

Random Graphs

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Abstract

Definition 1. A graph $G = (V, E)$ is a collection of elements called vertices connected by edges. The set of vertices is denoted by V (from “vertices”), and the set of edges is denoted by E (from “edges”), where $E \subset V \times V$. We denoted the set of graphs \mathcal{G} .

Definition 2. Let $n \in \mathbb{N}$ and $p \in [0, 1]$. A random graph $G \in \mathcal{G}(n, p)$ is defined as $G = (V, E)$ where: $V = \{1, \dots, n\}$, $\{i, j\} \in \binom{V}{2}$, $\mathbb{P}(\{i, j\} \in E) = p$.

1 Simulation of Graph $\mathcal{G}(n, p)$

In this section the objective is to simulate a random graph carried out by Python. For this we will need of the library networkx which give access to some useful functions.

1. Initialisation of parameters

```
n = 10 # number of vertices
p = 0.5
nb_graph = 10**4
graph_list = []
```

2. Function which generates an oriented random graph ($i < j$)

```
def generate_oriented_graph(n, p):
    G = nx.DiGraph()
    G.add_nodes_from(range(1, n+1))

    for i in range(1, n+1):
        for j in range(i+1, n+1): # i < j
            if np.random.rand() < p:
                G.add_edge(i, j)

    return G
```

3. Loop which generates a list of graph

```
for i in range(nb_graph):
    G = generate_oriented_graph(n, p)
    graph_list.append(G)
```

4. Computation of $\frac{\#\{\text{graphs where } 1 \rightarrow n\}}{\#\{\text{simulations}\}}$

```
graph_1_n = 0
for i in range(nb_graph):
    if (nx.has_path(graph_list[i], 1, n)):
        graph_1_n += 1
```