

COMS10003 Work Sheet 22

Linear Algebra: Solving Linear Equations and Inverting Matrices

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1. Use substitution to find solutions or otherwise to the following 2×2 linear systems. Sketch the geometric interpretation in each case.

$$\begin{array}{rcl} x_1 & - & 2x_2 = 1 \\ 2x_1 & + & x_2 = 2 \end{array} \qquad \begin{array}{rcl} x_1 & + & 2x_2 = 3 \\ 3x_1 & + & 6x_2 = 3 \end{array}$$

2. Use Gaussian elimination (GE) to find a solution to the following 3×3 system

$$\begin{array}{rcl} x_1 & - & 2x_2 + x_3 = 2 \\ 2x_1 & + & x_2 - x_3 = 1 \\ x_1 & + & 3x_2 + 2x_3 = 3 \end{array}$$

3. Use GE to show that the following system does not have a solution. Describe in geometric terms why this is so.

$$\begin{array}{rcl} 2x_1 & + & x_2 - 3x_3 = 1 \\ 4x_1 & - & 2x_2 + x_3 = 4 \\ 2x_1 & - & 3x_2 + 4x_3 = 2 \end{array}$$

4. Use GE with matrix notation to solve the following linear system

$$\begin{array}{rcl} x_1 & + & x_2 + x_3 = 1 \\ 2x_1 & + & 2x_2 + x_3 = 3 \\ 3x_1 & + & x_2 - x_3 = 2 \end{array}$$

5. Use GE with matrix notation to find a general solution to the system

$$\begin{array}{rcl} x_1 & - & 2x_2 + 3x_3 - x_4 = 1 \\ 2x_1 & - & x_2 + x_3 + 3x_4 = 1 \\ 4x_1 & + & x_2 - 2x_3 + 5x_4 = 2 \\ 6x_1 & - & 3x_2 + 4x_3 + 3x_4 = 4 \end{array}$$

6. Examine the GE algorithm and consider each division and each multiplication-subtraction as a single operation. Show that for an $n \times n$ system, GE is an $O(n^3)$ algorithm.
7. Use the Gauss-Jordan Method to find the inverses of the following matrices (if they exist). If you find one, confirm that it is correct using matrix multiplication.

$$\begin{bmatrix} 2 & 1 & -2 \\ 5 & -3 & 7 \\ 0 & -2 & -1 \end{bmatrix} \qquad \begin{bmatrix} 1 & 2 & -4 \\ -3 & 1 & -9 \\ 2 & -3 & 13 \end{bmatrix}$$