## Brief summary on Previous Lecture

- For a two-class problem, the optimum LDA solution or SLP initialization or *Fisher criterion* can be obtained by:

$$\mathbf{w} = \underset{\mathbf{w}}{\operatorname{arg\,max}} \left( \frac{\mathbf{w} \mathbf{S}_b \mathbf{w}^T}{\mathbf{w} \mathbf{S}_w \mathbf{w}^T} \right) = \mathbf{\Sigma}^{-1} \left( \mathbf{\mu}_1 - \mathbf{\mu}_2 \right) \text{ and SLP } y = \varphi \left( \mathbf{w}^T \left( \mathbf{x} - \mathbf{b}_0 \right) \right).$$

- In BP learning algorithm, weight updates are "local":

For output nodes

$$w_{k,j}(t+1) = w_{k,j}(t) + \eta \Delta_k(t) z_j(t)$$

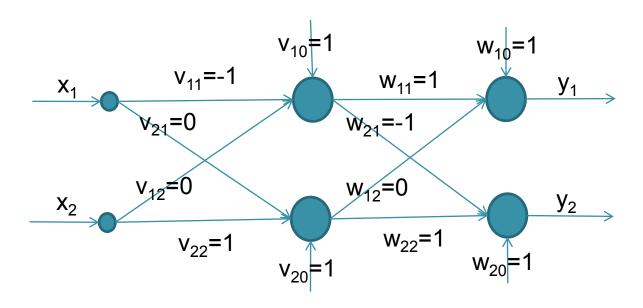
$$= w_{k,j}(t) + \eta \varphi'(a_k(t)) (d_k(t) - y_k(t)) z_j(t)$$

For hidden nodes

$$v_{j,i}(t+1) = v_{j,i}(t) + \eta \delta_j(t) x_i(t)$$

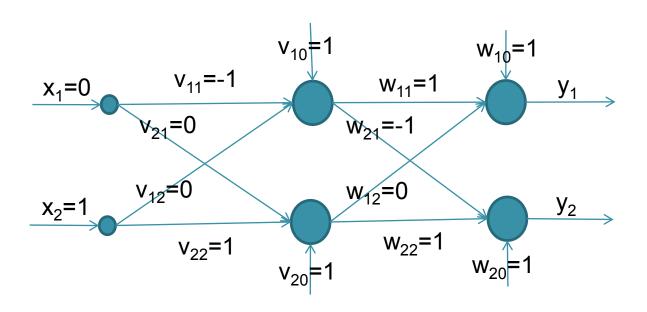
$$= v_{j,i}(t) + \eta \varphi'(u_j(t)) \sum_{k=1}^{m2} w_{k,j} \Delta_k(t) x_i(t)$$

- Use identity activation function  $\varphi(a) = a$ , for illustration
- Learning rate  $\eta$ =0.1
- Consider input [0 1] with target output [1 0]



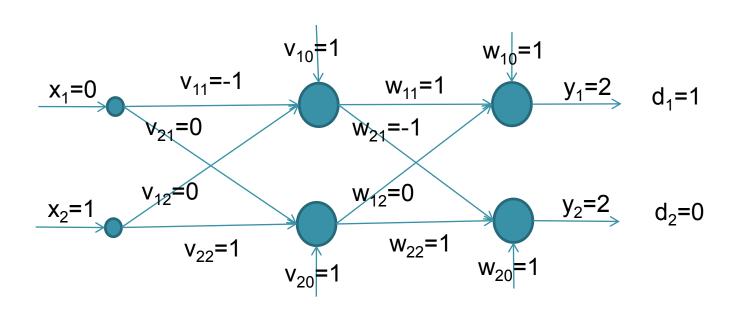
- Forward pass:

$$u_1 = x_1 v_{11} + x_2 v_{12} + v_{10} = 0 \cdot -1 + 1 \cdot 0 + 1 = 1,$$
  $z_1 = u_1 = 1$   
 $u_2 = x_1 v_{21} + x_2 v_{22} + v_{20} = 0 \cdot 0 + 1 \cdot 2 + 1 = 2,$   $z_2 = u_2 = 2$ 



#### - Forward pass:

$$a_1 = z_1 w_{11} + z_2 w_{12} + w_{10} = 1 \cdot 1 + 2 \cdot 0 + 1 = 2,$$
  $y_1 = a_1 = 2$   
 $a_2 = z_1 w_{21} + z_2 w_{22} + w_{20} = 1 \cdot -1 + 2 \cdot 1 + 1 = 2,$   $y_2 = a_2 = 2$ 



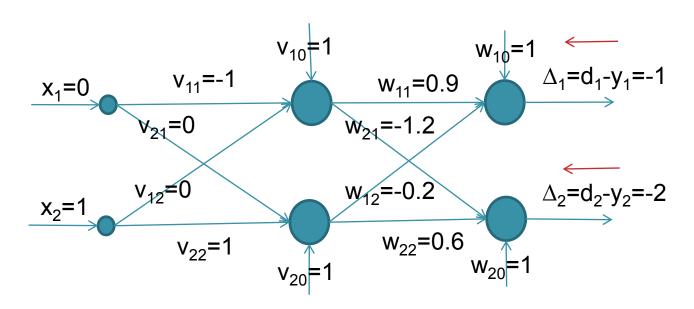
- Backward pass (output-to-hidden):

$$w_{1,1}(t+1) = w_{1,1}(t) + \eta \Delta_1(t) z_1(t) = 1 + 0.1 \cdot -1 \cdot 1 = 0.9$$

$$w_{2,1}(t+1) = w_{2,1}(t) + \eta \Delta_2(t) z_1(t) = -1 + 0.1 \cdot -2 \cdot 1 = -1.2$$

$$w_{1,2}(t+1) = w_{1,2}(t) + \eta \Delta_1(t) z_2(t) = 0 + 0.1 \cdot -1 \cdot 2 = -0.2$$

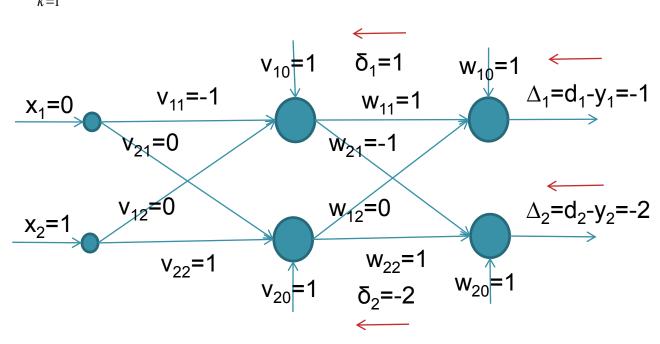
$$w_{2,2}(t+1) = w_{2,2}(t) + \eta \Delta_2(t) z_2(t) = 1 + 0.1 \cdot -2 \cdot 2 = 0.6$$



- Backward pass (hidden-to-input):

$$\delta_1 = \sum_{k=1}^{2} w_{k,1} \Delta_k = w_{1,1} \Delta_1 + w_{2,1} \Delta_2 = 1 \cdot -1 + -1 \cdot -2 = 1$$

$$\delta_2 = \sum_{k=1}^2 w_{k,2} \Delta_k = w_{1,2} \Delta_1 + w_{2,2} \Delta_2 = 0 \cdot -1 + 1 \cdot -2 = -2$$



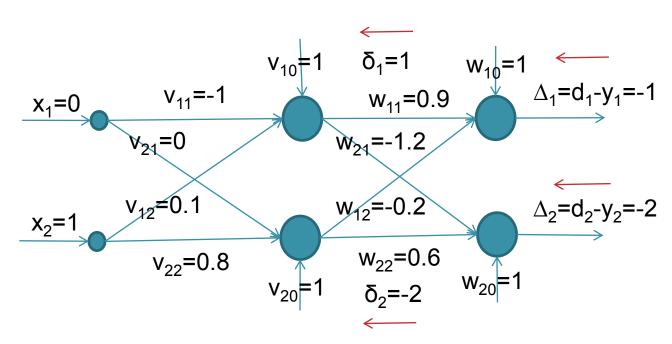
- Backward pass (hidden-to-input):

$$v_{1,1}(t+1) = v_{1,1}(t) + \eta \delta_1(t) x_1(t) = -1 + 0.1 \cdot 1 \cdot 0 = -1$$

$$v_{2,1}(t+1) = v_{2,1}(t) + \eta \delta_2(t) x_1(t) = 0 + 0.1 \cdot -2 \cdot 0 = 0$$

$$v_{1,2}(t+1) = v_{1,2}(t) + \eta \delta_1(t) x_2(t) = 0 + 0.1 \cdot 1 \cdot 1 = 0.1$$

$$v_{2,2}(t+1) = v_{2,2}(t) + \eta \delta_2(t) x_2(t) = 1 + 0.1 \cdot -2 \cdot 1 = 0.8$$



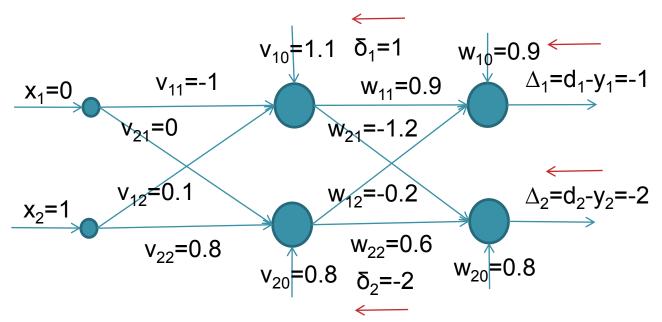
- Remark: the weights multiplied by the zero input are unchanged as they do not contribute to the error (and output signal).

$$v_{1,0}(t+1) = v_{1,0}(t) + \eta \delta_1(t) x_0(t) = 1 + 0.1 \cdot 1 \cdot 1 = 1.1$$

$$v_{2,0}(t+1) = v_{2,0}(t) + \eta \delta_2(t) x_0(t) = 1 + 0.1 \cdot -2 \cdot 1 = 0.8$$

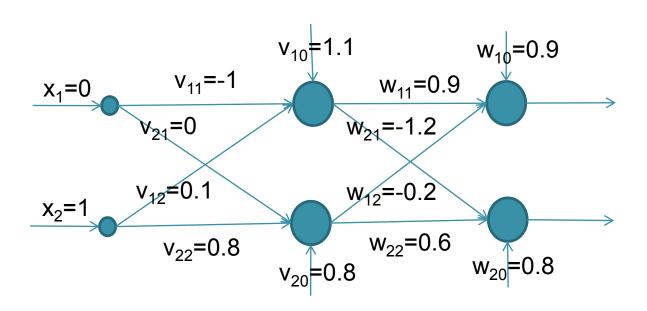
$$w_{1,0}(t+1) = w_{1,0}(t) + \eta \Delta_1(t) z_0(t) = 1 + 0.1 \cdot -1 \cdot 1 = 0.9$$

$$w_{2,0}(t+1) = w_{2,0}(t) + \eta \Delta_2(t) z_0(t) = 1 + 0.1 \cdot -2 \cdot 1 = 0.8$$



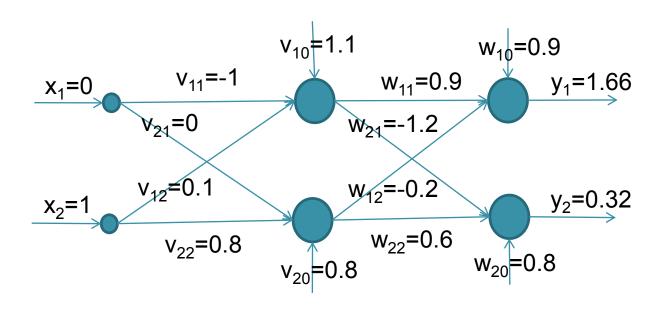
- Go forward again (normally use a new input):

$$u_1 = x_1 v_{11} + x_2 v_{12} + v_{10} = 0 \cdot -1 + 1 \cdot 0.1 + 1.1 = 1.2,$$
  $z_1 = u_1 = 1.2$   
 $u_2 = x_1 v_{21} + x_2 v_{22} + v_{20} = 0 \cdot 0 + 1 \cdot 0.8 + 0.8 = 1.6,$   $z_2 = u_2 = 1.6$ 



- Forward pass:

$$a_1 = z_1 w_{11} + z_2 w_{12} + w_{10} = 1.2 \cdot 0.9 + 1.6 \cdot -0.2 + 0.9 = 1.66, \quad y_1 = a_1 = 1.66$$
  
 $a_2 = z_1 w_{21} + z_2 w_{22} + w_{20} = 1.2 \cdot -1.2 + 1.6 \cdot 0.6 + 0.8 = 0.32, \quad y_2 = a_2 = 0.32$ 



- Remark: Outputs now are closer to target value [1 0].

## Advantages and Open Issues MLP

- Advantages:
  - \* Widely applicable (including regression for quantitative traits)
  - \* Provide posterior Bayes confidence
  - \* Insensitive to mislabeling and "brain damage"
- Open problems:
  - \* Nature of "black box" and model complexity
  - \* Local optima (non-convex, random initialization, learning rate)
  - \* Overfit (generalization performance, model selection #s)
- Remark:
  - \* Input range normalization
  - \* weight pruning (sparse solution, L<sub>1</sub> norm constraint)

# Interpretations of MLP

Alternative interpretations of hidden layer/nodes?

autoencoder

- \* 'Local' binary Bayesian classifier (approximation a posterior)
- \* 'Local' decision boundary
- \* Space projection/transform (feature extraction)

\* What would happen if m1 < m0/m2?

