COMS20001 lecture: week #19

- Question:
 - 1. what is this part of the unit about, and
 - 2. how does it relate to the rest of the unit?
- Answer: it should be obvious that

concurrent systems \supset computer networks \Rightarrow concurrency \cup communication

but beyond this, we need a motivating example ...

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PDP-11 \leftrightarrow Teletype 33 (1)

- ► TIA-232-F [6] specifies a communication medium used to connect
 - ▶ a **Data Terminal Equipment (DTE)** or *master* device, e.g., a workstation, with
 - a **Data Communication Equipment (DCE)** or *slave* device, e.g., a MODEM and hence provide a (more abstract) **communication channel** (or **link**).
- Question: what terms can you think of to characterise this channel?

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 - and hence provide a (more abstract) **communication channel** (or **link**).
- ▶ Question: what terms can you think of to characterise this channel?
- ► (Incomplete) answer:
 - serial (i.e., can communicate 1-bit per-unit of time),
 - (upto) full duplex (i.e., communication can occur simultaneously in both directions),
 - synchronous or asynchronous (i.e., can require or avoid shared control wrt. timing),
 - direct (i.e., there are no intermediate devices),
 - unicast (i.e., a single device recieves any transmitted data),
 - ٠..

PDP-11 ↔ Teletype 33 (2) – Communication medium

- ▶ The medium itself is formed from
 - 1. an interface (from a choice of two)





PDP-11 ↔ Teletype 33 (2) – Communication medium

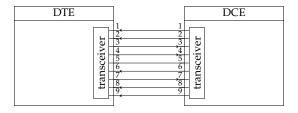
► The medium itself is formed from

2. a pin assignment which dictates how the interface is used

Class	Purpose	Mnemonic	Direction	9-pin	25-pin
Electrical properties	Reference (or signal) ground	GND	common	5	7
	Protective (or shield) ground	PG	common		1
Primary communication channel	Transmitted Data	TxD	$DTE \rightarrow DCE$	3	2
	Recieved Data	RxD	$DCE \rightarrow DTE$	2	3
	Request To Send	RTS	$DTE \rightarrow DCE$	7	4
	Clear To Send	CTS	$DCE \rightarrow DTE$	8	5
Secondary communication channel	Secondary Transmitted Data	STxD	$DTE \rightarrow DCE$		14
	Secondary Recieved Data	SRxD	$DCE \rightarrow DTE$		16
	Secondary Request To Send	SRTS	$DTE \rightarrow DCE$	İ	19
	Secondary Clear To Send	SCTS	$DCE \rightarrow DTE$		13
Control and status	Data Set Ready	DSR	$DCE \rightarrow DTE$	6	6
	Data Terminal Ready	DTR	$DTE \rightarrow DCE$	4	20
	Carrier Detect	CD	$DCE \rightarrow DTE$	1	8
	Secondary Carrier Detect	SCD	$DCE \rightarrow DTE$		12
	Ring Indicator	RI	$DCE \rightarrow DTE$	9	22
	Data Signal Rate		$DTE \rightarrow DCE$		23
Timing	External Transmitter Clock	ETC	$DTE \rightarrow DCE$		24
	Transmitter Clock	TC	$DCE \rightarrow DTE$		15
	Reciever Clock	RC	$DCE \rightarrow DTE$		17
Test and debug	Local Loop-back	LL	$DTE \rightarrow DCE$		18
	Remote Loop-back	RL	$DTE \rightarrow DCE$		21
	Test Mode 1	TM	$DCE \rightarrow DTE$		25

PDP-11 ↔ Teletype 33 (3) – Communication medium

▶ The medium is managed using some form of **transceiver**, i.e.,



- Example: depending on the context, either end-point might
 - rely on Universal Asynchronous Receiver/Transmitter (UART) hardware to provide a higher-level interface, or
- directly interface with low-level GPIO pins, ensuring correct voltage levels and timing in software (cf. bit-banging).

PDP-11 ↔ Teletype 33 (4) – Communication protocol Low-level protocol

- ► Fact: TIA-232-F does *not* define a **communication protocol** ...
- ... the ~ 100 year old protocol we *still* use actually stems from the design of electronic typewriters (cf. teletype):

Quote

In printing telegraphy, the method of selective signaling which consists in operating a transmitter solely under local control to impart to a line character signals of uniform length and each comprising the same number of positive or negative impulses in quick succession and without perceptible spacing intervals between the impulses, initiating the operation of a selecting receiver switch mechanism in response to transmitted impulses at the beginning of each signal, timing the operation of the switch mechanism in synchronism with the transmitted impulses of each signal independently of the line circuit land restoring the same to a condition of rest at the completion of each signal.

- Krum [7, Claim 1], 1918 (!)

Translation:

- all (binary) data transmitted is encoded as discrete voltage levels (cf. "positive and negative impulses"),
- 2. the data (cf. "character") has start and end markers added st. the receiver knows when transmission occurs,
- 3. this allows asynchronous communication (cf. "local control").



▶ So ... the DTE and DCE pre-agree a set of **signalling parameters**, e.g.,

```
baud rate ∈ {110,300,600,1200,2400,4800,9600,19200,...}
```

number of data bits $\in \{5, 6, 7, 8\}$

parity type $\in \{\text{none}, \text{odd}, \text{even}\}$

number of stop bits $\in \{1, 1.5, 2\}$

and, as such, agree how data is framed, i.e.,

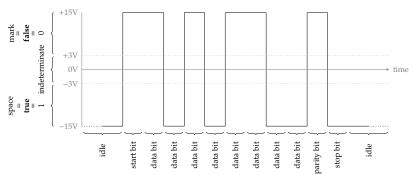
$$D \mapsto F = \text{start bit } || D || \text{ parity bit } || \text{ stop bits}$$

where

- ▶ the **baud rate** the number of transitions per-second of a given signal (e.g., TxD or RxD),
- the start bit mark the start of a frame,
- the stop bit(s) mark the end of a frame,
- the data bits are the data, and
- the parity type supports (optional) error detection.

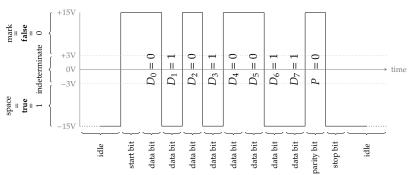
PDP-11 ↔ Teletype 33 (6) – Communication protocol

Low-level protocol



PDP-11 ↔ Teletype 33 (6) – Communication protocol

Low-level protocol



▶ We have

$$D = \langle D_0, D_1, D_2, D_3, D_4, D_5, D_6, D_7 \rangle = \langle 0, 1, 0, 1, 0, 0, 1, 1 \rangle \mapsto 202_{(10)}$$

noting that

$$\left(\bigoplus_{i=0}^{i<8} D_i\right) \oplus P = 0$$

which we come back to later ...

PDP-11 ↔ Teletype 33 (7) – Communication protocol High(er)-level protocol

- ► TIA-232-F supports (at least) two forms of **flow control**, namely
 - 1. hardware-based (RTS/CTS), and
 - 2. software-based (XON/XOFF)

which you can think of as managing workload of the end-points.

- ► Example:
 - ▶ imagine the DTE is a (fast) workstation, and the DCE is a (slower) printer,
 - if the DCE cannot process the data transmitted fast enough, it will need to either buffer or discard data ...
 - ... *or* it could ask the DTE to slow down, or stop until it has caught up.

PDP-11 ↔ Teletype 33 (8) – Communication protocol High(er)-level protocol

► RTS/CTS:

- When the transmitter is ready to transmit, it sets RTS; the receiver primes itself to monitor data signals.
- ▶ When the receiver is ready to receive, it sets CTS; the transmitter commences transmission.
- ► If either end-point is unable or unwilling to continue, it clears the associated control signal (i.e., RTS or CTS) so the other end-point stops.

PDP-11 ↔ Teletype 33 (8) – Communication protocol High(er)-level protocol

XON/XOFF:

Define two special symbols, e.g., with ASCII

$$XON = 19_{(10)} = 13_{(16)} \mapsto Ctrl - S$$

 $XOFF = 17_{(10)} = 11_{(16)} \mapsto Ctrl - Q$

articulated as "transmit on" and "transmit off".

- When the receiver is unable to accept more symbols, it sends the XOFF symbol; transmitter suspends transmission.
- When the receiver is able to accept more symbols, it sends the XON symbol; transmitter resumes transmission.

Based on some simple coding theory, i.e.,

Definition (parity)

The **parity** of an *n*-bit sequence *X* is defined as

$$\mathcal{P}(X) = \sum_{i=0}^{i < n} X_i \pmod{2} = \bigoplus_{i=0}^{i < n} X_i,$$

st. *X* has **even parity** (resp. **odd parity**) if $\mathcal{P}(X) = 0$ (resp. $\mathcal{P}(X) = 1$).

Definition (parity code)

An even (resp. odd) **parity code** appends a **parity bit** P to some sequence X st. $X \parallel P$ has even (resp. odd) parity:

even parity
$$\begin{cases} \mathcal{P}(X) = 0 & \Rightarrow \quad P = 0 & \rightsquigarrow \quad \mathcal{P}(X \parallel P) = 0 \\ \mathcal{P}(X) = 1 & \Rightarrow \quad P = 1 & \rightsquigarrow \quad \mathcal{P}(X \parallel P) = 0 \end{cases}$$

$$\text{odd parity} \quad \left\{ \begin{array}{ll} \mathcal{P}(X) = 0 & \Rightarrow & P = 1 \\ \mathcal{P}(X) = 1 & \Rightarrow & P = 0 \end{array} \right. \begin{array}{ll} \mathcal{P}(X \parallel P) = 1 \\ \mathcal{P}(X \parallel P) = 1 \end{array}$$

a (limited) form of error detection is possible

- the transmitter computes $\mathcal{P}(D)$, then appends an appropriate P before transmitting $D \parallel P$,
- the receiver recomputes $\mathcal{P}(D \parallel P)$ and signals an error if this does *not* match expectation.

► Take away points:

- TIA-232-F is a (very) specific example of more general concepts and requirements: the goal is a clear, general understanding.
- Put simply, we want to understand how we can communicate data reliably and efficiently via a computer network ...

- ► Remit:
 - understand a simple(ish) computer network



wrt. support for a HTTP transaction, but

- limit the detail and volume of coverage to fit allocated time.
- ▶ Why?!
 - 1. some of you may
 - develop network-related hardware or software, or
 - work in network operations,
 - 2. most of you will develop hardware or software that depends on a network, and
 - 3. many of the concepts and techniques generalise.

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- Wikipedia: Asynchronous serial communication. http://en.wikipedia.org/wiki/Asynchronous_start-stop.
- [2] Wikipedia: Flow control. http://en.wikipedia.org/wiki/Flow_control_(data).
- [3] Wikipedia: Parity bit. http://en.wikipedia.org/wiki/Parity_bit.
- [4] Wikipedia: Serial port. http://en.wikipedia.org/wiki/Serial_port.
- [5] Wikipedia: Teleprinter. http://en.wikipedia.org/wiki/Teletypewriter.
- [6] Interface between data terminal equipment and data circuit terminating equipment employing serial binary data interchange. Telecommunications Industry Association (TIA) TIA-232-F, 2002. http://www.tiaonline.org/standards/.
- [7] H.L. Krum.

Electric selective system.

U.S. Patent 1,286,351.

http://www.google.com/patents/US1286351.