

Machine Learning: Assignment 10

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Solution1: Assuming that the result holds for M dimensionality. The M+1 Dimensional subspace is governed by M principle eigen vectors and additional M+1 eigen vector that needs to be orthogonal to the previous $(u_1, u_2 \dots u_m)$. We apply lagrangian multiplier to constrain this. We know that by variance formula, that variance for M+1 = $u_{M+1}^T S u_{M+1}$ Applying lagrangian multiplier, we get the following function to maximise:

$$u_{M+1}^T S u_{M+1} + \lambda_{M+1} (1 - u_{M+1}^T u_{M+1}) + \sum_{i=1}^M \eta_i u_i^T u_{M+1}$$

Taking a derivative of above function wrt u_{M+1} we get:

$$2S u_{M+1} - 2\lambda_{M+1} u_{M+1} + \sum_{i=1}^M \eta_i u_i$$

Simplifying this by multiplying by u_j^T on both sides, we see that $\eta=0$ for j between 1,..M. Therefore, we obtain:

$$S u_{M+1} = \lambda_{M+1} u_{M+1}$$

Clearly, u_{M+1} is an eigen vector of S with eigen value λ_{M+1} . Thus the variance is maximised by selecting eigen vector u_{M+1} with largest eigen value λ_{M+1} .

Solution2: The log-likelihood function is given by:

$$L(\mu, W, \Phi) = -\frac{ND}{2} \ln(2\pi) - \frac{N}{2} \ln |W W^T + \Phi| - \frac{1}{2} \sum_{n=1}^N (x_n - \mu)^T (W W^T + \Phi)^{-1} (x_n - \mu)$$

Now the log likelihood function for the transformed data can be given as:

$$L_A(\mu, W, \Phi) = -\frac{ND}{2} \ln(2\pi) - \frac{N}{2} \ln |W W^T + \Phi| - \frac{1}{2} \sum_{n=1}^N (A x_n - \mu)^T (W W^T + \Phi)^{-1} (A x_n - \mu)$$

Solving for μ :

$$\mu_A = \frac{1}{N} \sum_{n=1}^N A x_n = A x' = A \mu$$

Substituting this back in the log-likelihood function and also the values for Φ_A and W_A , we get:

$$L_A(\mu_A, W_A, \Phi_A) = -\frac{ND}{2} \ln(2\pi) - \frac{N}{2} \ln |W_A W_A^T + \Phi_A| - \frac{1}{2} \sum_{n=1}^N (x_n - \mu_A)^T (W_A W_A^T + \Phi_A)^{-1} (x_n - \mu_A) - N \ln |A|$$

This looks exactly like the log-likelihood function except for the last term.

Solution3: We can map Leslie's choices [0,3,0,0,4] into concept space by multiplying it by the 5x5 V matrix, getting the form [1.74,2.84]. Multiplying this by V^T , we get [1.0092,1.0092,1.0092,2.0164,2.0164] which is useful to gauge how Leslie likes the other movies.

Programming assignment 10: Dimensionality Reduction

```
In [1]: import numpy as np
import matplotlib.pyplot as plt

%matplotlib inline
```

PCA Task

Given the data in the matrix X your tasks is to:

- Calculate the covariance matrix Σ .
- Calculate eigenvalues and eigenvectors of Σ .
- Plot the original data X and the eigenvectors to a single diagram. What do you observe? Which eigenvector corresponds to the smallest eigenvalue?
- Determine the smallest eigenvalue and remove its corresponding eigenvector. The remaining eigenvector is the basis of a new subspace.
- Transform all vectors in X in this new subspace by expressing all vectors in X in this new basis.

The given data X

```
In [2]: X = np.array([(-3,-2),(-2,-1),(-1,0),(0,1),
                    (1,2),(2,3),(-2,-2),(-1,-1),
                    (0,0),(1,1),(2,2), (-2,-3),
                    (-1,-2),(0,-1),(1,0), (2,1),(3,2)])
```

Task 1: Calculate the covariance matrix Σ

```
In [73]: def get_covariance(X):
        """Calculates the covariance matrix of the input data.

        Parameters
        -----
        X : array, shape [N, D]
            Data matrix.

        Returns
        -----
        Sigma : array, shape [D, D]
            Covariance matrix

        """
        Sigma = np.cov(np.transpose(X))

        return Sigma
```

Task 2: Calculate eigenvalues and eigenvectors of Σ .

```
In [74]: def get_eigen(S):
        """Calculates the eigenvalues and eigenvectors of the input matrix.

        Parameters
        -----
        S : array, shape [D, D]
            Square symmetric positive definite matrix.

        Returns
        -----
        L : array, shape [D]
            Eigenvalues of S
        U : array, shape [D, D]
            Eigenvectors of S

        """
        L,U = np.linalg.eig(S)
        return L,U
```

Task 3: Plot the original data X and the eigenvectors to a single diagram.

```

In [75]: # plot the original data
plt.scatter(X[:, 0], X[:, 1])

# plot the mean of the data
mean_d1, mean_d2 = X.mean(0)
plt.plot(mean_d1, mean_d2, 'o', markersize=10, color='red', alpha=0.5)

# calculate the covariance matrix
Sigma = get_covariance(X)
#print("Sigma is", Sigma)
# calculate the eigenvector and eigenvalues of Sigma
L, U = get_eigen(Sigma)
#print("L : ", L)
#print("U is: ", U)

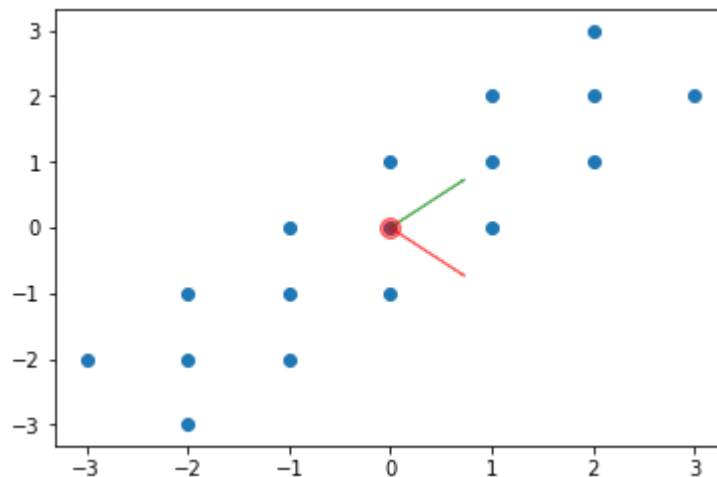
plt.arrow(mean_d1, mean_d2, U[0, 0], U[0, 1], width=0.01, color='red', alpha=0.5)
plt.arrow(mean_d1, mean_d2, U[1, 0], U[1, 1], width=0.01, color='green', alpha=0.5);

```

```

L : [ 5.625  0.375]
U is: [[ 0.70710678 -0.70710678]
 [ 0.70710678  0.70710678]]

```



What do you observe in the above plot? Which eigenvector corresponds to the smallest eigenvalue?

Write your answer here:

The eigenvector $U[1]$ corresponds to the smaller eigenvalue, 0.375

Task 4: Transform the data

Determine the smallest eigenvalue and remove its corresponding eigenvector. The remaining eigenvector is the basis of a new subspace. Transform all vectors in X in this new subspace by expressing all vectors in X in this new basis.

```
In [89]: def transform(X, U, L):
        """Transforms the data in the new subspace spanned by the eigenvector corresponding to the largest eigenvalue.

        Parameters
        -----
        X : array, shape [N, D]
            Data matrix.
        L : array, shape [D]
            Eigenvalues of Sigma_X
        U : array, shape [D, D]
            Eigenvectors of Sigma_X

        Returns
        -----
        X_t : array, shape [N, 1]
            Transformed data

        """
        L_list = L.tolist()
        U_list = U.tolist()
        position = L_list.index(min(L))
        U_list.pop(position)
        U_fin = np.asarray(U_list)
        #print(U_fin.shape)

        X_t = np.dot(X, np.transpose(U_fin))

        return X_t
```

```
In [90]: X_t = transform(X, U, L)
        #print(X_t)
```

Task SVD

Task 5: Given the matrix M find its SVD decomposition $M = U \cdot \Sigma \cdot V$ and reduce it to one dimension using the approach described in the lecture.

```
In [92]: M = np.array([[1, 2], [6, 3], [0, 2]])
```

```
In [112]: def reduce_to_one_dimension(M):  
    """Reduces the input matrix to one dimension using its SVD decomposition.  
  
    Parameters  
    -----  
    M : array, shape [N, D]  
    Input matrix.  
  
    Returns  
    -----  
    M_t: array, shape [N, 1]  
    Reduce matrix.  
  
    """  
    U,S,V = np.linalg.svd(M,full_matrices=False)  
    Sigma = np.diag(S)  
  
    M_t = np.dot(U,Sigma)  
    return M_t
```

```
In [113]: M_t = reduce_to_one_dimension(M)  
print(M_t)
```

```
[[-1.90211303  1.1755705 ]  
 [-6.68109819 -0.60243425]  
 [-1.05146222  1.70130162]]
```