# Aftab Narsimhan

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# Education UNIVERSITY OF BRITISH COLUMBIA

Electrical Engineering -Biomedical Option

Expected: May, 2017Dean's List (Year 2)

Cumulative GPA: 86.2%

### **Skills**

### **PROGRAMMING**

Proficient:

• C# • C • Java

Experienced:

 $\bullet \ \textit{Android} \bullet \ \textit{HTML} \bullet \ \textit{CSS}$ 

Familiar:

• JavaScript • Assembly

#### **EQUIPMENT**

Microcontrollers:

- Atmel Arduino Raspberry Pi
- Altera Smart Servo Motors
   Electrical:
- Liectificat.
- Standard Electrical Equipment
- Surface Mount Soldering

#### COMPUTER / SOFTWARE

Programming:

- MS Visual Studio Atmel Studio
- Android Studio Eclipse

**Electrical Design** 

Altium • CircuitMaker

Graphic / Web Design:

- Photoshop Illustrator WebStormOther:
- Git Perforce Linux

# Clubs and Societies UBC OPEN ROBOTICS

May, 2014 - Present

**UBC BEST** 

March, 2014 - March, 2015

### **Technical Experience**

KARDIUM INC. | AUTOMATION ENGINEER CO-OP

Sep, 2014 - Sep, 2015 | Burnaby, BC

- Created hardware and software solutions to automate the manufacturing processes involved with building the components of a medical catheter device
- Designed/updated PCBs using Altium, populated them through surface-mount soldering, and tested them using standard electrical tools
- Wrote the drivers for the board using Atmel or Arduino microcontrollers in C
- Created GUI applications that interfaced with the device and many APIs or supporting libraries using C#
- Implemented databases using Microsoft SQL Management Studio and Entity Framework with C# to log data and keep track of calibrations/settings between multiple devices
- Developed several solutions using PID controllers, threading, timers / interrupts, SPI, thermocouples, watchdogs, filters, ADCs, USART communication

### **Technical Projects**

**EC TURBO-FAN HELICOPTER** | TEAM LEAD, CONTROL SYSTEM LEAD January. 2016 - Present

- Designing a 2-Degree-of-Freedom (DoF) helicopter with all but the lift and yaw DoF mechanically constrained
- Developing a closed loop feedback system by implementing a PID controller within a microcontroller that interfaces with sensors to accurately control the position of the helicopter
- Writing the firmware for the microcontroller in C++ and creating a GUI test interface in C# for quicker and more efficient calibration, PID tuning, and debugging
- Adding Bluetooth capabilities to the device for wireless PID tuning and flashing of new firmware
- Creating an android app with a simulated joystick for easy, wireless control
  of the helicopter

## PATIENT E-DATA TRANSFER | VANCOUVER GENERAL HOSPITAL January, 2016 - Present

 Developing a way to modernize a paper-based data transfer process between doctor and patient after intubation procedures, through the use of QR codes, a patient Android app, and a web portal

### SMART FALL DETECTOR | NWHACKS HACKATHON

March, 2015

 Prototyped a smart fall detection system to alert hospital personnel in the event of a patient falling through the use of an Android app, a Myo armband, an online database (Firebase) and a central web portal