# Statistics MM2: Parameter estimation

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#### **Schedule**

- 1. Introduction to statistics
- 2. Parameter estimation
- 3. Confidence intervals
- 4. Hypothesis testing 1
- 5. Hypothesis testing 2
- 6. Regression
- 7. Workshop: wrap-up and exam problems



#### **Outline**

Recap on sampling

**Types of estimation** 

**Estimating the mean and variance** 

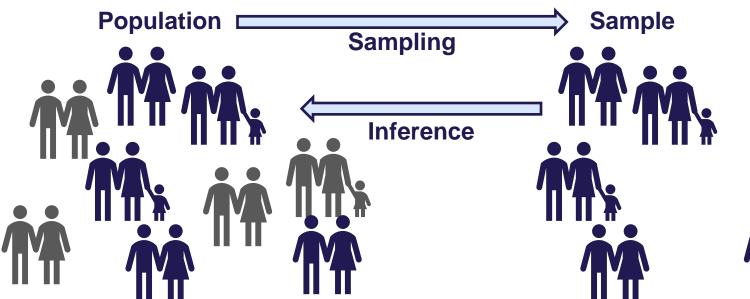
**Evaluating estimators** 

Maximum likelihood Estimation (MLE)

# Recap on sampling

### Sampling

If we cannot measure the whole population, we use a smaller sample

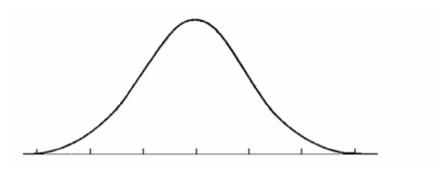


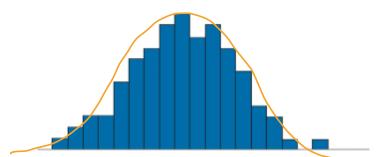




### How do we create a sample?

We randomly draw n values from the population Each value  $X_i$  is a random variable with distribution FWe use the sample to estimate some parameter of F (inference)







### Implications and assumptions during sampling

If we randomly draw n values from the population **And** each value  $X_i$  is a random variable with distribution F

Then a sufficiently large sample will look like the whole population

#### What does it mean looking like?

The parameters of the population are similar to the statistics

The parameters describe the population and the statistics describe the sample

- Mean
- Variance
- Quantiles



# **Types of estimation**

#### **Parametric estimation**

We observe a sample  $X_1, X_2, ..., X_n$ 

Each value  $X_i$  is a random variable with **known distribution** F with parameter  $\theta$  **The parameter**  $\theta$  **is a fixed value and not a RV** 

From the sample with n points, we create an estimate of  $\theta$ , denoted as

$$\hat{\theta}_n = h(X_1, X_2, \dots, X_n)$$

The estimate  $\hat{\theta}_n$  is our statistic derived from the sample data

Since  $\hat{\theta}_n$  depends on the sampled data, it is a RV

What are the properties of  $\hat{\theta}_n$ ?

We hope that the estimator  $\hat{\theta}_n$  is close to the real value of  $\theta$ 



### Non-parametric estimation

There are no assumptions on the parameters for distribution *F* 

We don't need to know F

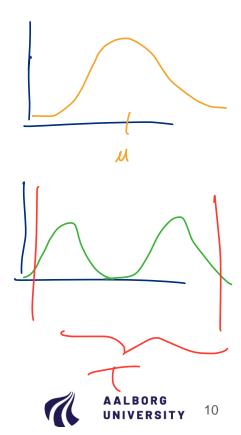
When compared to parametric estimation

Much more general

Much more difficult to do

#### **Example:**

Histograms and order statistics (quantiles) are non-parametric Can be used to show the shape of the distribution But don't give us any mathematical description of it



# Estimating the mean and variance

### Properties of the sample mean pt. 1

If  $X_1, X_2, ..., X_n$  are random variables, the **sample mean** is the random variable

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

Assuming the samples are drawn independently:

The expectation of the sample mean is

$$\mathbb{E}(\bar{X}_n) = \mu$$

The variance of the sample mean is  $var(\bar{X}_n) = \frac{\sigma^2}{n}$ Comes from the **central limit theorem** and the fact that the variance of each sample is  $var(X_i) = \sigma^2$ 

### Properties of the sample mean pt. 2

#### The law of large numbers

 $\bar{X}_n$  converges in probability to  $\mu = \mathbb{E}(X_i)$  as  $n \to \infty$ 

$$\bar{X}_n \stackrel{P}{\to} \mu = \mathbb{E}(X_i)$$

This means that, for any  $\epsilon > 0$ ,

$$\lim_{n\to\infty} P(|\bar{X}_n - \mu| > \epsilon) = 0$$

So,  $\bar{X}_n$  is close to  $\mu$  with high probability if the sample size is large

### Properties of the sample mean pt. 3

#### The central limit theorem

If n is large:

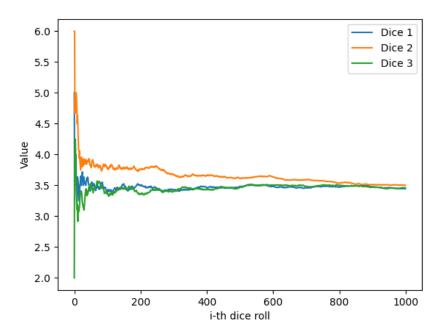
$$\sum_{i=1}^{n} X_{i} = X_{1} + X_{2} + \dots + X_{n} \approx N(n\mu, n\sigma^{2})$$

$$\bar{X}_{n} = \frac{1}{n} \sum_{i=1}^{n} X_{i} \approx N\left(\mu, \frac{\sigma^{2}}{n}\right) \qquad = \mathcal{N}\left(\frac{N}{n}\mu, \frac{N\sigma^{2}}{n^{2}}\right)$$

Recall that 
$$F(x; \mu, \sigma^2) = \Phi\left(\frac{x-\mu}{\sigma}\right)$$

### Dice example

We roll a dice i = 1, 2, ..., n times and compute the sample mean  $X_i$ 



### **Estimating the variance**

Sample variance

$$S_n^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X}_n)^2$$

The term n-1 is needed to have an unbiased estimate

$$\mathbb{E}[S_n^2] = \sigma^2$$

# **Evaluating estimators**

#### **Metrics to evaluate estimators**

An estimator should be as close as possible to the true value. This should happen as frequently as possible.

What does this mean?

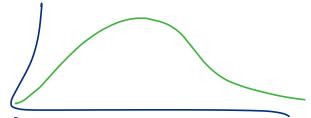
#### **Metrics for evaluation:**

■ Bias: measures accuracy

Variance: measures precision

Mean square error: measures both accuracy and precision

### **Bias**



#### Measure of how close the estimate is to the true value

Let  $\hat{\theta}_n = h(X_1, X_2, ..., X_n)$  be the estimator for parameter  $\theta$ 

#### The bias is defined as

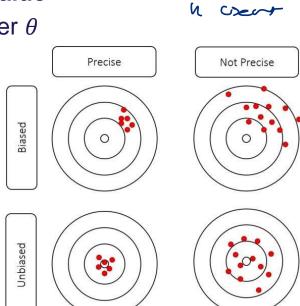
$$\operatorname{bias}(\hat{\theta}_n) = \mathbb{E}(\hat{\theta}_n) - \theta$$

#### **Unbiased estimator:**

An estimator with bias  $(\hat{\theta}_n) = 0$ 

This is what we hope for

There are tricks to correct the bias



#### Variance and standard error

#### Measure of how precise the estimator is for different samples

Let  $\hat{\theta}_n = h(X_1, X_2, ..., X_n)$  be the estimator for parameter  $\theta$ 

#### The variance is

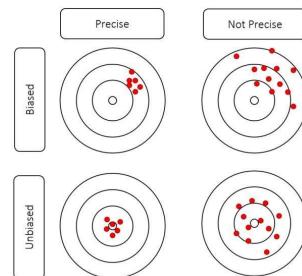
$$\operatorname{var}(\hat{\theta}_n) = \mathbb{E}\left[\left(\hat{\theta}_n - \mathbb{E}(\hat{\theta}_n)\right)^2\right]$$

#### The standard error is

$$\operatorname{se}(\hat{\theta}_n) = \sqrt{\operatorname{var}(\hat{\theta}_n)}$$

but  $se(\hat{\theta}_n)$  depends on F and might be unknown

### The estimated standard error is $\widehat{\operatorname{se}}(\widehat{\theta}_n)$



### Example: Point estimator for Bernoulli RVs pt. 1

Let  $X_1, X_2, ..., X_n \sim \text{Bernoulli}(p)$ . We don't know the real value of p We have to create an estimate for p, defined as

$$\hat{p}_n = \frac{1}{n} \sum_{i=1}^n X_i \subset \mathbf{X}_n$$

Then

$$\mathbb{E}(\hat{p}_n) = \mathbb{E}\left(\frac{1}{n}\sum_{i=1}^n X_i\right) = \frac{1}{n}\sum_{i=1}^n \mathbb{E}(X_i) = p$$

Is this estimator biased or not?

### Example: Point estimator for Bernoulli RVs pt. 2

The variance of a RV is  $var(X_i) = \mathbb{E}[(X_i - \mu_i)^2] = \mathbb{E}[X_i^2] - \mathbb{E}[X_i]^2$ 

$$\operatorname{var}\left(\sum_{i=1}^{n} a_i X_i + b\right) = \sum_{i=1}^{n} a_i^2 \operatorname{var}(X_i)$$

The **variance** for our estimator is

$$var(\hat{p}_n) = var\left(\frac{1}{n}\sum_{i=1}^n X_i\right) = \frac{1}{n^2}\sum_{i=1}^n var(X_i) = \frac{1}{n^2}\sum_{i=1}^n p(1-p) = \frac{p(1-p)}{n}$$

Then, the **estimated standard error** is  $\hat{se} = \sqrt{\text{var}(\hat{p}_n)} = \sqrt{p(1-p)/n}$ 



### The Mean Squared Error (MSE)

We define the Mean Squared Error (MSE) of an estimator as

$$MSE = \mathbb{E}[\hat{\theta}_n - \theta]^2 = bias^2(\hat{\theta}_n) + var(\hat{\theta}_n)$$

Combines the bias and variance

An estimator is consistent if  $\operatorname{bias}^2(\hat{\theta}_n) \to 0$  and  $\operatorname{var}(\hat{\theta}_n) \to 0$  as  $n \to \infty$ This means that  $\hat{\theta}_n \overset{P}{\to} \theta$ 

Is our estimator for parameter p of a Bernoulli RV, namely  $\hat{p}_n$ , consistent? Recall that  $\mathbb{E}(\hat{p}_n) = p$ , bias $(\hat{p}_n) = \mathbb{E}(\hat{p}_n) - p$ , and  $\text{var}(\hat{p}_n) = p(1-p)/n - p = 0$ 

### **Example**

Let  $X_1, X_2, ..., X_n$  be i.i.d. RVs with mean  $\mathbb{E}[X_i] = \theta$  and variance  $\text{var}(X_i) = \sigma^2$ Consider the following two estimators for  $\theta$ 

1. 
$$\hat{\theta}_1 = X_1$$

2. 
$$\hat{\theta}_n = \bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

Which one is a better estimator?

For 
$$\hat{\theta}_1 = X_1$$
: bias $(\hat{\theta}_1) = \mathbb{E}[X_1] - \theta = 0$  and var $(X_1) = \sigma^2$ 

For 
$$\hat{\theta}_n = \bar{X}_n$$
: bias $(\hat{\theta}_n) = \mathbb{E}[\bar{X}_n] - \theta = 0$  and  $var(\bar{X}_n) = \sigma^2/n$ 

Since 
$$var(\bar{X}_n) = \frac{\sigma^2}{n} \to 0$$
 as  $n \to \infty$ , the estimator  $\hat{\theta}_n = \bar{X}_n$  is consistent

The estimator  $\hat{\theta}_1 = X_1$  is not consistent



#### The bias-variance trade-off

Present in many cases in statistics and machine learning

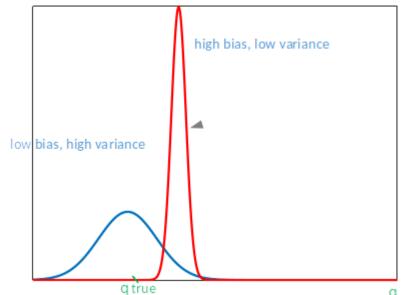
The variance of a parameter estimation can be decreased by increasing the bias

**Increased complexity** 

High accuracy but sensitive to variations

#### Reduced complexity

Low accuracy but resilient to variations



## **Maximum Likelihood Estimation (MLE)**

### **Maximum Likelihood Estimation (MLE)**

The most common method for parametric estimation

The **likelihood function for**  $X_1, X_2, ..., X_n$  i.i.d RVs with PDF/pmf  $f(x; \theta)$  is

$$\mathcal{L}_n(\theta) = \prod_{i=1}^n f(X_i; \theta)$$

Usually, we use the **log-likelihood function** is  $\ell_n(\theta) = \log \mathcal{L}_n(\theta)$ 

We treat the likelihood function as a function of parameter  $\theta$ 

**Maximum Likelihood Estimator (MLE)**  $\hat{\theta}_n$ : the value of  $\theta$  that maximizes  $\mathcal{L}_n(\theta)$ 

The MLE is consistent

#### MLE for discrete and continuous RVs

Suppose we observe the outcomes  $X_1 = x_1, X_2 = x_2, ..., X_n = x_n$ If  $X_1, X_2, ..., X_n$  are **discrete RVs**, the likelihood function is the joint pmf

$$\mathcal{L}_{n}(\theta) = \mathcal{L}(x_{1}, x_{2}, ..., x_{n}; \theta) = P_{X_{1}, X_{2}, ..., X_{n}}(x_{1}, x_{2}, ..., x_{n}; \theta)$$

If  $X_1, X_2, ..., X_n$  are **continuous RVs**, the likelihood function is the joint PDF

$$\mathcal{L}_n(\theta) = \mathcal{L}(x_1, x_2, ..., x_n; \theta) = f_{X_1, X_2, ..., X_n}(x_1, x_2, ..., x_n; \theta)$$

### Example: MLE for Bernoulli RV pt. 1

Let 
$$X_1, X_2, ..., X_n \sim \text{Bernoulli}(p)$$
 with pmf 
$$f(x; p) = p^{x}(1-p)^{1-x}, \qquad p^{x_1} \times p^{x_2} \times p^{x_3} \cdots p^{x_n} =$$

The likelihood function is 
$$\mathcal{L}_n(p) = \prod_{i=1}^n f(X_i; p) \neq \prod_{i=1}^n p^{X_i} (1-p)^{1-X_i}$$
 If we define  $X = \sum_{i=1}^n X_i$  we get the likelihood and log-likelihood functions: 
$$\mathcal{L}_n(p) = p^X(1-p)^{n-X}$$
 
$$\mathcal{L}_n(p) = \log(p^X(1-p)^{n-X}) = X \log p + (n-X) \log(1-p)$$

Linear 
$$\mathcal{L}_n(p) = p^X (1-p)^{n-X}$$

$$\ell_n(p) = \log(p^X (1-p)^{n-X}) = X \log p + (n-X) \log(1-p)$$

Which one should we work with?



### **Example: MLE for Bernoulli RV pt. 2**

How do we find the value of p that maximizes the likelihood  $\mathcal{L}_n(p)$  or  $\ell_n(p)$ ?

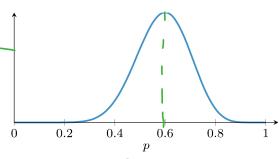
1. Take the derivative with respect to p and make it equal to 0

$$\frac{d\mathcal{L}_n(p)}{dp} = Xp^{X-1}(1-p)^{n-X} - (n-X)(1-p)^{n-X-1}p^X = 0$$

2. Solve for p

$$\frac{d\ell_n(p)}{dp} = \frac{X}{p} - \frac{n-X}{(1-p)} = 0$$

$$\widehat{\hat{p}_n} = \frac{X}{n} = \frac{1}{n} \sum_{i=1}^n X_i = \overline{X}_n$$



n = 20 and X = 12



There's a bag with 3 balls. Each ball is either red or blue.

We denote the number of blue balls as  $\theta$ , whose value can be 0, 1, 2, or 3.

We estimate  $\theta$  by grabbing and putting back a ball 4 times

This is a process of selection with replacement

Let  $X_1, X_2, X_3, X_4$  be the RVs of the color of the *i*-th ball

$$X_i = \begin{cases} 1, & \text{if the ball is blue} \\ 0, & \text{if the ball is red} \end{cases}$$

Then,  $X_i \sim \text{Bernoulli}\left(\frac{\theta}{3}\right)$ 

The outcomes are  $x_1 = 1$ ,  $x_2 = 0$ ,  $x_3 = 1$ ,  $x_4 = 1$ 

That is, 3 out of 4 of the balls are blue













1. For each possible value of  $\theta$ , find  $P_{X_1,X_2,X_3,X_4}$   $(1,0,1,1;\theta)$ 

$$P_{X_1,X_2,X_3,X_4}(1,0,1,1;\theta=0) = \prod_{i=1}^4 P(X_i = x_i; \theta=0) = 0 \times 1 \times 0 \times 0 = 0$$

$$P_{X_1,X_2,X_3,X_4}(1,0,1,1;\theta=1) = \prod_{i=1}^{4} P(X_i = x_i; \theta=1) = \frac{1}{3} \times \frac{2}{3} \times \frac{1}{3} \times \frac{1}{3} = \frac{2}{81} = 0.0247$$

$$P_{X_1, X_2, X_3, X_4}(1, 0, 1, 1; \theta = 2) = \prod_{i=1}^{4} P(X_i = x_i; \theta = 1) = \frac{2}{3} \times \frac{1}{3} \times \frac{2}{3} \times \frac{2}{3} = \frac{8}{81} = 0.0987$$

$$P_{X_1,X_2,X_3,X_4}$$
 (1, 0, 1, 1;  $\theta = 3$ ) = 1 × 0 × 1 × 1 = 0



2. Use the definition of MLE to estimate  $\theta$  with n experiments given  $p = \theta/3$  Previously, we defined  $\ell_n(p) = \log(p^X(1-p)^{n-X}) = X\log p + (n-X)\log(1-p)$ 

$$\ell_n(\theta) = \log\left(\left(\frac{\theta}{3}\right)^X \left(1 - \frac{\theta}{3}\right)^{n-X}\right) = X(\log \theta - \log 3) + (n - X)\log\left(1 - \frac{\theta}{3}\right)$$

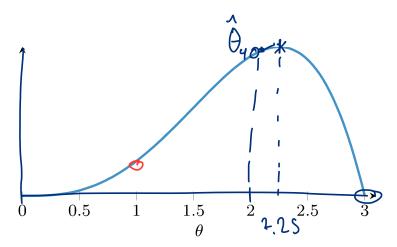
$$\frac{d\ell_n(\theta)}{d\theta} = \frac{X}{\theta} - \frac{n - X}{3\left(1 - \frac{\theta}{3}\right)} = 0$$

$$X(3 - \theta) = \theta(n - X) \Rightarrow 3X - \theta X = n\theta - \theta X \Rightarrow \theta = \frac{3X}{n} = 3\bar{X}_n$$



For n=4 and X=3 we have  $\bar{X}_4=3/4$  and the MLE becomes  $\hat{\theta}_4=3\bar{X}_4=3\times 3/4=9/4=2.25$ 

Since  $\hat{\theta}_n$  must be an integer, we take the closest integer value and  $\hat{\theta}_4 = 2$ 



# **Summary**

### **Summary**

Sampling is essential for estimation

In parametric estimation, we know the distribution but not the parameter

■ The estimator is a RV that takes a value based on the sample

In **non-parametric estimation**, we don't need to know the distribution

There can be an infinite number of estimators

We find the best ones using metrics: bias, variance, and MSE

If the MSE goes to 0, the estimator is **consistent** 

The Maximum Likelihood Estimator (MLE) is consistent



# **Appendix**

#### Useful derivative formulas and rules

$$\frac{da^x}{dx} = \log(a)a^x$$

$$\frac{d\log_a(x)}{dx} = \frac{1}{x\log(a)}$$

$$\frac{d\log(x)}{dx} = \frac{1}{x}$$

### Product rule: h(x) = f(x)g(x)h'(x) = f'(x)g(x) + f(x)g'(x)

**Quotient rule:** h(x) = f(x)/g(x)

$$h'(x) = \frac{f'(x)g(x) - f(x)g'(x)}{g(x)^2}$$

Chain rule: h(x) = f(g(x))

$$h'(x) = f'(g(x))g'(x)$$

### **Derivations for Bernoulli MLE (log-likelihood)**

$$\frac{d\ell_n(p)}{dp} = \frac{X}{p} + \frac{n-X}{(1-p)}(-1) = \frac{X}{p} - \frac{n-X}{(1-p)} = 0$$

$$\frac{X}{p} = \frac{n - X}{(1 - p)}$$

$$X(1-p) = p(n-X) \Rightarrow X - Xp = np - Xp$$

$$X = np \Rightarrow p = \hat{p}_n = \frac{X}{n} = \frac{1}{n} \sum_{i=1}^{n} X_i$$