Data Structures and Algorithms – COMS21103

2015/2016

Dynamic Search Structures

Self-balancing Trees and Skip Lists

Benjamin Sach





Dynamic Search Structures

A dynamic search structure,

stores a set of elements

Each element x must have a unique key - x.key

The following operations are supported:

INSERT(x, k) - inserts x with key k = x.key

FIND(k) - returns the (unique) element x with x.key = k

(or reports that it doesn't exist)

DELETE(k) - deletes the (unique) element x with x.key = k

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We would also like it to support (among others):

 $\frac{\text{PREDECESSOR}(k) - \text{returns the (unique) element } x}{\text{with the largest key such that } x.\text{key} < k}$

 $\mathsf{RangeFind}(k_1,k_2)$ - returns every element x with $k_1\leqslant x.\mathsf{key}\leqslant k_2$



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but they aren't all efficient

Let n denote the number of elements stored in the structure

- our goal is to implement a structure with operations which scale well as n grows



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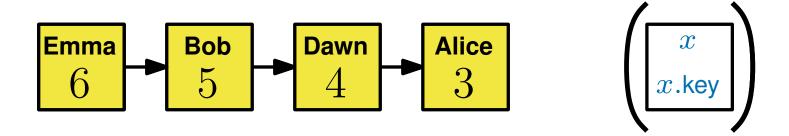
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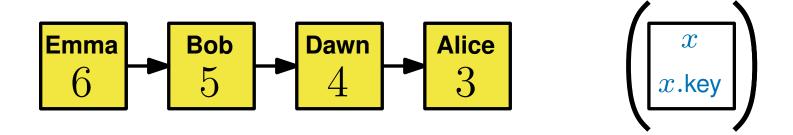
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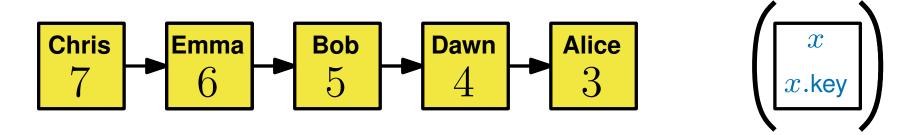
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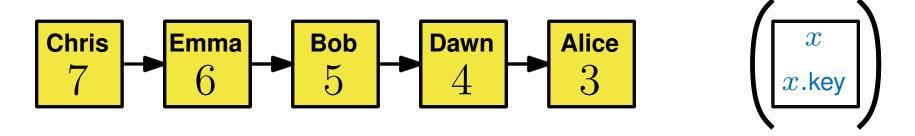
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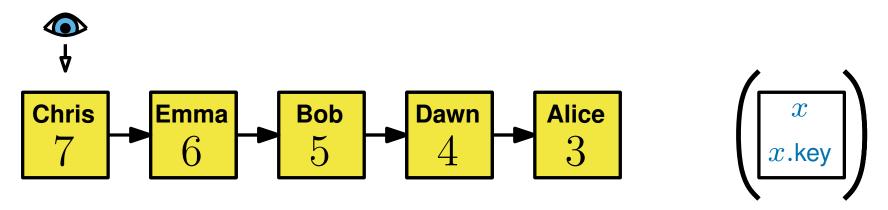
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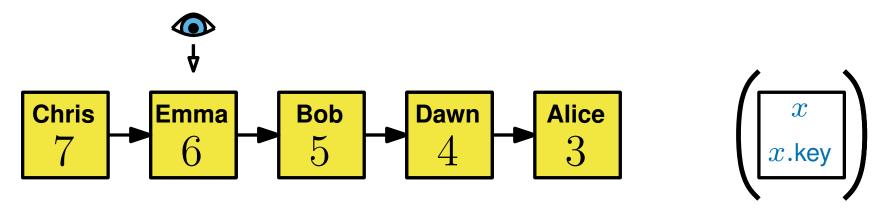
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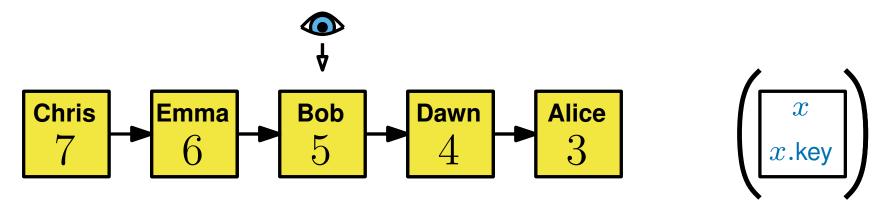
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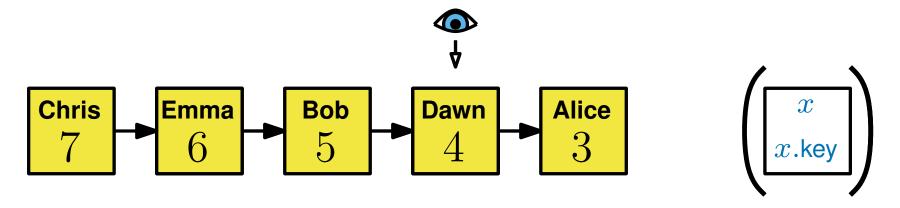
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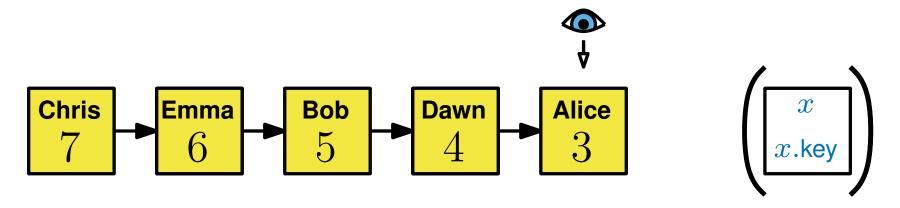
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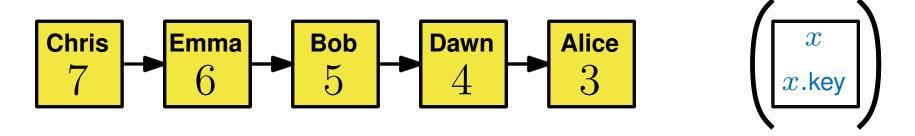
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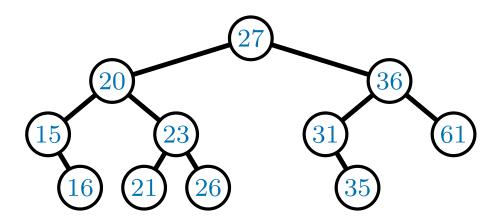
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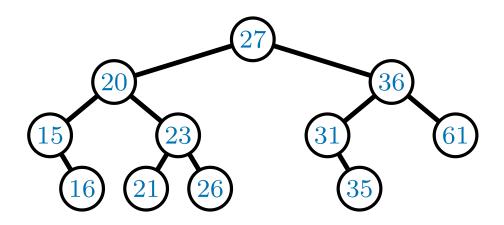






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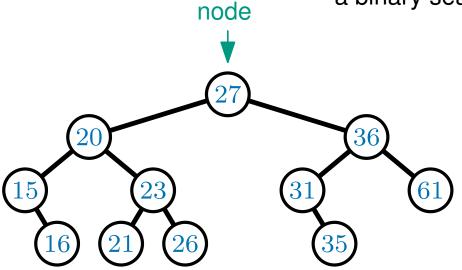
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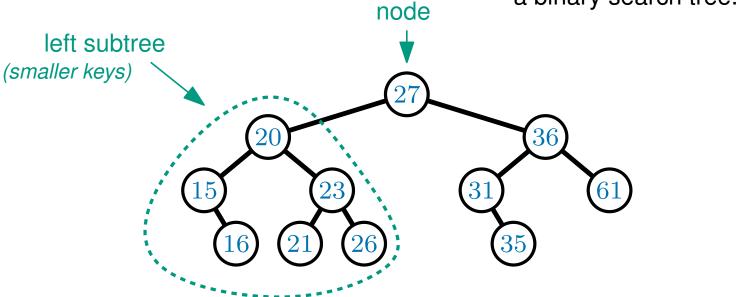
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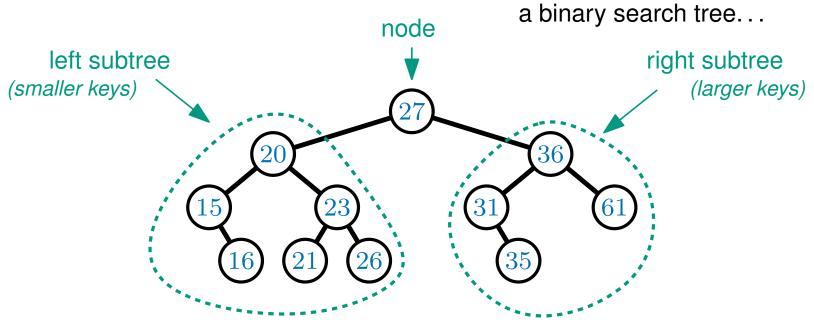


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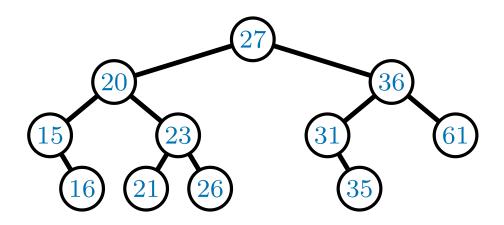


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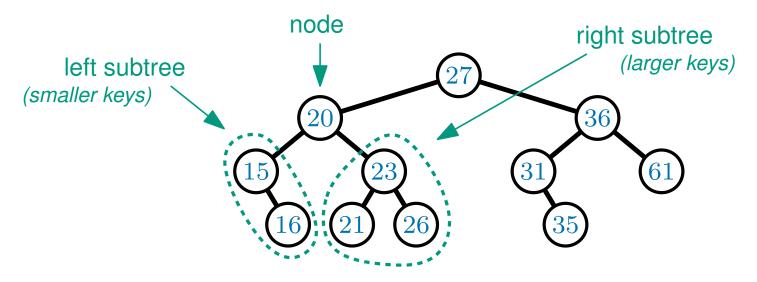


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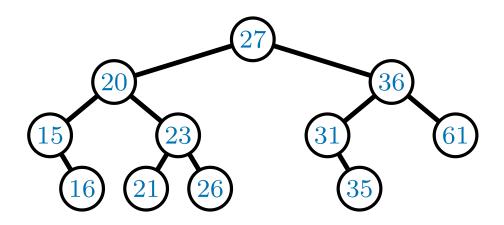


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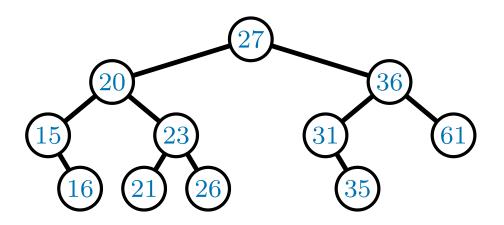


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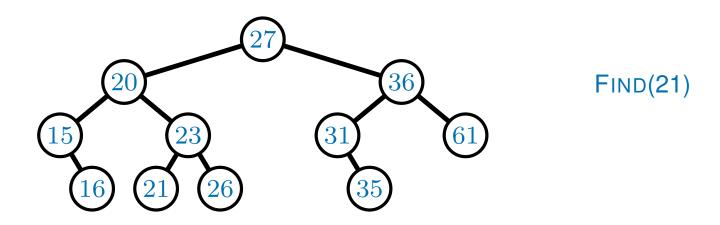
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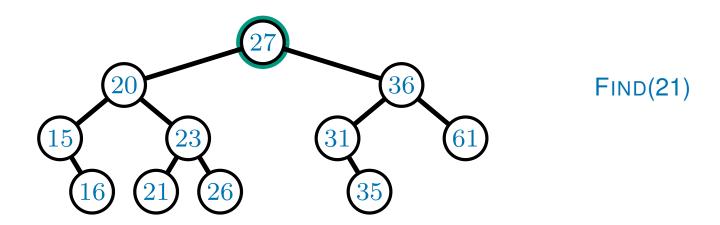
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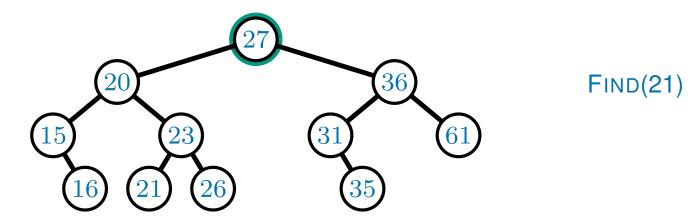
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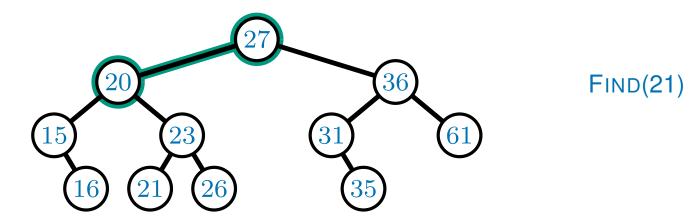
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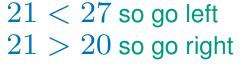
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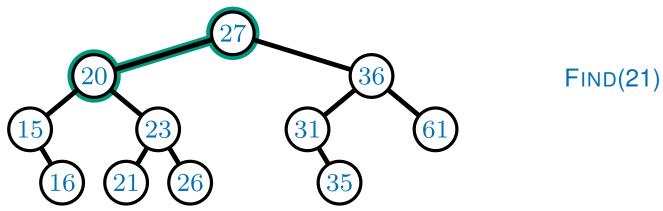
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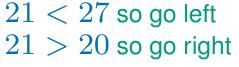
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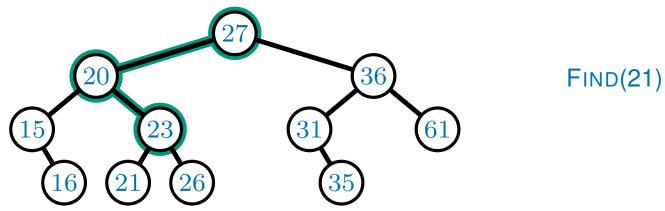
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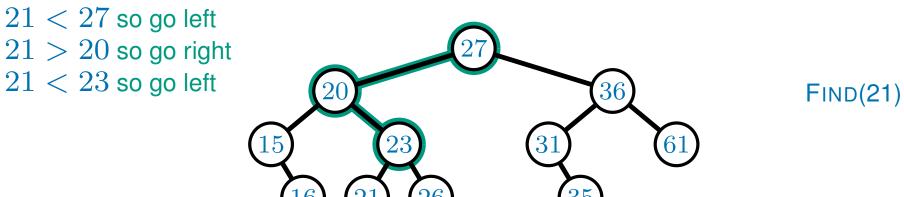
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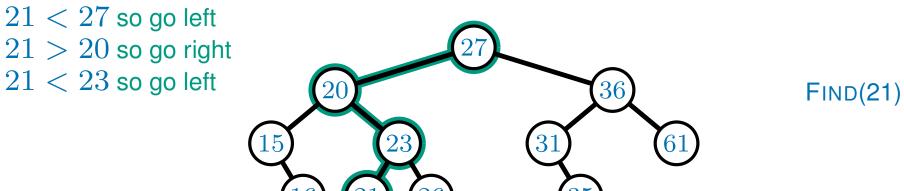
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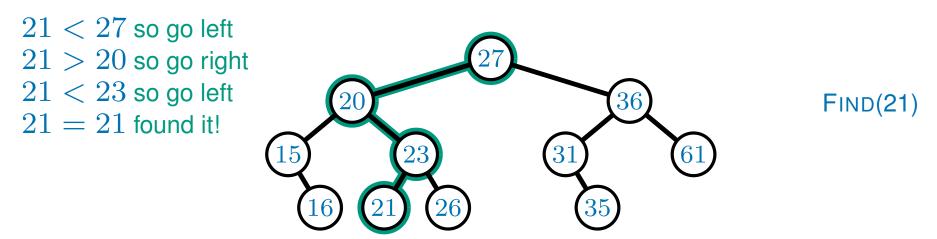
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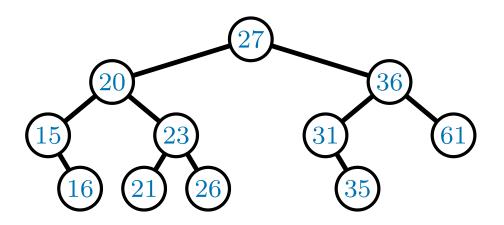
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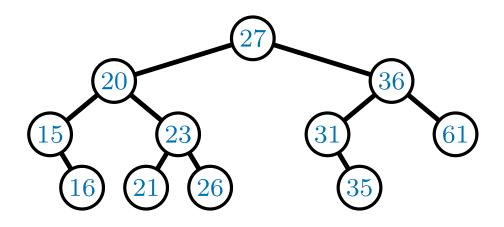
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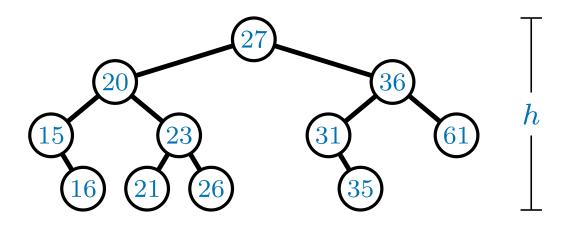
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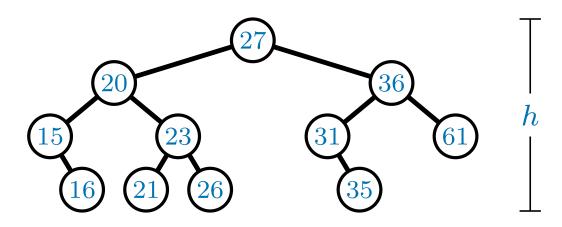
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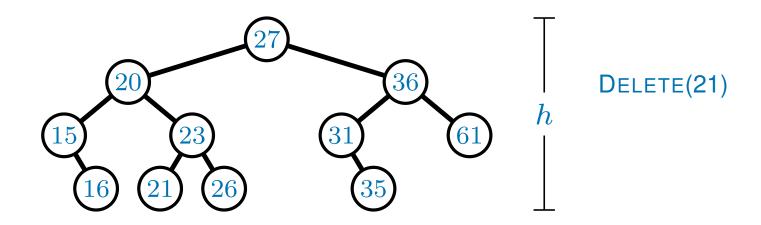
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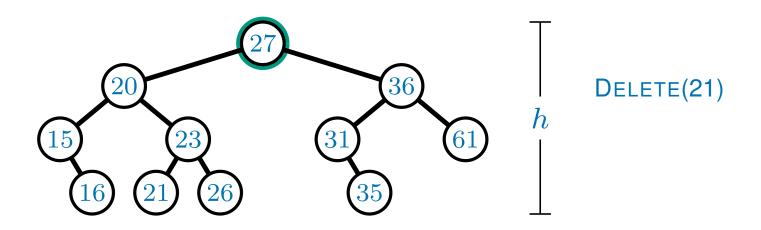
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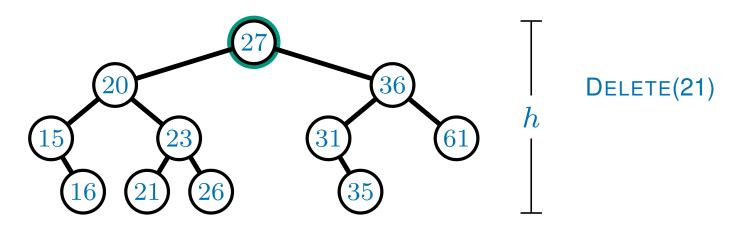
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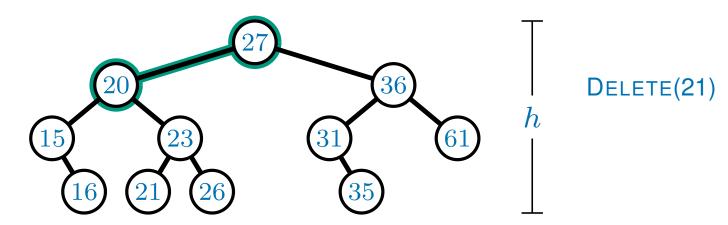
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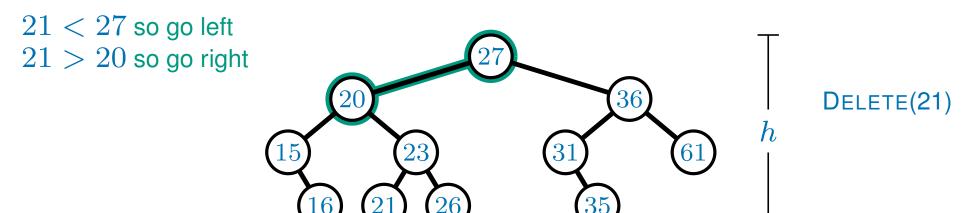
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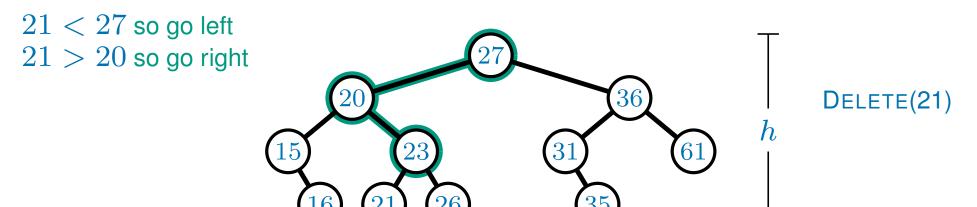
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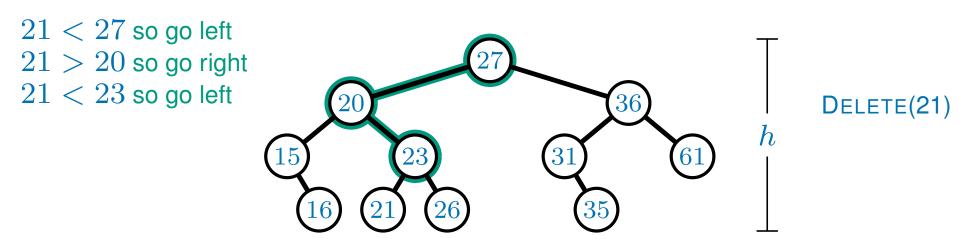
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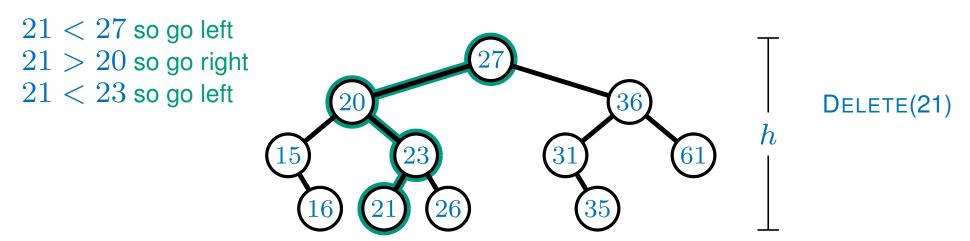
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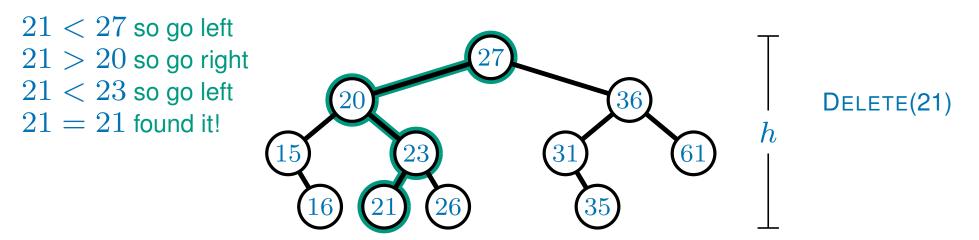
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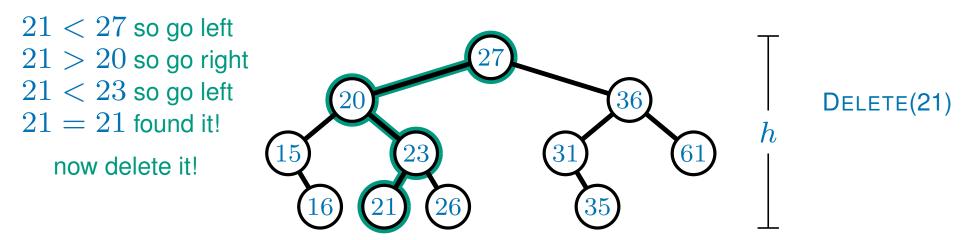
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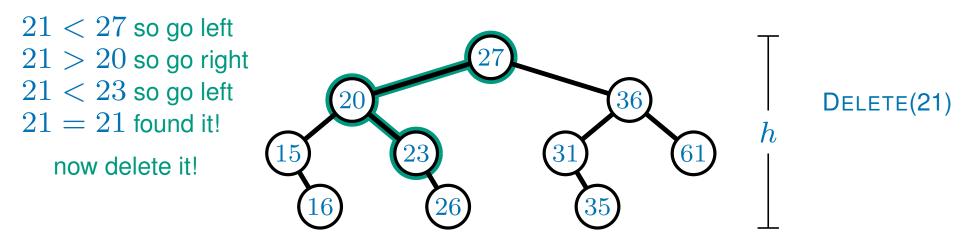
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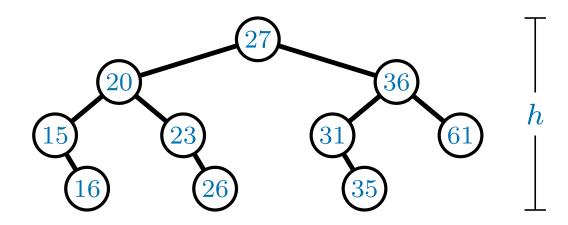
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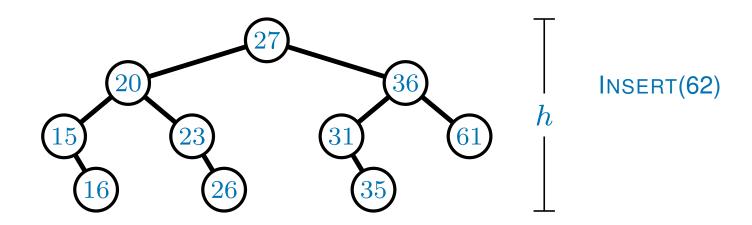
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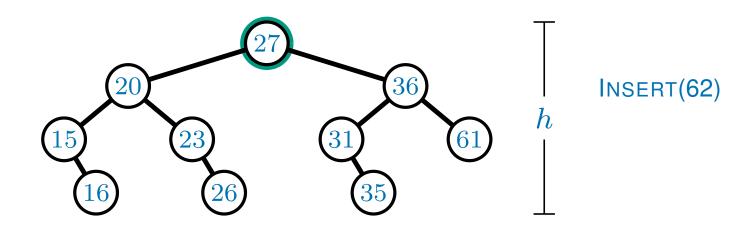
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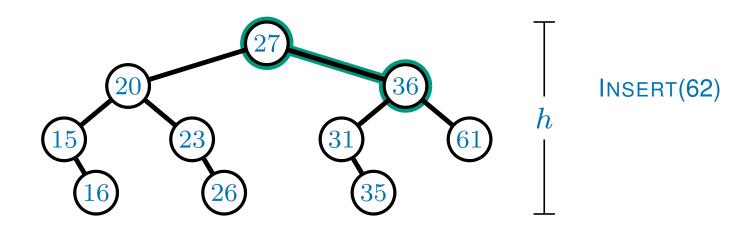
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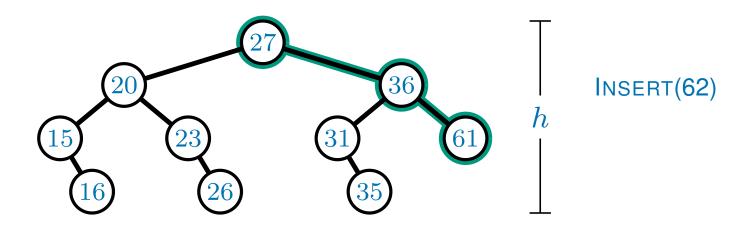
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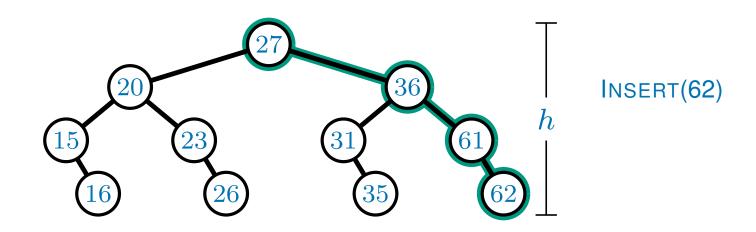
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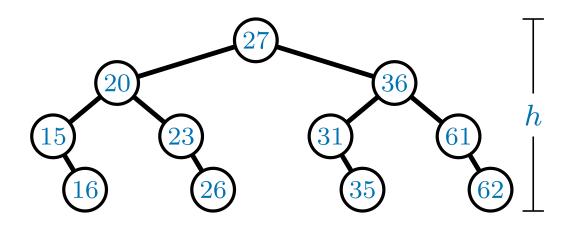
We perform a FIND operation by following a path from the root...

this takes O(h) time - where h is the height



A classic choice for a dynamic search structure is a binary search tree...





Recall that in a binary search tree, for any node

- all the nodes in the left subtree have smaller keys
- all the nodes in the right subtree have larger keys

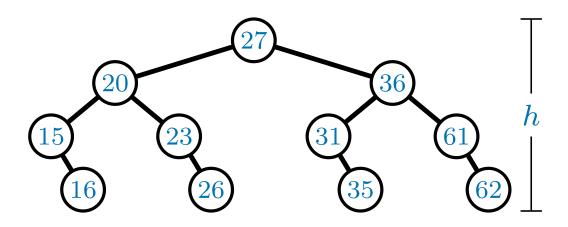
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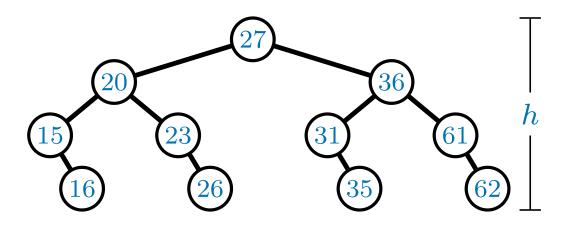






A classic choice for a dynamic search structure is a binary search tree...



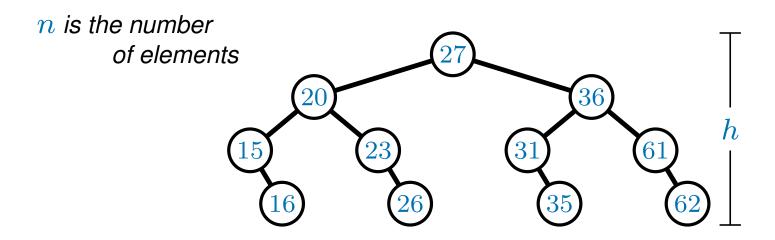


How big is h?



A classic choice for a dynamic search structure is a binary search tree...



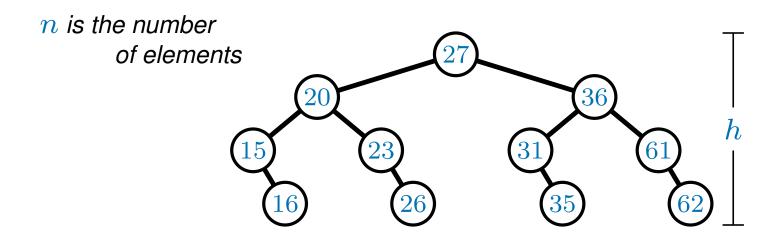


How big is h?



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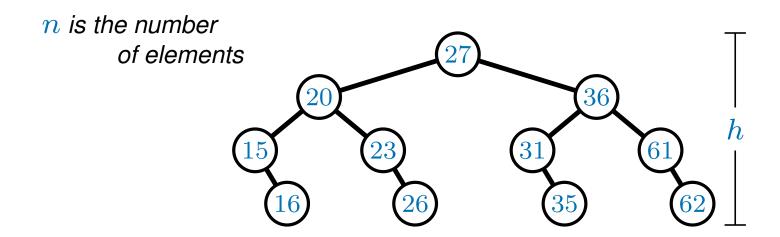
How big is h?

It might be as small as $\log_2 n$ (if the tree is perfectly balanced)



A classic choice for a dynamic search structure is a binary search tree...





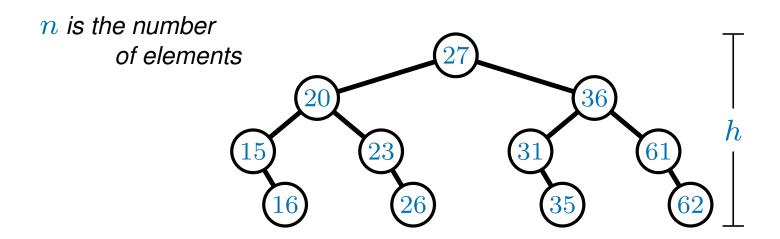
How big is h?

It might be as small as $\log_2 n$ (if the tree is perfectly balanced) but it might be as big as n (if the tree is completely unbalanced)



A classic choice for a dynamic search structure is a binary search tree...





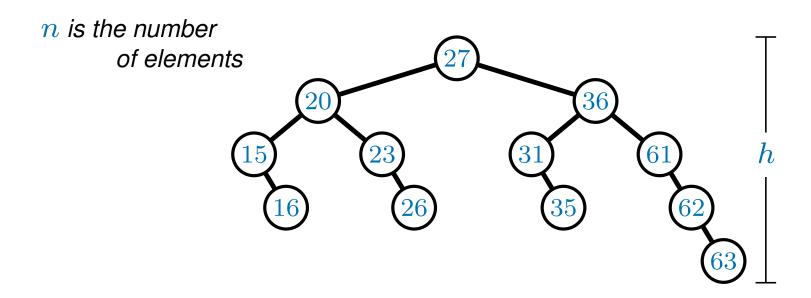
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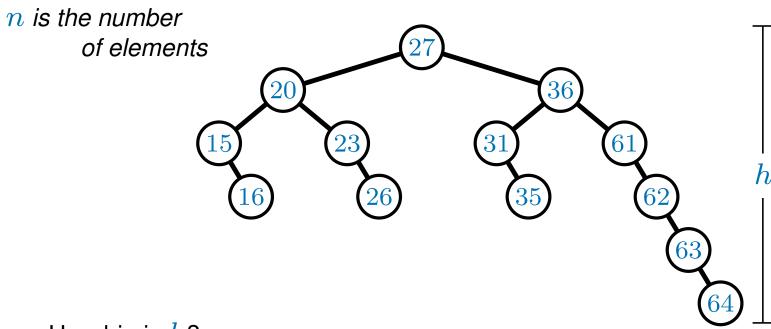
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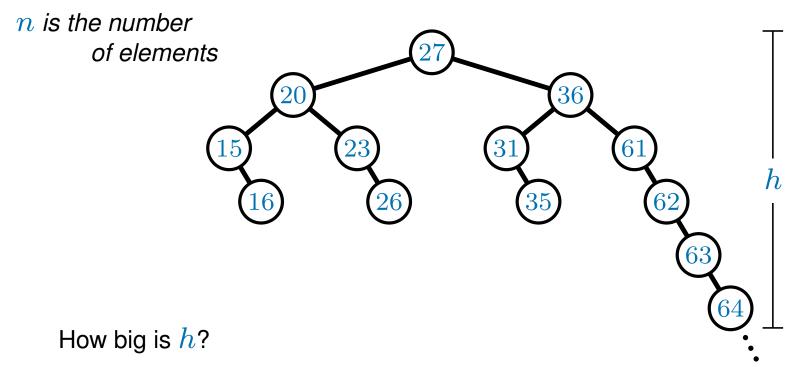
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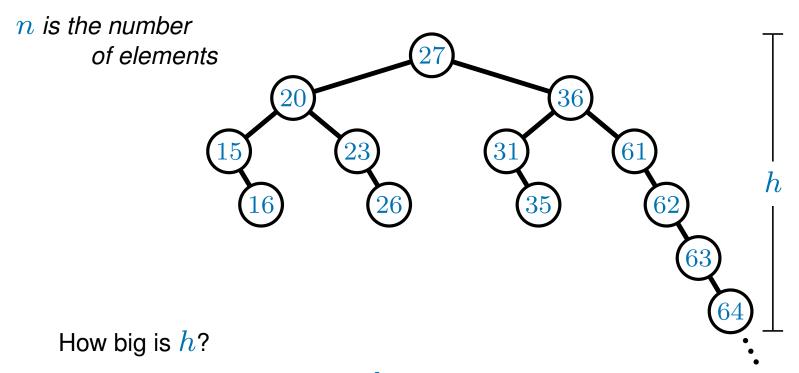


It might be as small as $\log_2 n$ (if the tree is perfectly balanced) but it might be as big as n (if the tree is completely unbalanced)



A classic choice for a dynamic search structure is a binary search tree...





It might be as small as $\log_2 n$ (if the tree is perfectly balanced) but it might be as big as n (if the tree is completely unbalanced)

In particular, each INSERT could increase h by one

how can we overcome this?

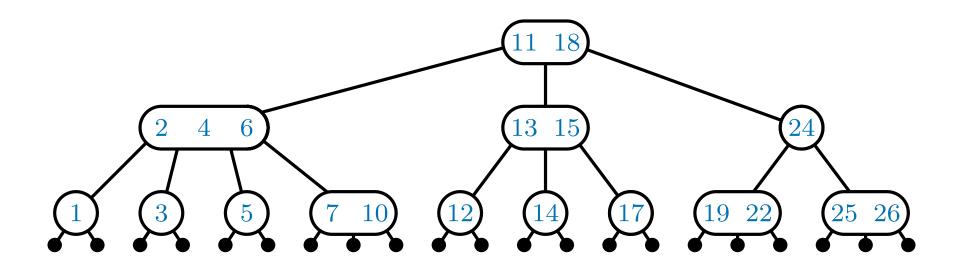


Part one

Self-balancing trees

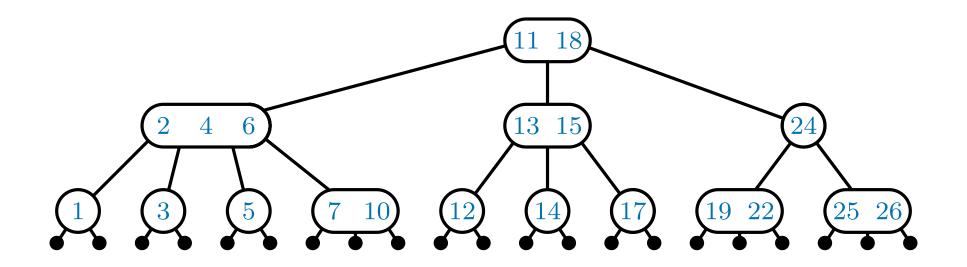
Key idea: Nodes can have between 2 and 4 children $_{(hence\ the\ name)}$

Perfect balance - every path from the root to a leaf has the same length (always, all the time)



Key idea: Nodes can have between 2 and 4 children $_{\it (hence\ the\ name)}$

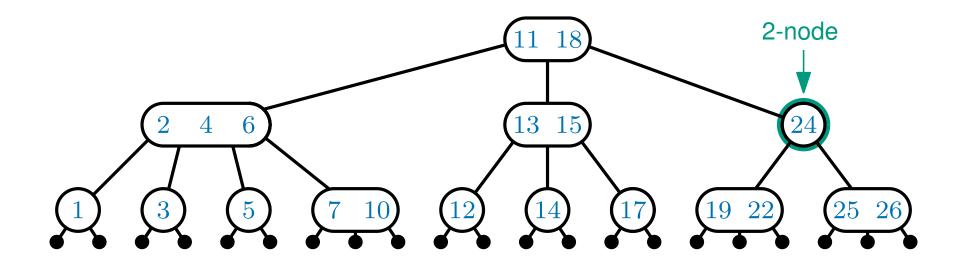
Perfect balance - every path from the root to a leaf has the same length (always, all the time)



2-node: 2 children and 1 key3-node: 3 children and 2 keys4-node: 4 children and 3 keys

Key idea: Nodes can have between 2 and 4 children $_{\it (hence\ the\ name)}$

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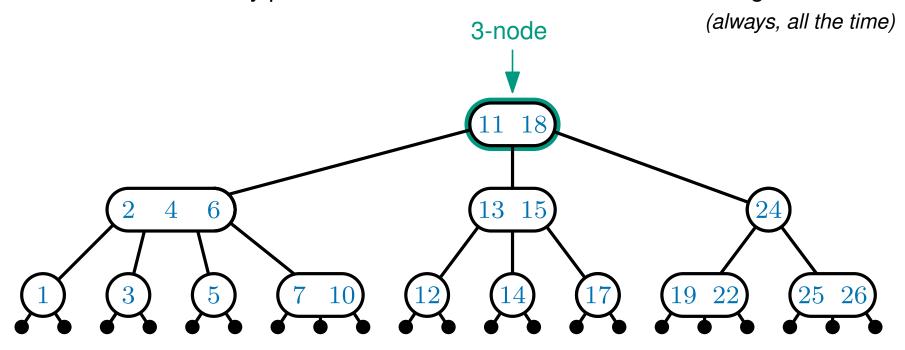


2-node: 2 children and 1 key **3-node:** 3 children and 2 keys

4-node: 4 children and 3 keys

Key idea: Nodes can have between 2 and 4 children $_{\it (hence\ the\ name)}$

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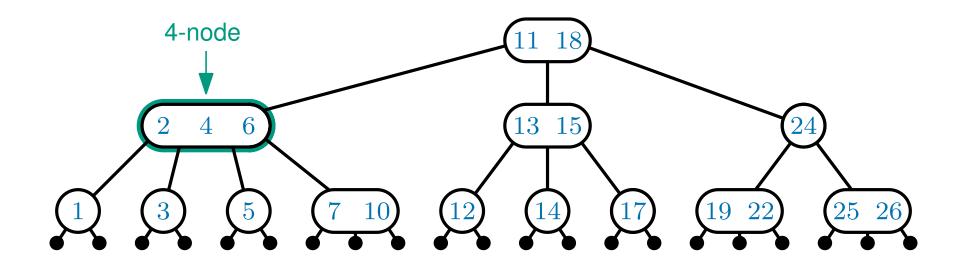
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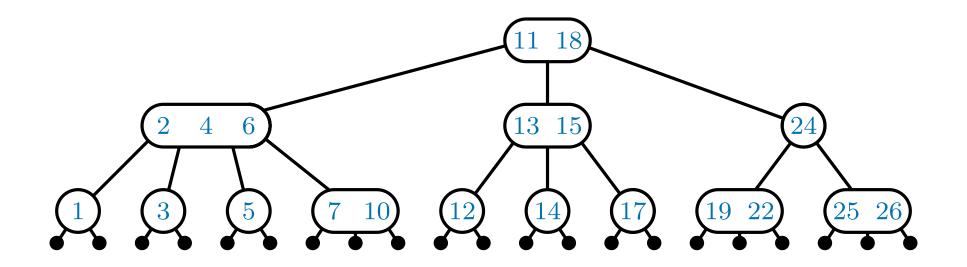
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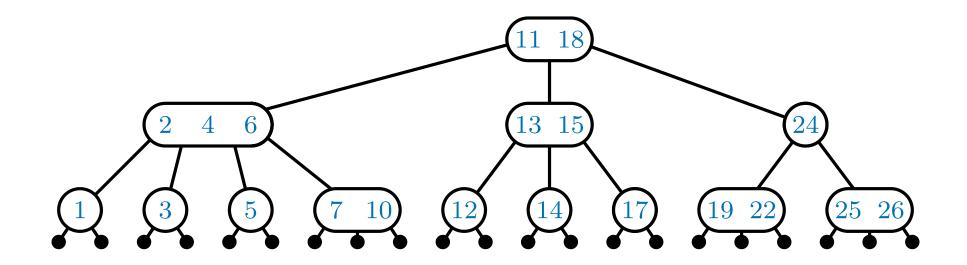


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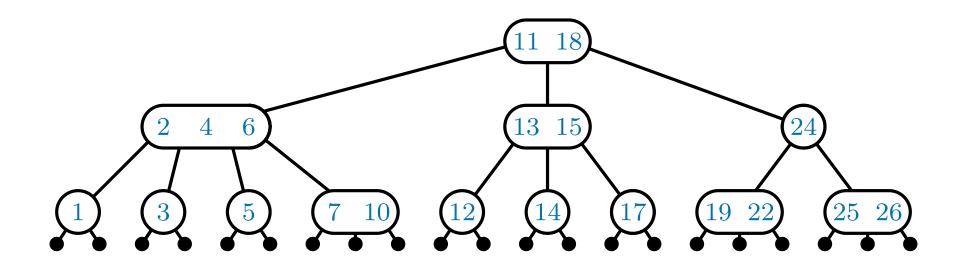
2-node: 2 children and 1 key3-node: 3 children and 2 keys4-node: 4 children and 3 keys

The ● are "dummy leaves" (they don't do or contain anything)



Key idea: Nodes can have between 2 and 4 children $_{(hence\ the\ name)}$

Perfect balance - every path from the root to a leaf has the same length (always, all the time)



2-node: 2 children and 1 key

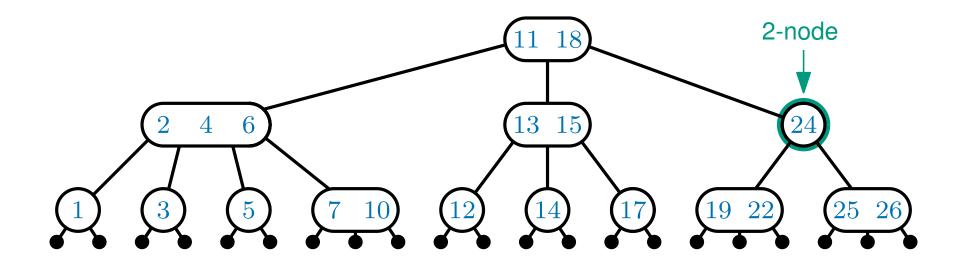
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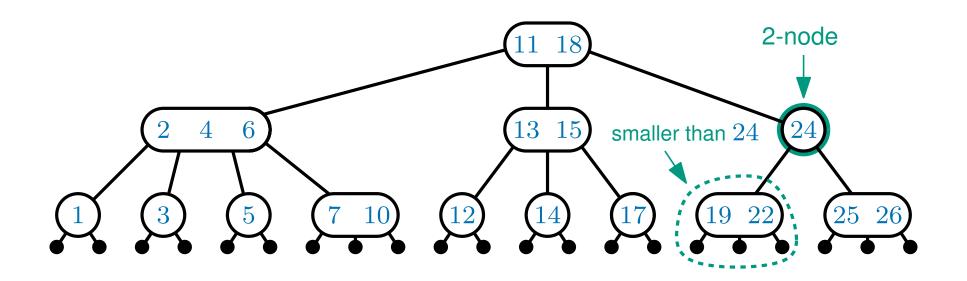
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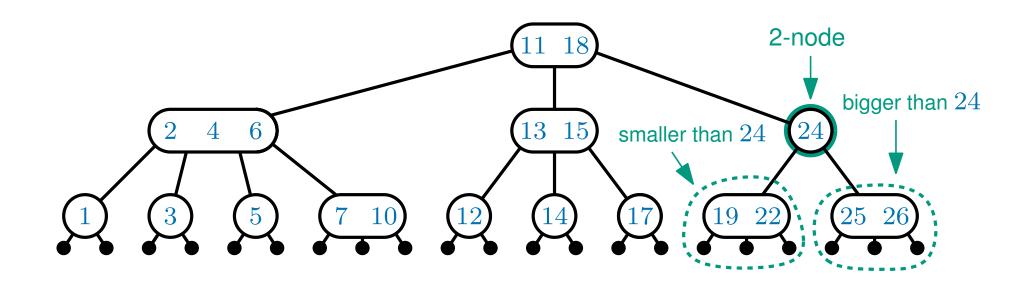
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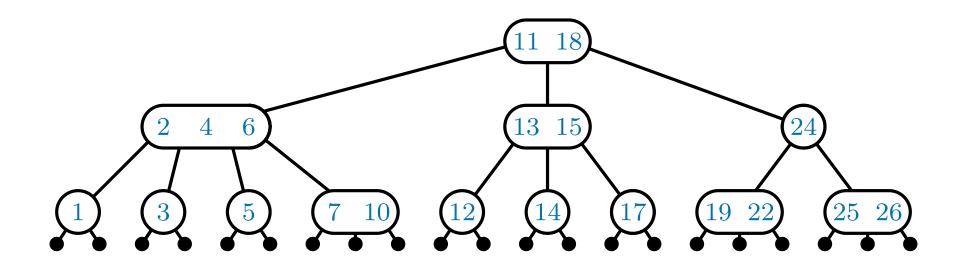
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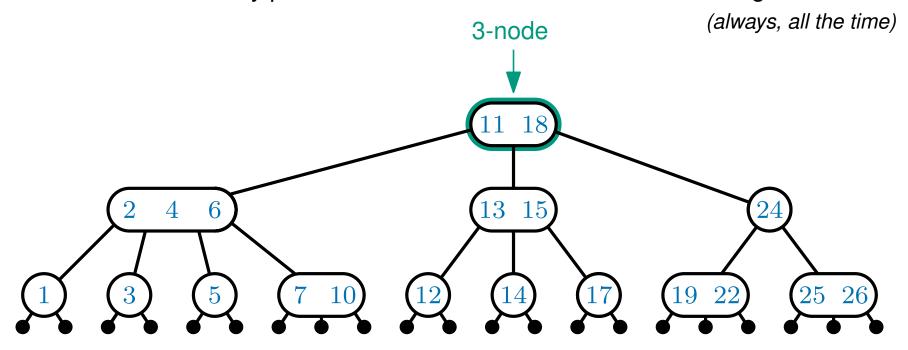
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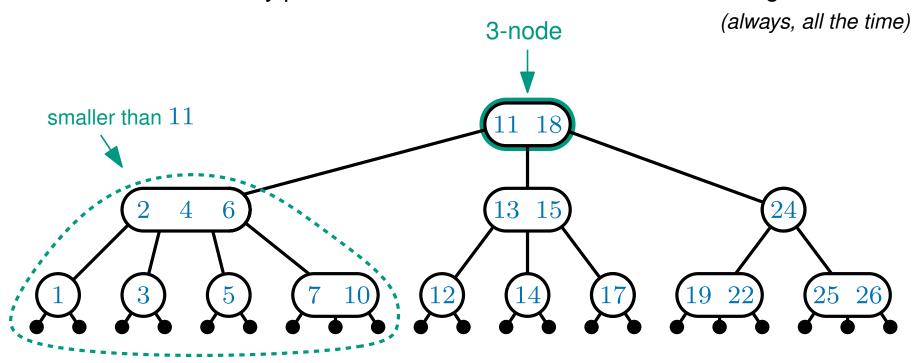
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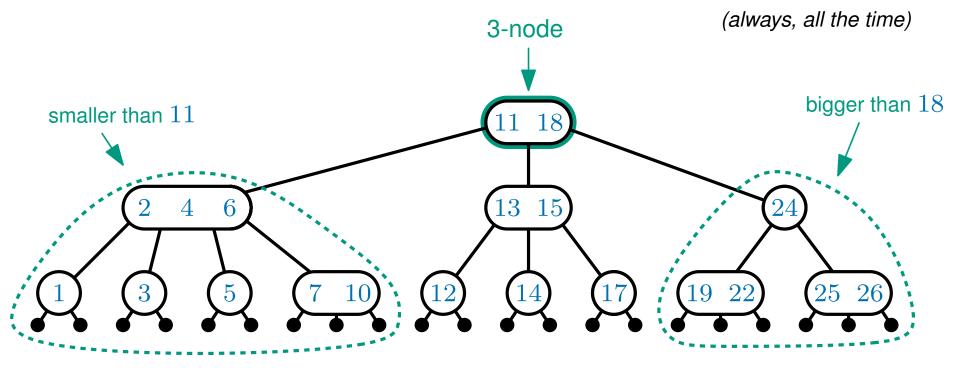
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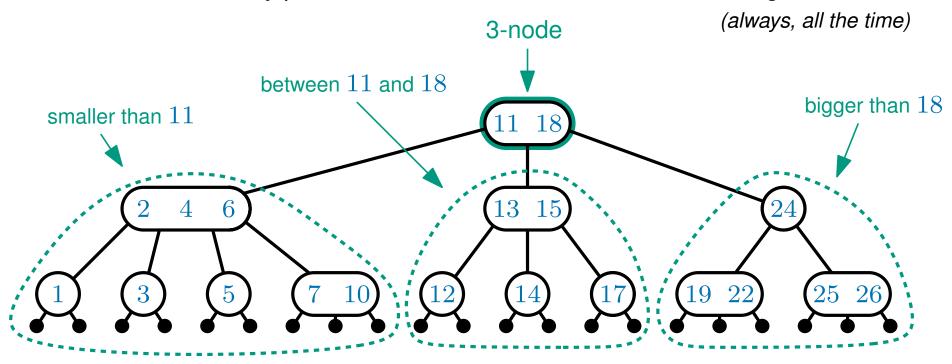
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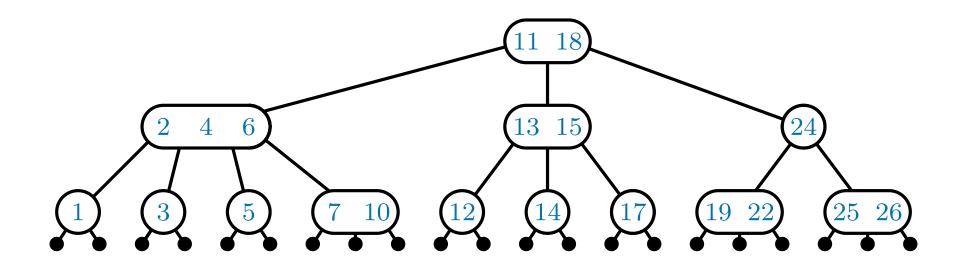
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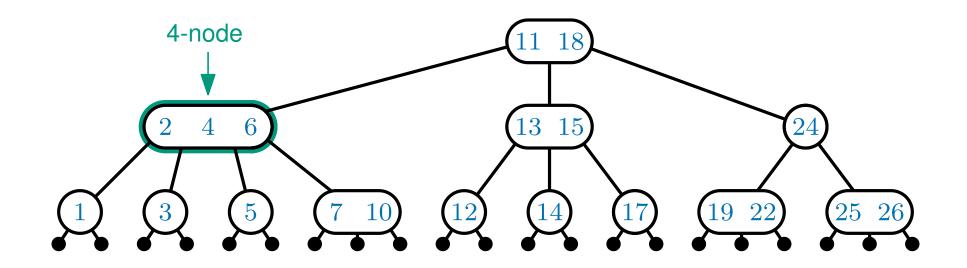
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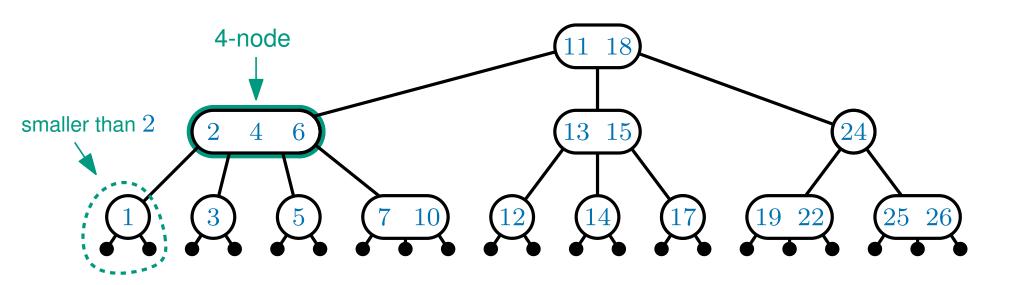
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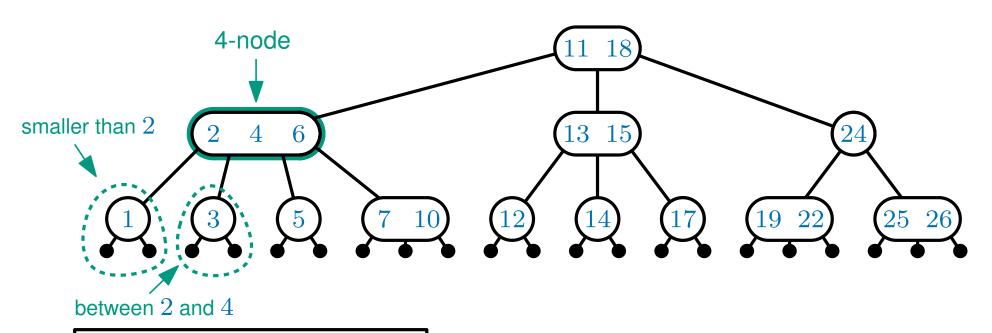
4-node: 4 children and 3 keys

Like in a binary search tree, the keys held at a node determine the contents of its subtrees



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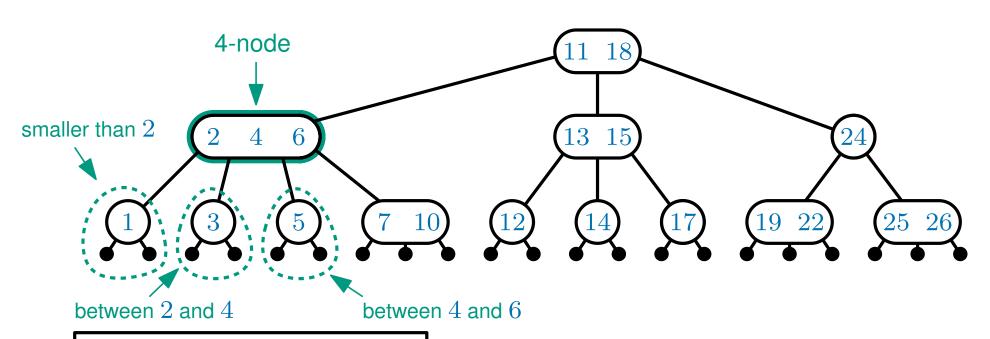
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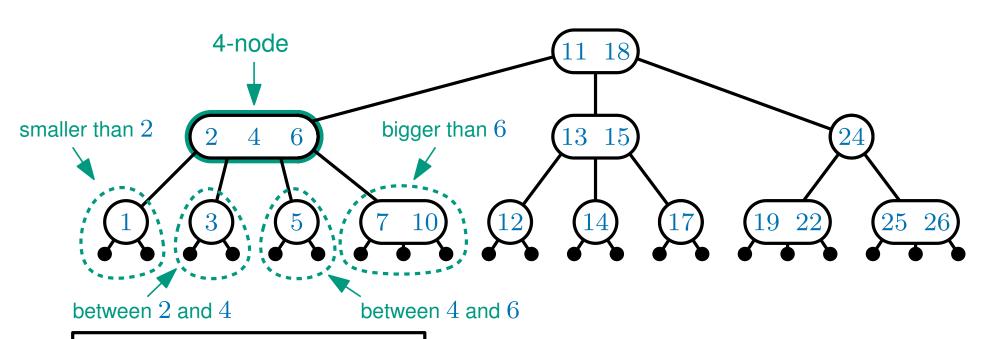
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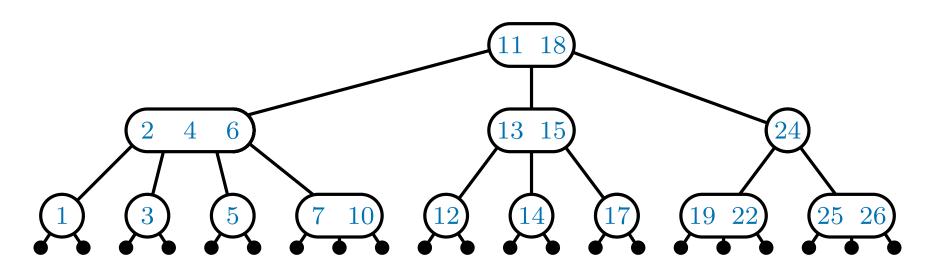
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Just like in a binary search tree,

we perform a FIND operation by following a path from the root...

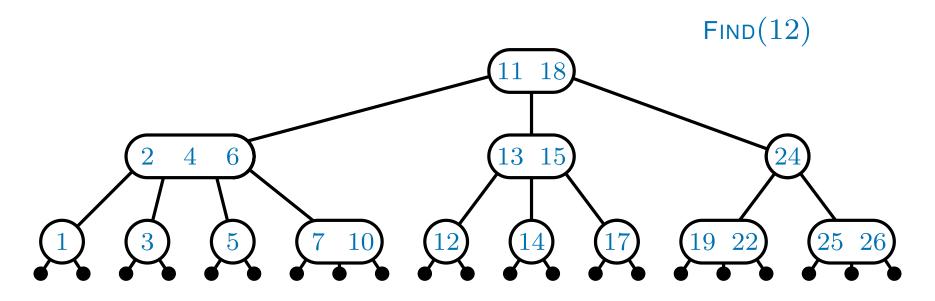


descisions are made by inspecting the key(s) at the current node and following the appropriate edge



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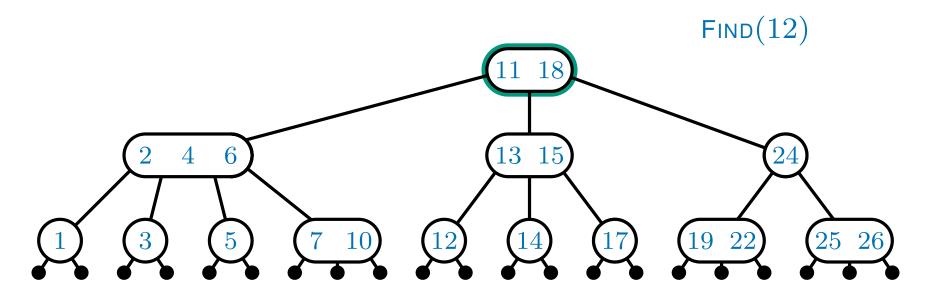
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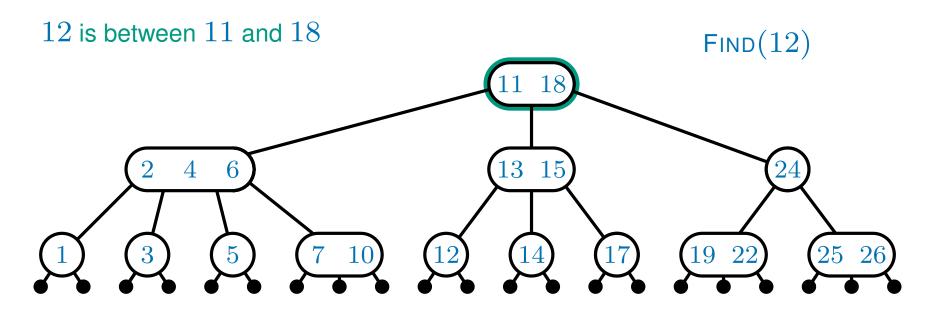
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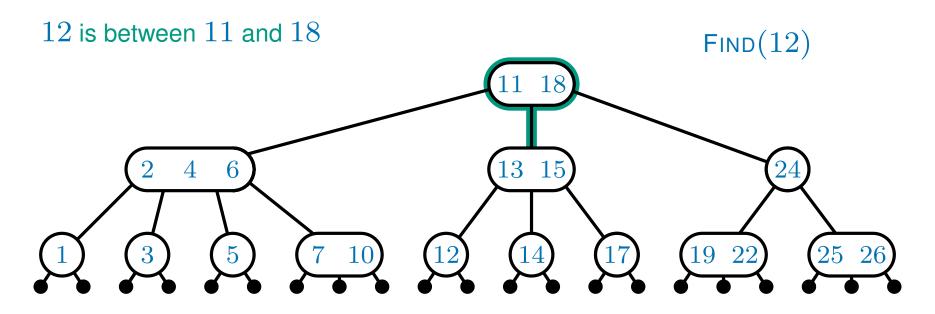


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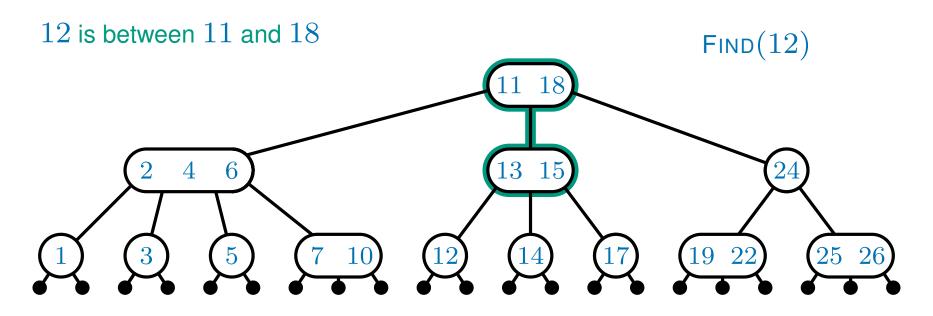


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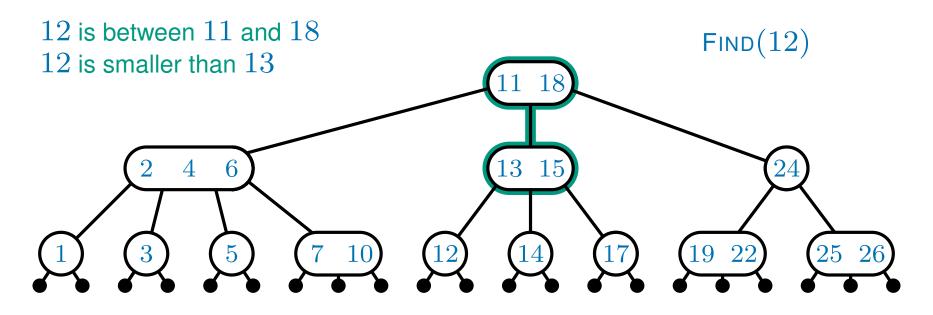
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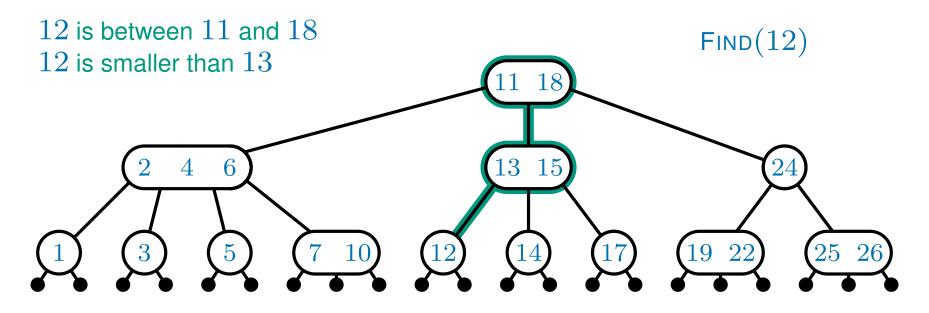
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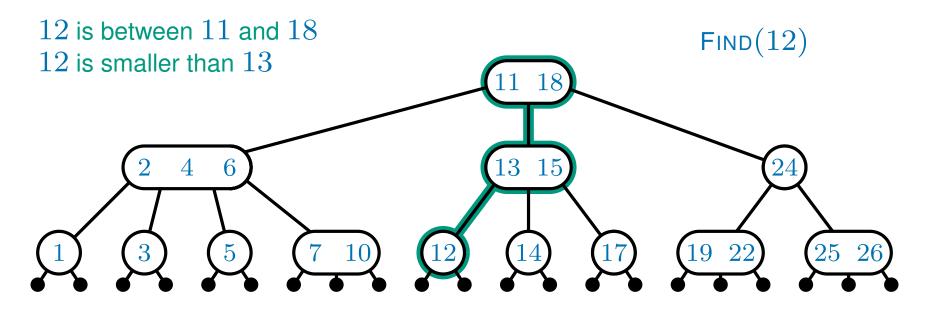
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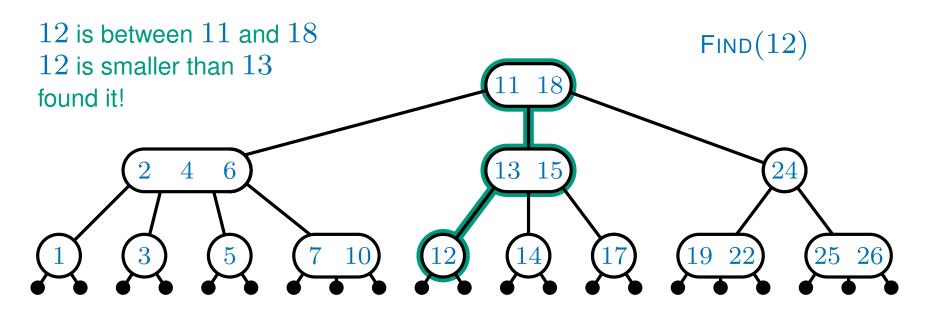
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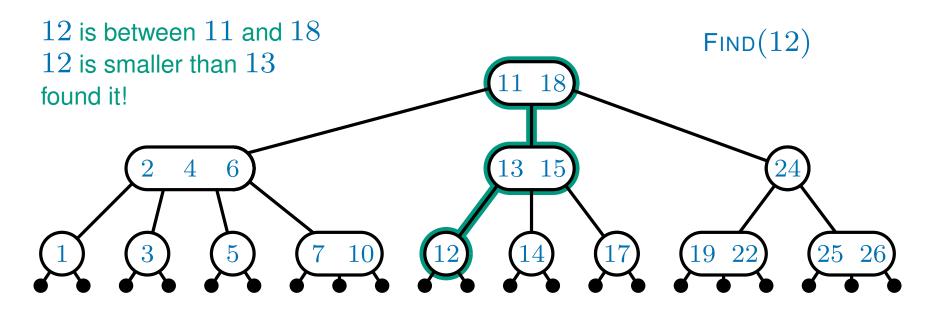
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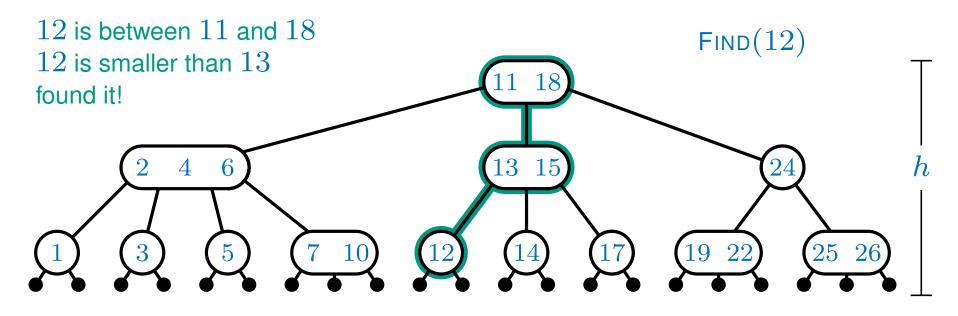
descisions are made by inspecting the key(s) at the current node and following the appropriate edge

What is the time complexity of the FIND operation?



Just like in a binary search tree,

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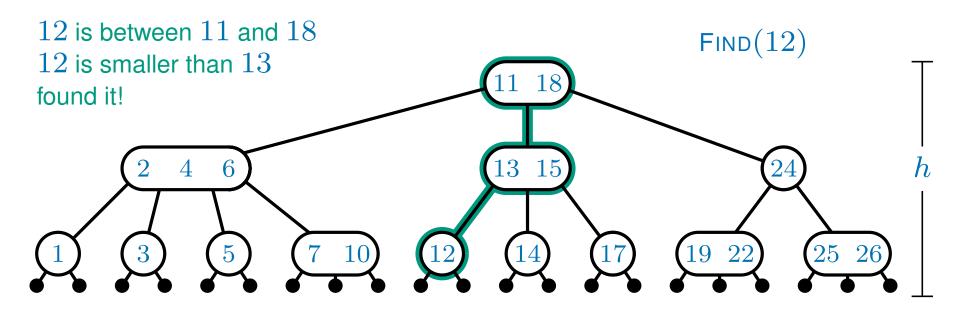
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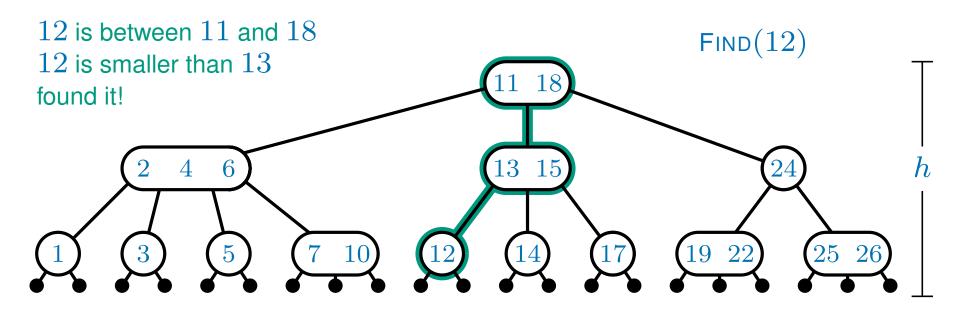
It's O(h) again

(each step down the path takes O(1) time)



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What is the time complexity of the FIND operation?

It's O(h) again

(each step down the path takes O(1) time)

What is the height, h of a 2-3-4 tree?



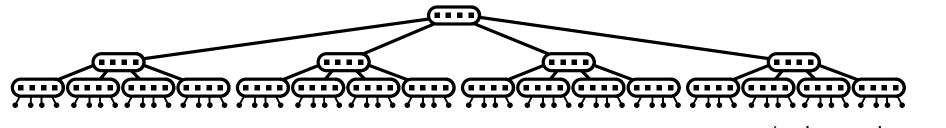
The height of a 2-3-4 tree

Perfect balance - every path from the root to a leaf has the same length

(we'll justify this as we go along)

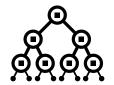
This implies that the height, h of a 2-3-4 tree with n nodes is

Best case:
$$\log_4 n = \frac{\log_2 n}{2}$$
 (all 4-nodes)



(■ is an element)

Worst case: $\log_2 n$ (all 2-nodes)



h is between 10 and 20 for a million nodes



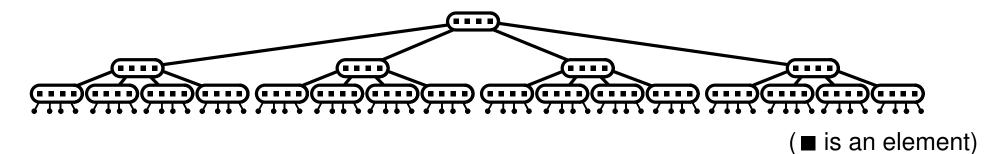
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h is between 10 and 20 for a million nodes

The time complexity of the FIND operation is O(h)



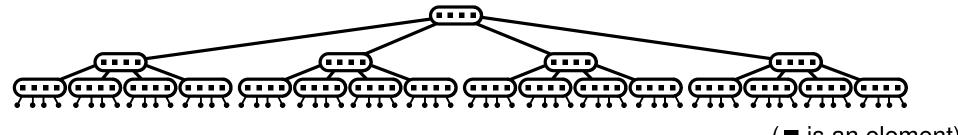
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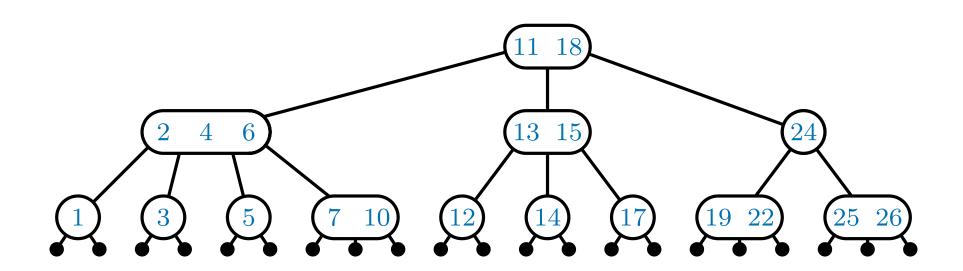
Worst case: $\log_2 n$ (all 2-nodes)



h is between 10 and 20 for a million nodes

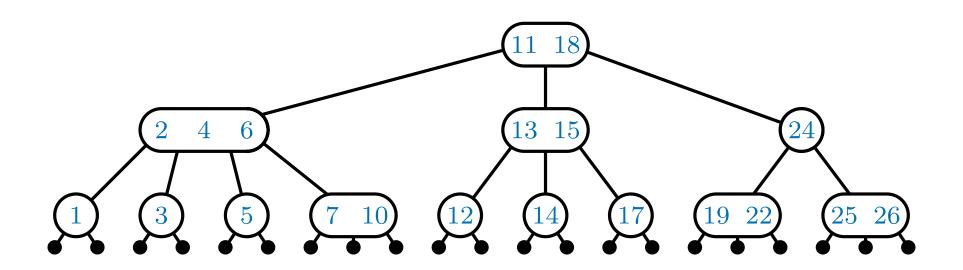
The time complexity of the FIND operation is $O(h) = O(\log n)$

The INSERT operation



To perform $\mathsf{INSERT}(x,k)$,

The **INSERT** operation

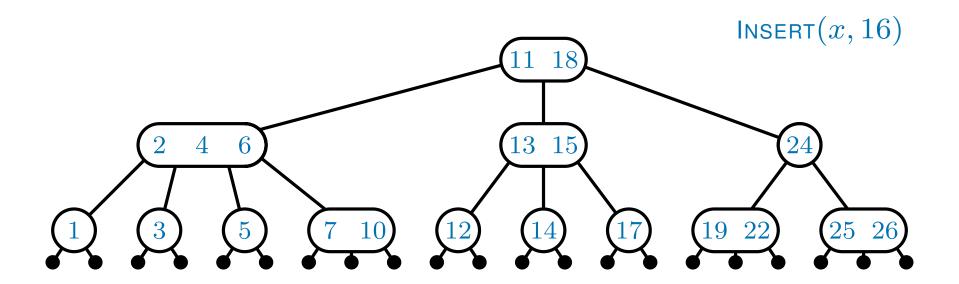


To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).



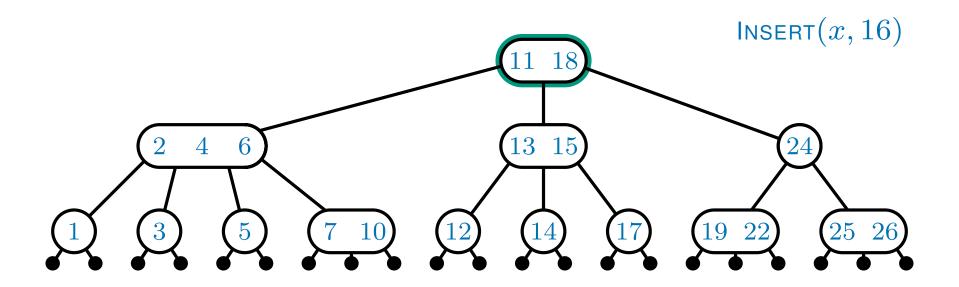
The **INSERT** operation



To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

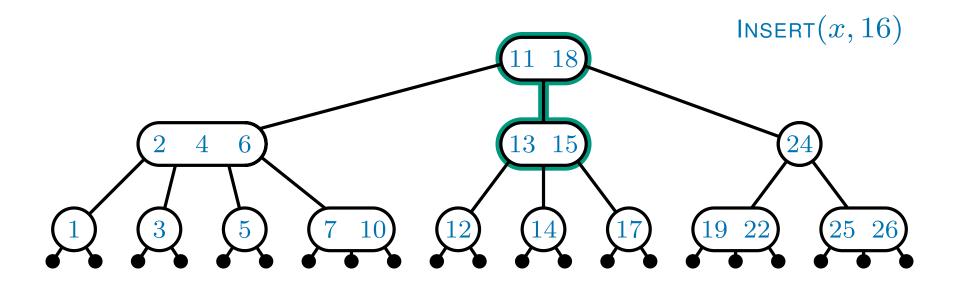




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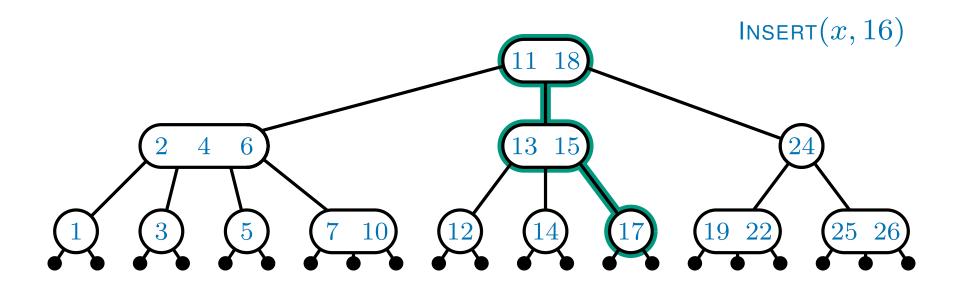




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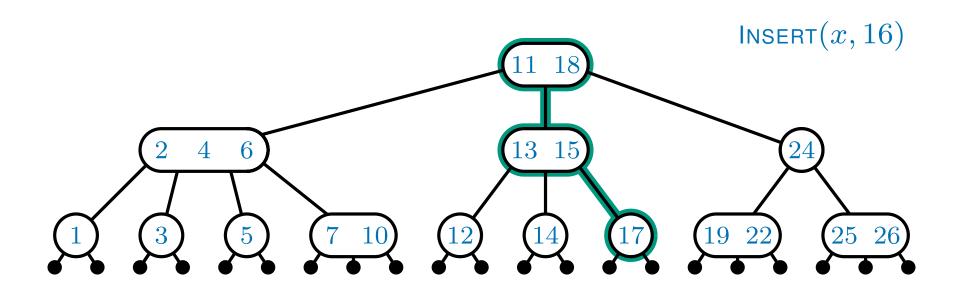




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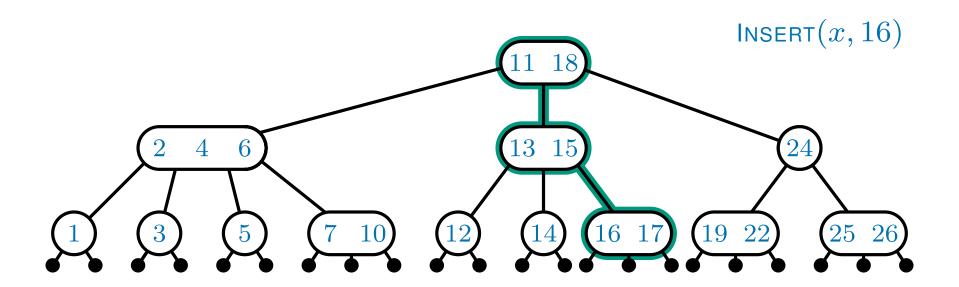


To perform INSERT(x, k),

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Step 2: If the leaf is a 2-node,



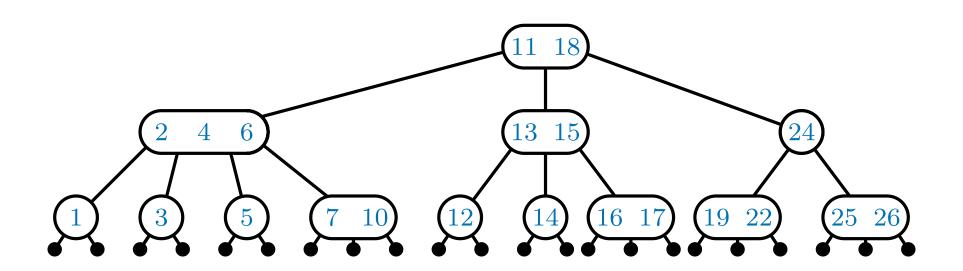


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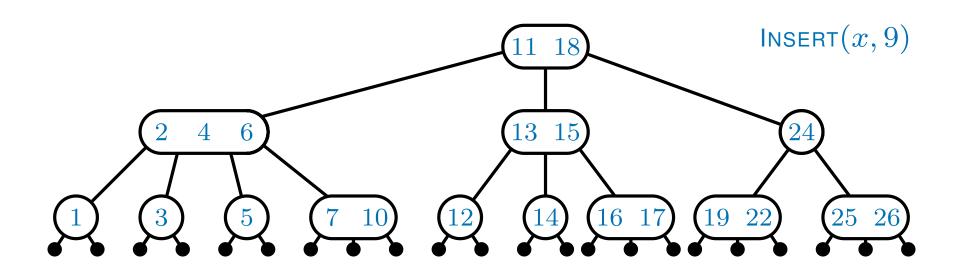


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Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,



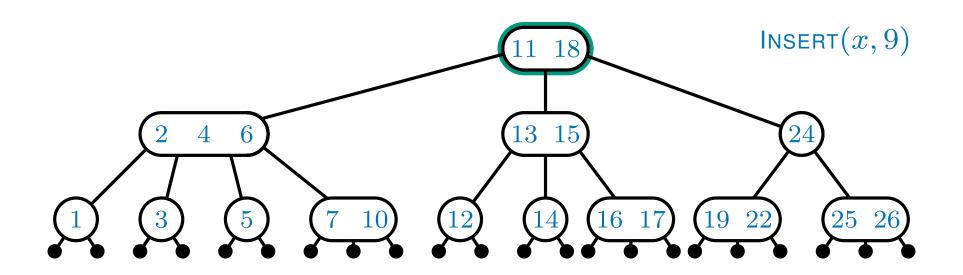


To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

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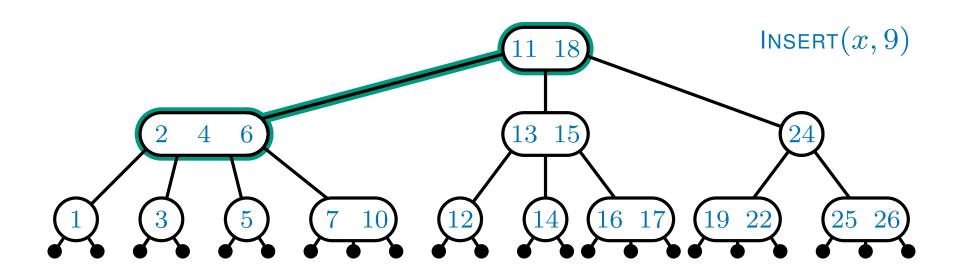


To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

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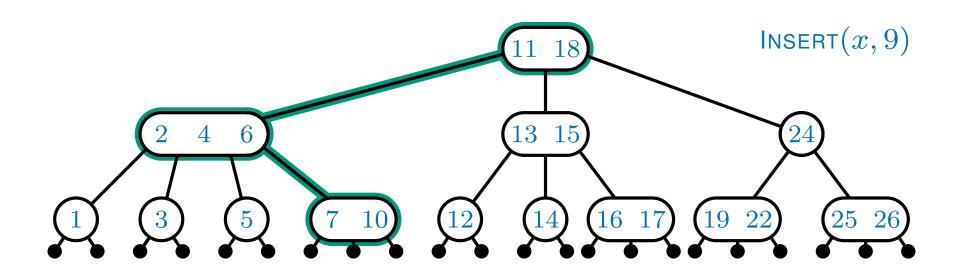


To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

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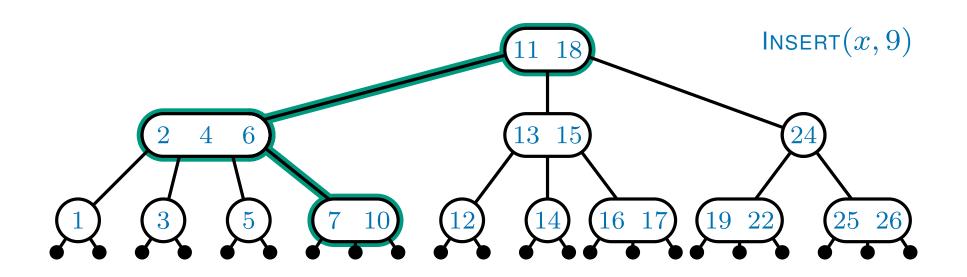


To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,





To perform INSERT(x, k),

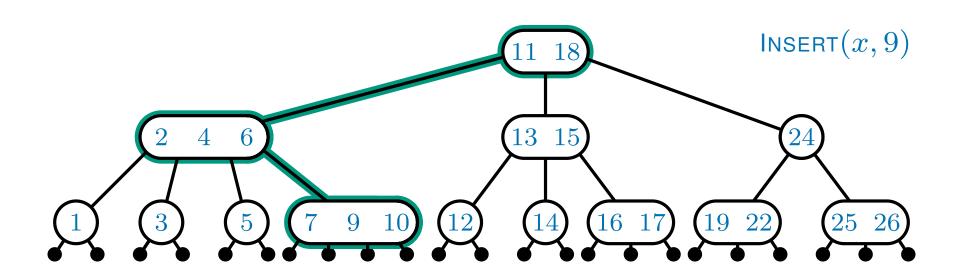
Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,

insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node,





To perform $\mathsf{INSERT}(x,k)$,

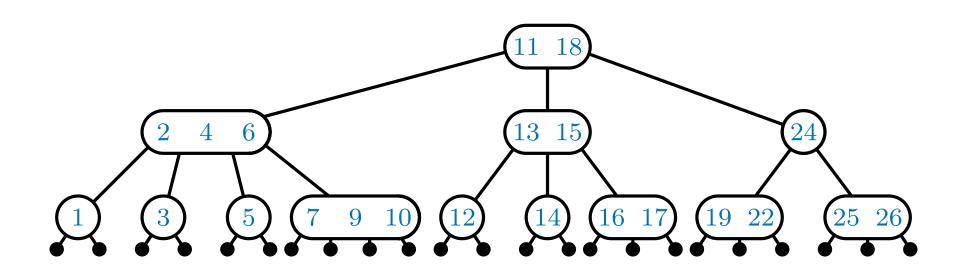
Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,

insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node,





To perform INSERT(x, k),

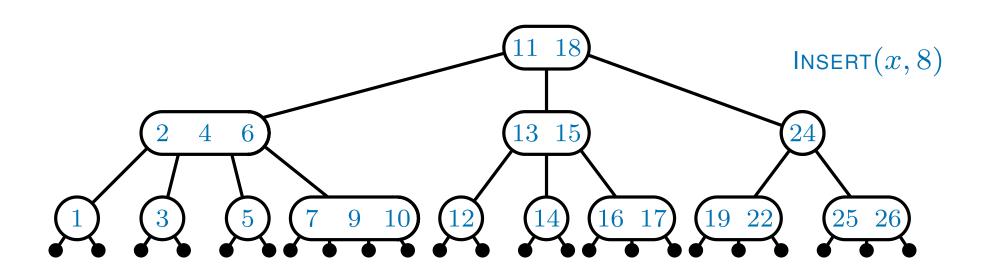
Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,

insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node,





To perform INSERT(x, k),

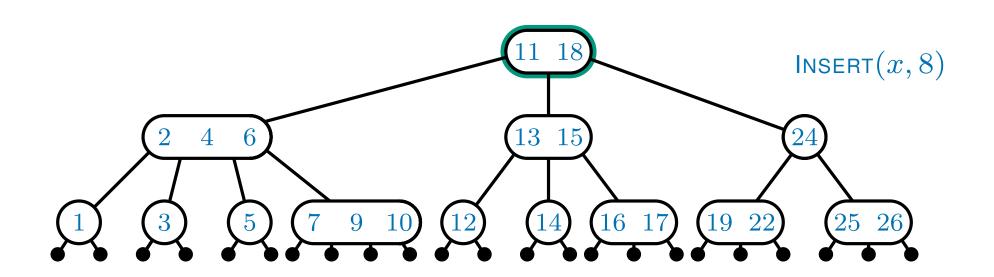
Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,

insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node,





To perform INSERT(x, k),

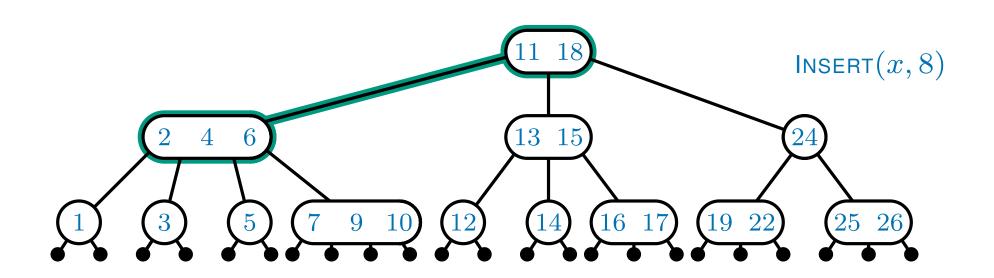
Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,

insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node,





To perform INSERT(x, k),

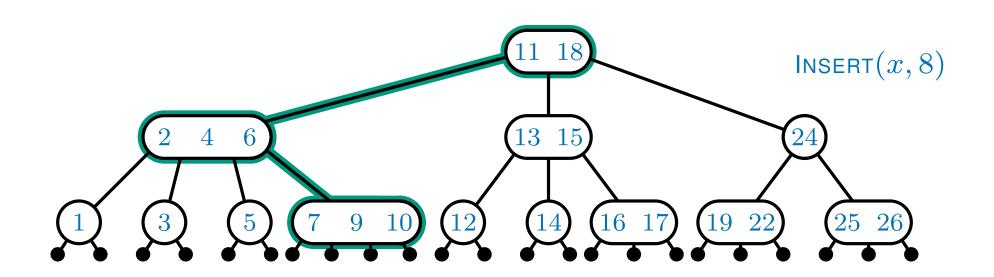
Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,

insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node,





To perform INSERT(x, k),

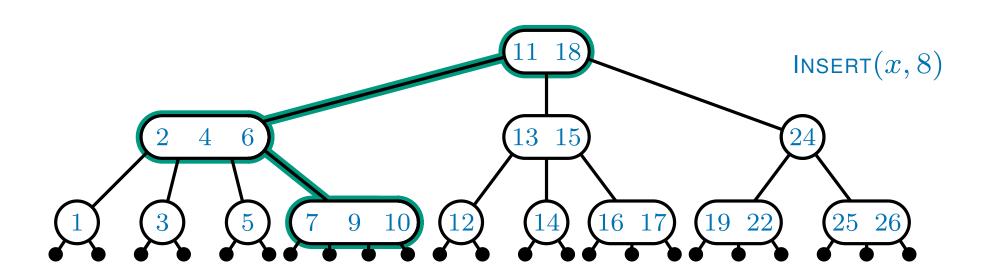
Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,

insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node,





To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,

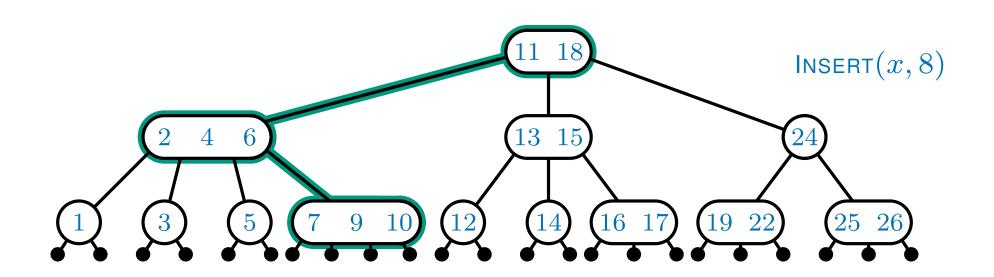
insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node,

insert (x, k), converting it into a 4-node

Step 4: If the leaf is a 4-node,





To perform $\mathsf{INSERT}(x,k)$,

Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,

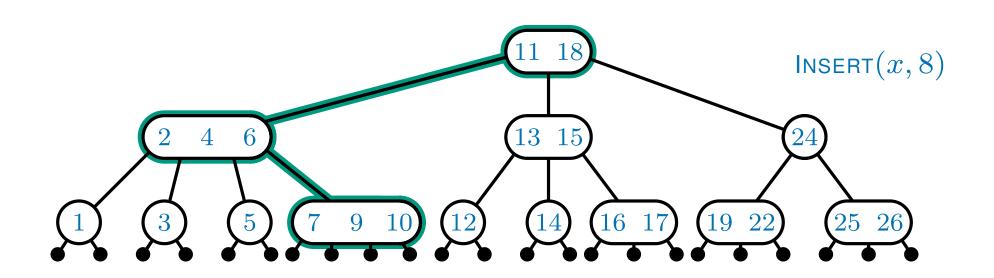
insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node,

insert (x, k), converting it into a 4-node

Step 4: If the leaf is a 4-node, ???





To perform $\mathsf{INSERT}(x,k)$,

Step 1: Search for the key k as if performing FIND(k).

Step 2: If the leaf is a 2-node,

insert (x, k), converting it into a 3-node

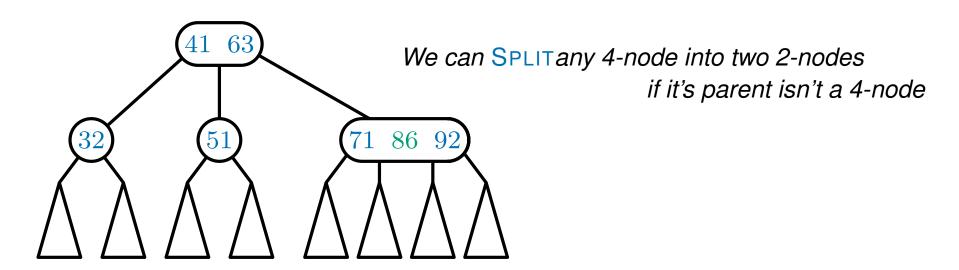
Step 3: If the leaf is a 3-node,

insert (x, k), converting it into a 4-node

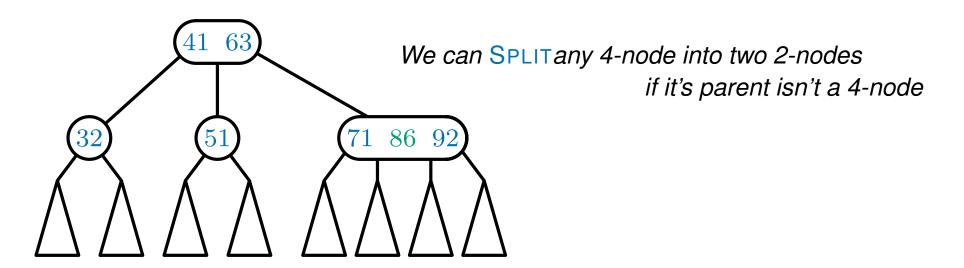
Step 4: If the leaf is a 4-node, ???

We will make sure this *never* happens

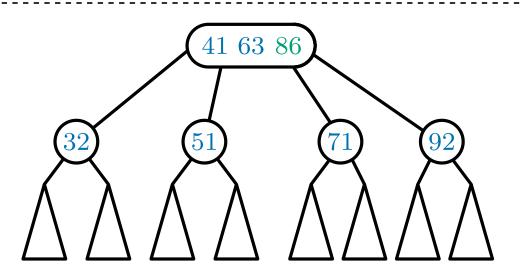






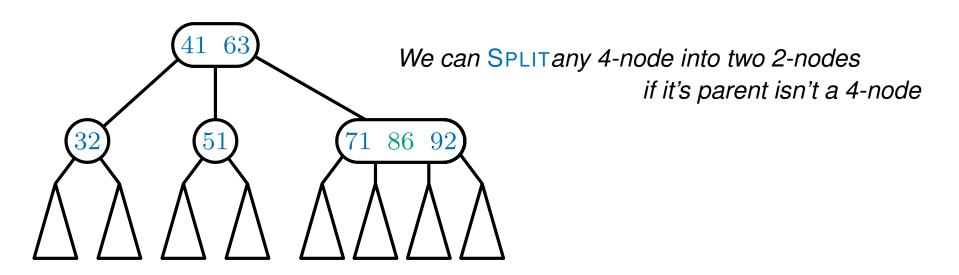


BEFORE

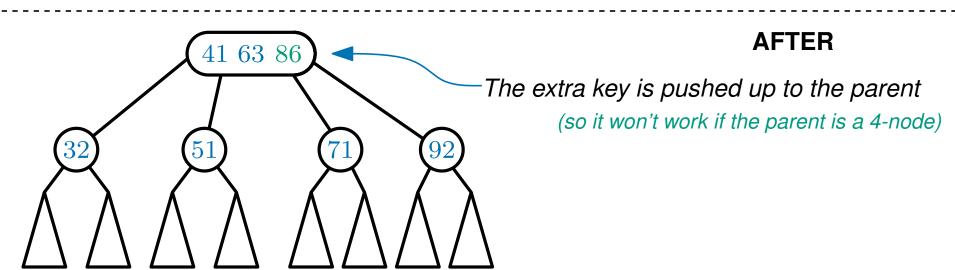


AFTER

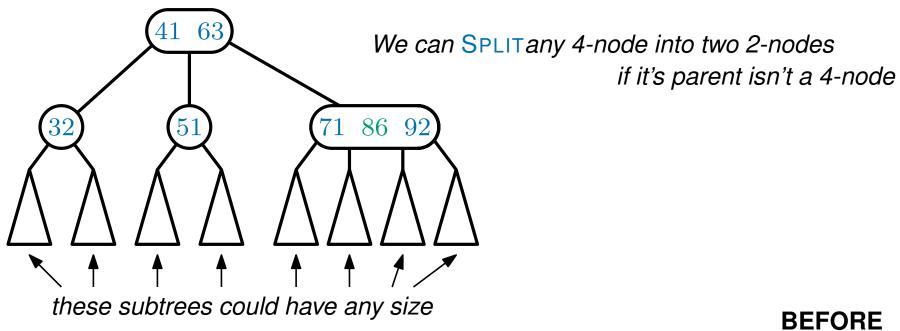


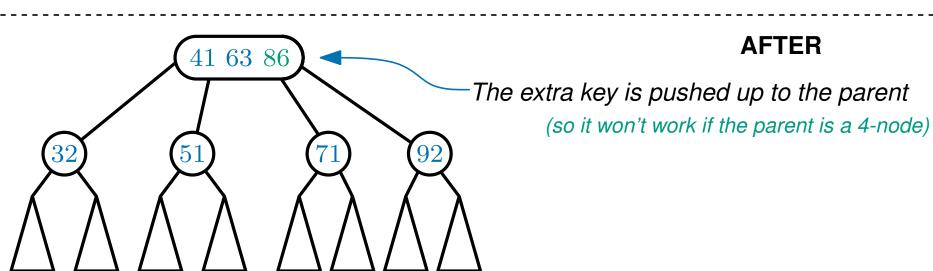


BEFORE

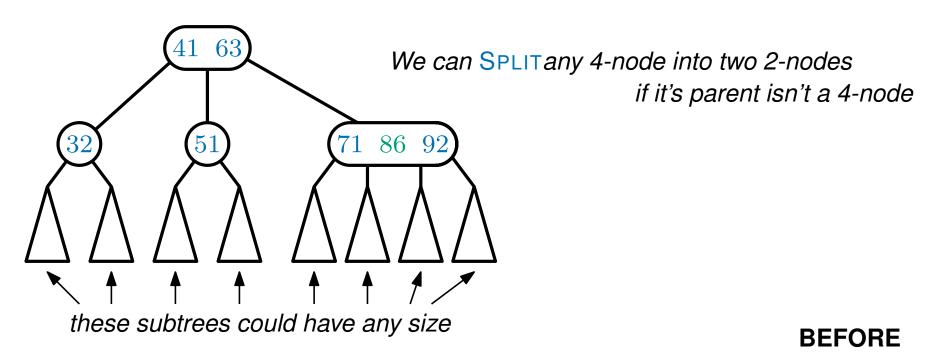








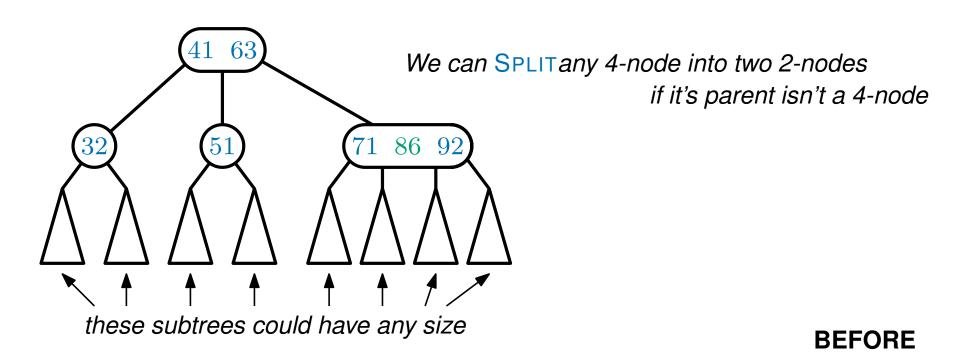




AFTER The extra key is pushed up to the parent (so it won't work if the parent is a 4-node)

these subtrees haven't changed





AFTER

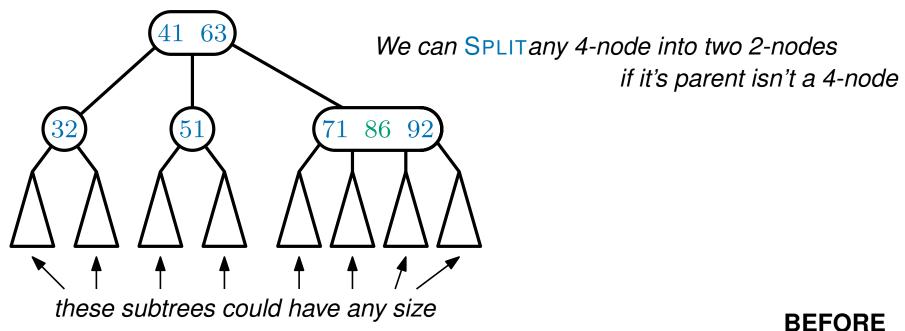
32 51 71 92

these subtrees haven't changed

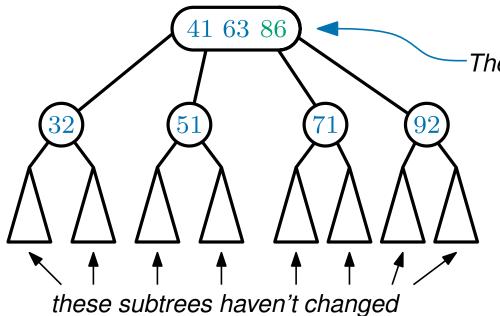
The extra key is pushed up to the parent (so it won't work if the parent is a 4-node)

no path lengths have changed





DEFUR



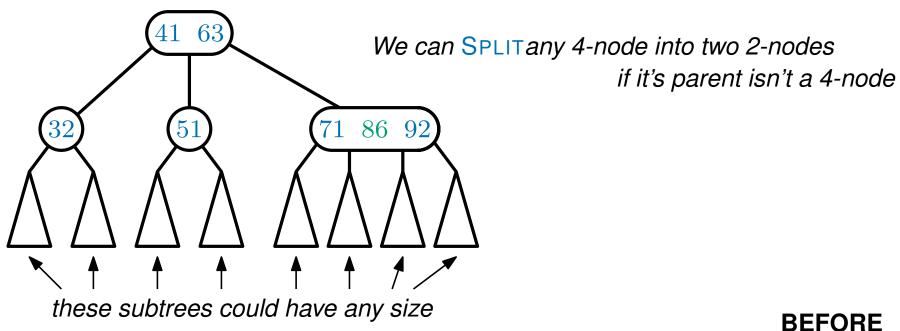
AFTER

The extra key is pushed up to the parent (so it won't work if the parent is a 4-node)

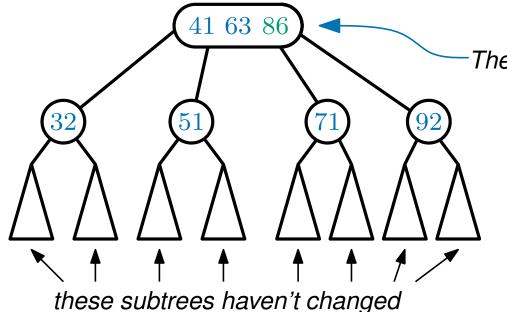
no path lengths have changed

(if it was perfectly balanced, it still is)





BEFUR



AFTER

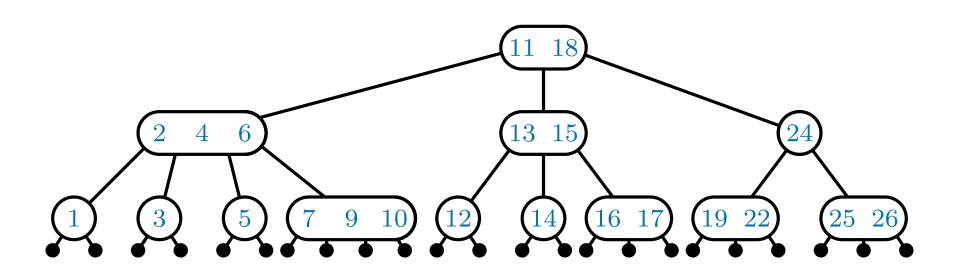
The extra key is pushed up to the parent (so it won't work if the parent is a 4-node)

no path lengths have changed

(if it was perfectly balanced, it still is)

SPLIT takes O(1) time





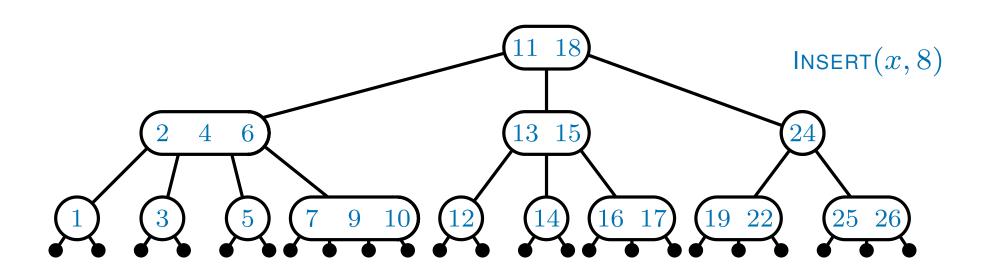
To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node





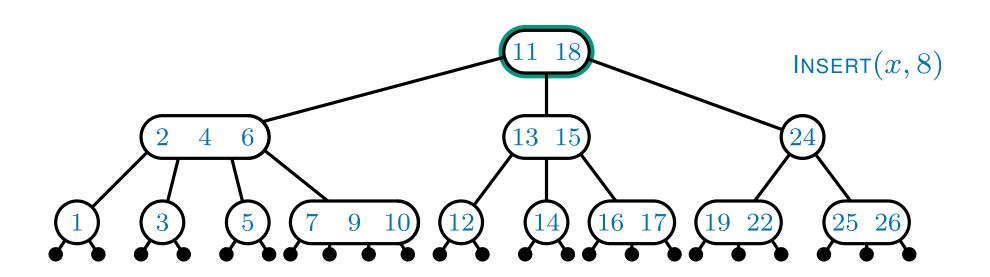
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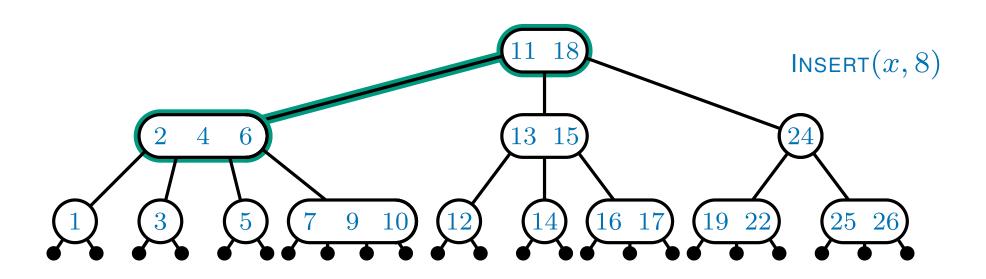
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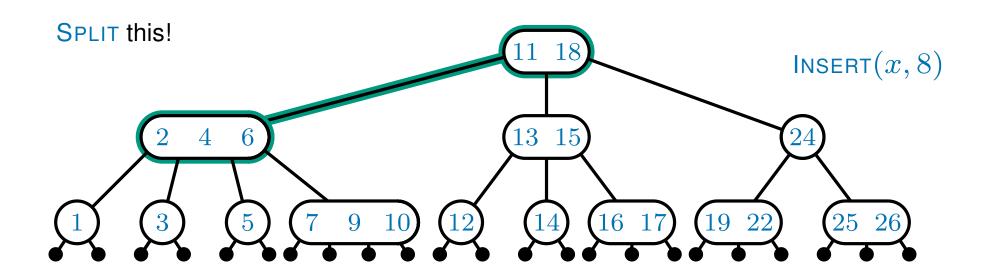
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Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node





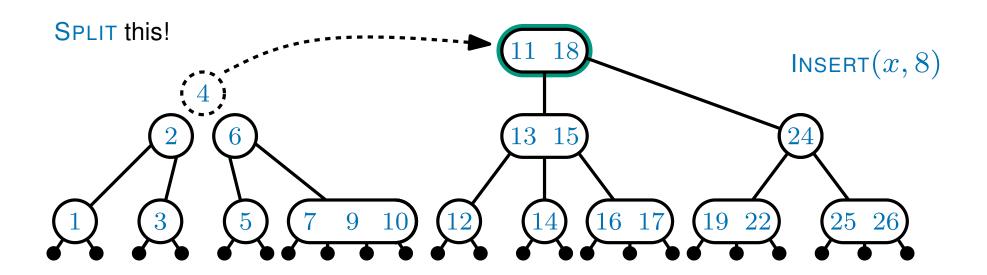
To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node





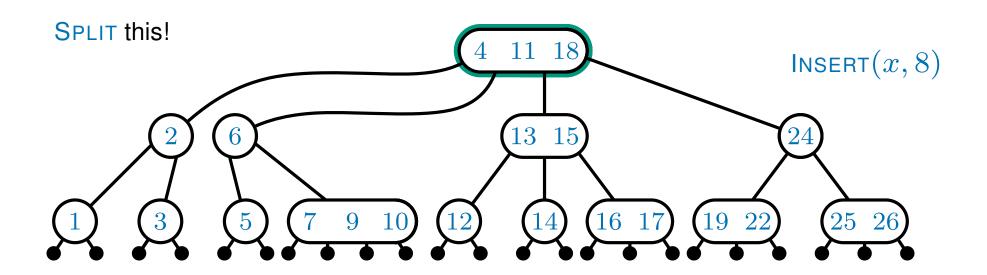
To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node





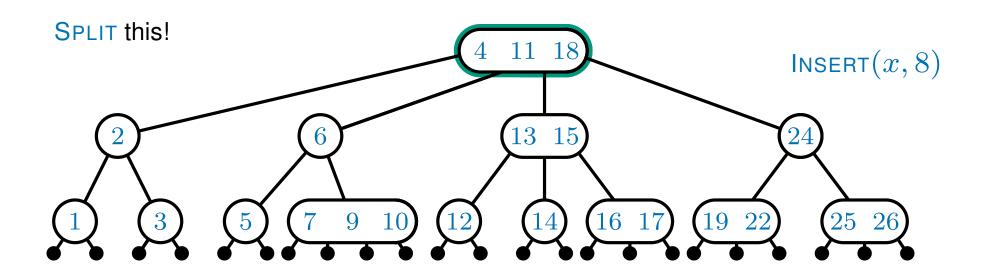
To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node





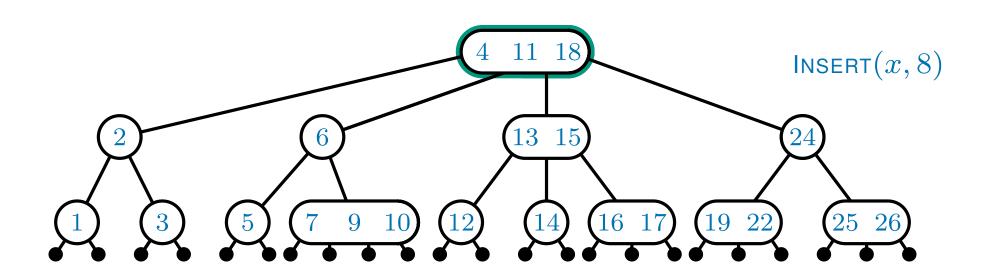
To perform $\mathsf{INSERT}(x,k)$,

Step 1: Search for the key k as if performing FIND(k).

SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node





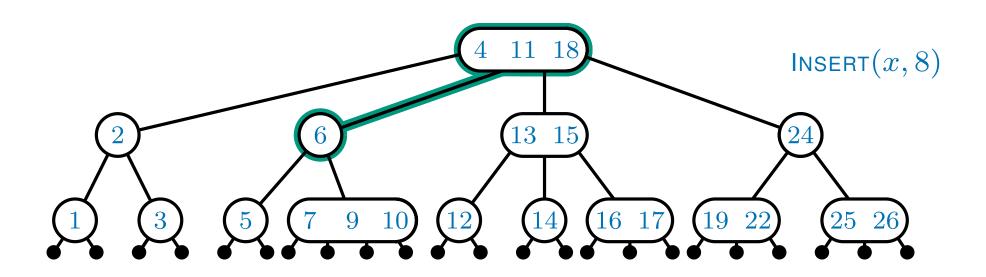
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Step 1: Search for the key k as if performing FIND(k).

SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node





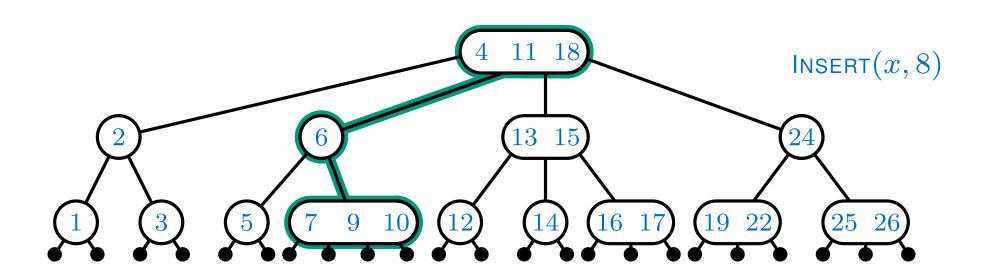
To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node





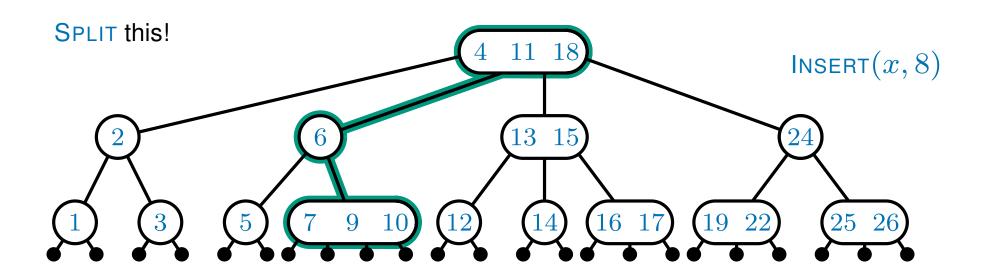
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Step 1: Search for the key k as if performing FIND(k).

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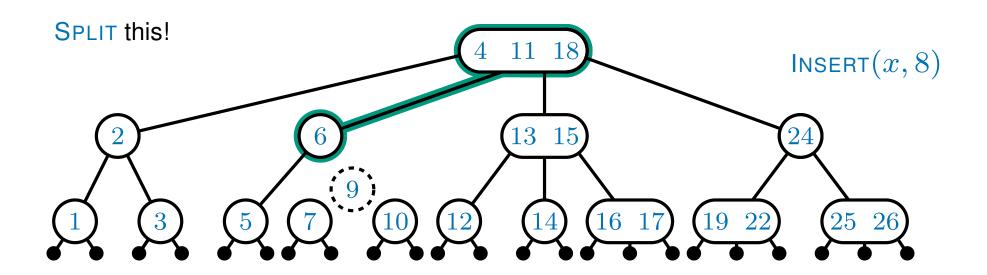
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SPLIT 4-nodes as we go down

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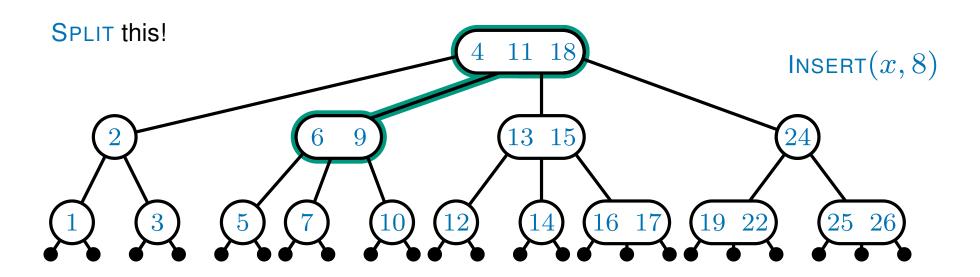
To perform INSERT(x, k),

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SPLIT 4-nodes as we go down

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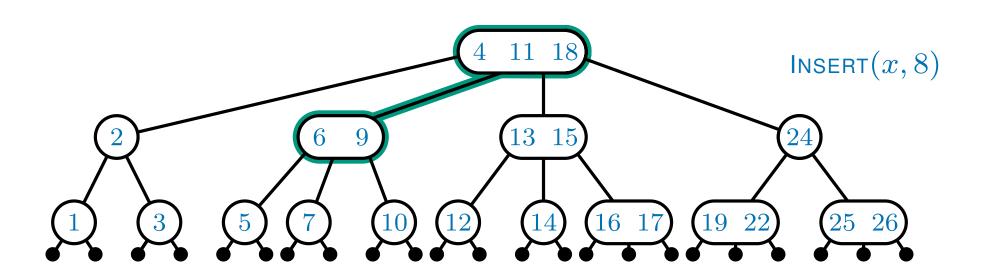
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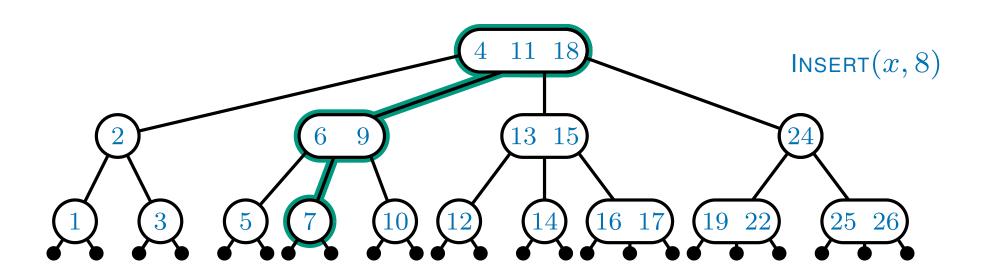
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SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node





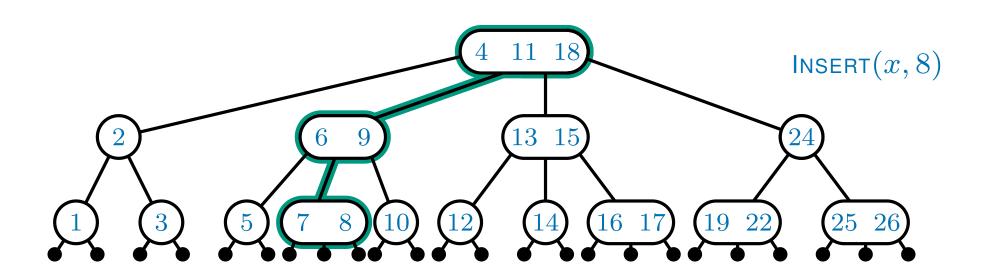
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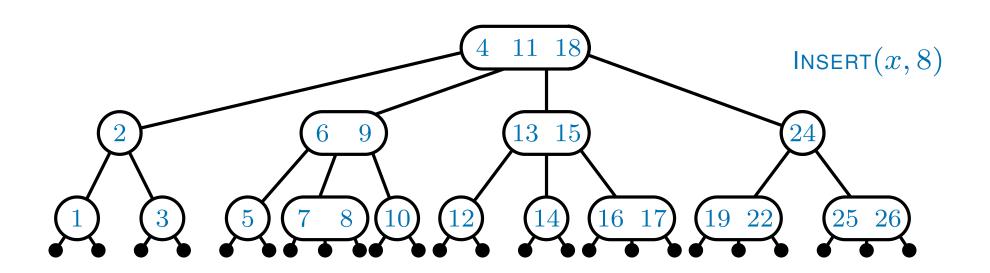
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SPLIT 4-nodes as we go down

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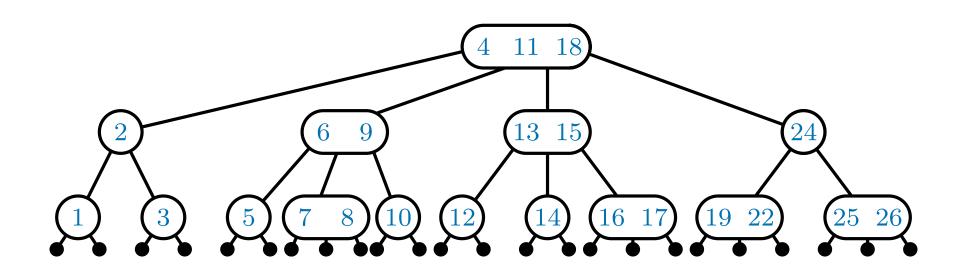
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SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node



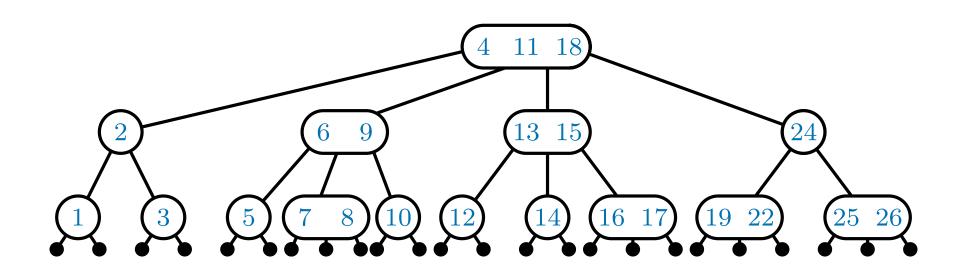


To perform INSERT(x, k),

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SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node



To perform INSERT(x, k),

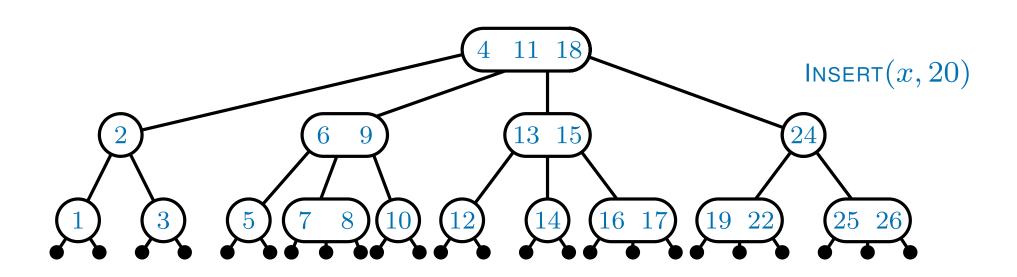
Step 1: Search for the key k as if performing FIND(k).

SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node, insert (x, k), converting it into a 4-node

OK, one more thing...



To perform INSERT(x, k),

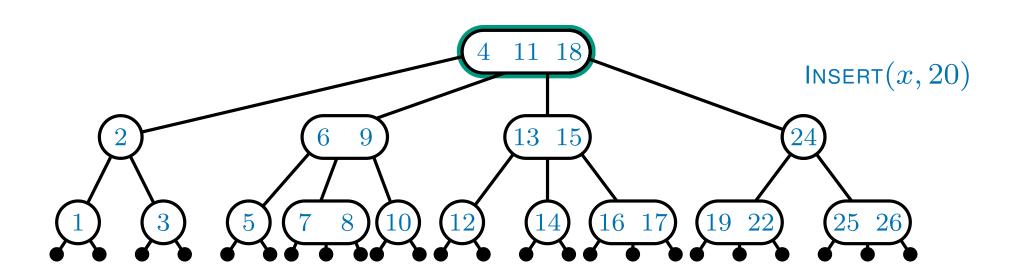
Step 1: Search for the key k as if performing FIND(k).

SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node, insert (x, k), converting it into a 4-node

OK, one more thing...



To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

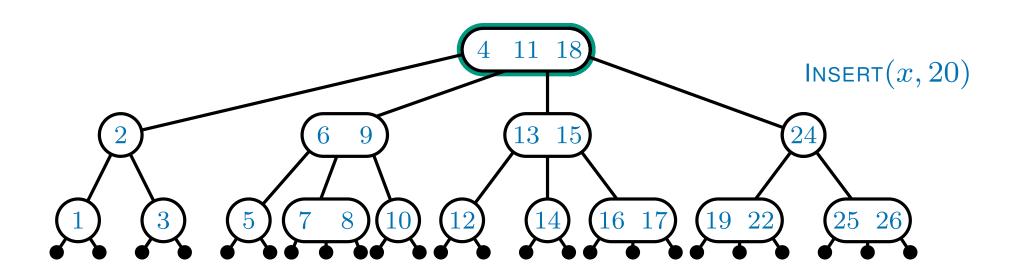
SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node, insert (x, k), converting it into a 4-node

OK, one more thing...





To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

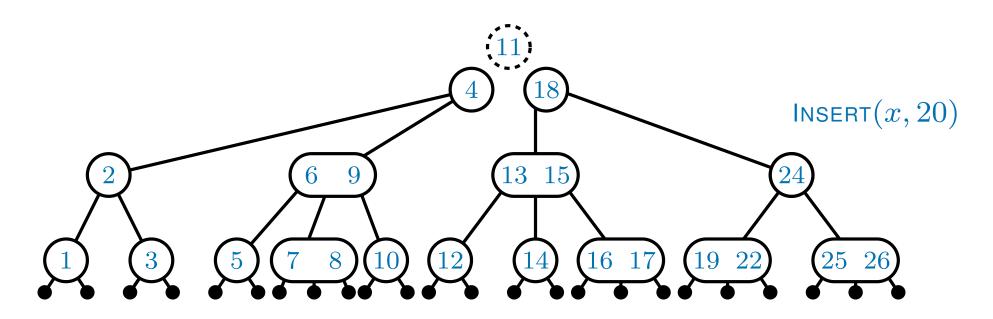
SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node, insert (x, k), converting it into a 4-node

OK, one more thing... what happens when we SPLIT the root?





To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

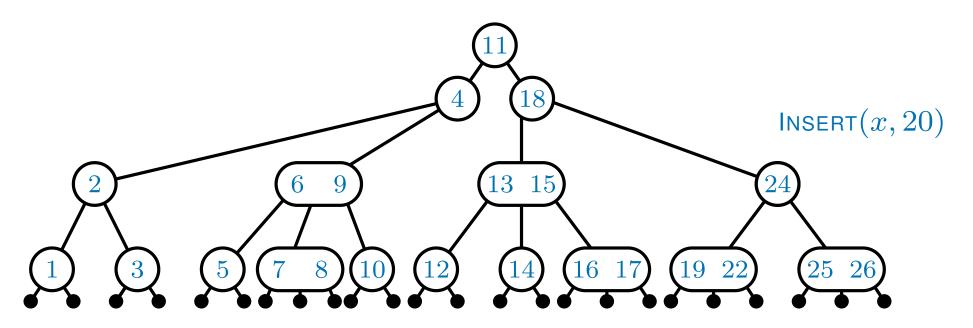
SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node

Step 3: If the leaf is a 3-node, insert (x, k), converting it into a 4-node

OK, one more thing... what happens when we SPLIT the root?





To perform INSERT(x, k),

Step 1: Search for the key k as if performing FIND(k).

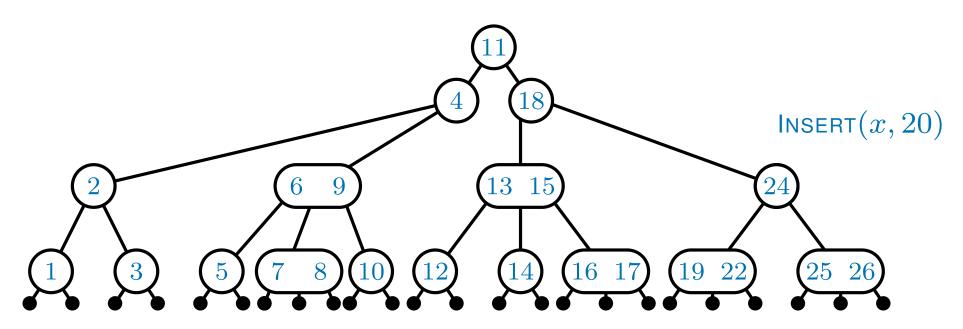
SPLIT 4-nodes as we go down

Step 2: If the leaf is a 2-node, insert (x, k), converting it into a 3-node

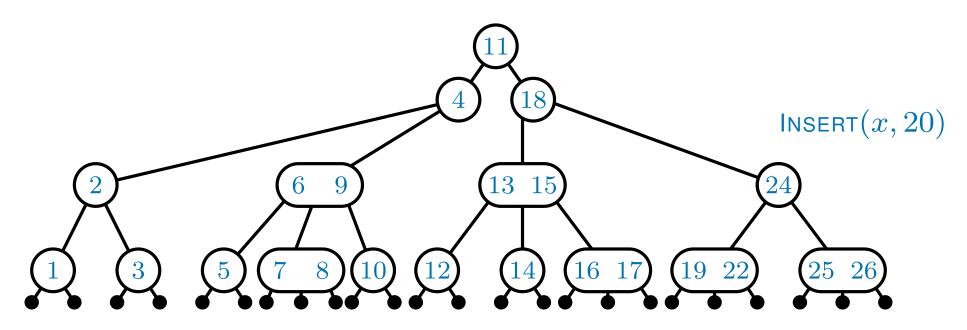
Step 3: If the leaf is a 3-node, insert (x, k), converting it into a 4-node

OK, one more thing... what happens when we SPLIT the root?







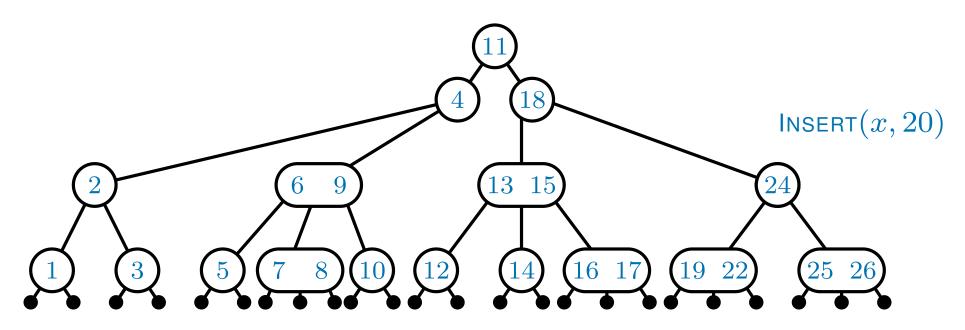


SPLITTING the root increases the height of the tree and increases the length of all root-leaf paths by one

So it maintains the **perfect balance** property

- i.e every path from the root to a leaf has the same length





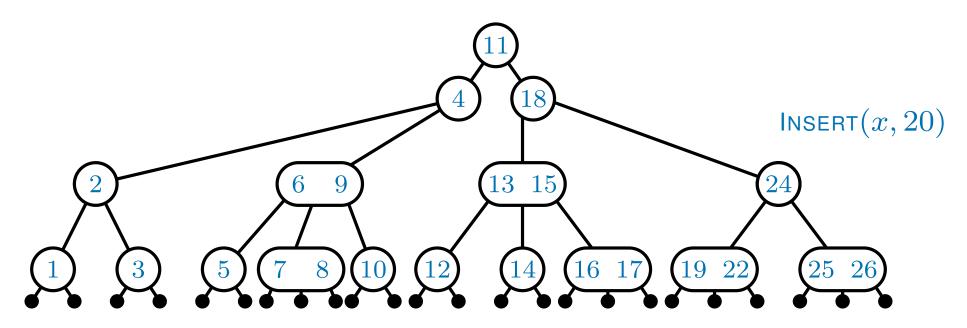
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This is the only way INSERT can affect the length of paths so it also maintains the **perfect balance** property





SPLITTING the root increases the height of the tree and increases the length of all root-leaf paths by one

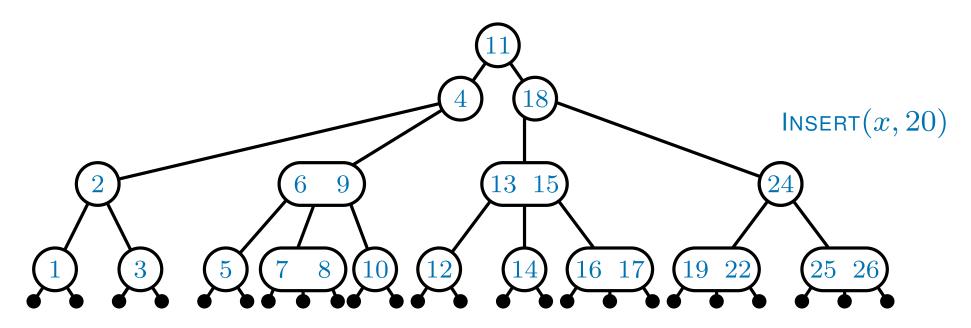
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This is the only way INSERT can affect the length of paths so it also maintains the **perfect balance** property

As each Split takes O(1) time, overall INSERT takes $O(\log n)$ time





To perform $\mathsf{INSERT}(x,k)$,

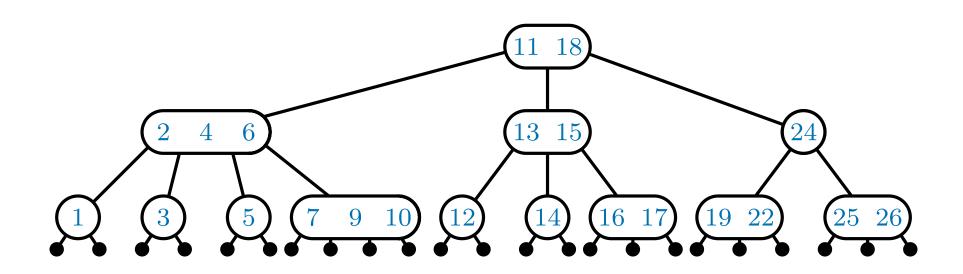
Step 1: Search for the key k as if performing FIND(k).

SPLIT 4-nodes as we go down

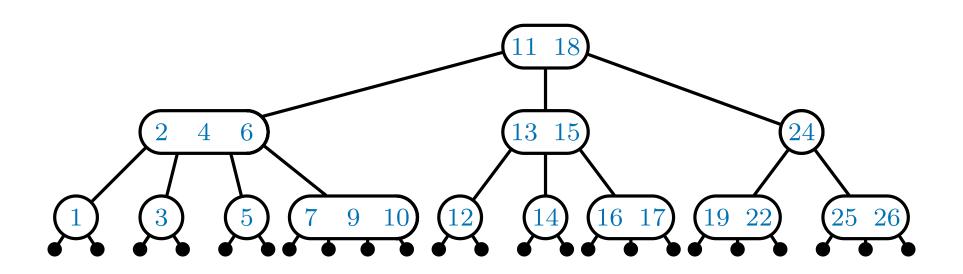
Step 2: If the bottom node is a 2-node, insert (x, k), converting it into a 3-node

Step 3: If the bottom node is a 3-node, insert (x, k), converting it into a 4-node

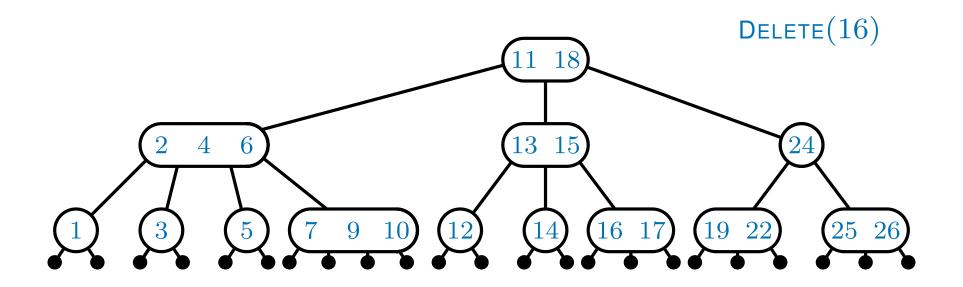
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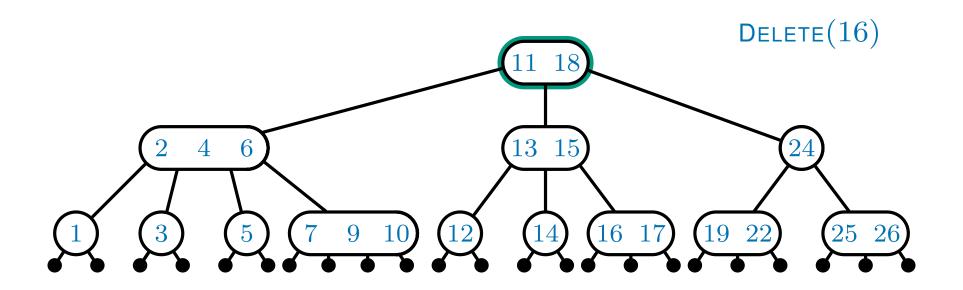
To perform DELETE(k) on a leaf (we'll deal with other nodes later)



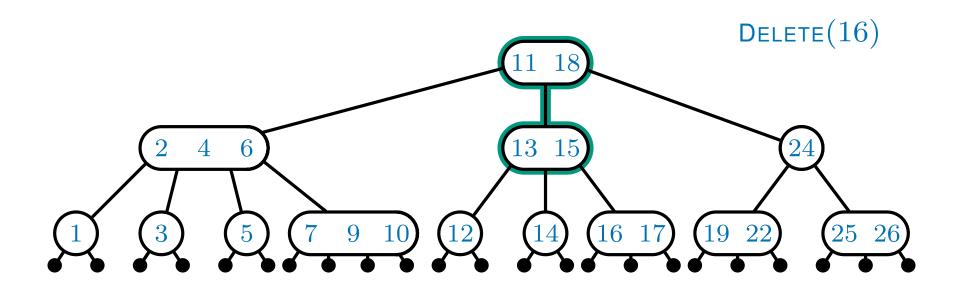
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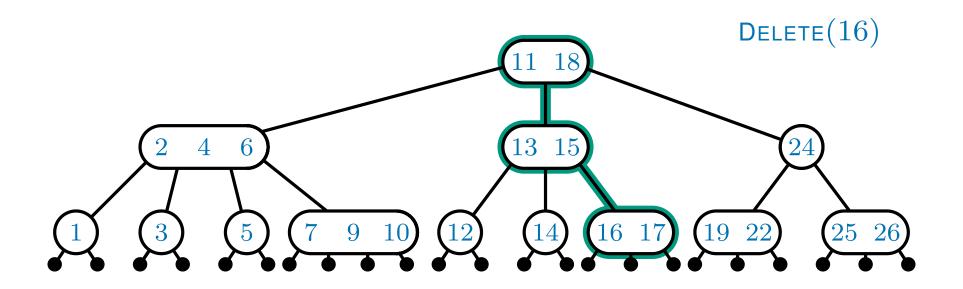


To perform DELETE(k) on a leaf (we'll deal with other nodes later)

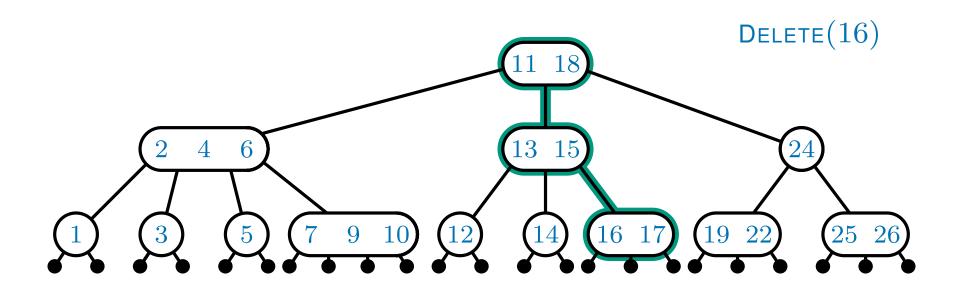


To perform DELETE(k) on a leaf (we'll deal with other nodes later)





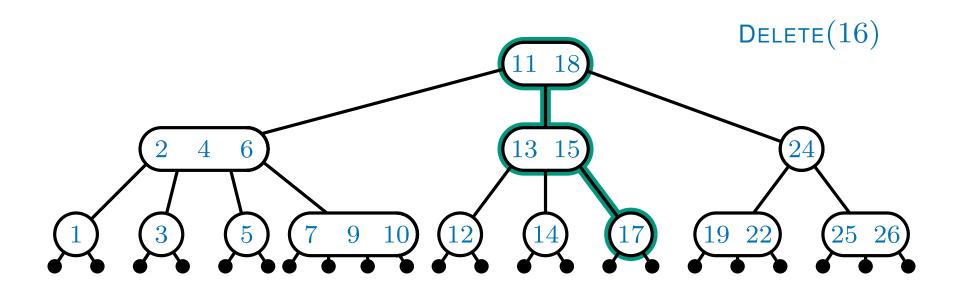
To perform DELETE(k) on a leaf (we'll deal with other nodes later)



To perform DELETE(k) on a leaf (we'll deal with other nodes later)

Step 1: Search for the key k using FIND(k).

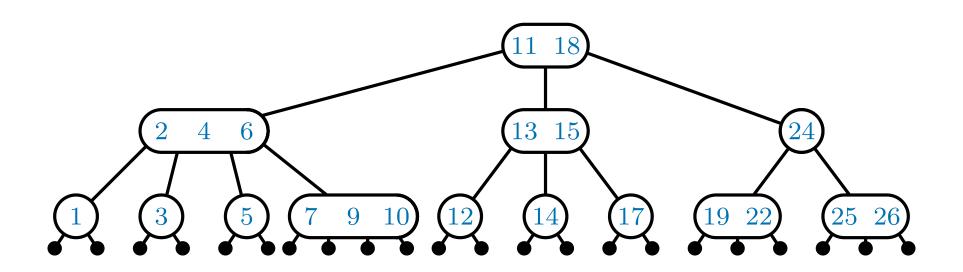
Step 2: If the leaf is a 3-node,



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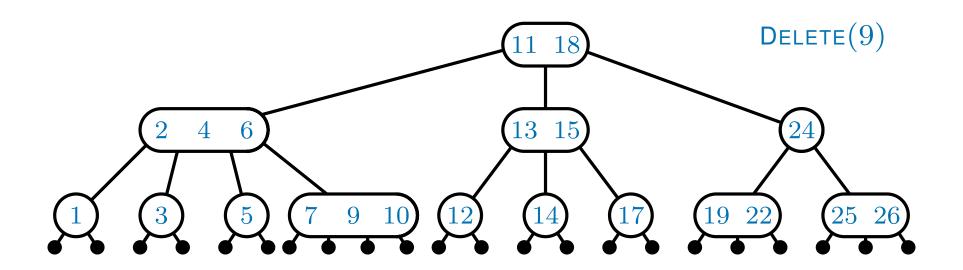
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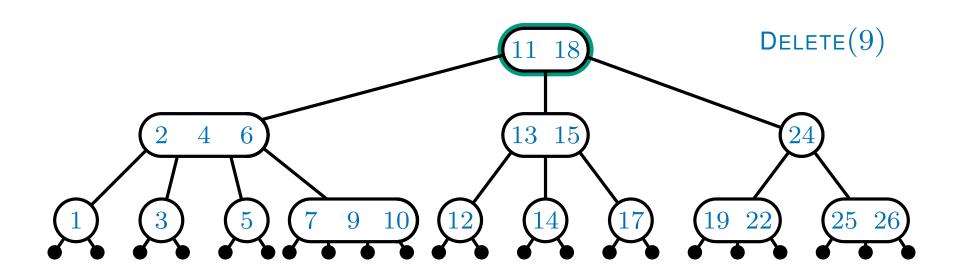
Step 2: If the leaf is a 3-node,



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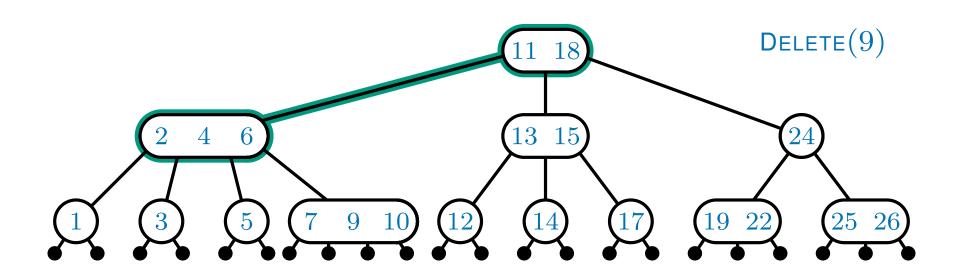


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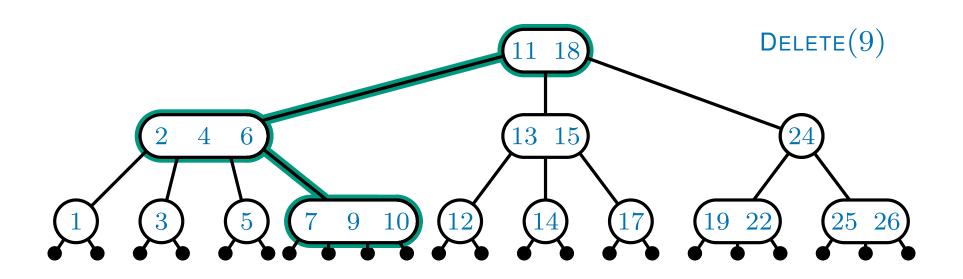


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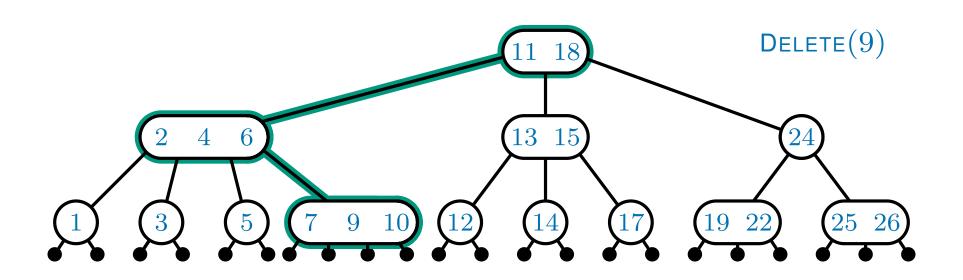


To perform DELETE(k) on a leaf (we'll deal with other nodes later)

Step 1: Search for the key k using FIND(k).

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To perform DELETE(k) on a leaf (we'll deal with other nodes later)

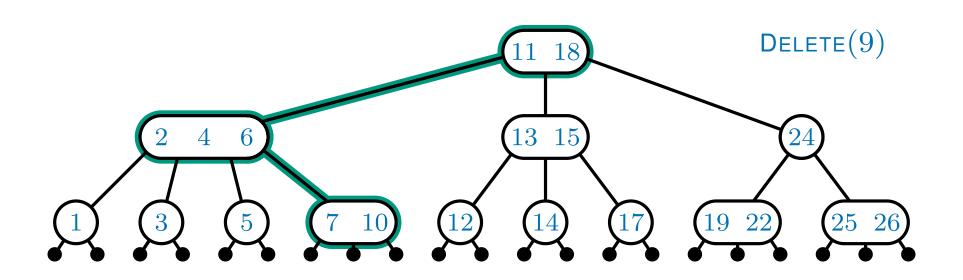
Step 1: Search for the key k using FIND(k).

Step 2: If the leaf is a 3-node,

delete (x, k), converting it into a 2-node

Step 3: If the leaf is a 4-node,





To perform DELETE(k) on a leaf (we'll deal with other nodes later)

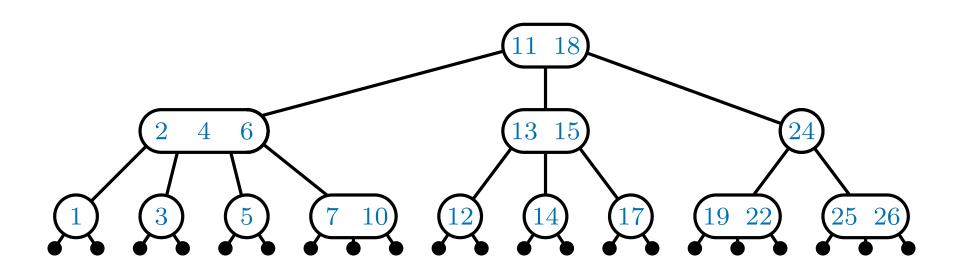
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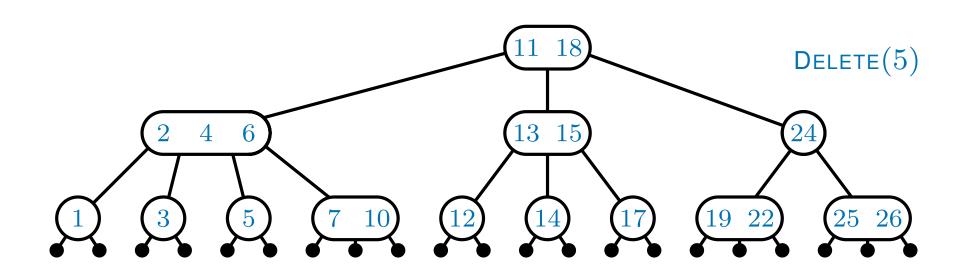
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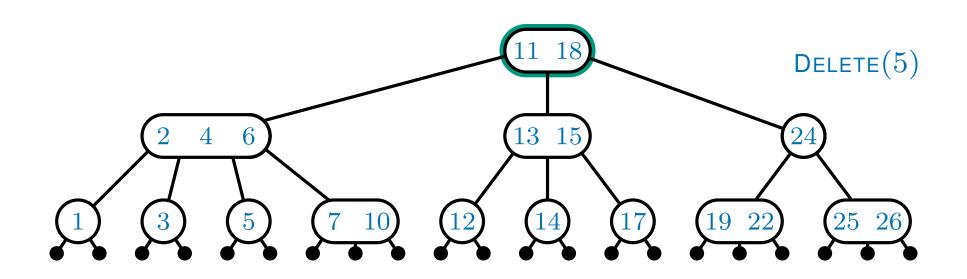
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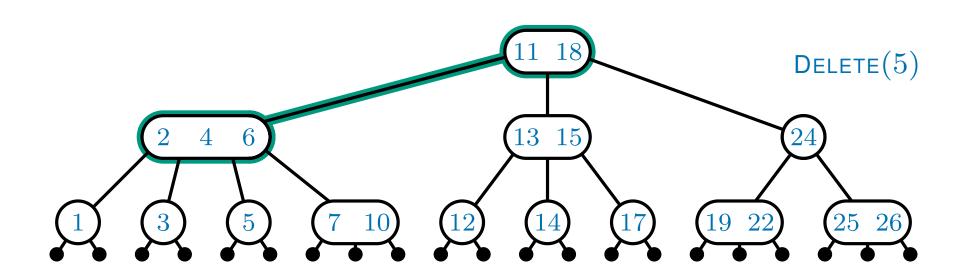
Step 1: Search for the key k using FIND(k).

Step 2: If the leaf is a 3-node,

delete (x, k), converting it into a 2-node

Step 3: If the leaf is a 4-node,





To perform DELETE(k) on a leaf (we'll deal with other nodes later)

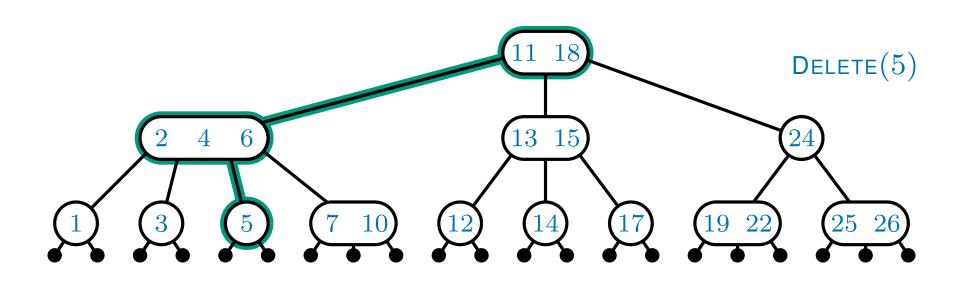
Step 1: Search for the key k using FIND(k).

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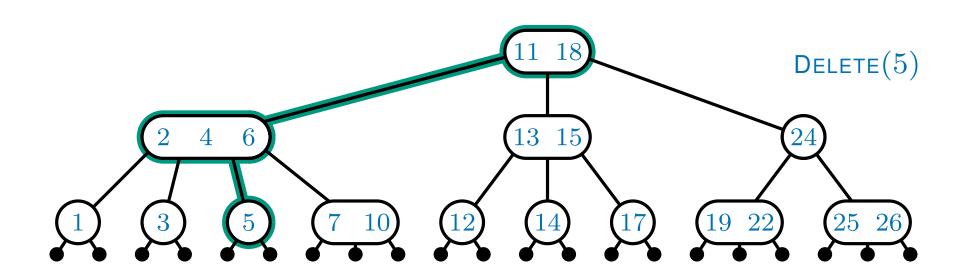
Step 1: Search for the key k using FIND(k).

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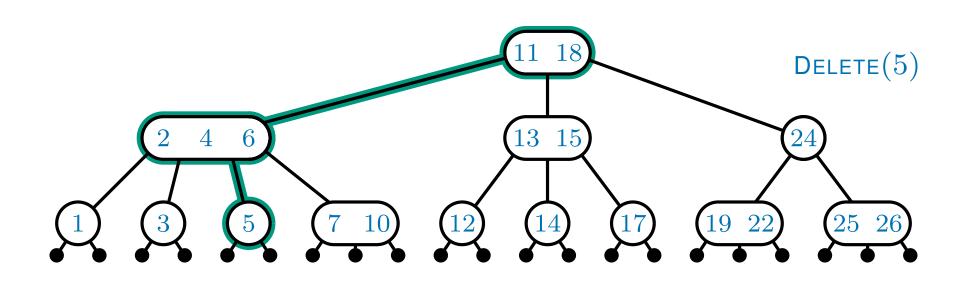
delete (x, k), converting it into a 2-node

Step 3: If the leaf is a 4-node,

delete (x, k), converting it into a 3-node

Step 4: If the leaf is a 2-node,





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Step 1: Search for the key k using FIND(k).

Step 2: If the leaf is a 3-node,

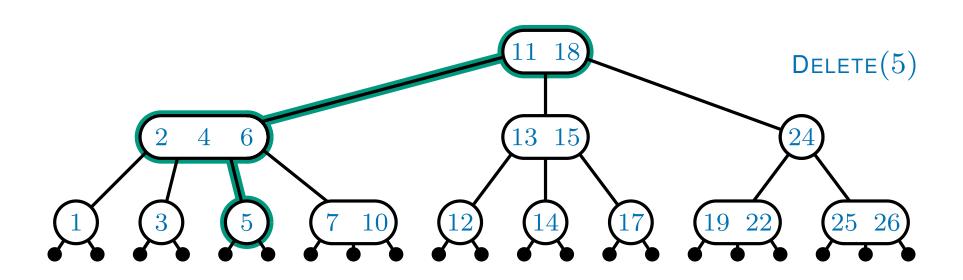
delete (x, k), converting it into a 2-node

Step 3: If the leaf is a 4-node,

delete (x, k), converting it into a 3-node

Step 4: If the leaf is a 2-node, 227





To perform DELETE(k) on a leaf (we'll deal with other nodes later)

Step 1: Search for the key k using FIND(k).

Step 2: If the leaf is a 3-node,

delete (x, k), converting it into a 2-node

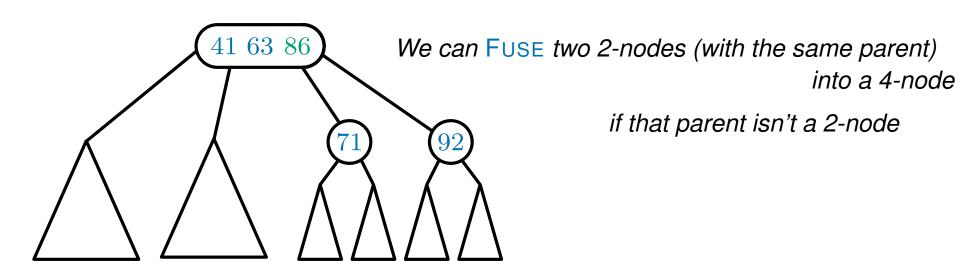
Step 3: If the leaf is a 4-node,

delete (x, k), converting it into a 3-node

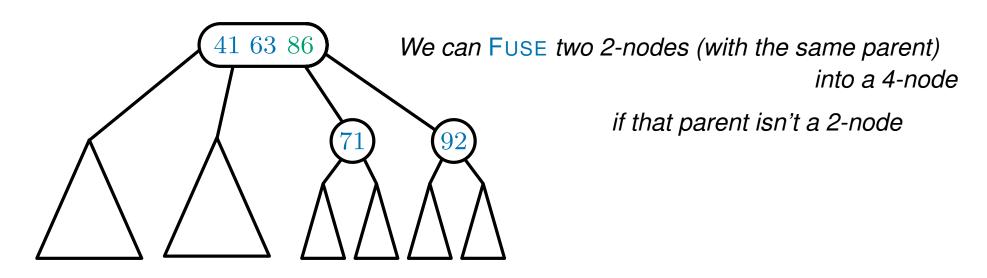
Step 4: If the leaf is a 2-node, ???

We will make sure this *never* happens

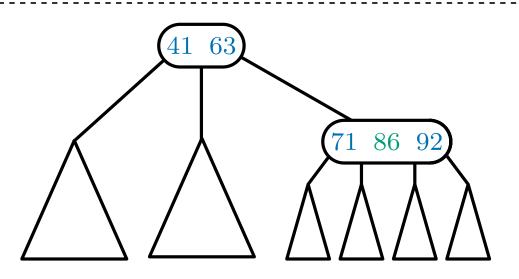






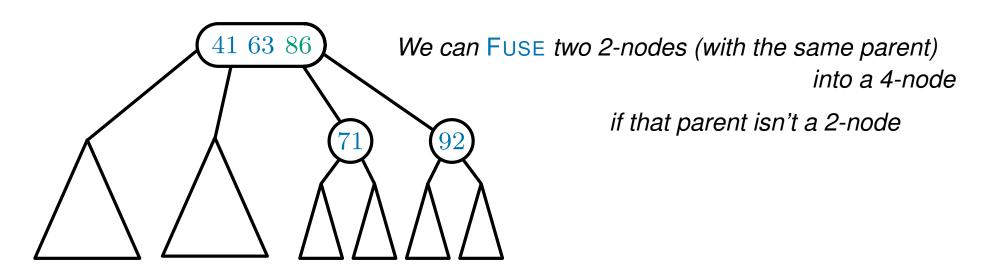


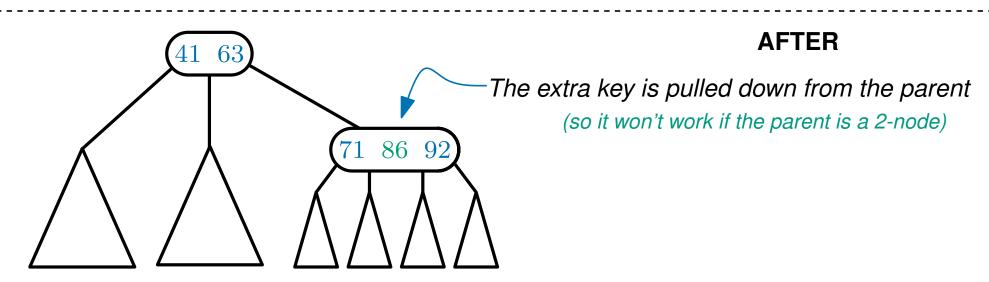
BEFORE



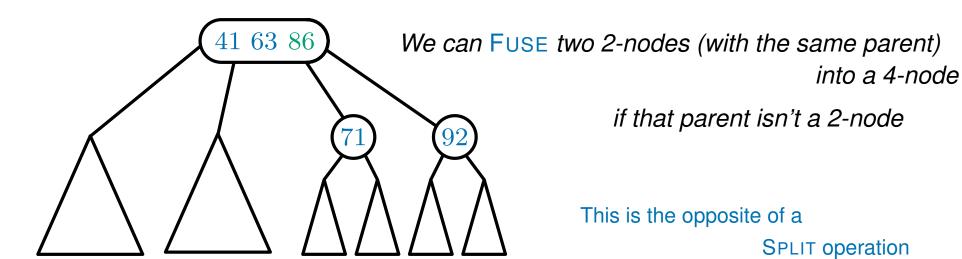
AFTER

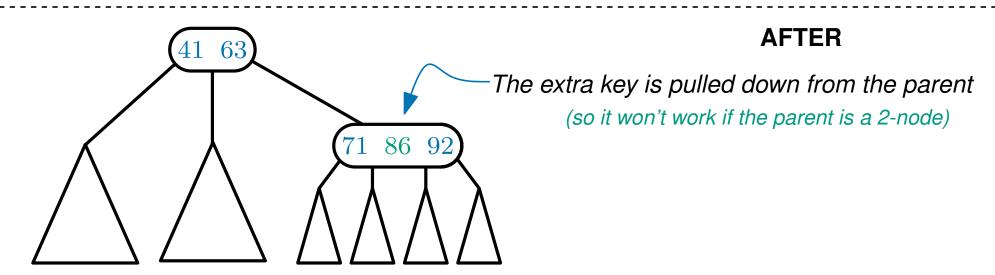




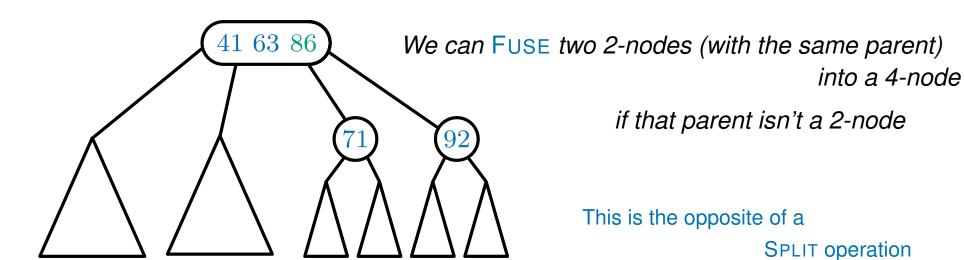


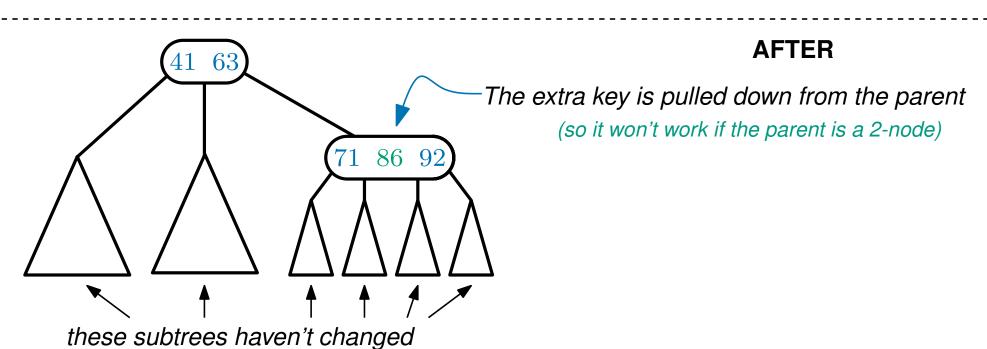




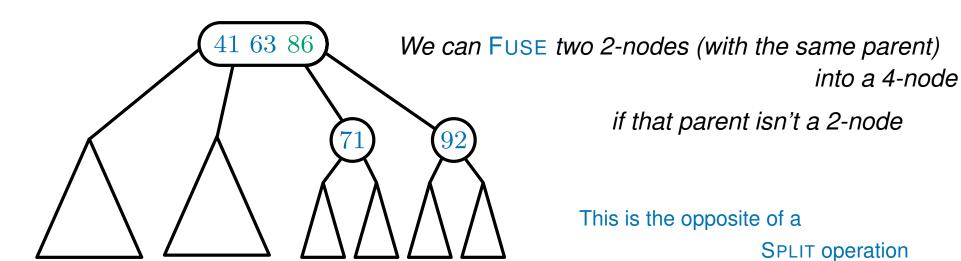




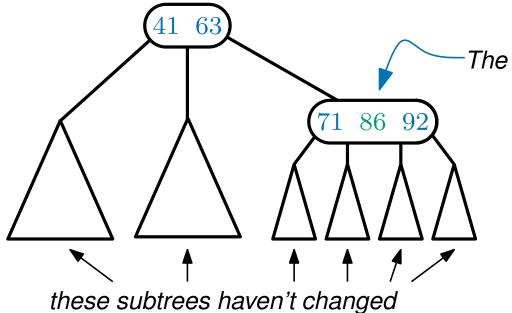








BEFORE

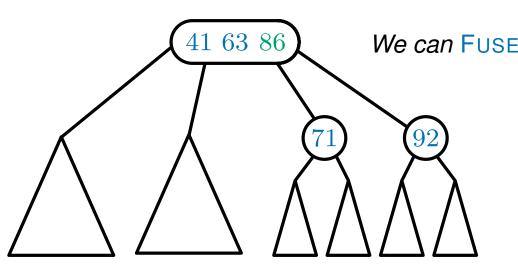


AFTER

The extra key is pulled down from the parent (so it won't work if the parent is a 2-node)

no path lengths have changed



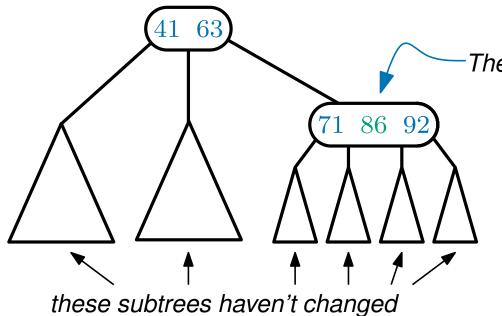


We can Fuse two 2-nodes (with the same parent) into a 4-node

if that parent isn't a 2-node

This is the opposite of a SPLIT operation

BEFORE



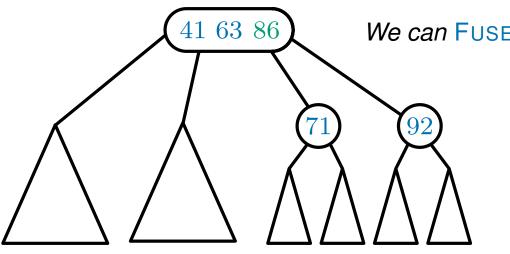
AFTER

The extra key is pulled down from the parent (so it won't work if the parent is a 2-node)

no path lengths have changed

(if it was perfectly balanced, it still is)



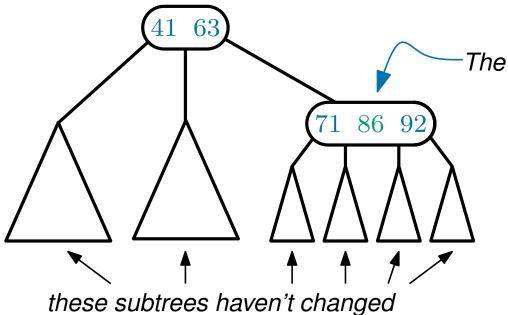


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AFTER

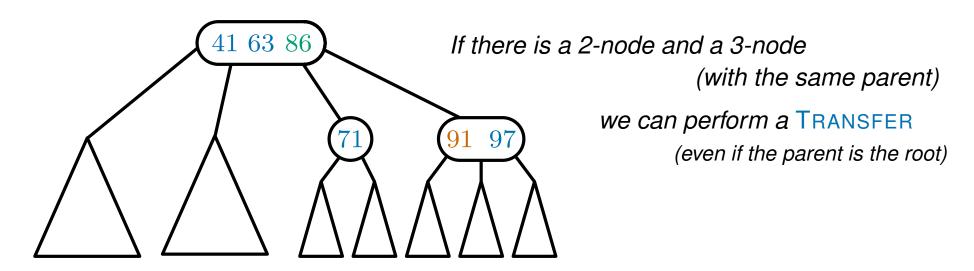
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no path lengths have changed

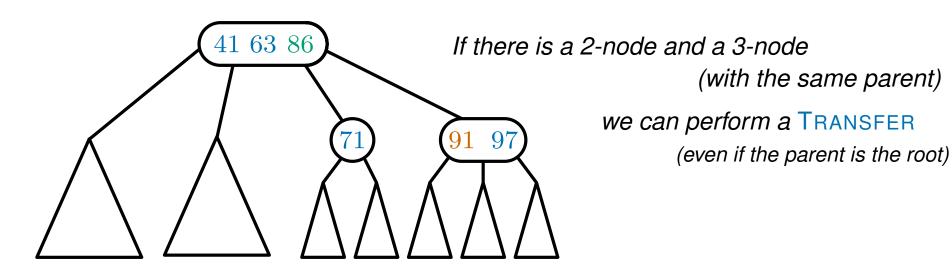
(if it was perfectly balanced, it still is)

FUSE takes O(1) time

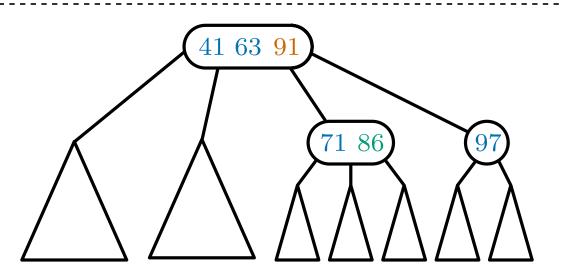






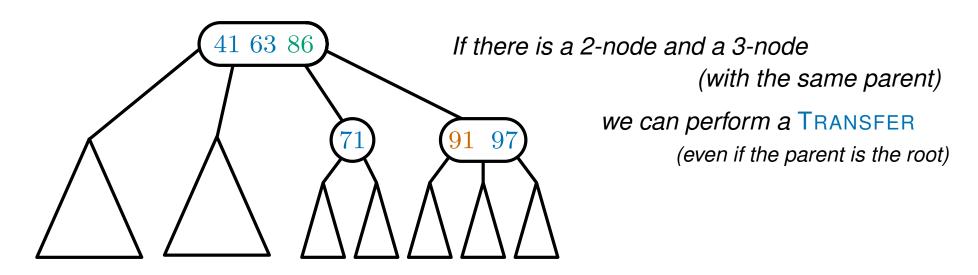


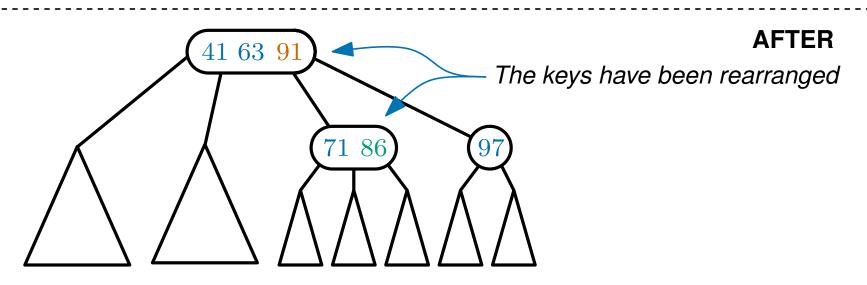
BEFORE



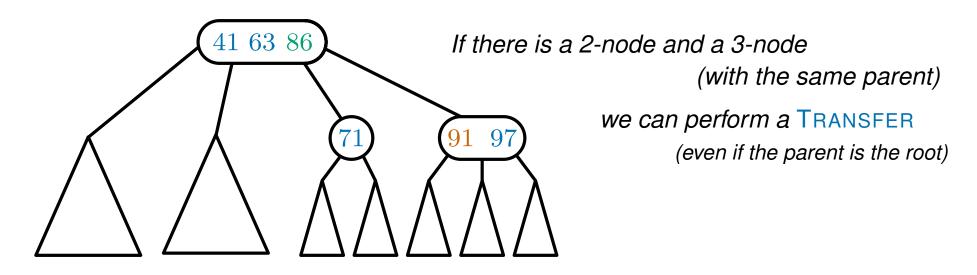
AFTER

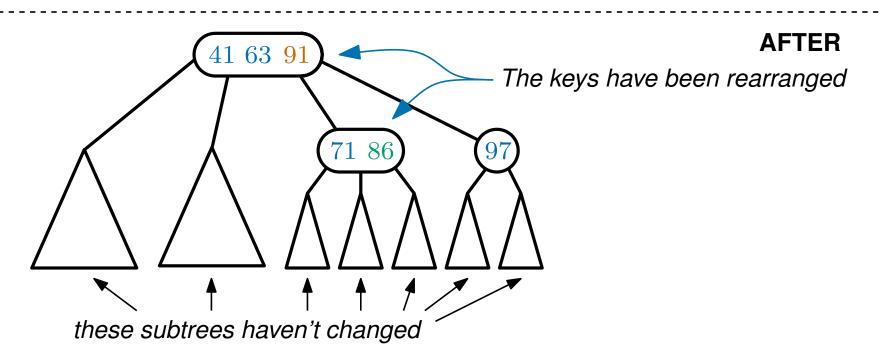




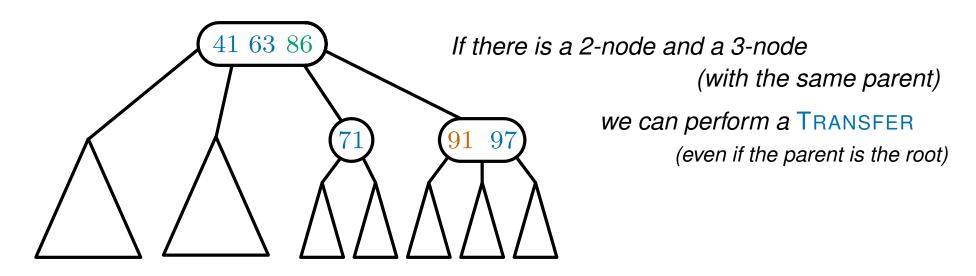


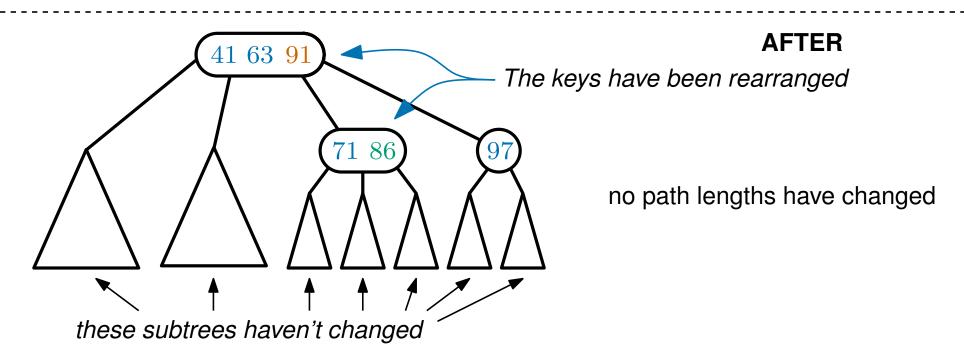




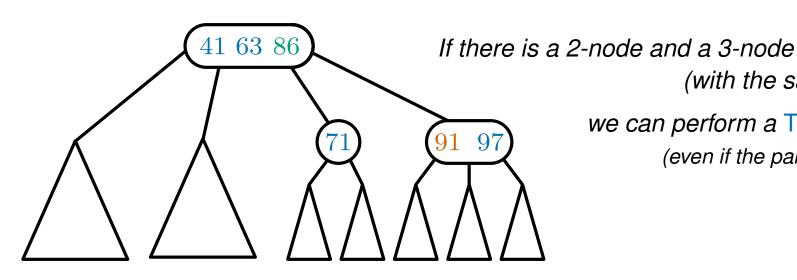








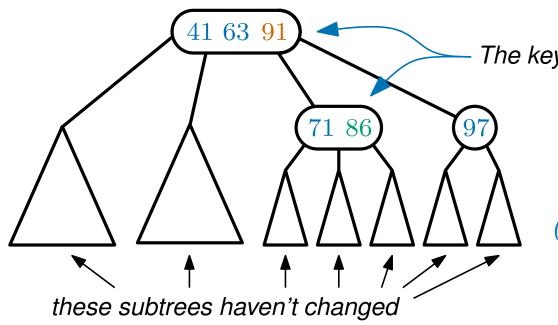




(with the same parent)

we can perform a TRANSFER (even if the parent is the root)

BEFORE



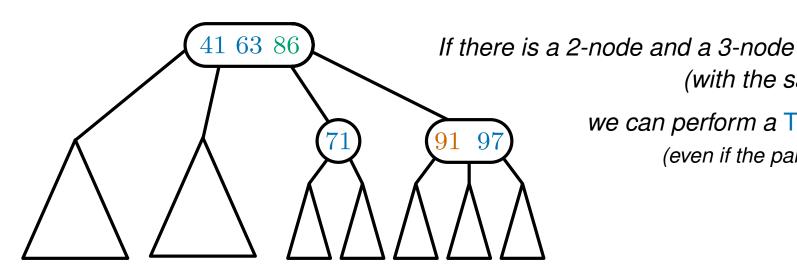
The keys have been rearranged

AFTER

no path lengths have changed

(if it was perfectly balanced, it still is)

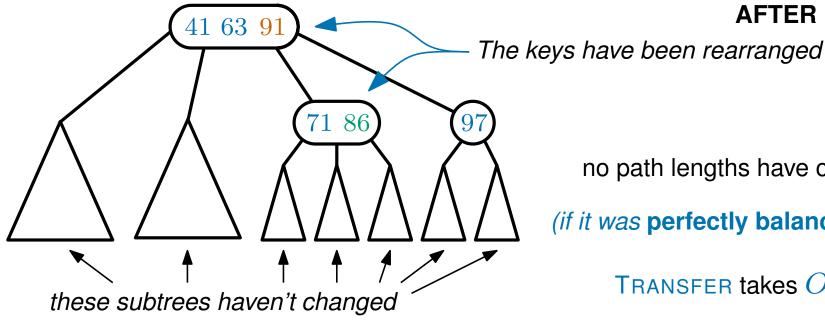




(with the same parent)

we can perform a TRANSFER (even if the parent is the root)

BEFORE



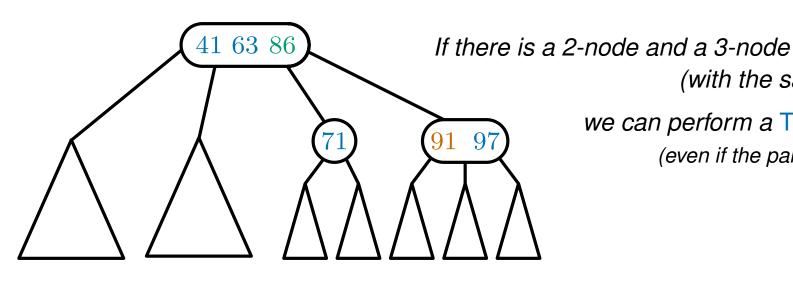
AFTER

no path lengths have changed

(if it was perfectly balanced, it still is)

TRANSFER takes O(1) time

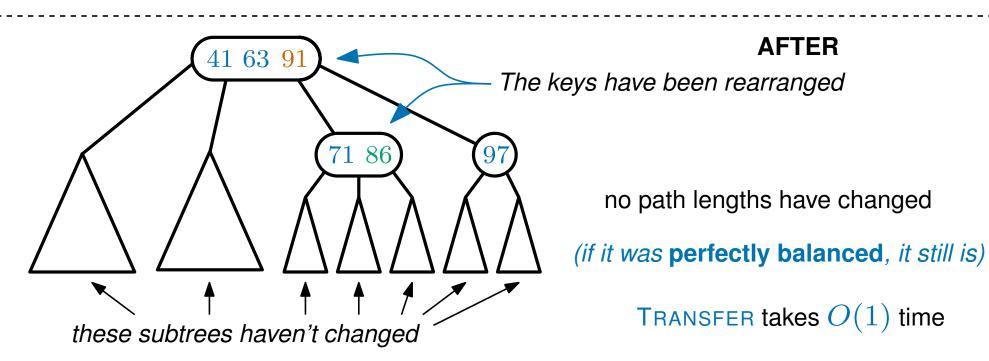




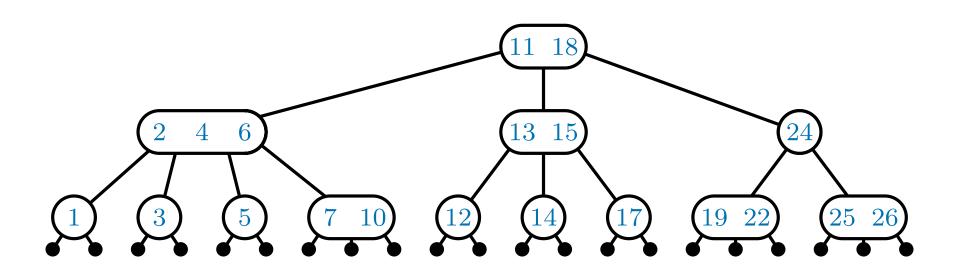
(with the same parent)

we can perform a TRANSFER (even if the parent is the root)

TRANSFER also works with a 2-node and a 4-node





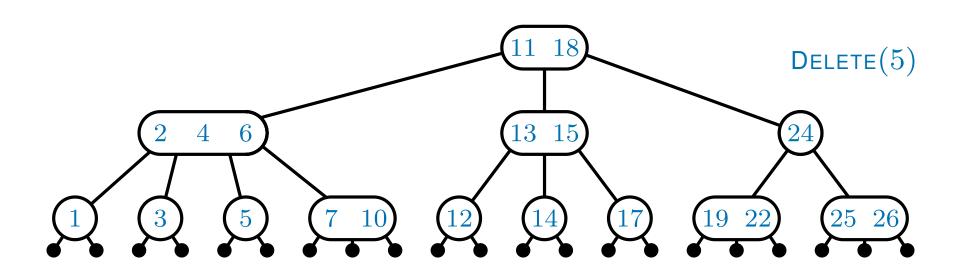


To perform DELETE(k) on a leaf (we'll deal with other nodes later)

Step 1: Search for the key k using $\mathsf{FIND}(k)$. use FUSE and $\mathsf{TRANSFER}$ to convert 2-nodes as we go down

Step 2: If the leaf is a 3-node, delete (x, k), converting it into a 2-node



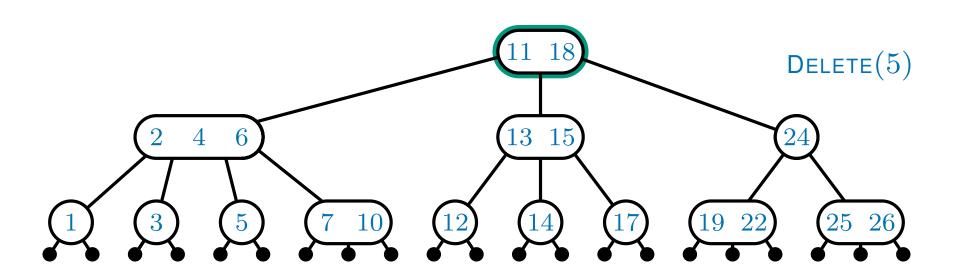


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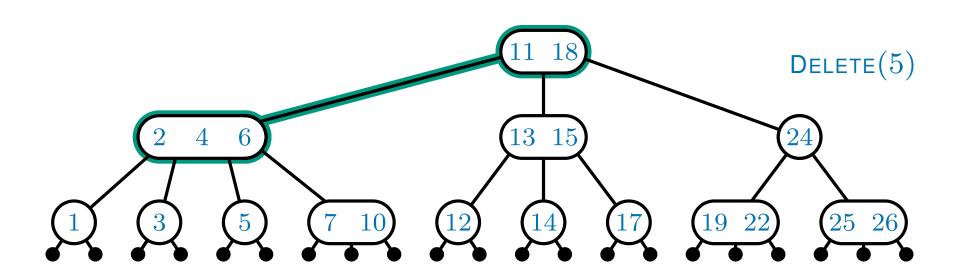


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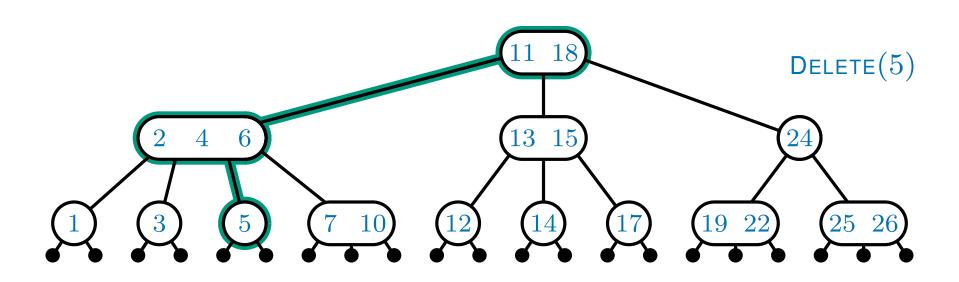


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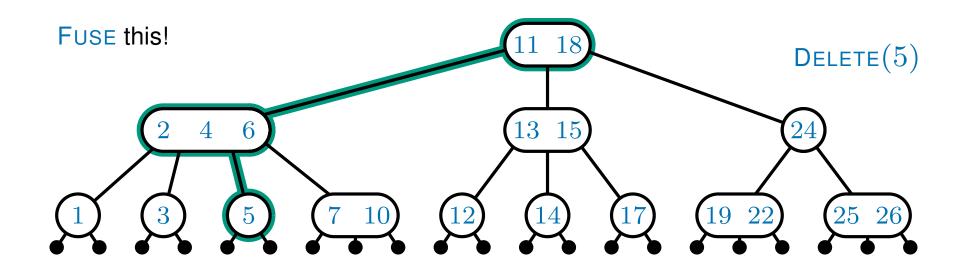


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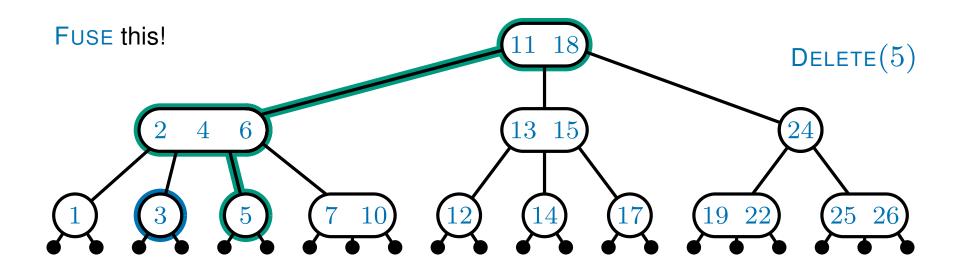


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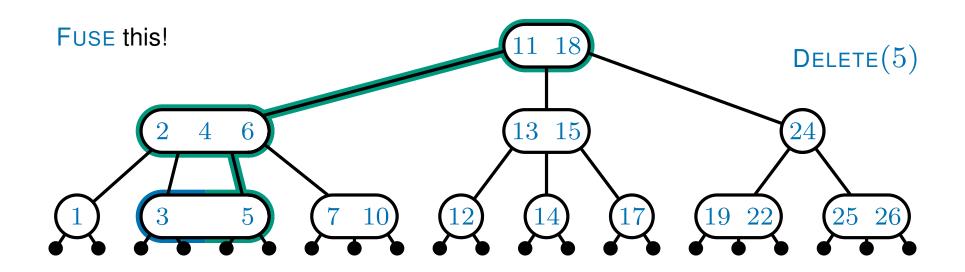


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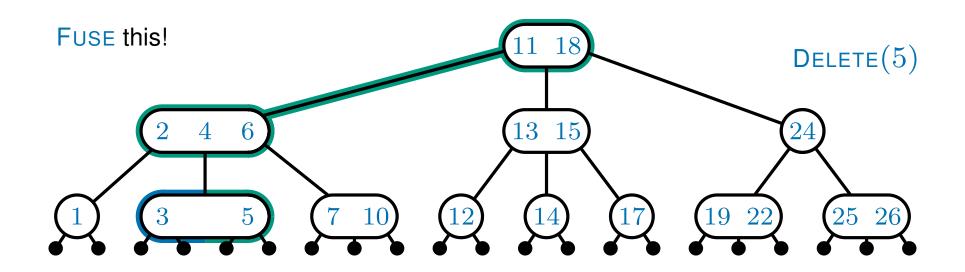


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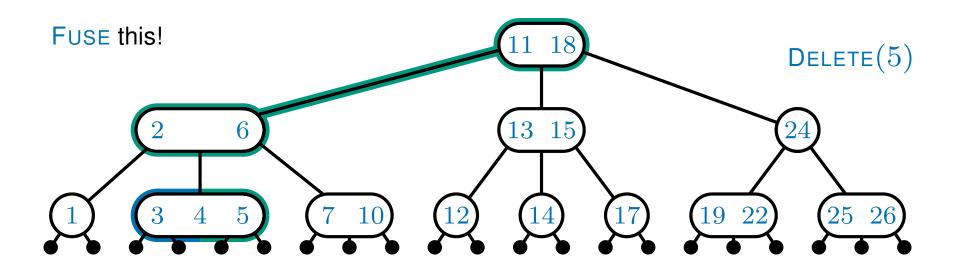


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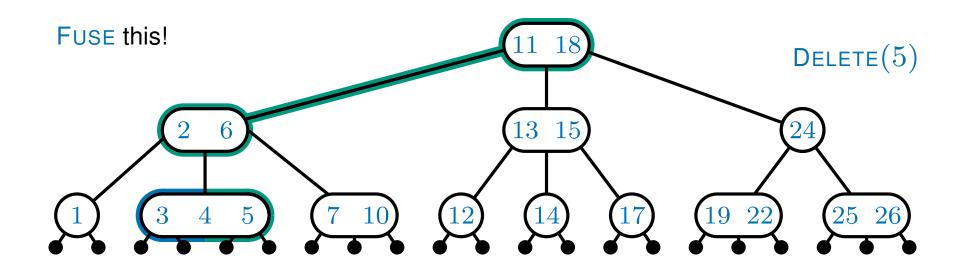


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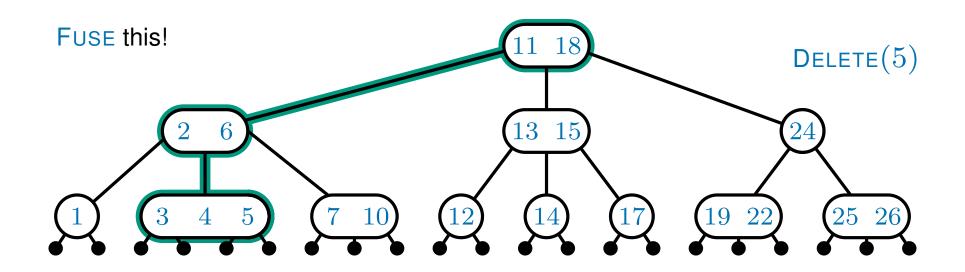


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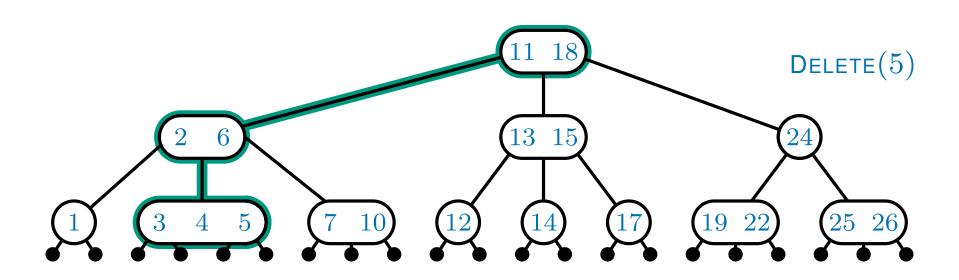


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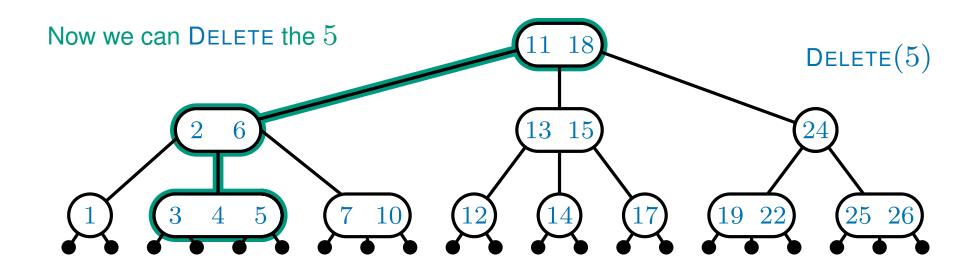


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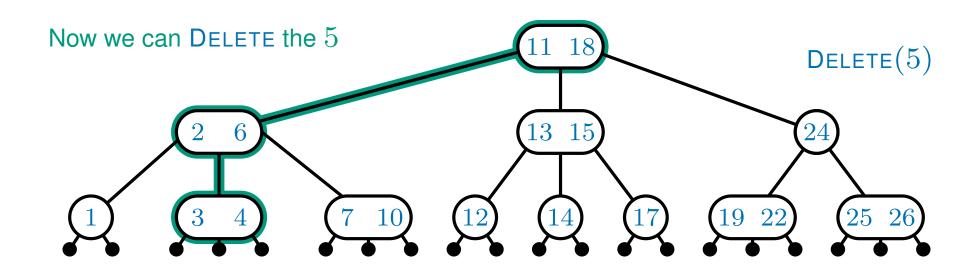


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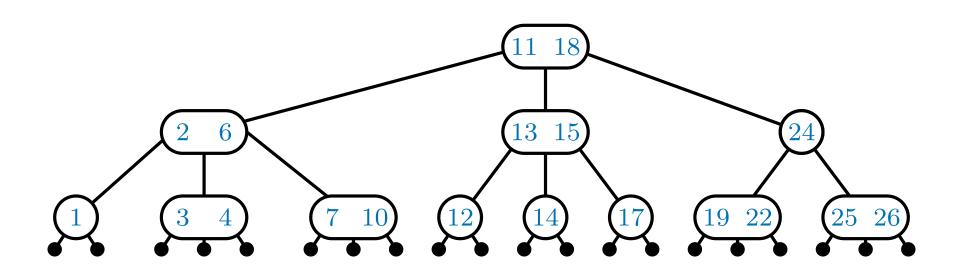


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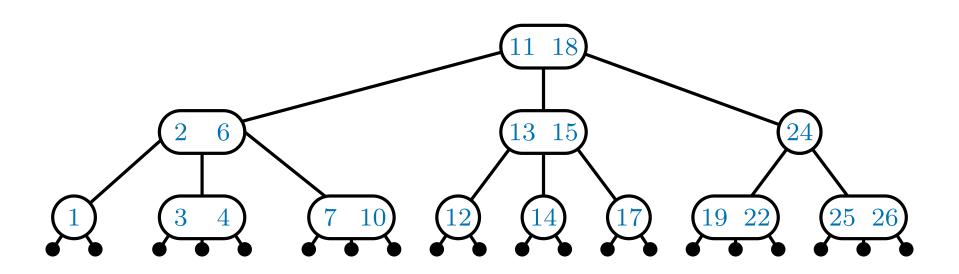




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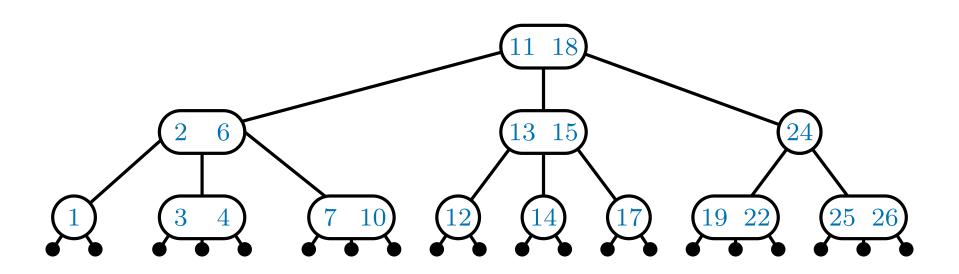
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Step 2: If the leaf is a 3-node, delete (x, k), converting it into a 2-node

Step 3: If the leaf is a 4-node, delete (x, k), converting it into a 3-node

OK, one more thing...





To perform DELETE(k) on a leaf (we'll deal with other nodes later)

Step 1: Search for the key k using $\mathsf{FIND}(k)$. use FUSE and $\mathsf{TRANSFER}$ to convert 2-nodes as we go down

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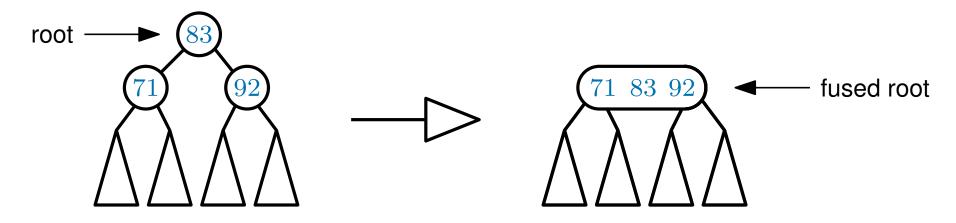
Step 3: If the leaf is a 4-node, delete (x, k), converting it into a 3-node

OK, one more thing... what happens when we FUSE the root?



Fusing the root

We said that we could only FUSE two 2-nodes if the parent was not a 2-node... we make an exception for the root

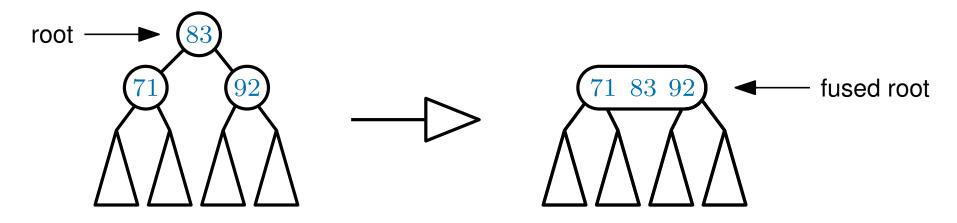


FUSING the root can decrease the height of the tree which in turn decreases the length of all root-leaf paths by one



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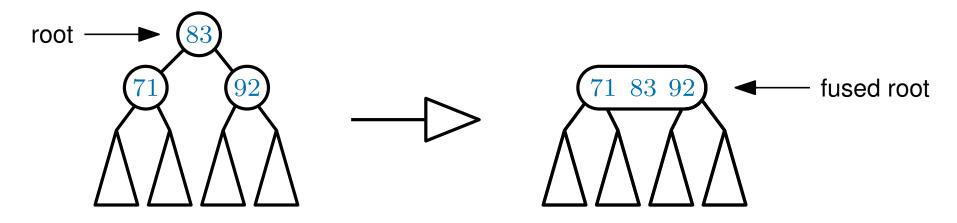
So it maintains the **perfect balance** property

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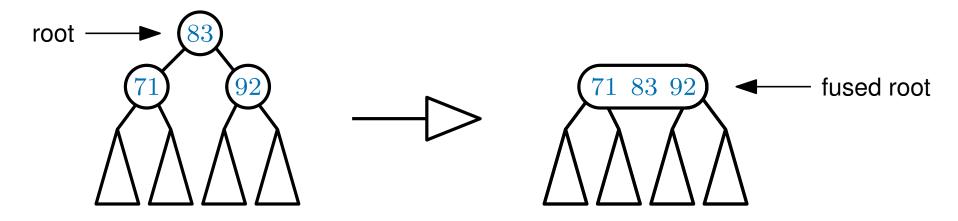
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This is the only way DELETE can affect the length of paths so it also maintains the **perfect balance** property



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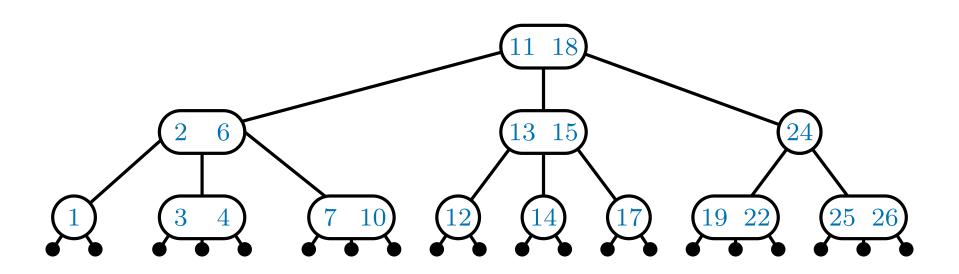
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This is the only way DELETE can affect the length of paths so it also maintains the **perfect balance** property

As each Fuse or Transfer takes O(1) time, overall Delete takes $O(\log n)$ time





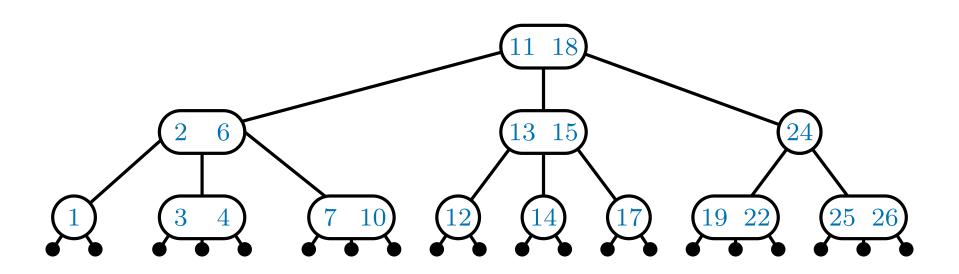
To perform DELETE(k) on a leaf (we'll deal with other nodes later)

Step 1: Search for the key k using $\mathsf{FIND}(k)$. use FUSE and $\mathsf{TRANSFER}$ to convert 2-nodes as we go down

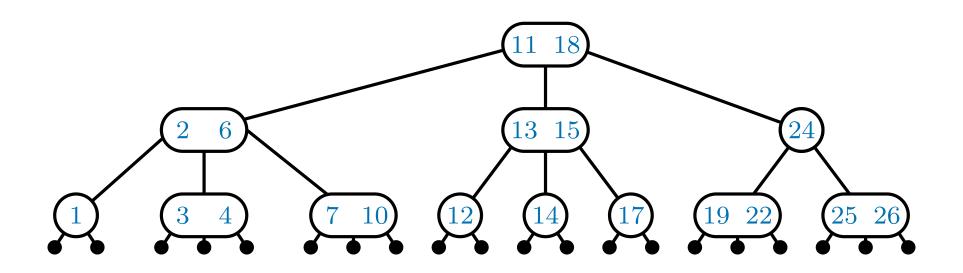
Step 2: If the leaf is a 3-node, delete (x, k), converting it into a 2-node

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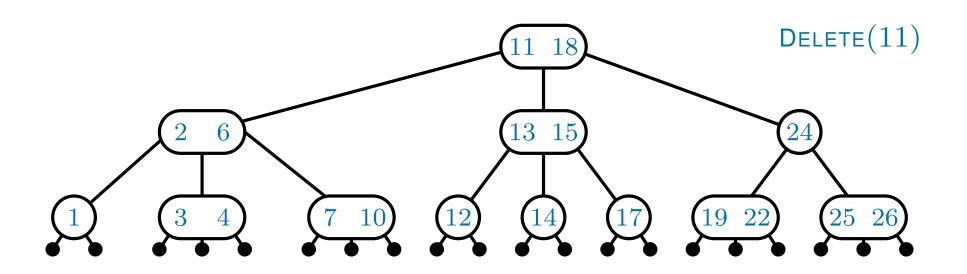
What if we want to **DELETE** something other than a leaf?



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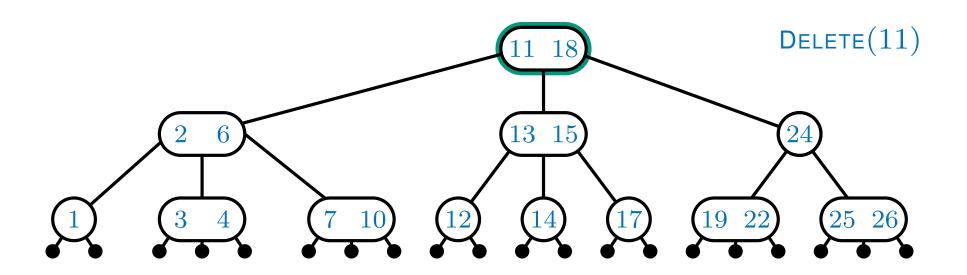
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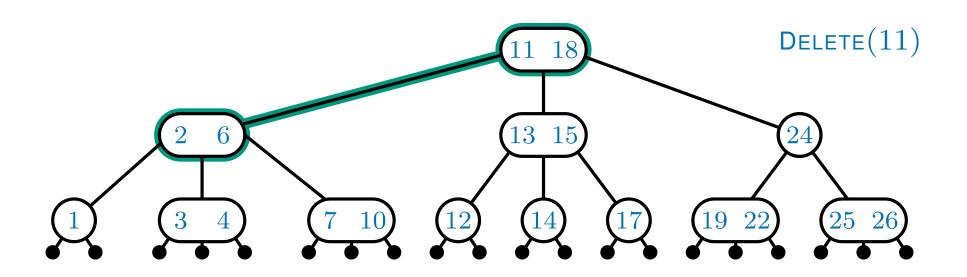
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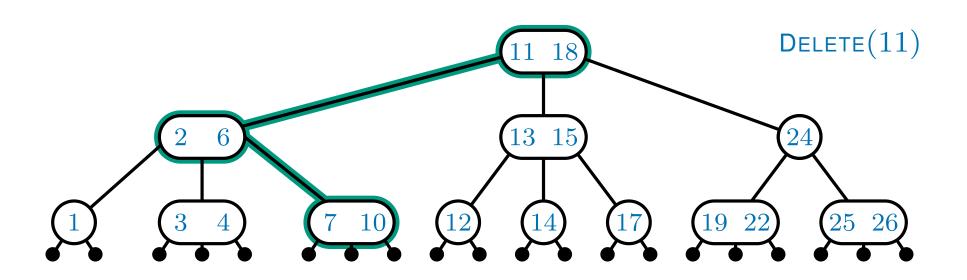
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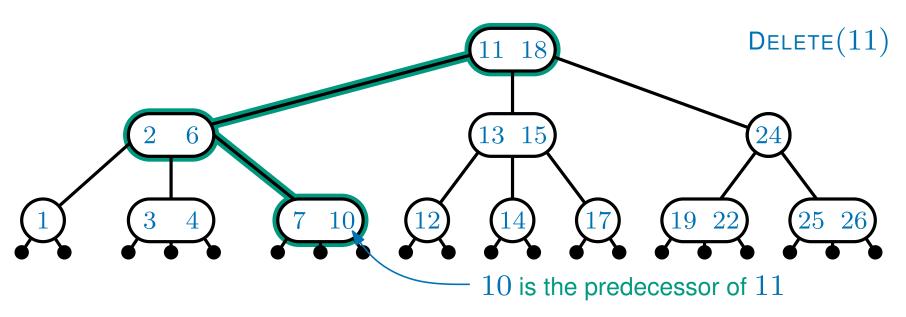
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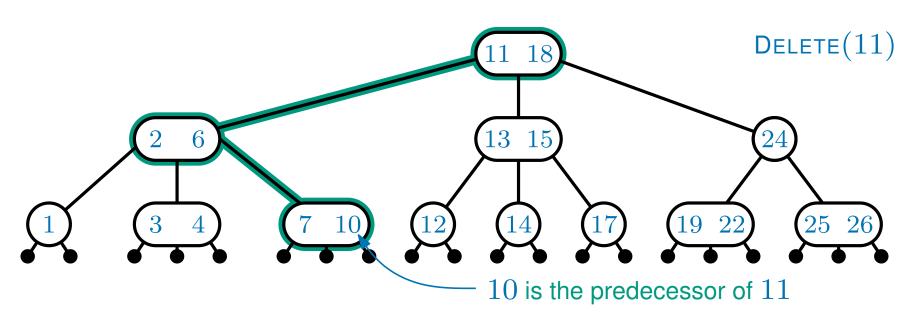
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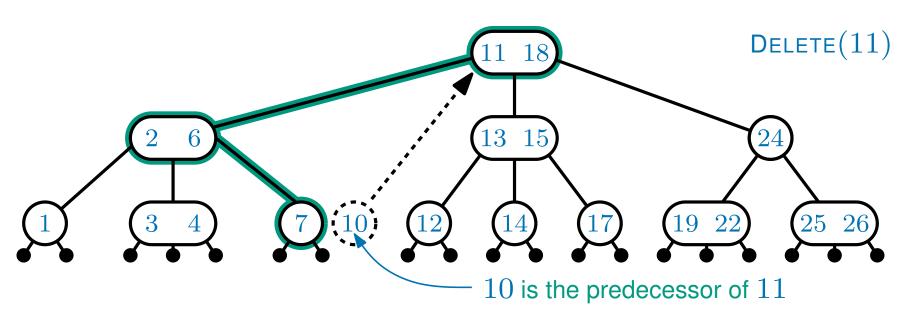
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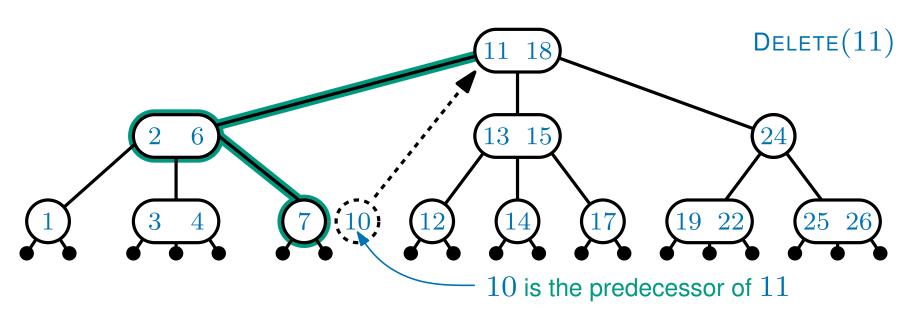
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University of BRISTOL

The **DELETE** operation



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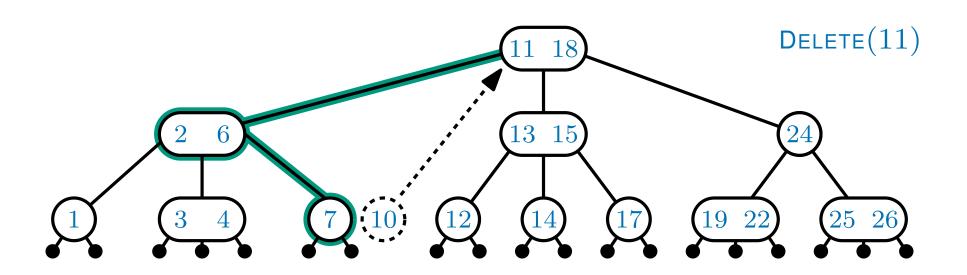
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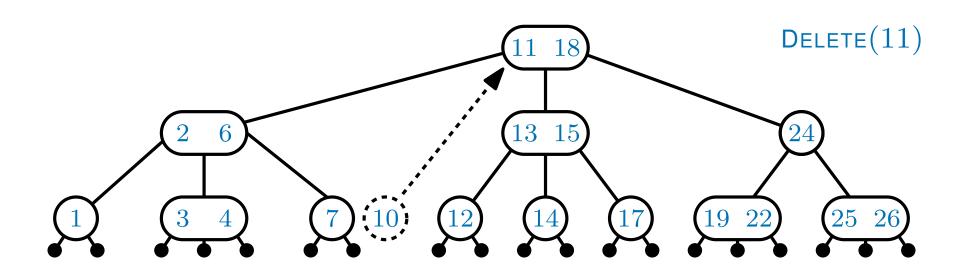
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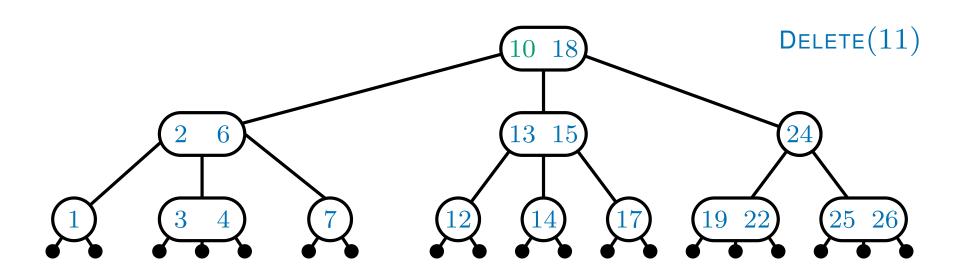
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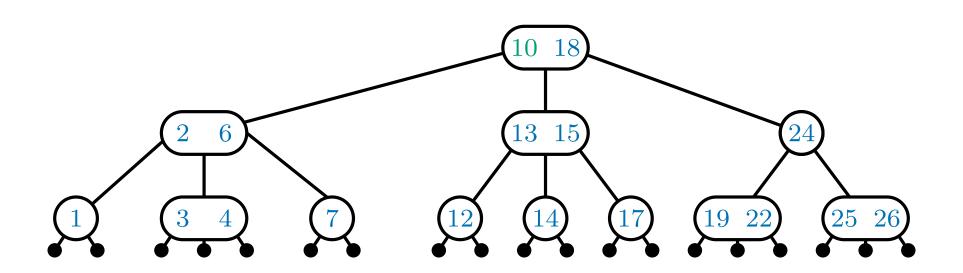
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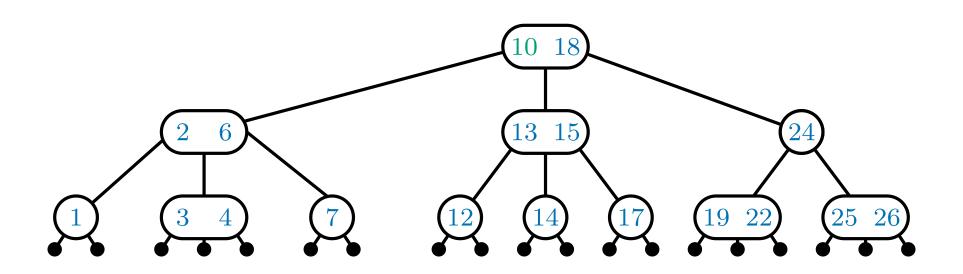
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Step 3: Overwrite k with another copy of k'

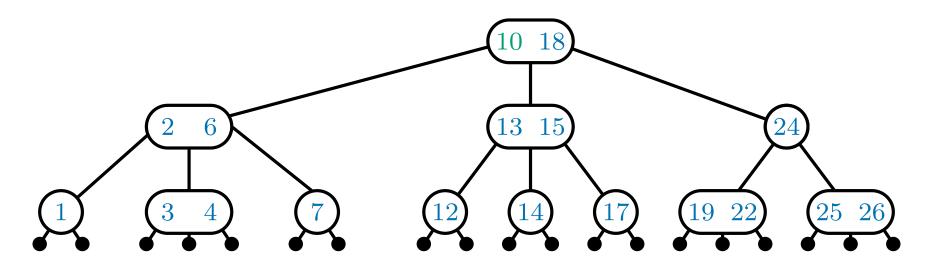
This also takes $O(\log n)$ time



2-3-4 tree summary

A 2-3-4 is a data structure based on a tree structure

which supports $\mathsf{INSERT}(x,k)$, $\mathsf{FIND}(k)$ and $\mathsf{DELETE}(k)$



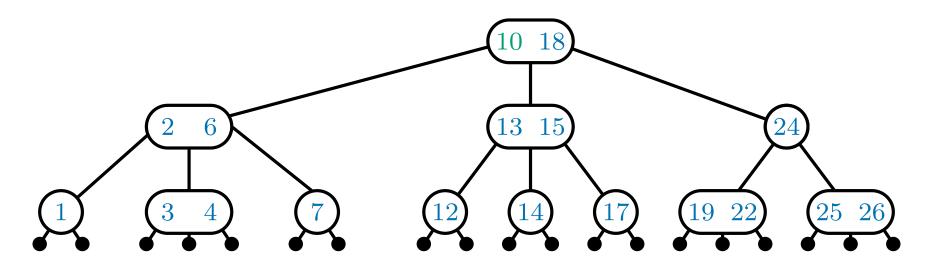
each of these operations takes *worst case* $O(\log n)$ time



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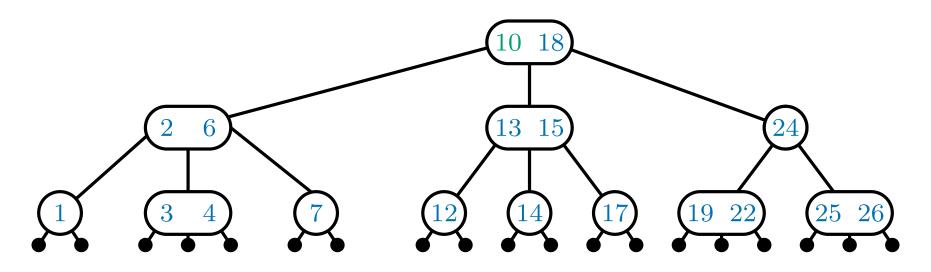
Unfortunately, 2-3-4 trees are awkward to implement because the nodes don't all have the same number of children



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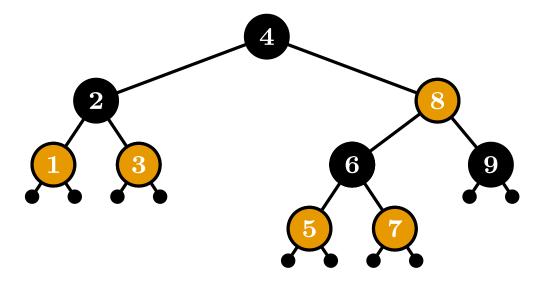
Unfortunately, 2-3-4 trees are awkward to implement because the nodes don't all have the same number of children

So, what is used in practice?



A Red-Black tree is a data structure based on a binary tree structure

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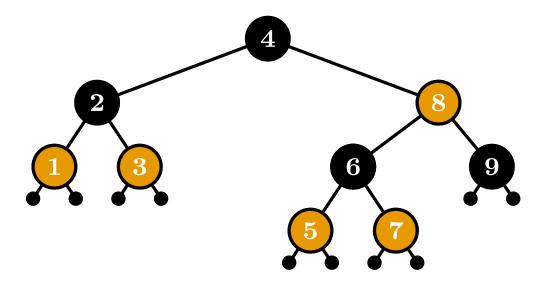


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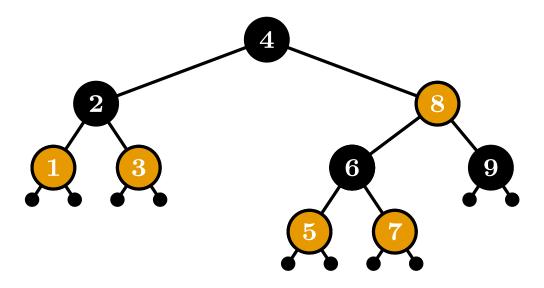
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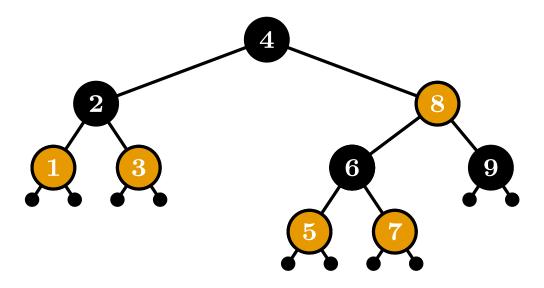
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All root-to-leaf paths have the same number of **black** nodes



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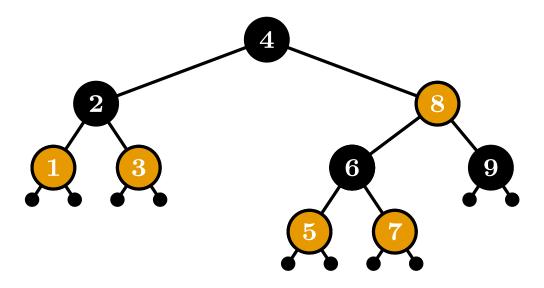
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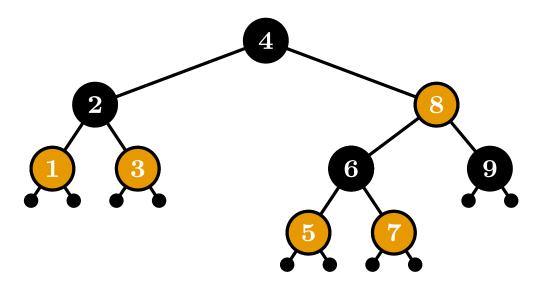
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If these are used in practice, why did you waste our time with 2-3-4 trees?



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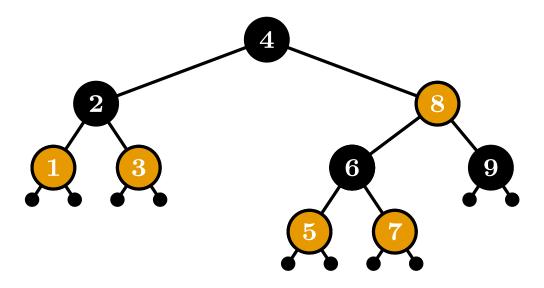
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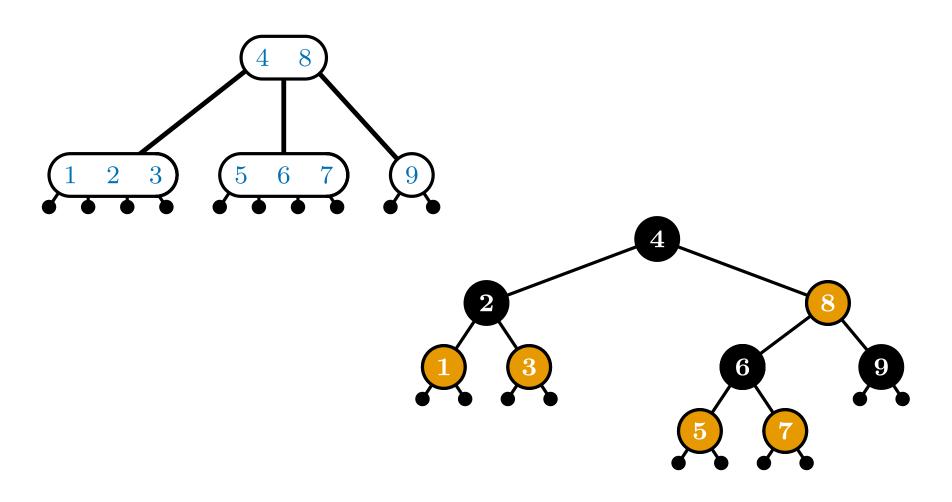
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If these are used in practice, why did you waste our time with 2-3-4 trees?

1. 2-3-4 trees are conceptually much nicer **2.** they are secretly the same :)

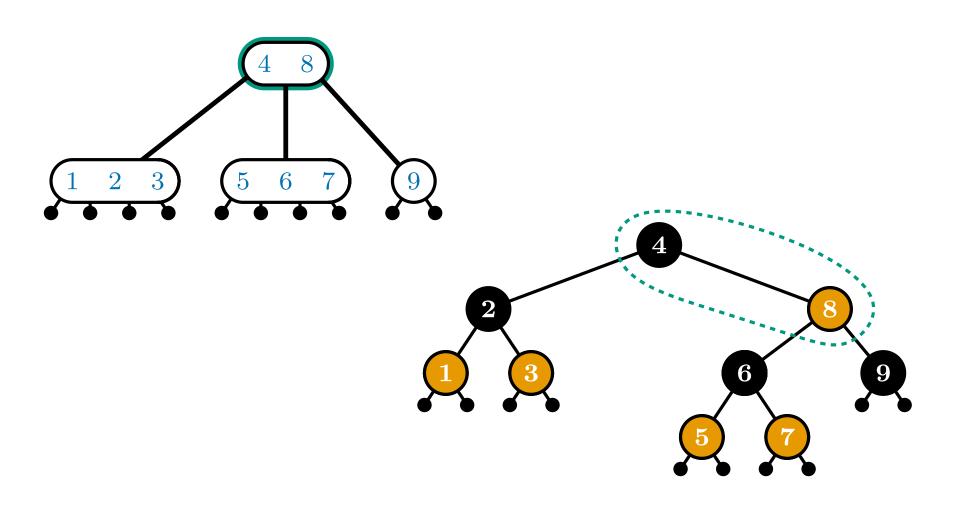


Any 2-3-4 tree can be converted into a Red-Black tree (and visa-versa)



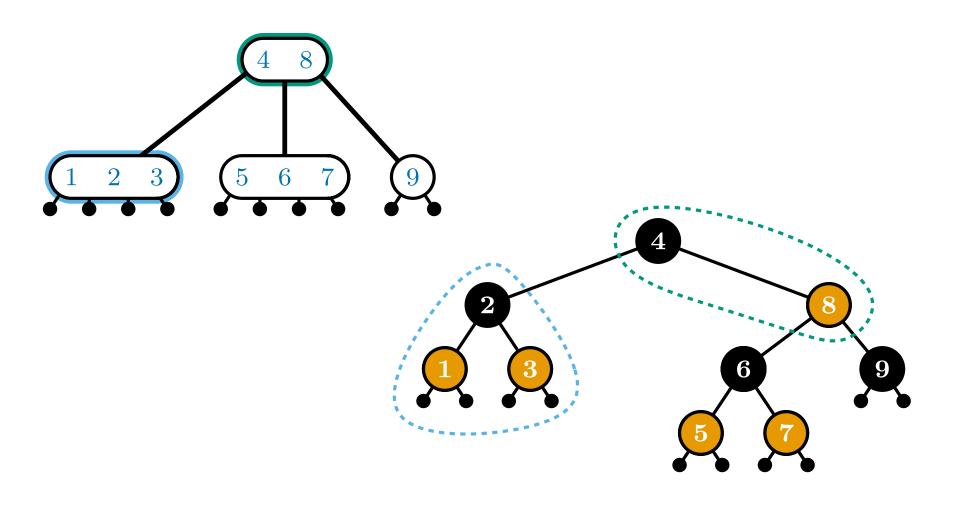


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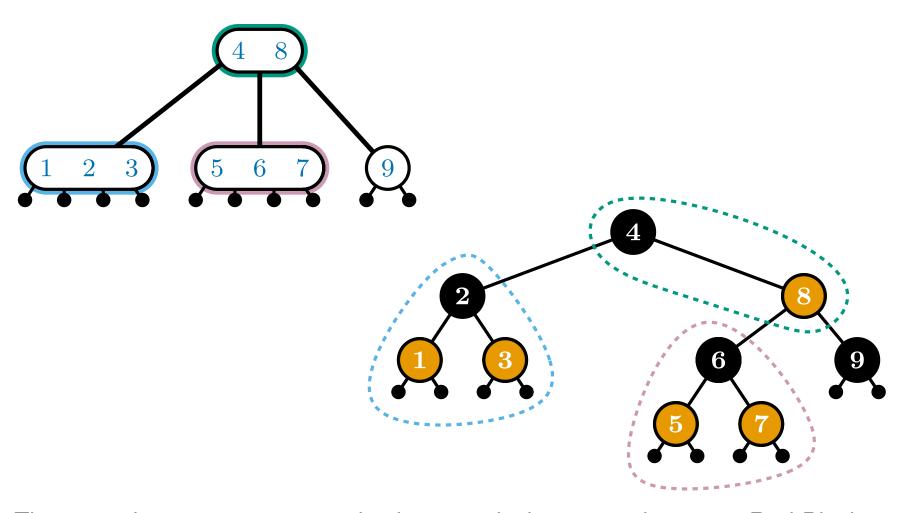


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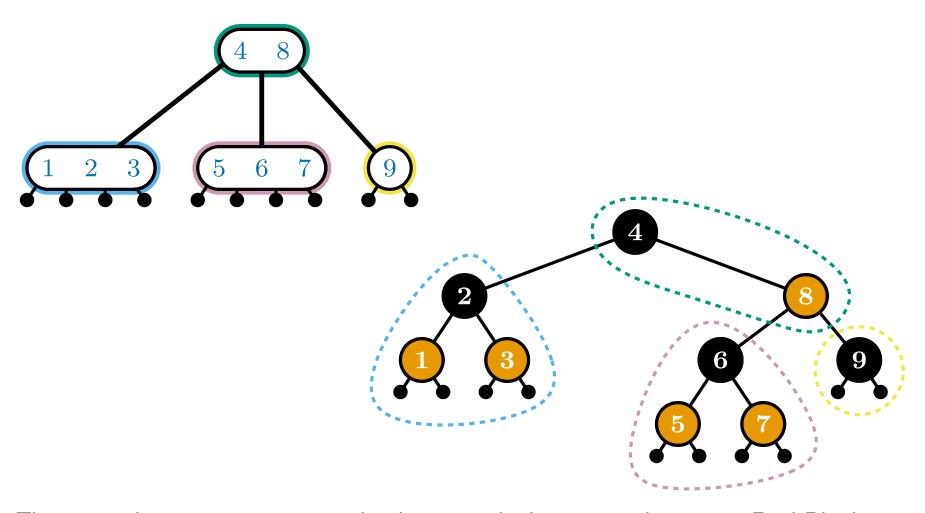


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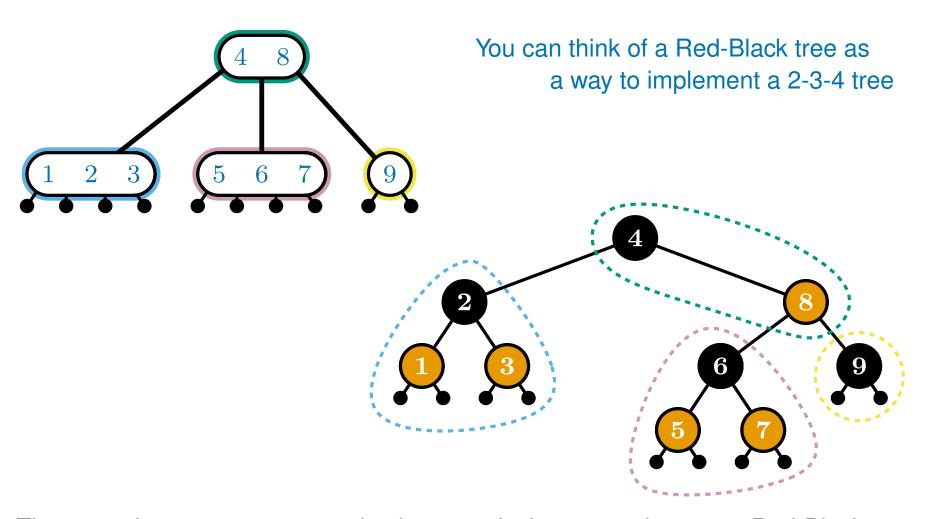


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Dynamic Search Structure Summary

A dynamic search structure supports (at least) the following three operations

Delete k - deletes the (unique) element x with $x.{\sf key}=k$ ${\sf INSERT}(x,k) \text{ - inserts } x \text{ with key } k=x.{\sf key}$

FIND(k) - returns the (unique) element x with x.key = k

Here are the worst case time complexities of the structures we have seen...

	INSERT	DELETE	FIND
Unsorted Linked List	O(1)	O(n)	O(n)
Binary Search Tree	O(n)	O(n)	O(n)
2-3-4 Tree	$O(\log n)$	$O(\log n)$	$O(\log n)$
Red-Black Tree	$O(\log n)$	$O(\log n)$	$O(\log n)$



End of part one



Part two

Skip lists



Dynamic Search Structures

A dynamic search structure,

stores a set of elements

Each element x must have a unique key - x.key

The following operations are supported:

INSERT(x, k) - inserts x with key k = x.key

FIND(k) - returns the (unique) element x with x.key = k

(or reports that it doesn't exist)

DELETE(k) - deletes the (unique) element x with x.key = k

(or reports that it doesn't exist)

We would also like it to support:

 $\frac{\text{PREDECESSOR}(k) - \text{returns the (unique) element } x}{\text{with the largest key such that } x.\text{key} < k}$

RangeFind (k_1,k_2) - returns every element x with $k_1\leqslant x.\mathsf{key}\leqslant k_2$



Earlier we briefly considered using an unsorted Linked List as a dynamic search structure



What about using a *sorted* Linked List?



The bottleneck is FIND, which is *very inefficient*,

- we have to look through the entire linked list to find an item
(in the worst case)

INSERT and DELETE also take O(n) time but only because they rely on FIND



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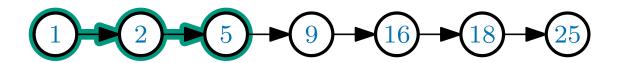


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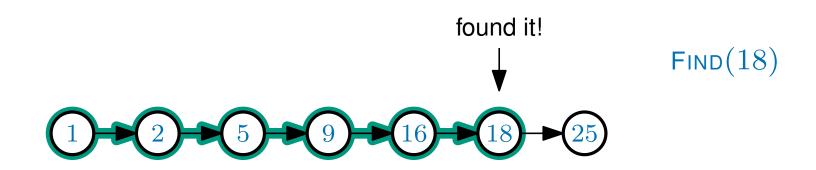
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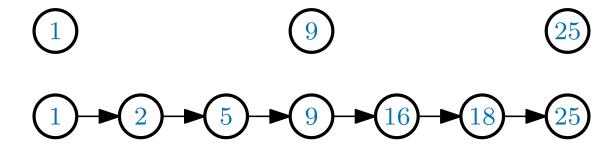
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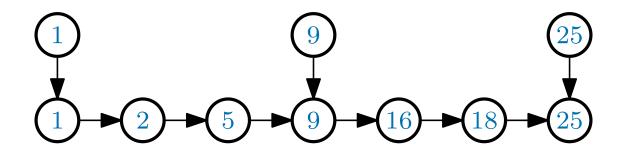
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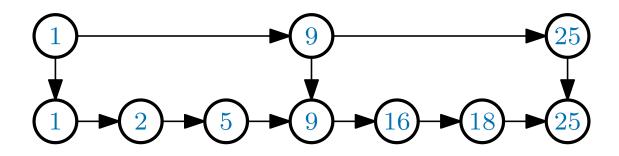






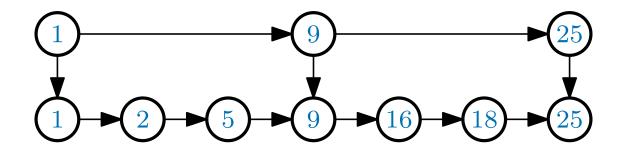






How about adding some shortcuts?

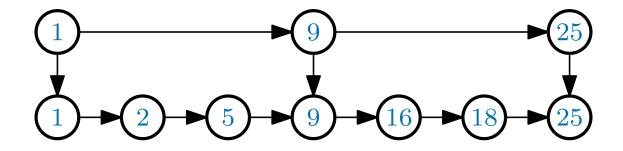
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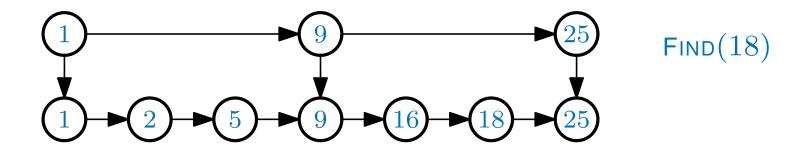


To perform ${\sf FIND}(k)$ we start in the top list and go right until we come to a key k'>k



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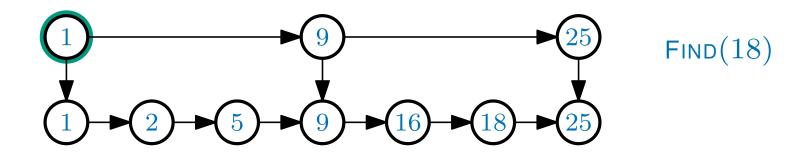


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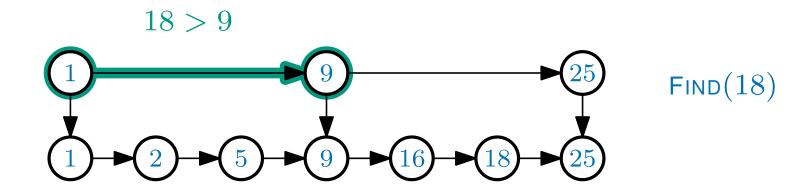


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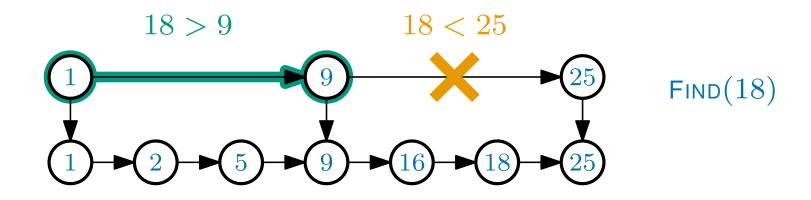


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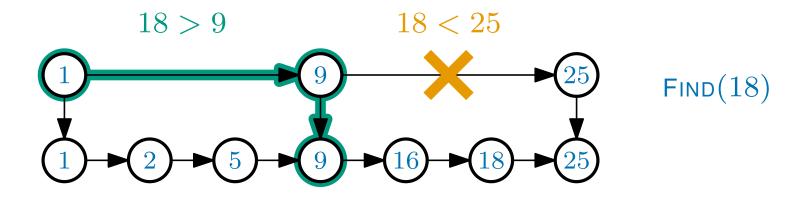


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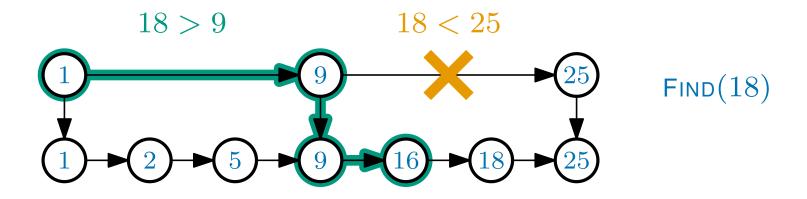


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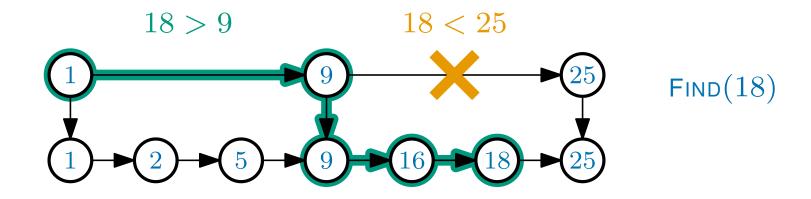


To perform ${\sf FIND}(k)$ we start in the top list and go right until we come to a key k'>k



How about adding some shortcuts?

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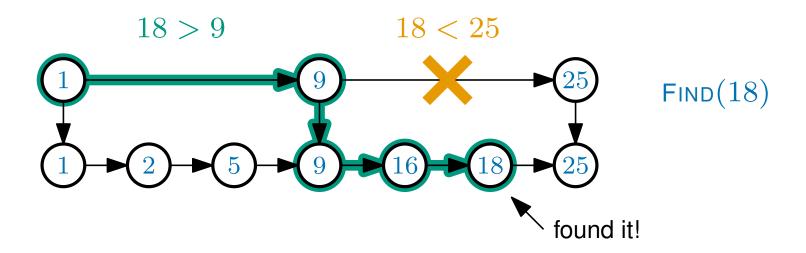


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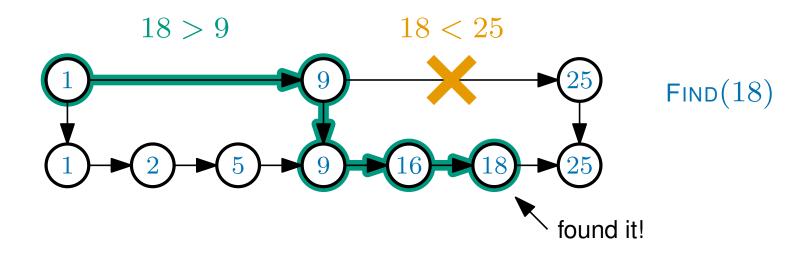
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University of BRISTOL

Making Shortcuts

How about adding some shortcuts?

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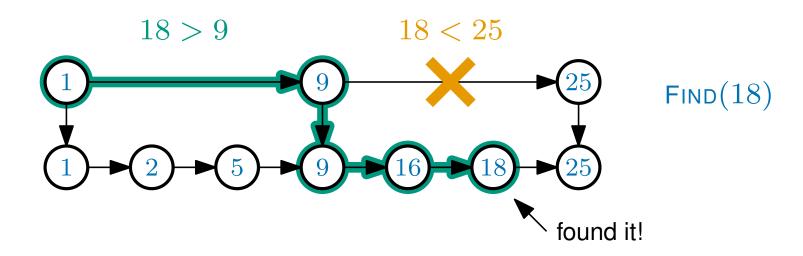
then we move down to the bottom list and go right until we find k

How long does this take?



How about adding some shortcuts?

We've attached a second linked list containing only some of the keys...



To perform ${\sf FIND}(k)$ we start in the top list and go right until we come to a key k'>k

then we move down to the bottom list and go right until we find k

How long does this take?

That depends on where we place the shortcuts

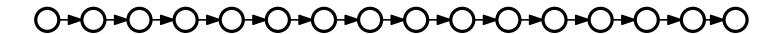


Imagine that we decide to place m keys in the top list... (the bottom list always contains all n keys)



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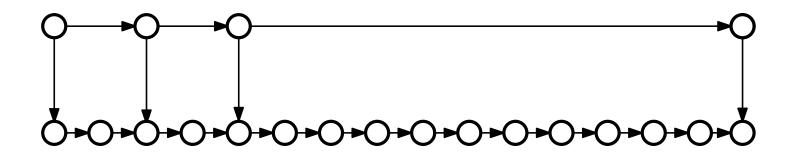
where should we put them to minimise the *worst case* time for a FIND operation?





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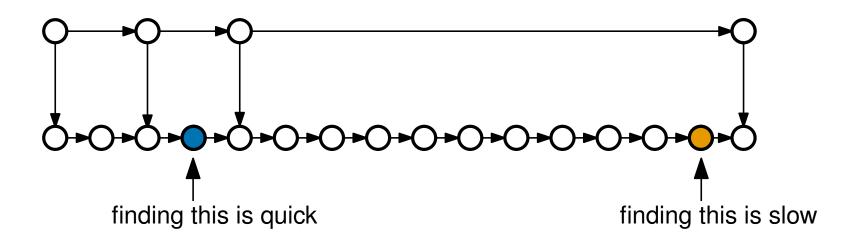
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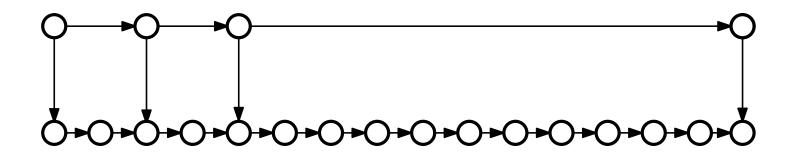
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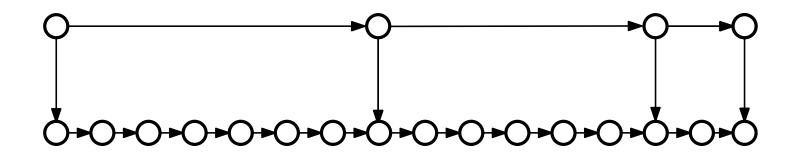
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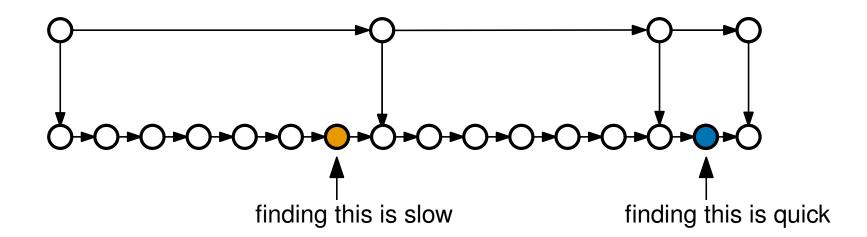
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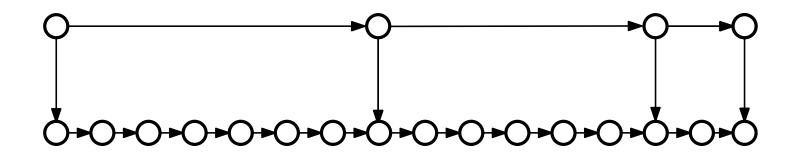
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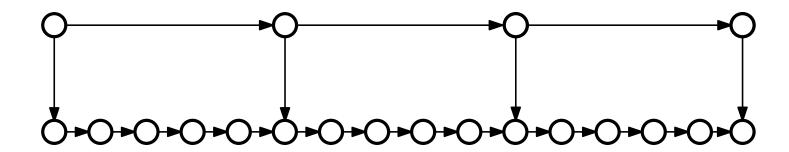
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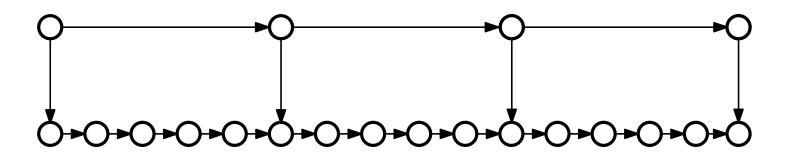




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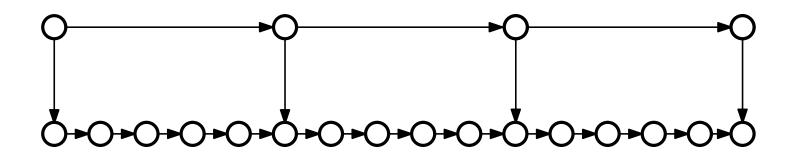
If we spread out the m keys in the top list evenly \dots



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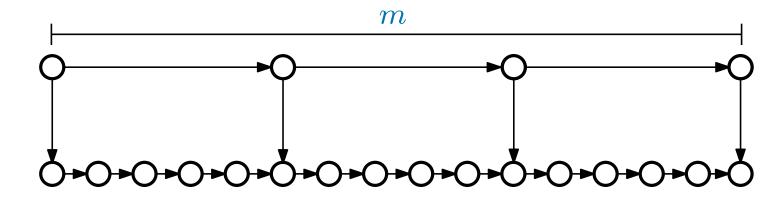
the *worst case* time for a FIND operation becomes O(m+n/m)



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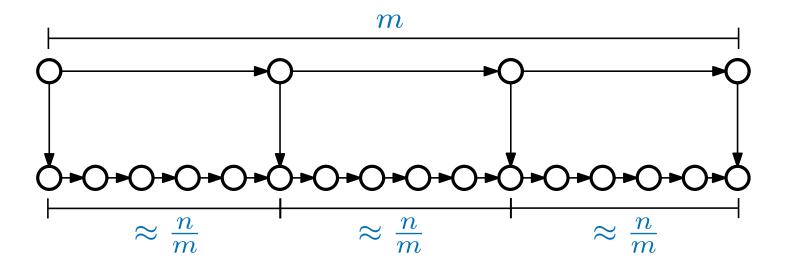
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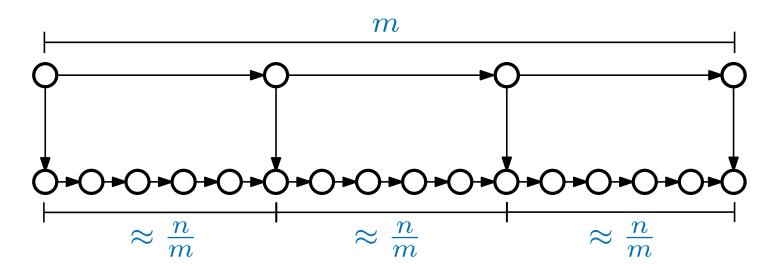


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the *worst case* time for a FIND operation becomes O(m+n/m)

By setting $m=\sqrt{n}$, we get

the *worst case* time for a FIND operation is $O(\sqrt{n})$



How about adding even more lists? (each list is called a level)



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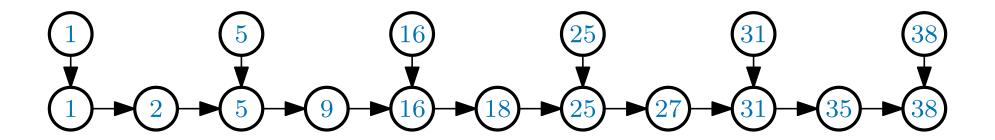


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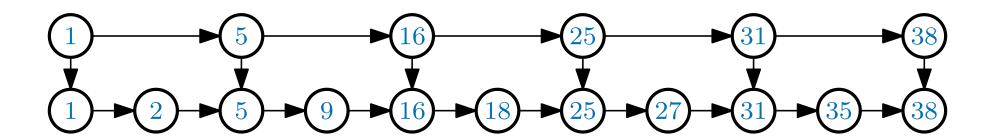


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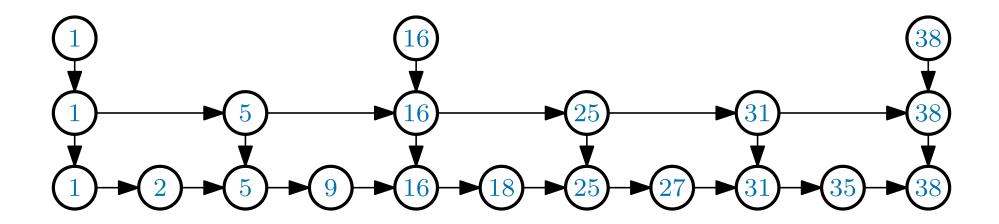


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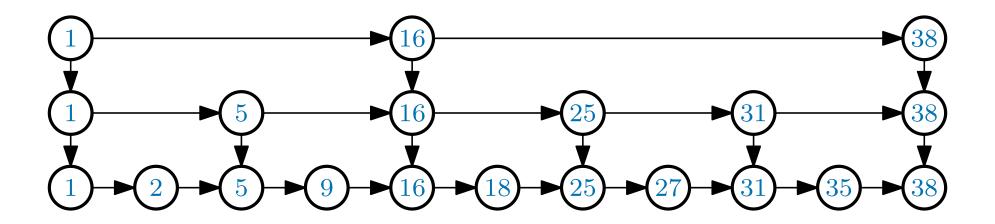


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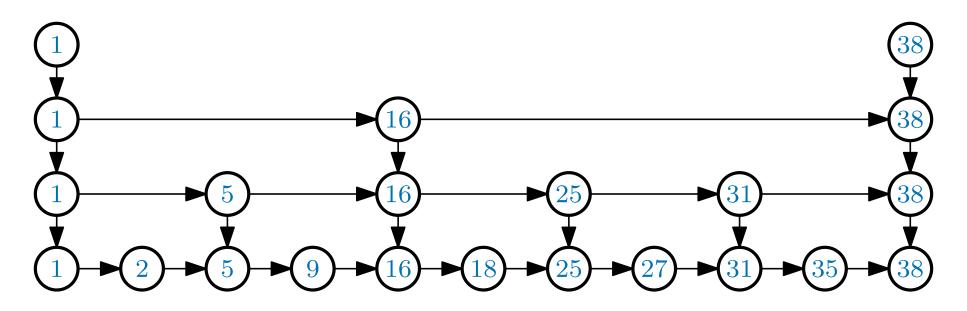


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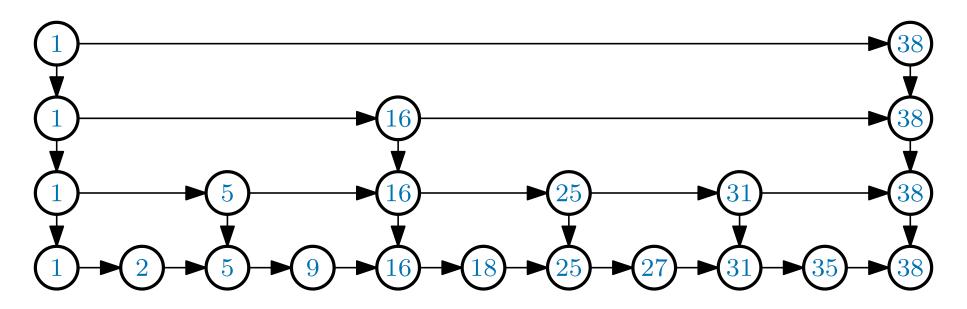


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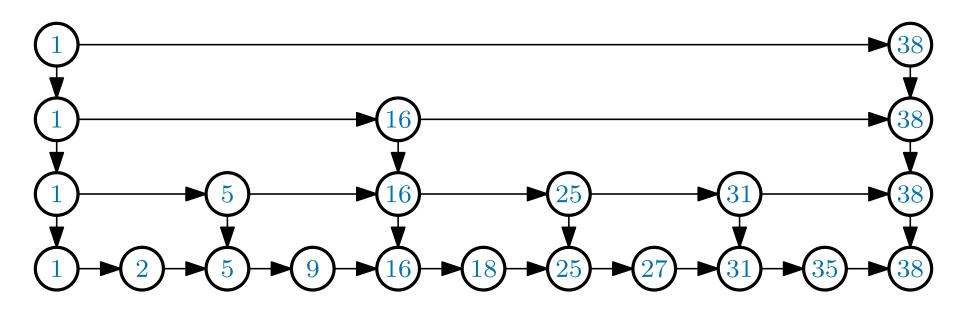




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Each level will now contain **half** of the keys *(rounding up)* from the level below

They are chosen to be as evenly spread as possible



The bottom level contains every key

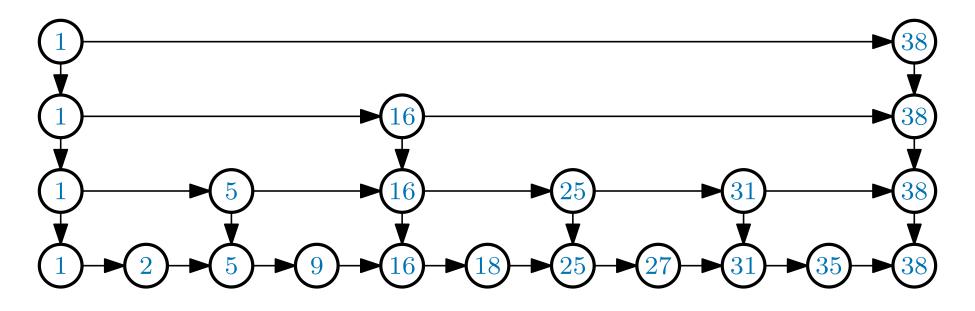
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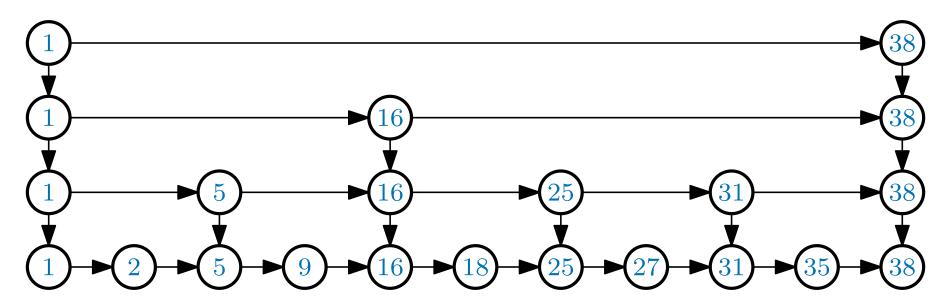
As each level contains half of the keys from the level below,

there are $O(\log n)$ levels



How do we perform FIND(k) in multi-level linked list?

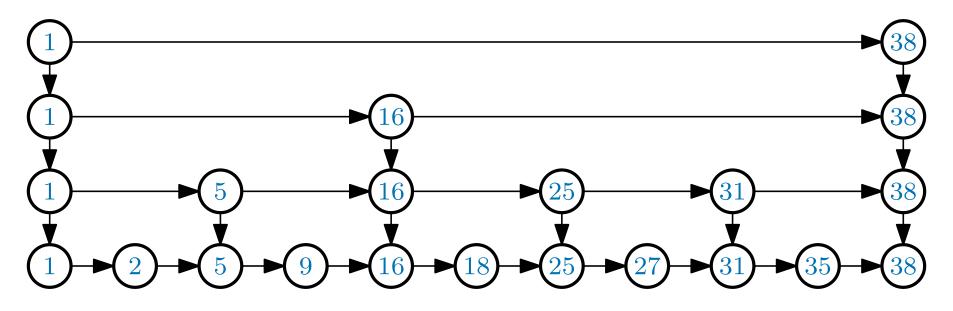
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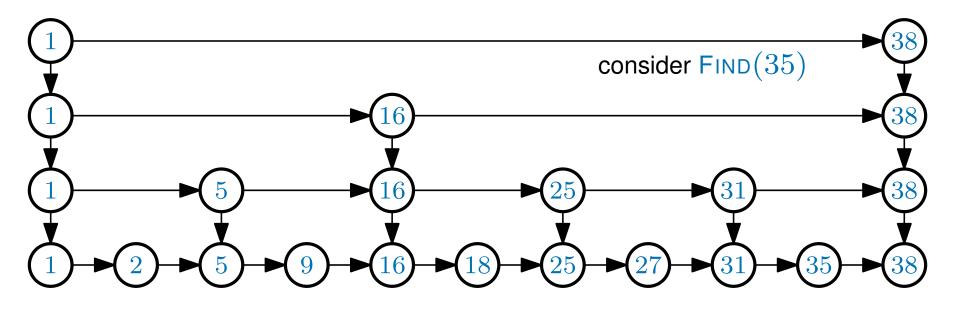


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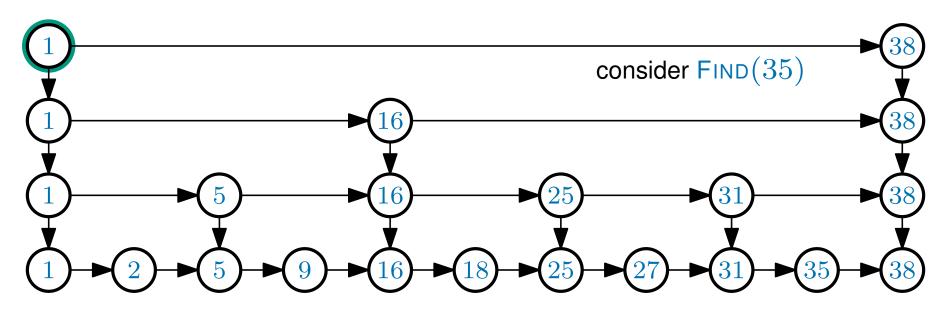


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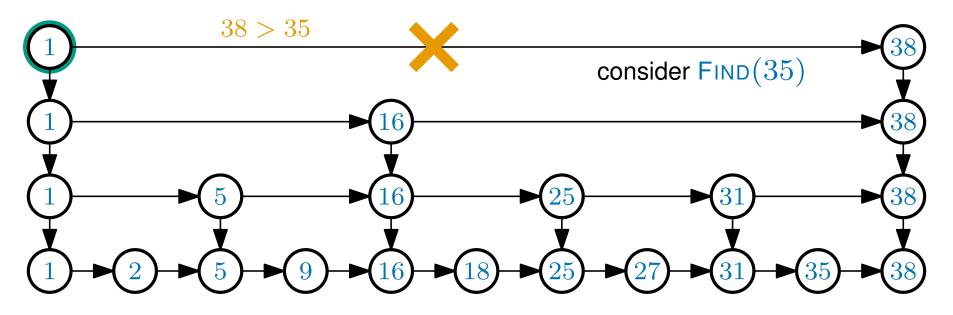


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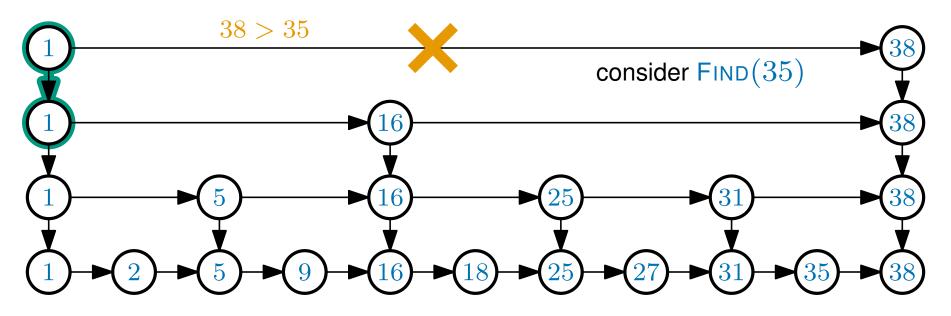


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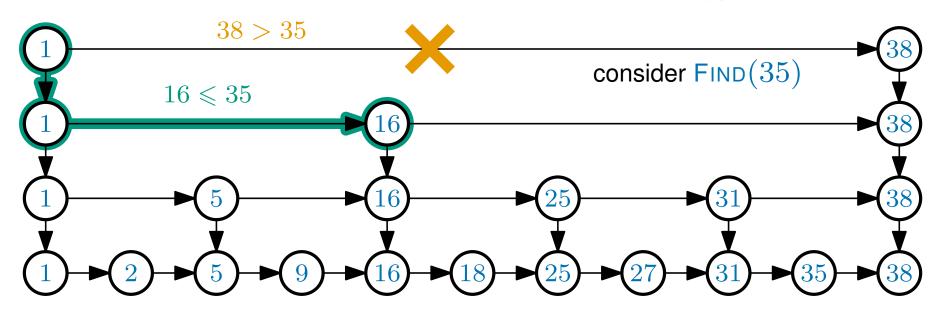


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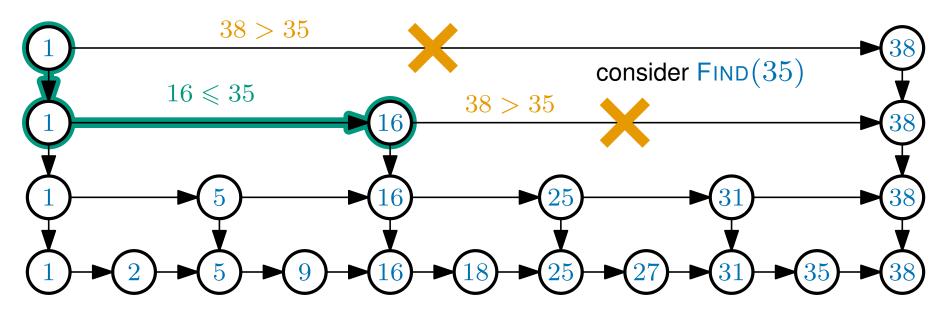


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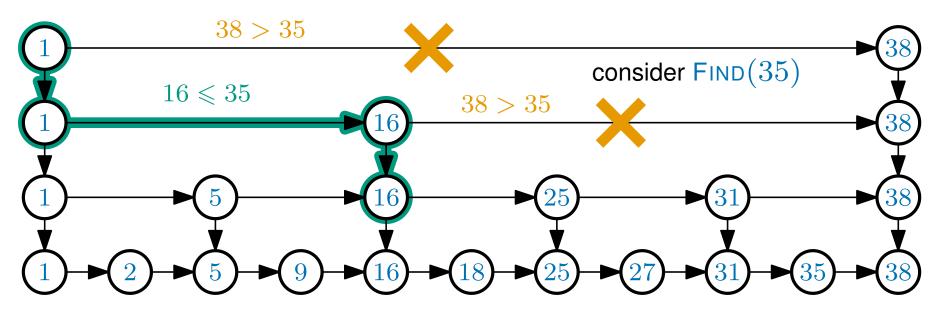


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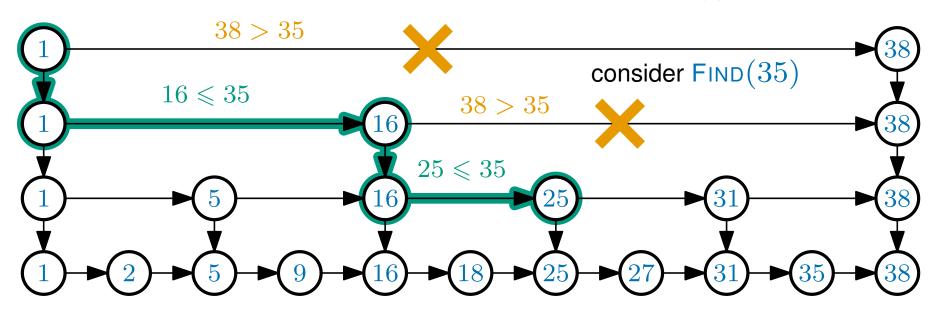


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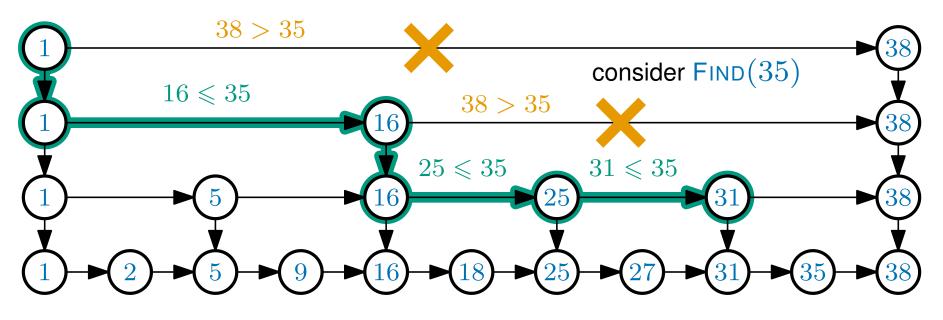
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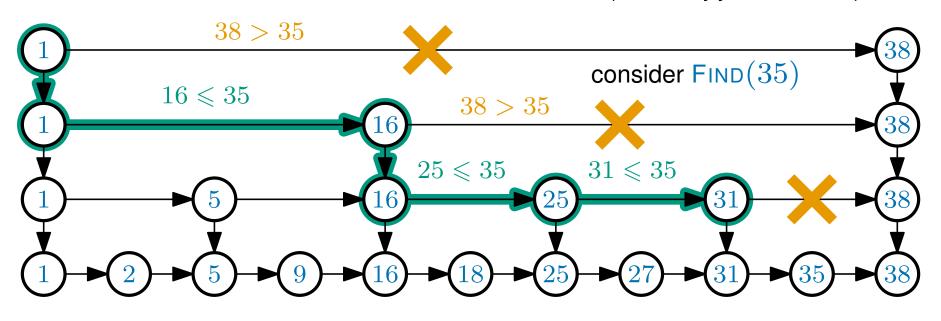




FIND in multi-level linked lists

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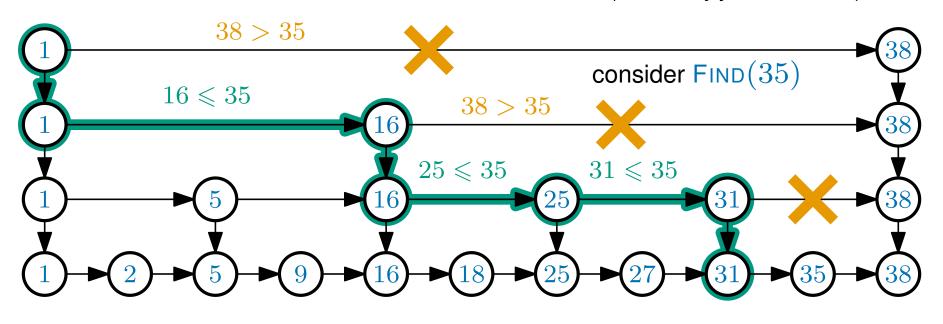
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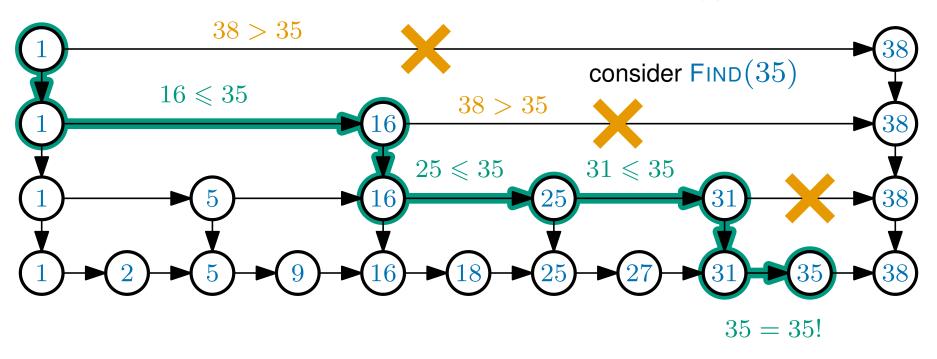
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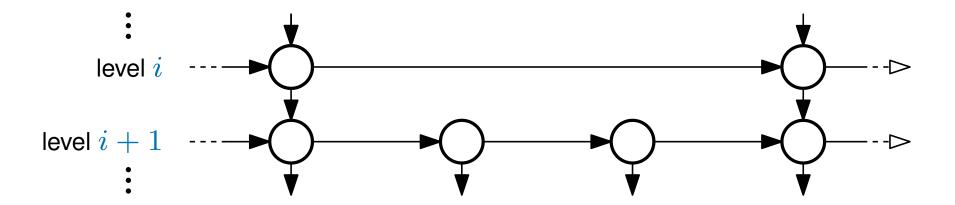


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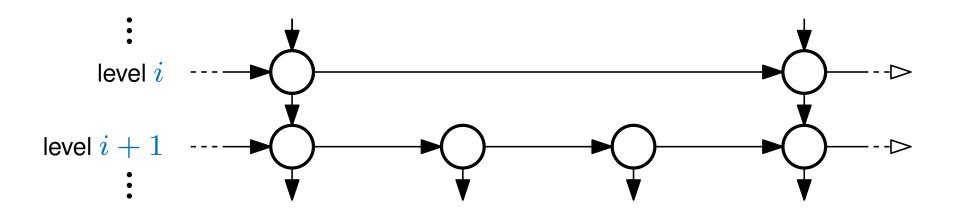




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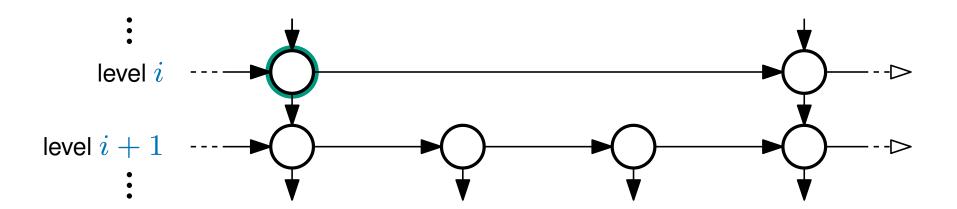




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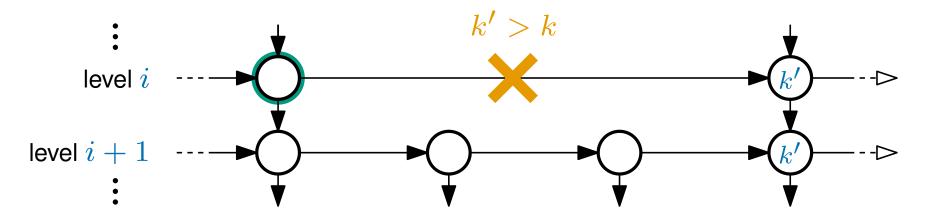


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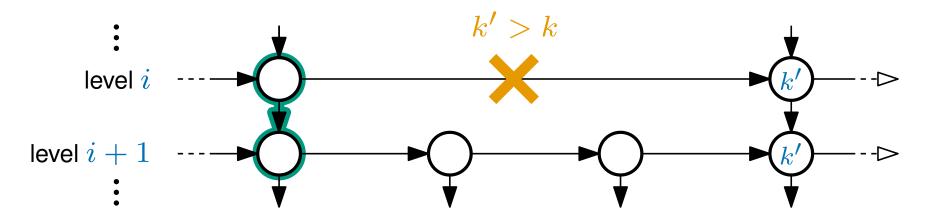


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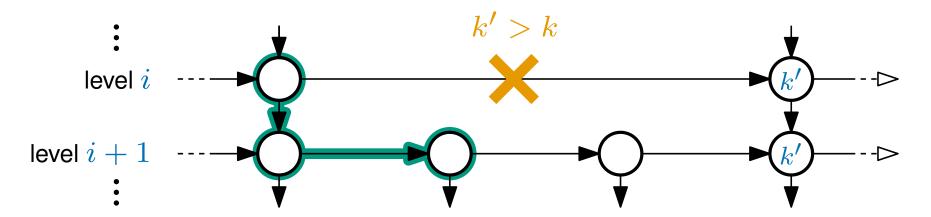


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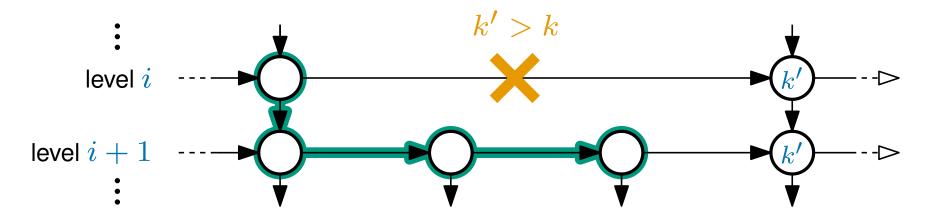


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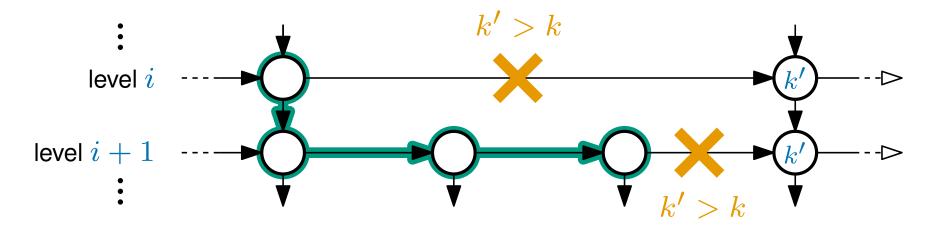


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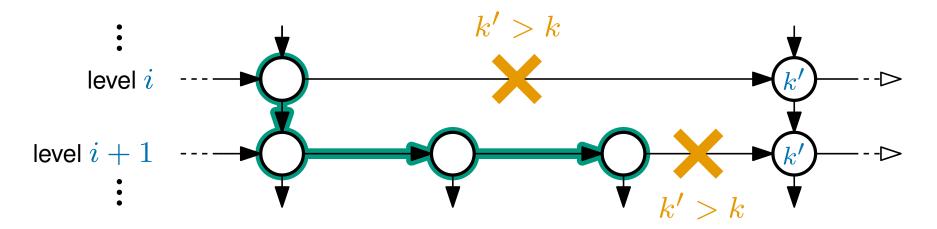




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Observation 3 We only move right at most 2 times on any level i+1 because we stopped moving right on level i

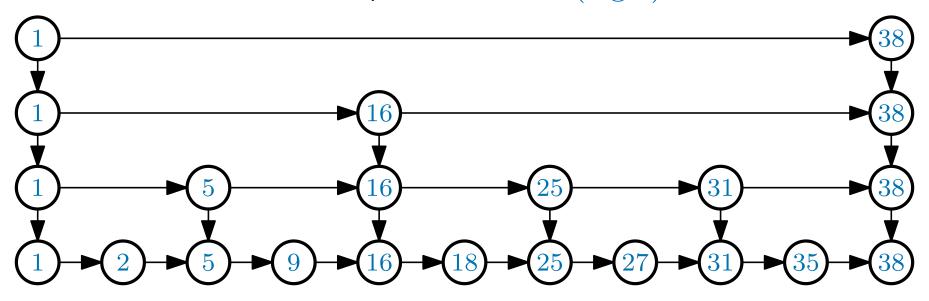
Fact We only move at most $O(\log n)$ times while performing a FIND



If we had a multi-level linked list with $O(\log n)$ levels

where each level contained half of the keys from the level below and the keys were evenly spread as possible

then we could perform FIND in $O(\log n)$ time

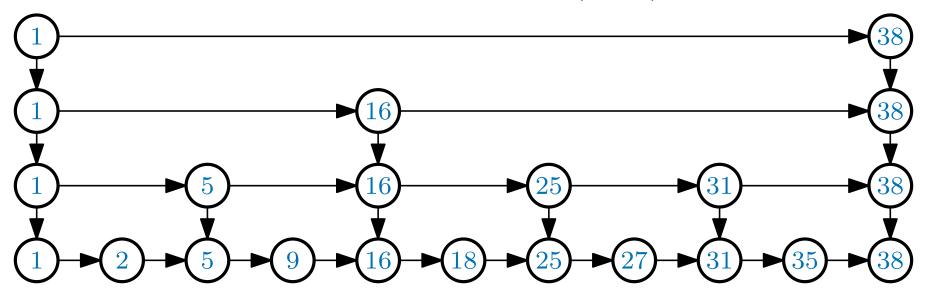




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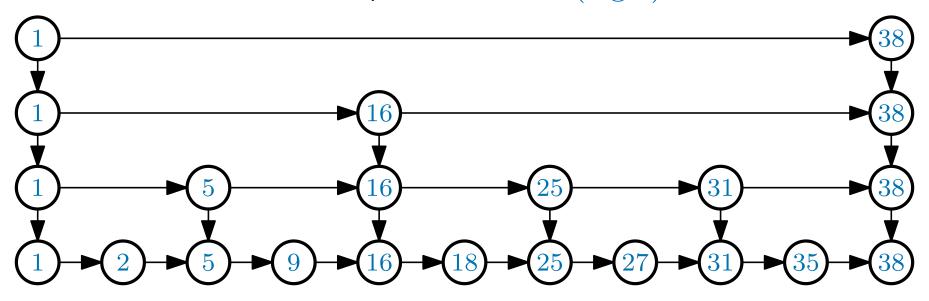
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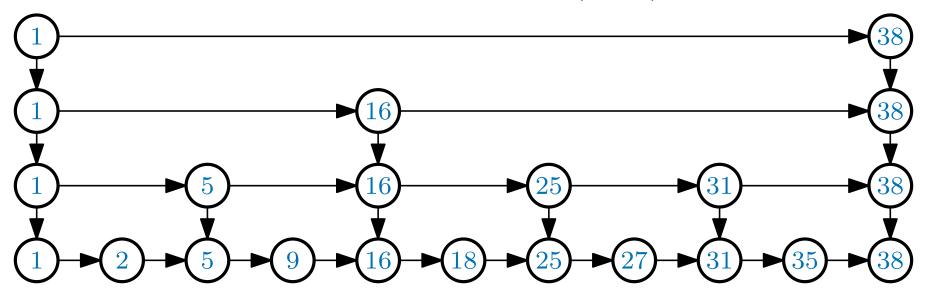
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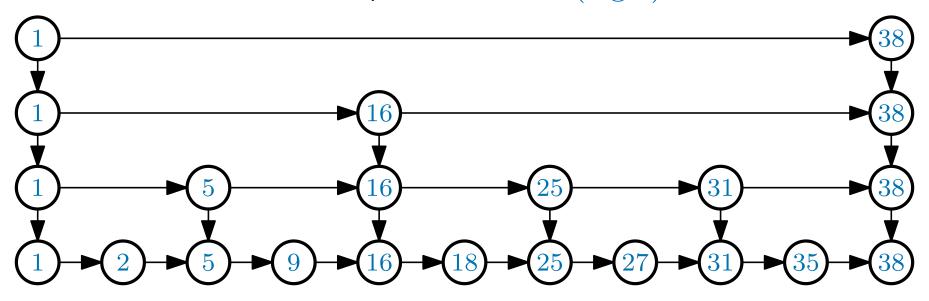
How can we keep a good spread of keys at each levels?



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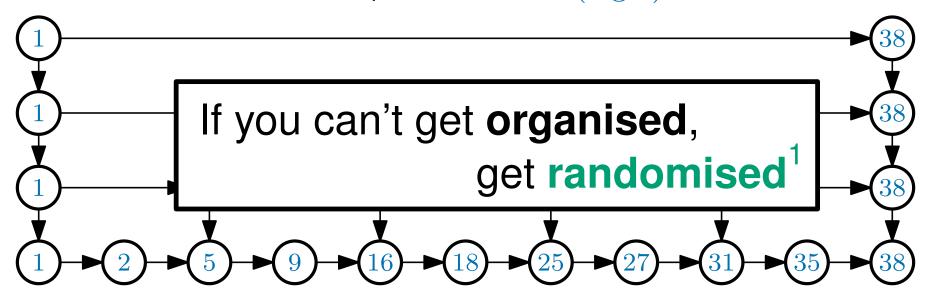
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Before we formally introduce Skip Lists, we let's rewind and try building another Multi-level Linked List... by flipping coins



(we still always include the smallest and largest keys in every level)



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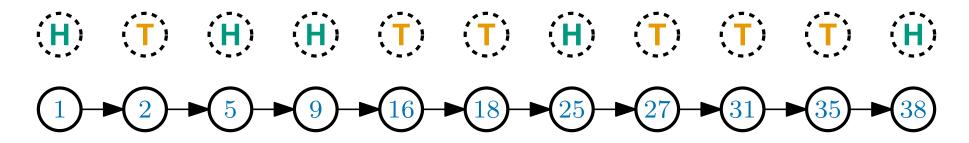
Flip one coin for each key...

For each key that got a head, put it in the new top level

Repeat with the keys from the new top level



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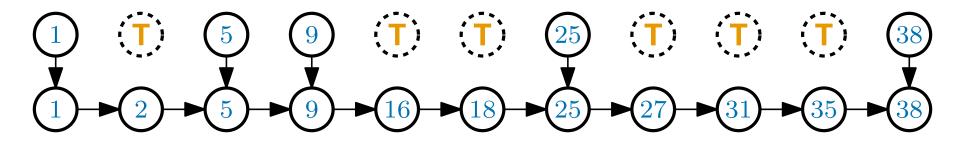
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Repeat with the keys from the new top level



Before we formally introduce Skip Lists, we let's rewind and try building another Multi-level Linked List... by flipping coins



(we still always include the smallest and largest keys in every level)

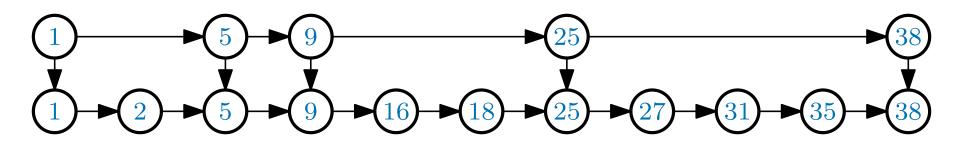
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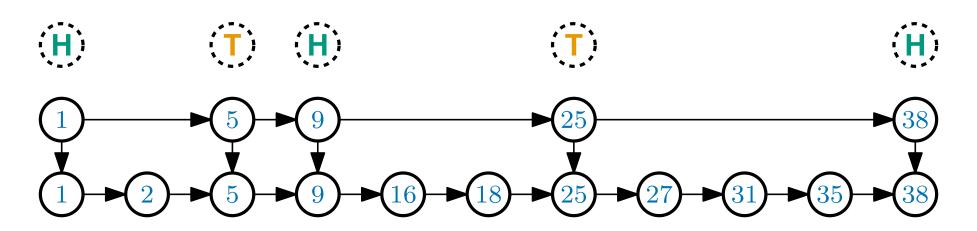
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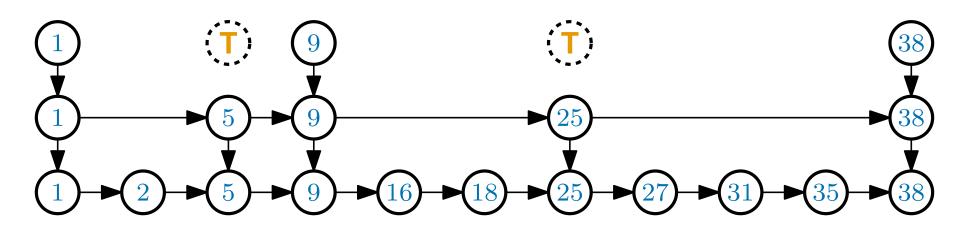
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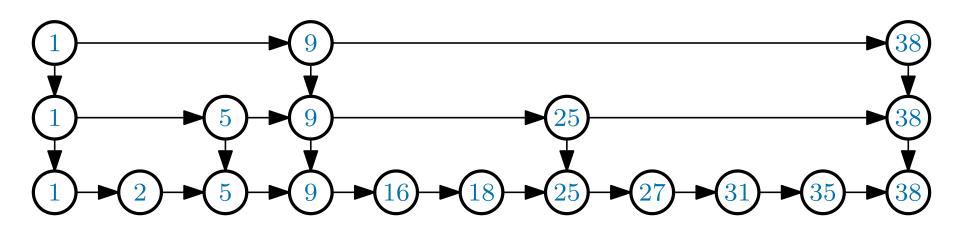
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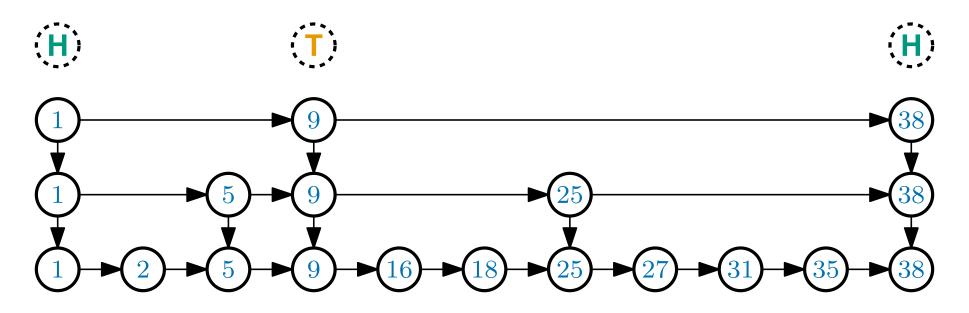
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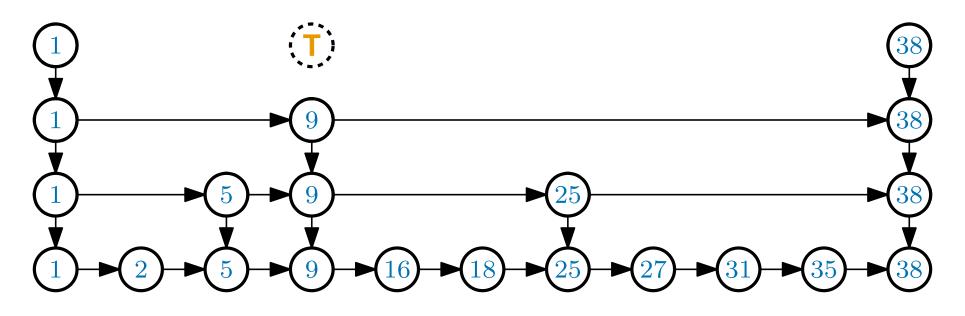
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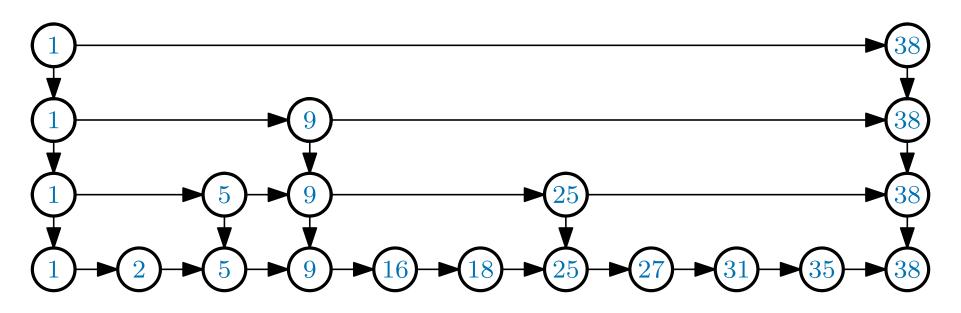
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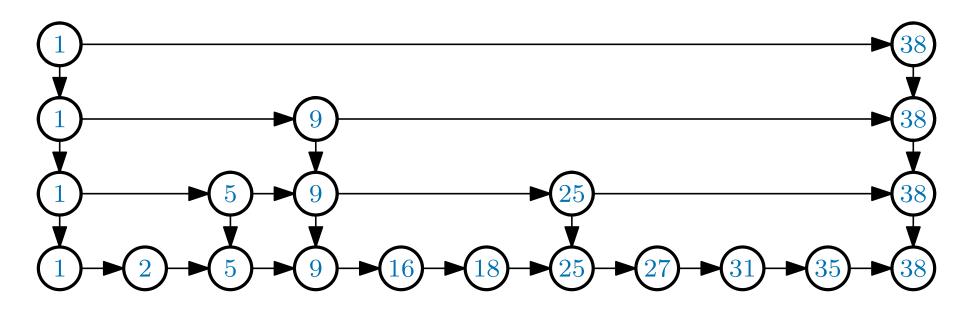
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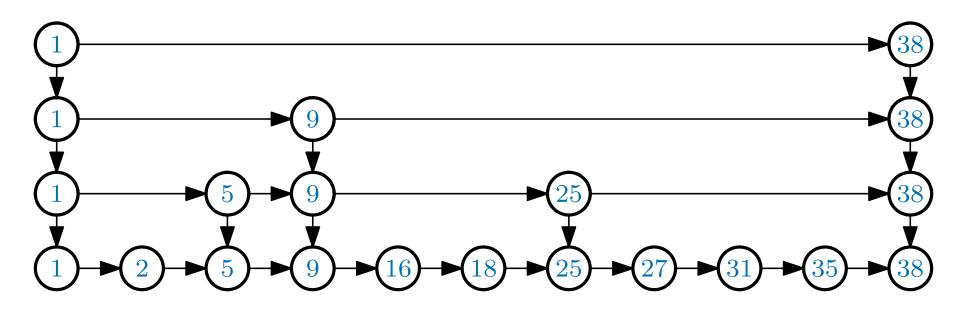
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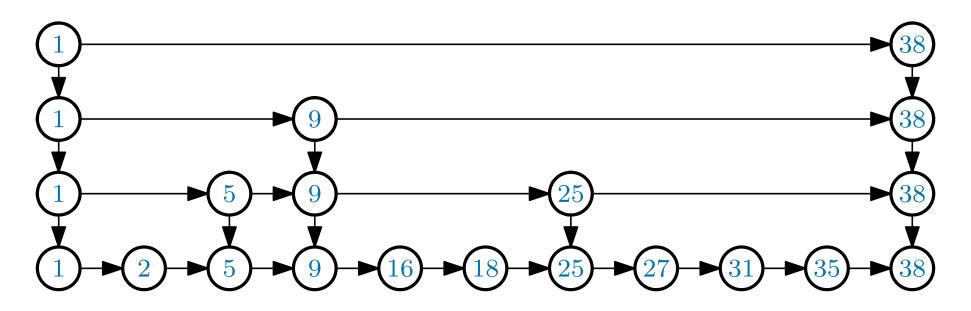


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This doesn't look quite perfect but actually, it's very good with high probability (more on this later)



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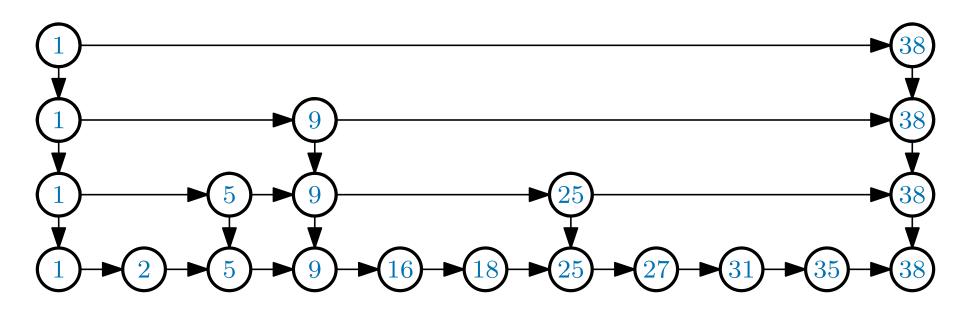
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The intuition is that n coin flips contain about $\frac{n}{2}$ heads and about $\frac{n}{2}$ tails



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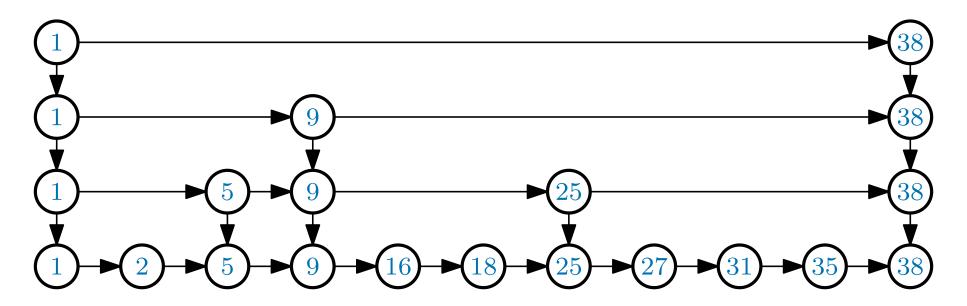


Skip Lists

A skip list is a multi-level linked list where

the INSERTS are done by flipping coins

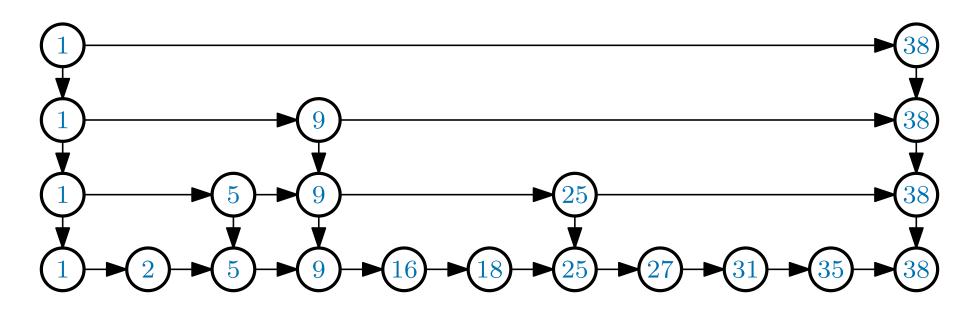
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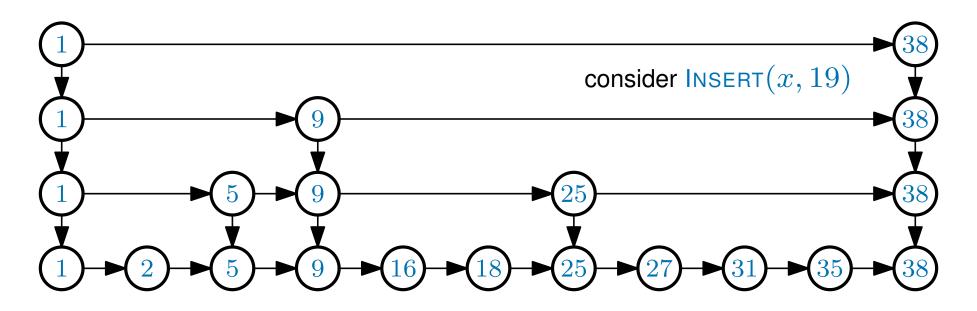
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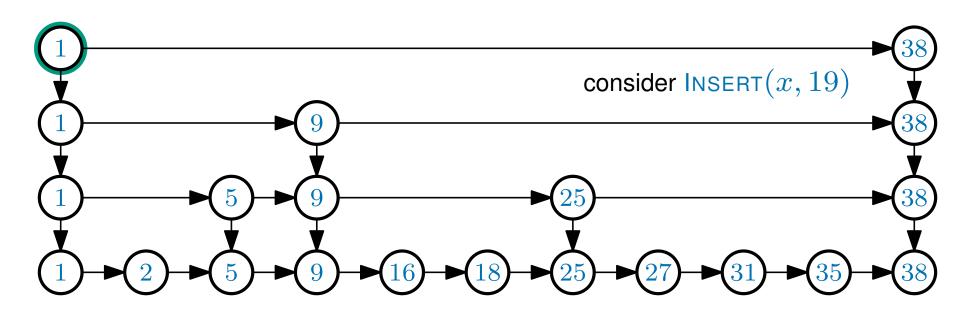
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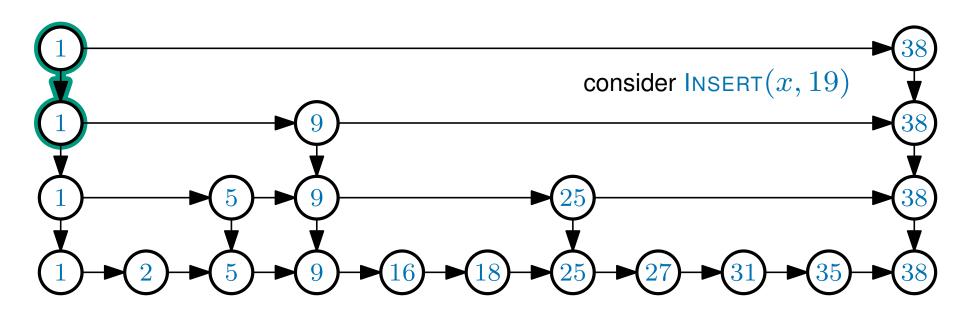
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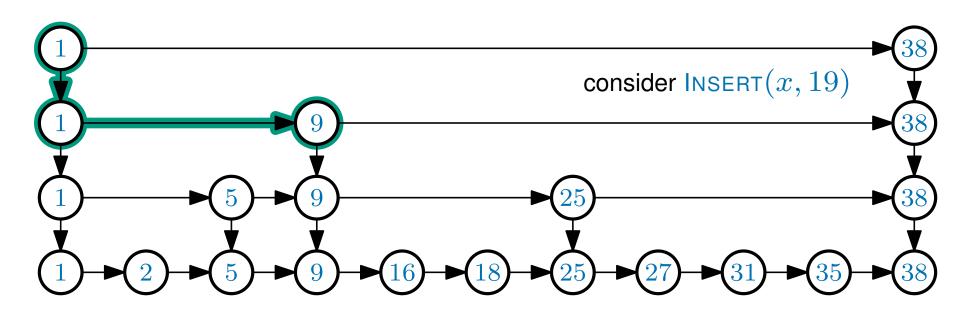
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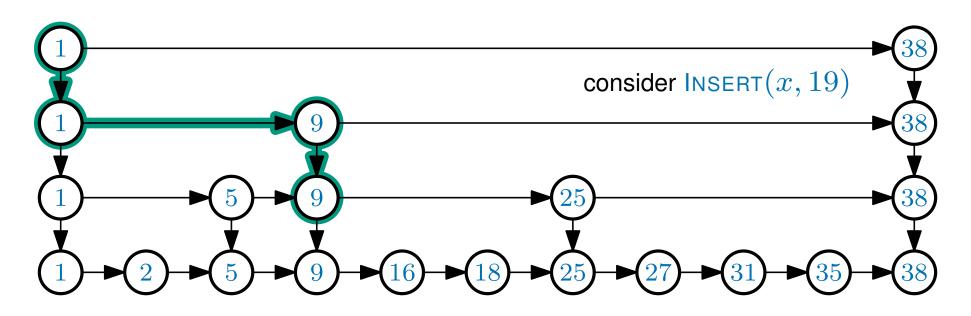
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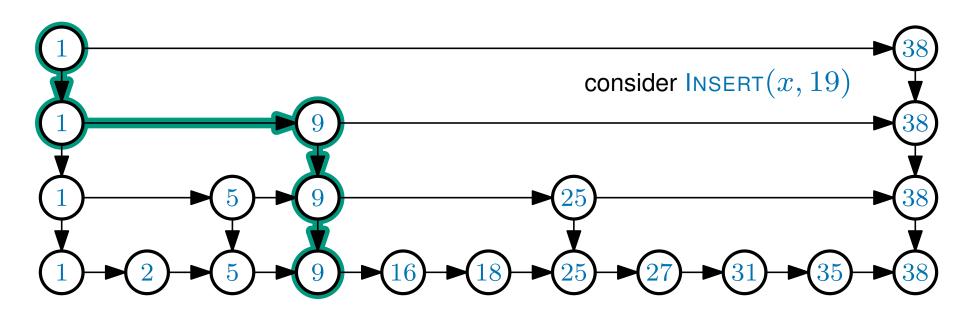
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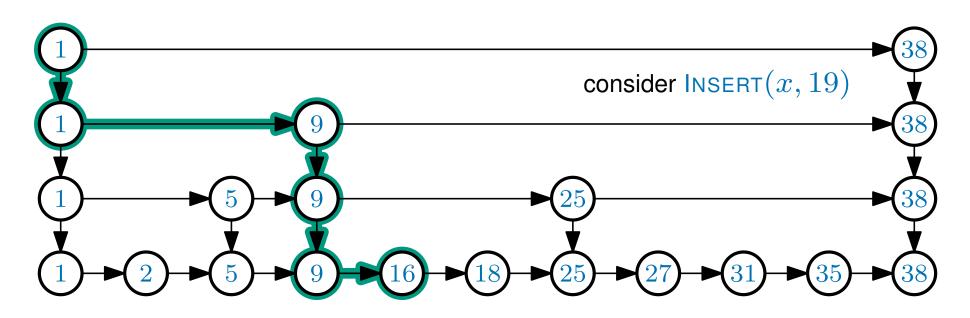
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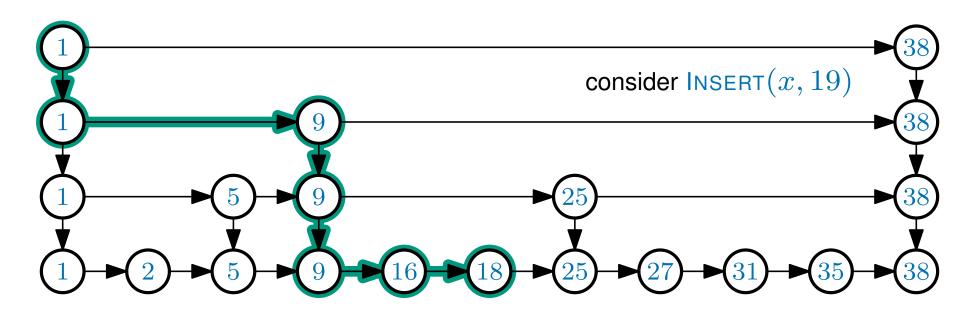
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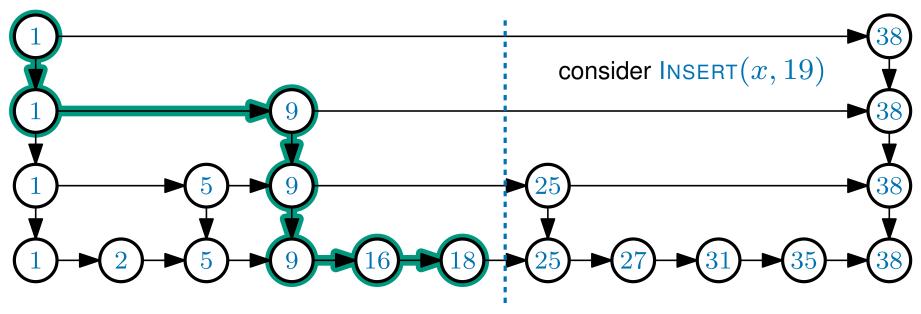
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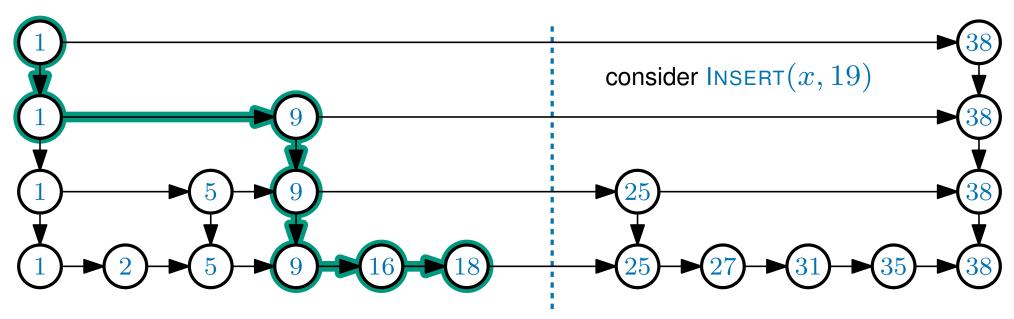
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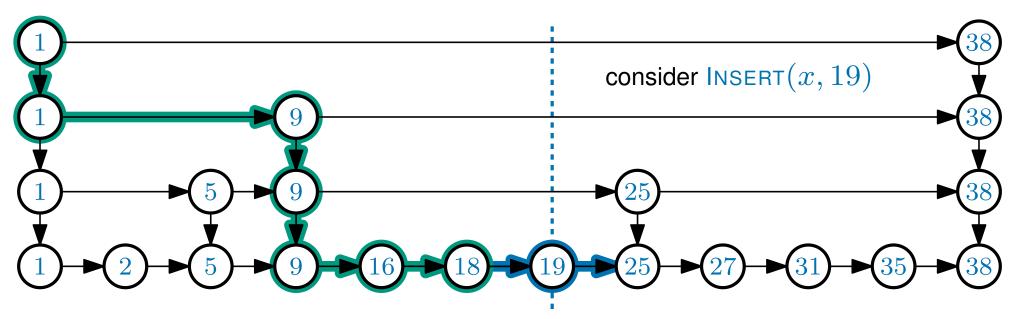
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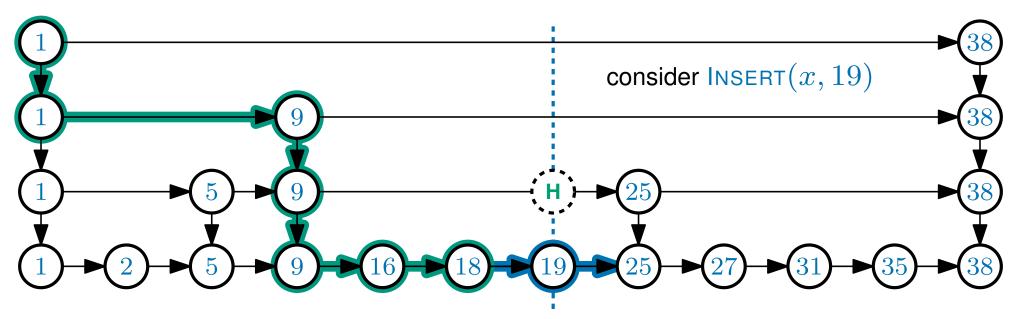
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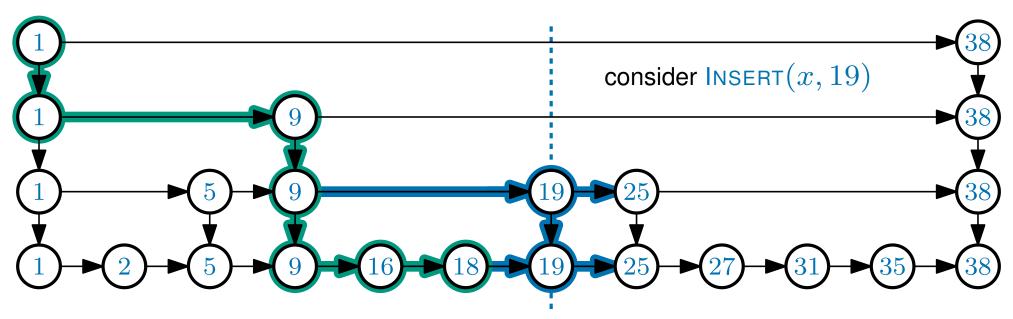
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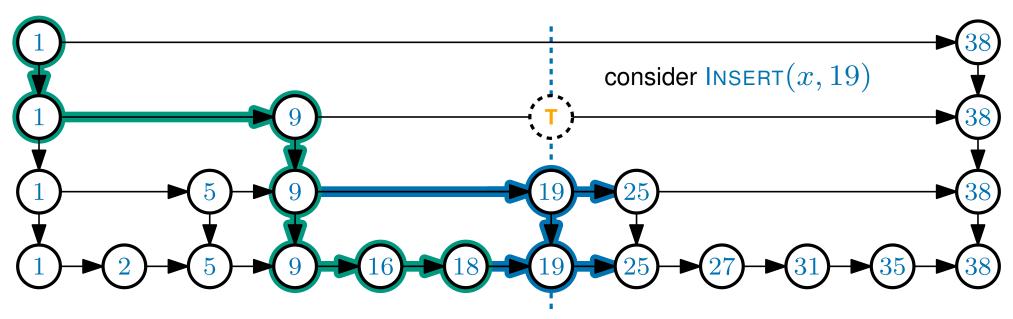
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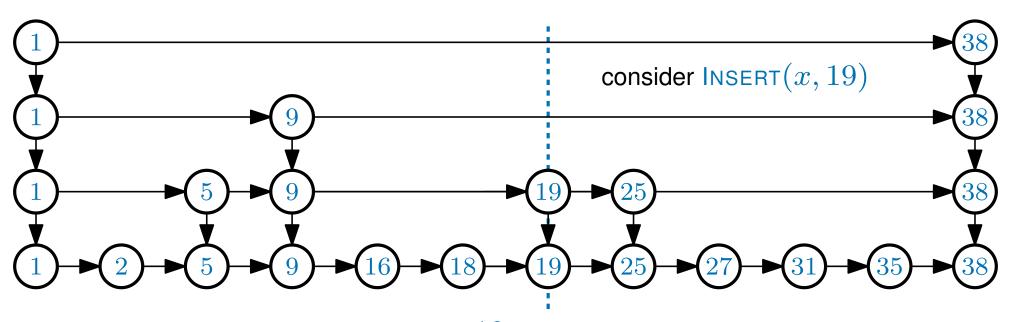
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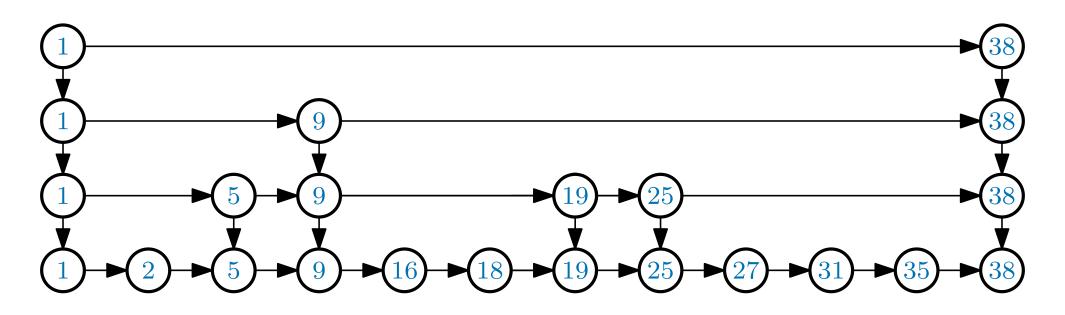
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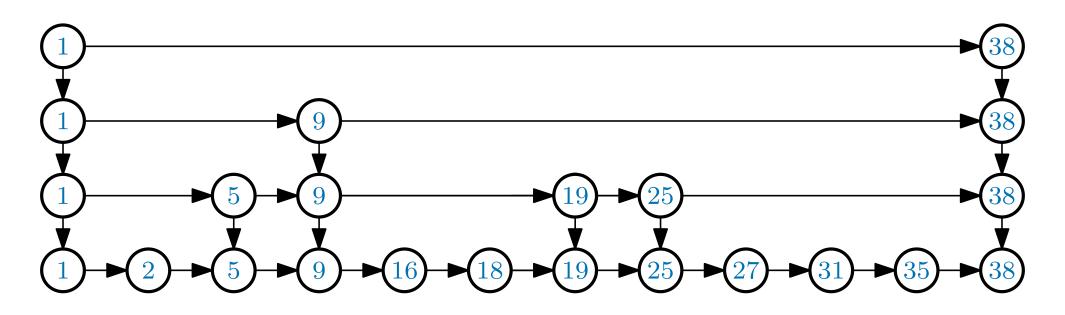
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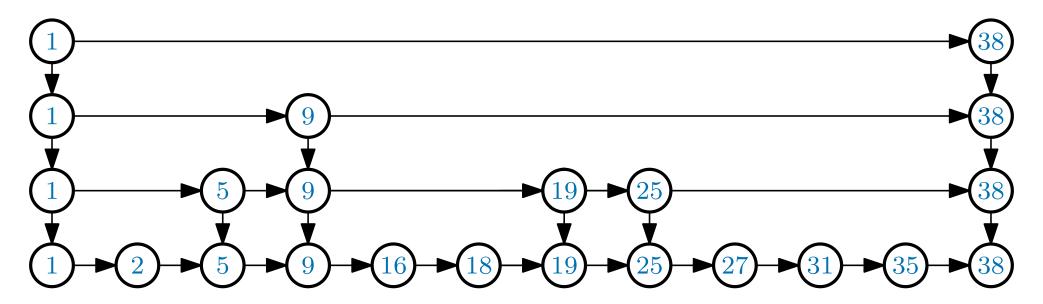
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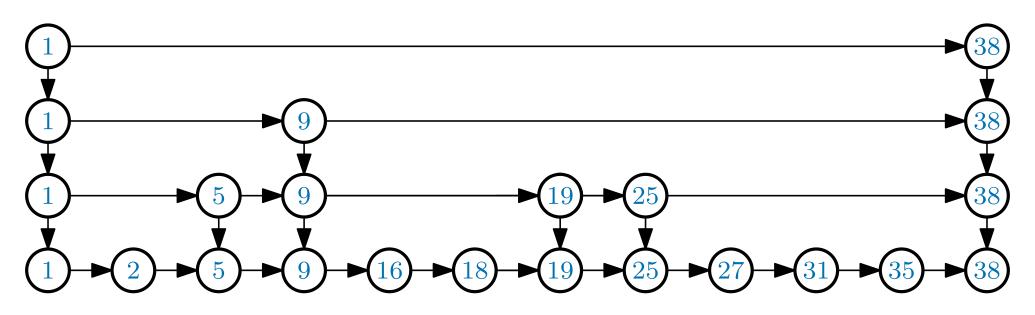
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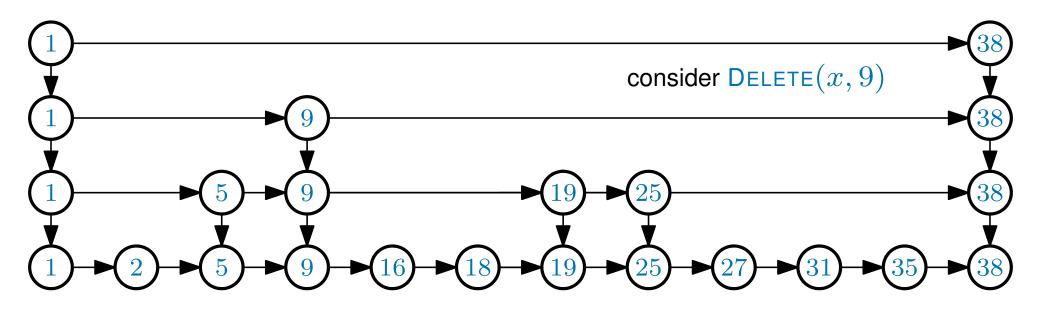
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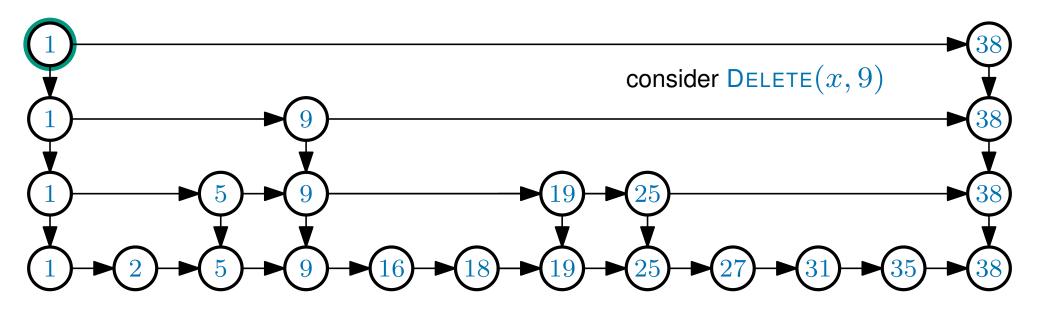
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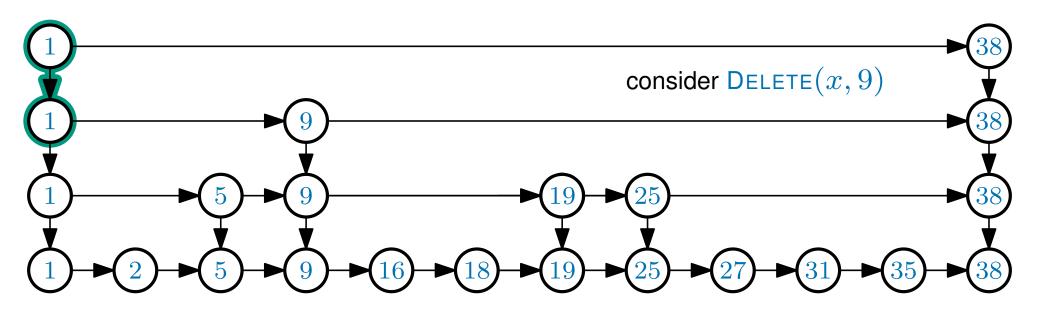
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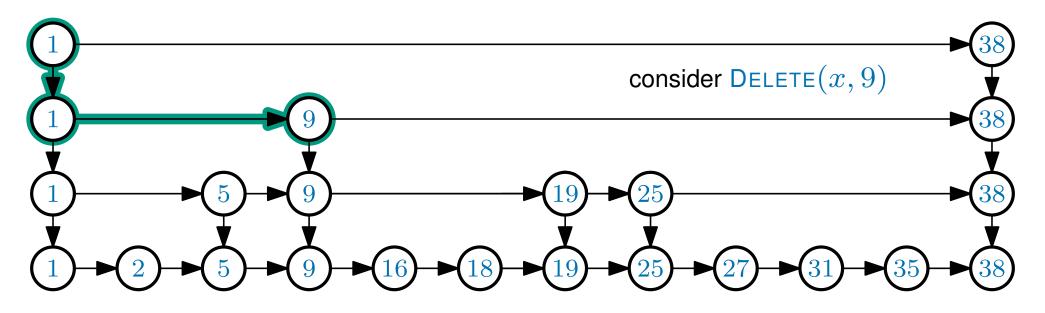
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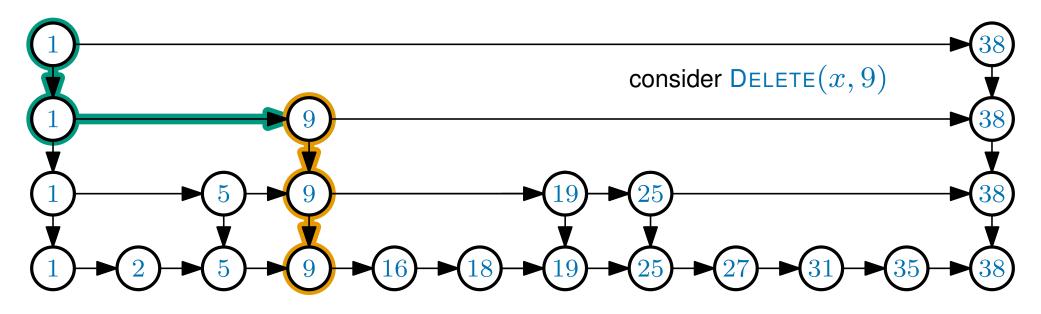
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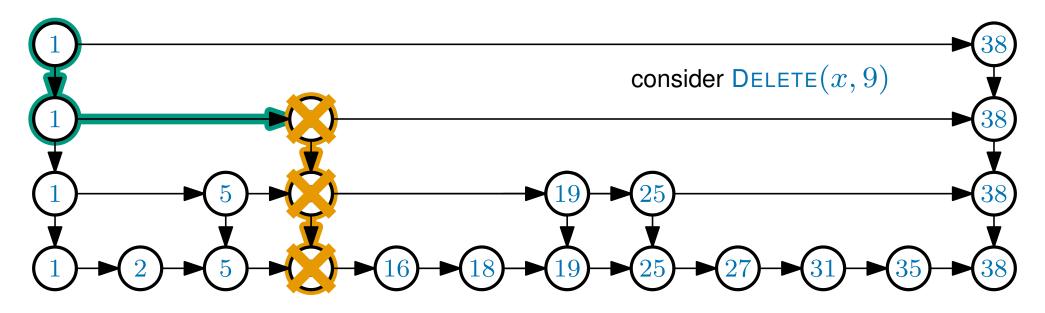
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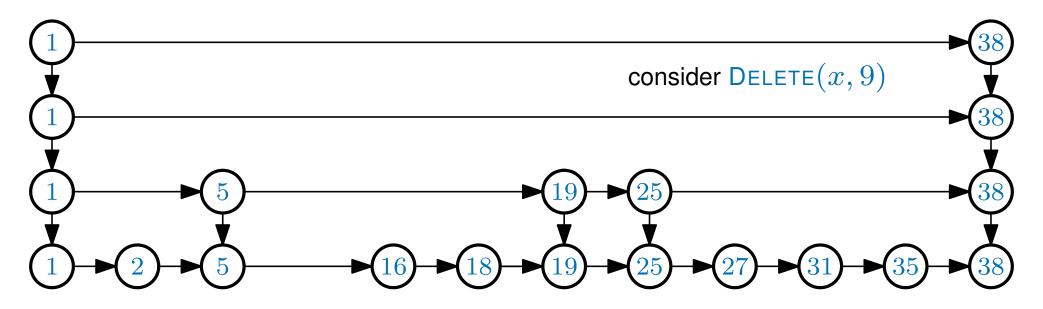
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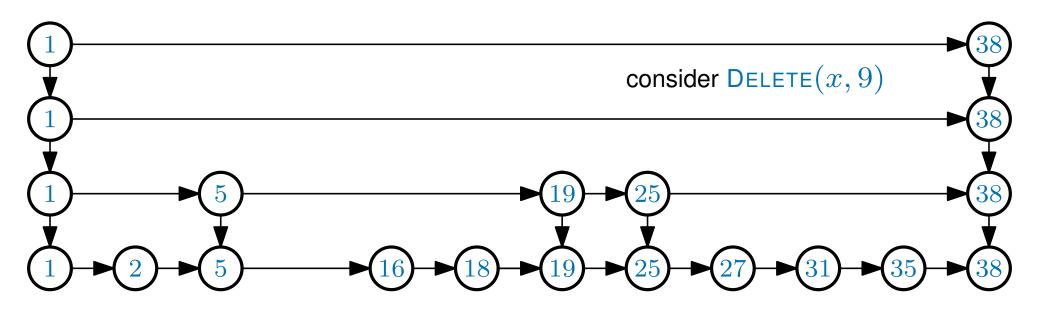
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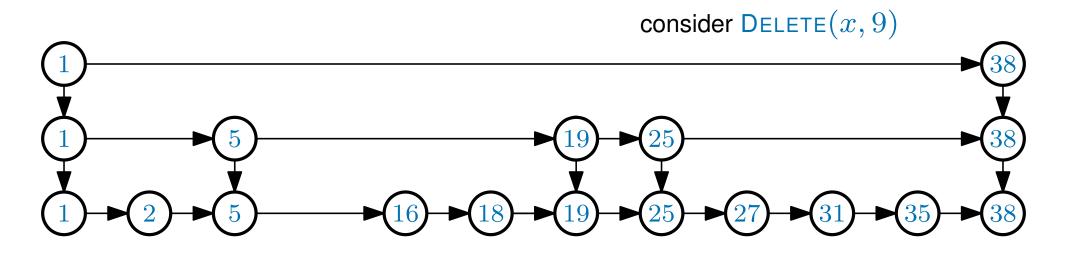
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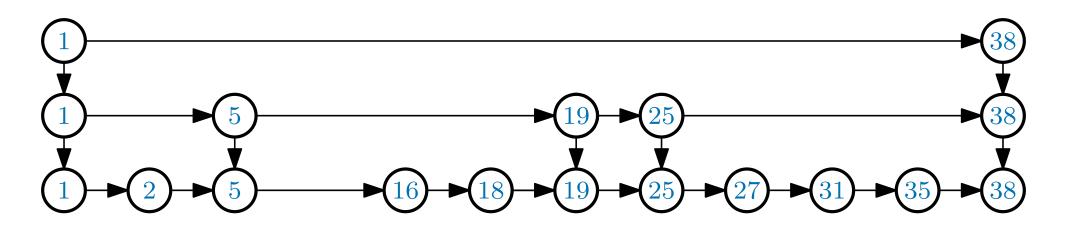
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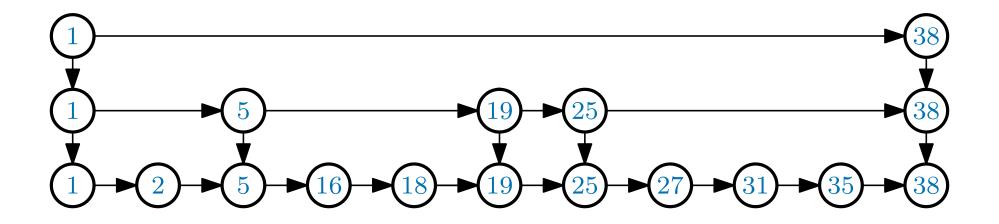
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Skip Lists (pre-proof) summary

A skip list is a randomised data structure, based on link lists with shortcuts which supports ${\tt INSERT}(x,k)$, ${\tt FIND}(k)$ and ${\tt DELETE}(k)$



We will show that each of these operations takes *expected* $O(\log n)$ time That is, they take $O(\log n)$ time 'on average'

Important There is *no randomness in the data*, the only randomness is in the coin flips

On the worst case input sequence, the expected time is $O(\log n)$



We begin by proving that after n insert operations, a skip list is very unlikely to have more than $2\log n$ levels...



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The probability (x,k) is inserted into more than 3 levels is $\frac{1}{8}$ (we throw HHH...)



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The probability of at least one E_j occurring is at most $\sum_j \frac{1}{n^2} = \frac{1}{n}$



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is at most
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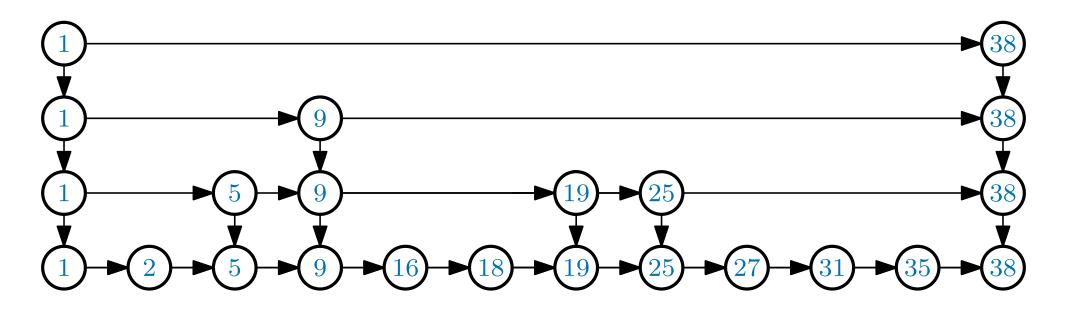
is at most
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It gets better as n increases!



As the number of levels is $O(\log n)$ (with high probability),

we can conclude that the number of times we **move down** is very likely to be $O(\log n)$



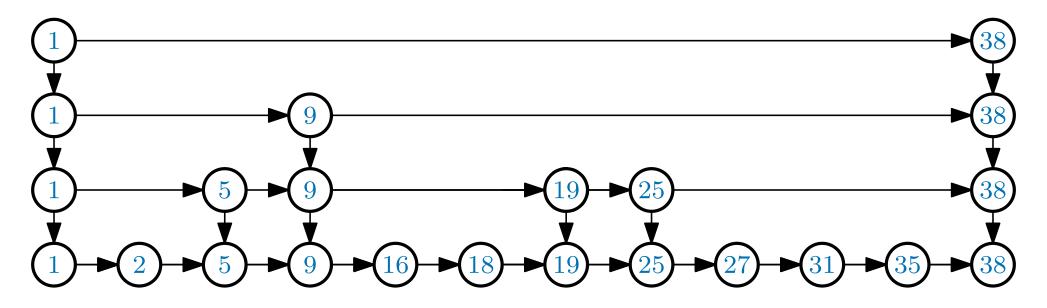
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Start at the top-left (the head of the top level)  
While you haven't found k:
    If the node to the right's key, k' \leq k
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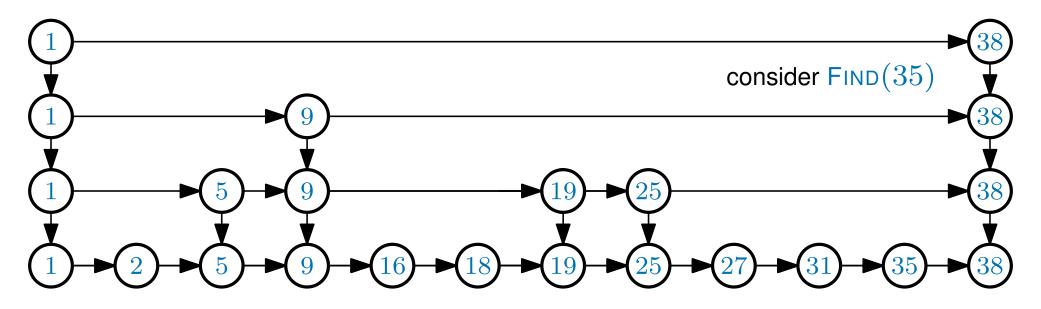
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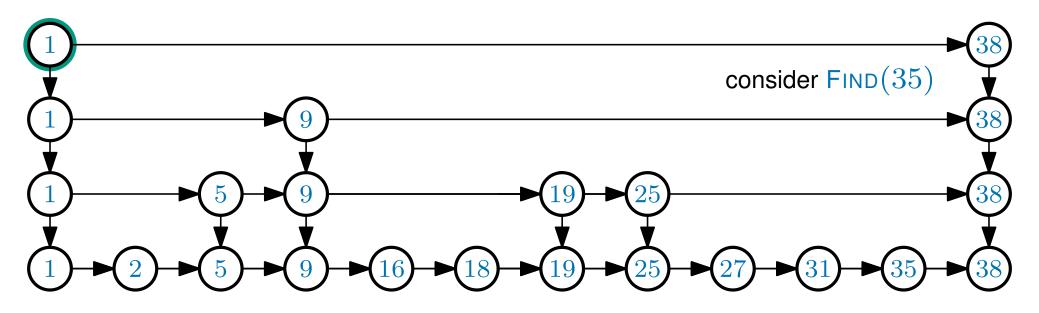
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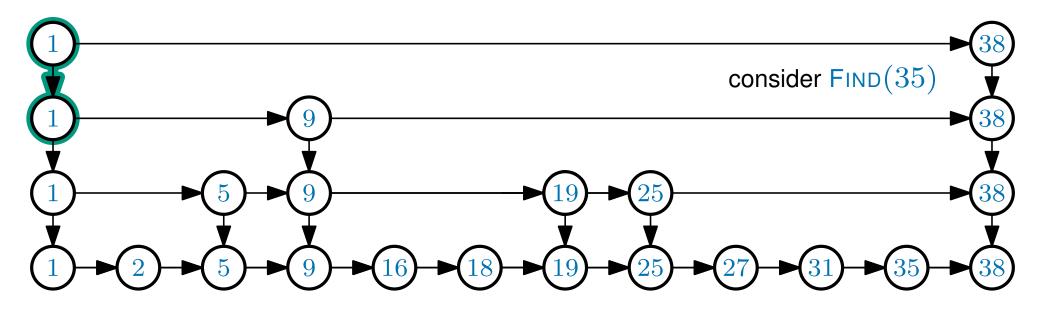
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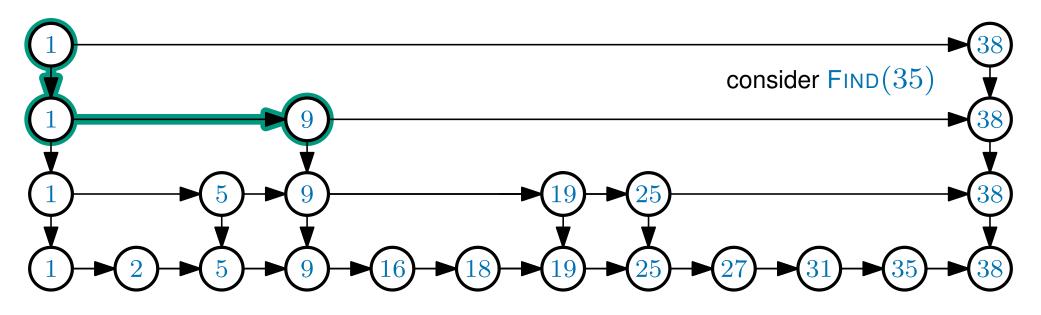
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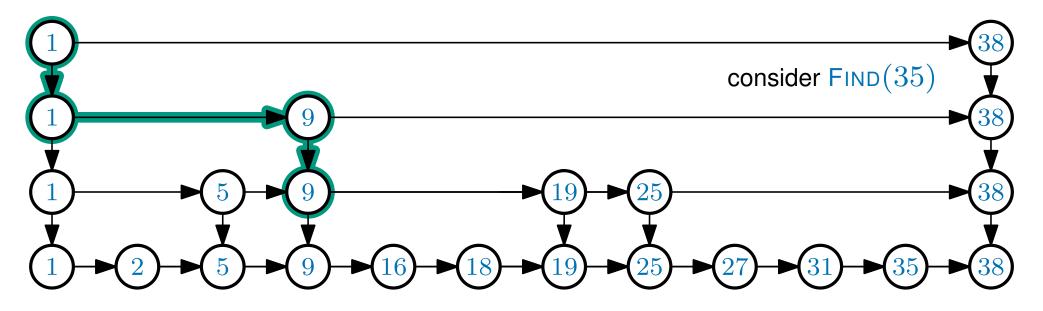
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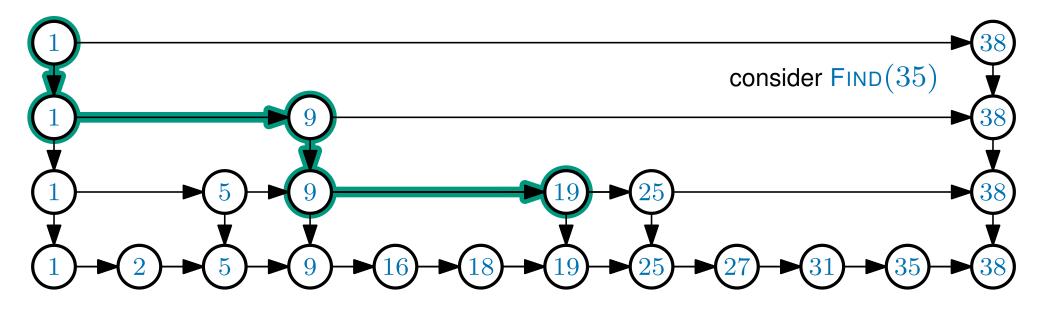




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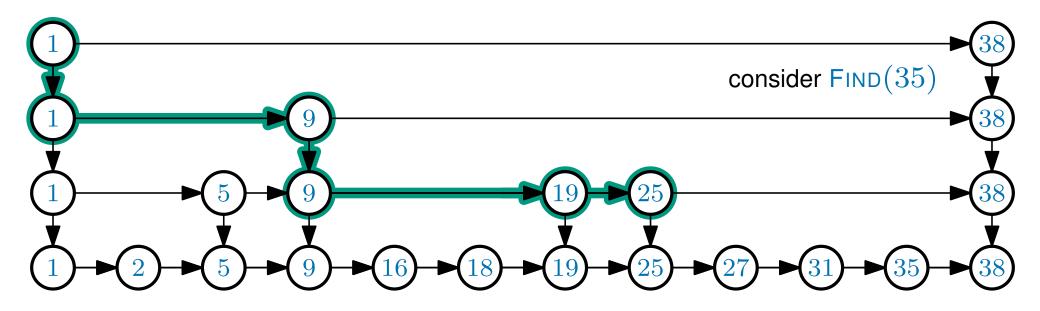
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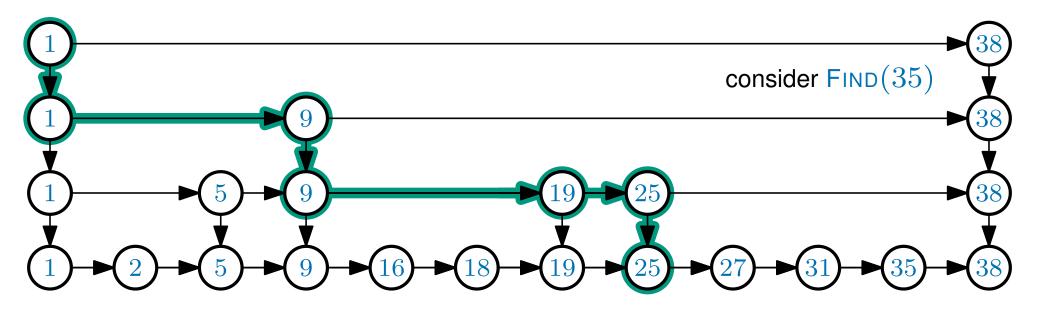




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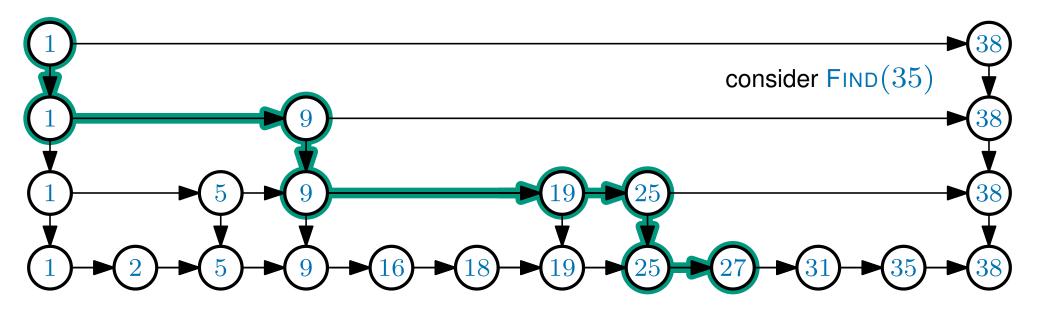
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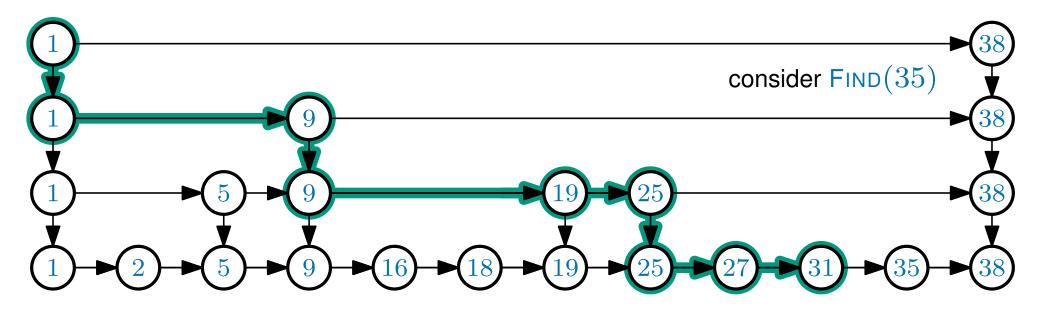
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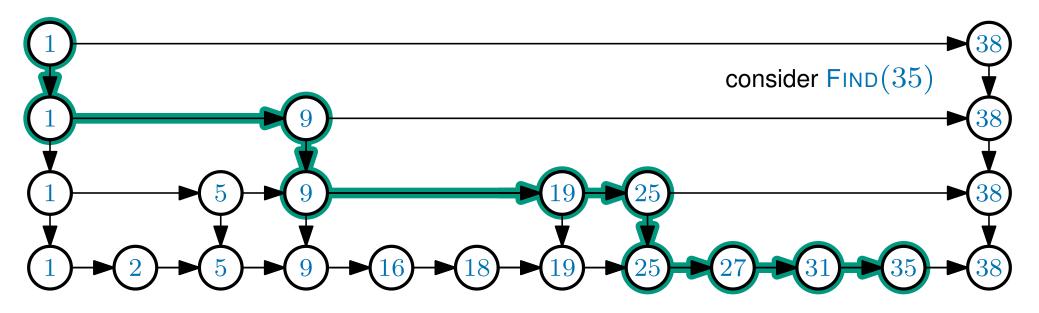
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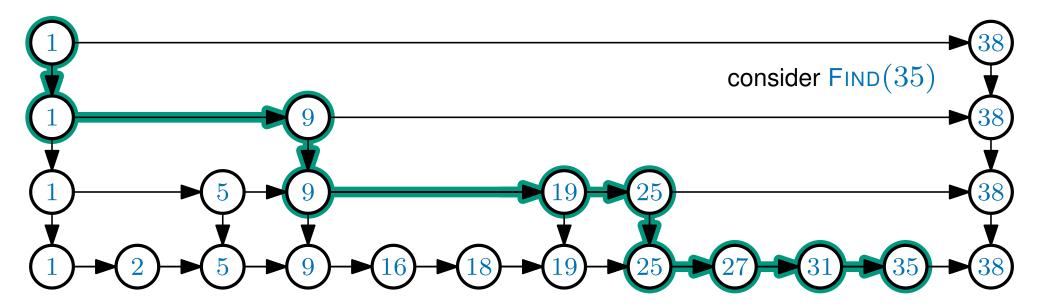
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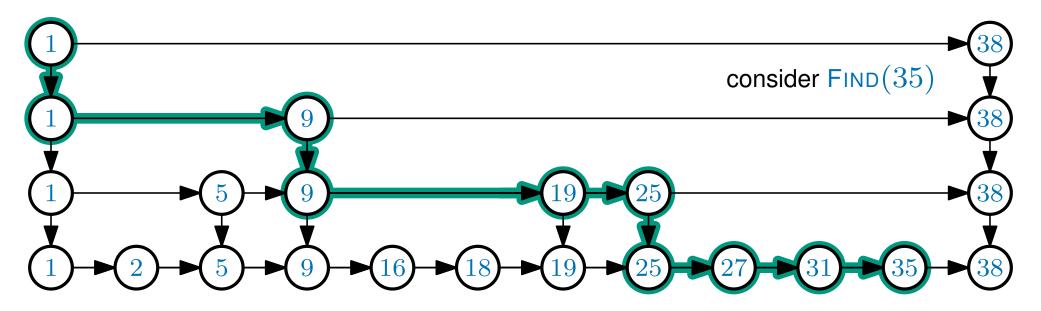




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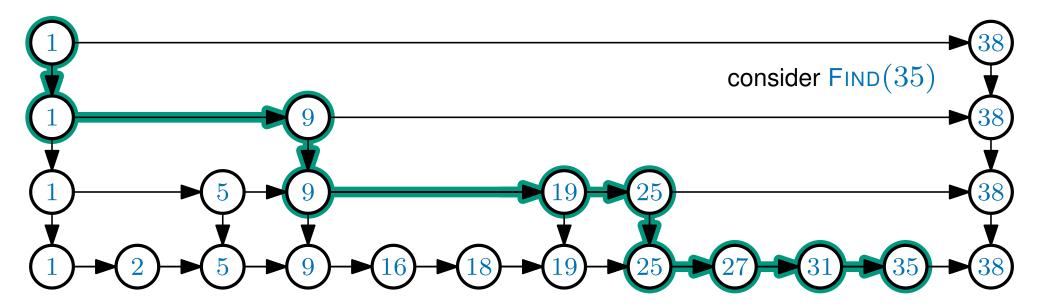




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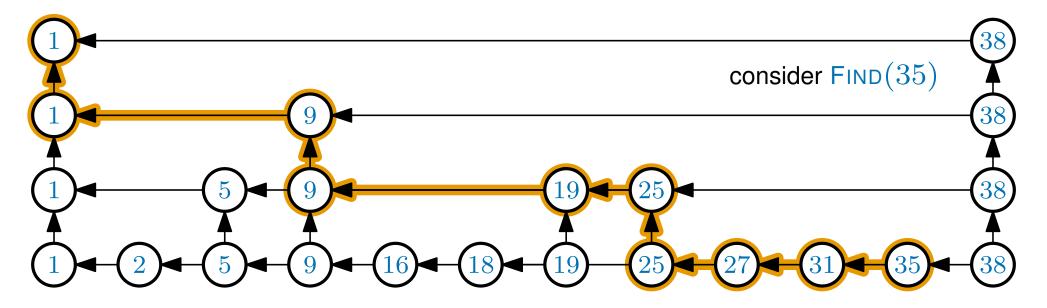
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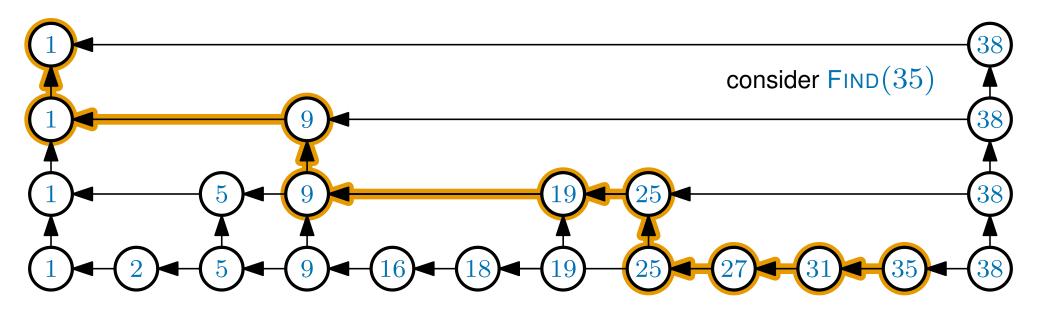
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- 1. Reverse it
- 2. Convince yourself this is the same path:

```
Start at k
While not at the top-left:

If you can,

Move up

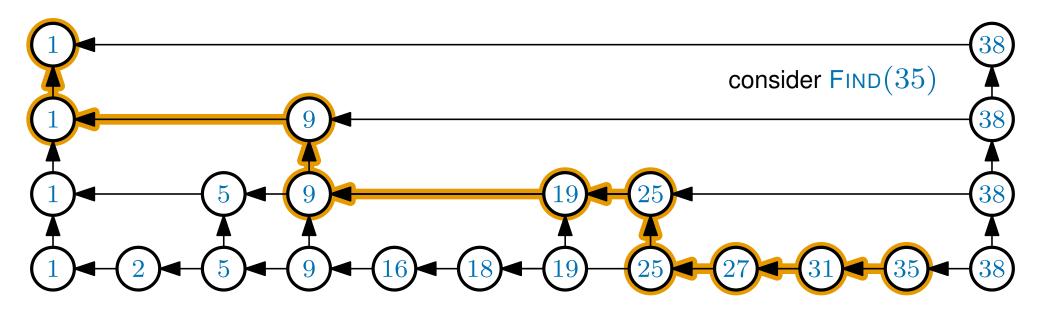
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- 3. Now convince yourself
 it takes the same time as this:

 (in expectation)

```
Start at k
While not at the top-left:

If (flip a coin)

Move up

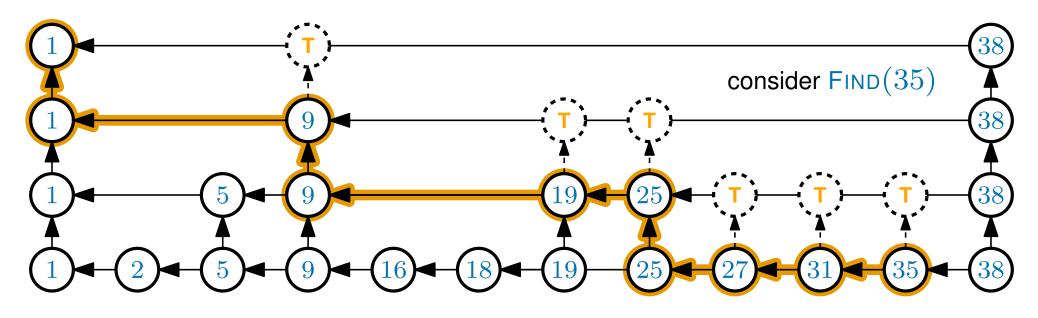
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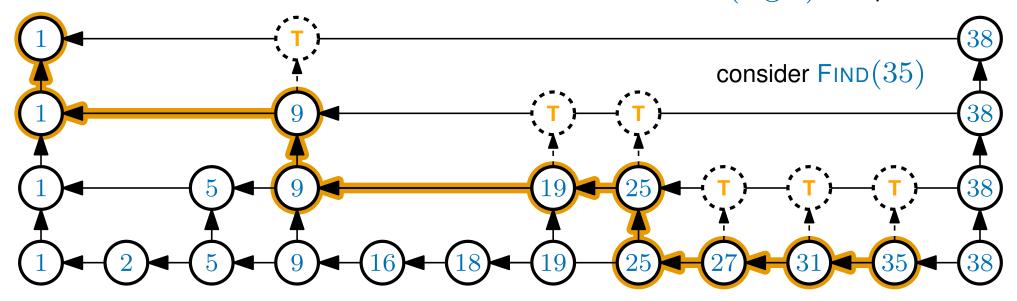
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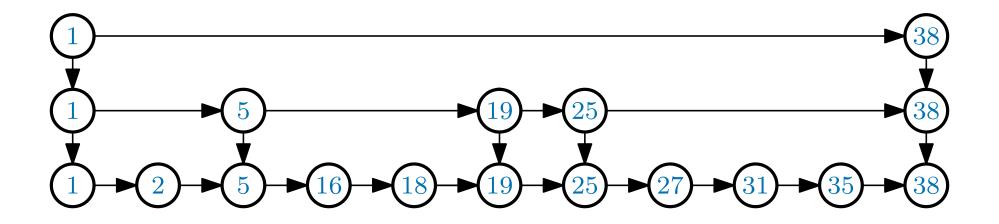
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(this is a stronger claim but proving it is harder)



Skip Lists (post-proof) summary

A skip list is a randomised data structure, based on link lists with shortcuts which supports ${\tt INSERT}(x,k)$, ${\tt FIND}(k)$ and ${\tt DELETE}(k)$



each of these operations takes expected $O(\log n)$ time

That is, they take $O(\log n)$ time 'on average'

Important There is *no randomness in the data*,

the only randomness is in the coin flips

On the worst case input sequence, the expected time is $O(\log n)$



Dynamic Search Structure Summary

A dynamic search structure supports (at least) the following three operations

DELETE(k) - deletes the (unique) element x with x.key = k

 $\mathsf{INSERT}(x,k)$ - inserts x with key $k=x.\mathsf{key}$

FIND(k) - returns the (unique) element x with x.key = k

Here are the time complexities of the structures we have seen...

	INSERT	DELETE	FIND
Unsorted Linked List	O(1)	O(n)	O(n)
Binary Search Tree	O(n)	O(n)	O(n)
2-3-4 Tree	$O(\log n)$	$O(\log n)$	$O(\log n)$
Red-Black Tree	$O(\log n)$	$O(\log n)$	$O(\log n)$
Skip list	$O(\log n)$	$O(\log n)$	$O(\log n)$

The time complexities for the Skip list are expected, for the others, they are worst case