

# Machine Learning: Assignment 7

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### 1 Problem 1

The Lagrangian is given by:  $L(x_1, x_2, \alpha) = -(x_1 + x_2) + \alpha(x_1^2 + x_2^2 - 1)$

The partial derivatives of L w.r.t.  $x_1, x_2$  are:

$$\frac{\partial L}{\partial x_1} = -1 + 2\alpha x_1 \quad \text{and} \quad \frac{\partial L}{\partial x_2} = -1 + 2\alpha x_2$$

Hence, the optimal values of  $x_1, x_2$  is at  $\frac{1}{2\alpha}$ . Replacing this value in the Lagrangian, and then finding the maximum.

$$L(x_1^*, x_2^*, \alpha) = -\left[\frac{1}{2\alpha} + \frac{1}{2\alpha}\right] + \alpha\left[\frac{1}{4\alpha^2} + \frac{1}{4\alpha^2} - 1\right] \Rightarrow L(\alpha) = \alpha - \frac{1}{2\alpha}$$

Now the derivative of L w.r.t.  $\alpha$  is  $\nabla_{\alpha} L = -1 + \frac{1}{2\alpha^2}$

Equating  $\nabla_{\alpha} L$  to 0, we have  $\alpha^* = \frac{1}{\sqrt{2}}$

As  $x_1, x_2 = \frac{1}{2\alpha}$ . Therefore,  $f_0$  reaches optimal at  $x_1^* = \frac{1}{\sqrt{2}}$  and  $x_2^* = \frac{1}{\sqrt{2}}$

And the optimal value of  $f_0$  is  $-\sqrt{2}$

### 2 Problem 2

The comparison of SVM and Perceptron method is:

- Both Perceptron and SVM try to find a hyperplane that will linearly separate the data points. Perceptron method is a generalized method of SVM.
- Perceptron finds the hyperplane with minimal misclassified points that separates the data points without considering the distance between them. SVM tries to find a hyperplane that maximizes the distance (margin) between the data points or the support vectors.
- Perceptron assumes that the data set is linearly separable. However, SVM uses a kernel function for the same.

### 3 Problem 3

To show that the duality gap is 0 in an SVM, we have to show that Slater's condition holds.

Now, the SVM function is:

$$\begin{aligned} \text{minimize} \quad & f_0(w, b) = \frac{1}{2} w^T w \\ \text{subject to} \quad & f_1(w, b) = y_i(w^T x_i + b) - 1 \geq 0 \text{ for } i = 1, \dots, N \end{aligned}$$

We can rewrite  $f_1$  as

$$-y_i(w^T x_i + b) + 1 \leq 0 \Rightarrow -y_i w^T x_i - y_i b + 1 \leq 0$$

This is an affine function in two variables  $w, b$  and a constant 1.

Hence, Slater's 2nd condition is satisfied. Therefore Duality gap is 0.

### 4 Problem 4

a)

The dual function is:  $g(\alpha) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N y_i y_j \alpha_i \alpha_j x_i^T x_j$

Here, each  $x_i$  is also a vector. To write it in the form of a quadratic function, we can write Q as:

$$Q = - \begin{bmatrix} y_1 y_1 x_1^T x_1 & y_1 y_2 x_1^T x_2 & \cdots & y_1 y_N x_1^T x_N \\ y_2 y_1 x_2^T x_1 & y_2 y_2 x_2^T x_2 & \cdots & y_2 y_N x_2^T x_N \\ \vdots & \vdots & \ddots & \vdots \\ y_N y_1 x_N^T x_1 & y_N y_2 x_N^T x_2 & \cdots & y_N y_N x_N^T x_N \end{bmatrix}$$

$$Q = - \begin{bmatrix} y_1 y_1 & y_1 y_2 & \cdots & y_1 y_N \\ y_2 y_1 & y_2 y_2 & \cdots & y_2 y_N \\ \vdots & \vdots & \ddots & \vdots \\ y_N y_1 & y_N y_2 & \cdots & y_N y_N \end{bmatrix} \odot \begin{bmatrix} x_1^T x_1 & x_1^T x_2 & \cdots & x_1^T x_N \\ x_2^T x_1 & x_2^T x_2 & \cdots & x_2^T x_N \\ \vdots & \vdots & \ddots & \vdots \\ x_N^T x_1 & x_N^T x_2 & \cdots & x_N^T x_N \end{bmatrix}$$

We can take Y to be a  $N \times 1$  vector of  $y_1, y_2, \dots, y_N$  values.

Similarly, we can take X to be  $1 \times N$  vector of vectors with  $x_1, x_2, \dots, x_N$  as values.

Then, Q can be written as:  $Q = -(YY^T) \odot (X^T X)$

b)

Now, Q is negative semi-definite as  $Q = -(YY^T) \odot (X^T X)$ . Clearly,  $(YY^T)$  and  $(X^T X)$  are squared positive values. Hence, the negative sign in front of it makes Q a symmetric matrix with negative values which means it is negative semi-definite.

c)

This is required as the objective is to maximize the dual function  $g(\alpha)$  whose solution is equal to the minimum of the primal problem. Being negative semi-definite, it ensures that there is only one global maximum of the dual. Hence, one global minimum of the primal.

# Programming assignment 7: SVM

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline

from sklearn.datasets import make_blobs

from cvxopt import matrix, solvers
```

## Your task

In this sheet we will implement a simple binary SVM classifier.

We will use **CVXOPT** <http://cvxopt.org/> (<http://cvxopt.org/>) - a Python library for convex optimization. If you use Anaconda, you can install it using

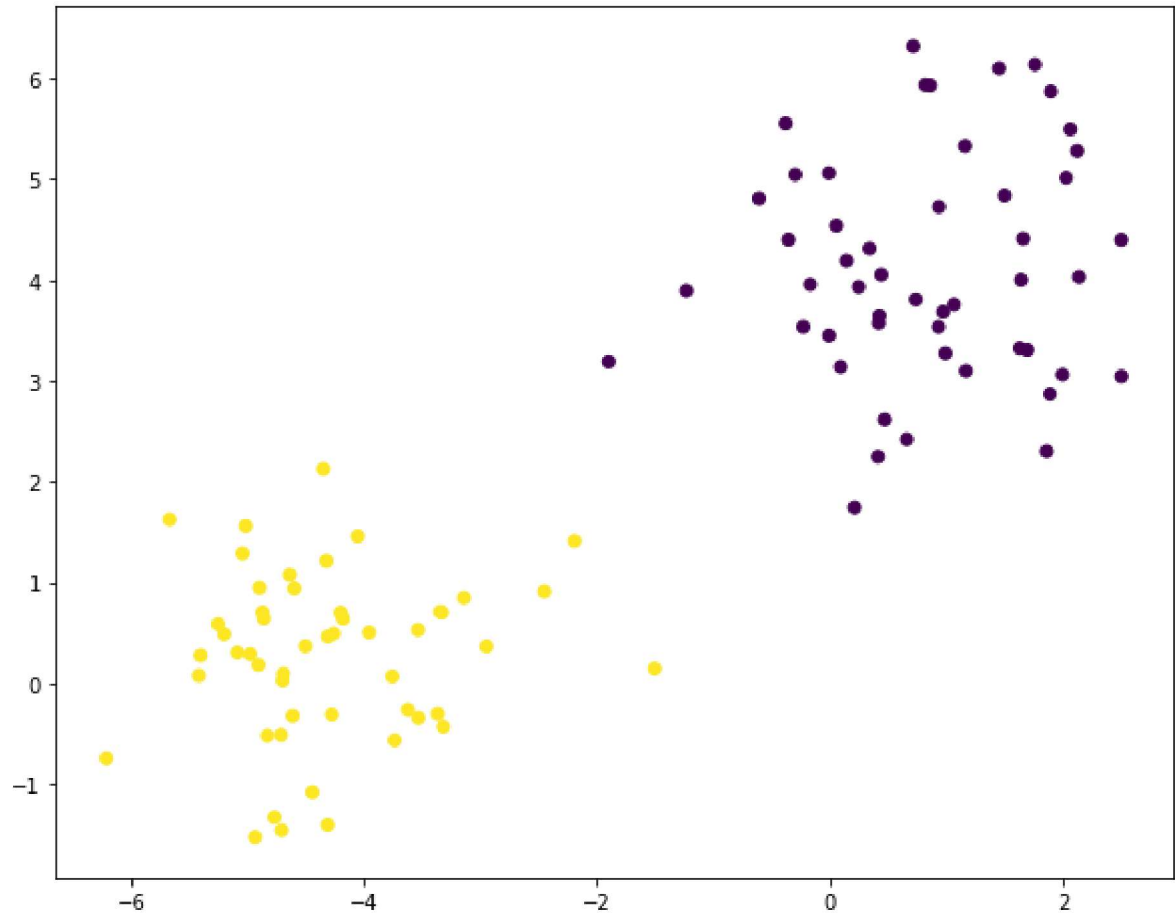
```
conda install cvxopt
```

As usual, your task is to fill out the missing code, run the notebook, convert it to PDF and attach it you your HW solution.

## Generate and visualize the data

```
In [2]: N = 100 # number of samples
D = 2 # number of dimensions
C = 2 # number of classes
seed = 3 # for reproducible experiments

X, y = make_blobs(n_samples=N, n_features=D, centers=2, random_state=seed)
y[y == 0] = -1 # it is more convenient to have {-1, 1} as class labels (instead of {0, 1})
y = y.astype(np.float)
plt.figure(figsize=[10, 8])
plt.scatter(X[:, 0], X[:, 1], c=y)
plt.show()
```



## Task 1: Solving the SVM dual problem

Remember, that the SVM dual problem can be formulated as a Quadratic programming (QP) problem. We will solve it using a QP solver from the CVXOPT library.

The general form of a QP is

$$\min_{\mathbf{x}} \frac{1}{2} \mathbf{x}^T \mathbf{P} \mathbf{x} + \mathbf{q}^T \mathbf{x}$$

$$\text{subject to } \mathbf{G} \mathbf{x} \preceq \mathbf{h}$$

$$\text{and } \mathbf{A} \mathbf{x} = \mathbf{b}$$

where  $\preceq$  denotes "elementwise less than or equal to".

**Your task** is to formulate the SVM dual problems as a QP and solve it using CVXOPT, i.e. specify the matrices  $\mathbf{P}$ ,  $\mathbf{G}$ ,  $\mathbf{A}$  and vectors  $\mathbf{q}$ ,  $\mathbf{h}$ ,  $\mathbf{b}$ .

```

In [3]: def solve_dual_svm(X, y):
        """Solve the dual formulation of the SVM problem.

        Parameters
        -----
        X : array, shape [N, D]
            Input features.
        y : array, shape [N]
            Binary class labels (in {-1, 1} format).

        Returns
        -----
        alphas : array, shape [N]
            Solution of the dual problem.
        """
        # TODO

        # These variables have to be of type cvxopt.matrix
        N, D = X.shape

        # Obtaining the kernel

        K = y[:, None] * X

        # Solving the dual problem for SVM

        K = np.dot(K, K.T)
        P = matrix(K)
        q = matrix(-np.ones((N, 1)))
        G = matrix(-np.eye(N))
        h = matrix(np.zeros(N))
        A = matrix(y.reshape(1, -1))
        b = matrix(np.zeros(1))
        solvers.options['show_progress'] = False
        sol = solvers.qp(P, q, G, h, A, b)
        alphas = np.array(sol['x'])

        return alphas

```

## Task 2: Recovering the weights and the bias

```
In [4]: def compute_weights_and_bias(alpha, X, y):  
        """Recover the weights w and the bias b using the dual solution alpha.  
  
        Parameters  
        -----  
        alpha : array, shape [N]  
            Solution of the dual problem.  
        X : array, shape [N, D]  
            Input features.  
        y : array, shape [N]  
            Binary class labels (in {-1, 1} format).  
  
        Returns  
        -----  
        w : array, shape [D]  
            Weight vector.  
        b : float  
            Bias term.  
        """  
  
        # Fit svm classifier  
        alphas = solve_dual_svm(X, y)  
  
        # Computation of weights  
        w = np.sum(alphas * y[:, None] * X, axis = 0)  
  
        # Computation of bias  
        cond = (alphas > 1e-4).reshape(-1)  
        b = y[cond] - np.dot(X[cond], w)  
        b = b[1]  
  
        return w, b
```

**Visualize the result (nothing to do here)**

```

In [5]: def plot_data_with_hyperplane_and_support_vectors(X, y, alpha, w, b):
        """Plot the data as a scatter plot together with the separating hyperplane.

        Parameters
        -----
        X : array, shape [N, D]
            Input features.
        y : array, shape [N]
            Binary class labels (in {-1, 1} format).
        alpha : array, shape [N]
            Solution of the dual problem.
        w : array, shape [D]
            Weight vector.
        b : float
            Bias term.
        """
        plt.figure(figsize=[10, 8])
        # Plot the hyperplane
        slope = -w[0] / w[1]
        intercept = -b / w[1]
        x = np.linspace(X[:, 0].min(), X[:, 0].max())
        plt.plot(x, x * slope + intercept, 'k-', label='decision boundary')
        # Plot all the datapoints
        plt.scatter(X[:, 0], X[:, 1], c=y)
        # Mark the support vectors
        support_vecs = (alpha > 1e-4).reshape(-1)
        plt.scatter(X[support_vecs, 0], X[support_vecs, 1], c=y[support_vecs], s=250, marker='*', label='support vectors')
        plt.xlabel('$x_1$')
        plt.ylabel('$x_2$')
        plt.legend(loc='upper left')

```

The reference solution is

```

w = array([[ -0.69192638],
           [-1.00973312]])

```

```

b = 0.907667782

```

Indices of the support vectors are

```

[38, 47, 92]

```



```
In [6]: alpha = solve_dual_svm(X, y)
w, b = compute_weights_and_bias(alpha, X, y)
plot_data_with_hyperplane_and_support_vectors(X, y, alpha, w, b)
plt.show()
```

