# COMS21103: Linear Programming - cont.

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Eg.

$$\begin{array}{ll} \text{maximise} & 2x_1-x_2\\ \text{subject to} & 2x_1-x_2 \leq 2\\ & x_1-5x_2 \leq -4\\ & x_1,x_2 \geq 0 \end{array}$$

Eg.

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Slack form:

$$Z = 2x_1 - x_2$$
  
 $x_3 = 2 - 2x_1 + x_2$   
 $x_4 = -4 - x_1 + 5x_2$ 

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- ► The Simplex Algorithm assumes the initial solution is feasible,
- We need to convert the linear program to slack form where the basic solution would be feasible

change the linear program L

maximise 
$$\sum_{j=1}^{n} c_j x_j$$
  
subject to  $\sum_{j=1}^{n} a_{ij} x_j \le b_i$  for  $i=1,2,..m$   
 $x_j \ge 0$  for  $j=1,2,..n$ 

to an auxiliary linear program  $L_{aux}$ 

maximise 
$$-x_0$$
 subject to  $\sum_{j=1}^n a_{ij}x_j - x_0 \le b_i$  for  $i=1,2,..m$   $x_j \ge 0$  for  $j=0,1,..n$ 

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L is feasible if and only if the optimal objective value of  $L_{aux}$  is 0

#### Basic solution for L is infeasible

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$$2x_1 - x_2$$
  
subject to  $2x_1 - x_2 \le 2$   
 $x_1 - 5x_2 \le -4$   
 $x_1, x_2 \ge 0$ 

#### Change to $L_{aux}$ :

$$\begin{array}{ll} \text{maximise} & -x_0 \\ \text{subject to} & 2x_1 - x_2 - x_0 \leq 2 \\ & x_1 - 5x_2 - x_0 \leq -4 \\ & x_0, x_1, x_2 \geq 0 \end{array}$$

 $L_{aux}$ :

maximise 
$$-x_0$$
  
subject to  $2x_1 - x_2 - x_0 \le 2$   
 $x_1 - 5x_2 - x_0 \le -4$   
 $x_0, x_1, x_2 \ge 0$ 

Laux:

$$\begin{array}{ll} \text{maximise} & -x_0 \\ \text{subject to} & 2x_1 - x_2 - x_0 \leq 2 \\ & x_1 - 5x_2 - x_0 \leq -4 \\ & x_0, x_1, x_2 \geq 0 \end{array}$$

Slack form:

$$Z = -x_0$$
  
 $X_3 = 2 - 2x_1 + x_2 + x_0$   
 $X_4 = -4 - x_1 + 5x_2 + x_0$ 

 $L_{aux}$ :

$$\begin{array}{ll} \text{maximise} & -x_0 \\ \text{subject to} & 2x_1 - x_2 - x_0 \leq 2 \\ & x_1 - 5x_2 - x_0 \leq -4 \\ & x_0, x_1, x_2 \geq 0 \end{array}$$

Slack form:

$$Z = -x_0$$
  
 $X_3 = 2 - 2x_1 + x_2 + x_0$   
 $X_4 = -4 - x_1 + 5x_2 + x_0$ 

Initial solution  $(x_0, x_1, x_2, x_3, x_4)$  equals (0, 0, 0, 2, -4) is **still** infeasible

Switch  $x_0$  with  $x_4$  (constraint causing solution to be infeasbile)

$$Z = -x_0$$
  
 $X_3 = 2 - 2x_1 + x_2 + x_0$   
 $X_4 = -4 - x_1 + 5x_2 + x_0$ 

Switch  $x_0$  with  $x_4$  (constraint causing solution to be infeasbile)

$$x_0 = 4 + x_1 - 5x_2 + x_4$$

Switch  $x_0$  with  $x_4$  (constraint causing solution to be infeasbile)

$$z = -4$$
 -  $x_1$  +  $5x_2$  -  $x_4$   
 $x_3 = 6$  -  $x_1$  -  $4x_2$  +  $x_4$   
 $x_0 = 4$  +  $x_1$  -  $5x_2$  +  $x_4$ 

Basic solution  $(x_0, x_1, x_2, x_3, x_4)$  is now feasible (4, 0, 0, 6, 0) for  $L_{aux}$  - but not yet for L

Solve the auxiliary linear program  $L_{aux}$ 

Solve the auxiliary linear program  $L_{aux}$ 

$$Z = -4 - x_1 + 5x_2 - x_4$$
  
 $x_3 = 6 - x_1 - 4x_2 + x_4$   
 $x_0 = 4 + x_1 - 5x_2 + x_4$ 

Switch  $x_2$  with  $x_0$ 

Solve the auxiliary linear program  $L_{aux}$ 

$$Z = -4 - x_1 + 5x_2 - x_4$$
  
 $x_3 = 6 - x_1 - 4x_2 + x_4$   
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Switch  $x_2$  with  $x_0$ 

$$x_2 = \frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5}$$

Solve the auxiliary linear program  $L_{aux}$ 

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Switch  $x_2$  with  $x_0$ 

$$Z = -X_0$$

$$X_3 = \frac{14}{5} + \frac{4x_0}{5} - \frac{9x_1}{5} + \frac{x_4}{5}$$

$$X_2 = \frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5}$$

Solve the auxiliary linear program  $L_{aux}$ 

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As we found a solution for  $L_{aux}$  with objective 0, we also know that the initial linear program L is feasible, and we have found a vertex on the convex hull of feasible explanations.

Now rewrite the objective function to be  $2x_1 - x_2$  for  $L_{aux}$ :

$$Z = -X_0$$

$$X_3 = \frac{14}{5} + \frac{4x_0}{5} - \frac{9x_1}{5} + \frac{x_4}{5}$$

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objective function 
$$2x_1 - x_2 = 2x_1 - (\frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5})$$

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objective function 
$$2x_1 - x_2 = 2x_1 - (\frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5})$$

Set 
$$x_0 = 0$$
 and simplify to be  $-\frac{4}{5} + \frac{9x_1}{5} - \frac{x_4}{5}$ 

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$$2x_1 - x_2 = 2x_1 - (\frac{4}{5} - \frac{x_0}{5} + \frac{x_1}{5} + \frac{x_4}{5})$$

Set 
$$x_0=0$$
 and simplify to be  $-\frac{4}{5}+\frac{9x_1}{5}-\frac{x_4}{5}$ 

The Slack form will accordingly be

$$Z = -\frac{4}{5} + \frac{9x_1}{5} - \frac{x_4}{5}$$

$$X_3 = \frac{14}{5} - \frac{9x_1}{5} + \frac{x_4}{5}$$

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Now rewrite the objective function to be  $2x_1 - x_2$  for  $L_{aux}$ :

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Initial feasible solution is  $(x_1, x_2, x_3, x_4) = (0, \frac{4}{5}, \frac{14}{5}, 0)$ 

(N',B',A',b',c',v') = INITIALISE-SIMPLEX (A,b,c);

returns modified slack form

```
(N',B',A',b',c',v') = INITIALISE-SIMPLEX (A,b,c);
Let k be the index of minimum b_i;
if b_k \ge 0 then
return (\{1,2,...,n\},\{n+1,...,n+m\},A,b,c,0)
```

end

- returns modified slack form
- is initial solution feasible?

(N',B',A',b',c',v') = INITIALISE-SIMPLEX (A,b,c);Let k be the index of minimum  $b_i$ ;

if 
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#### end

form Laux

- returns modified slack form
- is initial solution feasible?
- ▶ add  $-x_0$  to each constraint and set objective to  $-x_0$

(N',B',A',b',c',v') = INITIALISE-SIMPLEX (A,b,c);Let k be the index of minimum  $b_i$ ;

if 
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#### end

form Laux

$$I = n + k$$

- returns modified slack form
- is initial solution feasible?
- ▶ add  $-x_0$  to each constraint and set objective to  $-x_0$
- decide on basic variable with minimum b<sub>i</sub>

(N',B',A',b',c',v') = INITIALISE-SIMPLEX (A,b,c);Let k be the index of minimum  $b_i$ :

if 
$$b_k \ge 0$$
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#### end

form Laux

$$I = n + k$$

(N,B,A,b,c,v) = PIVOT(N,B,A,c,v,I,0)

- returns modified slack form
- is initial solution feasible?
- ▶ add  $-x_0$  to each constraint and set objective to  $-x_0$
- decide on basic variable with minimum b<sub>i</sub>
- switch the roles of x<sub>0</sub> and x<sub>l</sub>. Basic solution is now feasible

(N',B',A',b',c',v') = INITIALISE-SIMPLEX (A,b,c);Let k be the index of minimum  $b_i$ ;

if 
$$b_k \geq 0$$
 then return ({1,2,..,n},{n+1,...,n+m},A,b,c,0)

#### end

form Laux

$$I = n + k$$

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Solve SIMPLEX for Laux

- returns modified slack form
- is initial solution feasible?
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- iterate lines 2-12 of SIMPLEX

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if 
$$b_k \ge 0$$
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#### end

form Laux

$$I = n + k$$

$$(N,B,A,b,c,v) = PIVOT(N,B,A,c,v,I,0)$$

Solve SIMPLEX for Laux

if optimal solution of  $L_{aux}$  sets  $x_0$  to 0 then

- returns modified slack form
- is initial solution feasible?
- ▶ add  $-x_0$  to each constraint and set objective to  $-x_0$
- decide on basic variable with minimum b<sub>i</sub>
- switch the roles of x<sub>0</sub> and x<sub>I</sub>. Basic solution is now feasible
- ▶ iterate lines 2-12 of SIMPLEX
- L is feasible

#### else

return "infeasible"

end

## The Initialise-Simplex Algorithm

```
(N',B',A',b',c',v') = INITIALISE-SIMPLEX (A,b,c);
Let k be the index of minimum b_i:
if b_k > 0 then
    return ({1,2,..,n},{n+1,..,n+m},A,b,c,0)
end
form Laux
I = n + k
(N,B,A,b,c,v) = PIVOT(N,B,A,c,v,I,0)
Solve SIMPLEX for Laux
if optimal solution of L_{aux} sets x_0 to 0 then
    if x_0 is basic then
        perform one PIVOT to make it nonbasic
    end
    remove x_0 from constraints and restore L
else
    return "infeasible"
```

- returns modified slack form
- is initial solution feasible?
- ▶ add  $-x_0$  to each constraint and set objective to  $-x_0$
- decide on basic variable with minimum b<sub>i</sub>
- switch the roles of x<sub>0</sub> and x<sub>I</sub>. Basic solution is now feasible
- iterate lines 2-12 of SIMPLEX
- L is feasible
- Restore original objective function

end

# The Initialise-Simplex Algorithm

### Lemma

Given a linear program (A,b,c), suppose that the call to INITIALISE-SIMPLEX returns a slack form for which the basic solution is feasible, then if SIMPLEX returns a solution, it is a feasible solution to the linear program. If it returns "unbounded", the linear program is unbounded.

# Fundamental Theorem of Linear Programming

### **Theorem**

Any linear program L, given in standard form, either

- 1. has an optimal solution with a finite objective value,
- 2. is infeasible, or
- 3. is unbounded.

If L is infeasible, SIMPELX returns "infeasble". If L is unbounded, SIMPLEX returns "unbounded". Otherwise SIMPLEX returns an optimal solution with a finite objective value.



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- Borgwardt [1982] showed that average running time can be bounded by a polynomial.
- ► The Simplex algorithm is very efficient in practice.
- ► The Ellipsoid algorithm (ludin and Nemirovskii [1976] and Shor [1977]) is proven to be a polynomial-time algorithm.
- ► The Ellipsoid algorithm is though too inefficient in practice.

# Linear Programs - Duality

### **Definition**

Given a linear program L (also known as the **primal** L),

maximise 
$$\sum_{j=1}^{n} c_j x_j$$
  
subject to  $\sum_{j=1}^{n} a_{ij} x_j \le b_i$  for  $i=1,2,..m$   
 $x_j \ge 0$  for  $j=1,2,..n$ 

we define the **dual** *L* to be the linear program,

minimise 
$$\sum_{j=1}^{m} b_{j}y_{j}$$
subject to 
$$\sum_{j=1}^{n} a_{ji}y_{j} = c_{i} \text{ for } i = 1, 2, ...n$$

$$y_{j} \geq 0 \text{ for } j = 1, 2, ...m$$

## Linear Programs - Duality Ex

$$\begin{array}{ll} \text{maximise} & 18x_1 + 12.5x_2 \\ \text{subject to} & x_1 + x_2 \leq 20 \\ & x_1 \leq 12 \\ & x_2 \leq 16 \\ & x_1, x_2 \geq 0 \end{array}$$

### is equivalent to:

minimise 
$$20y_1 + 12y_2 + 16y_3$$
  
subject to  $y_1 + y_2 = 18$   
 $y_1 + y_3 = 12.5$   
 $y_1, y_2, y_3 \ge 0$ 

### Linear Programs - Duality

### Lemma

The dual of the dual of a linear program L is (equivalent to) the primal L.

# Linear Programs - Duality

### Lemma

If a primal linear program L is unbounded then its dual L is infeasible. If a primal linear program L has an optimum solution, then its dual also has an optimum solution.

Back to the Convex Hull...

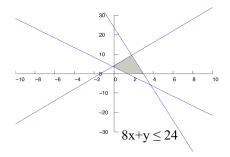
#### Back to the Convex Hull...

► The solution at each iteration of the simplex algorithm represents a vertex in the space of feasible solutions.

Back to the Convex Hull...

For the linear program

maximise 
$$-x + y$$
  
subject to  $-5x - 2y \le -7$   
 $-3x + y \le 4$   
 $8x + y \le 24$ 

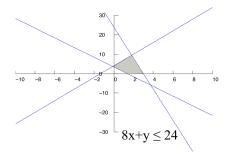


Back to the Convex Hull...

For the linear program

And its slack form

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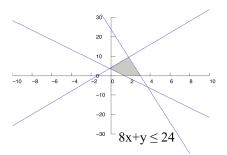
Back to the Convex Hull...

For the linear program

And its slack form

maximise
$$-x + y$$
subject to $-5x - 2y \le -7$  $-3x + y \le 4$  $8x + y \le 24$ 

$$Z = -x + y$$
  
 $X_2 = -7 + 5x + 2y$   
 $X_3 = 4 + 3x - y$   
 $X_4 = 24 - 8x - y$ 



Initial solution  $(x, y, x_2, x_3, x_4) = (0, 0, -7, 4, 24)$  is not feasible.

Using Initialise-Simplex, the slack form can be re-written to be:

$$Z = \frac{7}{2} - \frac{7x}{2} + \frac{x_2}{2}$$

$$Y = \frac{7}{2} - \frac{5x}{2} + \frac{x_2}{2}$$

$$X_3 = \frac{1}{2} + \frac{11x}{2} - \frac{x_2}{2}$$

$$X_4 = \frac{41}{2} - \frac{17x}{2} - \frac{x_2}{2}$$

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$$x_4 = \frac{41}{2} - \frac{11x}{2} - \frac{x_2}{2}$$

Initial solution is  $(0, \frac{7}{2}, 0, \frac{1}{2}, \frac{41}{2})$  is feasible

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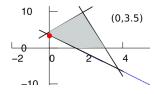
$$Z = \frac{7}{2} - \frac{7x}{2} + \frac{x_2}{2}$$

$$Y = \frac{7}{2} - \frac{5x}{2} + \frac{x_2}{2}$$

$$X_3 = \frac{1}{2} + \frac{11x}{2} - \frac{x_2}{2}$$

$$X_4 = \frac{41}{2} - \frac{11x}{2} - \frac{x_2}{2}$$

Initial solution is  $(0, \frac{7}{2}, 0, \frac{1}{2}, \frac{41}{2})$  is feasible



A vertex

After one iteration of Simplex algorithm

```
z = 4 + 2x - x_3

y = 4 + 3x - x_3

x_2 = 1 + 11x - 2x_3

x_4 = 20 - 11x + x_3
```

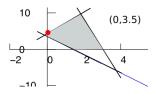
### After one iteration of Simplex algorithm

Current solution is (0,4,1,0,20) is feasible

### After one iteration of Simplex algorithm

$$Z = 4 + 2x - x_3$$
  
 $Y = 4 + 3x - x_3$   
 $X_2 = 1 + 11x - 2x_3$   
 $X_4 = 20 - 11x + x_3$ 

► Current solution is (0,4,1,0,20) is feasible



After the second iteration of Simplex algorithm

```
z = 7.636 - 0.818x_3 - 0.183x_4

y = 9.455 - 0.727x_3 - 0.273x_4

x_2 = 21 - x_3 - x_4

x = 1.818 + 0.091x_3 - 0.091x_4
```

### After the second iteration of Simplex algorithm

```
z = 7.636 - 0.818x_3 - 0.183x_4

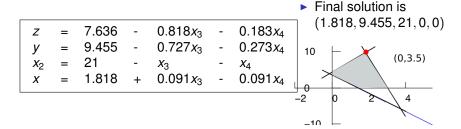
y = 9.455 - 0.727x_3 - 0.273x_4

x_2 = 21 - x_3 - x_4

x = 1.818 + 0.091x_3 - 0.091x_4
```

```
Final solution is (1.818, 9.455, 21, 0, 0)
```

### After the second iteration of Simplex algorithm



## **Further Reading**

- Introduction to Algorithms
   T.H. Cormen, C.E. Leiserson, R.L. Rivest and C. Stein.
   MIT Press/McGraw-Hill. ISBN: 0-262-03293-7.
  - Chapter 27 Linear Programming
- Combinatorial Optimization, Theory and Algorithms
   B. Korte and J. Vygen.
   Springer, 4th edition.
  - Chapter 3 Linear Programming