

# CS5800 – ALGORITHMS

## MODULE 5. DATA STRUCTURES & GRAPHS

### Lesson 2: Graph Traversals

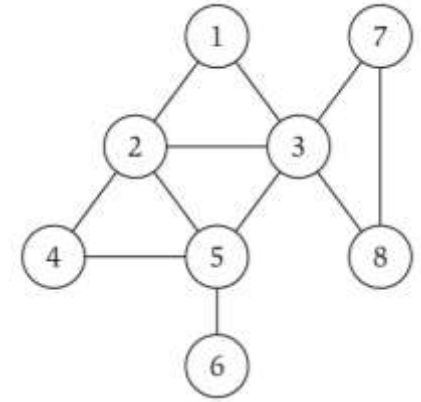
Ravi Sundaram

# Topics

- Why graph traversals?
- Breadth-First-Search
  - Shortest Path Tree
- Depth-First-Search
  - Combinatorics of long paths
- Connected component
- Unified approach to BFS & DFS
- Summary

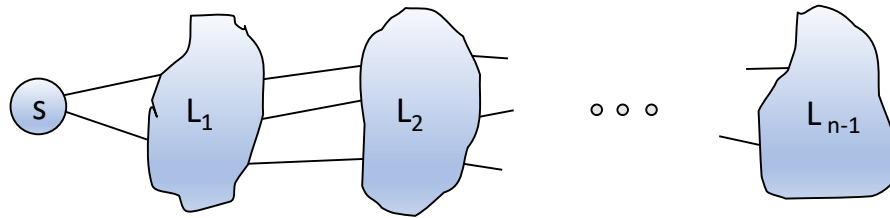
# Why graph traversals?

- Variety of applications in exploring and connectivity
  - Facebook/LinkedIn
  - Maze traversal.
  - Kevin Bacon number.
  - Fewest number of hops in a communication network
  - s-t connectivity: given nodes s and t, is there a path between s and t?
  - s-t shortest path: Given nodes s and t, what is the length of the shortest path between s and t?
  - Planarity: can a given graph be drawn in the plane with no crossing edges?



# Breadth First Search (BFS)

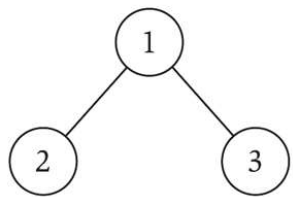
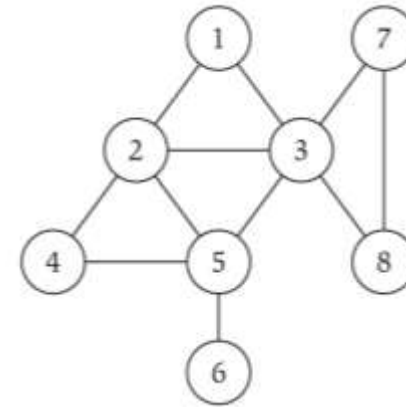
- BFS intuition: Explore outward from  $s$ , adding nodes a "layer" at a time.



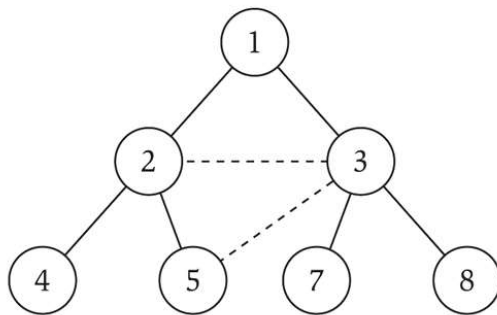
- BFS algorithm.
  - $L_0 = \{ s \}$ .
  - $L_1$  = all neighbors of  $L_0$ .
  - $L_2$  = all nodes that do not belong to  $L_0$  or  $L_1$ , and that have an edge to a node in  $L_1$ .
  - ...
  - $L_{i+1}$  = all nodes that do not belong to an earlier layer, and that have an edge to a node in  $L_i$ .
- For each  $i$ ,  $L_i$  consists of all nodes at distance exactly  $i$  from  $s$ .

# BFS Tree

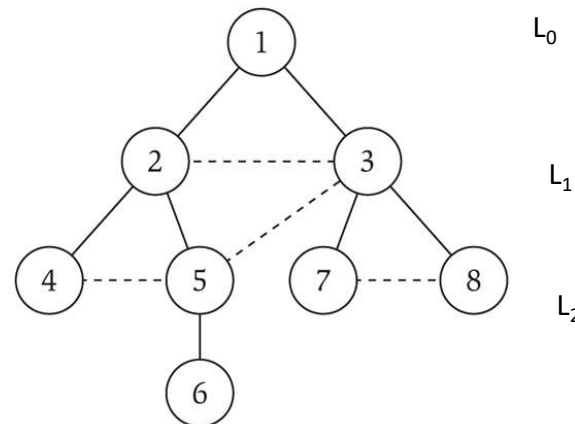
- The BFS tree is grown by adding an edge along which a node is encountered for the first time.
- Orienting edges towards parents we see it forms a tree.
- No edge in the graph can skip a level



(a)



(b)



(c)

$L_0$

$L_1$

$L_2$

$L_3$

# BFS: Shortest Path Tree & Analysis

- Theorem: The BFS tree is a Shortest Path Tree (SPT)
- Pf: By induction on levels. Use the induction hypothesis that the BFS tree upto level  $i$  is the SPT on all nodes at most distance  $i$  from the root ■
- Theorem: Given an adjacency list representation of the graph BFS can be implemented to run in  $O(m + n)$  time.
- Pf: when we consider node  $u$ , there are  $\deg(u)$  incident edges  $(u, v)$  Total time processing edges is  $\sum_{u \in V} \deg(u) = 2m$  ■

# Depth First Search (DFS)

- DFS intuition: Explore in one direction as far as possible before backtracking.
- DFS algorithm – recursive implementation
- DFS(v)

*Mark v*

*For each neighbor w of v*

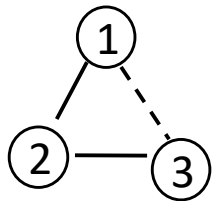
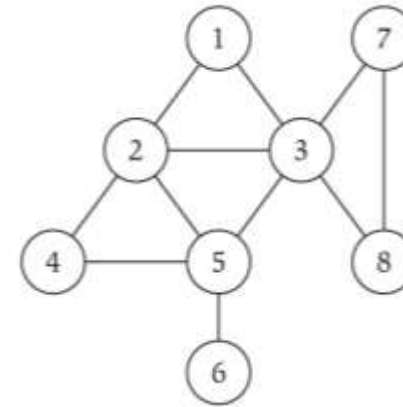
*If w is unmarked*

*Then DFS(w)*

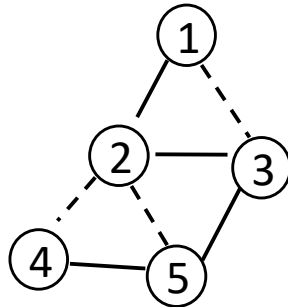
*Add (v, w) to Tree*

# DFS Tree

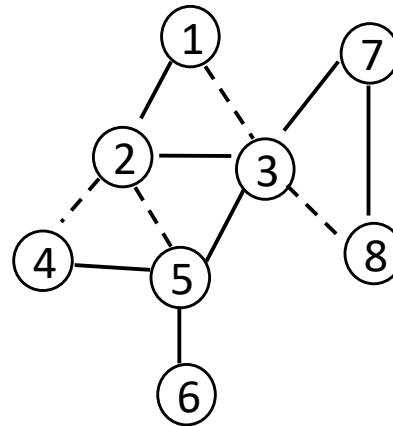
- The DFS tree grows in long and skinny fashion, compared to the short and bushy BFS tree
- Orienting edges towards parents we see it forms a tree.
- All edges run between ancestor and descendant



(a)



(b)



(c)

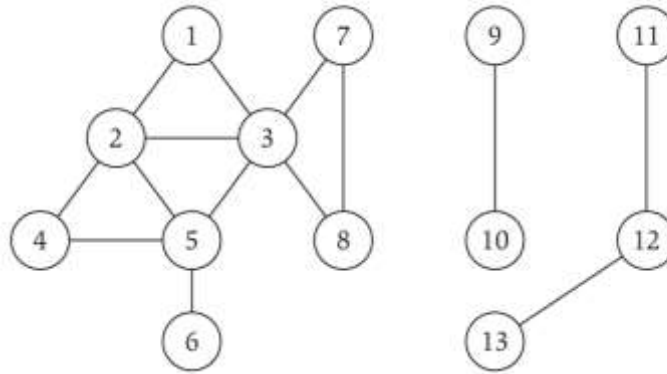


# DFS: Combinatorics & Analysis

- Theorem: Any graph on  $n$  vertices without a path of length  $k$  has  $O(kn)$  edges
- Pf: If the graph does not have a path of length  $k$  then the height of the DFS tree is at most  $k$ . Which means every node has at most  $k$  ancestors. But every edge runs between ancestor and descendant and hence the graph has at most  $kn/2 = O(kn)$  edges. ▀
- Theorem: Given an adjacency list representation of the graph DFS can be implemented to run in  $O(m + n)$  time.
- Pf: when we consider node  $u$ , there are  $\deg(u)$  incident edges  $(u, v)$  Total time processing edges is  $\sum_{u \in V} \deg(u) = 2m$  ▀

# Connected Component

- Connected component. Find all nodes reachable from s.

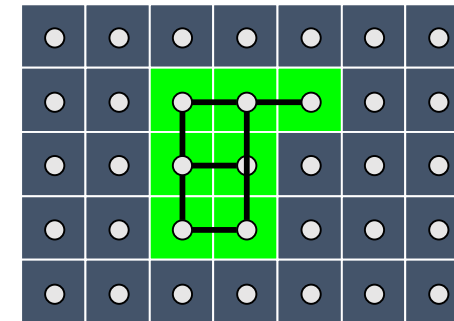
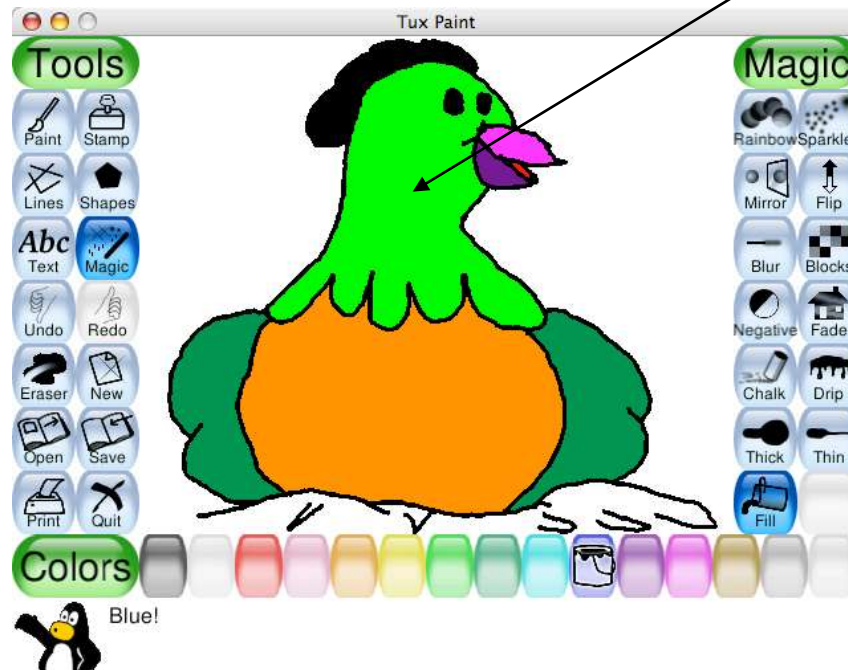


- Connected component containing node 1 = { 1, 2, 3, 4, 5, 6, 7, 8 }.

# Flood Fill

- Flood fill. Given lime green pixel in an image, change color of entire blob of neighboring lime pixels to blue.
  - Node: pixel.
  - Edge: two neighboring lime pixels.
  - Blob: connected component of lime pixels.

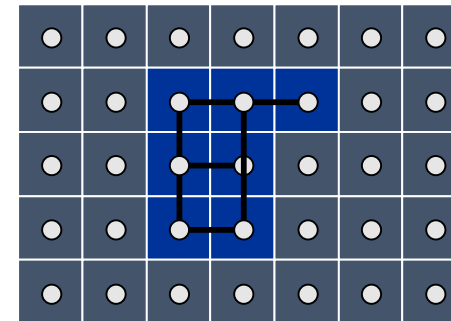
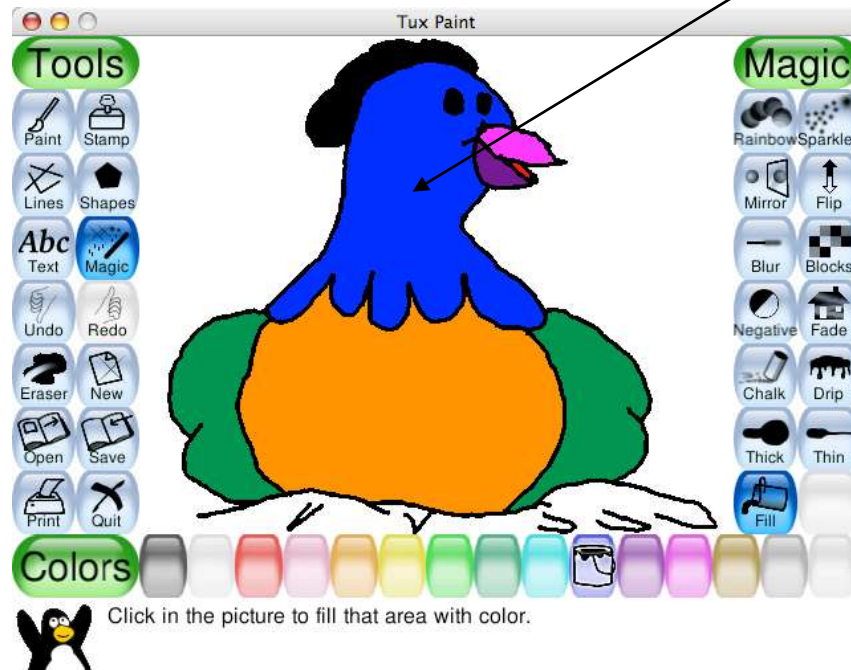
recolor lime green blob to blue



# Flood Fill

- Flood fill. Given lime green pixel in an image, change color of entire blob of neighboring lime pixels to blue.
  - Node: pixel.
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  - Blob: connected component of lime pixels.

recolor lime green blob to blue



# Unified iterative approach to DFS and BFS

- Use Data-Structure = Queue for BFS, Stack for DFS

*Add*  $(r, \phi = \text{parent}(r))$  to Data-Structure

*While not empty* Data-Structure

*Remove*  $(v, u)$

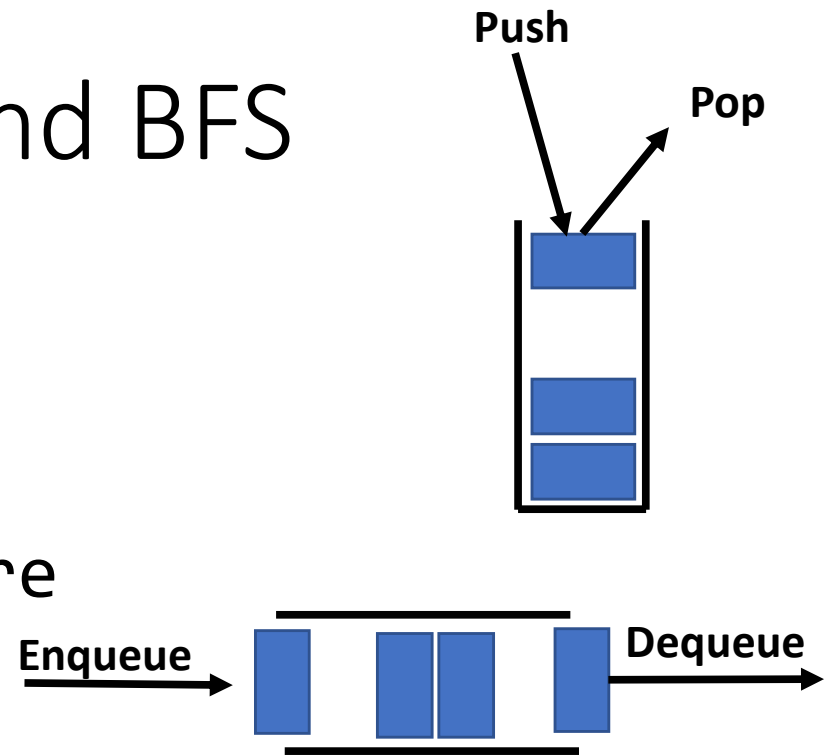
*If not marked*  $v$

*then add*  $(v, u = \text{parent}(v))$  to Tree

*Mark*  $v$

*For each neighbor*  $w$  of  $v$

*Add*  $(w, v)$  to Data-Structure



# Summary

- Graph traversals – several applications including exploration and connectivity
- Many kinds of traversals of which two are used frequently – BFS and DFS
  - BFS – generates a bushy tree, a shortest path tree
  - DFS – generates a narrow spindly tree
  - Both can be implemented in linear time, using queue for BFS and stack for DFS
- Main Takeaway: Graphs can be traversed in linear time to solve connectivity problems