# Covid 19-Xray Image Segmentation Using Thresholding And K-Means Clustering

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#### Introduction

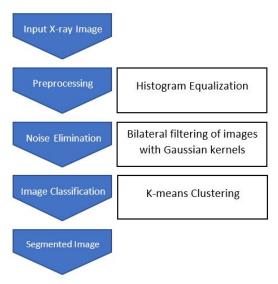
- The novel coronavirus disease 2019 (COVID-19) constitutes a public health emergency globally and causes severe inflammation in your lungs.
- Chest X-ray is among the most commonly used imaging modalities to identify COVID-19 infections and other various pulmonary diseases due to its low radiation, free of side effects, economic feasibility.
- Extraction of lung areas from the X-rays by accurately detecting lung boundaries is an important step, especially in determining whether the lung is normal or abnormal.



# Primary goal

- This project proposes two unsupervised learning method for lung segmentation of COVID 19 patients based on thresholding and k means clustering.
- This computational procedures for image preparation can be used for further analysis by medical specialists.
- Three-stage computational procedure includes
  - Pre processing X-ray images are typically low resolution, and the
    pixel intensity distribution can have wide verities due to patients age
    and configuration of X-ray capturing devise. Therefore, image pre
    processing will be carried out to improve the quality of the image and
    enhance significant areas.
  - Noise elimination Noise elimination techniques are used to eliminate noise occurred in the pre processing steps and initial steps by preserving the details of image.
  - **Classification** Proposed two classification methods local threshold method and k-means clustering method.

# Method Based on K means Clustering

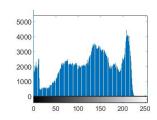


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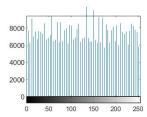
# Image Preprocessing Using Histogram Equalization

• Histogram equalization is a method to adjust the contrast of an image by modifying the intensity distribution of the histogram.









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# Noise Elimination Using Bilateral filtering

## **Gaussian filtering**

2-D convolution operator that is used to 'blur' images and remove detail and noise. The Gaussian outputs a 'weighted average' of each pixel's neighborhood, with the average weighted more towards the value of the central pixels.

## Bilateral filtering

The bilateral filter is also defined as a weighted average of nearby pixels, in a manner very similar to Gaussian convolution. The difference is that the bilateral filter takes into account the difference in value with the neighbors to preserve edges while smoothing.





# K Means Clustering For Image segmentation

The K-means algorithm clusters data by trying to separate pixels in 2 groups of equal variance, minimizing within-cluster sum-of-squares.

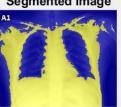
## **Algorithm**

- Randomly assign objects to 2 nonempty initial partitions
- Compute the centroids of the clusters of current partitioning
- Assign each object to the cluster with nearest centroid
- Repeat step 2 and 3, Stop when the assignment does not change

#### Image after preprocessing



Segmented image



Segmented image



## Convex Hull For Border Detection

- Convex hull (CH) is basically an important geometrical problem that could be solved computationally. The problem is all about constructing, developing, articulating, circumscribing or encompassing a given set of points in plane by a polygonal capsule called convex polygon.
- This algorithm search the border points, and help to determine an outline of the lung's boundaries.

Original image



Segmented image



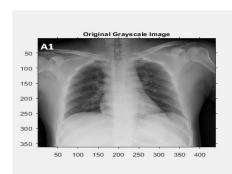
Final output

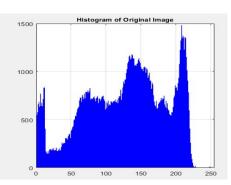


# Method Based On Thresholding

#### **Pre-processig**

• Images are converted from RGB to gray scale.





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# Thresholding Using Otsu's Method (Contd.)

- ullet Classify the pixel into two classes,  $C_1$  and  $C_2$  by a threshold at level T.
- The optimal T minimizes the within class variance  $\sigma_W^2$ , or equivalently, maximize the between class variance  $\sigma_B^2$ , where  $\sigma_W^2$  and  $\sigma_B^2$  defined as

$$\sigma_W^2 = w_1 \sigma_1^2 + w_2 \sigma_2^2$$

$$\sigma_B^2 = w_1 (\mu_1 - \mu_L)^2 + w_2 (\mu_2 - \mu_L)^2 = w_1 w_2 (\mu_2 - \mu_1)^2$$

where  $\sigma_1^2$  and  $\sigma_2^2$  are class variances,  $\mu_1$  and  $\mu_2$  are class mean levels, and  $w_1$  and  $w_2$  are the probabilities of class occurrence.

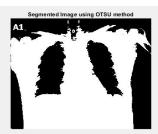
# Thresholding Using Otsu's Method (Contd.)

• If J(x,y) be the thresholded version of the grey-level image I(x,y) at threshold  $\mathsf{T}$ ,

$$J(x,y) = \begin{cases} 1 & if \ I(x,y) > T \\ 0 & if \ I(x,y) \le T \end{cases}$$

# Thresholding Using Otsu's Method (Contd.)











### Discussion

- This project proposes two unsupervised learning method for lung segmentation of COVID 19 patients based on thresholding and k means clustering.
- Obtained segmented X-ray image will be helpful in the medical diagnosis by medical specialists
- Method is incapable of extracting lung region associated with heart from the X-ray image.

## References

- Aleksandr Zotin, Yousif Hamad, Konstantin Simonov, Mikhail Kurako (2019) "Lung boundary detection for chest X-ray images classification based on GLCM and probabilistic neural networks", *Procedia Computer Science*, Vol. 159, pp 1439-1448,
- P. Pattrapisetwong and W. Chiracharit (2016) "Automatic lung segmentation in chest radiographs using shadow filter and local thresholding", *IEEE Conference on Computational Intelligence in Bioinformatics and Computational Biology* (CIBCB), pp. 1-6
- Sylvain Paris, Pierre Kornprobst, Jack Tumblin and Frédo Durand (2009), "Bilateral Filtering: Theory and Applications", Foundations and Trends® in Computer Graphics and Vision: Vol. 4: No. 1, pp 1-73.

