Qualis: the Quality of Service Component for the Globus Metacomputing System

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1 Introduction

General computing over a widely distributed set of heterogeneous machines — typically called metacomput ing—offers definite advantages. In addition to allowing a single application to bring together different types of resources, such as specialized data sources, data bases, and visualization systems, it allows an application to acquire and utilize many different machines to attain a level of compute power that is not possible any other way. It may also be more cost-effective to aggregate several machines over a network on a per-need basis rather than acquire and maintain one large machine.

The performance of netacomputing systems, how ever, can be highly dependent on the available network bandwidth and latencies. While performance can be improved by designing applications to adapt to the available bandwidth and tolerate latencies, the notion of quality of service (QoS) for netacomputing is important. However, QoS in a netacomputing environment.

Service for CORBA Objects (QnO) [11] is an example of high-level QoS that augments the CORBA Interface Definition Language with a QoS Definition Language (QLL) that allows specification of QoS in terms of object behavior, e.g., nethod invocations per second. Very In large distributed computing enterprises, it has been recognized that end-to-end QoS requires that QoS be integrated within a general resource man a general resource.

Much work has been done on how to provide QoS in networks. The literature has investigated both connectionless [1] and connection-oriented [8] networks, resulting in an extremely large archive of results. Less thoroughly investigated, however, are the problems that arise in providing end-to-end QoS to large applications. The exception here, of course, is network-based multimedia, such as the popular MB one-based tools [10], in which it is paramount to assure that the required QoS can be provided from a source — typically a stream ing video or audio source —to one or more destina-

tions. The service model for these tools tends to be an isochronous bit rate with minimal delay jitter and low packet loss. We anticipate that netacomputing will need a substantially different service model for the non-visualization applications.

QoS specification and management can be implemented at different levels of abstraction. The Integrated Services Architecture, which includes the Reservation Protocol [2] (RSVP), serves as Qualis' basic mechanism for QoS signaling protocol and traffic management. This is an example of a low-level QoS mechanism that allows reservations to be made on a network for a flow between a sender and a receiver. Quality of Service for CORBA Objects (QuO) [11] is an example of high-level QoS that augments the CORBA Interface Definition Language with a QoS Definition Language (QL) that allows specification of QoS in terms of object behavior, e.g., method invocations per second.

been recognized that end-to-end QoS requires that QoS
be integrated within a general resource management project [4] which plans to support com
nand, control, communications, and intelligence (C ³I)
applications, in addition to multimedia applications.
The ERDoS project (End-to-End Resource Management for Distributed Systems) [3] is developing an infrastructure to map end-to-end, application-level QoS
specifications to middleware-, QS-, and network-level
QoS specifications; allocate and schedule computing,
communication and storage resources to applications;
and appropriately handle QoS violations.

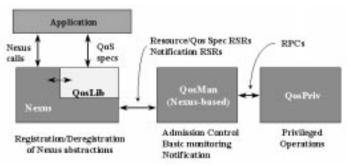
This position paper presents $Qu\ a\ l\ i\ s$, the quality of

service component for the Gl obus Metacomputing system [6]. We present the Qualis architecture, how it is integrated into the Gobus architecture, and howit addresses QoS in a netacomputing environment.

$\mathbf{2}$ The Qualis Architectur

A guiding principle in the implementation of QoS for Gobus was not to build a single, unique QoS tool, but to build an infrastructure where lower-level QoS mechanisms can be integrated and debugged, thereby allow ing higher-level QoS tools and functionality to be built and evaluated. Since Nexus [7] is the communication and process control workhorse of Gobus, it is clear that implementing QoS for G obus meant implementing QoS for Nexus. Hence, we chose to implement QoS for relevant Ne xus a b s t r a c t i o n s . The abstractions we chast engisters a process, thread, or bound start-(1) processes, (2) threads, (3) memory, and (4) communi cation start points and endpoints which are used for asynchronous Remote Service Reques are the QoS-able objects of Qualis. While Nexus does not actually have a separate abstraction for $me \ mo \ r \ y$, it is not inconsistent with the Nexus model and will be useful since it will allow a coordination of buffer management along with other forms of QoS services.

For Nexus, a process involves an address space on some processor that could be a uniprocessor, a sharedmenory machine, or one node in a distributed-menory machine. Threads lives within an address space and synchronize in the usual manner with mutexs and condition variables. Communication via RSRs is done between a start point that is bound to an endpoint. Acontext may have an arbitrary number of start/endpoints. Start points (but not endpoints) can be freely passed One or more threaded or nonamong processes. threaded h a n dl e r s are associated with an endpoint. An RSR is initiated with a startpoint, handler id, and The data buffer is then delivered to a data buffer. the context with bound endpoint and passed to the handler. RSRs are supported by a variety of p r o t o $c\ o\ l\ mo\ d\ u\ l\ e\ s\ that\ utilize,\ for\ example,\ TCP\ (Transm one on the control for\ processes\ can be done on the control for\ processes\ can be done on the control for\ processes\ can be done on the control for\ processes\ can be done$ sion Control Protocol), UDP (User Datagram Protocol), MPL (the IBMMessage Passing Layer), NX (the Intel message-passing library), or shared-memory. single context can use multiple modules depending on which one is best for the target endpoint. This approach can be used to support traditional nessagepassing, synchronous remote procedure call, distributed shared memory, streams, multicast, and other commu-



Egure 1: The Qualis Architecture.

nication and control models.

The Qualis architecture is shown in Figure 1. point/endpoint with Qos Li b whenever they are created as part of normal operation. They are deregistered then the are descroved. Nexus applications can specify the QoS and call back handler associated with QoSable objects. When this association is made, Qos Lib passes the information to $Qo \ s \ Ma \ n$ which does local admission control and monitoring. If the relevant QoS næchanismrequires root privilege, Qos Man will send an RPC to Qos Pr i v which does the privileged operation. (Modularizing privileged operations and using RPC (rather than Nexus remote service requests) was done so that only a relatively small amount of code using a more familiar (and perhaps more trusted) communi cati on nechani s mwould be needed, thereby mitigating any need for verification by systemadministrators.) If QosMan detects a QoS violation, an RSR is sent to the application's callback handler.

Qualis is currently integrated with two low-level QoS nechanisms: the POSIX Real-time Extensions [9] and RSVP [2]. The POSIX Real-time Extensions are used to control the priority of processes and threads and to lock-down pages of memory. Currently process and thread QoS is simply specified as a priority by the local by comparing the current load with the anticipated load of another process with the requested priority. Admission control for threads is done in a similar manner but can be complicated by the OS's thread scheduling model.

QoS for startpoints/endpoints is currently based only on RSVP. While RSVP supports both TCP and UP, including multicast, only the Nexus TOP pro-

tocol module has been integrated into Qualis at this tine. After the start point has been bound to the endpoint, the application has specified the RSVP Rs p e c and $Ts \ p \ e \ c$, and the socket connection has been made, then the RSVP signaling protocol is initiated. If the bandwidth is available, RSVP returns a reservation confirmation. The Aternative Queuing (ALTQ) Class-Based Queuing package [5] polices traffic and provides static admission control. We currently have no neasurement based admission control (MBAC) that would provide better utilization of the link.

Whave built a wide area test bed over CAIRN (Collaborative Advanced Interagency Research Network) using Integrated Services capable routers and hosts. The routers were constructed using IBMPC compatible machines running FreeBSD2.2.X with a quadfast ethernet network adapter and the AIIQpackage which utilizes the packet scheduler developed at LBNL, UCL, and Sun Mcrosystems. Our end hosts are Sun Utra 1 workstations running the Sun Integrated Services package. A network of two routers and three end hosts are located at both ISI and ANL and connected by the CAIRN research network.

This basic infrastructure allows a number of issues to be investigated. Qo S mapping from higher level speci fications that are related to application behavior, such as method invocations per second, to lower level systemQoS primitives is important but difficult. Any QoS nechanismentails some overhead and, hence, implies some minimum $g \ r \ a \ n \ u \ l \ a \ r \ i \ t \ y$ that can realize a net gain [7] I. Foster, C. Kesselman, and S. Thecke. The Nexus necessary to specify QoS prior to creation rather than after. More effective monitoring and policing mechamisms need to be in place such that applications can adapt when necessary in a timely fashion. True end-toend, application-level QoS will require taking network, thread, process and application behavior into account together as a whole. Better overall performance may be possible if multiple QosMans negotiate among them selves to maintain global or distributed QoS properties.

Using the wide area testbed described above, the Gobus/Qualis projects are currently performing a number of experiments including basic RSVP microbenchmarks and instrumented applications to evaluate the performance and overhead of these QoS mechamisms. We are also investigating the design of QoSaware resource brokers and schedulers that interact with the Metacomputing Directory Service and other Gobus services.

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