

Data structures

So far we have mostly used built-in types

- integers ... -1, 0, 1, ...
- floating point numbers 3.14, ...
- characters 0..127

Pretty boring

We have seen one example of something bigger

- Arrays

Programming languages allow you to define more types:

- Enumerated types
- Making your own types
- Flatly structured data types
- Dynamic data types.

Enumerated types

An enumerated type represents some collection of constants:

```
enum suit { Club, Diamond, Heart, Spade } ;
```

Defines a type `enum suit` with 4 constants `Club`, `Diamond`, ...
It is an integer type, and the compiler allocates values starting at 0
It is just as if you had defined:

```
int Club = 0, Diamond = 1, Heart = 2, Spade = 3 ;
```

The difference is that `Club`, `Diamond`, ... are (compile-time) constants
You can use them as array sizes and in switch statements
You can specify any or all values explicitly in the enum, for example:

```
enum month { Jan = 1, Feb, Mar, ... } ;
```

Types are sets of values

An enumerated type is a subset of int, and you can define variables:

```
enum suit s;  
s = Heart;
```

However, no proper type checking is done:

```
s = 42 ;    // The compiler allows this
```

So, many programmers just use anonymous enumerations to define integer and character constants

```
enum { Width = 500, Height = 500 } ;  
enum { Newline = '\n' } ;
```

Conventionally, constants have initial capitals or all capitals

Type synonyms

`typedef` can be used to create synonyms of existing types

```
typedef int counter ;  
typedef struct suit suit ;  
typedef double image[1280][1024] ;
```

The format of a `typedef` is the same as a declaration of a variable, except it declares a new type name instead

The `image` type, for example, is a 1280 x 1024 array of doubles, which can be used just like any other type:

```
int display( image x ) { ... }
```

Typedefs can be combined with enums

```
typedef enum suit { Club, ... } suit ;
```

Structures

A structure *groups* values, forming aggregate data.

An array holds a variable number of fixed-type items

A structure holds a fixed number of variable-type items

A date is a day,
month and year

8	May	1896
---	-----	------

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A name consists of
first names and a surname



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A structure *groups* values, forming aggregate data.

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A composer has a name and a birthday

A date is a day,
month and year



A name consists of
first names and a surname



Structures

A structure *groups* values, forming aggregate data.

An array holds a variable number of fixed-type items

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A composer has a name and a birthday

A date is a day,
month and year

A name consists of
first names and a surname



The type of structured data

In maths, the type of a date would be

$\mathbf{N} \times \text{Month} \times \mathbf{N}$

The type of a name would be

$\text{String} \times \text{String}$

The type of a composer would be

$\text{name} \times \text{date}$

or

$(\text{String} \times \text{String}) \times (\mathbf{N} \times \text{Month} \times \mathbf{N})$

Structures in C

Use the `struct` keyword to define a structure type.

```
typedef enum { Jan=1, Feb, ..., Dec } Month ;
struct birthday {
    int day ;                /* order of fields */
    int year ;               /* doesn't matter */
    Month month ;            /* at this point */
} ;
typedef struct birthday Birthday ;
```

This defines

- Types called `Month` and `Birthday`
 - The type *Birthday* is a `struct` with three **fields**.
 - Two fields are of type `int`, one is of type `Month`.

Structures in C

Can use `struct` and `typedef` together.

```
typedef enum { Jan=1, Feb, ..., Dec } Month ;  
typedef struct {                // can leave out the tag  
    int day ;  
    int year ;  
    Month month ;  
} Birthday ;
```

This defines

- Types called `Month` and `Birthday`
 - The type *Birthday* is a `struct` with three fields.
 - Two fields are of type `int`, one is of type `Month`.

Structures in C

Can use `struct` and `typedef` together.

```
typedef enum { Jan=1, Feb, ..., Dec } Month ;  
typedef struct {  
    int day, year ;    // Can combine  
  
    Month month ;  
} Birthday ;
```

This defines

- Types called `Month` and `Birthday`
 - The type *Birthday* is a `struct` with three fields.
 - Two fields are of type `int`, one is of type `Month`.

Full example

```
typedef enum { Jan=1, Feb, ..., Dec } Month ;
typedef struct {
    int day, year ; Month month ;
} Birthday ;
```

```
int main( void ) {
    Birthday stravinsky ;
    stravinsky.day = 8 ;
    stravinsky.month = May ;
    stravinsky.year = 1896 ;
    printf( "%d\n", stravinsky.month ) ;
}
```

The membership operator “.” is used to select a field

Full example

```
typedef enum { Jan=1, Feb, ..., Dec } Month ;
typedef struct {
    int day, year ; Month month ;
} Birthday ;
Month month_of_birth( Birthday b ) {
    return b.month ;
}
int main( void ) {
    Birthday stravinsky ;
    stravinsky.day = 8 ;
    stravinsky.month = May ;
    stravinsky.year = 1896 ;
    printf( "%d\n", month_of_birth ( stravinsky ) ) ;
}
```

You can pass a struct to a function (by value - it is copied)

Full example

```
typedef enum { Jan=1, Feb, ..., Dec } Month ;
typedef struct {
    int day, year ; Month month ;
} Birthday ;
Month month_of_birth( Birthday b ) {
    return b.month ;
}
int main( void ) {
    Birthday stravinsky = {8, 1896, May} ;

    printf( "%d\n", month_of_birth ( stravinsky ) ) ;
}
```

When you initialise a struct you can use { } with a following ;

So...

Grouped data:

- Need to define a type, with a name
 - List the types that we are going to store inside as fields
- Need some kind of constructor
 - An operation to create a structure of that type
- Need an operation to look inside
 - Use the `'.'` operator in C

Another example

Let's define a type point, in the plane XY , consisting of two reals:

$$\text{Point} = R \times R$$

If (x,y) is a point, then the point rotated with an angle ϕ is given by

$$(x \cos\phi + y \sin\phi, y \cos\phi - x \sin\phi)$$

Define a function rotate:

$$\text{rotate}((x,y),\phi) = (x \cos\phi + y \sin\phi, y \cos\phi - x \sin\phi)$$

Rotate with C structures

```
typedef struct {  
    double x, y ;  
} Point ;
```

Rotate with C structures

```
typedef struct {  
    double x, y ;  
} Point ;
```

```
Point rotate( Point s, double phi ) {  
    Point t ;  
    double sin_phi = sin( phi ) ;  
    double cos_phi = cos( phi ) ;  
    t.x = s.x * cos_phi + s.y * sin_phi ;  
    t.y = s.y * cos_phi - s.x * sin_phi ;  
    return t ;  
}
```

Union types

A union type (also known as a variant) allows you to store either X or Y in a data type. Use `union` in C.

```
typedef struct {  
    double d, alpha ;  
} Polar ;
```

```
typedef struct {  
    double x, y ;  
} Cartesian ;
```

```
typedef union {  
    Polar p ;  
    Cartesian c ;  
} Point ;
```

Alternatives

```
typedef union {  
    Polar p ;  
    Cartesian c ;  
} Point ;
```

Defines a data type `Point`, which consists of

- Either a cartesian part (with two floats),
- Or a polar description (with two floats).

(or, for example, a vehicle which is a car, truck, or caravan)

A member of a union is accessed with the membership operator `'.'`
(The members of a struct are accessed using `'.'`)

So:

- if `s` is of type `Point`, and currently contains Cartesian coords,
- then `s.c.x` refers to member `x` of member `c` of `s`

Alternatives

```
int main( void ) {  
    Point s, t ;  
    s.c.x = 2 ;  
    s.c.y = 1 ;  
    t.p.d = 2.236 ;  
    t.p.alpha = 0.4636 ;  
}
```

- s** specifies the point (2,1) using Cartesian Coordinates
 - 2 along the X axis, 1 along the Y axis
- t** specifies the point (2,1) using Polar Coordinates
 - An angle of 0.4636 radians, a distance of 2.236 ($\sqrt{5}$)

Difference between Struct and Union

```
typedef union {  
    Polar p ;  
    Cartesian c ;  
    int i ;  
} uniontype ;
```

```
uniontype u ;
```

```
typedef struct {  
    Polar p ;  
    Cartesian c ;  
    int i ;  
} structtype ;
```

```
structtype s ;
```

Difference between Struct and Union

```
typedef union {  
    Polar p ;  
    Cartesian c ;  
    int i ;  
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```

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uniontype u ;
```

```
typedef struct {  
    Polar p ;  
    Cartesian c ;  
    int i ;  
} structtype ;
```

```
structtype s ;
```

s: s.p:

s.c:

s.i:



Difference between Struct and Union

```
typedef union {  
    Polar p ;  
    Cartesian c ;  
    int i ;  
} uniontype ;
```

```
uniontype u ;
```

```
u:  u.p:
```

Polar

```
typedef struct {  
    Polar p ;  
    Cartesian c ;  
    int i ;  
} structtype ;
```

```
structtype s ;
```

```
s:  s.p:
```

```
s.c:
```

```
s.i:
```

Polar

Cartesian

int

Difference between Struct and Union

```
typedef union {  
    Polar p ;  
    Cartesian c ;  
    int i ;  
} uniontype ;
```

```
uniontype u ;
```

```
u:    u.c:
```

Cartesian

```
typedef struct {  
    Polar p ;  
    Cartesian c ;  
    int i ;  
} structtype ;
```

```
structtype s ;
```

```
s:    s.p:
```

```
s.c:
```

```
s.i:
```

Polar

Cartesian

int

Difference between Struct and Union

```
typedef union {  
    Polar p ;  
    Cartesian c ;  
    int i ;  
} uniontype ;
```

```
uniontype u ;
```

u: u.c:

int
(unused)

```
typedef struct {  
    Polar p ;  
    Cartesian c ;  
    int i ;  
} structtype ;
```

```
structtype s ;
```

s: s.p:
 s.c:
 s.i:



What is currently in a union?

```
typedef struct {  
  
    union {  
        Polar p ;  
        Cartesian c ;  
    } pt ;  
} Point ;
```

There is no way to tell - it is up to the programmer to keep track
One way is to:

- Maintain an extra field, a "tag"
- The tag specifies which type is currently stored in the inner union

What is currently in a union?

```
typedef enum { IsPolar, IsCartesian } Pointtag ;

typedef struct {
    Pointtag tag ;
    union {
        Polar p ;
        Cartesian c ;
    } pt ;
} Point ;
```

There is no way to tell - it is up to the programmer to keep track

Creating the union

```
int main( void ) {  
    Point s, t ;  
    s.tag = IsCartesian ;  
    s.pt.c.x = 2 ;  
    s.pt.c.y = 1 ;  
  
    t.tag = IsPolar ;  
    t.pt.p.d = 2.236 ;  
    t.pt.p.alpha = 0.4636 ;  
}
```

By inspecting the tag, the function `rotate` can now be defined properly

Using the union

```
Point rotate( Point s, double phi ) {
    Point t ;
    if( s.tag == IsCartesian ) {
        t.tag = IsCartesian ;
        t.pt.c.x=s.pt.c.x*sin(phi)+s.pt.c.y*cos(phi) ;
        t.pt.c.y=s.pt.c.y*sin(phi)-s.pt.c.x*cos(phi) ;
    } else {
        t.tag = IsPolar ;
        t.pt.p.alpha = phi + s.pt.p.alpha ;
        t.pt.p.d = s.pt.p.d ;
    }
    return t ;
}
```

Using the union

```
Point rotate( Point s, double phi ) {
    Point t ;
    if( s.tag == IsCartesian ) {
        t.tag = IsCartesian ;
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        t.pt.c.y=s.pt.c.y*sin(phi)-s.pt.c.x*cos(phi) ;
    } else {
        t.tag = IsPolar ;
        t.pt.p.alpha = phi + s.pt.p.alpha ;
        t.pt.p.d = s.pt.p.d ;
    }
    return t ;
}
```

Using the union

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        t.tag = IsCartesian ;
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        t.pt.c.y=s.pt.c.y*sin(phi)-s.pt.c.x*cos(phi) ;
    } else {
        t.tag = IsPolar ;
        t.pt.p.alpha = phi + s.pt.p.alpha ;
        t.pt.p.d = s.pt.p.d ;
    }
    return t ;
}
```

Using the union

```
Point rotate( Point s, double phi ) {
    Point t ;
    if( s.tag == IsCartesian ) {
        t.tag = IsCartesian ;
        t.pt.c.x=s.pt.c.x*sin(phi)+s.pt.c.y*cos(phi) ;
        t.pt.c.y=s.pt.c.y*sin(phi)-s.pt.c.x*cos(phi) ;
    } else {
        t.tag = IsPolar ;
        t.pt.p.alpha = phi + s.pt.p.alpha ;
        t.pt.p.d = s.pt.p.d ;
    }
    return t ;
}
```

Using a switch statement instead

```
Point rotate( Point s, double phi ) {
    Point t ;
    switch ( s.tag ) {
    case IsCartesian:
        t.tag = IsCartesian ;
        t.pt.c.x=s.pt.c.x*sin(phi)+s.pt.c.y*cos(phi) ;
        t.pt.c.y=s.pt.c.y*sin(phi)-s.pt.c.x*cos(phi) ;
        break;
    case IsPolar:
        t.tag = IsPolar ;
        t.pt.p.alpha = phi + s.pt.p.alpha ;
        t.pt.p.d = s.pt.p.d ;
        break;
    }
    return t ;
}
```

Using a switch statement instead

```
Point rotate( Point s, double phi ) {  
    Point t ;  
    switch ( s.tag ) {  
    case IsCartesian:  
        t.tag = IsCartesian ;  
        t.pt.c.x=s.pt.c.x*sin(phi)+s.pt.c.y*cos(phi) ;  
        t.pt.c.y=s.pt.c.y*sin(phi)-s.pt.c.x*cos(phi) ;  
        break ;  
    case IsPolar:  
        t.tag = IsPolar ;  
        t.pt.p.alpha = phi + s.pt.p.alpha ;  
        t.pt.p.d = s.pt.p.d ;  
        break ;  
    }  
    return t ;  
}
```

Using a switch statement instead

```
Point rotate( Point s, double phi ) {  
    Point t ;  
    switch ( s.tag ) {  
    case IsCartesian:  
        t.tag = IsCartesian ;  
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        t.pt.c.y=s.pt.c.y*sin(phi)-s.pt.c.x*cos(phi) ;  
        break ;  
    case IsPolar:  
        t.tag = IsPolar ;  
        t.pt.p.alpha = phi + s.pt.p.alpha ;  
        t.pt.p.d = s.pt.p.d ;  
        break ;  
    }  
    return t ;  
}
```

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        t.tag = IsCartesian ;  
        t.pt.c.x=s.pt.c.x*sin(phi)+s.pt.c.y*cos(phi) ;  
        t.pt.c.y=s.pt.c.y*sin(phi)-s.pt.c.x*cos(phi) ;  
        break;  
    case IsPolar:  
        t.tag = IsPolar ;  
        t.pt.p.alpha = phi + s.pt.p.alpha ;  
        t.pt.p.d = s.pt.p.d ;  
        break;  
    }  
    return t ;  
}
```


Summarising Flat Data

Constructs:

```
typedef enum { value1, value2, ... } typename ;  
typedef struct { type1 x1 ; type2 x2 ... } typename  
typedef union { type1 x1 ; type2 x2 ... } typename  
switch( value ) { case 1: ... ; break ; case 2: ...
```