EE24BTECH11002 - Agamjot Singh

Question:

Solve the differential equation:

$$\frac{d^2y}{dx^2} + y = 0\tag{1}$$

Solution:

Theoritical solution:

The given differential equation is a second-order linear ordinary differential equation. Let $y(0) = c_1$ and $y'(0) = c_2$. By definition of Laplace transform,

$$\mathcal{L}(f(t)) = \int_0^\infty e^{-st} f(t) dt$$
 (2)

Some used properties of Laplace transform include,

$$\mathcal{L}(y'') = s^2 \mathcal{L}(y) - sy(0) - y'(0) = s^2 \mathcal{L}(y) - sc_1 - c_2$$
(3)

$$\mathcal{L}(\cos t) = \frac{s}{s^2 + 1} \tag{4}$$

$$\mathcal{L}(\sin t) = \frac{1}{c^2 + 1} \tag{5}$$

$$\mathcal{L}(cf(t)) = c\mathcal{L}(f(t)) \tag{6}$$

$$\mathcal{L}(f(t)) = F(s) \implies \mathcal{L}(e^{at}f(t)) = F(s-a)$$
 (7)

Applying Laplace transform on the given differential equation, we get,

$$y'' + y = 0 \tag{8}$$

$$\mathcal{L}(y'') + \mathcal{L}(y) = 0 \tag{9}$$

$$s^{2} \mathcal{L}(y) - sc_{1} - c_{2} + \mathcal{L}(y) = 0$$
 (10)

$$\mathcal{L}(y) = \frac{sc_1 + c_2}{s^2 + 1} = c_1 \frac{s}{s^2 + 1} + c_2 \frac{1}{s^2 + 1}$$
(11)

(12)

Taking laplace inverse on both sides, we get,

$$y = c_1 \mathcal{L}^{-1} \left(\frac{s}{s^2 + 1} \right) + c_2 \mathcal{L}^{-1} \left(\frac{1}{s^2 + 1} \right)$$
 (13)

$$y = c_1 \cos x + c_2 \sin x \tag{14}$$

$$\implies y(x) = \sqrt{(c_1)^2 + (c_2)^2} \sin\left(x + \tan^{-1}\left(\frac{c_1}{c_2}\right)\right) \tag{15}$$

Computational Solution: Trapezoid Method

The given differential equation can be represented as

$$y'' + y = 0 \tag{16}$$

Let $y = y_1$ and $y' = y_2$, then,

$$\frac{dy_2}{dx} = -y_1 \text{ and } \frac{dy_1}{dx} = y_2 \tag{17}$$

$$\int_{y_{2,n}}^{y_{2,n+1}} dy_2 = \int_{x_n}^{x_{n+1}} -y_1 dx \tag{18}$$

$$\int_{y_{1,n}}^{y_{1,n+1}} dy_1 = \int_{x_n}^{x_{n+1}} y_2 dx \tag{19}$$

Discretizing the steps (Trapezoid rule),

$$y_{2,n+1} - y_{2,n} = -\frac{h}{2} \left(y_{1,n} + y_{1,n+1} \right) \tag{21}$$

$$y_{1,n+1} - y_{1,n} = \frac{h}{2} (y_{2,n} + y_{2,n+1})$$
 (22)

Solving for $y_{1,n+1}$ and $y_{2,n+1}$, we get,

$$y_{1,n+1} = y_{1,n} + \frac{h}{2} \left(2y_{2,n} - \frac{h}{2} \left(y_{1,n} + y_{1,n+1} \right) \right)$$
 (23)

(24)

(20)

The difference equations can be written as,

$$y_{1,n+1} = \frac{\left(4 - h^2\right) y_{1,n} + 4h y_{2,n}}{\left(4 + h^2\right)} \tag{25}$$

$$y_{2,n+1} = \frac{\left(4 - h^2\right) y_{2,n} - 4h y_{1,n}}{\left(4 + h^2\right)} \tag{26}$$

(27)

Iteratively plotting the above system taking intial conditions as

$$x_0 = 0$$
, $y_{1,0} = 0$, $y_{2,0} = 1$ (28)

we get the plot of the given differential equation.

Alternative Computational Solution: Bilinear transform

We have to apply laplace transformation on the given differential equation. From (11), we get,

$$Y(s) = \frac{sc_1 + c_2}{s^2 + 1} \tag{29}$$

$$Y(s) = \frac{sc_1 + c_2}{s^2 + 1} \tag{30}$$

Applying Bilinear transform, with T = h, we get,

$$s = \frac{2}{T} \frac{1 - z^{-1}}{1 + z^{-1}} = \frac{2}{h} \frac{1 - z^{-1}}{1 + z^{-1}}$$
(31)

$$\implies Y(z) = \frac{2hc_1(z^2 - 1) + c_2h^2(z + 1)^2}{(h^2 + 4)z^2 + 2(h^2 - 4)z + (h^2 + 4)}$$
(32)

$$\implies \left(z^2 + 2\frac{h^2 - 4}{h^2 + 4}z + 1\right)Y(z) = 2hc_1\left(z^2 - 1\right) + c_2h^2\left(z^2 + 2z + 1\right) \tag{33}$$

$$\implies z^2 Y(z) + 2 \frac{h^2 - 4}{h^2 + 4} z Y(z) + Y(z) = \left(2hc_1 + c_2 h^2\right) z^2 + \left(2h^2 c_2\right) z + \left(h^2 c_2 - 2hc_1\right)$$
(34)

$$\implies \left(z^2 + 2\frac{h^2 - 4}{h^2 + 4}z + 1\right)Y(z) = \left(2hc_1 + c_2h^2\right)z^2 + \left(2h^2c_2\right)z + \left(h^2c_2 - 2hc_1\right) \tag{35}$$

Some properties of one sided z transform,

$$Z(y[n+2]) = z^{2}Y(z) - y[1]z - y[0]$$
(36)

$$\mathcal{Z}(y[n+1]) = zY(z) - zy[0] \tag{37}$$

$$\mathcal{Z}(\delta[n]) = 1, z \neq 0 \tag{38}$$

$$\mathcal{Z}(y[n]) = Y(z) \implies \mathcal{Z}(y[n-n_0]) = z^{-n_0}Y(z) \tag{39}$$

By the time shift property (39),

$$\mathcal{Z}(\delta[n+2]) = z^2, z \neq 0 \tag{40}$$

$$\mathcal{Z}(\delta[n+1]) = z, z \neq 0 \tag{41}$$

Taking z inverse transform on both sides of equation (35),

$$hello$$
 (42)

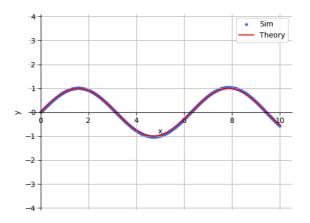


Fig. 0: Computational solution for y'' + y = 0