

Coronal Mass Ejections: Characterisation & Kinematics

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CME Study

- Eruptions of Plasma & Magnetic Field
- Theoretical Models
- Image Processing
- Morphology & Kinematics
- STEREO Analysis

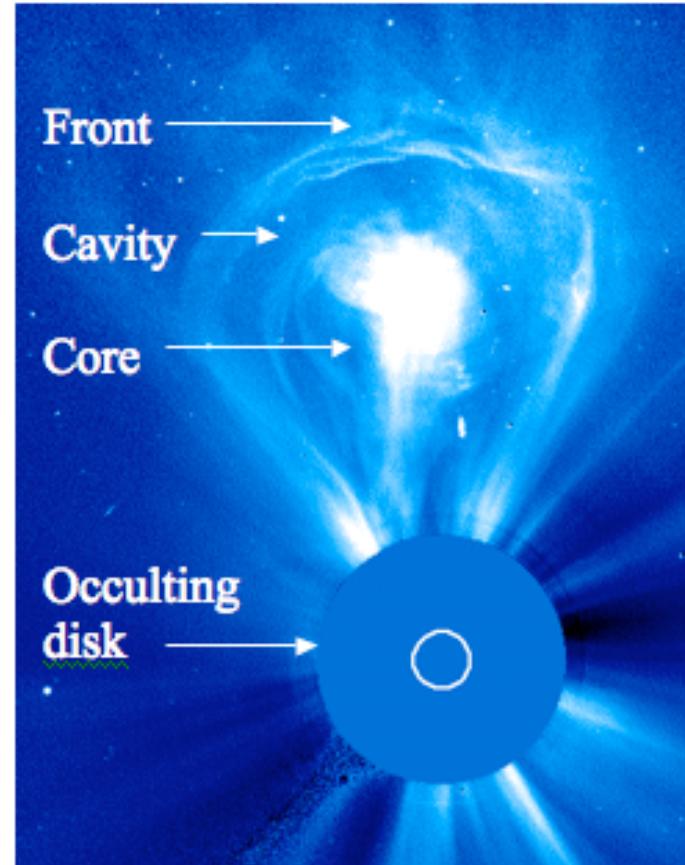


Figure 1: The fundamental components of a CME observed by the LASCO coronagraph on the SOHO spacecraft.

CME Models

- Magnetic Flux-Rope:
- Magnetic Break-out:

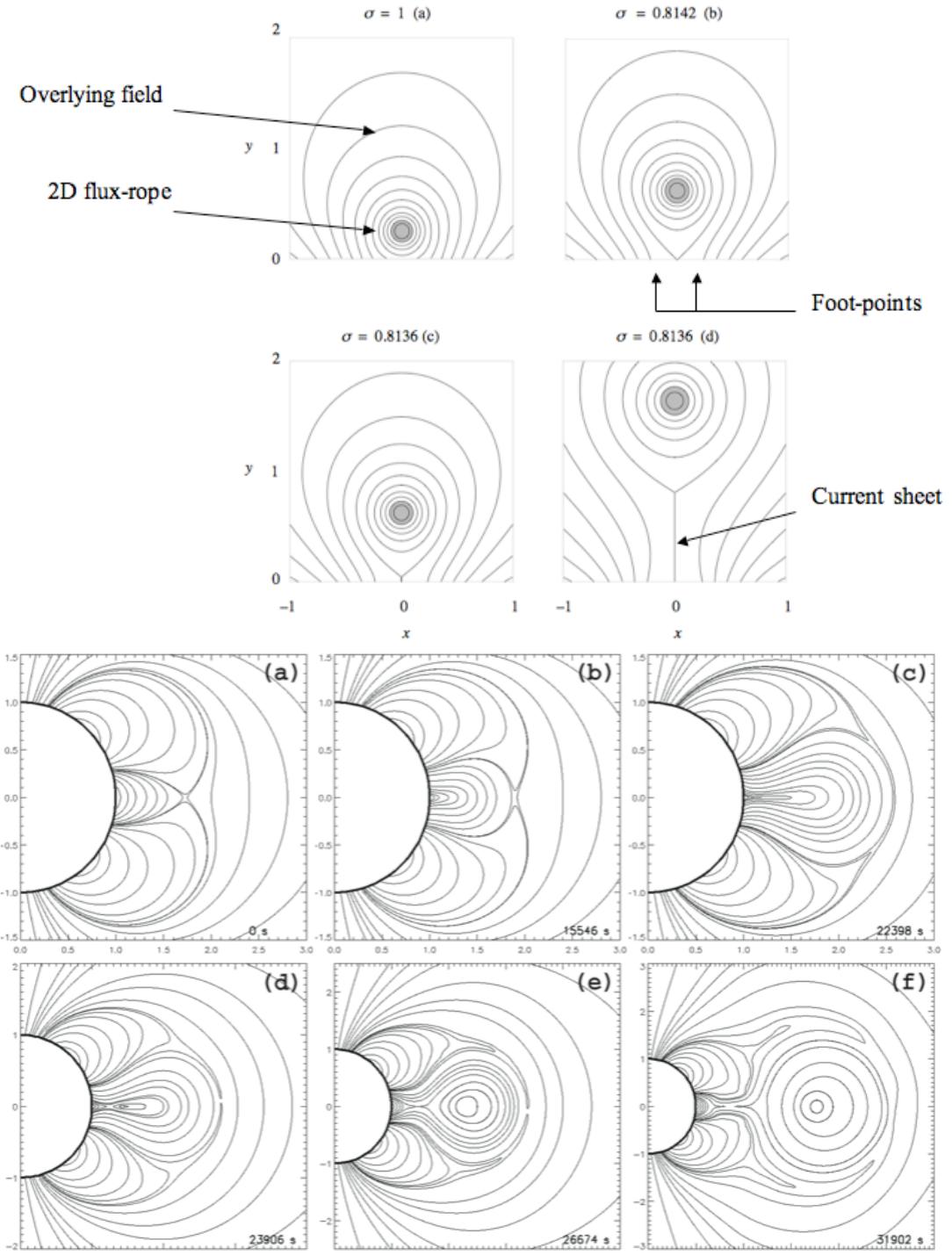
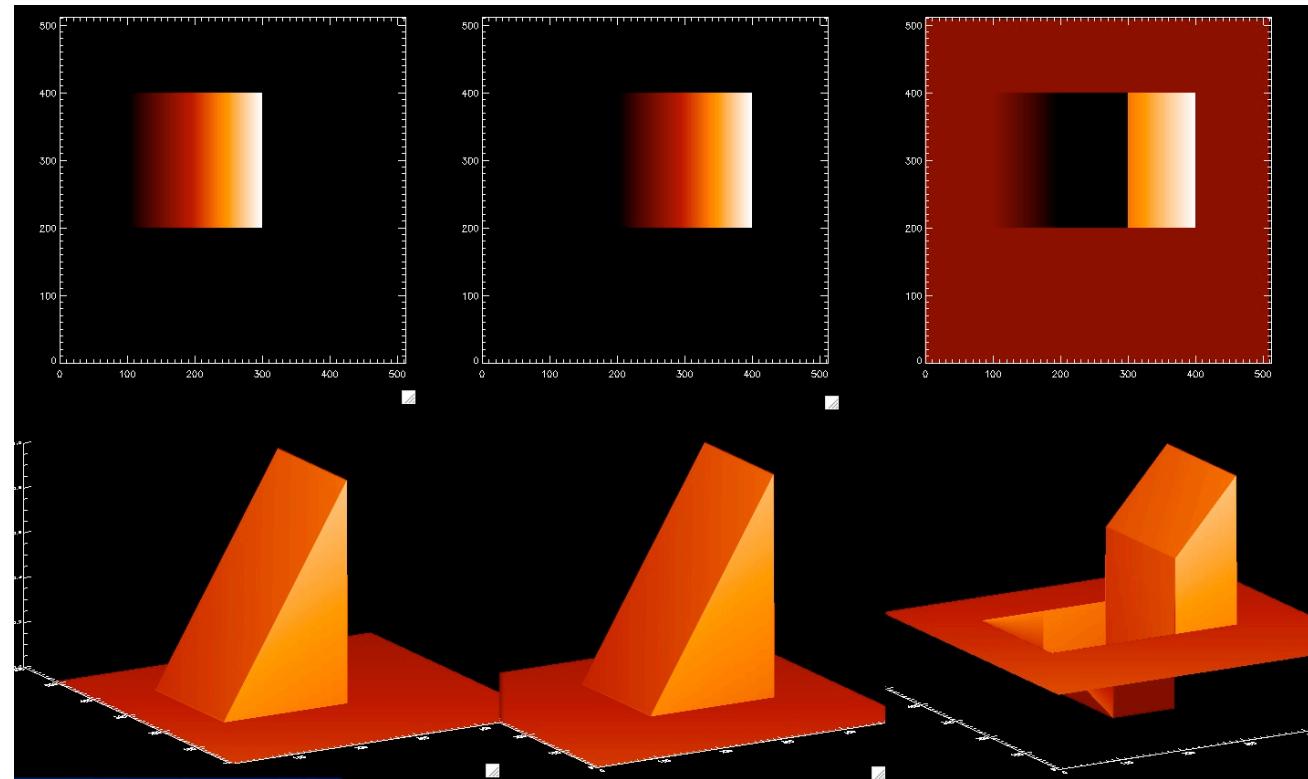


Image Processing

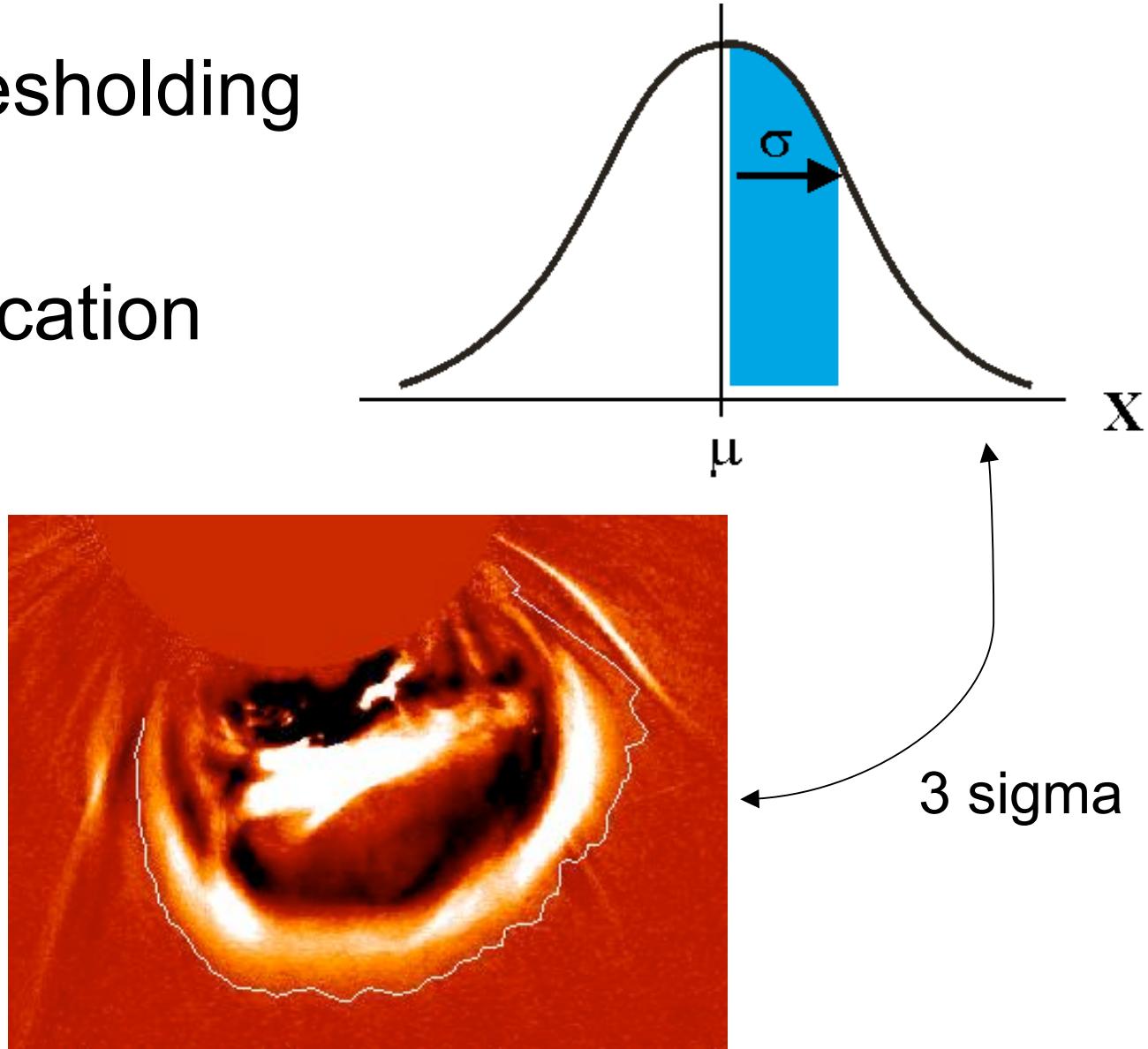
Running Difference



$$\text{Diff}(*, *, j) = \text{Data}(*, *, j+1) - \text{Data}(*, *, j)$$

Running Difference

- Intensity thresholding
- Front identification
- Contouring



CME Front Characterisation

- Ellipse fit
- Height, Width, Curvature, Orientation

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

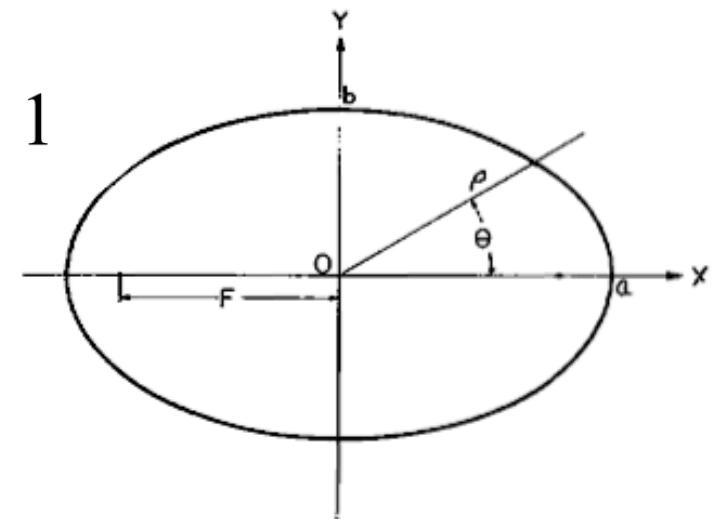


Fig. 3—Ellipse in rectangular coordinates.

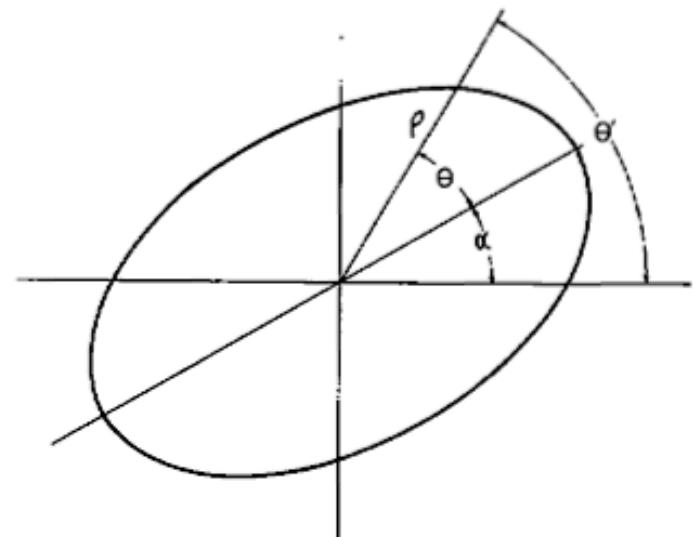
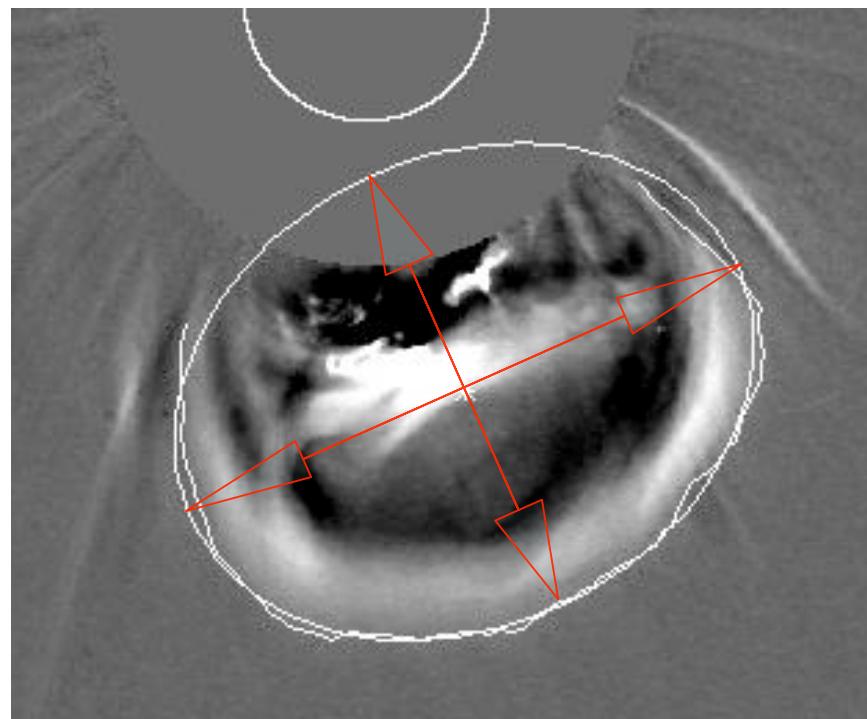
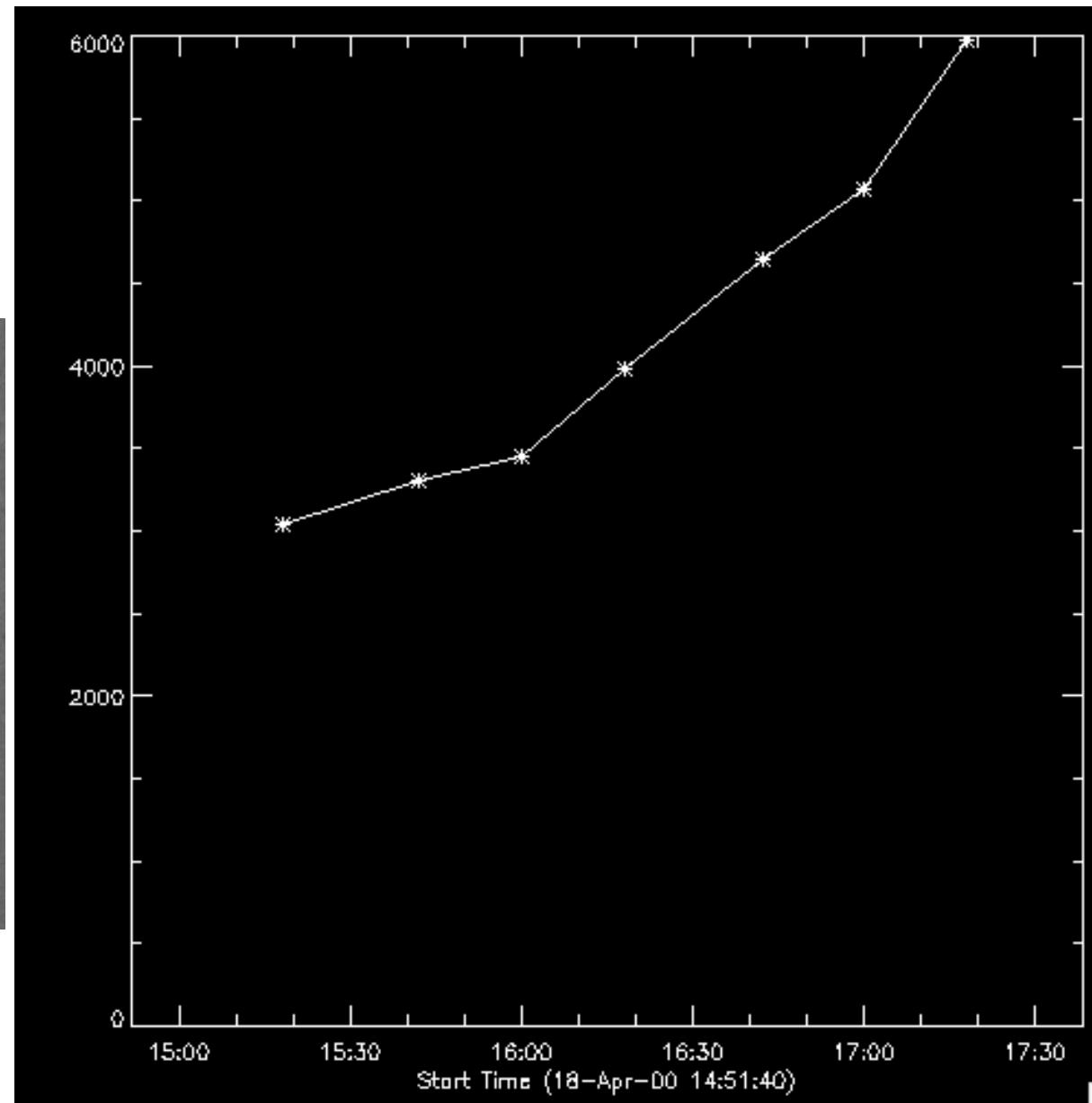
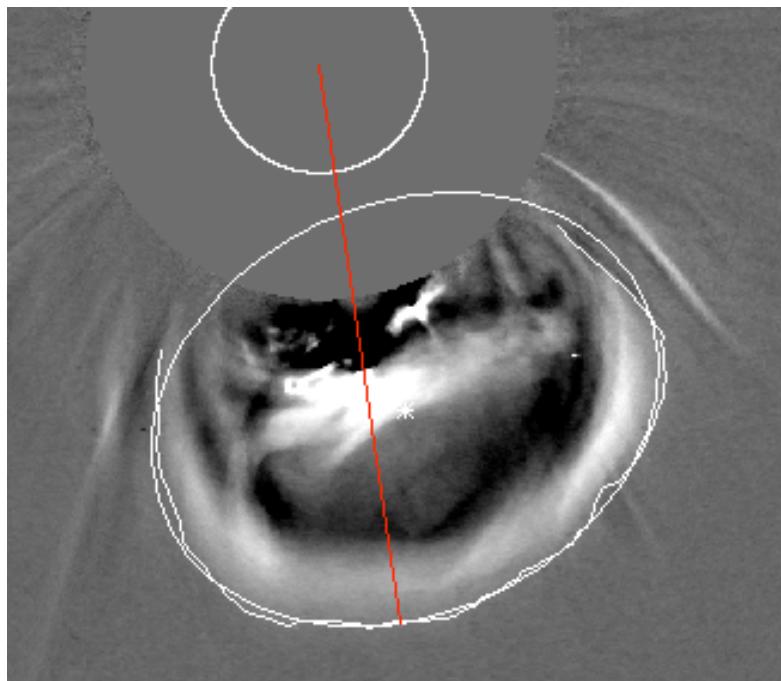


Fig. 4—Inclined ellipse.

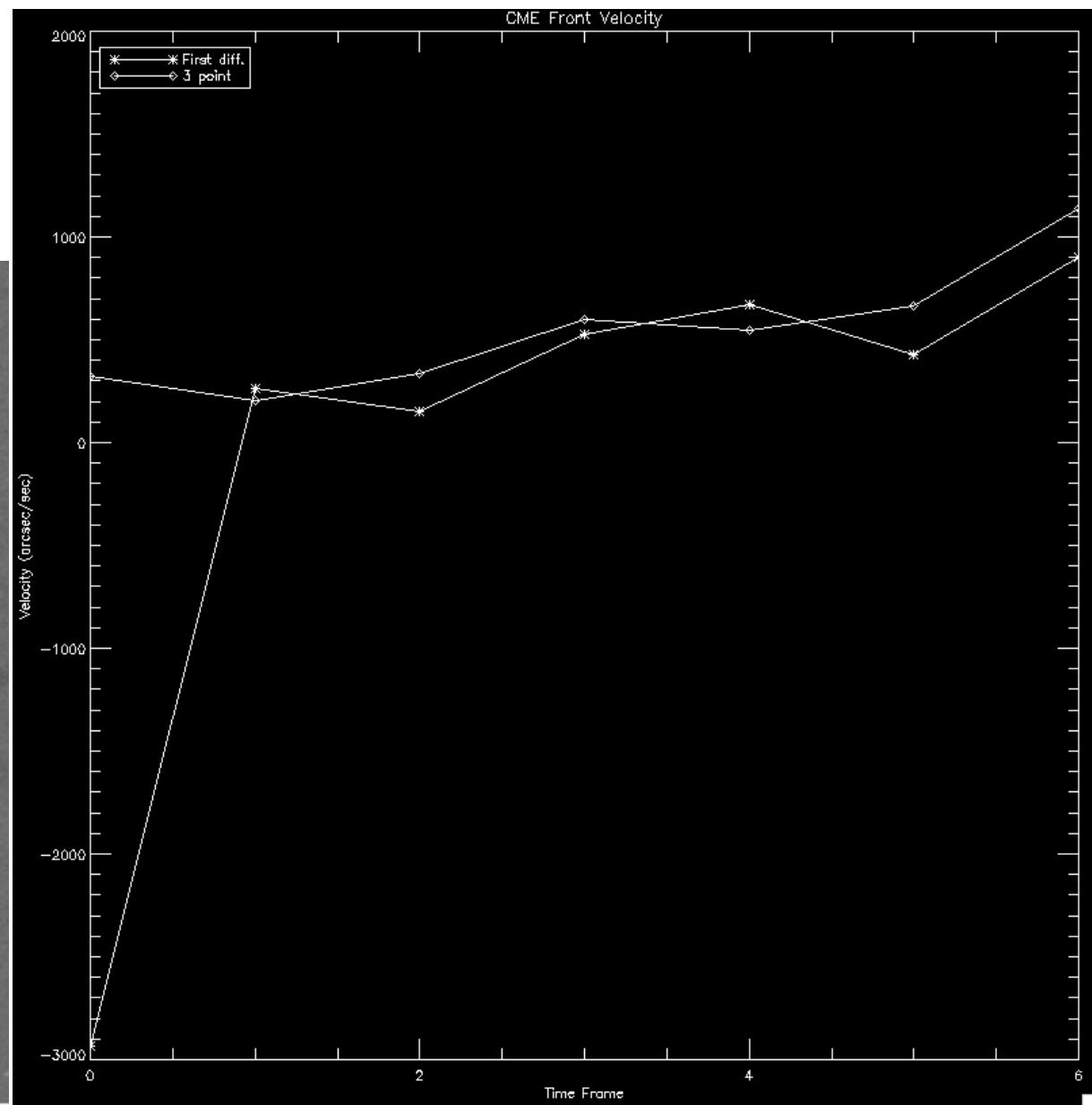
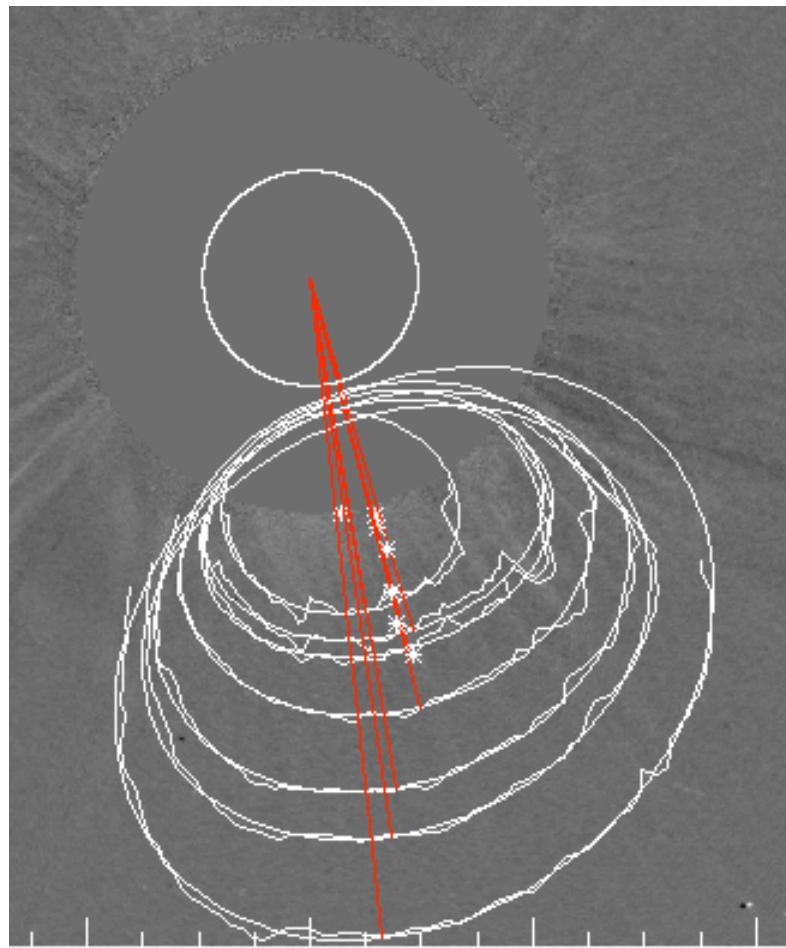
CME Kinematics

- Height-time profile



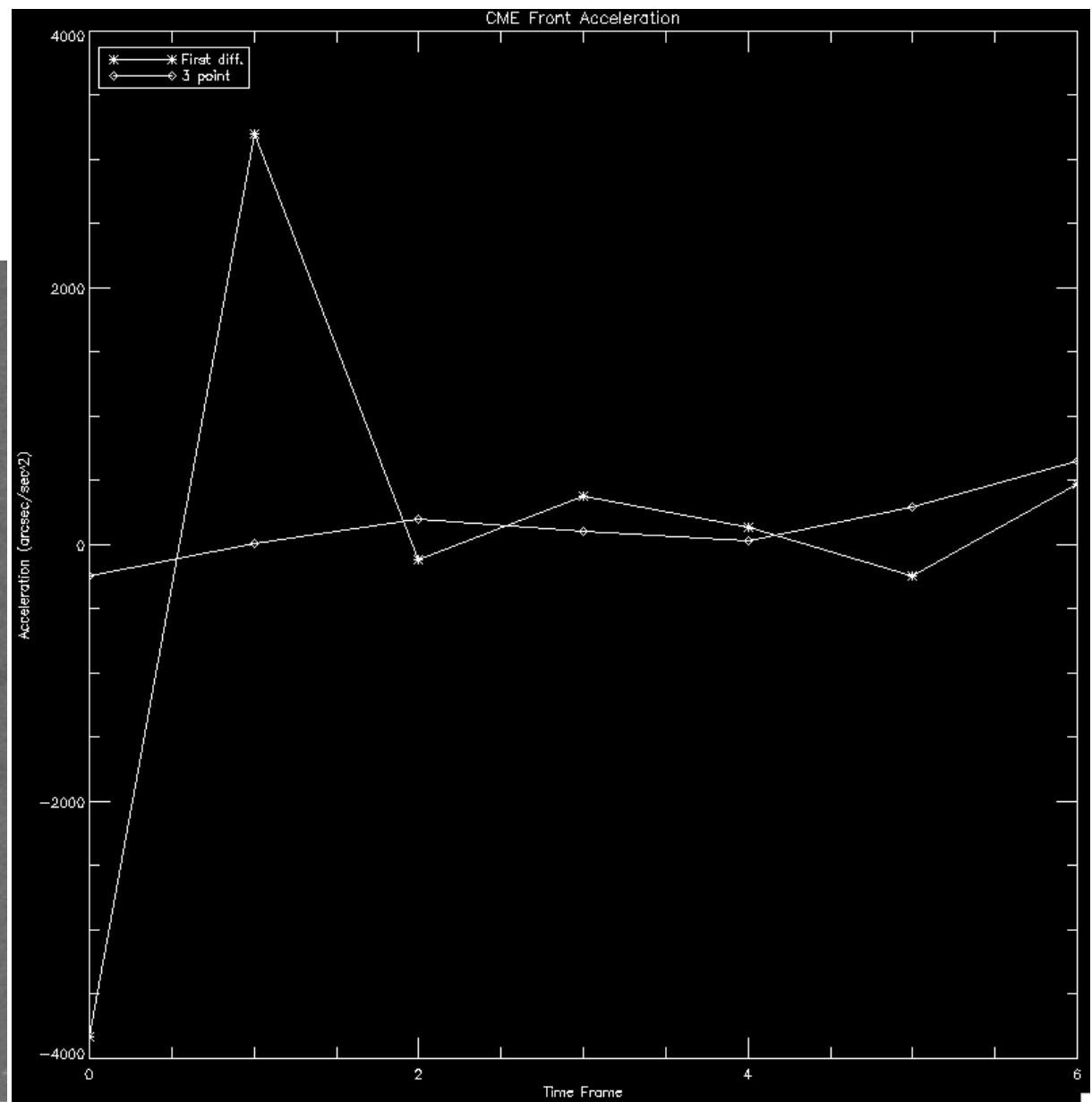
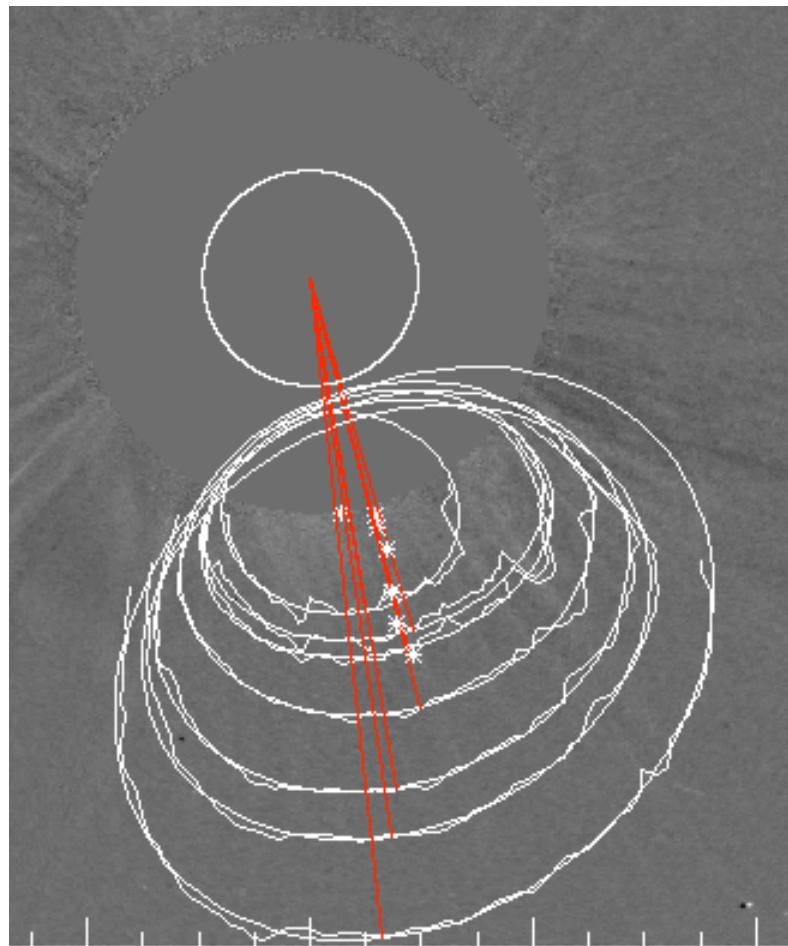
CME Kinematics

- Velocity profile



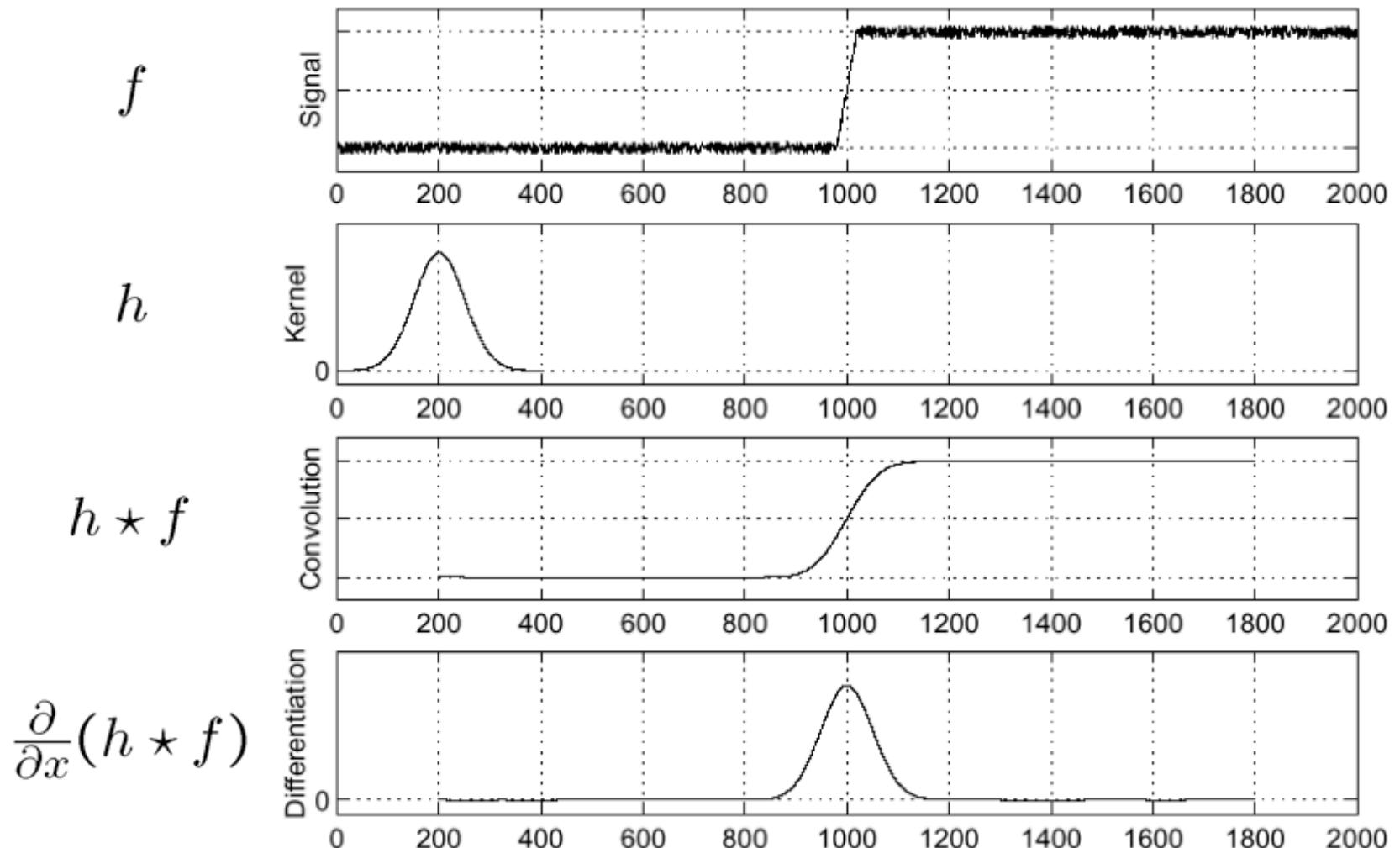
CME Kinematics

- Acceleration profile



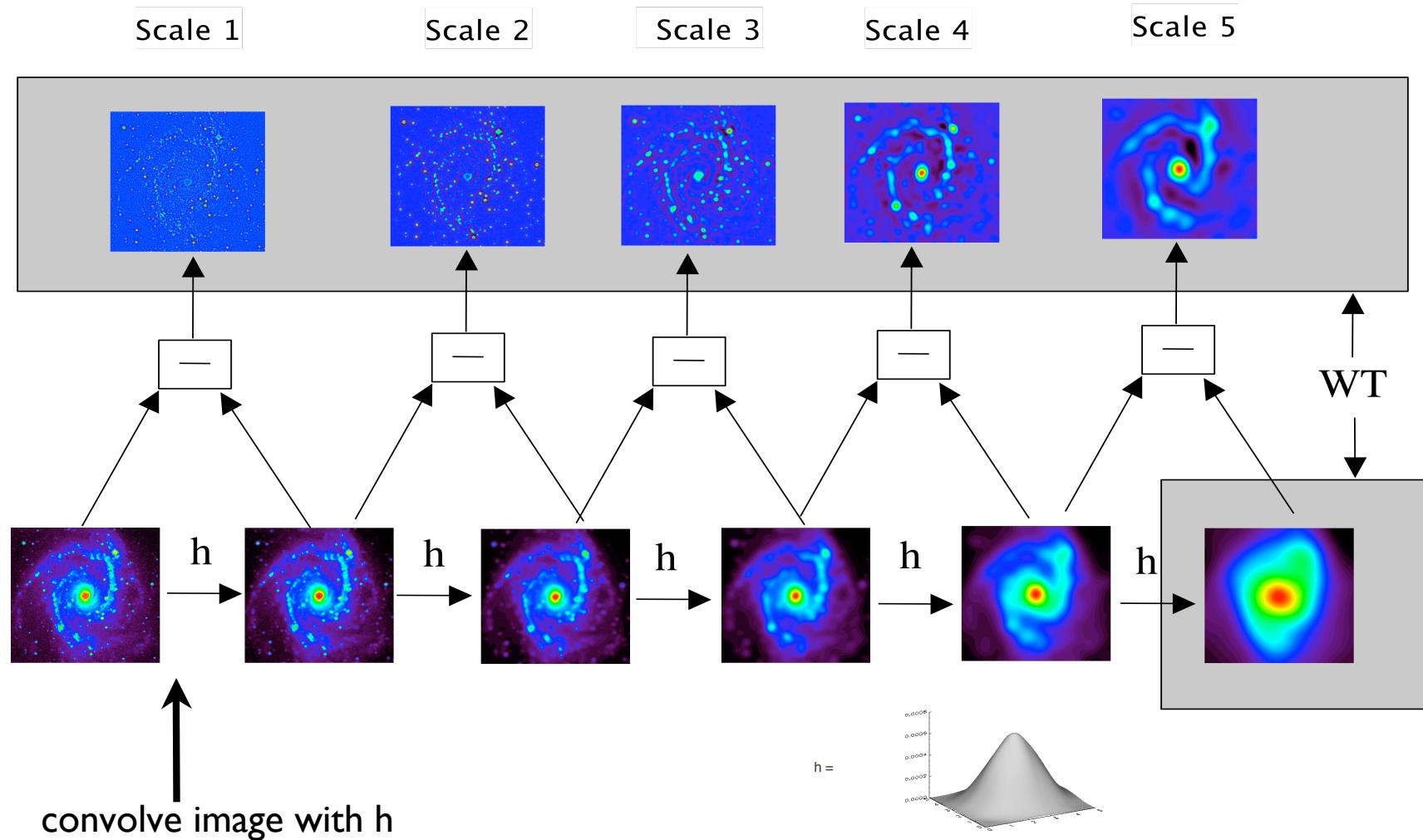
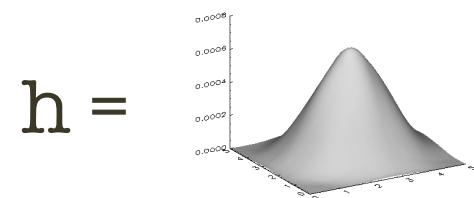
Multiscale Analysis

- Edge Detection:

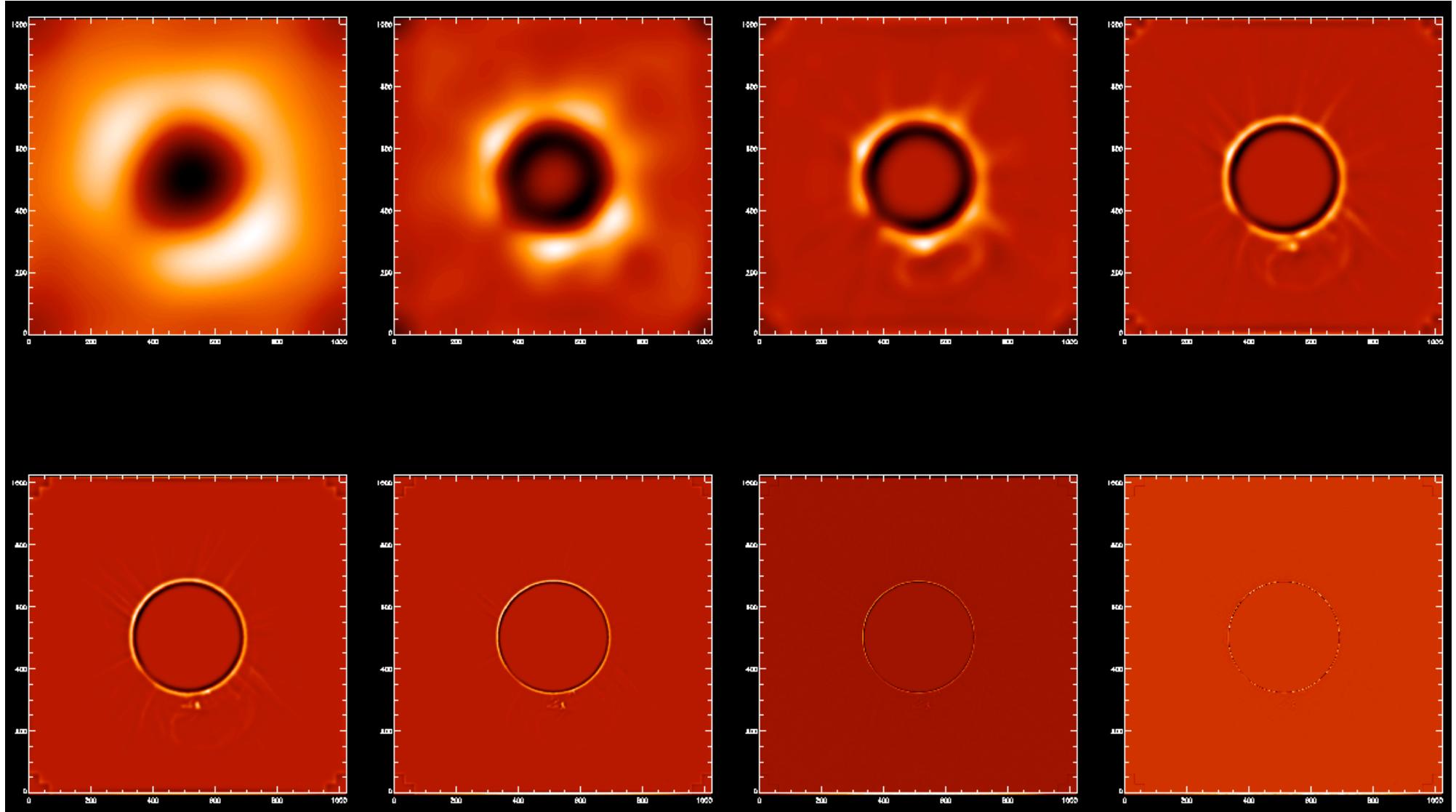


Multiscale Analysis

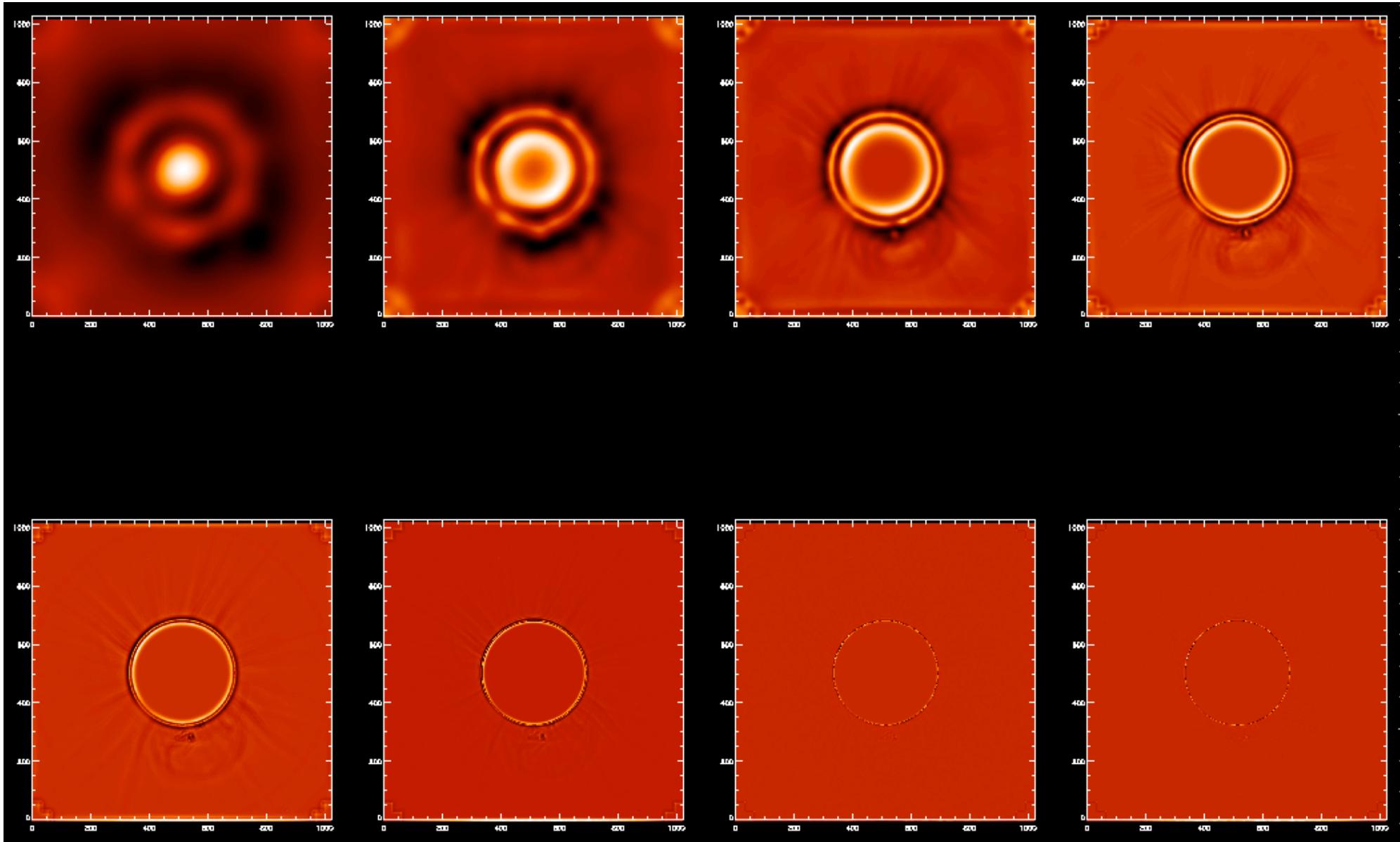
- ‘a trous’ wavelet



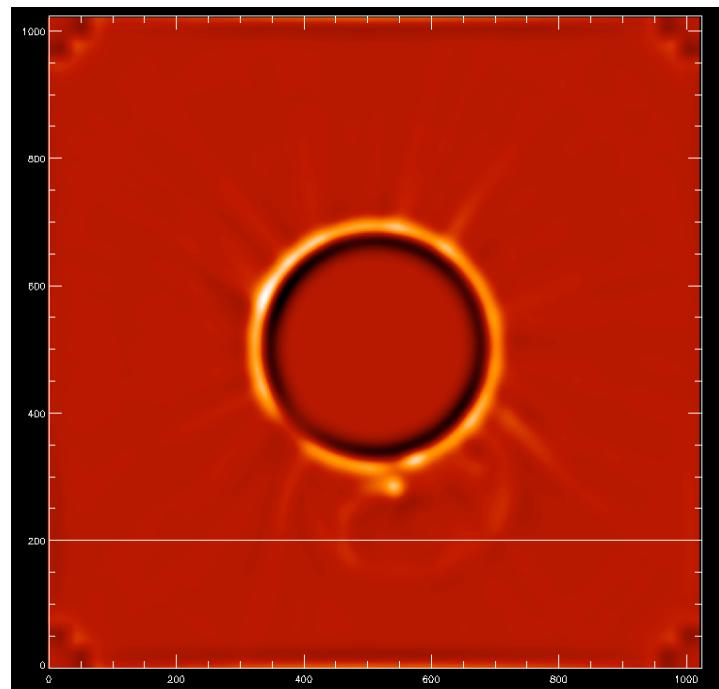
Multiscales of CME



'a trous' wavelets



Scale 5



Scale 5-4

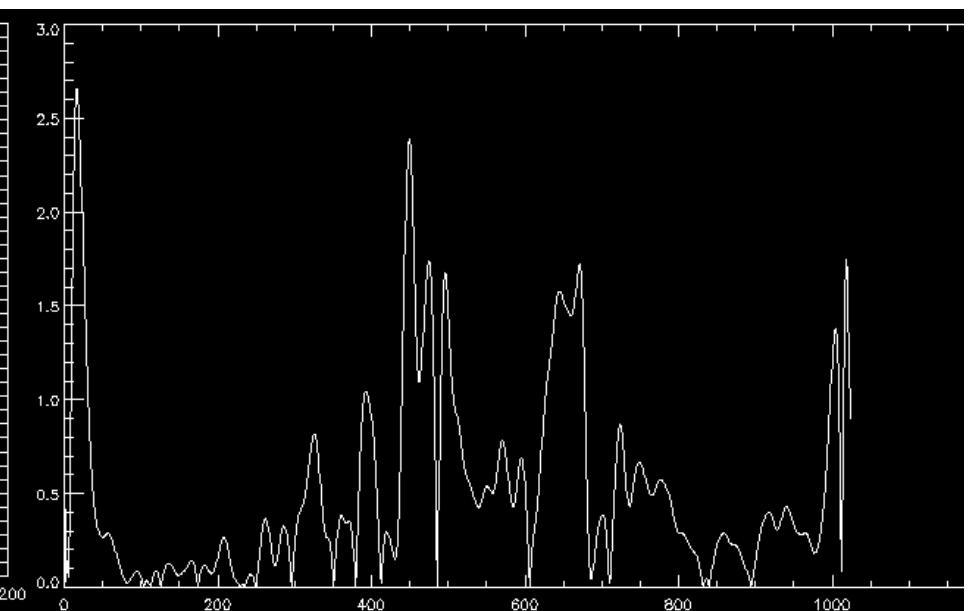
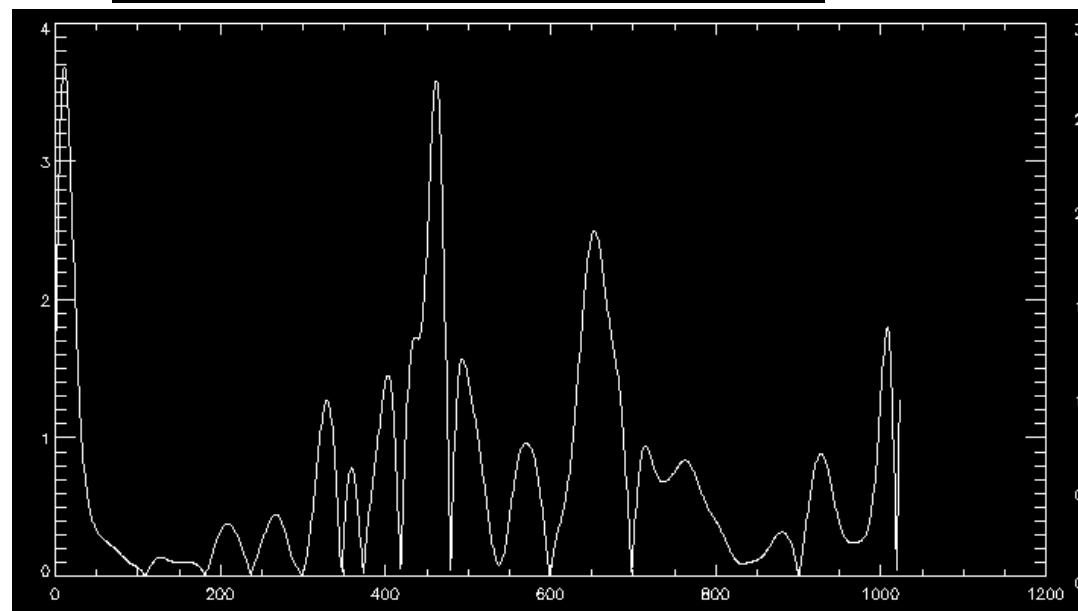
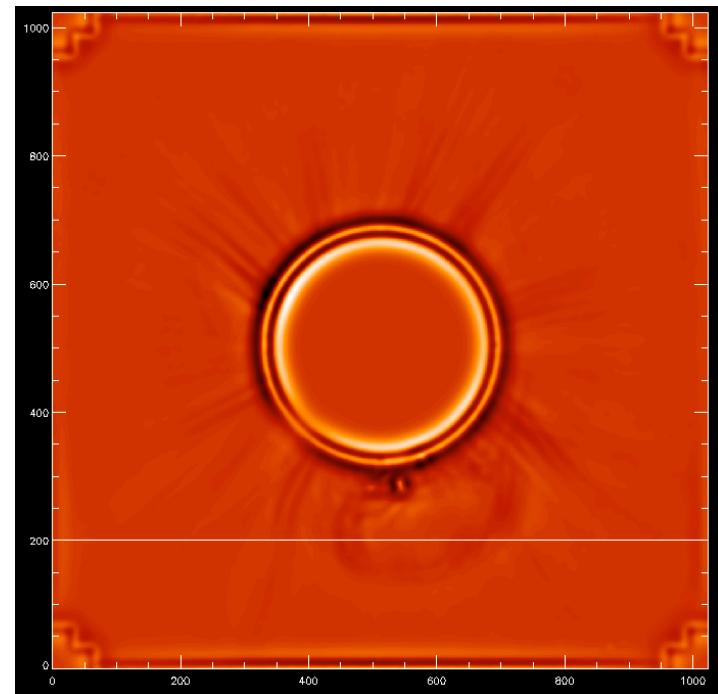
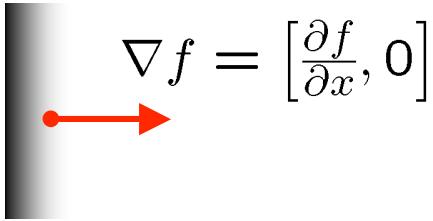
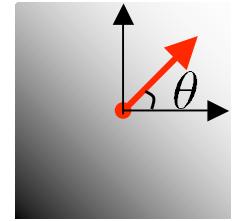


Image gradient

- The gradient of an image: $\nabla f = \left[\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right]$
- The gradient points in the direction of most rapid change in intensity


$$\nabla f = \left[\frac{\partial f}{\partial x}, 0 \right]$$


$$\nabla f = \left[0, \frac{\partial f}{\partial y} \right]$$


$$\nabla f = \left[\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right]$$

- The gradient direction is given by:
$$\theta = \tan^{-1} \left(\frac{\partial f}{\partial y} / \frac{\partial f}{\partial x} \right)$$
- The *edge strength* is given by the gradient magnitude

$$\|\nabla f\| = \sqrt{\left(\frac{\partial f}{\partial x}\right)^2 + \left(\frac{\partial f}{\partial y}\right)^2}$$

WTMM?

$$\dots \text{Max} \left| \frac{d}{dx} (f * \theta_s)(x) \right|$$

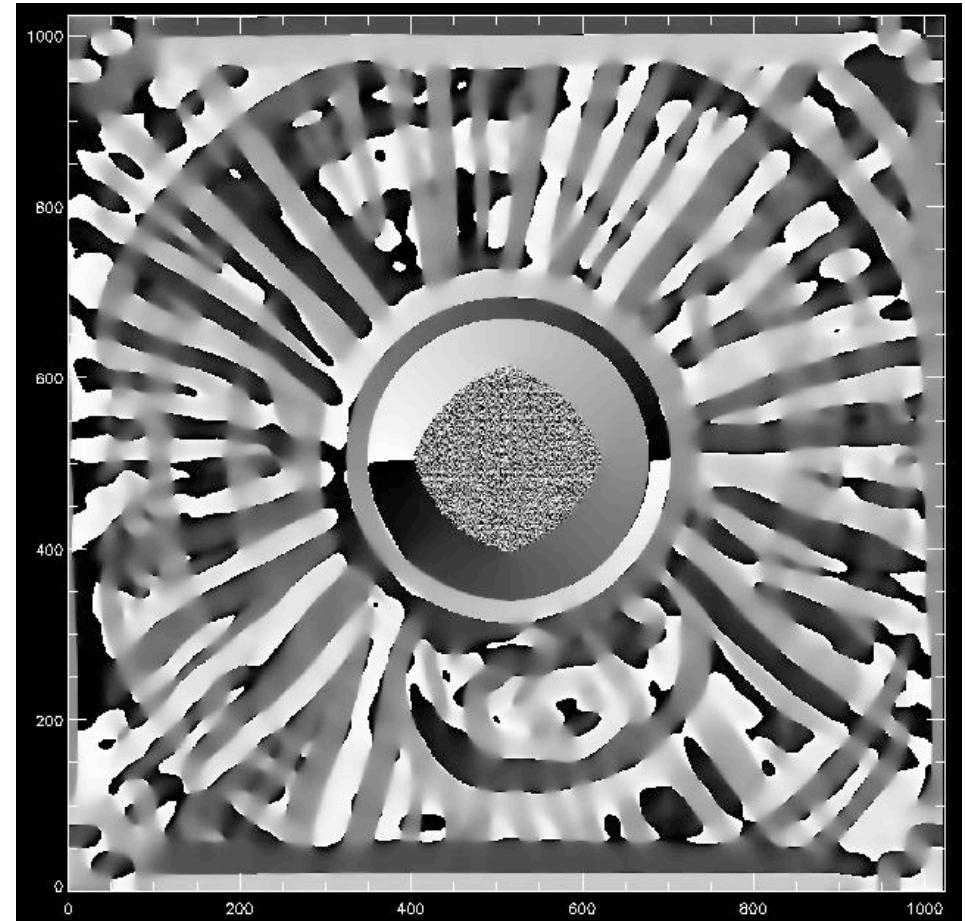
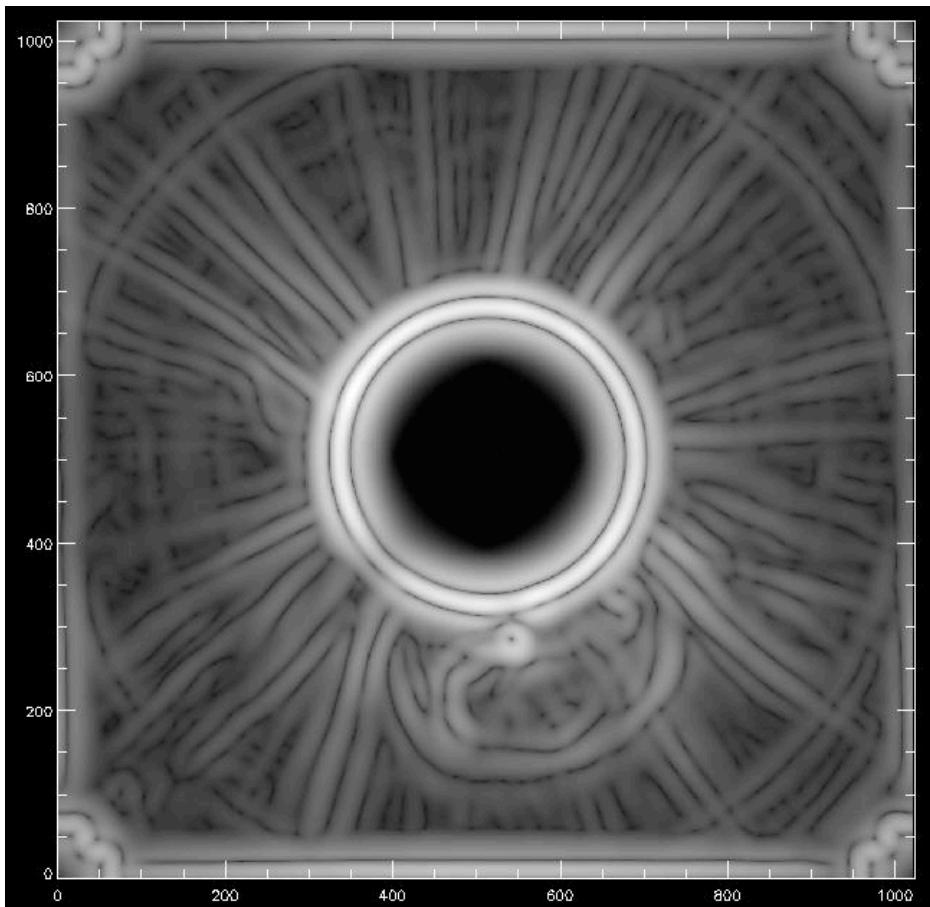
- Canny:
$$\begin{pmatrix} W_s^1 f(x, y) \\ W_s^2 f(x, y) \end{pmatrix} = s \begin{pmatrix} \frac{\partial}{\partial x} (f * \theta_s)(x, y) \\ \frac{\partial}{\partial y} (f * \theta_s)(x, y) \end{pmatrix} = s \nabla (f * \theta_s)(x, y).$$

=> WTMM twice smoothed!

- a trous:
$$W_s^a f(x) = (f * \psi_s^a)(x) = s \frac{d}{dx} (f * \theta_s)(x)$$

=> WTMM twice differentiated!

‘a trous’ image gradient

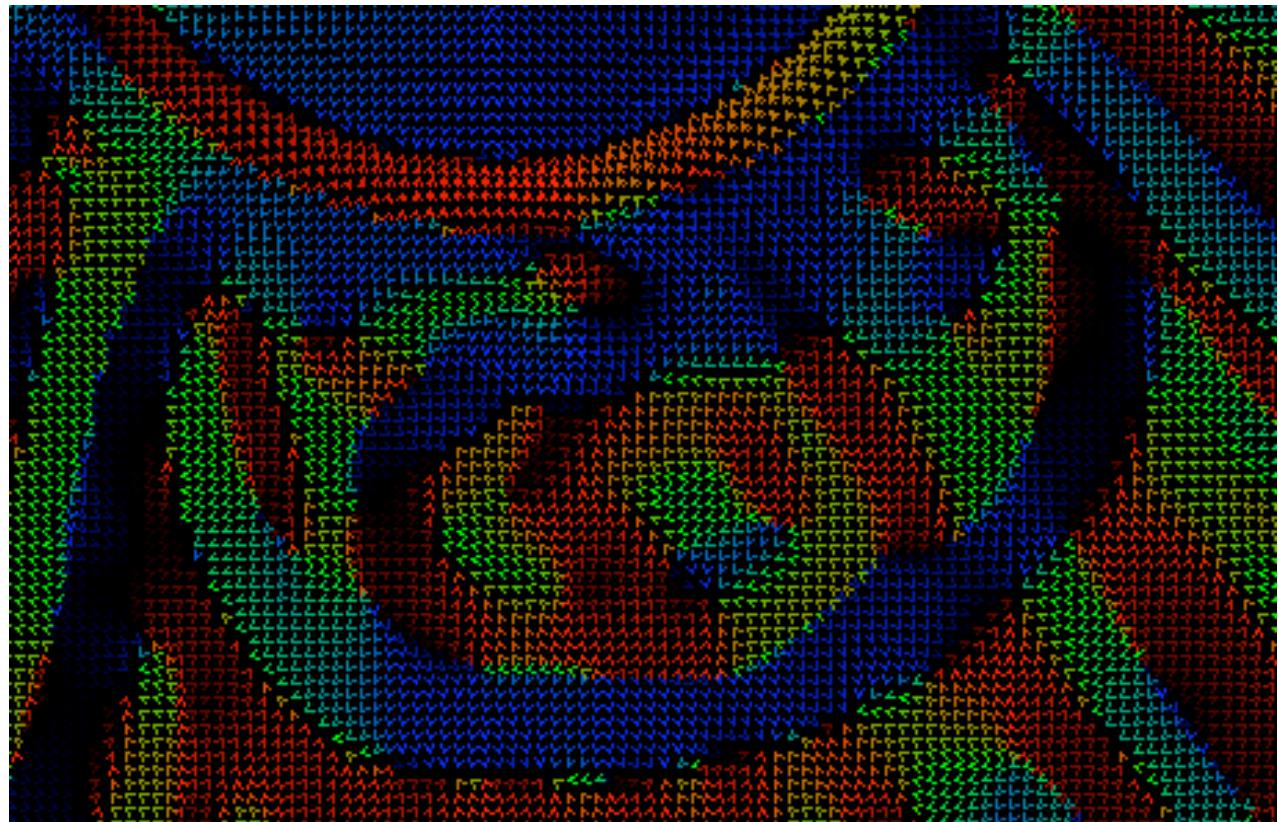


$$\|\nabla f\| = \sqrt{\left(\frac{\partial f}{\partial x}\right)^2 + \left(\frac{\partial f}{\partial y}\right)^2}$$

$$\theta = \tan^{-1} \left(\frac{\partial f}{\partial y} / \frac{\partial f}{\partial x} \right)$$

Next Steps...

- Front only
 - further wavelet analysis
- More data + C3
- STEREO



STEREO: Early / Initial Analysis

