

CS5800 – ALGORITHMS

MODULE 5. DATA STRUCTURES & GRAPHS

Lesson 2: Graph Traversals

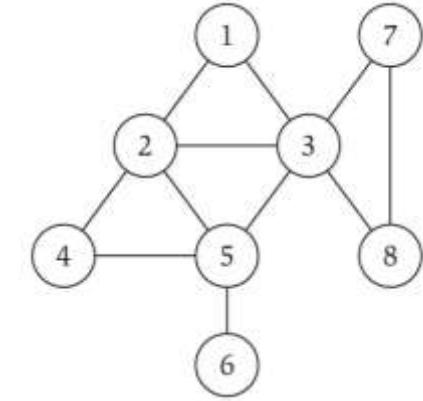
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Topics

- Why graph traversals?
- Breadth-First-Search
 - Shortest Path Tree
- Depth-First-Search
 - Combinatorics of long paths
- Connected component
- Unified approach to BFS & DFS
- Summary

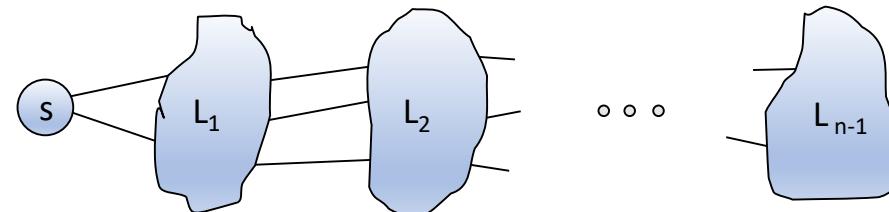
Why graph traversals?

- Variety of applications in exploring and connectivity
 - Facebook/LinkedIn
 - Maze traversal.
 - Kevin Bacon number.
 - Fewest number of hops in a communication network
 - s-t connectivity: given nodes s and t, is there a path between s and t?
 - s-t shortest path: Given nodes s and t, what is the length of the shortest path between s and t?
 - Planarity: can a given graph be drawn in the plane with no crossing edges?



Breadth First Search (BFS)

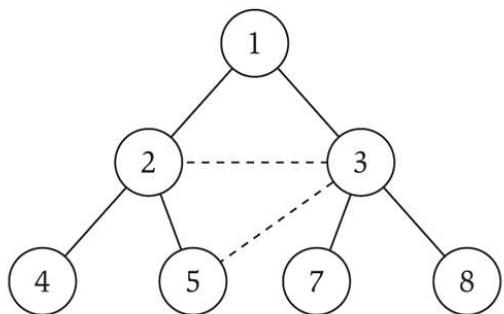
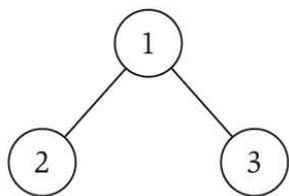
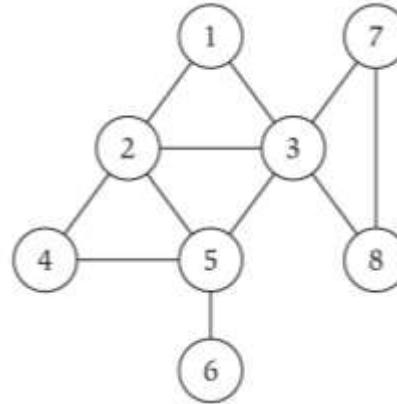
- BFS intuition: Explore outward from s , adding nodes a "layer" at a time.



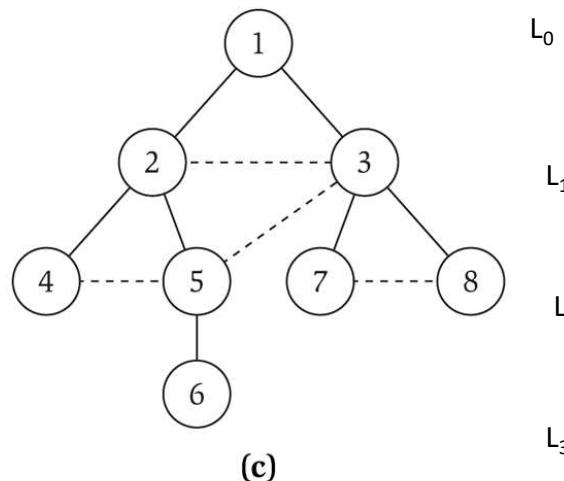
- BFS algorithm.
 - $L_0 = \{ s \}$.
 - $L_1 = \text{all neighbors of } L_0$.
 - $L_2 = \text{all nodes that do not belong to } L_0 \text{ or } L_1, \text{ and that have an edge to a node in } L_1$.
 - ...
 - $L_{i+1} = \text{all nodes that do not belong to an earlier layer, and that have an edge to a node in } L_i$.
- For each i , L_i consists of all nodes at distance exactly i from s .

BFS Tree

- The BFS tree is grown by adding an edge along which a node is encountered for the first time.
- Orienting edges towards parents we see it forms a tree.
- No edge in the graph can skip a level



(a)



(b)

L_3

(c)

L_0

L_1

L_2

BFS: Shortest Path Tree & Analysis

- Theorem: The BFS tree is a Shortest Path Tree (SPT)
- Pf: By induction on levels. Use the induction hypothesis that the BFS tree upto level i is the SPT on all nodes at most distance i from the root ▀
- Theorem: Given an adjacency list representation of the graph BFS can be implemented to run in $O(m + n)$ time.
- Pf: when we consider node u , there are $\deg(u)$ incident edges (u, v) Total time processing edges is $\sum_{u \in V} \deg(u) = 2m$ ▀

Depth First Search (DFS)

- DFS intuition: Explore in one direction as far as possible before backtracking.
- DFS algorithm – recursive implementation
- DFS(v)

Mark v

For each neighbor w of v

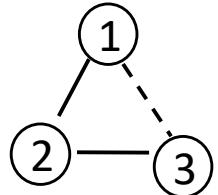
If w is unmarked

Then DFS(w)

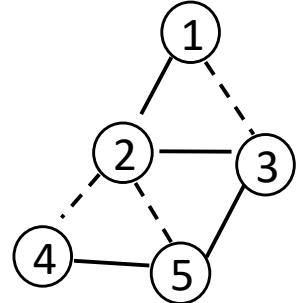
Add (v, w) to Tree

DFS Tree

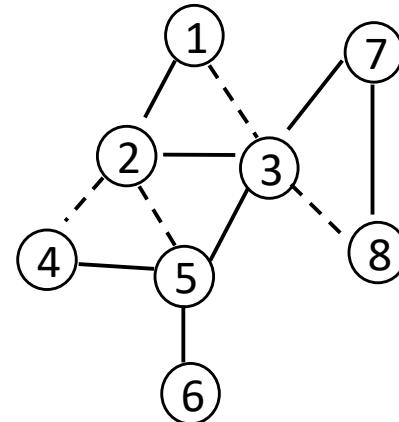
- The DFS tree grows in long and skinny fashion, compared to the short and bushy BFS tree
- Orienting edges towards parents we see it forms a tree.
- All edges run between ancestor and descendant



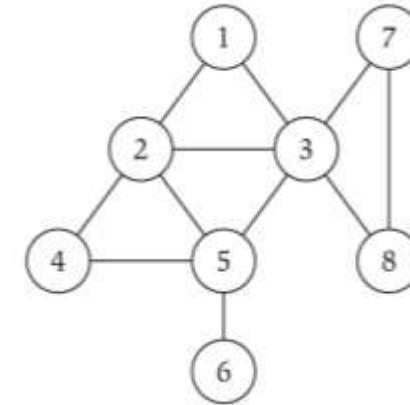
(a)



(b)



(c)

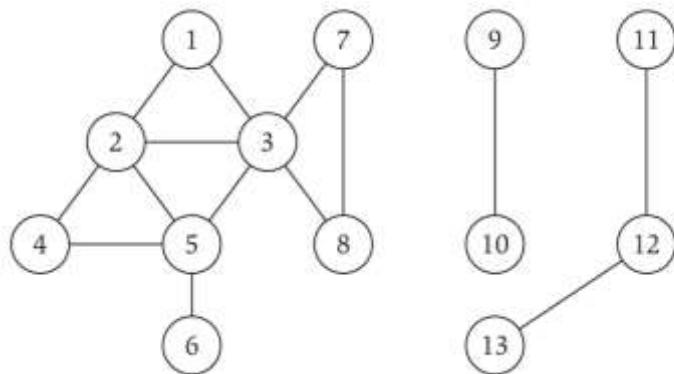


DFS: Combinatorics & Analysis

- Theorem: Any graph on n vertices without a path of length k has $O(kn)$ edges
- Pf: If the graph does not have a path of length k then the height of the DFS tree is at most k . Which means every node has at most k ancestors. But every edge runs between ancestor and descendant and hence the graph has at most $kn/2 = O(kn)$ edges. ▀
- Theorem: Given an adjacency list representation of the graph DFS can be implemented to run in $O(m + n)$ time.
- Pf: when we consider node u , there are $\deg(u)$ incident edges (u, v) Total time processing edges is $\sum_{u \in V} \deg(u) = 2m$ ▀

Connected Component

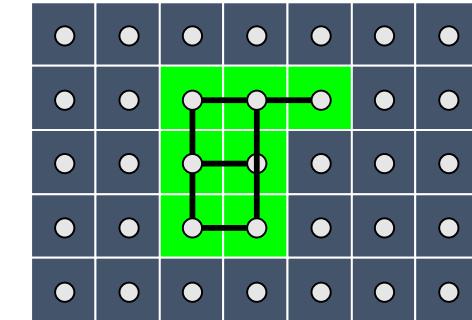
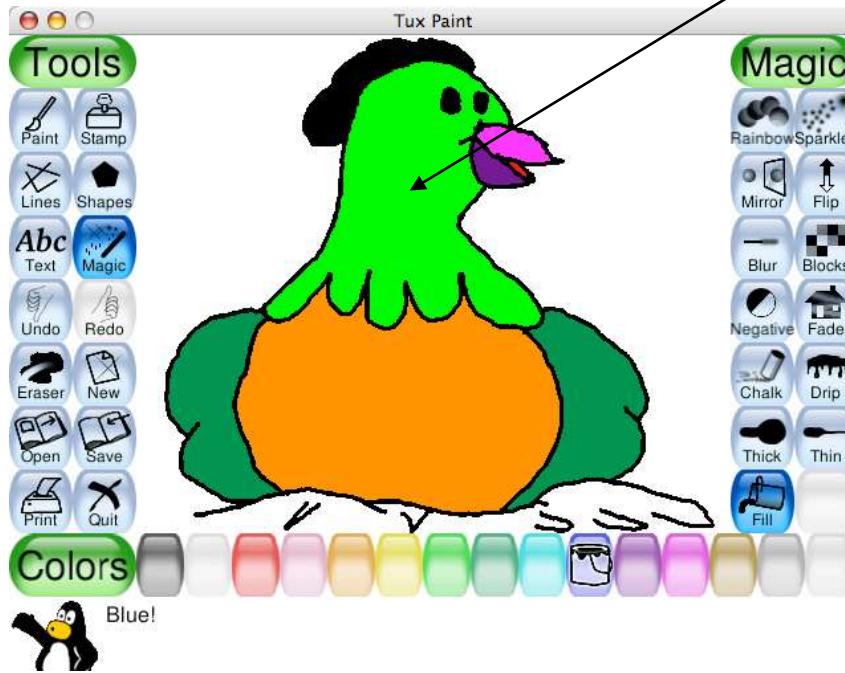
- Connected component. Find all nodes reachable from s.



- Connected component containing node 1 = { 1, 2, 3, 4, 5, 6, 7, 8 }.

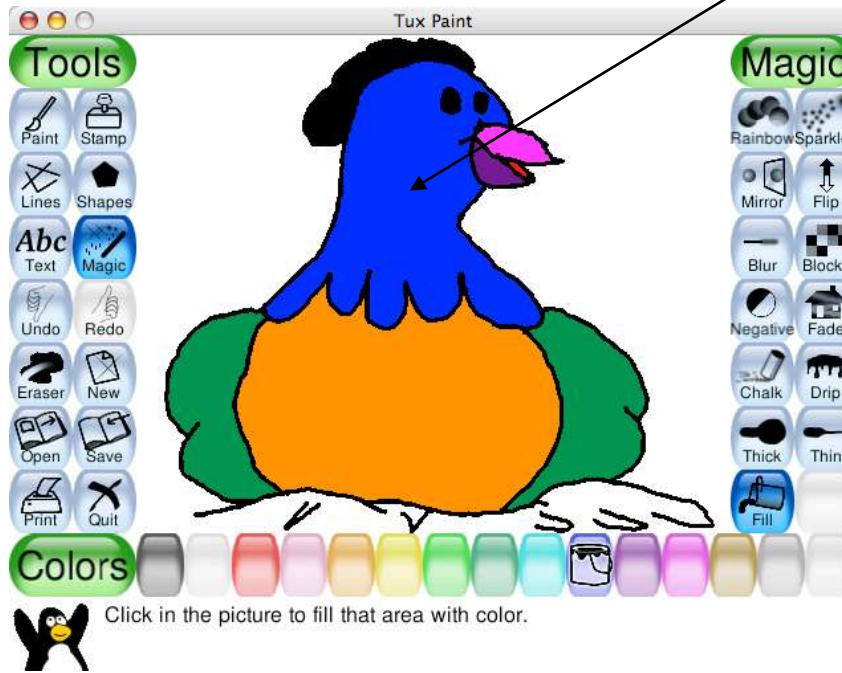
Flood Fill

- Flood fill. Given lime green pixel in an image, change color of entire blob of neighboring lime pixels to blue.
 - Node: pixel.
 - Edge: two neighboring lime pixels.
 - Blob: connected component of lime pixels.

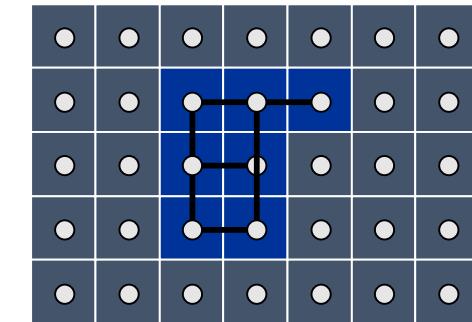


Flood Fill

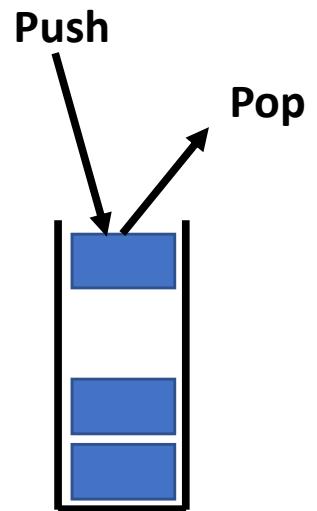
- Flood fill. Given lime green pixel in an image, change color of entire blob of neighboring lime pixels to blue.
 - Node: pixel.
 - Edge: two neighboring lime pixels.
 - Blob: connected component of lime pixels.



recolor lime green blob to blue



Unified iterative approach to DFS and BFS



- Use Data-Structure = Queue for BFS, Stack for DFS

Add (r , $\phi = \text{parent}(r)$) to Data-Structure

While not empty Data-Structure

Remove (v , u)

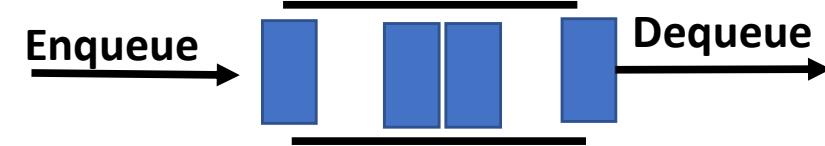
If not marked v

then add (v , $u = \text{parent}(v)$) to Tree

Mark v

For each neighbor w of v

Add (w , v) to Data-Structure



Summary

- Graph traversals – several applications including exploration and connectivity
- Many kinds of traversals of which two are used frequently – BFS and DFS
 - BFS – generates a bushy tree, a shortest path tree
 - DFS – generates a narrow spindly tree
 - Both can be implemented in linear time, using queue for BFS and stack for DFS
- Main Takeaway: Graphs can be traversed in linear time to solve connectivity problems