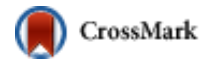


## Retraction Note



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# Retraction Note to: Cascade controller design and stability analysis in FES-aided upper arm stroke rehabilitation robotic system

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## Copyright information

The online version of the original article can be found under doi:[10.1007/s11071-014-1726-1](https://doi.org/10.1007/s11071-014-1726-1).

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## 1 Retraction Note to: Nonlinear Dyn (2015)79:1099–1114DOI: 10.1007/s11071-014-1726-1

This article has been retracted by the Editor-in-Chief of Nonlinear Dynamics.

The stability analysis, which comprises the three-page entirety of Section 4, is an equation-by-equation copy, included without credit or citation, of Section III.C of the paper “Freeman, Christopher, Tong, Daisy, Meadmore, Katie, Hughes, Ann-Marie, Rogers, Eric and BurrIDGE, Jane (2012) FES based Rehabilitation of the Upper Limb using Input/Output Linearization and ILC. In: 2012 American Control Conference, Montréal, 27–29 June 2012, pp. 4825–4830”.

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