Aftab Narsimhan

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TECHNICAL SKILLS

Programming: C# • C • Java • Android • HTML / CSS / JS • Assembly (8051)

Software Tools: MS Visual Studio • Atmel Studio • Android Studio • Git / Perforce • Linux

Embedded Systems: Atmel • Arduino • Raspberry Pi • Altera • Smart Servo Motors

EDUCATION

University of British Columbia

Bachelor of Applied Science - Electrical Engineering

• Expected Graduation: 2017

• Dean's Honour List (2014 - 2015)

Credits: 86 Cumulative Grade: 86.2%

September, 2012 - Present

CO-OP WORK EXPERIENCE

Kardium Inc.

Automation Engineer Co-op

September, 2014 - September, 2015

- Created hardware and software solutions to automate the manufacturing processes involved with building the components of a medical catheter device
- Designed/updated PCBs using Altium, populated the boards through surface-mount soldering, and tested with standard electrical tools
- Wrote the drivers for the board using Atmel or Arduino microcontrollers in C
- Used C# to create GUI applications that interfaced with the device and many APIs or supporting libraries
- Implemented databases using Microsoft SQL Management Studio and Entity Framework with C# to log data and keep track of calibrations/settings between multiple devices
- Developed several solutions using PID controllers, threading, timers / interrupts, SPI, thermocouples, watchdogs, filters, ADCs, USART communication

TECHNICAL PROJECTS

EC Turbo-Fan Helicopter Team Lead, Control System Lead

January, 2016 - Present

- Designing a 2-Degree-of-Freedom (DoF) helicopter with all but the lift and yaw DoF mechanically constrained
- Developing a closed loop feedback system by implementing a PID controller within a microcontroller that interfaces with sensors to control the position of the helicopter
- Writing the firmware for the microcontroller in C++ and creating a GUI test interface in C# to allow for quicker and more efficient calibration, PID tuning and debugging
- Adding Bluetooth capabilities to the device to allow for wireless PID tuning and flashing of new firmware
- Creating an Android app with a simulated joystick to allow for easy, wireless control of the helicopter

Raspberry Pi Internet Monitor Personal Project

January, 2016 - Present

- Developing a small embedded solution on a Raspberry Pi 2 in order to monitor the status of my home internet and alert me of connectivity issues, as well as to gain experience using Python
- Implementing a GUI to allow for easy customization of monitoring parameters, and hardware indicators (LEDs) for easy visual cues of internet status

Personal Portfolio Website

August, 2015 - Present

http://www.aftabnarsimhan.com

- Developed a personal website from the ground up using HTML, CSS, JS and PHP with the Bootstrap framework in order to have a more prominent online presence and learn the basics of web development
- Learned how to use Adobe Photoshop and Illustrator CS6 in order to create my own graphics

Smart Fall Detector March, 2015

nwHacks Hackathon

- Prototyped a smart fall detector for safety of elderly patients in a care-home
- Developed an Android app which relays alerts sent from the fall detector (i.e. Myo armband) by Bluetooth
- Implemented a cloud-based backend storage (Firebase) which updates a central web portal monitored in real-time by hospital personnel based on data received by the Android app

Electromagnetic Tether Robots Firmware Lead

March, 2014 - April, 2014

- Firmware Lead
- Worked with a group of 6 peers to design, build, program and test an autonomous robot (receiver) that follows another keypad controlled robot (electromagnetic beacon)
- Designed and programmed a state machine for the robots and implemented several commands such as parallel park with SPI using Assembly and C

VOLUNTEER WORK EXPERIENCE

Vancouver General Hospital, Vancouver, BC Electronic Patient Data Transfer Solution

January, 2016 - Present

- Developing a way to modernize a paper-based data transfer process between a doctor and patient after intubation procedures
- Implementing the data transfer through the use of a QR code generated from a web portal, which can then be scanned by an Android app on the patient's phone in order to generate an electronic copy

Toronto General Hospital, Toronto, ON Research Assistant / Engineering Consultant

July, 2013 - August, 2013

- Worked meticulously and independently to learn the complex aspects of a portable ex vivo liver perfusion device being developed, within two weeks, to further my understanding of the device and how to simplify its components
- Demonstrated initiative beyond expectation by producing the outline of a new prototype, with modifications that makes the device more portable, earning me a recommendation letter from my supervisor

Agilent Technologies, Santa Clara, CA *QA Intern*

July, 2010 - August, 2010

- Worked with the R&D Team in the automation and robotics department, classifying and validating up to 20 software
 defects a day to improve robustness and stability of the Bravo Liquid Handling System
- Learned VWorks automation and the Bravo instrument software independently within a few days and used them for debugging purposes
- Documented and organized findings using an excel spreadsheet and submitted to the supervisor for further functional improvement of the Bravo instrument

CLUBS AND SOCIETIES

UBC Open Robotics
APEGBC Member Advantage Program for Students (MAPs)
UBC Biomedical Engineering Student Team

May, 2014 – Present September, 2013 – Present March, 2014 – March, 2015

ACTIVITIES AND INTERESTS

- Coding, gaming, reading, learning languages
- Rock climbing, badminton, Ultimate Frisbee, exercising, travelling
- Technology that has a huge impact / influence on society