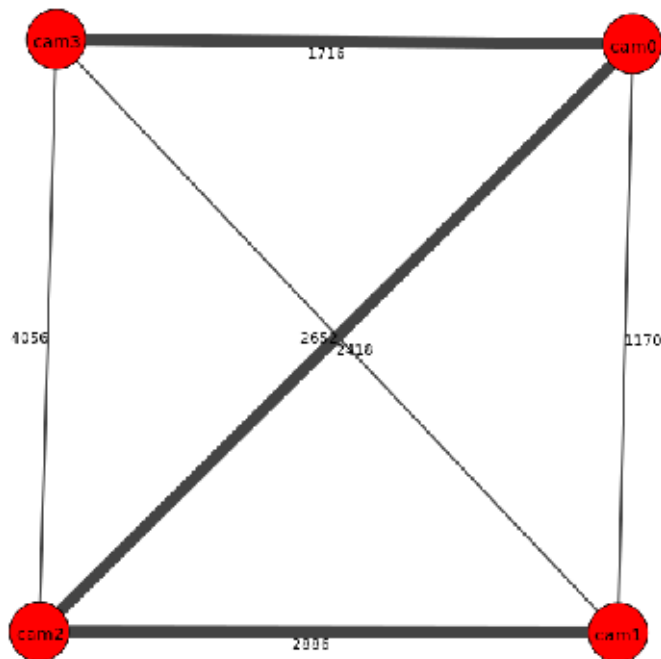
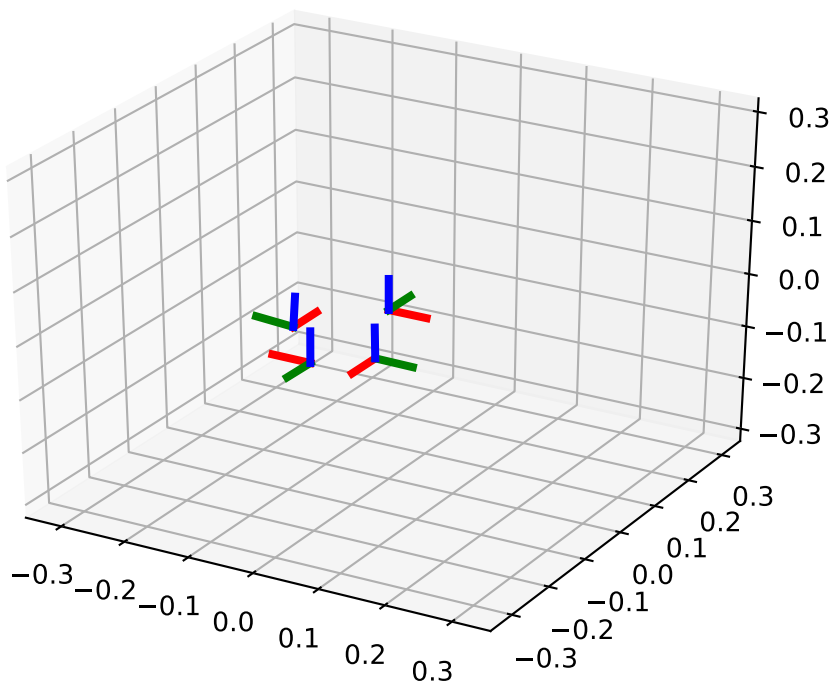


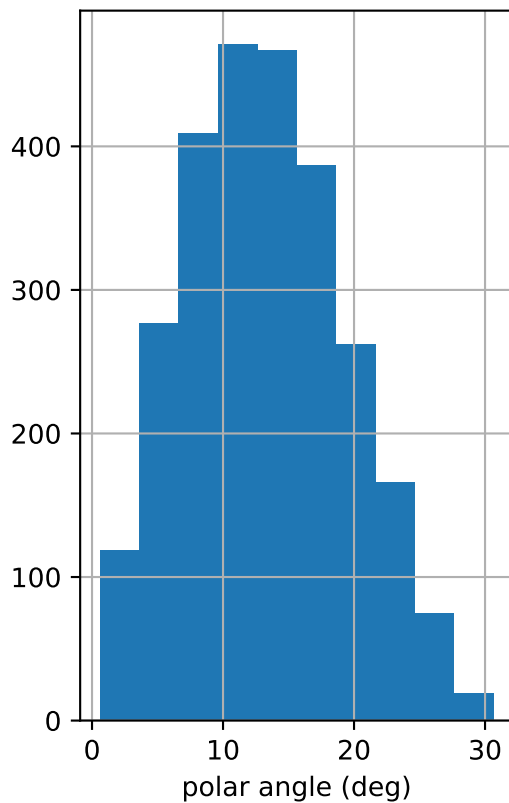
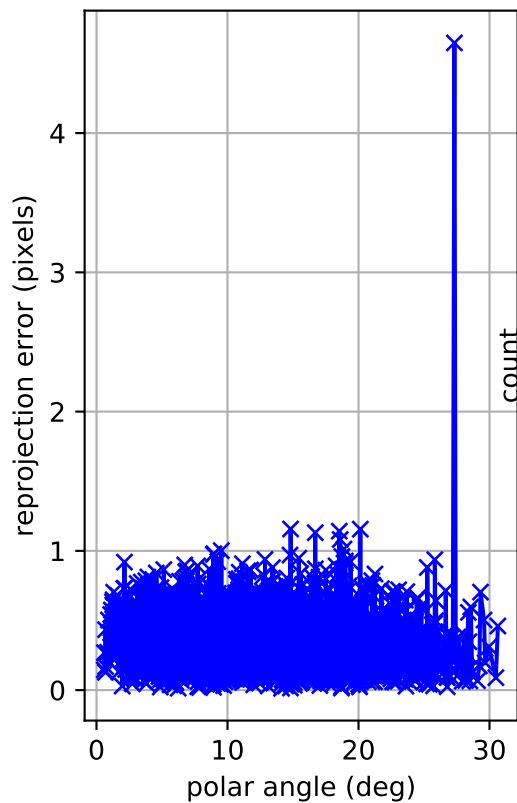
Inter-camera observations graph (edge weight=#mutual obs.)



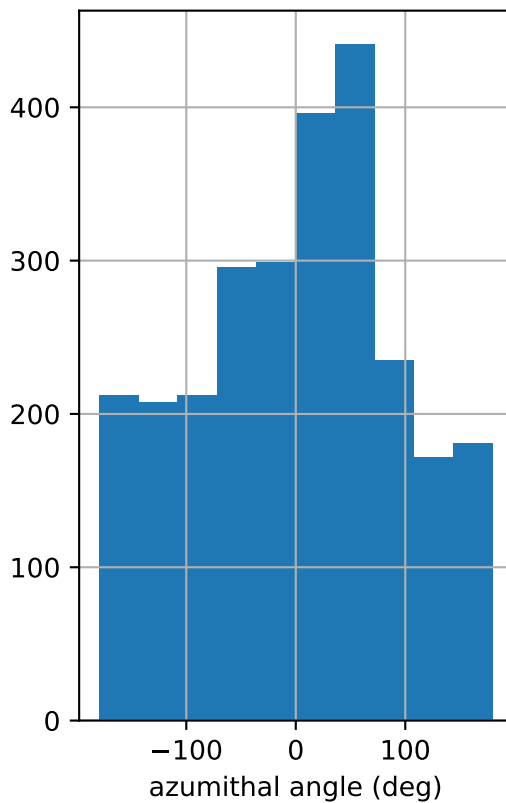
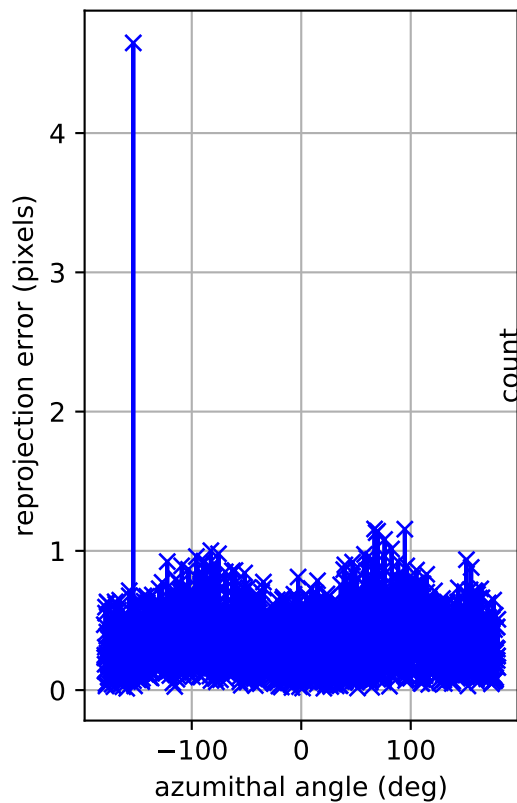
camera system



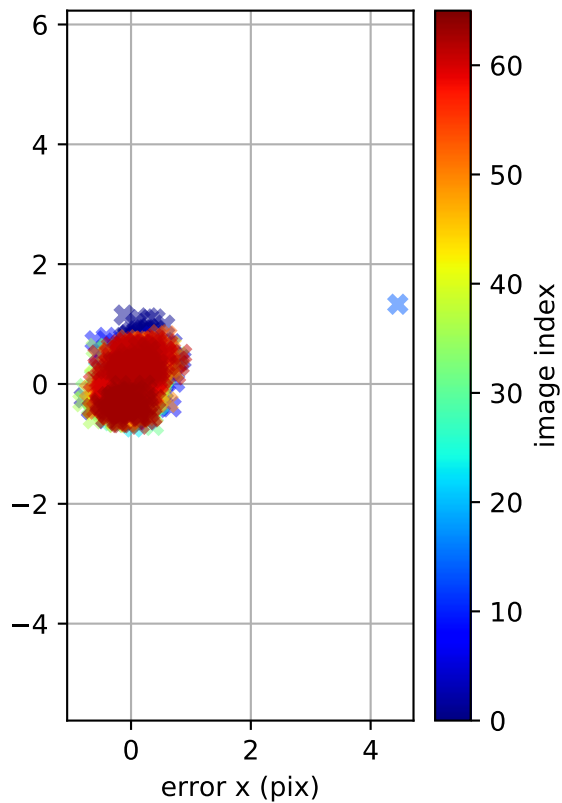
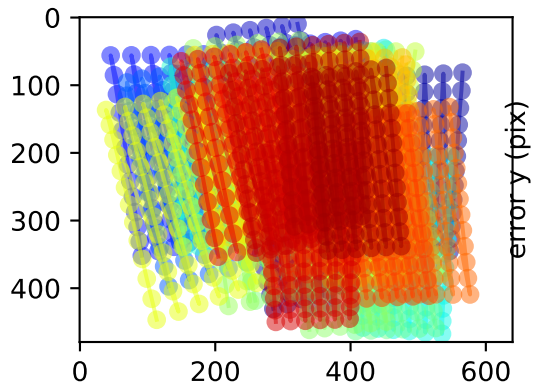
cam0: polar error



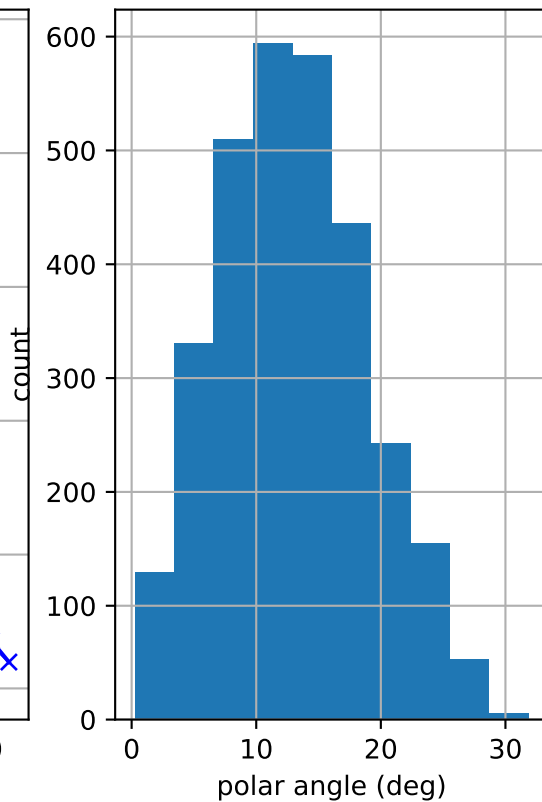
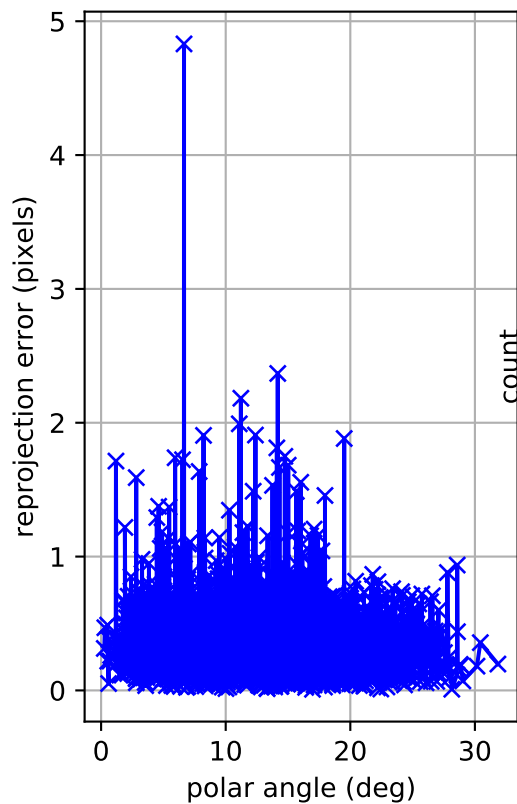
cam0: azimuthal error



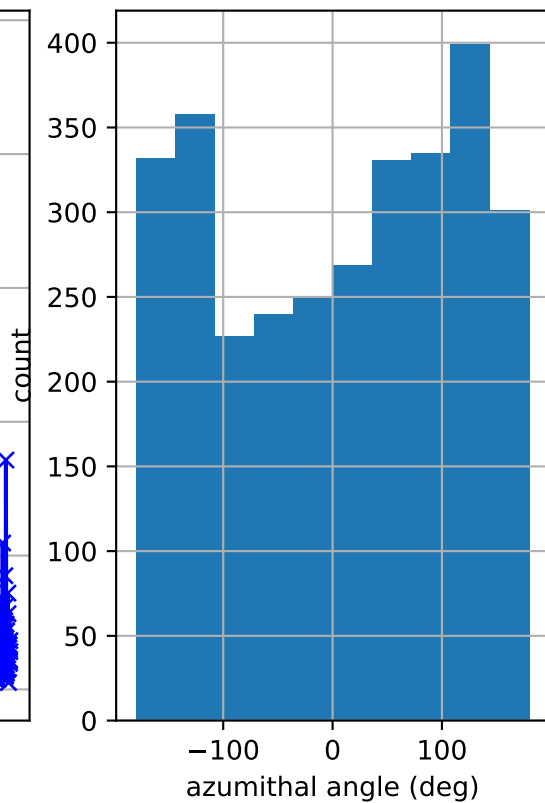
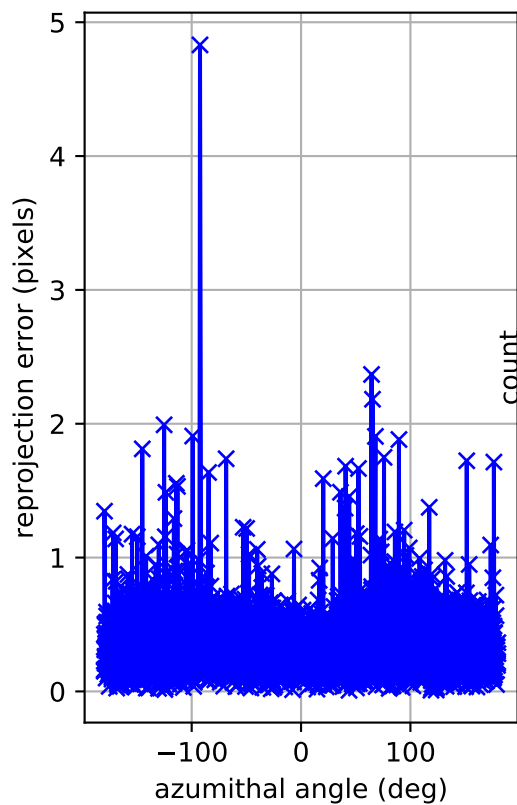
cam0: reprojection errors



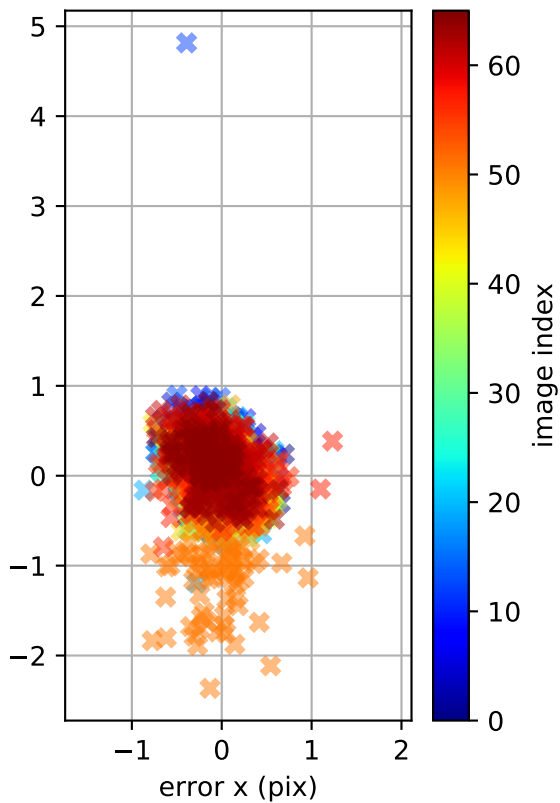
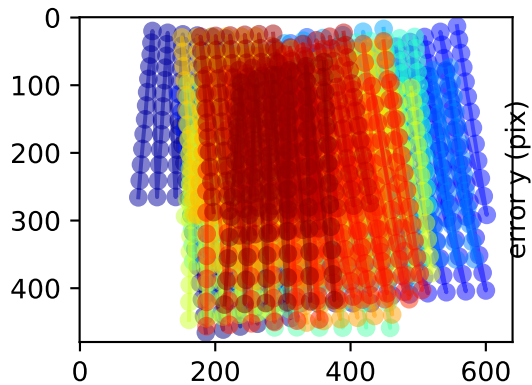
cam1: polar error



cam1: azimuthal error

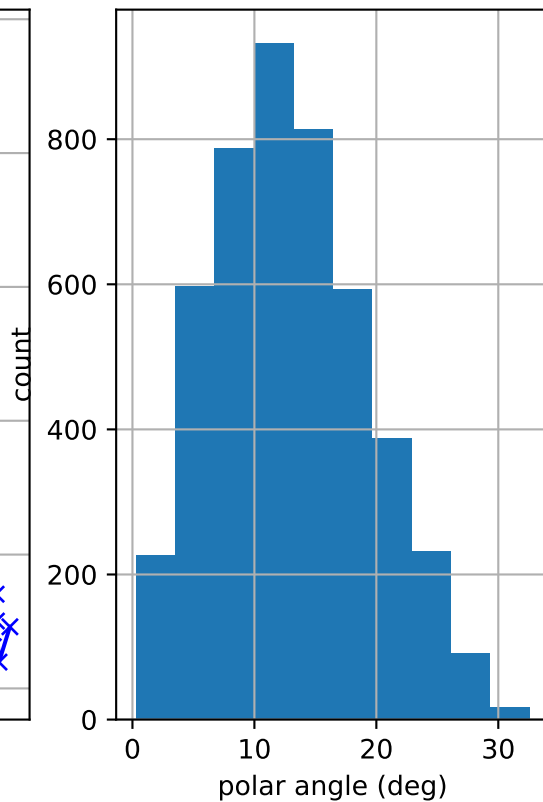
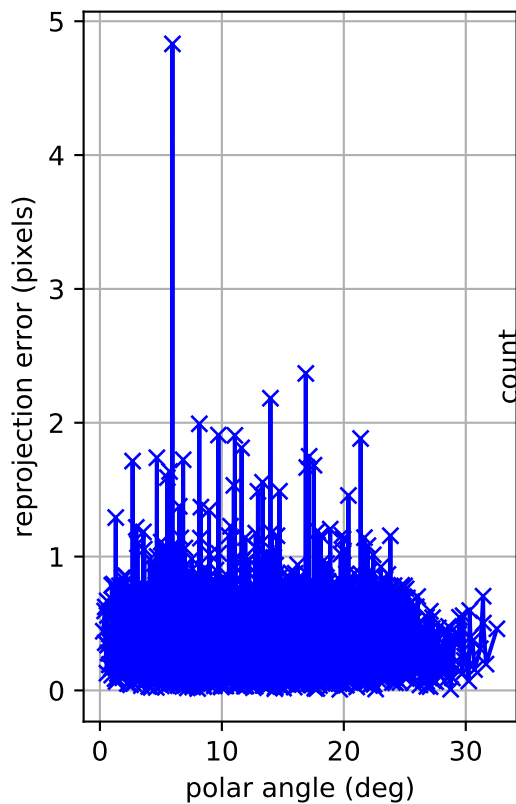


cam1: reprojection errors

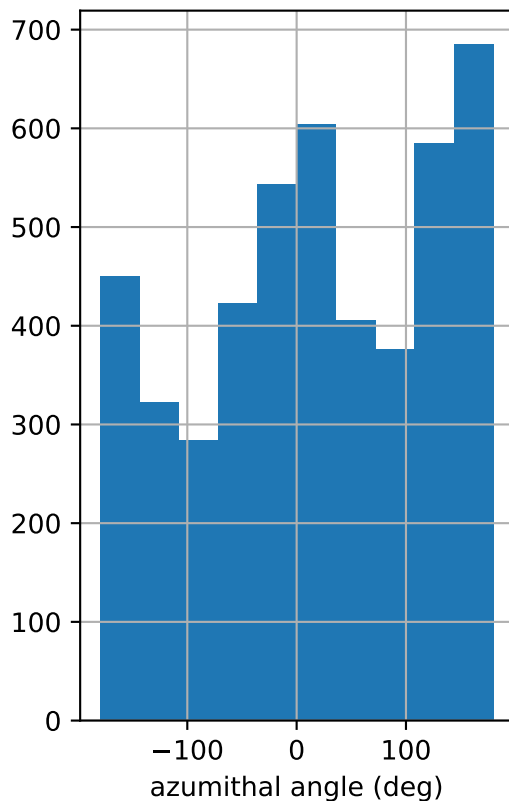
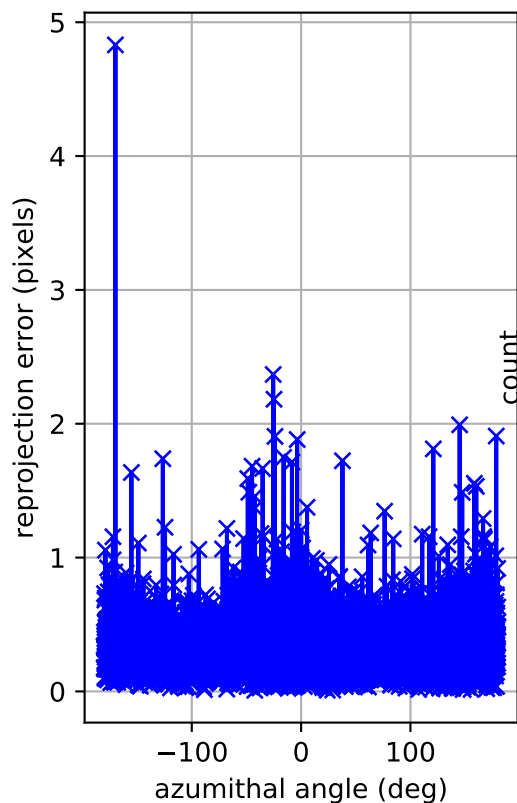




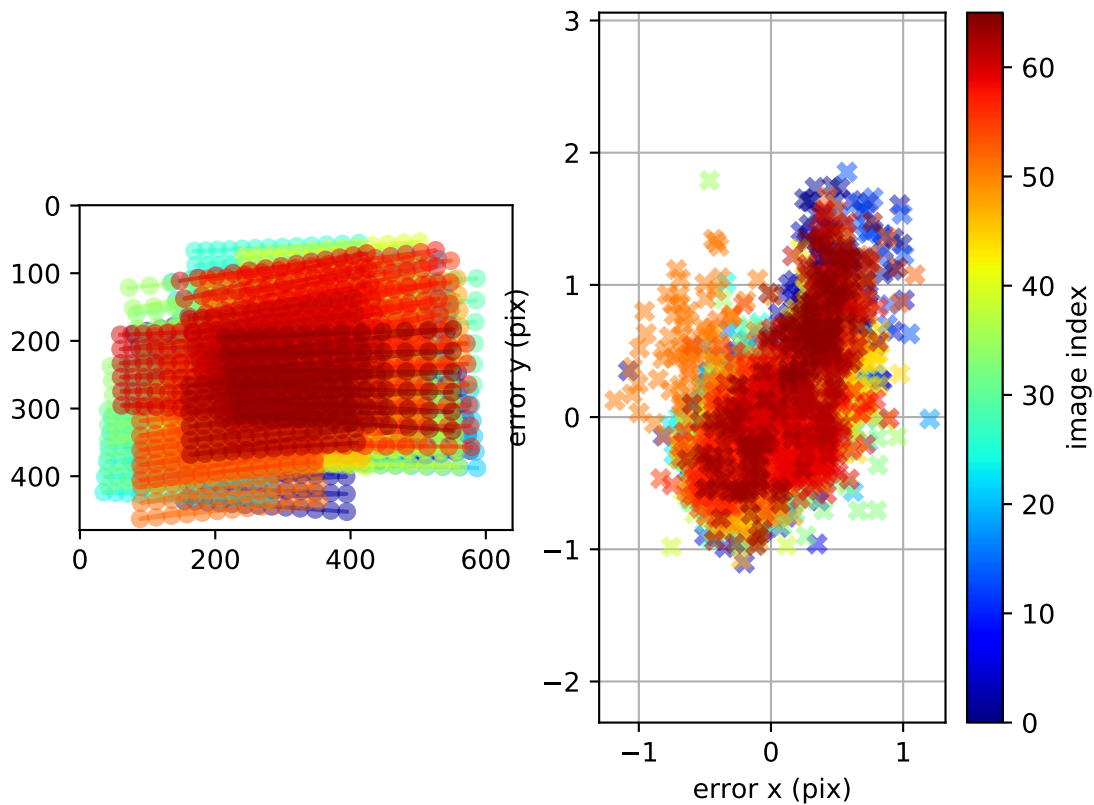
cam2: polar error



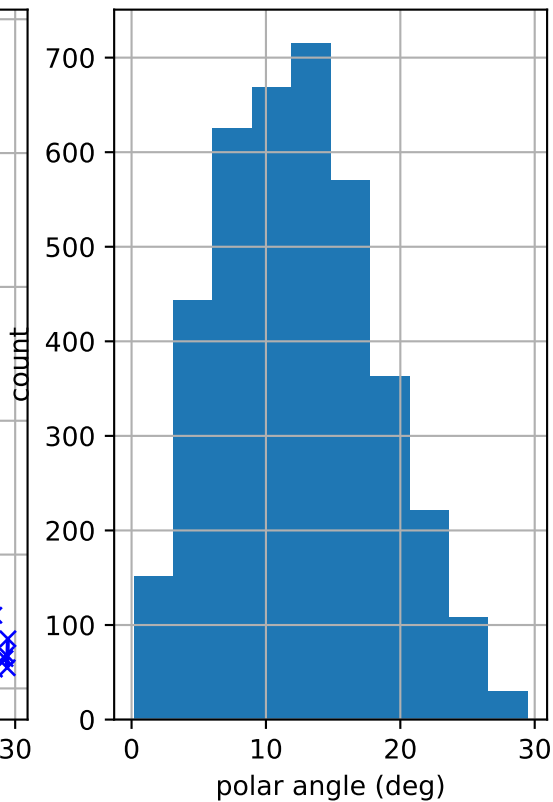
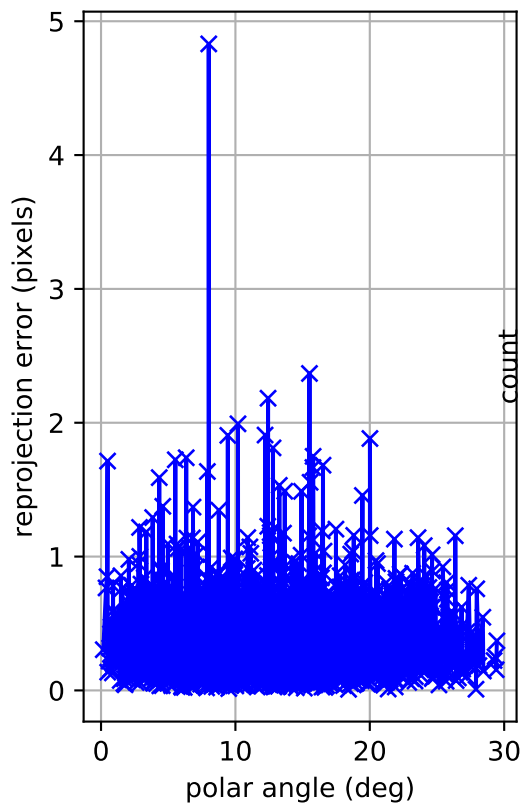
cam2: azimuthal error



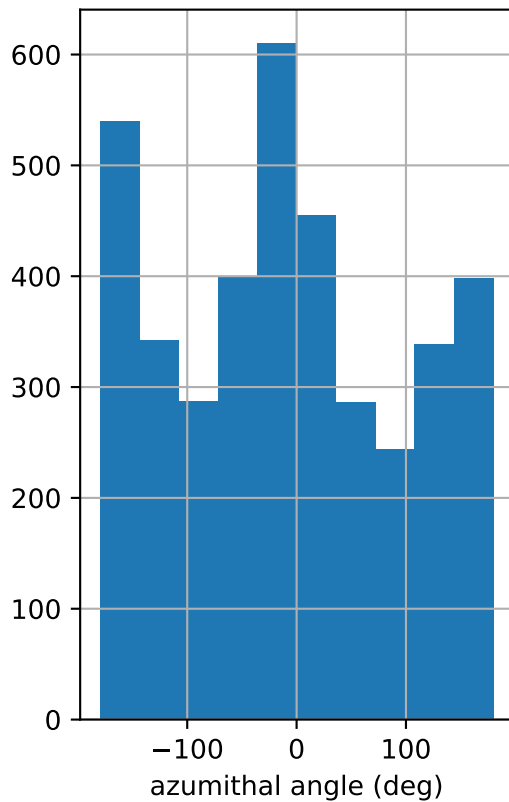
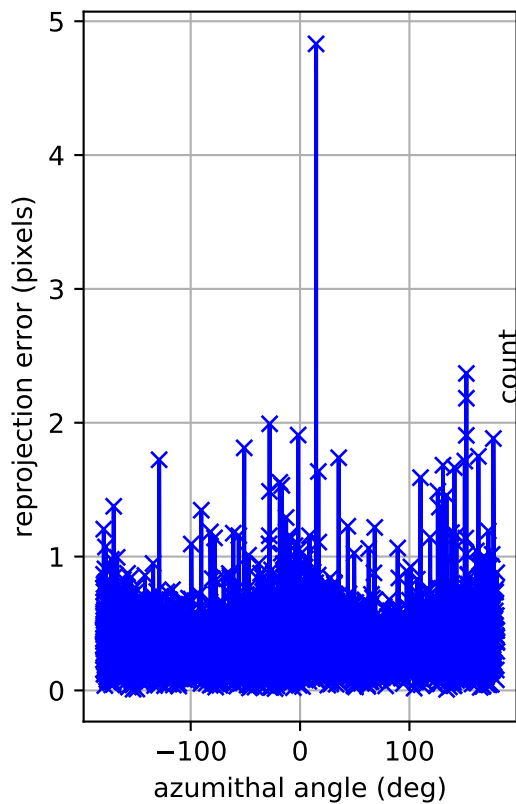
cam2: reprojection errors



cam3: polar error



cam3: azimuthal error



cam3: reprojection errors

