

# Part 1: General Introduction into Uncertainty & Domain Shift

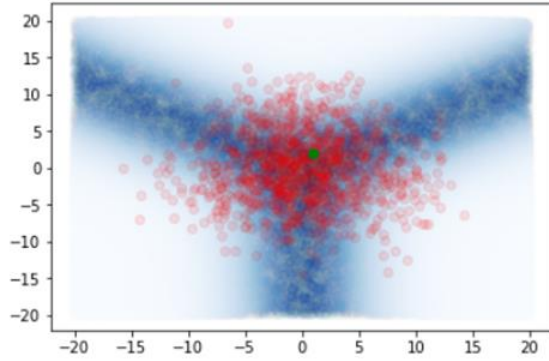
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Vatsal Raina

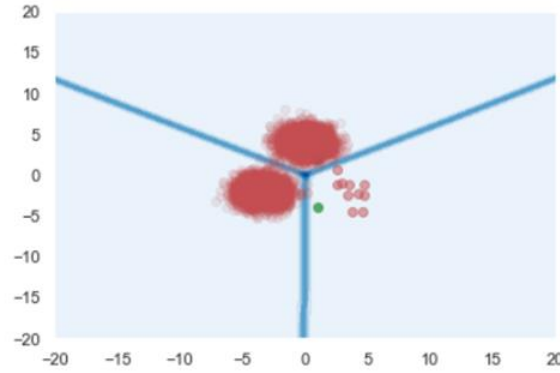


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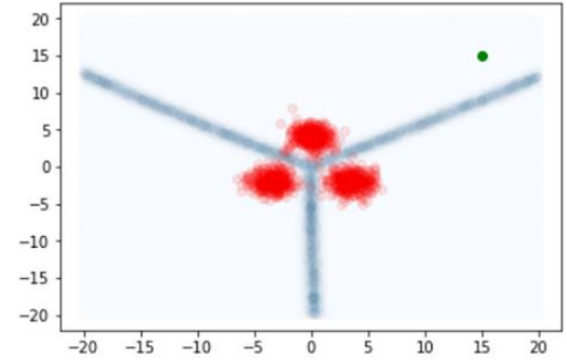
# Sources of Uncertainty - *Classification*



(a) Data Uncertainty



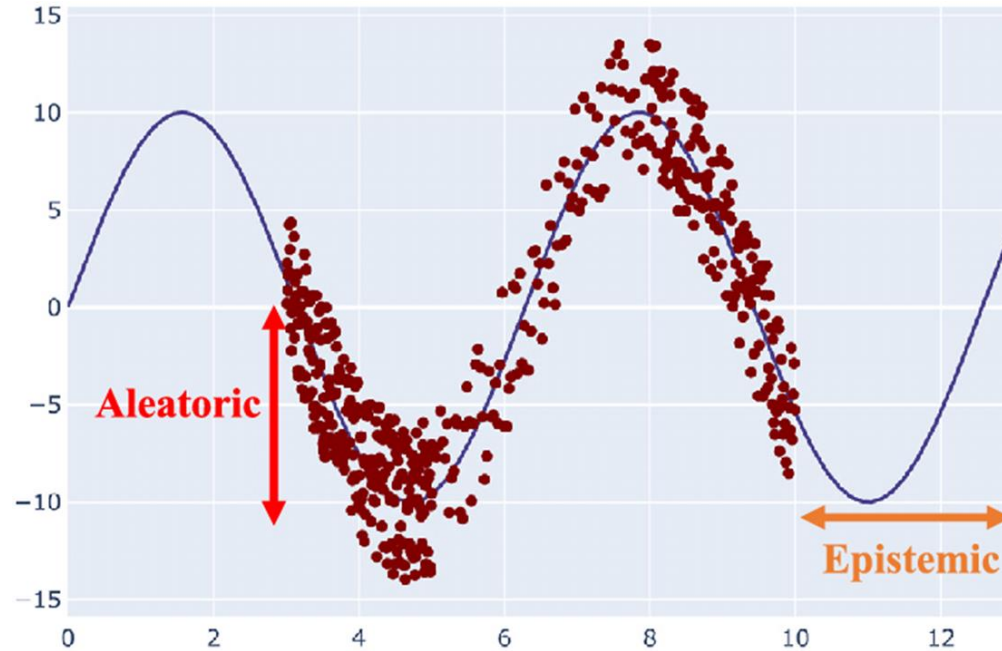
(b) Knowledge Uncertainty



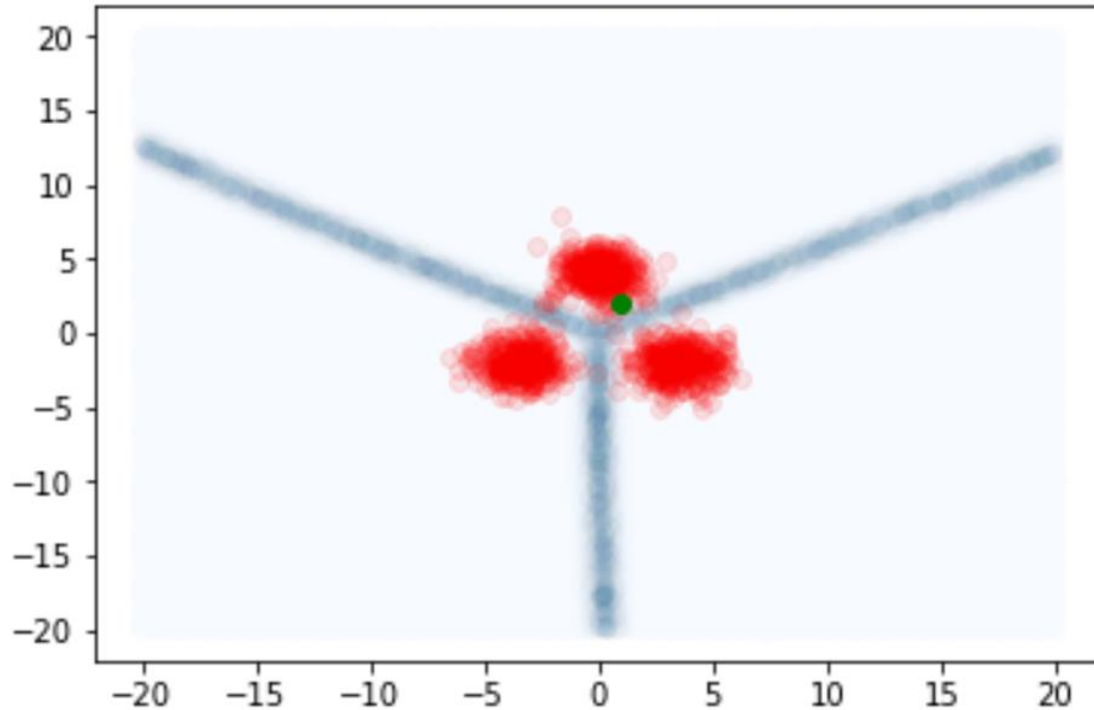
(c) Knowledge Uncertainty

- Data Uncertainty  $\rightarrow$  Aleatoric Uncertainty
- Knowledge Uncertainty  $\rightarrow$  Epistemic Uncertainty

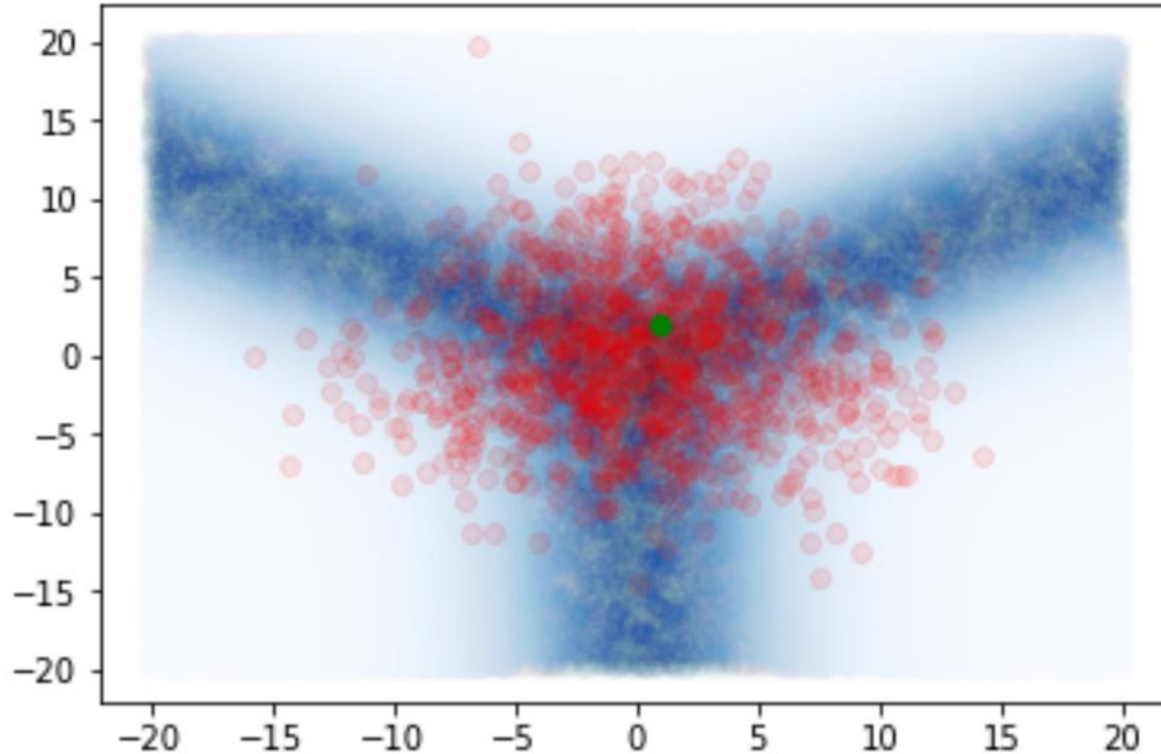
# Sources of Uncertainty - *Regression*



# Data (Aleatoric) Uncertainty - Classification



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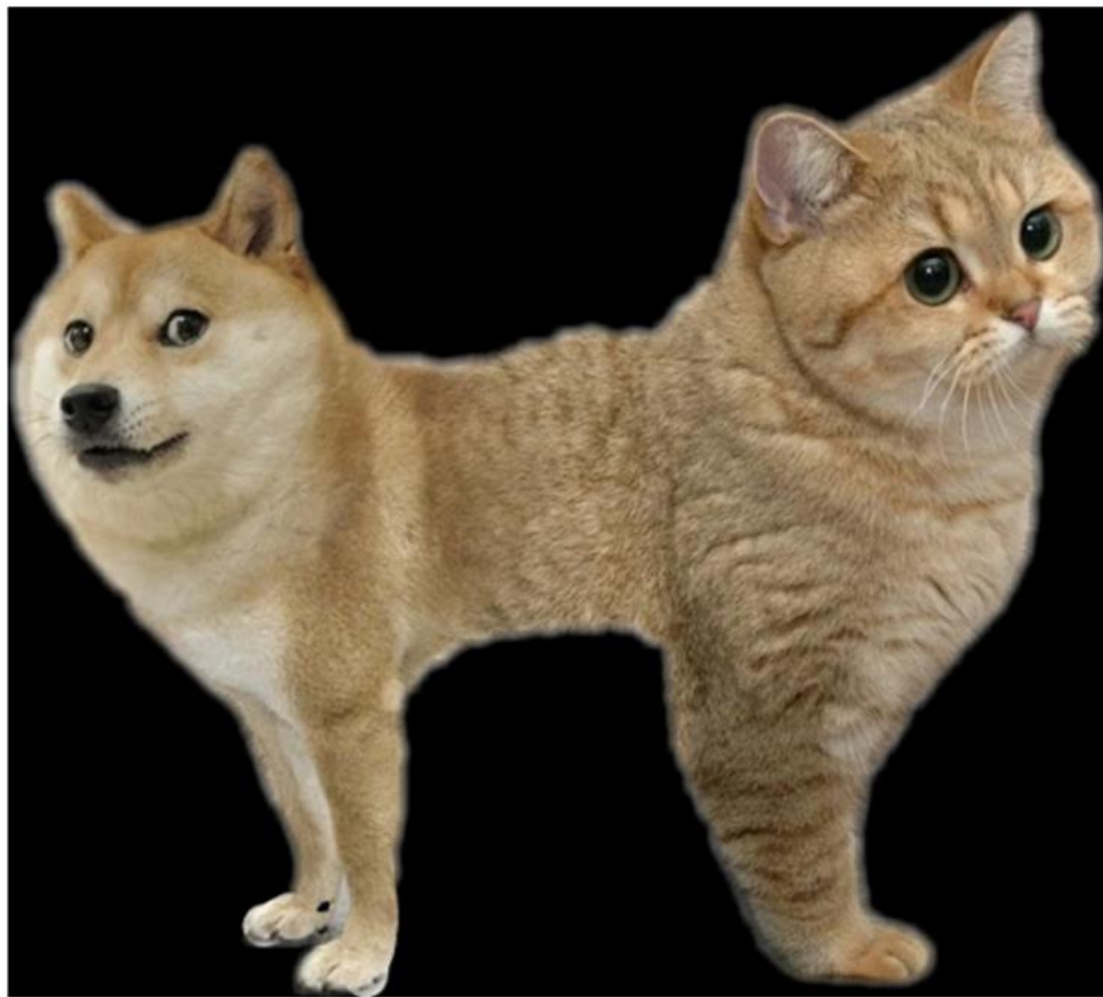


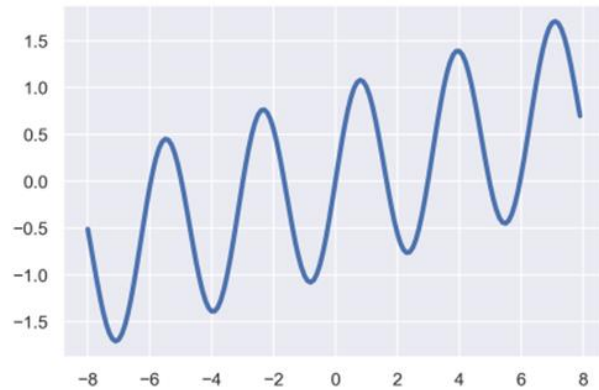
- Distinct Classes



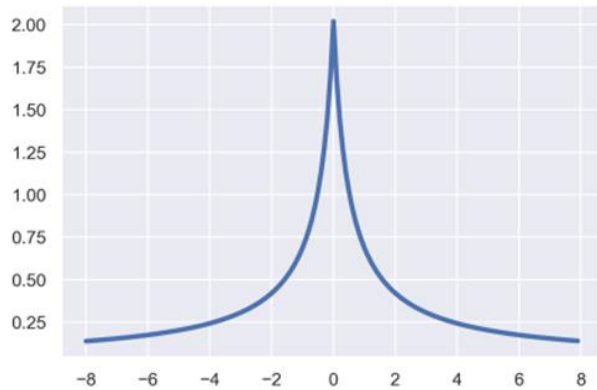
- Overlapping Classes



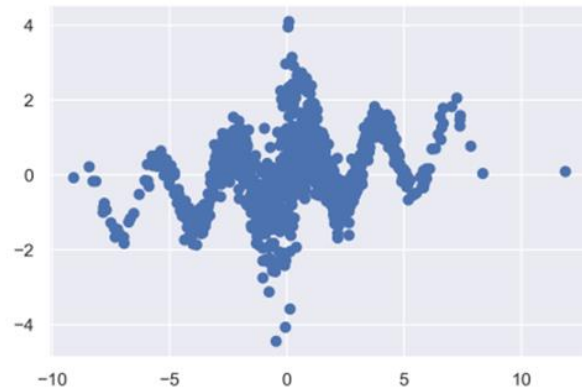




(a) Function  $\mu(x) = \sin(2x) + \frac{x}{10}$



(b) Noise std  $\sigma(x) = 0.02 + \frac{2}{|x^2|+1}$



(c) Sampled Data  $y \sim p(\mu(x), \sigma(x))$

- Data Uncertainty for Regression  $\rightarrow$  additive noise  $\sigma(x)$ 
  - Homoscedastic - input **independent**  $\sigma(x) = C$
  - Heteroscedastic - input **dependant**  $\sigma(x) = g(x)$



# Example reasons for data uncertainty



Measurement  
Error



Data  
Noise



Temporal  
Uncertainty



Sampling  
Uncertainty



Bias in Data  
Collection



Inconsistent  
Data Formats

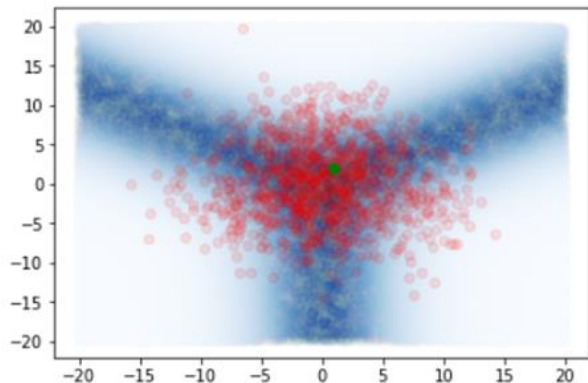


Missing  
Data

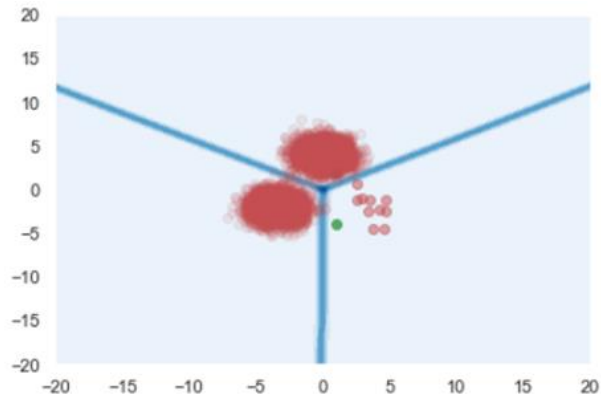


Ambiguity in  
Data Sources

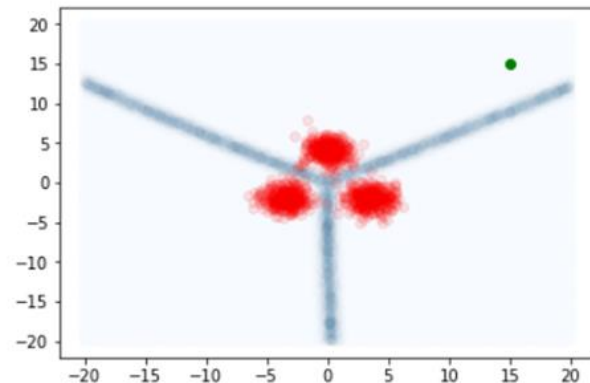
# Sources of Uncertainty



(a) Data Uncertainty



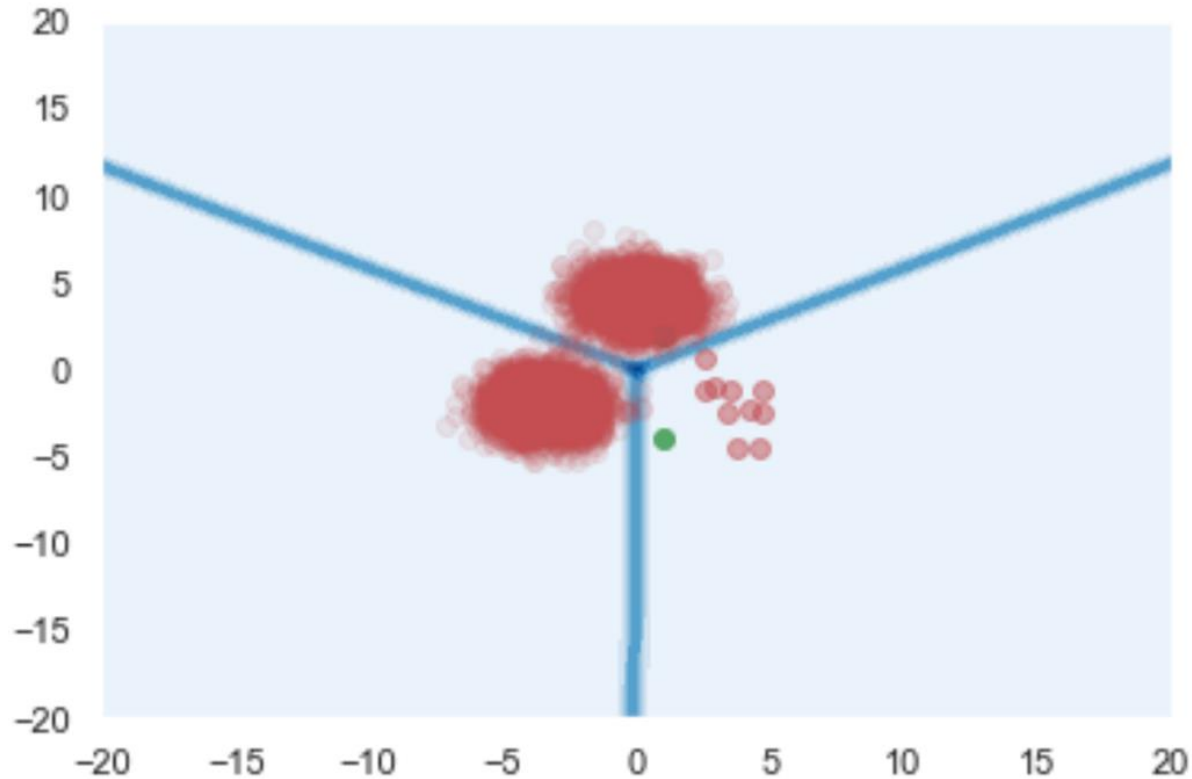
(b) Data Sparsity



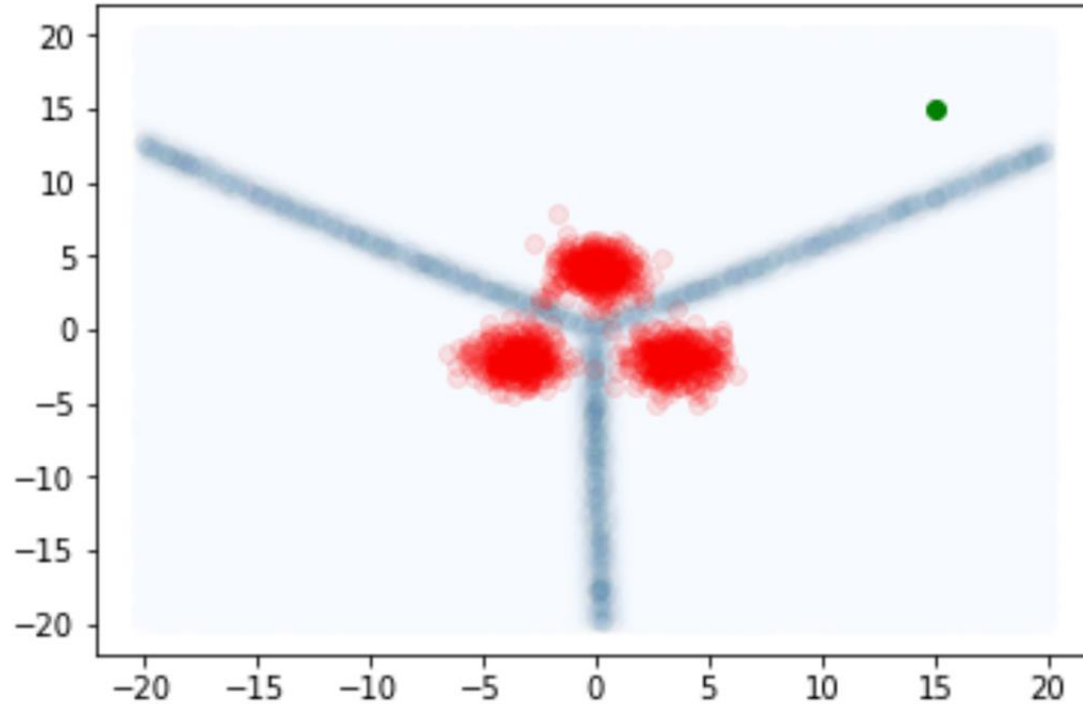
(c) Out-of-Distribution inputs

- Knowledge (epistemic) uncertainty refers to both:
  - Data Sparsity and Out-of-distribution inputs

# Knowledge (Epistemic) Uncertainty - Classification

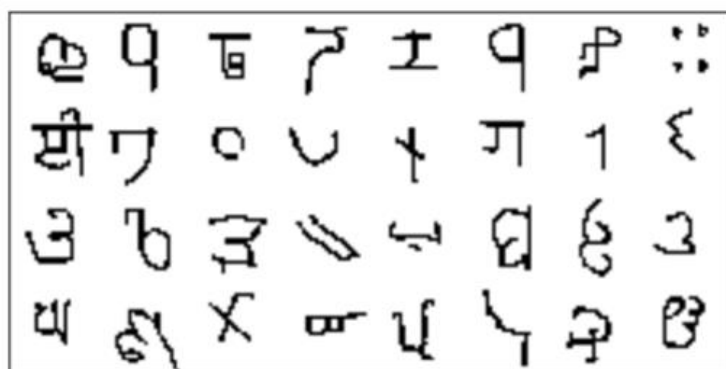
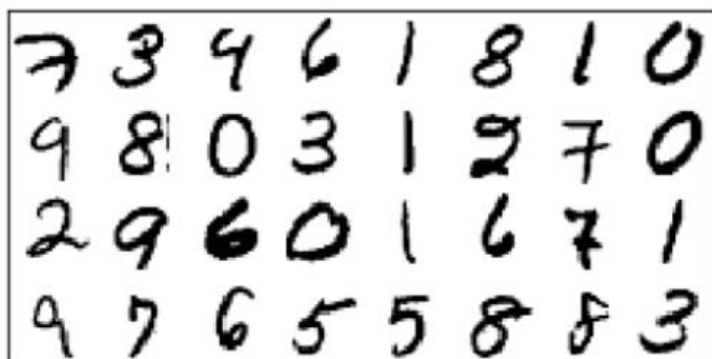


# Knowledge (Epistemic) Uncertainty - Classification



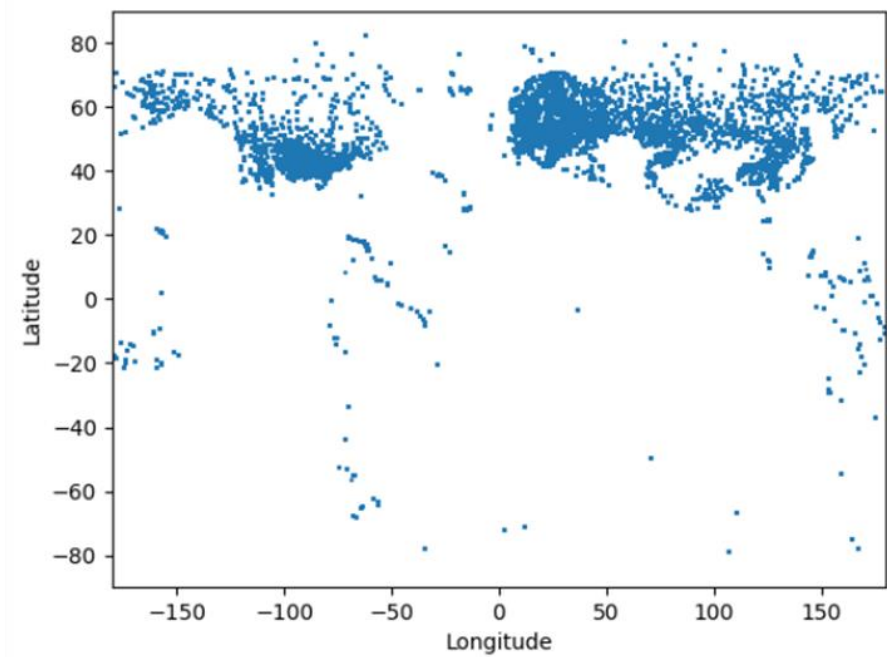
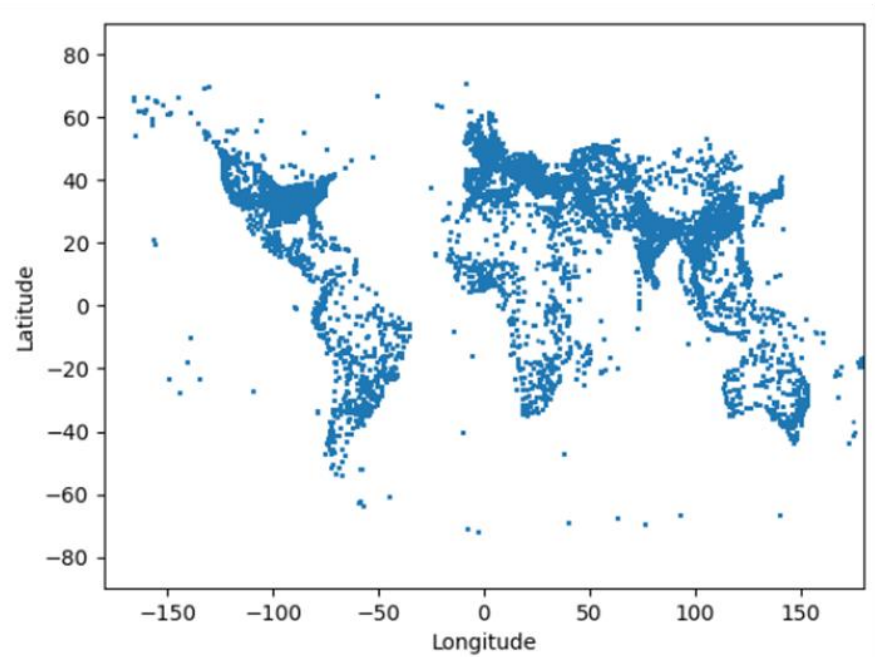
Data Sparsity + OOD is all  
**DOMAIN SHIFT**

- Unseen classes



- Unseen variations of seen classes



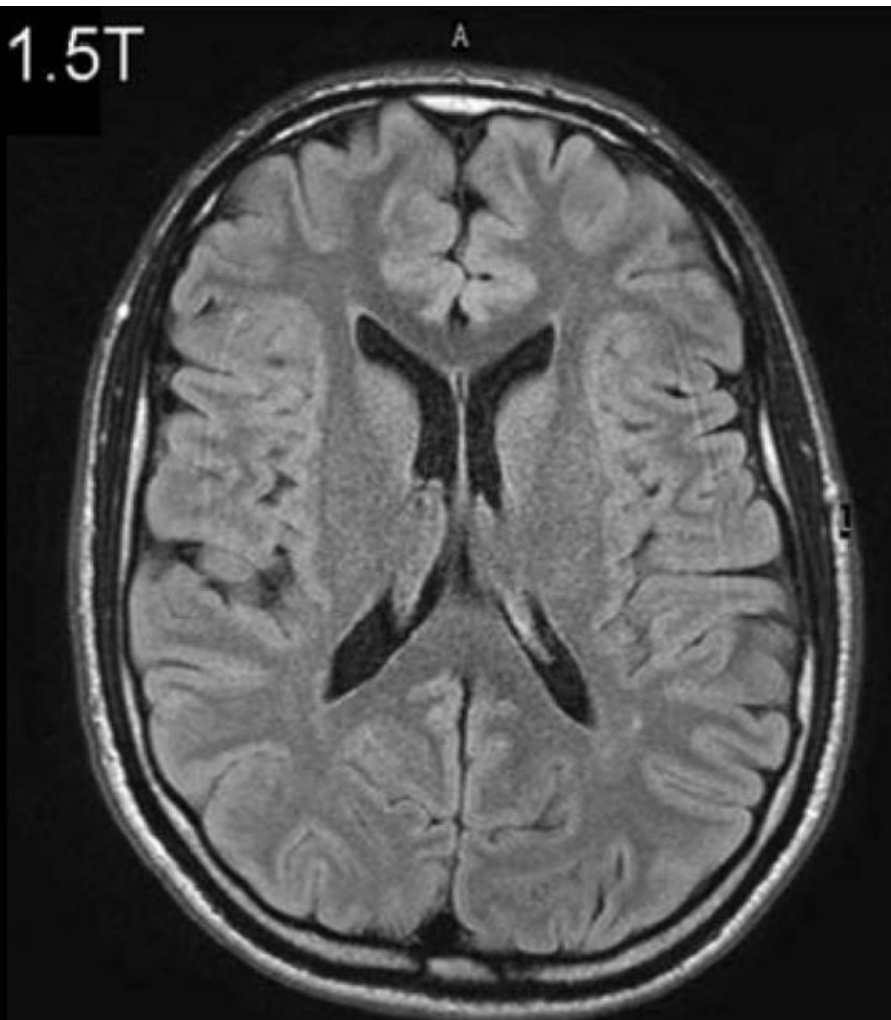
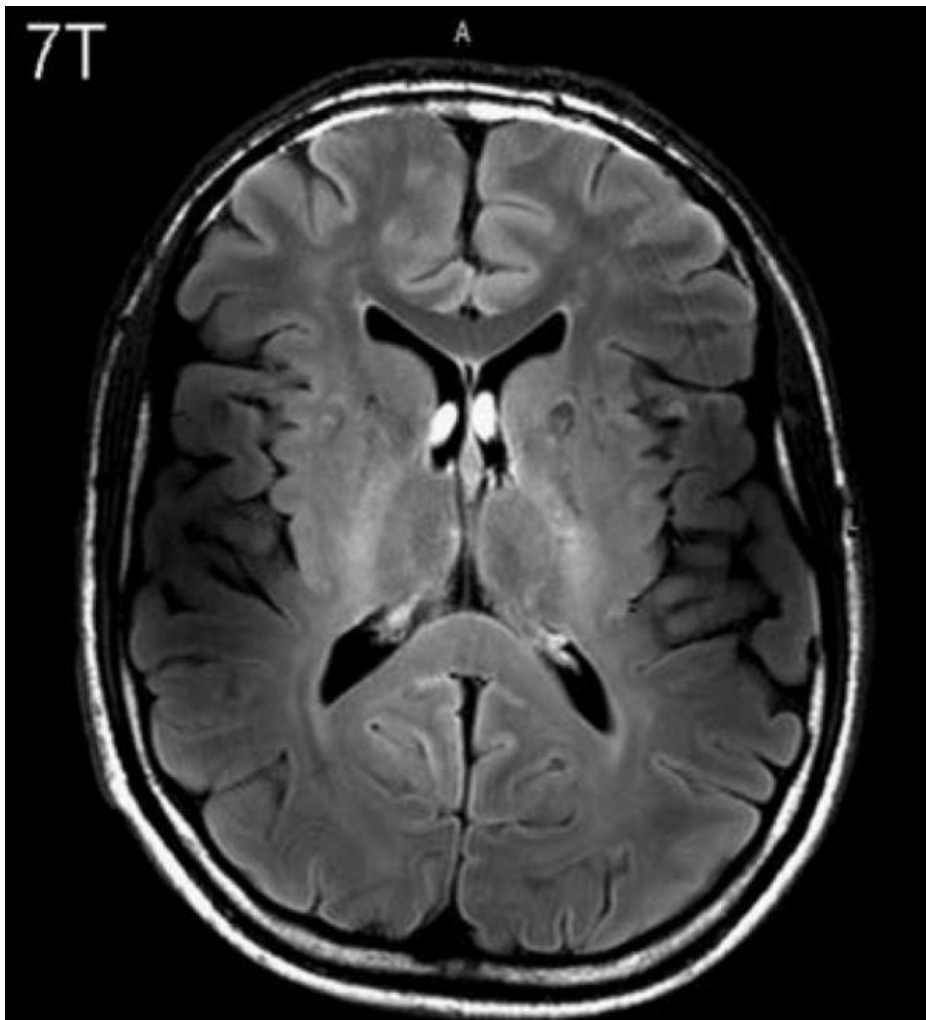


7T

A

1.5T

A





# Formal definitions - *Bayesian framework*

$$\mathbf{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_N\}$$

$$\mathbf{Y} = \{\mathbf{y}_1, \dots, \mathbf{y}_N\}$$

$$p(\mathbf{y}^* | \mathbf{x}^*, \mathbf{X}, \mathbf{Y}) = \int p(\mathbf{y}^* | \mathbf{x}^*, \omega) p(\omega | \mathbf{X}, \mathbf{Y}) d\omega$$

Interested in uncertainty of  
this distribution

Uncertainty of this  
distribution is DATA  
uncertainty

Uncertainty of this  
distribution is  
KNOWLEDGE uncertainty

# Next

- The sources of uncertainty in medical imaging?
- Why is measuring uncertainty useful?
- How can we practically measure uncertainty?
- How to assess the quality of uncertainty quantification?

# Q&A