

Inverse Scattering Without Phase Information

Alexey Agaltsov

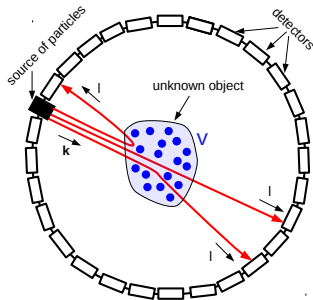
Max Planck Institute for Solar System Research, Germany
agaltsov@mps.mpg.de

Joint work with T. Hohage and R. G. Novikov

Malta – May 24, 2018

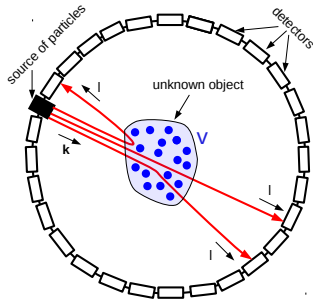
I. Problem setting

Elastic scattering by a macroscopic object



I. Problem setting

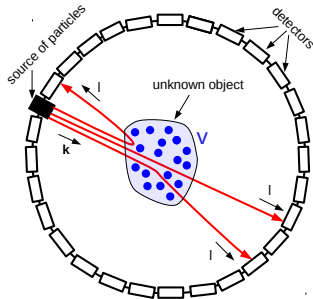
Elastic scattering by a macroscopic object



- Irradiate an object by a plane wave of wave vector \mathbf{k}

I. Problem setting

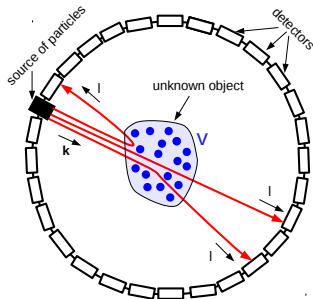
Elastic scattering by a macroscopic object



- Irradiate an object by a plane wave of wave vector \mathbf{k}
- Count particles scattered to different wave vectors \mathbf{l}

I. Problem setting

Elastic scattering by a macroscopic object



- Irradiate an object by a plane wave of wave vector \mathbf{k}
- Count particles scattered to different wave vectors \mathbf{l}

Inverse problem: Given the distribution of directions of scattered particles for different \mathbf{k} , recover the parameters of the object

I. Problem setting

- Quantum particle interacting with a macroscopic object:

$$-\Delta\psi + v(x)\psi = E\psi, \quad v \in L_{\text{comp}}^{\infty}(\mathbb{R}^d)$$

I. Problem setting

- Quantum particle interacting with a macroscopic object:

$$-\Delta\psi + v(x)\psi = E\psi, \quad v \in L_{\text{comp}}^{\infty}(\mathbb{R}^d)$$

- Scattering amplitude:

$$\psi(r\mathbf{l}) = e^{ir\mathbf{k}\mathbf{l}} + c(d, E) \frac{e^{iEr}}{r^{(d-1)/2}} f(\mathbf{k}, \mathbf{l}) + o(r^{(d-1)/2})$$

I. Problem setting

- Quantum particle interacting with a macroscopic object:

$$-\Delta\psi + v(x)\psi = E\psi, \quad v \in L_{\text{comp}}^{\infty}(\mathbb{R}^d)$$

- Scattering amplitude:

$$\psi(r\mathbf{l}) = e^{ir\mathbf{k}\mathbf{l}} + c(d, E) \frac{e^{iEr}}{r^{(d-1)/2}} f(\mathbf{k}, \mathbf{l}) + o(r^{(d-1)/2})$$

Meaning: $|f(\mathbf{k}, \mathbf{l})|^2$ is the probability density of $\mathbf{k} \rightarrow \mathbf{l}$ scattering (*different. scattering cross-section*) (M.Born'26 [3])

I. Problem setting

- Quantum particle interacting with a macroscopic object:

$$-\Delta\psi + v(x)\psi = E\psi, \quad v \in L_{\text{comp}}^{\infty}(\mathbb{R}^d)$$

- Scattering amplitude:

$$\psi(r\mathbf{l}) = e^{ir\mathbf{k}\mathbf{l}} + c(d, E) \frac{e^{iEr}}{r^{(d-1)/2}} f(\mathbf{k}, \mathbf{l}) + o(r^{(d-1)/2})$$

Meaning: $|f(\mathbf{k}, \mathbf{l})|^2$ is the probability density of $\mathbf{k} \rightarrow \mathbf{l}$ scattering (*different. scattering cross-section*) (M.Born'26 [3])

Domain: $T_E = \{(\mathbf{k}, \mathbf{l}) \in \mathbb{R}^d \times \mathbb{R}^d, |\mathbf{k}| = |\mathbf{l}| = \sqrt{E}\}$

I. Problem setting

- Quantum particle interacting with a macroscopic object:

$$-\Delta\psi + v(x)\psi = E\psi, \quad v \in L_{\text{comp}}^\infty(\mathbb{R}^d)$$

- Scattering amplitude:

$$\psi(r\mathbf{l}) = e^{ir\mathbf{k}\mathbf{l}} + c(d, E) \frac{e^{iEr}}{r^{(d-1)/2}} f(\mathbf{k}, \mathbf{l}) + o(r^{(d-1)/2})$$

Meaning: $|f(\mathbf{k}, \mathbf{l})|^2$ is the probability density of $\mathbf{k} \rightarrow \mathbf{l}$ scattering (*different. scattering cross-section*) (M.Born'26 [3])

Domain: $T_E = \{(\mathbf{k}, \mathbf{l}) \in \mathbb{R}^d \times \mathbb{R}^d, |\mathbf{k}| = |\mathbf{l}| = \sqrt{E}\}$

Inverse problem: Given $|f(\mathbf{k}, \mathbf{l})|^2$ on T_E at fixed E , recover v

I. Problem setting

- Quantum particle interacting with a macroscopic object:

$$-\Delta\psi + v(x)\psi = E\psi, \quad v \in L_{\text{comp}}^{\infty}(\mathbb{R}^d)$$

- Scattering amplitude:

$$\psi(r\mathbf{l}) = e^{i r \mathbf{k} \cdot \mathbf{l}} + c(d, E) \frac{e^{i E r}}{r^{(d-1)/2}} f(\mathbf{k}, \mathbf{l}) + o(r^{(d-1)/2})$$

Meaning: $|f(\mathbf{k}, \mathbf{l})|^2$ is the probability density of $\mathbf{k} \rightarrow \mathbf{l}$ scattering (*different. scattering cross-section*) (M.Born'26 [3])

Domain: $T_E = \{(\mathbf{k}, \mathbf{l}) \in \mathbb{R}^d \times \mathbb{R}^d, |\mathbf{k}| = |\mathbf{l}| = \sqrt{E}\}$

Inverse problem: Given $|f(\mathbf{k}, \mathbf{l})|^2$ on T_E at fixed E , recover v

- K.Chadan, P.C. Sabatier'77 and references therein

I. Problem setting

- Quantum particle interacting with a macroscopic object:

$$-\Delta\psi + v(x)\psi = E\psi, \quad v \in L_{\text{comp}}^\infty(\mathbb{R}^d)$$

- Scattering amplitude:

$$\psi(r\mathbf{l}) = e^{ir\mathbf{k}\mathbf{l}} + c(d, E) \frac{e^{iEr}}{r^{(d-1)/2}} f(\mathbf{k}, \mathbf{l}) + o(r^{(d-1)/2})$$

Meaning: $|f(\mathbf{k}, \mathbf{l})|^2$ is the probability density of $\mathbf{k} \rightarrow \mathbf{l}$ scattering (*different. scattering cross-section*) (M.Born'26 [3])

Domain: $T_E = \{(\mathbf{k}, \mathbf{l}) \in \mathbb{R}^d \times \mathbb{R}^d, |\mathbf{k}| = |\mathbf{l}| = \sqrt{E}\}$

Inverse problem: Given $|f(\mathbf{k}, \mathbf{l})|^2$ on T_E at fixed E , recover v

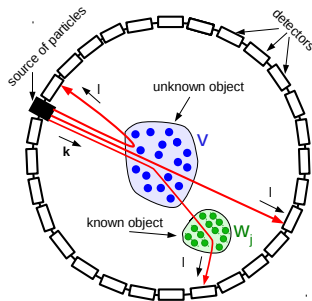
- K.Chadan, P.C. Sabatier'77 and references therein
- Similar problems:** Klivanov ('14: uniq. in 3d), Klivanov-Romanov ('16: recons.), Romanov-Yamamoto('18)

I. Problem setting

- **Non-uniqueness:** Translating the object does not change $|f(\mathbf{k}, \mathbf{l})|^2$

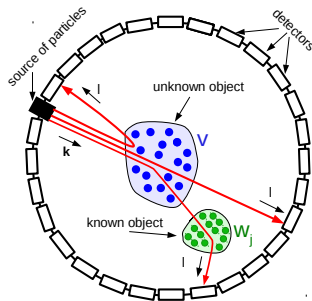
I. Problem setting

- **Non-uniqueness:** Translating the object does not change $|f(\mathbf{k}, \mathbf{l})|^2$
- Make additional experiments with known background potentials



I. Problem setting

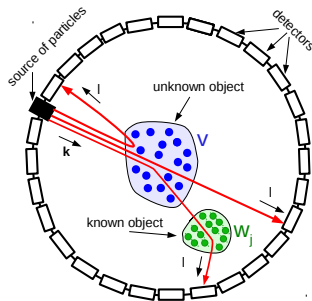
- **Non-uniqueness:** Translating the object does not change $|f(\mathbf{k}, \mathbf{l})|^2$
- Make additional experiments with known background potentials



Inverse problem: Given the distribution of directions of scattered particles for several experiments, recover the parameters of the object

I. Problem setting

- **Non-uniqueness:** Translating the object does not change $|f(\mathbf{k}, \mathbf{l})|^2$
- Make additional experiments with known background potentials



Inverse problem: Given the distribution of directions of scattered particles for several experiments, recover the parameters of the object

- **Similar idea in 1d:** Aktosun-Sacks (IP'98)

I. Problem setting

- Quantum particle in presence of a background object:

$$-\Delta\psi_j + (v(x) + w_j(x))\psi_j = E\psi_j, \quad j = 1, 2$$

I. Problem setting

- Quantum particle in presence of a background object:

$$-\Delta\psi_j + (v(x) + w_j(x))\psi_j = E\psi_j, \quad j = 1, 2$$

- Scattering amplitude:

$$\psi_j(r\mathbf{l}) = e^{ir\mathbf{k}\mathbf{l}} + c(d, E) \frac{e^{iEr}}{r^{(d-1)/2}} f_j(\mathbf{k}, \mathbf{l}) + o(r^{(d-1)/2})$$

I. Problem setting

- Quantum particle in presence of a background object:

$$-\Delta\psi_j + (v(x) + w_j(x))\psi_j = E\psi_j, \quad j = 1, 2$$

- Scattering amplitude:

$$\psi_j(r\mathbf{l}) = e^{ir\mathbf{k}\mathbf{l}} + c(d, E) \frac{e^{iEr}}{r^{(d-1)/2}} f_j(\mathbf{k}, \mathbf{l}) + o(r^{(d-1)/2})$$

Inverse problem: Given $|f(\mathbf{k}, \mathbf{l})|^2$, $|f_1(\mathbf{k}, \mathbf{l})|^2$, $|f_2(\mathbf{k}, \mathbf{l})|^2$ on T_E at fixed E , recover v

II. Main result – Comparison

Main result: Iterative reconstruction algorithm at big E

II. Main result – Comparison

Main result: Iterative reconstruction algorithm at big E

Comparison with existing results: error for $v \in C_{\text{comp}}^\infty$

| | Phased | Phaseless |
|-----------|--------|-----------|
| Born | | |
| Iterative | | |

II. Main result – Comparison

Main result: Iterative reconstruction algorithm at big E

Comparison with existing results: error for $v \in C_{\text{comp}}^\infty$

| | Phased | Phaseless |
|-----------|----------------------|-----------|
| Born | $O(E^{-1/2})$ [3, 4] | |
| Iterative | | |

[3] M. Born (Zeit. Physik, '26)

[4] L.D. Faddeev (Vestnik LGU, '56)

II. Main result – Comparison

Main result: Iterative reconstruction algorithm at big E

Comparison with existing results: error for $v \in C_{\text{comp}}^\infty$

| | Phased | Phaseless |
|-----------|----------------------|----------------------|
| Born | $O(E^{-1/2})$ [3, 4] | $O(E^{-1/2})$ [6, 2] |
| Iterative | | |

[2] Agaltsov-Novikov (J. Geom. Anal., accepted)

[3] M. Born (Zeit. Physik, '26)

[4] L.D. Faddeev (Vestnik LGU, '56)

[6] R.G. Novikov (J. Geom. Anal., '16)

II. Main result – Comparison

Main result: Iterative reconstruction algorithm at big E

Comparison with existing results: error for $v \in C_{\text{comp}}^\infty$

| | Phased | Phaseless |
|-----------|-------------------------------|----------------------|
| Born | $O(E^{-1/2})$ [3, 4] | $O(E^{-1/2})$ [6, 2] |
| Iterative | $O(E^{-j/2})$ for j it. [5] | |

[2] Agaltsov-Novikov (J. Geom. Anal., accepted)

[3] M. Born (Zeit. Physik, '26)

[4] L.D. Faddeev (Vestnik LGU, '56)

[5] R.G. Novikov (Mat. Sbornik, '15)

[6] R.G. Novikov (J. Geom. Anal., '16)

II. Main result – Comparison

Main result: Iterative reconstruction algorithm at big E

Comparison with existing results: error for $v \in C_{\text{comp}}^\infty$

| | Phased | Phaseless |
|-----------|-------------------------------|-------------------------------|
| Born | $O(E^{-1/2})$ [3, 4] | $O(E^{-1/2})$ [6, 2] |
| Iterative | $O(E^{-j/2})$ for j it. [5] | $O(E^{-j/2})$ for j it. [1] |

[1] Agaltsov-Hohage-Novikov (in progress)

[2] Agaltsov-Novikov (J. Geom. Anal., accepted)

[3] M. Born (Zeit. Physik, '26)

[4] L.D. Faddeev (Vestnik LGU, '56)

[5] R.G. Novikov (Mat. Sbornik, '15)

[6] R.G. Novikov (J. Geom. Anal., '16)

II. Main result – First approximation

- **Born approximation:**

$$\hat{v}(p) = f(\mathbf{k}, \mathbf{l}) + O(E^{-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$

II. Main result – First approximation

- **Born approximation:**

$$\widehat{v}(p) = f(\mathbf{k}, \mathbf{l}) + O(E^{-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$

- **Phaseless Born approximation:**

$$|\widehat{v}|^2 = |f|^2 + O(E^{-\frac{1}{2}}),$$

II. Main result – First approximation

- **Born approximation:**

$$\widehat{v}(p) = f(\mathbf{k}, \mathbf{l}) + O(E^{-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$

- **Phaseless Born approximation:**

$$|\widehat{v}|^2 = |f|^2 + O(E^{-\frac{1}{2}}),$$

$$|\widehat{v} + \widehat{w}_1|^2 = |f_1|^2 + O(E^{-\frac{1}{2}}),$$

$$|\widehat{v} + \widehat{w}_2|^2 = |f_2|^2 + O(E^{-\frac{1}{2}}).$$

II. Main result – First approximation

- **Born approximation:**

$$\widehat{v}(p) = f(\mathbf{k}, \mathbf{l}) + O(E^{-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$

- **Phaseless Born approximation:**

$$|\widehat{v}|^2 = |f|^2 + O(E^{-\frac{1}{2}}),$$

$$|\widehat{v} + \widehat{w}_1|^2 = |f_1|^2 + O(E^{-\frac{1}{2}}),$$

$$|\widehat{v} + \widehat{w}_2|^2 = |f_2|^2 + O(E^{-\frac{1}{2}}).$$

$$\Rightarrow \begin{pmatrix} \operatorname{Re} \widehat{w}_1 & \operatorname{Im} \widehat{w}_1 \\ \operatorname{Re} \widehat{w}_2 & \operatorname{Im} \widehat{w}_2 \end{pmatrix} \begin{pmatrix} \operatorname{Re} \widehat{v} \\ \operatorname{Im} \widehat{v} \end{pmatrix} = \begin{pmatrix} |f_1|^2 - |f|^2 - |\widehat{w}_1|^2 \\ |f_2|^2 - |f|^2 - |\widehat{w}_2|^2 \end{pmatrix} + O(E^{-\frac{1}{2}})$$

II. Main result – First approximation

- **Born approximation:**

$$\widehat{v}(p) = f(\mathbf{k}, \mathbf{l}) + O(E^{-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$

- **Phaseless Born approximation:**

$$|\widehat{v}|^2 = |f|^2 + O(E^{-\frac{1}{2}}),$$

$$|\widehat{v} + \widehat{w}_1|^2 = |f_1|^2 + O(E^{-\frac{1}{2}}),$$

$$|\widehat{v} + \widehat{w}_2|^2 = |f_2|^2 + O(E^{-\frac{1}{2}}).$$

$$\Rightarrow \begin{pmatrix} \operatorname{Re} \widehat{w}_1 & \operatorname{Im} \widehat{w}_1 \\ \operatorname{Re} \widehat{w}_2 & \operatorname{Im} \widehat{w}_2 \end{pmatrix} \begin{pmatrix} \operatorname{Re} \widehat{v} \\ \operatorname{Im} \widehat{v} \end{pmatrix} = \begin{pmatrix} |f_1|^2 - |f|^2 - |\widehat{w}_1|^2 \\ |f_2|^2 - |f|^2 - |\widehat{w}_2|^2 \end{pmatrix} + O(E^{-\frac{1}{2}})$$

[6] Drop $O(E^{-\frac{1}{2}})$ and use this to define $\operatorname{Re} \widehat{v}_E^*$, $\operatorname{Im} \widehat{v}_E^*$

II. Main result – First approximation

- **Born approximation:**

$$\widehat{v}(p) = f(\mathbf{k}, \mathbf{l}) + O(E^{-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$

- **Phaseless Born approximation:**

$$|\widehat{v}|^2 = |f|^2 + O(E^{-\frac{1}{2}}),$$

$$|\widehat{v} + \widehat{w}_1|^2 = |f_1|^2 + O(E^{-\frac{1}{2}}),$$

$$|\widehat{v} + \widehat{w}_2|^2 = |f_2|^2 + O(E^{-\frac{1}{2}}).$$

$$\Rightarrow \begin{pmatrix} \operatorname{Re} \widehat{w}_1 & \operatorname{Im} \widehat{w}_1 \\ \operatorname{Re} \widehat{w}_2 & \operatorname{Im} \widehat{w}_2 \end{pmatrix} \begin{pmatrix} \operatorname{Re} \widehat{v} \\ \operatorname{Im} \widehat{v} \end{pmatrix} = \begin{pmatrix} |f_1|^2 - |f|^2 - |\widehat{w}_1|^2 \\ |f_2|^2 - |f|^2 - |\widehat{w}_2|^2 \end{pmatrix} + O(E^{-\frac{1}{2}})$$

[6] Drop $O(E^{-\frac{1}{2}})$ and use this to define $\operatorname{Re} \widehat{v}_E^*$, $\operatorname{Im} \widehat{v}_E^*$

Result: [2] For optimal w_1, w_2 one has $v = v_E^* + O(E^{-\frac{1}{2}})$

II. Main result – Iterative step

Setup: Given an approximation v_E^* such that $v = v_E^* + O(E^{-\alpha})$, find a better approximation v_E^{**}

II. Main result – Iterative step

Setup: Given an approximation v_E^* such that $v = v_E^* + O(E^{-\alpha})$, find a better approximation v_E^{**}

- **Born approximation with a background:** [5]

$$\hat{v}(p) - \hat{v}_E^*(p) = f(\mathbf{k}, \mathbf{l}) - f_E^*(\mathbf{k}, \mathbf{l}) + O(E^{-\alpha-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$

II. Main result – Iterative step

Setup: Given an approximation v_E^* such that $v = v_E^* + O(E^{-\alpha})$, find a better approximation v_E^{**}

- **Born approximation with a background:** [5]

$$\hat{v}(p) - \hat{v}_E^*(p) = f(\mathbf{k}, \mathbf{l}) - f_E^*(\mathbf{k}, \mathbf{l}) + O(E^{-\alpha-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$

$$\Rightarrow \begin{pmatrix} \operatorname{Re}(f_{E,1}^* - f_E^*) & \operatorname{Im}(f_{E,1}^* - f_E^*) \\ \operatorname{Re}(f_{E,2}^* - f_E^*) & \operatorname{Im}(f_{E,2}^* - f_E^*) \end{pmatrix} \begin{pmatrix} \operatorname{Re} f \\ \operatorname{Im} f \end{pmatrix} = \begin{pmatrix} |f_1|^2 - |f|^2 - |f_E^* - f_{E,1}^*|^2 \\ |f_2|^2 - |f|^2 - |f_E^* - f_{E,2}^*|^2 \end{pmatrix} + O(E^{-\alpha-\frac{1}{2}})$$

II. Main result – Iterative step

Setup: Given an approximation v_E^* such that $v = v_E^* + O(E^{-\alpha})$, find a better approximation v_E^{**}

- **Born approximation with a background:** [5]

$$\widehat{v}(p) - \widehat{v}_E^*(p) = f(\mathbf{k}, \mathbf{l}) - f_E^*(\mathbf{k}, \mathbf{l}) + O(E^{-\alpha-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$

$$\Rightarrow \begin{pmatrix} \operatorname{Re}(f_{E,1}^* - f_E^*) & \operatorname{Im}(f_{E,1}^* - f_E^*) \\ \operatorname{Re}(f_{E,2}^* - f_E^*) & \operatorname{Im}(f_{E,2}^* - f_E^*) \end{pmatrix} \begin{pmatrix} \operatorname{Re} f \\ \operatorname{Im} f \end{pmatrix} = \begin{pmatrix} |f_1|^2 - |f|^2 - |f_E^* - f_{E,1}^*|^2 \\ |f_2|^2 - |f|^2 - |f_E^* - f_{E,2}^*|^2 \end{pmatrix} + O(E^{-\alpha-\frac{1}{2}})$$

[1] Drop $O(E^{-\alpha-\frac{1}{2}})$ and use this to define $\operatorname{Re} f_{\text{ap}}$, $\operatorname{Im} f_{\text{ap}}$

II. Main result – Iterative step

Setup: Given an approximation v_E^* such that $v = v_E^* + O(E^{-\alpha})$, find a better approximation v_E^{**}

- **Born approximation with a background:** [5]

$$\hat{v}(p) - \hat{v}_E^*(p) = f(\mathbf{k}, \mathbf{l}) - f_E^*(\mathbf{k}, \mathbf{l}) + O(E^{-\alpha-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$

$$\Rightarrow \begin{pmatrix} \operatorname{Re}(f_{E,1}^* - f_E^*) & \operatorname{Im}(f_{E,1}^* - f_E^*) \\ \operatorname{Re}(f_{E,2}^* - f_E^*) & \operatorname{Im}(f_{E,2}^* - f_E^*) \end{pmatrix} \begin{pmatrix} \operatorname{Re} f \\ \operatorname{Im} f \end{pmatrix} = \begin{pmatrix} |f_1|^2 - |f|^2 - |f_E^* - f_{E,1}^*|^2 \\ |f_2|^2 - |f|^2 - |f_E^* - f_{E,2}^*|^2 \end{pmatrix} + O(E^{-\alpha-\frac{1}{2}})$$

[1] Drop $O(E^{-\alpha-\frac{1}{2}})$ and use this to define $\operatorname{Re} f_{\text{ap}}, \operatorname{Im} f_{\text{ap}}$

[1] Put $\hat{v}_E^{**} = (\hat{v}_E^* + f_{\text{ap}} - f_E^*) \times \text{appropriate_cutoff}$

II. Main result – Iterative step

Setup: Given an approximation v_E^* such that $v = v_E^* + O(E^{-\alpha})$, find a better approximation v_E^{**}

- **Born approximation with a background:** [5]

$$\hat{v}(p) - \hat{v}_E^*(p) = f(\mathbf{k}, \mathbf{l}) - f_E^*(\mathbf{k}, \mathbf{l}) + O(E^{-\alpha-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$

$$\Rightarrow \begin{pmatrix} \operatorname{Re}(f_{E,1}^* - f_E^*) & \operatorname{Im}(f_{E,1}^* - f_E^*) \\ \operatorname{Re}(f_{E,2}^* - f_E^*) & \operatorname{Im}(f_{E,2}^* - f_E^*) \end{pmatrix} \begin{pmatrix} \operatorname{Re} f \\ \operatorname{Im} f \end{pmatrix} = \begin{pmatrix} |f_1|^2 - |f|^2 - |f_E^* - f_{E,1}^*|^2 \\ |f_2|^2 - |f|^2 - |f_E^* - f_{E,2}^*|^2 \end{pmatrix} + O(E^{-\alpha-\frac{1}{2}})$$

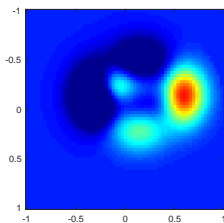
[1] Drop $O(E^{-\alpha-\frac{1}{2}})$ and use this to define $\operatorname{Re} f_{\text{ap}}, \operatorname{Im} f_{\text{ap}}$

[1] Put $\hat{v}_E^{**} = (\hat{v}_E^* + f_{\text{ap}} - f_E^*) \times \text{appropriate_cutoff}$

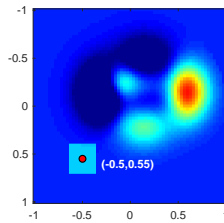
Result: [1] For optimal w_1, w_2 one has $v = v_E^{**} + O(E^{-\alpha-\frac{1}{2}})$

III. Numerical examples

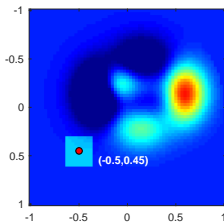
Unknown potential and background potentials:



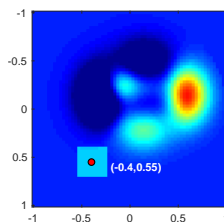
V



$V + w_1$



$V + w_2$



$V + w_3$

III. Numerical examples

Data: Simulate the scattering experiment by Poisson data for a given total number N_p of particles registered by 256 detectors for each \mathbf{k} and 32 different \mathbf{k}

III. Numerical examples

Data: Simulate the scattering experiment by Poisson data for a given total number N_p of particles registered by 256 detectors for each \mathbf{k} and 32 different \mathbf{k}

L^∞ errors in percents:

- Born approximation

| $N_p \backslash E$ | 5^2 | 10^2 | 15^2 |
|--------------------|-------|--------|--------|
| 10^7 | 35 | 10 | 7.4 |
| 10^8 | 35 | 10 | 7.4 |
| 10^9 | 35 | 10 | 7.5 |

III. Numerical examples

Data: Simulate the scattering experiment by Poisson data for a given total number N_p of particles registered by 256 detectors for each \mathbf{k} and 32 different \mathbf{k}

L^∞ errors in percents:

- Born approximation

| $N_p \backslash E$ | 5^2 | 10^2 | 15^2 |
|--------------------|-------|--------|--------|
| 10^7 | 35 | 10 | 7.4 |
| 10^8 | 35 | 10 | 7.4 |
| 10^9 | 35 | 10 | 7.5 |

- Our method

| $N_p \backslash E$ | 5^2 | 10^2 | 15^2 |
|--------------------|-------|--------|--------|
| 10^7 | 32 | 6.2 | 5.1 |
| 10^8 | 25 | 3.4 | 2.3 |
| 10^9 | 24 | 1.5 | 1.3 |

III. Numerical examples

Data: Simulate the scattering experiment by Poisson data for a given total number N_p of particles registered by 256 detectors for each \mathbf{k} and 32 different \mathbf{k}

L^∞ errors in percents:

- Born approximation

| $N_p \backslash E$ | 5^2 | 10^2 | 15^2 |
|--------------------|-------|--------|--------|
| 10^7 | 35 | 10 | 7.4 |
| 10^8 | 35 | 10 | 7.4 |
| 10^9 | 35 | 10 | 7.5 |

- Our method

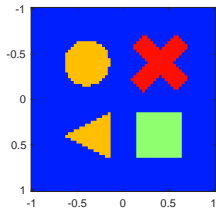
| $N_p \backslash E$ | 5^2 | 10^2 | 15^2 |
|--------------------|-------|--------|--------|
| 10^7 | 32 | 6.2 | 5.1 |
| 10^8 | 25 | 3.4 | 2.3 |
| 10^9 | 24 | 1.5 | 1.3 |

- Our method+NewtonCG

| $N_p \backslash E$ | 5^2 | 10^2 | 15^2 |
|--------------------|-------|--------|--------|
| 10^7 | 28 | 3.4 | 3.4 |
| 10^8 | 23 | 1.8 | 1.6 |
| 10^9 | 22 | 1.3 | 0.83 |

III. Numerical examples

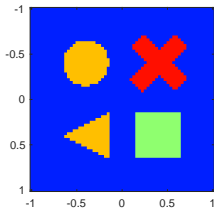
Nonsmooth potential:



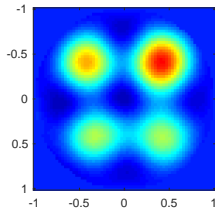
Exact potential

III. Numerical examples

Nonsmooth potential:



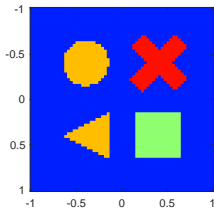
Exact potential



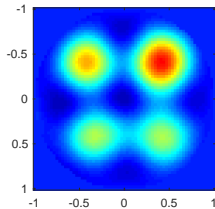
Born approximation

III. Numerical examples

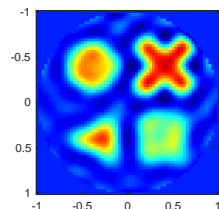
Nonsmooth potential:



Exact potential



Born approximation



Our method

III. Numerical examples

Our method vs NewtonCG: Pros and Cons

| | our method | NewtonCG |
|--------------------|------------|----------|
| global convergence | yes | no |

III. Numerical examples

Our method vs NewtonCG: Pros and Cons

| | our method | NewtonCG |
|----------------------|-------------------------|-------------|
| global convergence | yes | no |
| asymptotically exact | $E \rightarrow +\infty$ | potentially |

III. Numerical examples

Our method vs NewtonCG: Pros and Cons

| | our method | NewtonCG |
|-------------------------|-------------------------|-------------|
| global convergence | yes | no |
| asymptotically exact | $E \rightarrow +\infty$ | potentially |
| black-box direct solver | yes | no |

III. Numerical examples

Our method vs NewtonCG: Pros and Cons

| | our method | NewtonCG |
|-------------------------|-------------------------|-------------|
| global convergence | yes | no |
| asymptotically exact | $E \rightarrow +\infty$ | potentially |
| black-box direct solver | yes | no |
| reference exec. time | 1s | 23s |

III. Numerical examples

Our method vs NewtonCG: Pros and Cons

| | our method | NewtonCG |
|-------------------------|-------------------------|-------------|
| global convergence | yes | no |
| asymptotically exact | $E \rightarrow +\infty$ | potentially |
| black-box direct solver | yes | no |
| reference exec. time | 1s | 23s |
| stopping rule | no | yes |

IV. Implementation

- Born approximation formula

$$\begin{aligned}\widehat{v}(p) &= f(\mathbf{k}, \mathbf{l}) + O(E^{-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l} \\ (\mathbf{k}, \mathbf{l}) \in T_E &\Rightarrow p \in B_{2\sqrt{E}}\end{aligned}$$

IV. Implementation

- Born approximation formula

$$\hat{v}(p) = f(\mathbf{k}, \mathbf{l}) + O(E^{-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$
$$(\mathbf{k}, \mathbf{l}) \in T_E \Rightarrow p \in B_{2\sqrt{E}}$$

- **Ewald sphere:** given n_1, n_2 uniform inc., meas. directions:

$$\mathcal{E}_{n_1, n_2} = \{p = \mathbf{k} - \mathbf{l} \mid \mathbf{k} : \text{inc. direction}, \mathbf{l} : \text{meas. direction}\}$$

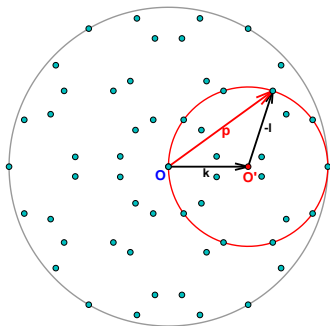
IV. Implementation

- Born approximation formula

$$\hat{v}(p) = f(\mathbf{k}, \mathbf{l}) + O(E^{-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$
$$(\mathbf{k}, \mathbf{l}) \in T_E \Rightarrow p \in B_{2\sqrt{E}}$$

- Ewald sphere:** given n_1, n_2 uniform inc., meas. directions:

$$\mathcal{E}_{n_1, n_2} = \{p = \mathbf{k} - \mathbf{l} \mid \mathbf{k} : \text{inc. direction}, \mathbf{l} : \text{meas. direction}\}$$



$$n_1 = 6, n_2 = 10$$

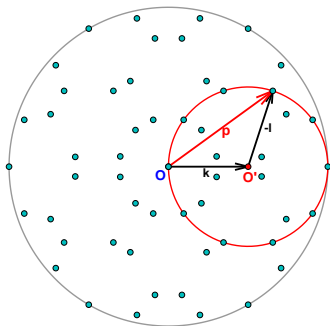
IV. Implementation

- Born approximation formula

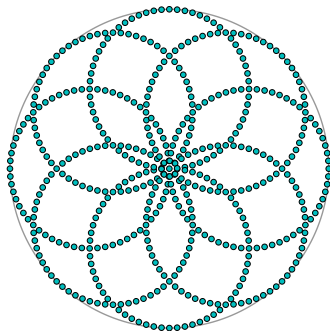
$$\hat{v}(p) = f(\mathbf{k}, \mathbf{l}) + O(E^{-\frac{1}{2}}), \quad p = \mathbf{k} - \mathbf{l}$$
$$(\mathbf{k}, \mathbf{l}) \in T_E \Rightarrow p \in B_{2\sqrt{E}}$$

- Ewald sphere:** given n_1, n_2 uniform inc., meas. directions:

$$\mathcal{E}_{n_1, n_2} = \{p = \mathbf{k} - \mathbf{l} \mid \mathbf{k} : \text{inc. direction}, \mathbf{l} : \text{meas. direction}\}$$

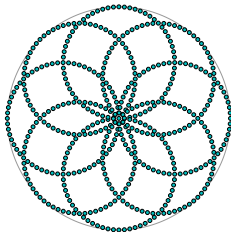


$$n_1 = 6, n_2 = 10$$



$$n_1 = 8, n_2 = 64$$

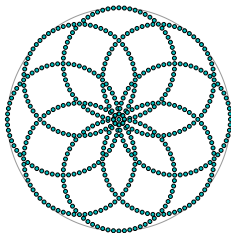
IV. Implementation



- **Inverse Fourier transform:**

$$v(x) = \int_{\mathbb{R}^2} e^{-ipx} \hat{v}(p) dp$$

IV. Implementation



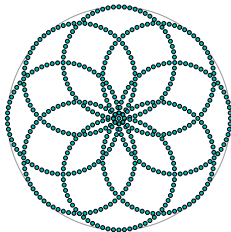
- **Inverse Fourier transform:**

$$v(x) = \int_{\mathbb{R}^2} e^{-ipx} \widehat{v}(p) dp$$

- Approximation by a Riemann's sum:

$$v(x) \approx \sum_{p \in \mathcal{E}_{n_1, n_2}} e^{-ipx} \widehat{v}(p) w(p),$$

IV. Implementation



- **Inverse Fourier transform:**

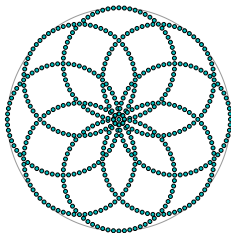
$$v(x) = \int_{\mathbb{R}^2} e^{-ipx} \hat{v}(p) dp$$

- Approximation by a Riemann's sum:

$$v(x) \approx \sum_{p \in \mathcal{E}_{n_1, n_2}} e^{-ipx} \hat{v}(p) w(p),$$

- NFFT: J.Keiner, S.Kunis, D.Potts (ACM Trans. Math. Software'09)

IV. Implementation



- Inverse Fourier transform:

$$v(x) = \int_{\mathbb{R}^2} e^{-ipx} \hat{v}(p) dp$$

- Approximation by a Riemann's sum:

$$v(x) \approx \sum_{p \in \mathcal{E}_{n_1, n_2}} e^{-ipx} \hat{v}(p) w(p),$$

- NFFT: J.Keiner, S.Kunis, D.Potts (ACM Trans. Math. Software'09)

Question: How to subdivide $B_{2\sqrt{E}}$ in cells with nodes at \mathcal{E}_{n_1, n_2} ?

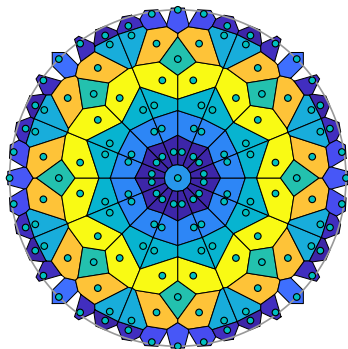
IV. Implementation

Voronoi diagram:

`/wiki/Voronoi_diagram`

IV. Implementation

Voronoi diagram:



`/wiki/Voronoi_diagram`

$$n_1 = 8, n_2 = 10$$

Established results:

- Iterative algorithm for phaseless inverse potential scattering

Established results:

- Iterative algorithm for phaseless inverse potential scattering
- Estimates of reconstruction errors

Established results:

- Iterative algorithm for phaseless inverse potential scattering
- Estimates of reconstruction errors

How and why to use it?

- Find an approximation using our method and then feed it to NewtonCG

Established results:

- Iterative algorithm for phaseless inverse potential scattering
- Estimates of reconstruction errors

How and why to use it?

- Find an approximation using our method and then feed it to NewtonCG
- Much faster and more precise than standard methods

Established results:

- Iterative algorithm for phaseless inverse potential scattering
- Estimates of reconstruction errors

How and why to use it?

- Find an approximation using our method and then feed it to NewtonCG
- Much faster and more precise than standard methods

Limitations:

- Convergence at small E

References

- [1] A. D. Agaltsov, T. Hohage, and R. G. Novikov. “An iterative approach to monochromatic phaseless inverse scattering”. In: (). in preparation.
- [2] A. D. Agaltsov and R. G. Novikov. “Error estimates for phaseless inverse scattering in the Born approximation at high energies”. In: *The Journal of Geometric Analysis* (). accepted. ISSN: 1050-6926. DOI: 10.1007/s12220-017-9872-6.
- [3] M. Born. “Quantenmechanik der Stoßvorgänge”. In: *Zeitschrift für Physik* 38.11 (1926), pp. 803–827.
- [4] L. D. Faddeev. “Uniqueness of the solution of the inverse scattering problem”. In: *Vest. Leningrad Univ.* 7 (1956). (in Russian), pp. 126–130.
- [5] R. G. Novikov. “An iterative approach to non-overdetermined inverse scattering at fixed energy”. In: *Sbornik: Mathematics* 206.1 (2015), pp. 120–134.
- [6] R. G. Novikov. “Explicit formulas and global uniqueness for phaseless inverse scattering in multidimensions”. In: *The Journal of Geometric Analysis* 26.1 (2016), pp. 346–359.