

CENG 384 - Signals and Systems for Computer Engineers  
Spring 2023  
Homework 4

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1. (a)

$$H(jw) = \frac{jw - 1}{jw + 1}$$

$$H(jw) = \frac{Y(jw)}{X(jw)} = \frac{jw - 1}{jw + 1}$$

$$\Rightarrow jwY(jw) + Y(jw) = jwX(jw) - X(jw)$$

$$\Rightarrow \frac{dy(t)}{dt} + y(t) = \frac{dx(t)}{dt} - x(t)$$

(b)

$$h(t) \xleftrightarrow{FT} H(jw)$$

$$\begin{aligned} \frac{jw - 1}{jw + 1} &= \frac{jw}{1 + jw} - \frac{1}{1 + jw} \xleftrightarrow{FT} \frac{d(e^{-t}u(t))}{dt} - e^{-t}u(t) \\ &= 2e^{-t}u(t) \end{aligned}$$

where  $t > 0$

(c)

$$y = y_h + y_p$$

$$y_h = Ae^{st} \Rightarrow Ase^{st} + Ae^{st} = 0 \Rightarrow Ae^{st}(s + 1) = 0 \Rightarrow s = -1$$

$$\Rightarrow y_h(t) = Ae^{-t}$$

$$y_p = Kx(t) = Ke^{-2t}u(t) \Rightarrow -2Ke^{-2t} + Ke^{-2t} = -2e^{-2t} + e^{-2t}$$

$$\Rightarrow -Ke^{-2t} = -e^{-2t} \Rightarrow K = 1$$

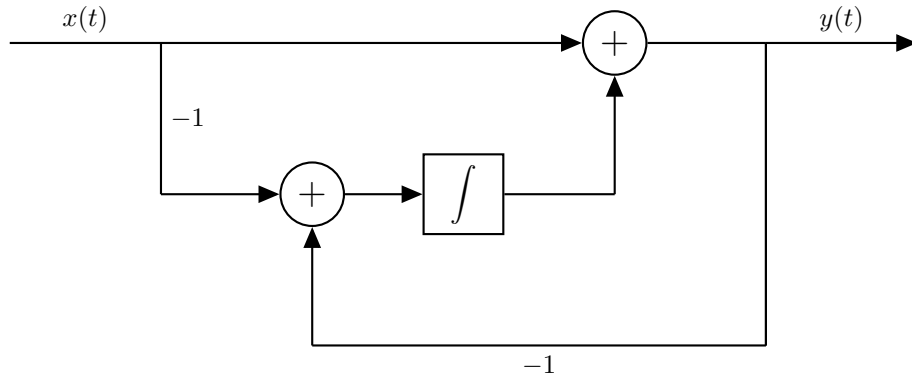
$$\Rightarrow y_p(t) = x(t)$$

$$y(t) = Ae^{-t} + e^{-2t}$$

$$y(0) = 0 \Rightarrow A + 1 = 0 \Rightarrow A = -1$$

$$\Rightarrow y(t) = (e^{-2t} - e^{-t})u(t)$$

(d)



2. (a)

$$\begin{aligned}
y[n] &\stackrel{FT}{\longleftrightarrow} Y(e^{jw}) \Rightarrow y[n+1] = e^{jw} Y(e^{jw}) \\
x[n] &\stackrel{FT}{\longleftrightarrow} X(e^{jw}) \Rightarrow x[n+1] = e^{jw} X(e^{jw}) \\
&\Rightarrow e^{jw} Y(e^{jw}) - \frac{1}{2} Y(e^{jw}) = e^{jw} X(e^{jw}) \\
&\Rightarrow Y(e^{jw}) \left( e^{jw} - \frac{1}{2} \right) = e^{jw} X(e^{jw}) \\
H(e^{jw}) &= \frac{Y(e^{jw})}{X(e^{jw})} = \frac{2e^{jw}}{2e^{jw} - 1} = \frac{1}{1 - \frac{1}{2}e^{-jw}}
\end{aligned}$$

Divided all terms with  $2e^{jw}$ .

(b) From the table 5.2, we see that the inverse transform of  $H(e^{jw})$  gives us:

$$h[n] = \left(\frac{1}{2}\right)^n u[n]$$

(c)

$$\begin{aligned}
y[n] &= x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k] = \sum_{k=-\infty}^{\infty} \left(\frac{3}{4}\right)^k u[k] \left(\frac{1}{2}\right)^{n-k} u[n-k] \\
&= \sum_{k=0}^n \left(\frac{3}{2}\right)^k \left(\frac{1}{2}\right)^k \left(\frac{1}{2}\right)^{n-2k} \\
&= \sum_{k=0}^n \left(\frac{3}{2}\right)^k \left(\frac{1}{2}\right)^n = \left(\frac{1}{2}\right)^n \sum_{k=0}^n \left(\frac{3}{4}\right)^k \\
&= \left(\frac{1}{2}\right)^n \frac{1 - \left(\frac{3}{4}\right)^{n+1}}{1 - \frac{3}{4}} \\
&= \left(\frac{1}{2}\right)^n \left(4 - \frac{3^{n+1}}{4^n}\right)
\end{aligned}$$

3. (a) Let  $G(jw) = X(jw)H_1(jw)$  and  $Y(jw) = G(jw)H_2(jw)$  Then,

$$\begin{aligned}
Y(jw) &= X(jw)H_1(jw)H_2(jw) = X(jw) \frac{1}{jw+1} \frac{1}{jw+2} \\
&\Rightarrow Y(jw)(jw+1)(jw+2) = X(jw) \\
&\Rightarrow (jw)^2 Y(jw) + 3jwY(jw) + 2Y(jw) = X(jw) \\
&\Rightarrow y''(t) + 3y'(t) + 2y(t) = x(t)
\end{aligned}$$

(b) From  $Y(jw) = X(jw)H_1(jw)H_2(jw)$  we see that if  $Y(jw) = H(jw)X(jw)$  Then,

$$H(jw) = H_1(jw)H_2(jw)$$

Let  $x(t) \stackrel{FT}{\longleftrightarrow} H_1(jw) = \frac{1}{jw+1}$  and  $y(t) \stackrel{FT}{\longleftrightarrow} H_2(jw) = \frac{1}{jw+2}$  Then,

$$x(t) = e^{-t} u(t)$$

$$y(t) = e^{-2t} u(t)$$

We also see that

$$(x * y)(t) \stackrel{FT}{\longleftrightarrow} H_1(jw)H_2(jw) = H(jw)$$

It is clear that if we find  $H(jw)$  we can find  $h(t)$  using Inverse Fourier Transform. To obtain  $H(jw)$  we can use the convolution of input and output signals.

$$\begin{aligned}
(x * y)(t) &= \int_{-\infty}^{\infty} x(\tau) y(t-\tau) d\tau \\
&= \int_{-\infty}^{\infty} e^{-\tau} u(\tau) e^{-2(t-\tau)} u(t-\tau) d\tau \\
&= e^{-2t} \int_0^t e^{-\tau} e^{2\tau} d\tau = e^{-2t} (e^{\tau}) \Big|_0^t \\
&\Rightarrow h(t) = (e^{-t} - e^{-2t}) u(t)
\end{aligned}$$

(c)

$$\begin{aligned}
Y(jw) &= X(jw)H(jw) = jwH(jw) \\
y(t) &\xleftrightarrow{FT} Y(jw) \\
\frac{dh(t)}{dt} &\xleftrightarrow{FT} jwH(jw) \\
\Rightarrow y(t) &= \frac{dh(t)}{dt} = (-e^{-t} + 2e^{-2t})u(t)
\end{aligned}$$

4. (a)

$$\begin{aligned}
Y(e^{jw}) &= X(e^{jw})(H_1(e^{jw}) + H_2(e^{jw})) \\
&= X(e^{jw})\left(\frac{3}{3 + e^{-jw}} + \frac{2}{2 + e^{-jw}}\right) \\
&= X(e^{jw})\left(\frac{12 + 5e^{-jw}}{6 + 5e^{-jw} + e^{-2jw}}\right) \\
\Rightarrow e^{-2jw}Y(e^{jw}) + 5e^{-jw}Y(e^{jw}) + 6Y(e^{jw}) &= 5e^{-jw}X(e^{jw}) + 12X(e^{jw}) \\
\Rightarrow y[n-2] + 5y[n-1] + 6y[n] &= 5x[n-1] + 12x[n]
\end{aligned}$$

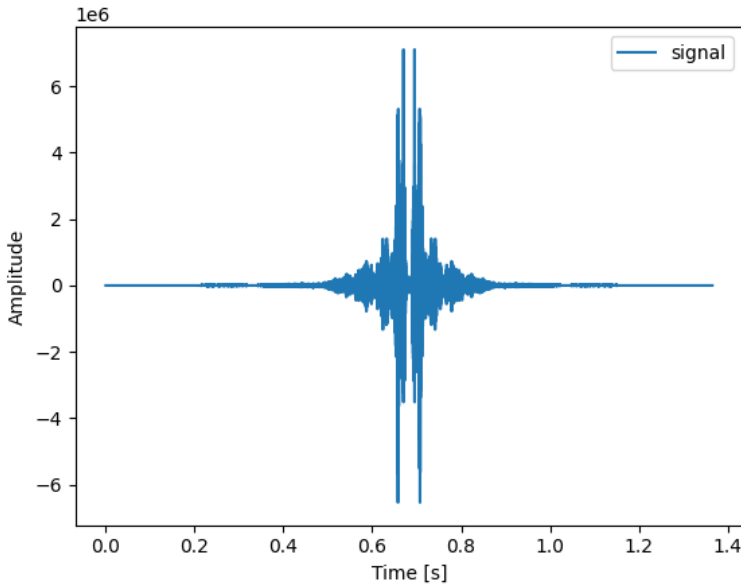
(b)

$$H(e^{jw}) = \frac{Y(e^{jw})}{X(e^{jw})} = \frac{12 + 5e^{-jw}}{6 + 5e^{-jw} + e^{-2jw}}$$

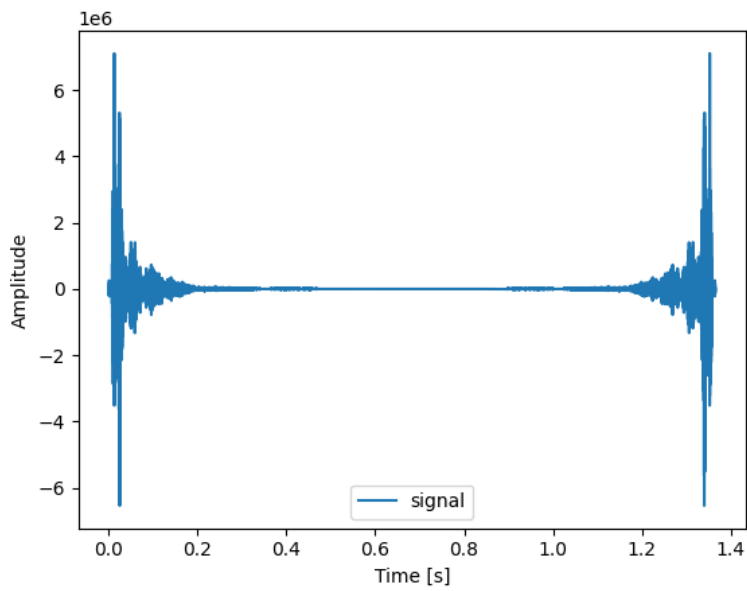
(c)

$$\begin{aligned}
h[n] &\xleftrightarrow{FT} H(e^{jw}) = \frac{3}{3 + e^{-jw}} + \frac{2}{2 + e^{-jw}} = \frac{1}{1 + \frac{1}{3}e^{-jw}} + \frac{1}{1 + \frac{1}{2}e^{-jw}} \\
\Rightarrow h[n] &= \left(-\frac{1}{3}\right)^n u[n] + \left(-\frac{1}{2}\right)^n u[n]
\end{aligned}$$

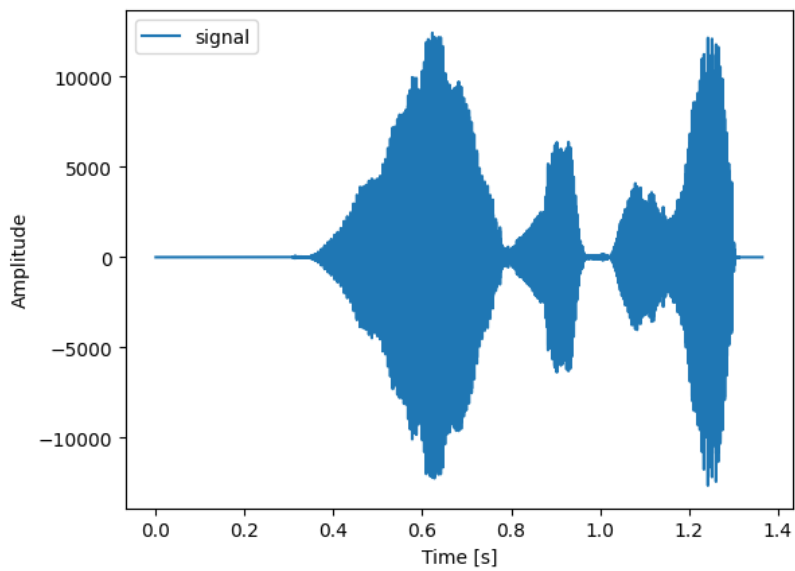
5. Frequency domain magnitude plot of encoded message:



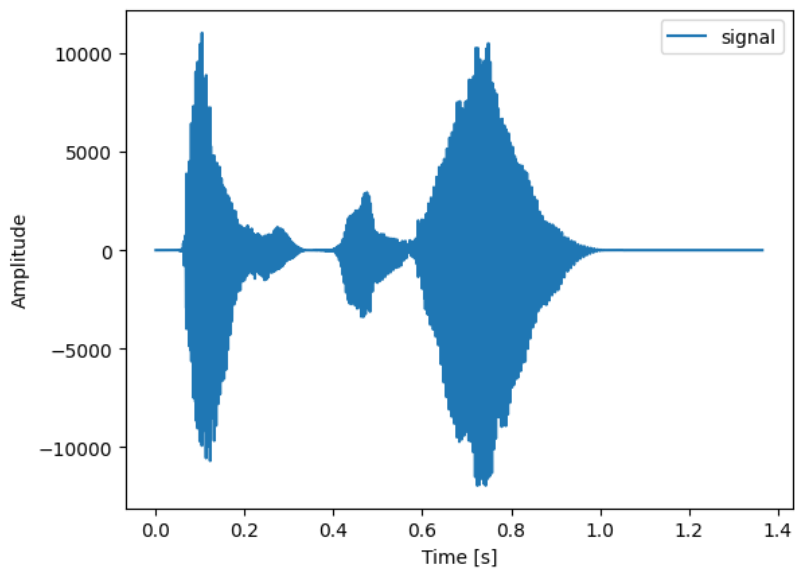
Frequency domain magnitude plot of decoded message:



Time domain magnitude plot of encoded message:



Time domain magnitude plot of decoded message:



Code:

```

import numpy as np
import matplotlib.pyplot as plt
from scipy.io import wavfile
import scipy.io

# fast fourier transformation function
def fft(x):
    x = np.asarray(x, dtype=float)
    N = x.shape[0]
    n = np.arange(N)
    k = n.reshape((N,1))
    M = np.exp(-2j * np.pi * k * n / N)
    return np.dot(M, x)

# inverse fast fourier transformation function
def ifft(X):
    X = np.asarray(X, dtype=complex)
    N = X.shape[0]
    n = np.arange(N)
    k = n.reshape((N,1))
    M = np.exp(2j * np.pi * k * n / N)
    return np.dot(M, X) / N

# get data
path = r"/content/encoded.wav"
samplerate, data = wavfile.read(path)
length = data.shape[0] / samplerate

# obtain fourier domain representation of the signal
fourier_domain_signal = fft(data)

# apply decoding recipe step 2
X_prime_1 = fourier_domain_signal[:len(fourier_domain_signal)//2]
X_prime_2 = fourier_domain_signal[len(fourier_domain_signal)//2:]

X_1 = []
for i in range(1, len(X_prime_1)+1):
    X_1.append(X_prime_1[-i])
X_2 = []
for i in range(1, len(X_prime_2)+1):
    X_2.append(X_prime_2[-i])

X_prime = np.concatenate((X_1, X_2), axis=None)

# return to time domain
time_domain_signal = ifft(X_prime)

# convert signal to wav file
wavfile.write("decoded_message.wav", samplerate, time_domain_signal.astype(np.int16))

# plot function
def plot(data_to_plot):
    time = np.linspace(0., length, data_to_plot.shape[0])

    plt.plot(time, data_to_plot[:,], label="signal")

    plt.legend()

    plt.xlabel("Time [s]")

    plt.ylabel("Amplitude")

    plt.show()

```