



Aftab Narsimhan

Electrical Engineering

TECHNICAL SKILLS

Programming: C# • C • Java • Android • HTML / CSS / JS • Assembly (8051)

Software Tools: MS Visual Studio • Atmel Studio • Android Studio • Brackets • Git / Perforce • Linux

Embedded Systems: Atmel, Arduino, Raspberry Pi, Altera, Smart Servo Motors

ACADEMIC & CO-OP STATUS

- | | |
|-------------------------|--|
| Academic Program | <ul style="list-style-type: none">• Biomedical Electrical Engineering; 6 of 8 academic terms completed• Anticipated date of graduation: May, 2017 |
| Co-op Status | <ul style="list-style-type: none">• Completed 3/4 work terms; available for 4 months beginning May, 2016 |

CO-OP WORK EXPERIENCE

Kardium Inc. **September, 2014 – September, 2015**

Automation Engineer Co-op

- Created hardware and software solutions to automate the manufacturing processes involved with building the components of a medical catheter device
- Designed/updated PCBs using Altium, populated them through surface-mount soldering, and tested them using standard electrical tools
- Wrote the drivers for the board using Atmel or Arduino microcontrollers in C
- Created GUI applications that interfaced with the device and many APIs or supporting libraries using C#
- Implemented databases using Microsoft SQL Management Studio and Entity Framework with C# to log data and keep track of calibrations/settings between multiple devices
- Created solutions using concepts such as PID controllers, threading, SPI, thermocouples, watchdogs, filters,

TECHNICAL PROJECTS

EC Turbo-Fan Helicopter **January, 2016 – Present**

Team Lead, Control System Lead

- Designing a 2-Degree-of-Freedom (DoF) helicopter with all but the lift and yaw DoF mechanically constrained
- Developing a closed loop feedback system by implementing a PID controller within a microcontroller that interfaces with sensors to control the position of the helicopter
- Writing the firmware for the microcontroller in C++ and creating a GUI test interface in C# to allow for quicker and more efficient calibration, PID tuning and debugging
- Adding Bluetooth capabilities to the device to allow for wireless PID tuning and flashing of new firmware
- Creating an android app with a simulated joystick to allow for easy, wireless control of the helicopter

Raspberry Pi Internet Monitor **January, 2016 – Present**

Personal Project

- Developing a small embedded solution on a Raspberry Pi 2 in order to monitor the status of my home internet and alert me of connectivity issues, as well as to gain experience using Python
- Implemented a GUI to allow for easy customization of monitoring parameters, and hardware indicators (LEDs) for easy visual cues of internet status

Smart Fall Detector **March, 2015**

nwHacks Hackathon

- Prototyped a smart fall detector for safety of elderly patients in a care-home
- Developed an Android app which relays alerts sent from the fall detector (i.e. Myo armband) by Bluetooth
- Implemented a cloud-based backend storage (Firebase) which updates a central web portal monitored in real-time by hospital personnel based on data received by the Android app

Electromagnetic Tether Robots

March, 2014 – April, 2014

Firmware Lead

- Worked with a group of 6 peers to design, build, program and test an autonomous robot (receiver) that follows another keypad controlled robot (electromagnetic beacon)
- Designed and programmed a state machine for the robots and implemented several commands such as parallel park with SPI using Assembly and C

VOLUNTEER WORK EXPERIENCE

Vancouver General Hospital, Vancouver, BC

January, 2016 – Present

Electronic Patient Data Transfer Solution

- Developing a simple Android app and web portal to modernize a paper-based data transfer process while also maintaining “backwards compatibility” for user preference
- Using the web portal to allow a doctor to generate and print a QR code from entered patient data, which is to be scanned and populated into a pdf template on the patient's phone using the Android App

Toronto General Hospital, Toronto, ON

July, 2013 – August, 2013

Research Assistant / Engineering Consultant

- Worked meticulously and independently to learn the complex aspects of a portable ex vivo liver perfusion device being developed, within two weeks, to further my understanding of the device and how to simplify its components
- Demonstrated initiative beyond expectation by producing the outline of a new prototype, with modifications that makes the device more portable, earning me a recommendation letter from my supervisor

Agilent Technologies, Santa Clara, CA

July, 2010 – August, 2010

QA Intern

- Worked with the R & D Team in the automation and robotics department, classifying and validating up to 20 software defects a day to improve robustness and stability of the Bravo Liquid Handling System
- Learned VWorks automation and the Bravo instrument software independently within a few days and used them for debugging purposes
- Documented and organized findings using an excel spreadsheet and submitted to the supervisor for further functional improvement of the Bravo instrument

EDUCATION

University of British Columbia

September, 2012 – Present

Bachelor of Applied Science – Electrical Engineering

- Dean's Honour List (2014 – 2015)

Credits: 86 Cumulative Grade: 86.2%

North Toronto Collegiate Institute

September, 2009 – June, 2012

High School Diploma

- Achieved Honour Roll for all 4 years

CLUBS AND SOCIETIES

UBC Open Robotics

May, 2014 – Present

APEGBC Member Advantage Program for Students (MAPs)

September, 2013 – Present

UBC Biomedical Engineering Student Team

March, 2014 – March, 2015

ACTIVITIES AND INTERESTS

- Coding, gaming, reading
- Rock climbing, badminton, Ultimate Frisbee, exercising, Travelling
- Technology that has a huge impact / influence on society
- Learning languages