

RB f

$$F_k = Z_i = \sum_j [(X_j - W_{ij})^2]$$

$$= \begin{bmatrix} (x_1 - w_{11})^2 + (x_2 - w_{12})^2 + (x_3 - w_{13})^2 + \dots \\ (x_1 - w_{21})^2 + (x_2 - w_{22})^2 + \dots \\ \vdots \end{bmatrix}$$

$$\frac{\partial F_k}{\partial X_{k+1}} = \begin{bmatrix} 2(x_1 - w_{11}) & 2(x_2 - w_{12}) & \dots \\ 2(x_1 - w_{21}) & 2(x_2 - w_{22}) & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

$$\frac{\partial \mathcal{E}}{\partial X_{k+1}} = \frac{\partial \mathcal{E}}{\partial F_k} \times \left(\frac{\partial F_k}{\partial X_{k+1}} \right)$$

$\hookrightarrow [p_1, p_2, \dots]$

$$\frac{\partial \mathcal{E}}{\partial X_{k+1}} = [p_1, p_2, \dots] \begin{bmatrix} 2(x_1 - w_{11}) & 2(x_2 - w_{12}) & \dots \\ 2(x_1 - w_{21}) & 2(x_2 - w_{22}) & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

$$\frac{\partial \mathcal{E}}{\partial X_{k+1}} = \begin{bmatrix} 2p_1(x_1 - w_{11}) + 2p_2(x_1 - w_{21}) + \dots \\ 2p_1(x_2 - w_{12}) + 2p_2(x_2 - w_{22}) + \dots \\ \vdots \end{bmatrix}$$

$$\frac{\delta E}{\delta w_k} = \frac{\delta \mathcal{E}}{\delta x_k} \times \frac{\delta f_k}{\delta w}$$

$$\text{Now } \frac{\delta f_k}{\delta w_k} = \left[\begin{array}{cc} -2(x_1 - u_{11}) & -2(x_2 - u_{12}) \\ \vdots & \vdots \\ -2(x_1 - u_{n1}) & -2(x_2 - u_{n2}) \end{array} \right]$$

$$\text{So } \frac{\delta \mathcal{E}}{\delta w_k} = \frac{\delta \mathcal{E}}{\delta x_k} \times \downarrow$$

$$= [P_1, P_2, \dots] \times \left[\begin{array}{c} \vdots \\ \vdots \end{array} \right]$$

$$= \left[\begin{array}{cc} -2P_1(x_1 - u_{11}) & -2P_1(x_2 - u_{12}) \dots \\ -2P_2(x_1 - u_{21}) & -2P_2(x_2 - u_{22}) \dots \\ \vdots & \vdots \end{array} \right]$$

MUL POST

$$\frac{\delta F_k}{\delta x_{k-1}}$$

$$F_k = \begin{bmatrix} x_1 e^w \\ x_2 e^w \\ \vdots \end{bmatrix}$$

$$\frac{\delta F_k}{\delta x_{k-1}} = \begin{bmatrix} e^w & 0 & 0 & 0 & \dots & 0 \\ 0 & e^w & 0 & 0 & \dots & 0 \\ 0 & 0 & e^w & 0 & \dots & 0 \\ 0 & 0 & 0 & 0 & \dots & e^w \end{bmatrix}$$

$$\frac{\delta \mathcal{E}}{\delta x_{k-1}} = \begin{bmatrix} \tau_1 & \tau_2 & \dots \end{bmatrix} \begin{bmatrix} \end{bmatrix}$$

$$= \begin{bmatrix} \tau_1 e^w \\ \tau_2 e^w \\ \vdots \end{bmatrix}$$

$$\frac{\delta \mathcal{E}}{\delta w_k} = \frac{\delta \mathcal{E}}{\delta x_k} \times \frac{\delta F_k}{\delta w}$$

$$\frac{\delta F_k}{\delta w} = \begin{bmatrix} x_1 e^w \\ x_2 e^w \\ \vdots \end{bmatrix} \quad \frac{\delta \mathcal{E}}{\delta x_k} = \begin{bmatrix} \tau_1 & \tau_2 & \dots \end{bmatrix}$$

$$\frac{\delta \mathcal{E}}{\delta w_k} = \begin{bmatrix} \tau_1 x_1 e^w + \tau_2 x_2 e^w + \tau_3 x_3 e^w + \dots \end{bmatrix}$$

Neq Exp

$$F_k = \begin{bmatrix} e^{-x_1} \\ e^{-x_2} \\ e^{-x_3} \\ \vdots \end{bmatrix}$$

$$\frac{\delta F_k}{\delta X_{k-1}} = \begin{bmatrix} -e^{-x_1} & 0 & 0 & \dots & 0 & 0 \\ 0 & -e^{-x_2} & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & \dots & -e^{-x_n} \end{bmatrix}$$

$$\frac{\delta E}{\delta X_{k-1}} = [P_1, P_2, \dots] \quad \downarrow$$

$$= \begin{bmatrix} -P_1 e^{-x_1} \\ -P_2 e^{-x_2} \\ \vdots \end{bmatrix}$$

$$\frac{\delta E}{\delta w_k} = [P_1, P_2, \dots, P_k] \times 0$$

$$= 0$$