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heap insertion algorithm

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The heap insertion algorithm inserts a new value into a heap, maintaining the heap property. Let H be a heap, storing n elements over which the http://planetmath.org/Relationrelation \leq imposes a total ordering. Insertion of a value x consists of initially adding x to the bottom of the tree, and then sifting it upwards until the heap property is regained.

Sifting consists of comparing x to its parent y. If $x \leq y$ holds, then the heap property is violated. If this is the case, x and y are swapped and the operation is repeated for the new parent of x.

Since H is a balanced binary tree, it has a maximum depth of $\lceil \log_2 n \rceil + 1$. Since the maximum number of times that the sift operation can occur is constrained by the depth of the tree, the worst case time complexity for heap insertion is $\mathcal{O}(\log n)$. This means that a heap can be built from scratch to hold a multiset of n values in $\mathcal{O}(n \log n)$ time.

What follows is the pseudocode for implementing a heap insertion. For the given pseudocode, we presume that the heap is actually represented implicitly in an array (see the binary tree entry for details).

```
HeapInsert(H, n, \preceq, x)
```

Input: A heap (H, \preceq) (represented as an array) containing n values and a new value x to be inse**Output**: H and n, with x inserted and the heap property preserved.

Procedure:

```
\begin{split} n \leftarrow n+1 \\ H[n] \leftarrow x \\ child \leftarrow n \\ parent \leftarrow n \text{ div } 2 \\ \text{while } parent \geq 1 \text{ do} \\ \text{ if } H[child] \preceq H[parent] \\ \text{ then } child \leftarrow parent \\ parent \leftarrow parent \text{ div } 2 \\ \text{ else } parent \leftarrow 0 \\ \text{ fi} \\ \text{od} \end{split}
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