

PSYC 10004-6 – FOUNDATIONS OF PSYCHOLOGY  
Introduction to Cognitive Psychology

Lecture 3 – Sensation and Perception

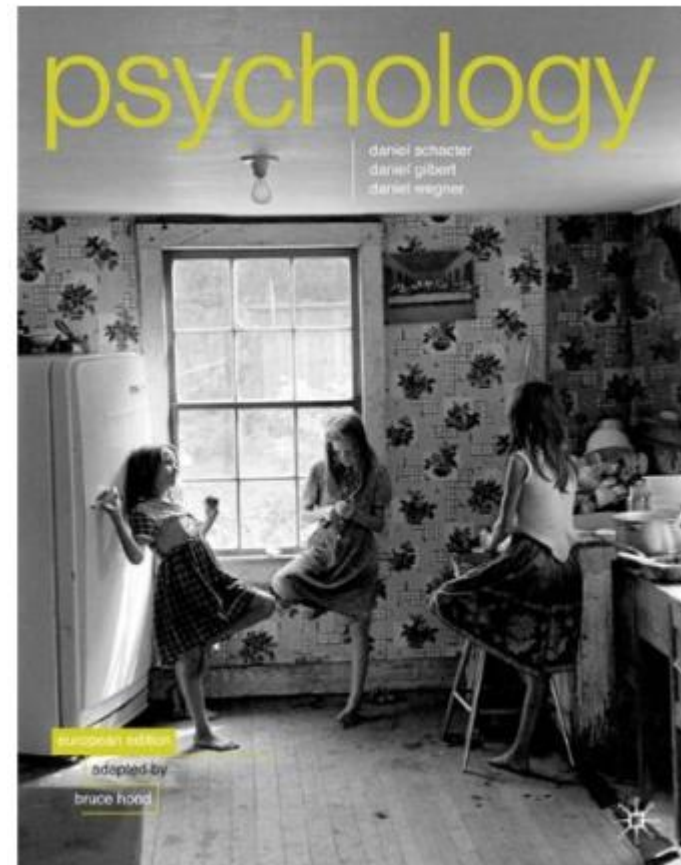
Prof Markus Damian

# Aims of lecture

- How is information about the external world transmitted to the brain?
  - Sensory receptors, neural pathways, etc.
- How does our brain accomplish perception of the external world?
  - Via automatic (and inaccessible) low-level neural processes
- many of the processes involved in sensation/perception are innately determined, and/or automatic
- *interpretation* is an integral part of our sensory experience, with limited awareness of 'raw' sensory input

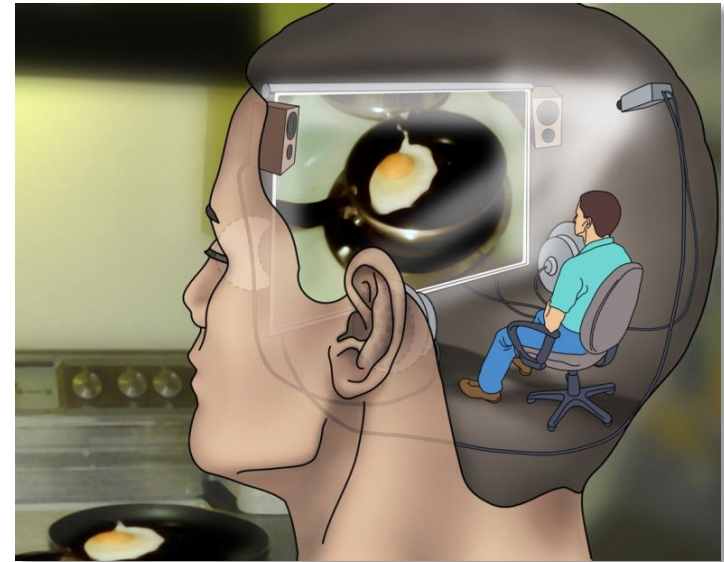
## Required reading:

- Schacter, Gilbert, Wegner & Hood (2012), Psychology. Palgrave Macmillan. European Edition.
  - Chapter 4 (“Sensation and Perception”, pp. 120-129 and pp. 147-149 only)
- Recommended but not required: Chapter 3 (“Neuroscience & Behaviour”), pp. 80-92 (“Neurons: the origin of behaviour”)



# Sensory perception

- do sensory systems provide an image that is a copy of the world?
- cognitive processes are based on *internal representations* (primarily of an external world)
- input from sensory systems is restricted to specific properties or attributes
- cognitive processes *construct* perceptual interpretations from data provided by sensory input



# Sensation and perception – a conventional distinction

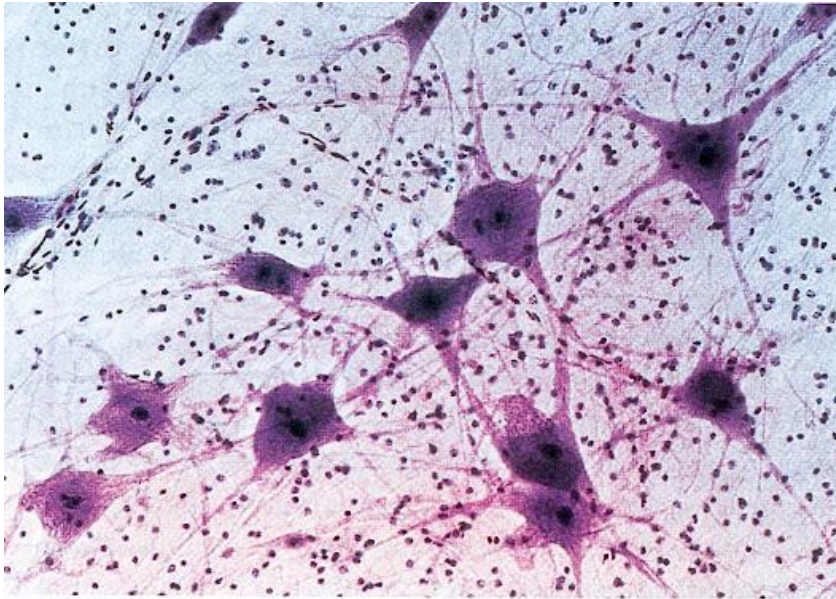
- Sensation
  - detection of simple properties, e.g.: brightness, colour, loudness, sweetness etc.
- Perception - *interpretation* of sensory signals
  - object recognition
  - identification of properties such as location, size, movement, etc.
- but distinction is not always clear-cut – properties that can be directly “sensed” may be computationally complex

# Requirements for sensory systems

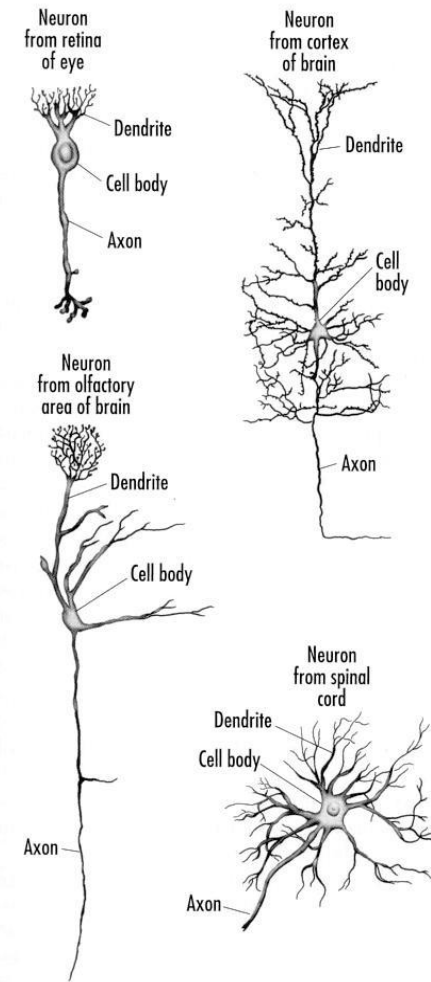
- the brain can't sense the external world directly – it relies on signals received from sense organs (eyes, ears, skin, etc.) via *afferent* nerves
- sensory systems therefore need
  - a biological mechanism for translating physical attributes into electrical signals (*receptors*)
  - mechanism for conveying this information to CNS

# Biological components – Nerve cells (neurons)

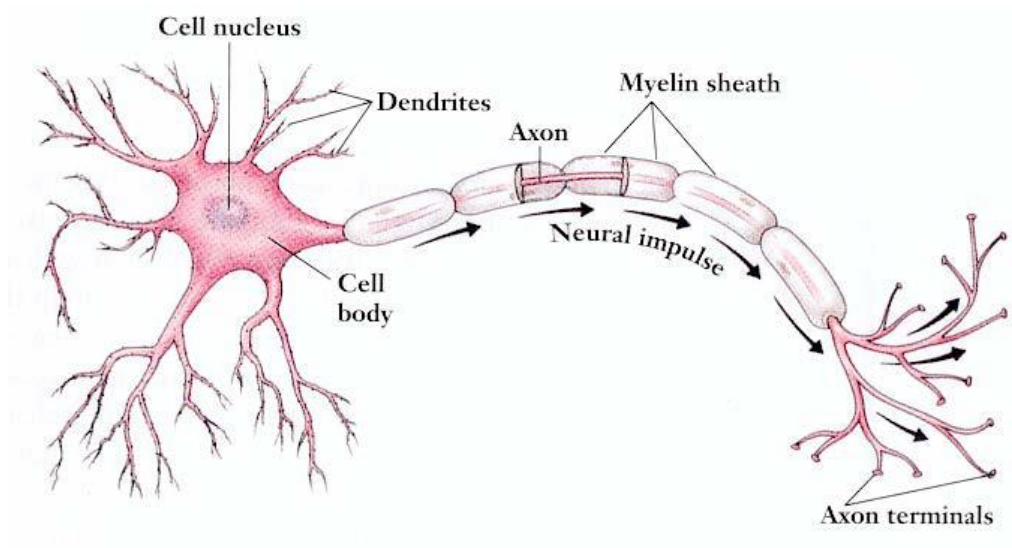
- neurons come in many shapes and sizes
- most sensory detectors are modified neurons



*Neurons in the spinal cord*



# Neural computing - what can nerve cells do?

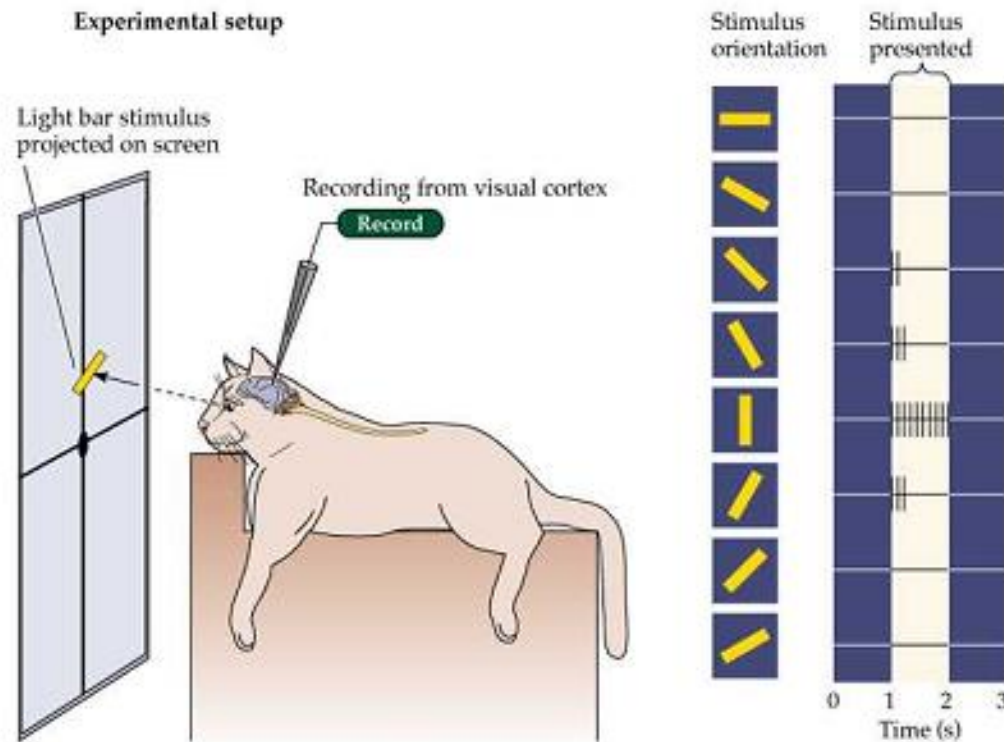


- neurons transmit brief electrical pulses with fixed amplitude and duration
- make excitatory or inhibitory connections with each other to create networks with one-to-many and many-to-one linkages

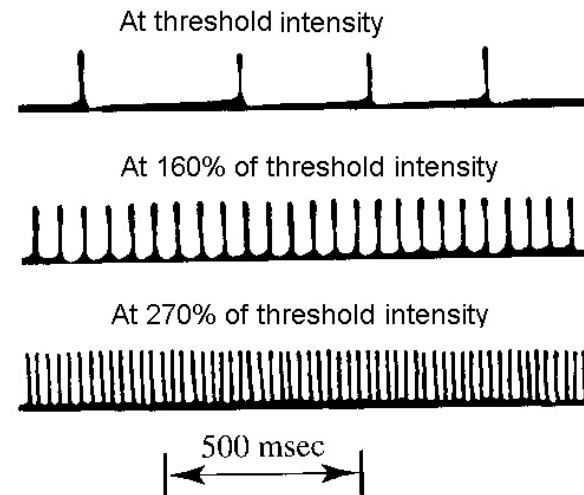
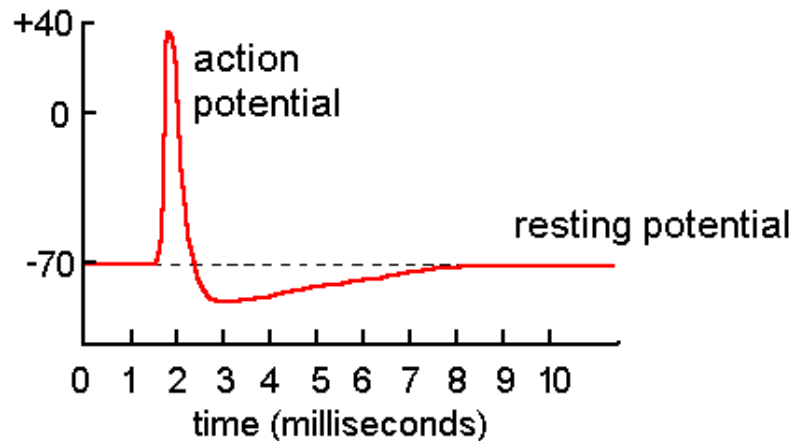


# Single-cell recording

- Electro-physiological response of a single neuron can be observed by inserting a microelectrode (“single cell recording”)



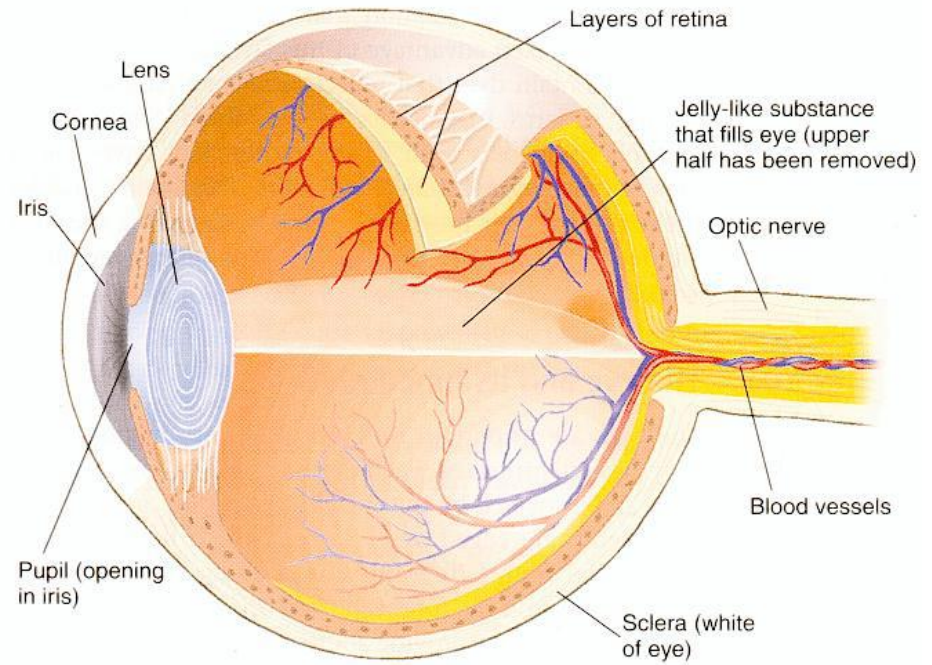
# Coding of stimulus intensity



- electrical 'spike' has *fixed amplitude*, regardless of stimulus intensity – signal is one-dimensional (i.e., can only encode one stimulus dimension)
- for most sensory systems, intensity is signaled by the *rate* at which neurons fire

# Vision

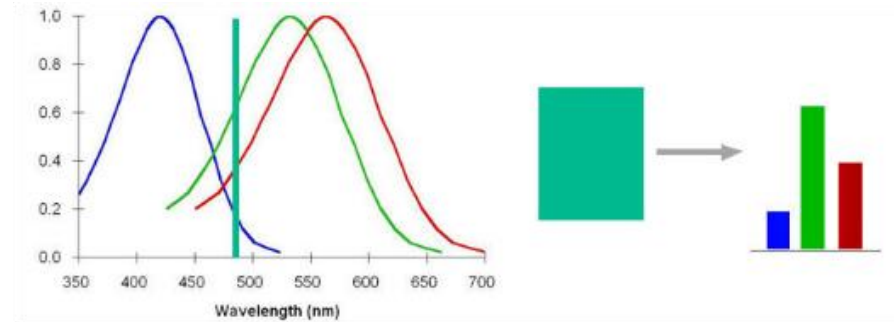
- receptors in the retina of the eye are *rods* and *cones* – modified neurons containing photosensitive pigment (rhodopsin)
- rods function at low light levels, cones in bright light
- cones are colour-tuned – peak sensitivity to either red, green or blue (different rhodopsins)



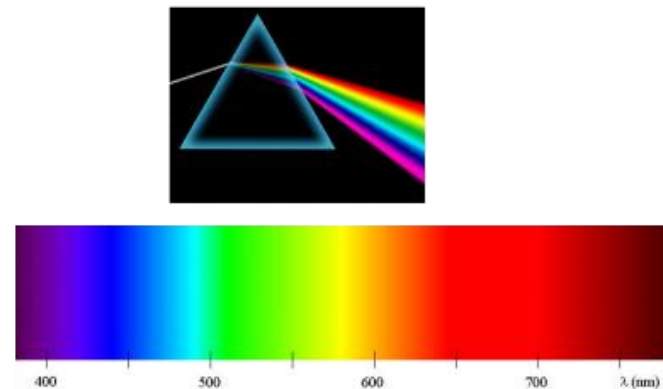
# Perception of colour

- cones are colour-sensitive – output depends on wavelength of light
- for any *single* wavelength, colour is uniquely coded by output pattern
- principle extends to light that contains a mixture of wavelengths

*sensitivity of three types of cone*

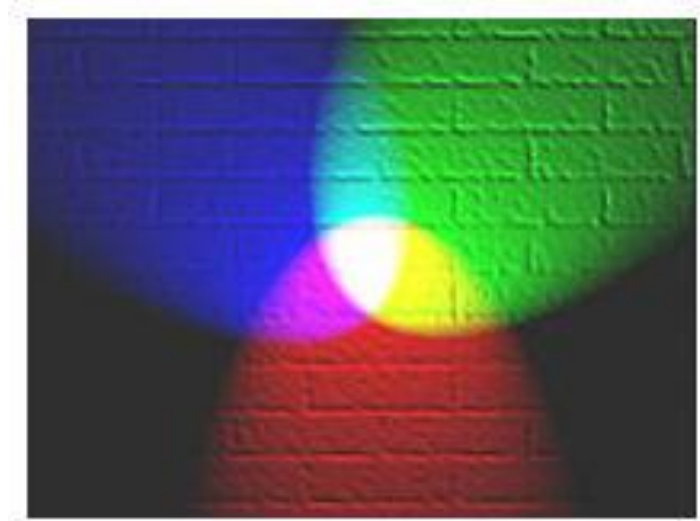


- white light is a mix of all visible wavelengths, all at the same intensity
- “white” is therefore coded as equal output of red, green, blue receptors



# Perception of colour

- the perception of white can be created by mixing *pure* red, green and blue light at equal intensities
- this is the basis of colour mixing (makes colour TV possible)



# Structure of the retina

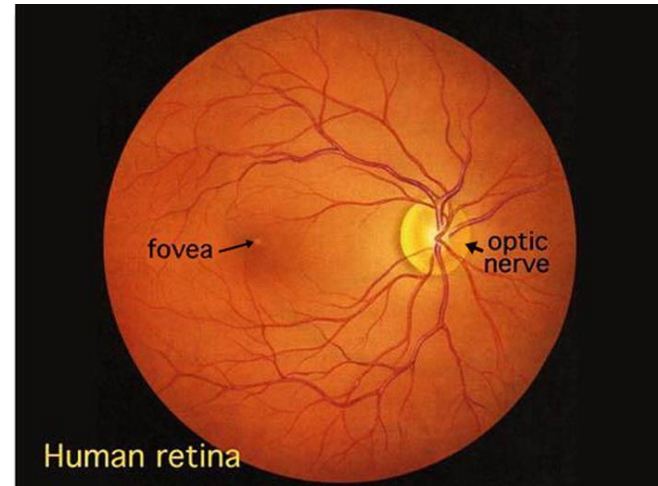
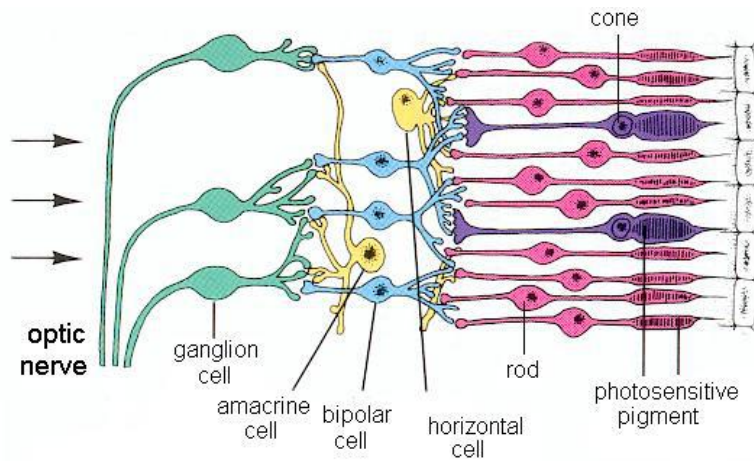


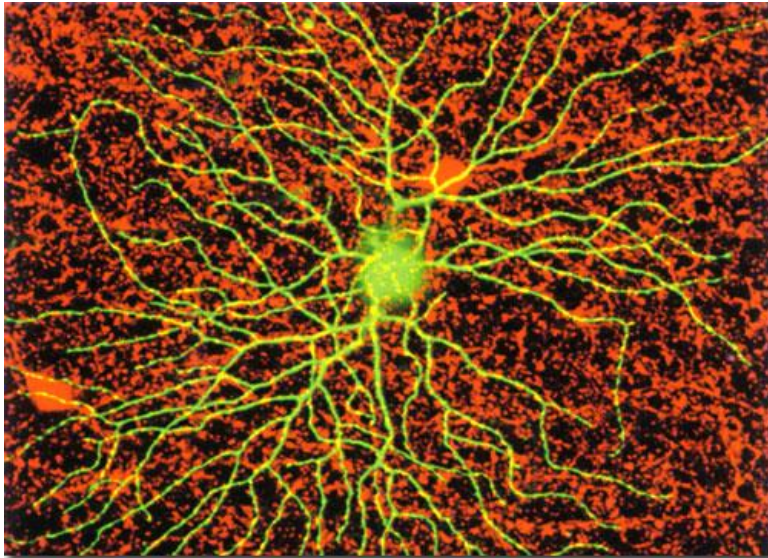
Fig. 1. Human retina as seen through an ophthalmoscope.

- network of connections between receptors and optic nerve *performs local computations*
  - response of photoreceptors and bipolar cells to illumination is graded
  - amacrine cells and horizontal cells combine and contrast signals from adjacent photoreceptors
  - ganglion cells generate action potentials and form the *optic nerve*

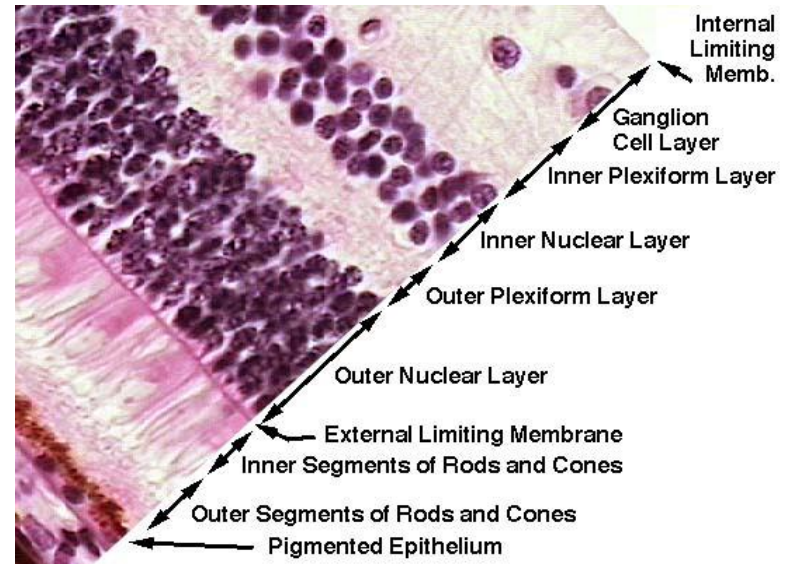


# Retinal complexity

- retina contains around 120 million rods and 7 million cones, richly interconnected
- optic nerve is formed from axons of approximately one million ganglion cells

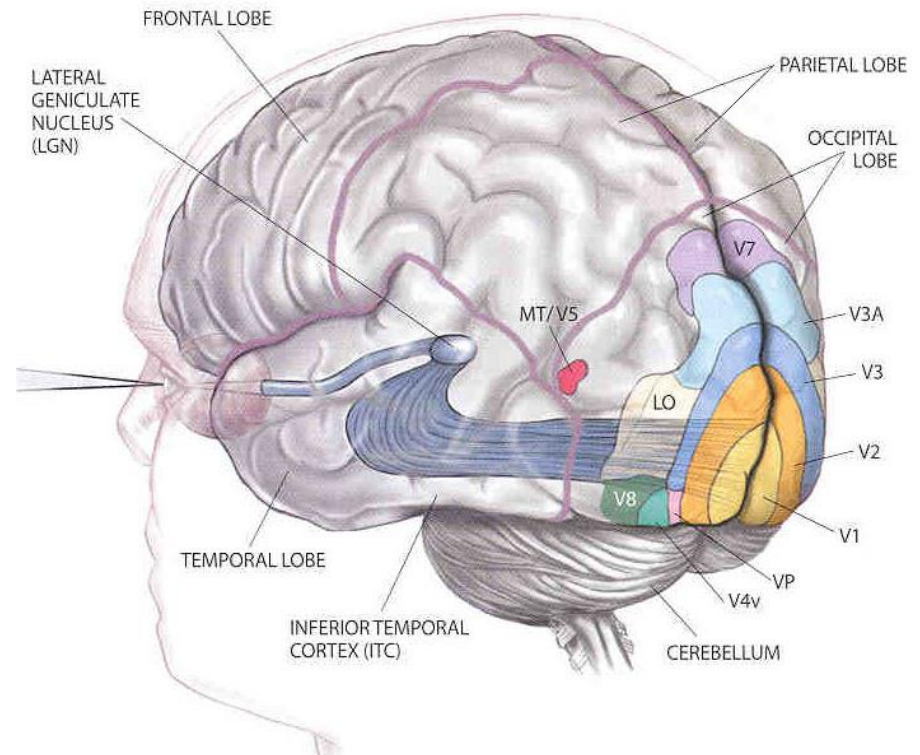


*A single ganglion cell*



# Early processing of visual information

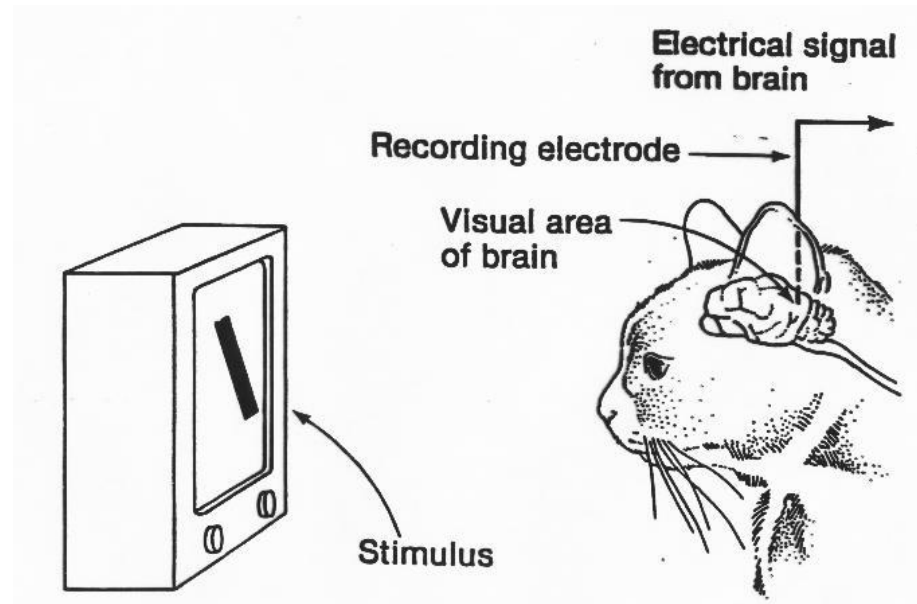
- interconnections mean that retina does not function as a simple light detector
  - retinal processing involves 'cleaning up' of image and beginnings of feature extraction
- separate structures exist in *visual cortex* for extracting information about shape, colour, position, motion, etc.





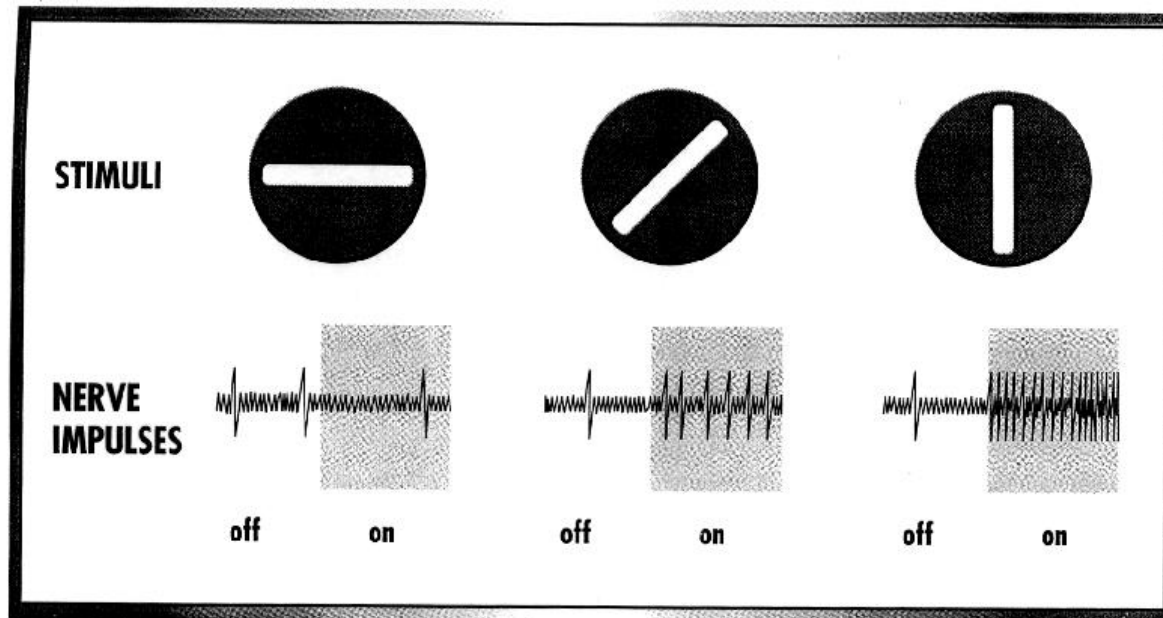
# Cortical processing of visual information

- feature processing structures in visual cortex arranged in layers
- early stages of processing detect elementary visual features - 'simple cells' discovered by Hubel and Wiesel in the 1960s (Nobel prize in 1981)
- identified via single-cell recordings from neurons in visual cortex
- collections of 'simple cells', each responding to a line or edge in illumination reaching a particular region in the retina



# Feature detection – neurophysiological evidence

- electrical responses monitored in a single cell when bright lines in different orientations are projected onto a small area of the retina
- particular cells are selective active in response to a particular stimulus (say, a line) in a particular orientation (e.g., vertical) – “feature detectors”



**FIGURE 5-11**

Response of a Simple Cell *This figure illustrates the response of a simple cortical cell to a bar of light.*

# Perception

- perception involves *interpretation* of sensory input as information about an external world
- requires computational processing of sensory data, including
  - segmentation and object recognition
  - construction of 3-dimensional representation
- many of the processes involved in this are automatic and/or innately determined
  - interpretation is an integral part of our sensory experience, with limited awareness of “raw” sensory input

# Segmentation (“parsing”) of the visual scene

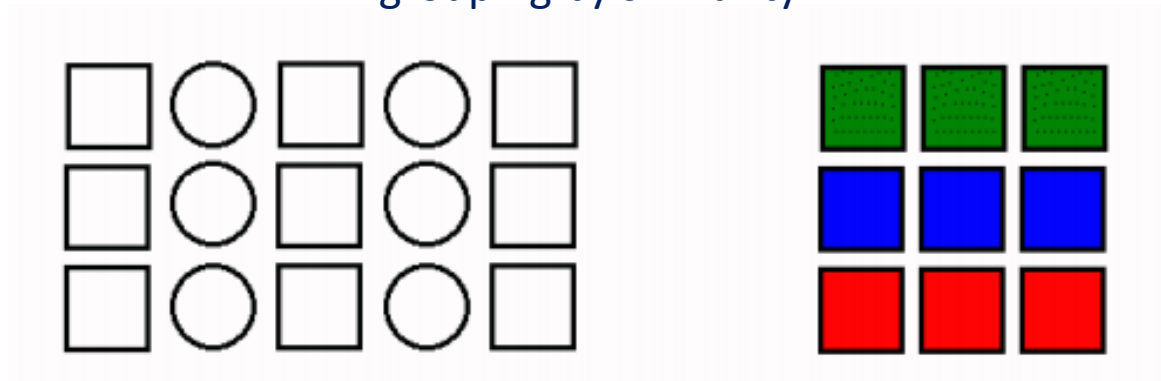
- first stage of object recognition – visual features that belong to the same object are grouped together
- “Gestalt” principles of perceptual organization, such as
- fundamental distinction between figure and ground
  - a prerequisite for object recognition (applies to *all* objects in visual field)
  - assignment of figure and ground can be ambiguous or reversible (but distinction must always be made)



# Gestalt principles of grouping (e.g., Wertheimer, 1923)

- grouping of elements to make a “figure” is determined by a set of heuristic\* principles
  - based on processes that are automatic, and *innate* (evidence from studies of infants)
  - principles include grouping by similarity, proximity, goodness of form, etc.

grouping by similarity

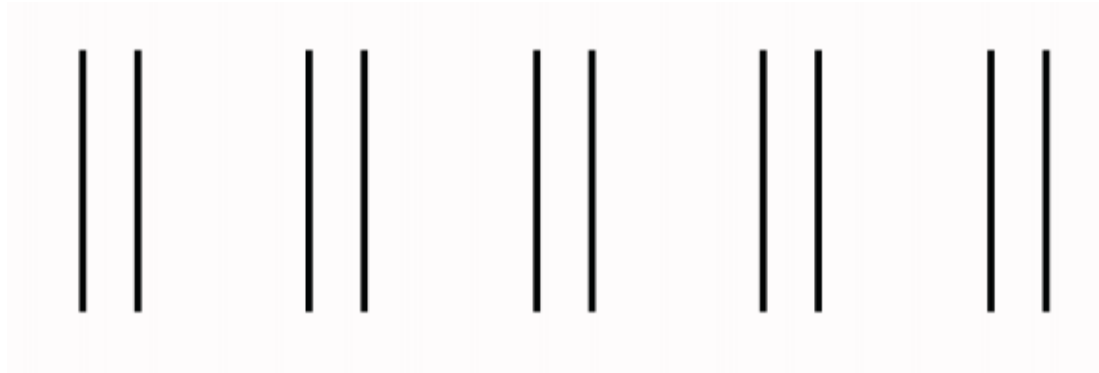


\*heuristics are simple, efficient rules to solve problems - typically when incomplete information is available or there is too much information for all possibilities to be fully considered

# Gestalt principles of grouping

- grouping of elements to make a “figure” is determined by a set of heuristic\* principles
  - based on processes that are automatic, and innate (evidence from studies of infants)
  - principles include grouping by similarity, proximity, goodness of form, etc.

## grouping by proximity



# Gestalt principles of grouping

- grouping of elements to make a “figure” is determined by a set of heuristic\* principles
  - based on processes that are automatic, and innate (evidence from studies of infants)
  - principles include grouping by similarity, proximity, goodness of form, etc.

grouping by goodness of form



# Living in a 3-D world

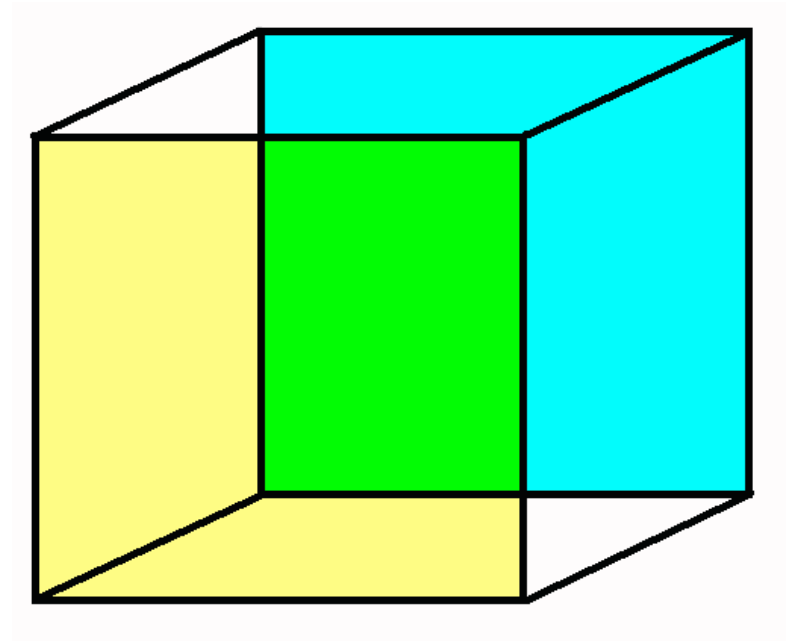
- visual images are two-dimensional - but the world is three-dimensional!



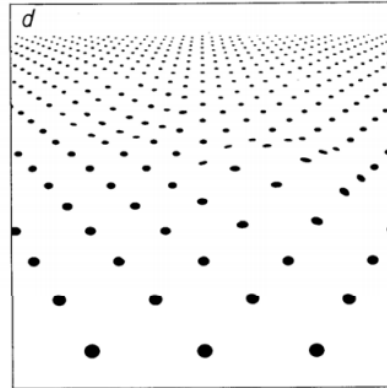
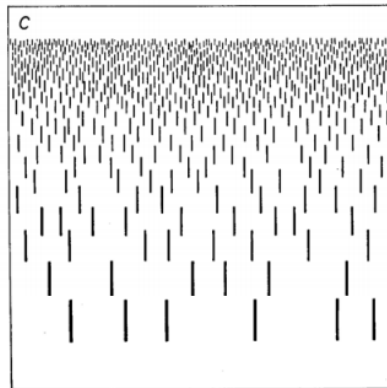
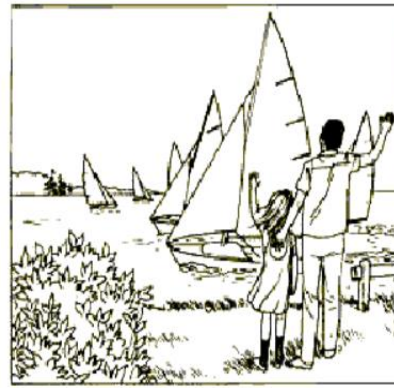
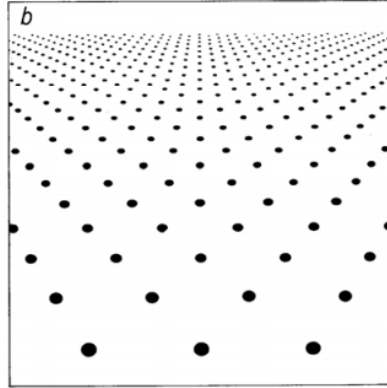
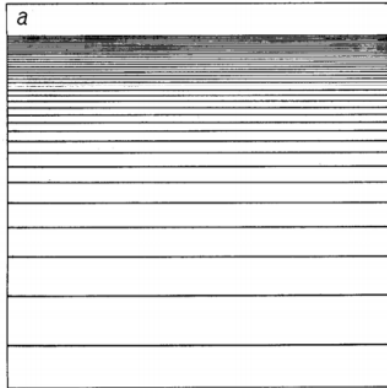


# The 'Necker cube'

- demonstrates that we automatically construct a 3-D world from a two-dimensional image
- an ambiguous figure – yellow in front of blue, or vice versa?
- either is possible, but at any given moment, *must* be one or the other (not both)
- [hollow faces](#) illusion:



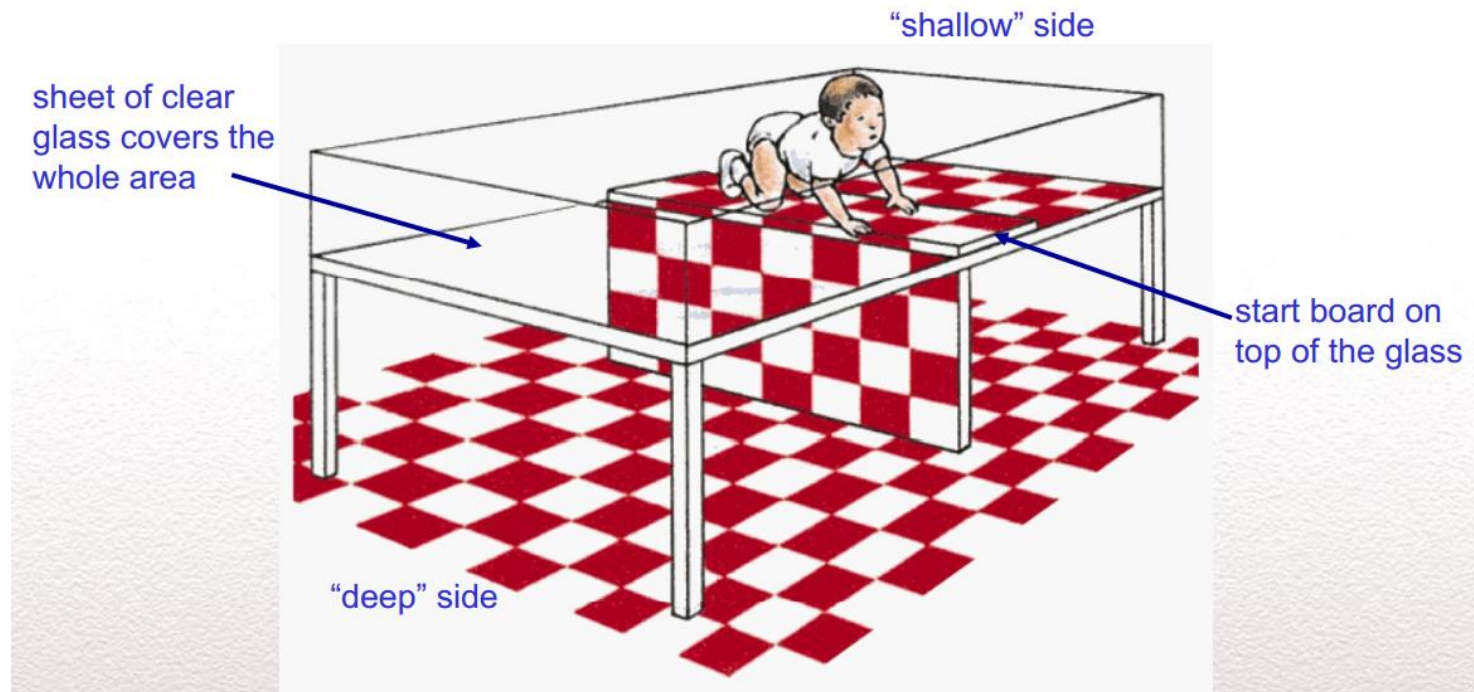
# Cues for depth perception



- texture gradient
- relative size
- superposition
- height in field

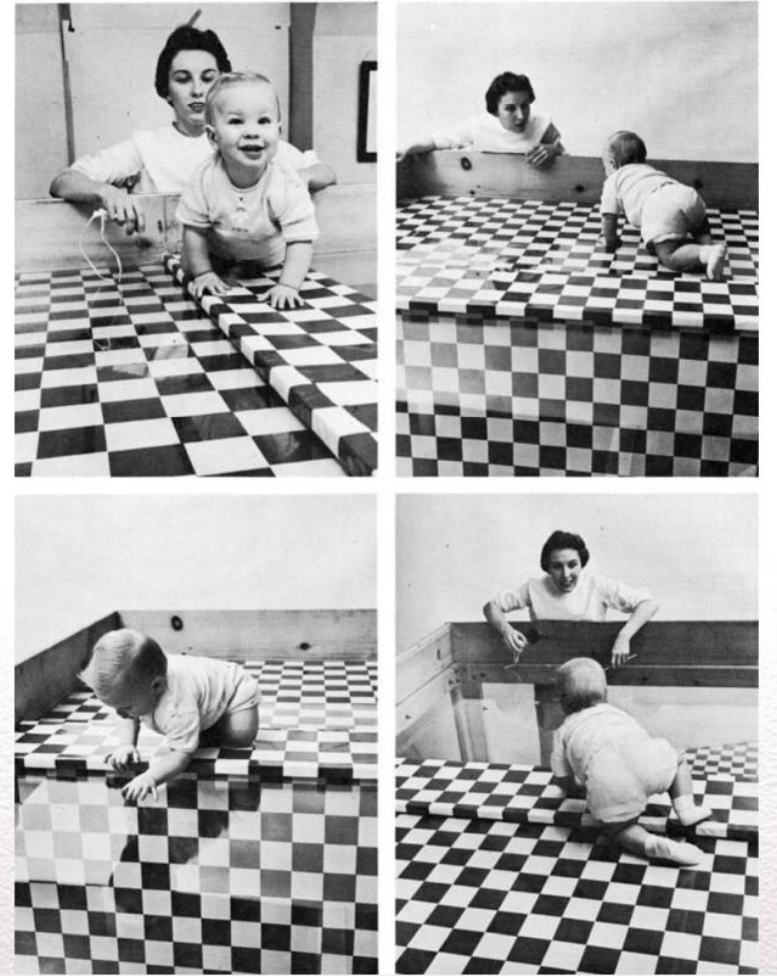
# Is depth perception innate? The “visual cliff”

- Gibson and Walk (1960): apparatus for testing whether animals or infants are able to interpret these kinds of cues to depth

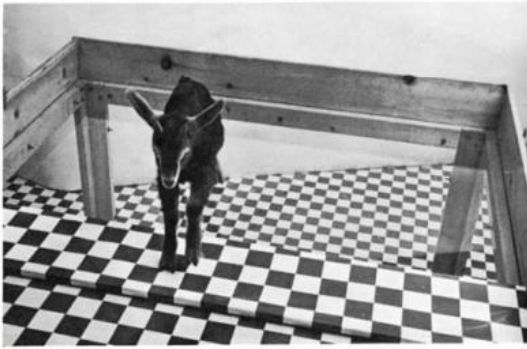
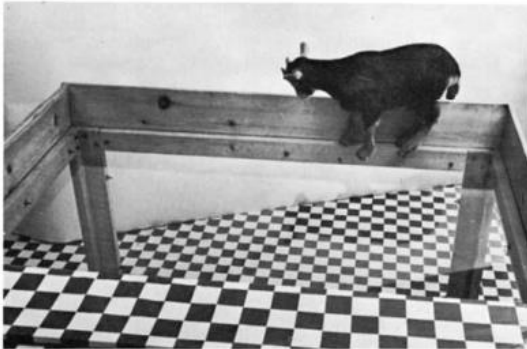


# The “visual cliff”

- Gibson & Walk (1960) tested 36 infants old enough to crawl (6 – 14 mths)
- 27 were willing to move onto the shallow side, but only 3 onto the deep side



# The “visual cliff”



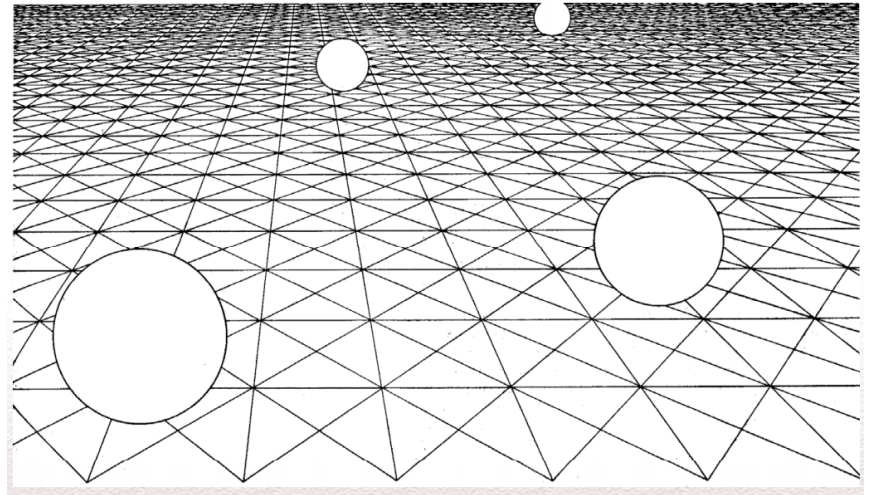
- for some animals, depth perception appears to be innate - when placed on the deep side, a one-day old goat jumps to the safety of the start board

# Perceptual constancy

- visual images are *ambiguous* in many aspects – e.g.:
  - size vs. distance
  - shape vs. rotation/orientation
  - colour/brightness vs. illumination
- Our brains resolve this ambiguity via implicit assumption that objects are stable and unchanging (“perceptual constancy”)
  - size, shape, colour, brightness constancy
- The brain automatically computes “true” size, shape etc. of objects by taking into account viewing conditions

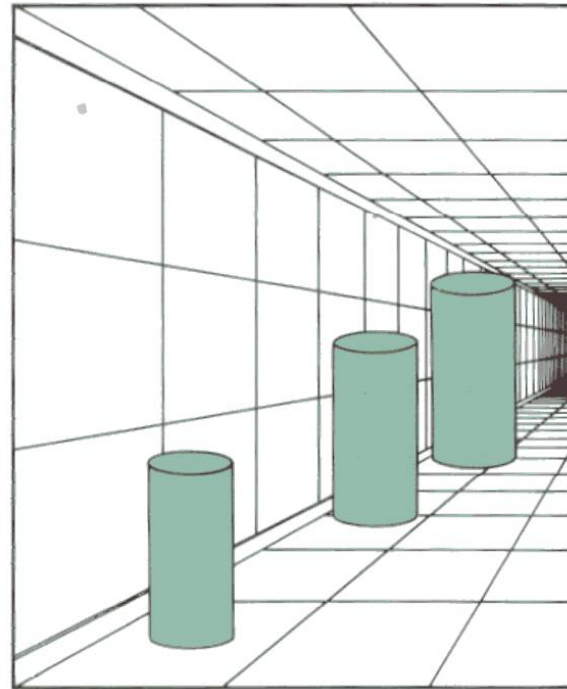


# Objects the same (real) size seen at different distances



# Objects with the same image size at different apparent distances

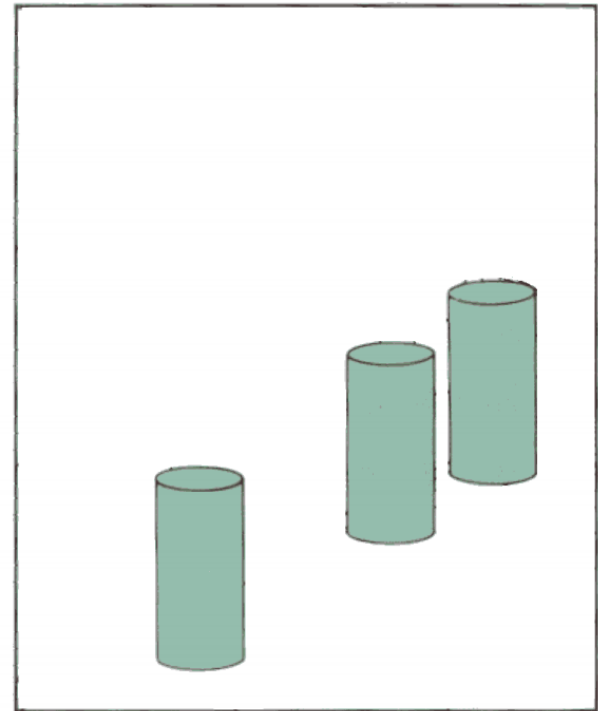
...produce a visual illusion!





# Objects with the same (image) size at different distances

- judgments of image size are influenced by perceptual processes that produce awareness of “real” size

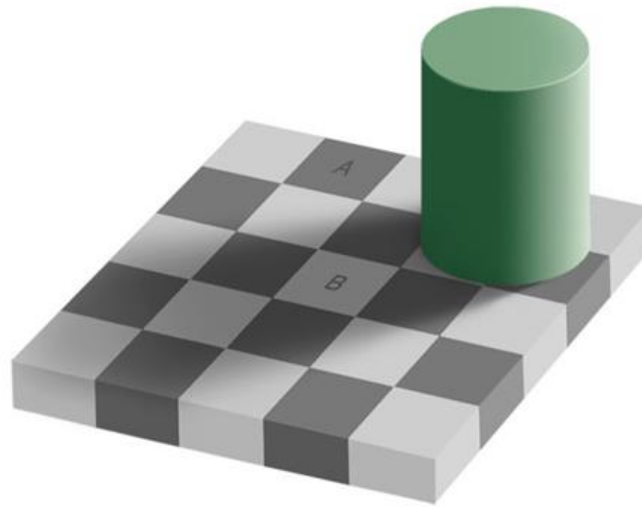


## Size/distance illusion in a real world scene



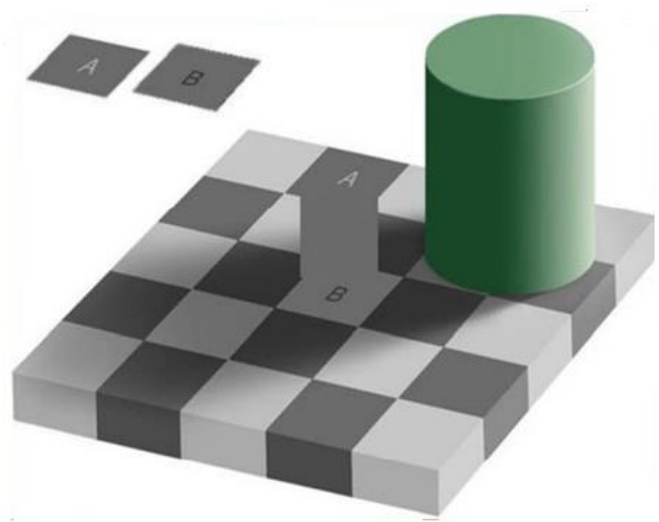
# Brightness constancy

- when painting a picture of this scene, what shades of grey would I need for squares A and B?



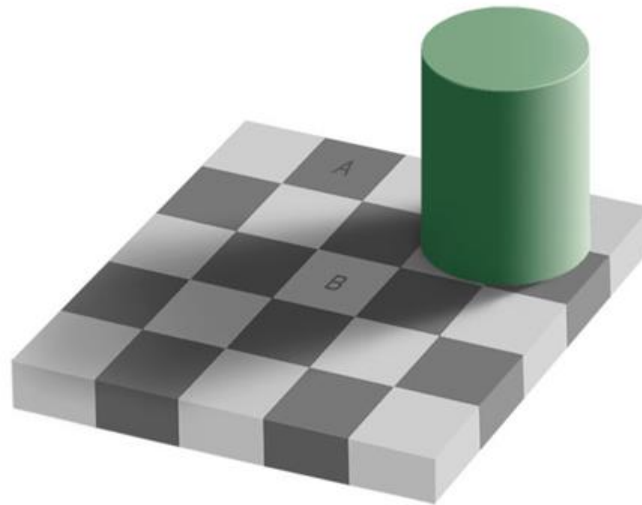
# Brightness constancy

- when painting a picture of this scene, what shades of grey would I need for squares A and B?



# Brightness constancy

- when we view this scene, we automatically compensate for differences in illumination from an unseen light source (somewhere off to the right of the picture)



# Perceptual constancy

- perceptual mechanisms are designed to provide awareness of physical reality, rather than appearance
- cues extracted from the scene provide information about viewing conditions and observer's relation to the object
- perceptual experience is shaped by this interpretation - observers do not have direct access to sensory data

# Summary and key points

- Sensation - involves conversion of physical energy into signals in sensory neurons (“transduction”)
  - requires specialised sense organs, containing receptors which convert physical energy to neural signals
- Perception - perceptual processing is based not on passive reception of sensory information from an external world, but rather involves interpretation
- Interpretation is based on:
  - innate principles of perceptual organisation
  - procedures acquired through perceptual learning
  - memory (stored knowledge)
- Perceptual experience (i.e. what we see) is shaped by these computational processes – can produce powerful “visual illusions”

# References

Gibson, E. J., & Walk, R. D. (1960). *The "visual cliff"*. WH Freeman Company.

Hubel, D. H., & Wiesel, T. N. (1962). Receptive fields, binocular interaction and functional architecture in the cat's visual cortex. *The Journal of Physiology*, 160, 106.

Wertheimer, M. (1923). Untersuchungen zur Lehre von der Gestalt. II. *Psychological Research*, 4, 301-350.