].

Creates an array that contains the elements of the supplied array.

**Listing 13.29: Array.copy**

```

1 > let a = [|1; 2; 3|]
2 let b = Array.copy a;;
3 val a: int[] = [|1; 2; 3|]
4 val b: int[] = [|1; 2; 3|]

```

**Array.ofList: lst:'T list -> 'T [].**

Creates an array whose elements are copied from lst.

**Listing 13.30: Array.ofList**

```

1 > Array.ofList [1; 2; 3];;
2 val it: int[] = [|1; 2; 3|]

```

**Array.toList: arr:'T [] -> 'T list.**

Creates a new list whose elements are copied from arr.

**Listing 13.31: Array.toList**

```

1 > Array.toList [|1; 2; 3|];;
2 val it: int list = [1; 2; 3]

```

**13.4.3 Multidimensional Arrays**

*Multidimensional arrays* can be created as arrays of arrays (of arrays . . . ). These are known as *jagged arrays*, since there is no inherent guarantee that all sub-arrays are of the same size. The example in Listing 13.32 is a jagged array of increasing width. Indexing arrays of arrays is done sequentially, in the sense that in the above example,

**Listing 13.32 arrayJagged.fsx:**

An array of arrays of non-equal lengths is a jagged array.

```

1 let arr = [| [|1|]; [|1; 2|]; [|1; 2; 3|] |]
2
3 for row in arr do
4     for elm in row do
5         printf "%A " elm
6     printf "\n"

```

---

```

1 $ dotnet fsi arrayJagged.fsx
2 1
3 1 2
4 1 2 3

```

the number of outer arrays is `a.Length`, `a[i]` is the *i*'th array, the length of the

i'th array is `a[i].Length`, and the j'th element of the i'th array is thus `a[i][j]`. Often 2-dimensional rectangular arrays are used, which can be implemented as a jagged array, as shown in Listing 13.33. Note that, the `arr[i][j]` argument in

**Listing 13.33** `arrayJaggedSquare.fsx`:

A rectangular array.

```
1 let pownArray (arr : int array array) p =
2   for i = 1 to arr.Length - 1 do
3     for j = 1 to arr[i].Length - 1 do
4       arr[i][j] <- pown (arr[i][j]) p
5
6 let printArrayOfArrays (arr : int array array) =
7   for row in arr do
8     for elm in row do
9       printf "%3d " elm
10      printf "\n"
11
12 let A = [| [|1 .. 4|]; [|1 .. 2 .. 7|]; [|1 .. 3 .. 10|] |]
13 pownArray A 2
14 printArrayOfArrays A
```

---

```
1 $ dotnet fsi arrayJaggedSquare.fsx
2   1   2   3   4
3   1   9  25  49
4   1  16  49 100
```

line 4 must be parenthesized to avoid ambiguity. Further, the `for-in` cannot be used in `pownArray`, e.g.,

```
for row in arr do
  for elm in row do
    elm <- pown elm p
```

since the iterator value `elm` is not mutable, even though `arr` is an array.

Square arrays of dimensions 2 to 4 are so common that F# has built-in modules for their support. Here, we will describe `Array2D`. The workings of `Array3D` and `Array4D` are very similar. A generic `Array2D` has type 'T [, ]', and it is indexed also using the `[,]` notation. The `Array2D.length1` and `Array2D.length2` functions are supplied by the `Array2D` module for obtaining the size of an array along the first and second dimension. Rewriting the with jagged array example in Listing 13.33 to use `Array2D` gives a slightly simpler program, which is shown in Listing 13.34. Note that the `printf` supports direct printing of the 2-dimensional array. `Array2D` arrays support slicing. The `"*"` lexeme is particularly useful to obtain all values along a dimension. This is demonstrated in Listing 13.35. Note that in almost all cases, slicing produces a sub-rectangular 2 dimensional array, except for `arr[1,*]`, which is an array, as can be seen by the single `"["`. In contrast, `A[1..1,*]` is an



**Listing 13.34 array2D.fsx:**  
**Creating a 3 by 4 rectangular array of integers.**

```

1 let arr = Array2D.create 3 4 0
2 for i = 0 to (Array2D.length1 arr) - 1 do
3     for j = 0 to (Array2D.length2 arr) - 1 do
4         arr[i,j] <- j * Array2D.length1 arr + i
5 printfn "%A" arr

```

---

```

1 $ dotnet fsi array2D.fsx
2 [[0; 3; 6; 9]
3  [1; 4; 7; 10]
4  [2; 5; 8; 11]]

```

**Listing 13.35: Examples of Array2D slicing. Compare with Listing 13.34.**

```

1 > let arr = Array2D.init 3 4 (fun i j -> i + 10 * j);;
2 val arr: int[,] = [[0; 10; 20; 30]
3                   [1; 11; 21; 31]
4                   [2; 12; 22; 32]]
5
6 > arr[2,3];;
7 val it: int = 32
8
9 > arr[1..,3..];;
10 val it: int[,] = [[31]
11                  [32]]
12
13 > arr[..1,*];;
14 val it: int[,] = [[0; 10; 20; 30]
15                  [1; 11; 21; 31]]
16
17 > arr[1,*];;
18 val it: int[] = [|1; 11; 21; 31|]
19
20 > arr[1..1,*];;
21 val it: int[,] = [[1; 11; 21; 31]]

```

Array2D. Note also that `printfn` typesets 2 dimensional arrays as `[[ ... ]]` and not `[| | ... | |]`, which can cause confusion with lists of lists.

Multidimensional arrays have the same properties and methods as arrays, see Section 13.4.1.

### 13.4.4 The Array2D Module

The Array2D module is somewhat limited. In particular neither `fold` nor `foldback` functions exists. Most of the module's functions are mentioned below:

`copy: arr:'T [,] -> 'T [,]`.

Creates a new array whose elements are copied from `arr`.

#### Listing 13.36: Array2D.copy

```
1 > let a = Array2D.init 3 4 (fun i j -> i + 10 * j)
2 let b = Array2D.copy a;;
3 val a: int[,] = [[0; 10; 20; 30]
4                  [1; 11; 21; 31]
5                  [2; 12; 22; 32]]
6 val b: int[,] = [[0; 10; 20; 30]
7                  [1; 11; 21; 31]
8                  [2; 12; 22; 32]]
```

`create: m:int -> n:int -> v:'T -> 'T [,]`.

Creates an `m` by `n` array whose elements are set to `v`.

#### Listing 13.37: Array2D.create

```
1 > Array2D.create 2 3 3.14;;
2 val it: float[,] = [[3.14; 3.14; 3.14]
3                    [3.14; 3.14; 3.14]]
```

`init: m:int -> n:int -> f:(int -> int -> 'T) -> 'T [,]`.

Creates an `m` by `n` array whose elements are the result of applying `f` to the index of an element.

#### Listing 13.38: Array2D.init

```
1 > Array2D.init 3 4 (fun i j -> i + 10 * j);;
2 val it: int[,] = [[0; 10; 20; 30]
3                  [1; 11; 21; 31]
4                  [2; 12; 22; 32]]
```

`iter: f:('T -> unit) -> arr:'T [,] -> unit.`

Applies `f` to each element of `arr`.

**Listing 13.39: Array2D.iter**

```

1 > let arr = Array2D.init 3 4 (fun i j -> i + 10 * j)
2 Array2D.iter (fun elm -> printf "%A " elm) arr
3 printfn "";
4 0 10 20 30 1 11 21 31 2 12 22 32
5 val arr: int[,] = [[0; 10; 20; 30]
6                   [1; 11; 21; 31]
7                   [2; 12; 22; 32]]
8 val it: unit = ()

```

**length1:** arr:'T [,] -> int.

Returns the length the first dimension of arr.

**Listing 13.40: Array2D.length1**

```

1 > let arr = Array2D.create 2 3 0.0 in Array2D.length1
  arr;;
2 val it: int = 2

```

**length2:** arr:'T [,] -> int.

Returns the length of the second dimension of arr.

**Listing 13.41: Array2D.forall length2**

```

1 > let arr = Array2D.create 2 3 0.0 in Array2D.length2
  arr;;
2 val it: int = 3

```

**map:** f:('T -> 'U) -> arr:'T [,] -> 'U [,].

Creates a new array whose elements are the results of applying f to each of the elements of arr.

**Listing 13.42: Array2D.map**

```

1 > let arr = Array2D.init 3 4 (fun i j -> i + 10 * j)
2 Array2D.map (fun x -> x * x) arr;;
3 val arr: int[,] = [[0; 10; 20; 30]
4                   [1; 11; 21; 31]
5                   [2; 12; 22; 32]]
6 val it: int[,] = [[0; 100; 400; 900]
7                   [1; 121; 441; 961]
8                   [4; 144; 484; 1024]]

```

## 13.5 Tracing Imperative Programs

Debugging imperative programs is more complicated than declarative programs. In particular, the notion of states require us to keep track of the dynamic scope of values.

In the following, we will discuss trace-by-hand of **for**-loops followed by programs which involves states.

### 13.5.1 Tracing Loops

Consider the program in Listing 13.43. The program includes a function for printing

**Listing 13.43** `printSquares.fsx`:  
Print the squares of a sequence of positive integers.

```

1 let N = 3
2 let printSquares n =
3   for i = 1 to n do
4     let p = i * i
5     printfn "%d: %d" i p
6
7 printSquares N

```

---

```

1 $ dotnet fsi printSquares.fsx
2 1: 1
3 2: 4
4 3: 9

```

the sequence of the first  $N$  squares of integers. It uses a **for**-loop with a counting value. F# creates a new environment each time the loop body is executed. Thus, to trace this program, we mentally *unfold* the loop as shown in Listing 13.44. The unfolding contains 3 new scopes lines 3–7, lines 8–12, and lines 13–17 corresponding to the 3 times, the loop is repeated, and each scope starts by binding the counting value to the name `i`.

In the rest of this section, we will refer to the code in Listing 13.43. The first rows in our tracing-table looks as follows:

Step	Line	Env.	Bindings and evaluations
0	-	$E_0$	()
1	1	$E_0$	$N = 3$
2	2	$E_0$	$\text{printSquares} = ((n), \text{printSquares-body}, (N = 3))$
3	7	$E_0$	$\text{printSquares } N = ?$

Note that due to the lexical scope rule, the closure of `printSquares` includes `N` in its environment element. Calling `printSquares N` causes the creation of a new environment,

**Listing 13.44** printSquaresUnfold.fsx:  
An unfolded version of Listing 13.43.

```

1 let N = 3
2 let printSquaresUnfold n =
3   (
4     let i = 1
5     let p = i * i
6     printfn "%d: %d" i p
7   )
8   (
9     let i = 2
10    let p = i * i
11    printfn "%d: %d" i p
12  )
13  (
14    let i = 3
15    let p = i * i
16    printfn "%d: %d" i p
17  )
18
19 printSquaresUnfold N

```

---

```

1 $ dotnet fsi printSquaresUnfold.fsx
2 1: 1
3 2: 4
4 3: 9

```

Step	Line	Env.	Bindings and evaluations
4	2	$E_1$	$((n = 3), \text{printSquares-body}, (N = 3))$

The first statement of printSquares-body is the **for**-loop. As our unfolding in Listing 13.44 demonstrated, each time the loop-body is executed, a new scope is created with a new binding to *i*. Reusing the notation from closures, we write

Step	Line	Env.	Bindings and evaluations
5	3	$E_1$	for ... = ?

and create a new environment as if it had been a function,

Step	Line	Env.	Bindings and evaluations
6	3	$E_2$	$((i = 1), \text{for-body}, (n = 3, N = 3))$

As for functions, this denotes the bindings available at beginning of the execution of the **for**-body. The first line in the **for**-body is the binding of the value of an expression to *p*. The expression is *i*\**i*, and to calculate its value, we look in the **for**-loop's pseudo-closure where we find the *i* = 1 binding. Hence,

Step	Line	Env.	Bindings and evaluations
7	4	$E_2$	$i * i = 1$
8	4	$E_2$	$p = 1$

The final step in the for-body is the `printfn`-statement. Its arguments we get from the updated, active environment  $E_2$  and write,

Step	Line	Env.	Bindings and evaluations
9	5	$E_2$	output = "1 : 1\n"

At this point, the `for`-loop has reached its last line,  $E_2$  is deleted, we create a new environment with the counter variable increased by 1, and repeat. Hence,

Step	Line	Env.	Bindings and evaluations
10	3	$E_3$	$((i = 2), \text{for-body}, (n = 3, N = 3))$
11	4	$E_3$	$i * i = 4$
12	4	$E_3$	$p = 4$
13	5	$E_3$	output = "2 : 4\n"

Again, we delete  $E_3$ , create  $E_4$  where  $i$  is incremented, and repeat,

Step	Line	Env.	Bindings and evaluations
14	3	$E_4$	$((i = 3), \text{for-body}, (n = 3, N = 3))$
15	4	$E_4$	$i * i = 9$
16	4	$E_4$	$p = 9$
17	5	$E_4$	output = "3 : 9\n"

Finally, incrementing  $i$  would mean that  $i > n$ , hence the `for`-loop ends and as all statements returns `()`

Step	Line	Env.	Bindings and evaluations
18	3	$E_4$	return = <code>()</code>

At this point, the environment  $E_4$  is deleted, and we return to the enclosing environment  $E_1$  and the statement or expression following Step 5. Since the `for`-loop is the last expression in the `printSquares` function, its return value is that of the `for`-loop,

Step	Line	Env.	Bindings and evaluations
19	3	$E_1$	return = <code>()</code>

Returning to Step 3 and environment  $E_0$ , we have now calculated the return-value of `printSquares N` to be `()`, and since this line is the last of our program, we return `()` and end the program:

Step	Line	Env.	Bindings and evaluations
20	3	$E_0$	return = ()

### 13.5.2 Tracing Mutable Values

For mutable bindings, the scope is dynamic. For this, we need the concept of storage. Consider the program in Listing 13.45. To trace the dynamic behavior of this

**Listing 13.45** dynamicScopeTracing.fsx:  
Example of lexical scope and closure environment.

```

1 let testScope x =
2   let mutable a = 3.0
3   let f z = a * z
4   a <- 4.0
5   f x
6 printfn "%A" (testScope 2.0)
-----
1 $ dotnet fsi dynamicScopeTracing.fsx
2 8.0

```

program, we add a second table to our hand tracing, which is initially empty and has the columns Step and Value to hold the Step number when the value was updated and the value stored. For Listing 13.45, the firsts 4 steps thus look like,

Step	Line	Env.	Bindings and evaluations	Step	Value
0	-	$E_0$	()	0	-
1	1	$E_0$	testScope = ((x), body, ())		
2	6	$E_0$	testScope 2.0 = ?		
3	1	$E_1$	((x = 2.0), body, ())		

The mutable binding in line 2 creates an internal name and a dynamic storage location. The name *a* will be bound to a reference value, which we call  $\alpha_1$ , and which is a unique name shared between the two tables:

Step	Line	Env.	Bindings and evaluations	Step	Value
4	2	$E_1$	$a = \alpha_1$	4	$\alpha_1 = 3.0$

The following closure of *f* uses the reference-name instead of its value,

Step	Line	Env.	Bindings and evaluations	Step	Value
5	3	$E_1$	$f = ((z), a * z, (x = 2.0, a = \alpha_1))$	4	$\alpha_1 = 3.0$

In line 4, the value in the storage is updated by the assignment operator, which we denote as,

Step	Line	Env.	Bindings and evaluations	Step	Value
6	4	$E_1$	$a \leftarrow 4.0$	6	$\alpha_1 = 4.0$

Hence, when we evaluate the function  $f$ , its closure looks up the value of  $a$  by following the reference and finding the new value:

Step	Line	Env.	Bindings and evaluations	Step	Value
7	5	$E_1$	$f\ x = ?$	6	$\alpha_1 = 4.0$
8	5	$E_2$	$((z = 2.0), a * z, (x = 2.0, a = \alpha_1))$		
9	5	$E_2$	$a * z = 8.0$		
10	5	$E_2$	return = 8.0		
10	5	$E_1$	return = 8.0		
11	6	$E_0$	output = "8.0\n"		
12	6	$E_0$	return = ()		

For reference, the complete pair of tables is shown in Table 13.1. By comparing this

Step	Line	Env.	Bindings and evaluations	Step	Value
0	-	$E_0$	()	0	-
1	1	$E_0$	testScope = ((x), body, ())	4	$\alpha_1 = 3.0$
2	6	$E_0$	testScope 2.0 = ?	6	$\alpha_1 = 4.0$
3	1	$E_1$	((x = 2.0), body, ())		
4	2	$E_1$	$a = \alpha_1$		
5	3	$E_1$	$f = ((z), a * z, (x = 2.0, a = \alpha_1))$		
6	4	$E_1$	$a \leftarrow 4.0$		
7	5	$E_1$	$f\ x = ?$		
8	5	$E_2$	$((z = 2.0), a * z, (x = 2.0, a = \alpha_1))$		
9	5	$E_2$	$a * z = 8.0$		
10	5	$E_2$	return = 8.0		
10	5	$E_1$	return = 8.0		
11	6	$E_0$	output = "8.0\n"		
12	6	$E_0$	return = ()		

**Table 13.1** The complete table produced while tracing the program in Listing 13.45 by hand.

to the value-bindings in Listing 4.32, we see that the mutable values give rise to a different result due to the difference between lexical and dynamic scope.

## 13.6 Key Concepts and Terms in This Chapter

In this chapter, we have looked at programming with states using the imperative programming paradigm. You have seen how to:



- define **mutable variables** and make loops with **while**- and **for**- loops
- work with **arrays**, **jagged arrays**, and **2-dimensional arrays**.
- **trace-by-hand** programs involving mutable values and for-loops.

